

$$\frac{\partial L}{\partial w_{ij}^{[2]}} = \frac{\partial L}{\partial a^{[3]}} \frac{\partial a^{[3]}}{\partial w_{ij}^{[2]}}$$

$$= \underbrace{\frac{\partial L}{\partial a^{[3]}} \frac{\partial a^{[3]}}{\partial z^{[3]}}}_{\downarrow} \frac{\partial z^{[3]}}{\partial a^{[2]}} \frac{\partial a^{[2]}}{\partial z^{[2]}} \frac{\partial z^{[2]}}{\partial w_{ij}^{[2]}}$$

$$= (a^{[3]} - y) \cdot w^{[3]} \text{diag}[g'(z^{[2]})]$$

$$\begin{bmatrix} 0 \\ 0 \\ \vdots \\ a_j \\ \vdots \end{bmatrix} \leftarrow \begin{matrix} i\text{th} \\ \text{position} \end{matrix}$$

element wise product

$$\left[(a^{[3]} - y) w^{[3]} \odot g'(z^{[2]}) \right] \begin{bmatrix} 0 \\ 0 \\ \vdots \\ a_j^{[1]} \\ \vdots \end{bmatrix} \leftarrow i\text{th}$$

X

$$= X_i a_j^{[1]}$$

\uparrow i^{th} element of vector X

$$\frac{\partial L}{\partial w^{[2]}} = X a^{[1]T}$$

Network View

$$f: \mathbb{R}^n \rightarrow \mathbb{R}^m$$

$$\frac{\partial f}{\partial x} \in \mathbb{R}^{m \times n}$$

$$\frac{\partial L}{\partial x}$$

$$\begin{array}{c} \xleftarrow{\text{Row vector } \delta^{[2]}} \\ \text{diag}' w^{[1-1]} \dots \\ \frac{\partial L}{\partial w_{ij}^{[2]}} = \underbrace{\frac{\partial L}{\partial a^{[1]}}}_{1 \times 1} \underbrace{\frac{\partial a^{[1]}}{\partial z^{[1]}}}_{1 \times 1} \underbrace{\frac{\partial z^{[1]}}{\partial a^{[1-1]}}}_{1 \times m} \underbrace{\dots}_{m \times m} \underbrace{\frac{\partial a^{[2]}}{\partial z^{[2]}}}_{m \times m} \underbrace{\frac{\partial z^{[2]}}{\partial w_{ij}^{[2]}}}_{m \times 1} \\ \hspace{15em} \xrightarrow{\text{column vector}} \end{array}$$

Logistic Regression

$$[y^{(i)} - h_0(x^{(i)})] x^{(i)} \leftarrow \frac{\partial L}{\partial x}$$

$$(y^{(i)} - a^{[1]}) w^{[1]} \leftarrow \frac{\partial L}{\partial a}$$

$$\frac{\partial \mathcal{L}}{\partial w_{ij}^{[1]}} = \frac{\partial \mathcal{L}}{\partial z^{[2]}} \frac{\partial z^{[2]}}{\partial a^{[1]}} \frac{\partial a^{[1]}}{\partial z^{[1]}} \frac{\partial z^{[1]}}{\partial w_{ij}^{[1]}}$$

$| \times |$ $| \times m$ $m \times m$ $m \times m$ $m \times |$

$$\frac{\partial a^{[L-1]}}{\partial z^{[L-1]}} = \begin{bmatrix} g' & & & \\ & g' & & \\ & & \bigcirc & \\ & & & \bigcirc \\ & \bigcirc & & \\ & & g' & \\ & & & g' \end{bmatrix}$$

Diagonal

$a_i = g(z_i)$

$$\frac{\partial z^{[2]}}{\partial w_{ij}^{[2]}} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ a_j \end{bmatrix}$$

$z_i = \sum_j w_{ij} a_j + b_i$

$a_j \leftarrow i^{\text{th}} \text{ position}$

$$\frac{\partial \mathcal{L}}{\partial w_{ij}^{[2]}} = \delta^{[2]} \cdot \begin{bmatrix} 0 \\ \vdots \\ a_j \\ \vdots \end{bmatrix}$$

$$= \frac{\partial \mathcal{L}}{\partial z^{[2]}} \begin{bmatrix} 0 \\ \vdots \\ a_j \\ \vdots \end{bmatrix} = \left[\frac{\partial \mathcal{L}}{\partial z^{[2]}} \right]_i a_j$$

$$\frac{\partial \mathcal{L}}{\partial w^{[2]}} = \left(\frac{\partial \mathcal{L}}{\partial z^{[2]}} \right)^T (a^{[1]})^T \rightarrow \text{think as outer product}$$

$$w^{[2]} := w^{[2]} - \alpha \frac{\partial \mathcal{L}}{\partial w^{[2]}}$$

$$J(w, b) = \sum_{i=1}^B \mathcal{L}(y^{(i)}, \hat{y}^{(i)})$$

B is size of batch

$$\underbrace{z^{[1]}}_m = \underbrace{w^{[1]}}_{m \times d} \underbrace{x^{(i)}}_d + \underbrace{b^{[1]}}_m$$

$$z^{[1]} = \underbrace{w^{[1]}}_{m \times d} \underbrace{\begin{bmatrix} x^{(1)} & x^{(2)} & \dots & x^{(B)} \end{bmatrix}}_{d \times B} + \underbrace{b^{[1]}}_{m \times 1}$$

$\xleftarrow{\hspace{10em}} m \times B \hspace{1em} \xleftarrow{\hspace{5em}} m \times 1$

Broadcasting

Stochastic Gradient Descent

$i()$

\dots

$$\alpha \rightarrow 1/x$$

$$\left. \begin{aligned} \sum_t \alpha^{(t)} &= \infty \\ \sum_t \alpha^{(t)^2} &< \infty \end{aligned} \right\} \begin{array}{l} \text{if cond}^n \text{ satisfied} \\ \text{local optima} \\ \text{SGD} \end{array}$$

NN. : learnable feature map +
Linear model
 GLM

You learning representations
 [like $x \rightarrow \phi(x)$] & then you apply
 GLM

Associated with each n.n. is a kernel,

$$K(x_i, x_j) = \phi(x_i)^T \phi(x_j), \quad \phi \text{ takes you have}$$

input to represent
 learnt in $l-1^{\text{th}}$
 layer

So you can learn kernel & combine it with

Gr.P.

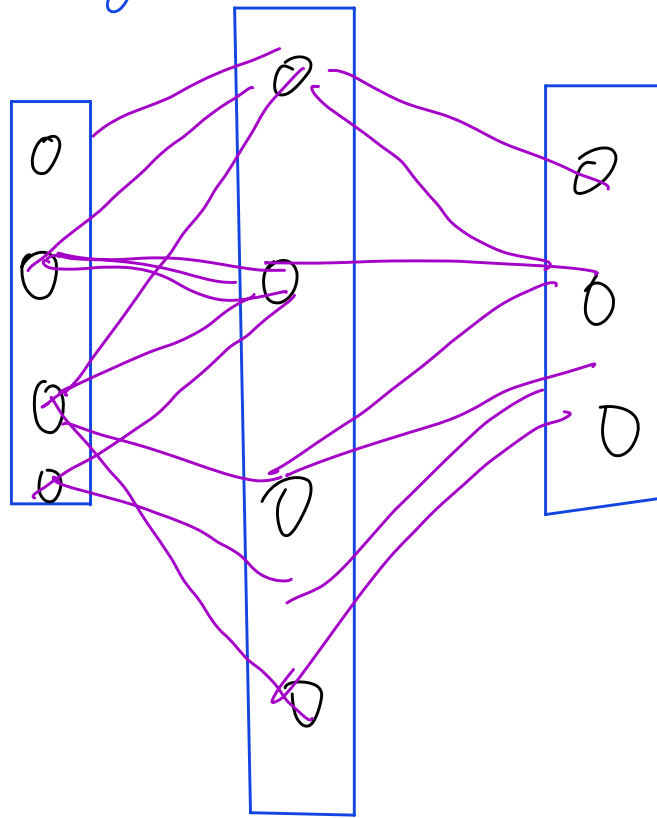
NN. becomes Gr.P. \rightarrow

Also, 2 layer NN as no. of neuron in hidden layer $\rightarrow \infty$

Universal Approximation Theorem

$$\begin{aligned}y &= f(x) \\ x &\in \mathbb{R}^d \\ y &\in \mathbb{R}^k \\ \varepsilon &= 10^{-6}\end{aligned}$$

bounded region of x
Exists a NN of 1 hidden layer.



that mimics function
to an arbitrary
precision assuming
function is continuous