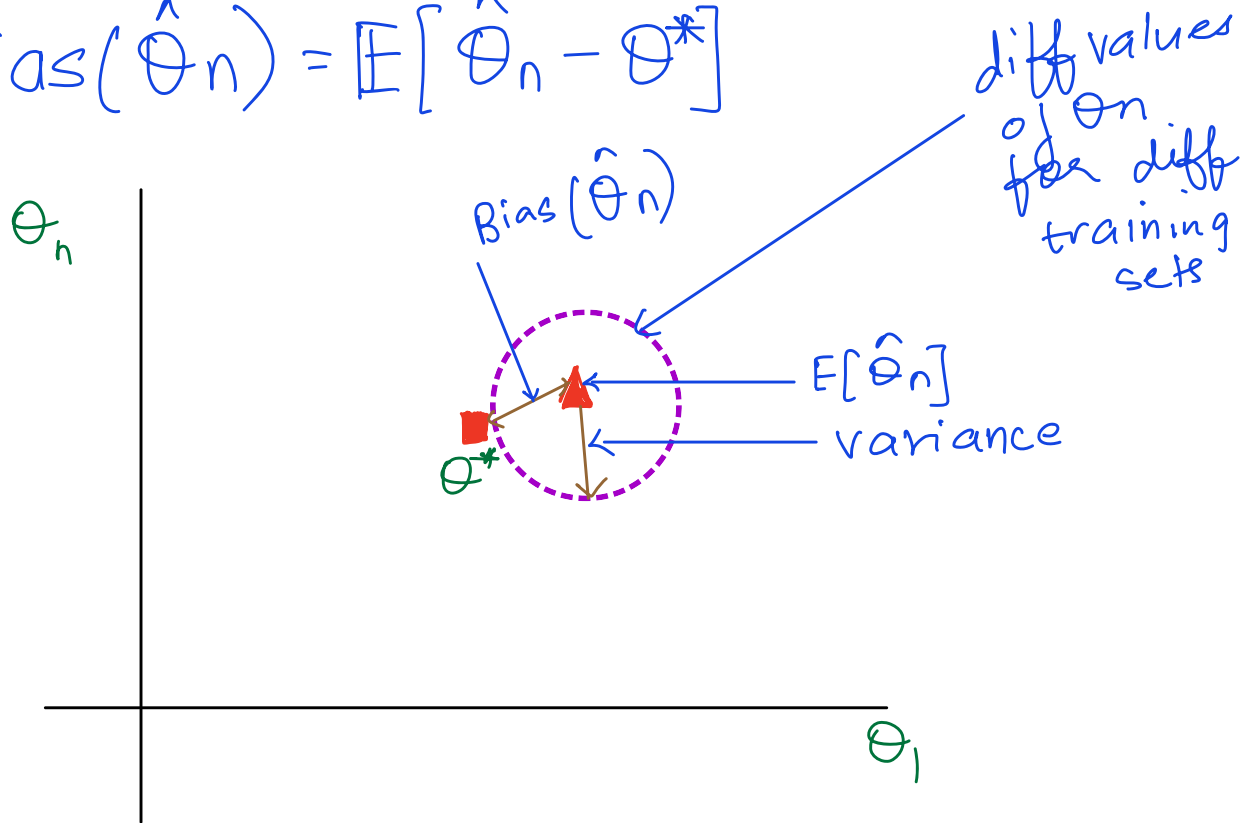


Statistical Learning Uniform Convergence

$$\text{Bias}(\hat{\Theta}_n) = \mathbb{E}[\hat{\Theta}_n - \Theta^*]$$

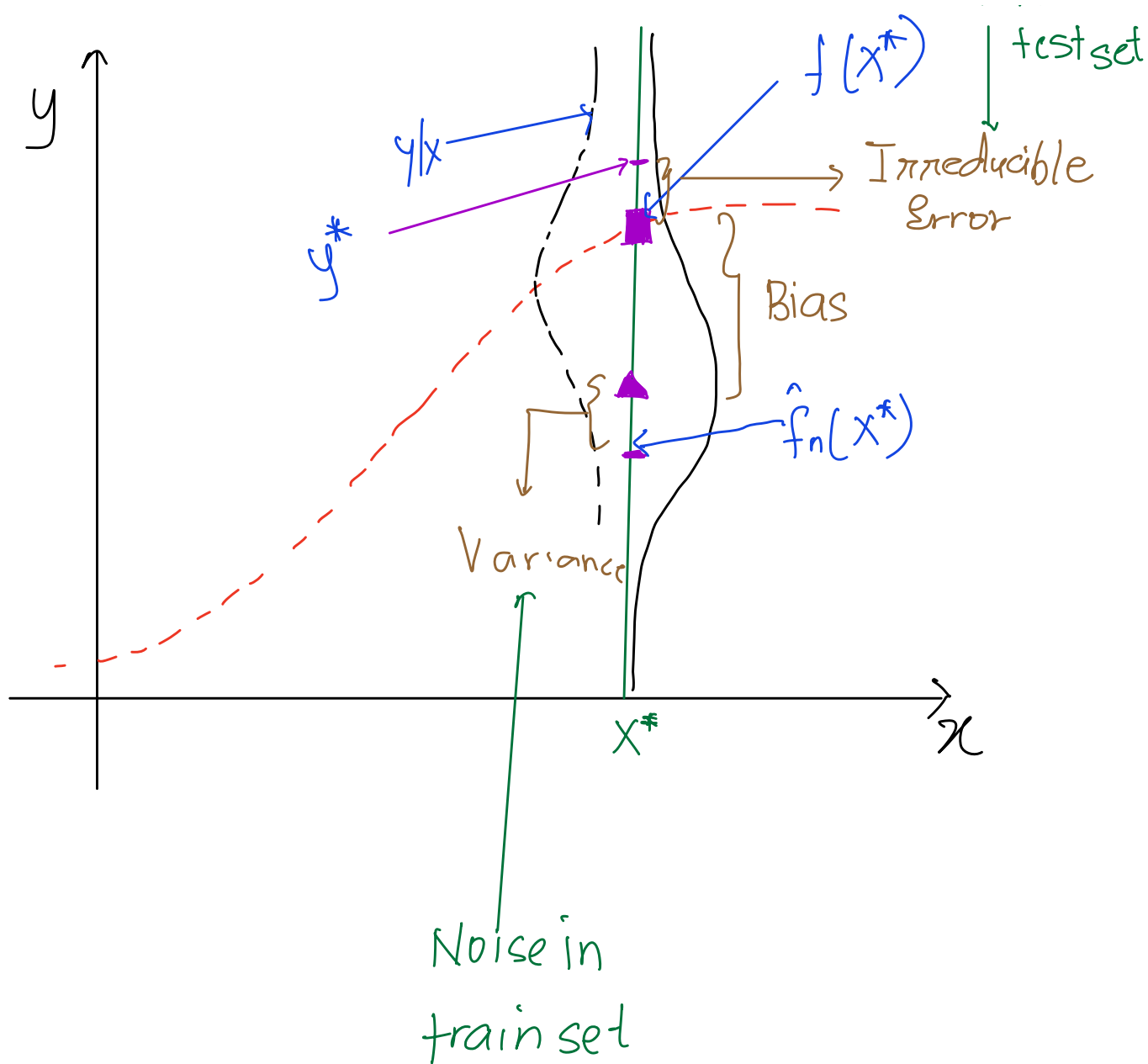


$$\text{Bias}(\hat{f}_n) = \mathbb{E}[\hat{f}_n(x^*) - f(x^*)]$$

where $f = \mathbb{E}[y|x]$, $y = f(x) + \epsilon$

$$\text{Var}(\hat{f}_n) = \mathbb{V}[\hat{f}_n(x^*)]$$

Noise in



Regularization

Equivalent to MAP

estimation $J(\theta) = \|X\theta - \vec{y}\|_2^2 + \lambda \|\theta\|^2$

$S \rightarrow$ training set $\{(x^{(1)}, y^{(1)}), \dots, (x^{(i)}, y^{(i)}), \dots\}$

$$\hat{\theta}_{\text{MAP}} = \arg \max_{\theta} \underbrace{p(s|\theta)}_{\text{Likelihood}} \underbrace{p(\theta)}_{\text{Regularizer}}$$

MAP - Maximum a posteriori estimate

Instead of calculation the whole posterior, calculate mode of posterior & use that point estimate as output of estimator

For Linear Regression,

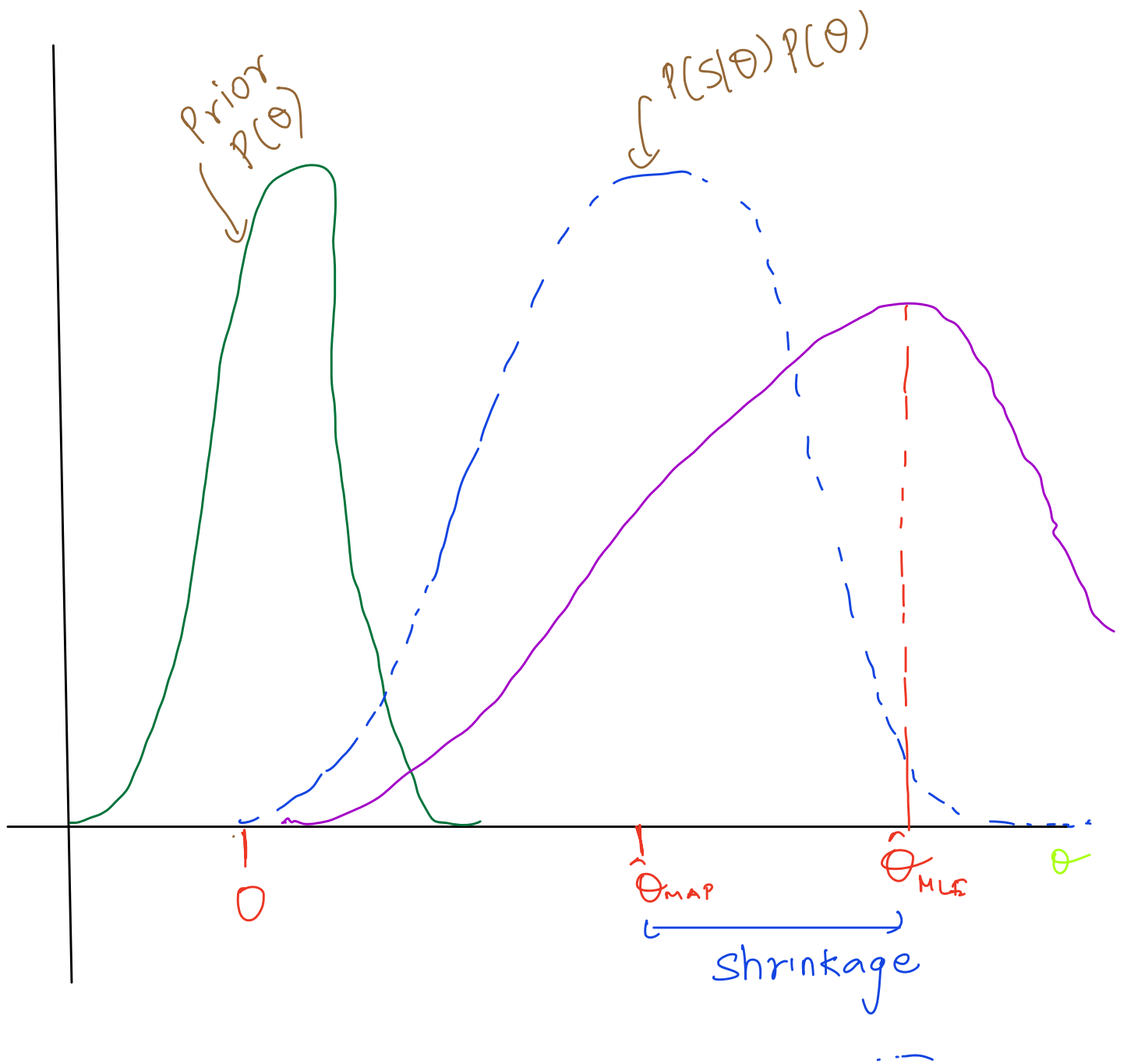
$p(s|\theta) \rightarrow$ Likelihood is some scalar multiple of $\|X\theta - y\|_2^2$

for Gaussian priors, prior takes form of squared error on θ and the λ is directly related to the variance of the prior

$$P(\theta|s) = \frac{P(s|\theta) P(\theta)}{P(s)}$$

$$\arg \max_{\theta} P(\theta|s) = \arg \max_{\theta} \frac{P(s|\theta) P(\theta)}{P(s)}$$

$$= \arg \max_{\theta} P(s|\theta) P(\theta)$$



L2 Regularized Linear Regression

$$J(\theta) = \left(\sum_{i=1}^n (y^{(i)} - \theta^T x^{(i)})^2 \right) + \lambda \|\theta\|_2^2$$

$$\hat{\theta}_n = (X^T X + \lambda I)^{-1} X^T \vec{y}$$

$$X^T X + \lambda I = U \begin{bmatrix} \sigma_1^2 + \lambda & & \\ & \ddots & \\ & & \sigma_d^2 + \lambda \end{bmatrix} U^T$$

$$(X^T X + \lambda I)^{-1} = U \begin{bmatrix} (\sigma_1^2 + \lambda)^{-1} & & \\ & \ddots & \\ & & (\sigma_d^2 + \lambda)^{-1} \end{bmatrix} U^T$$

$$U U^T = I = U^T U$$

$$E[\hat{\theta}_n] = \begin{bmatrix} U \begin{bmatrix} \frac{\sigma_1^2}{\sigma_1^2 + \lambda} & & 0 \\ & \ddots & \\ 0 & & \frac{\sigma_d^2}{\sigma_d^2 + \lambda} \end{bmatrix} U^T \end{bmatrix} \theta^*$$

$$\hat{\theta}_n = (X^T X + \lambda I)^{-1} X^T (X \theta^* + \varepsilon)$$

Standard L.R. is unbiased
 $E[\hat{\theta}_n] = \theta^*$

But when $\lambda > 0$, $\theta^* \neq E[\hat{\theta}_n]$ so bias added.

Also, see eigen values are all < 1 , so they have a shrinkage effect

$$\text{cov}(\hat{\theta}_n) = U \begin{bmatrix} \frac{\tau^2 \sigma_1^2}{(\sigma_1^2 + \lambda)^2} & & \\ & \ddots & \\ & & \frac{\tau^2 \sigma_d^2}{(\sigma_d^2 + \lambda)^2} \end{bmatrix} U^T$$

$$\varepsilon \sim N(0, \tau^2)$$

$$y = \theta^{*T} x + \varepsilon$$

$$\text{Cov}(\hat{\theta}_n) = U \begin{bmatrix} \frac{\tau^2 \sigma_1^2}{(\sigma_1^2 + \lambda)^2} & & \\ & \ddots & \\ & & \frac{\tau^2 \sigma_d^2}{(\sigma_d^2 + \lambda)^2} \end{bmatrix} U^T$$

As $\lambda \uparrow$, variance reduces, bias increases.

$$MSE[\hat{f}_n] = \underbrace{\gamma^2}_{\text{Irreducible error}} + \underbrace{E[\hat{f}_n(x^*) - f(x^*)]^2}_{\text{Bias}^2} + \underbrace{V[\hat{f}_n(x^*)]}_{\text{Variance}}$$

$$f(x) = \theta^{*T} x$$

$$\text{Bias}(f_n(x^*)) = E[\hat{f}_n(x^*) - f(x^*)]$$

$$= E[\hat{\theta}_n^T x^* - \theta^{*T} x^*]$$

$$= E[\hat{\theta}_n - \theta^*]^T x^*$$

$$= \text{Bias}(\hat{\theta}_n)^T x^*$$

$$\text{Var}[\hat{f}_n] = x^T \text{Cov}[\hat{\theta}_n] x$$

Heuristics for Bias & Variance

Training Error \approx Bias

Cross Val. Error - Training Error \approx Variance

To fight Bias

To fight Variance

* Make model larger

* Collect more data

* Reduce regularization

* Increase regularization

LEARNING THEORY

① Train & Test Data \sim Same Distribution

② Examples are sampled i.i.d.

Risk of Hypothesis

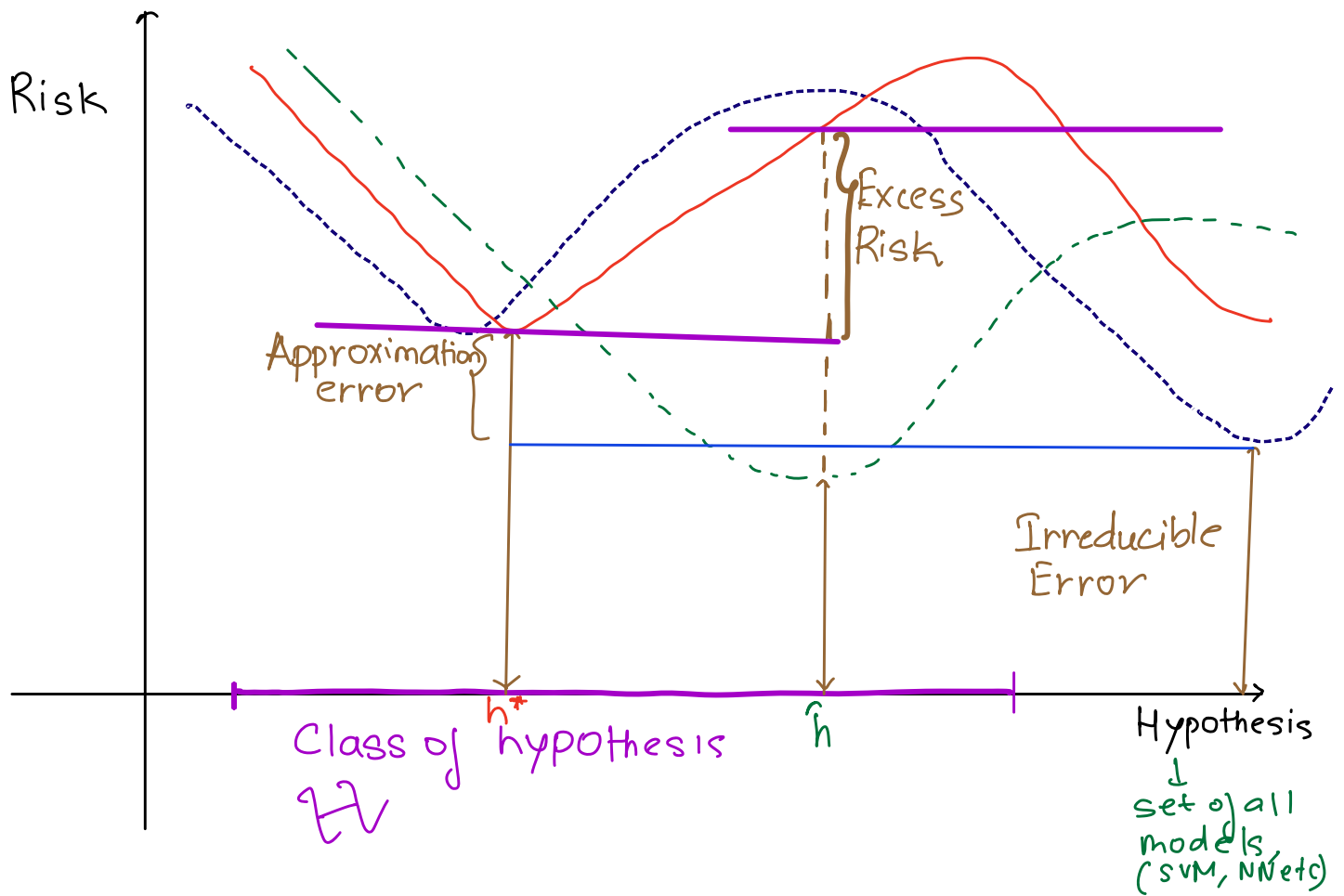
$$\mathcal{E}(h) = \mathbb{E} \left[\text{loss}(y, h(x)) \right]_{(x,y) \sim D}$$

$$S = \{ (x^{(i)}, y^{(i)}) \}_{i=1}^n$$

Empirical Risk

$$\hat{\mathcal{E}}(h) = \frac{1}{|S|} \sum_{(x,y) \in S} \text{loss}(y, h(x))$$

- For a given h , relation betⁿ $\hat{\mathcal{E}}(h)$ & $\mathcal{E}(h)$?
- How does our G.E. compare to the best G.E.?



- True Risk
- Empirical Risk (M1)
- Empirical Risk (M2)

As you \uparrow size of dataset, the distⁿ betⁿ curves decreases i.e. becomes tighter.

h^* Best in class hypothesis

Approximation Error - Penalty you pay by limiting to a class of models

Excess Risk - Penalty due to smaller dataset

Step 1: Uniform Convergence

Step 2: Excess Risk Bound

Uniform Convergence, w.p. $\geq 1 - \delta$,
all $h \in \mathcal{H}$

$$|\varepsilon(h) - \hat{\varepsilon}(h)| \leq \gamma$$

\downarrow
Term(n, δ, \mathcal{H})

Eg. Suppose $\delta = 0.1$, then we say

with 90% probability, the gap betⁿ
true & empirical risk is less than $\sqrt{\frac{1}{n}}$