

# GPU Acceleration of the Material Point Method

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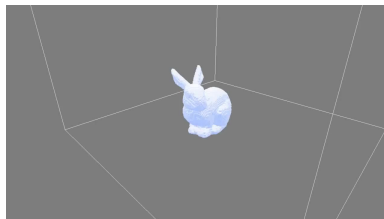
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## A Brief MPM Overview: Do You Want to Build a Snowman?

A short historical summary of MPM:

- ▶ Belongs to family of particle-in-cell(PIC) techniques [EHB57].
- ▶ Initial application to solids [SZS95] → MPM
- ▶ From research to production in *Disney's* animation film *Frozen* [Sto+13].
- ▶ Avalanche research [Gau+18]



Video result of my bachelor thesis on the simulation of snow [Mey15].

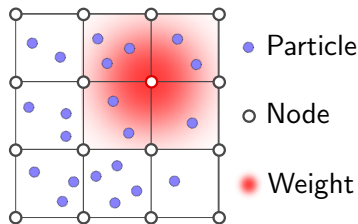
## PIC ideas:

- ▶ Combine Lagrangian particles & Eulerian grid
- ▶ Particles store all information

## Typical PIC/MPM roundtrip:

1. Particle-to-grid(P2G) transfer to an unmoving grid
2. Solve discretized governing equations on grid
3. Grid-to-particle(G2P) transfer back to particles & move them

⇒ **meshfree, non-empirical**



Transfers: Interpolation functions are defined over grid nodes.

## GPGPU for performance enthusiasts

Why would('nt) you?

### Drawbacks:

- ▶ Interactivity much easier on CPU, but slow PCI-Bus communication
- ▶ Code is mostly written against GPU architecture
- ▶ A lot of strain on the programmer

### Benefits:

- ▶ Data is already on the GPU for rendering
- ▶ **Higher parallelization acceleration**

## Governing Equations: Conservation of Mass & Momentum

**Conservation of mass**, continuum assumption holds.

Lagrangian (moving with a particle  ${}_0\mathbf{x}$ ):

$${}_0J\rho({}_0\mathbf{x}, t) = \rho({}_0\mathbf{x}, 0). \quad (1)$$

Eulerian (outside observer  ${}_t\mathbf{x}$ ):

$$\frac{\partial}{\partial t}\rho({}_t\mathbf{x}, t) = -\vec{\nabla} \cdot (\rho({}_t\mathbf{x}, t)\mathbf{v}({}_t\mathbf{x}, t)). \quad (2)$$

Lagrangian and Eulerian view measure differently but give same results. Equations are given in the strong form! [\[Jia+16\]](#)[\[Abe12\]](#)

## Conservation of momentum:

Lagrangian (moving with a particle  ${}_0\mathbf{x}$ ):

$$\rho({}_0\mathbf{x}, 0) \mathbf{a}({}_0\mathbf{x}, t) = \vec{\nabla} \cdot \mathbf{P}({}_0\mathbf{x}, t) + \mathbf{f}^{\text{body}}({}_0\mathbf{x}, t)_0 J. \quad (3)$$

Eulerian (outside observer  ${}_t\mathbf{x}$ ):

$$\rho({}_t\mathbf{x}, t) \mathbf{a}({}_t\mathbf{x}, t) = \vec{\nabla} \cdot \boldsymbol{\sigma}({}_t\mathbf{x}, t) + \mathbf{f}^{\text{body}}({}_t\mathbf{x}, t) \quad (4)$$

Solving this equation will tell us how the velocity fields  $\mathbf{v}({}_t\mathbf{x})$ ,  $\mathbf{v}({}_0\mathbf{x})$  change on the whole domain due to acceleration  $\mathbf{a}$ . This is important to advect particles accounting for all forces.

[Jia+16][Abe12]

## The Pretty Strong but Mathematically Weak Formulation

$$\int_{\Omega^0} {}_0\mathbf{q} \cdot \left[ ({}_0\rho_0)({}_0\mathbf{a}) - {}_t\mathbf{f}^{\text{body}} \right] d_0\mathbf{x} =$$

$$\int_{\partial\Omega^{t^n}} {}_t\mathbf{q} \cdot \boldsymbol{\sigma} d_t\mathbf{A} - \int_{\Omega^{t^n}} \nabla_t \mathbf{q} : \boldsymbol{\sigma} d_t\mathbf{x} \quad (5)$$

hi

## 1. [Jia+16]



hi

## 1. [Jia+16]



Rohan Abeyaratne. *Volume II of Lecture Notes on, The Mechanics of Elastic Solids: Continuum Mechanics.*

http:

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[Online; accessed 08-November-2018]. MIT Department of Mechanical Engineering, 2012.



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