

Problem 1

$$\dot{y} + y = x(t)$$

$$sY(s) + Y(s) = X(s)$$

$$H(s) = \frac{Y(s)}{X(s)} = \frac{1}{s+1}$$

step response = $\frac{1}{s} H(s)$

$$\hookrightarrow \frac{1}{s} \cdot \frac{1}{s+1} = \frac{A}{s} + \frac{B}{s+1}$$

$$1 = s(s+1) \frac{A}{s} + s(s+1) \frac{B}{s+1}$$

$$1 = (s+1)A + sB$$

$$\underline{s=-1}: 1 = -B \rightarrow B = -1$$

$$\underline{s=0}: 1 = A$$

$$Y(s) = \frac{1}{s} - \frac{1}{s+1}$$

$$\begin{aligned} \mathcal{L}^{-1} \left\{ \frac{1}{s} - \frac{1}{s+1} \right\} &= \mathcal{L}^{-1} \left\{ \frac{1}{s} \right\} - \mathcal{L}^{-1} \left\{ \frac{1}{s+1} \right\} \\ &= u(t) - e^{-t} u(t) \end{aligned}$$

$$\boxed{y(t) = (1 - e^{-t}) u(t)}$$

Problem 2

A. DC gain = $\lim_{s \rightarrow 0} H(s)$

$$H(s) = \frac{1/\tau}{s + 1/\tau}$$

$$\frac{Y(s)}{Y_{sp}(s)} = \frac{K_1 H}{1 + K_1 H} = \frac{(K_1/s)H}{1 + (K_1/s)H} = \frac{K_1 H}{s} \cdot \frac{s}{s + K_1 H} = \frac{K_1 H}{s + K_1 H}$$

$$\lim_{s \rightarrow 0} \frac{K_1 H}{s + K_1 H} = \boxed{1}$$

The DC gain is 1 for any $H(s)$, and does not depend on the value of K_1 , because that gets cancelled out.

B. $\frac{Y(s)}{Y_{sp}(s)} = \frac{K_1 H}{s + K_1 H} = \frac{K_1 \left(\frac{1/\tau}{s + 1/\tau} \right)}{s + K_1 \left(\frac{1/\tau}{s + 1/\tau} \right)} = \frac{K_1 / \tau}{s + 1/\tau} \cdot \frac{s + 1/\tau}{s^2 + s/\tau + K_1/\tau}$

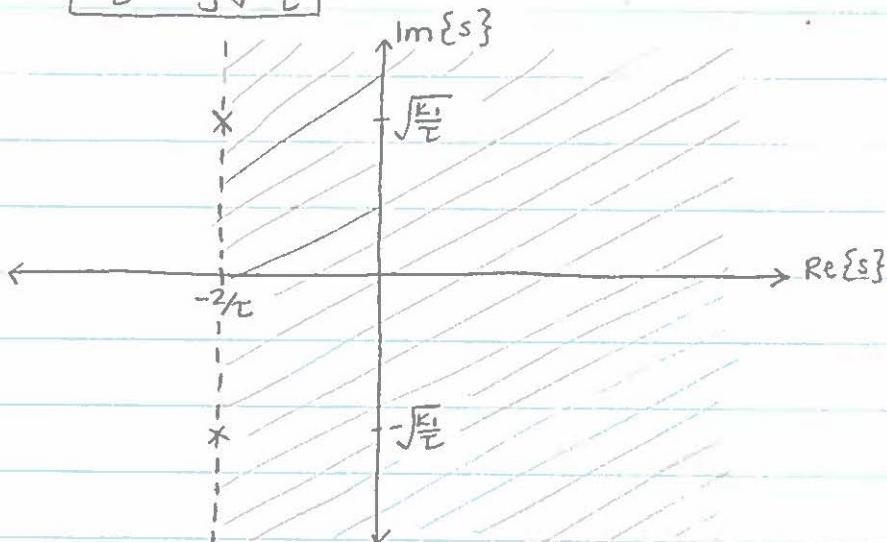
$$= \boxed{\frac{K_1 / \tau}{s^2 + s/\tau + K_1/\tau}}$$

pole:

$$0 = s^2 + s/\tau + K_1/\tau$$

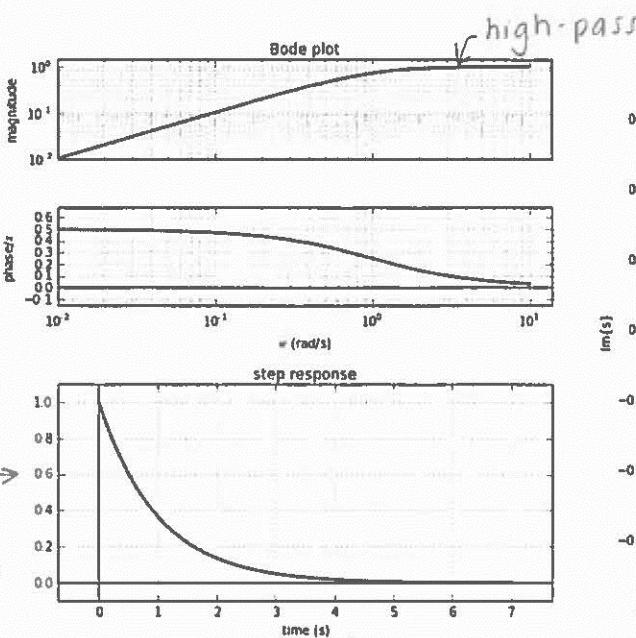
$$\text{poles @ } s = \frac{-\frac{1}{\tau} \pm \sqrt{(\frac{1}{\tau})^2 - 4K_1/\tau}}{2} = \frac{-2}{\tau} \pm \frac{1}{2} \sqrt{(\frac{1}{\tau})^2 - 4K_1/\tau}$$

$$= \boxed{\frac{-2}{\tau} \pm j\sqrt{\frac{K_1}{\tau}}}$$

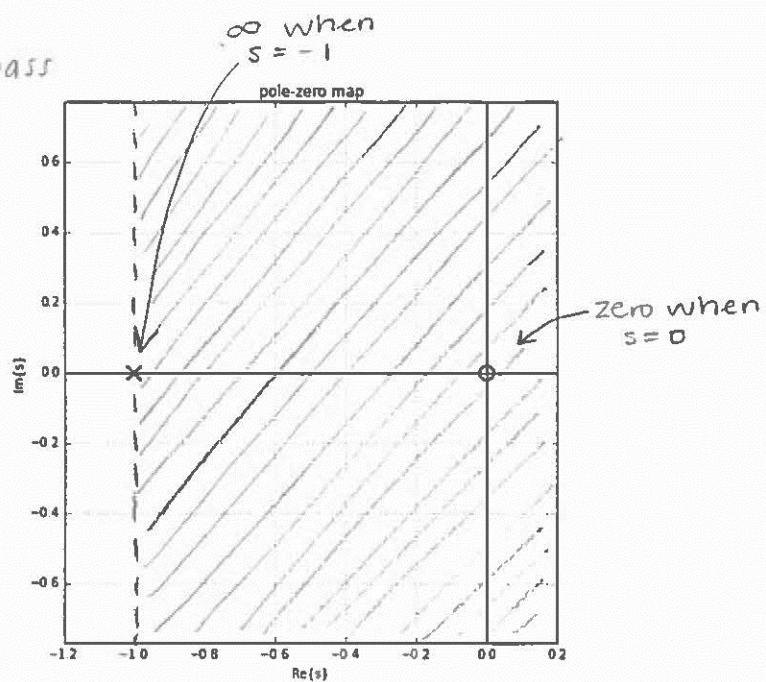


Problem 3

A. $\frac{s}{s+1}$

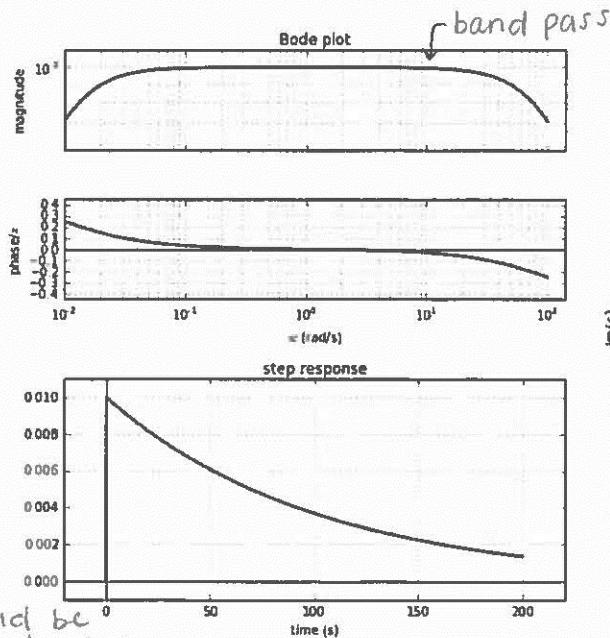


first order system



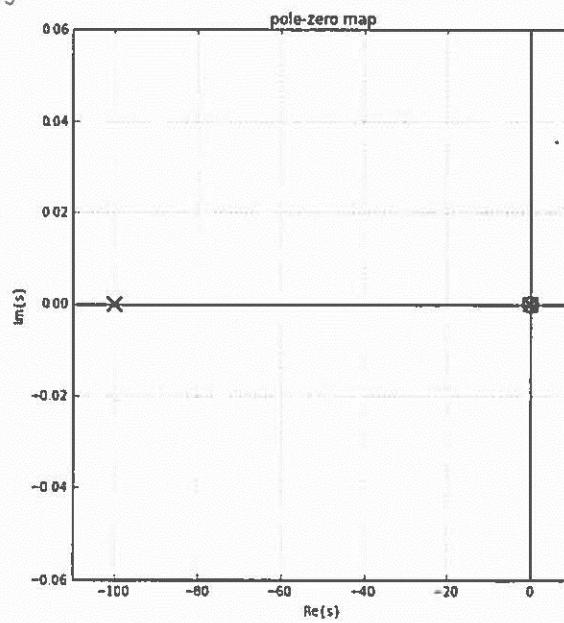
The Bode plot of this system shows a high-pass behavior, and the step response agrees that the system is first-order. The pole-zero map has one real pole and a zero at $(0,0)$.

B. $\frac{s}{s^2 + 100s + 1}$



looks like
first
order
system

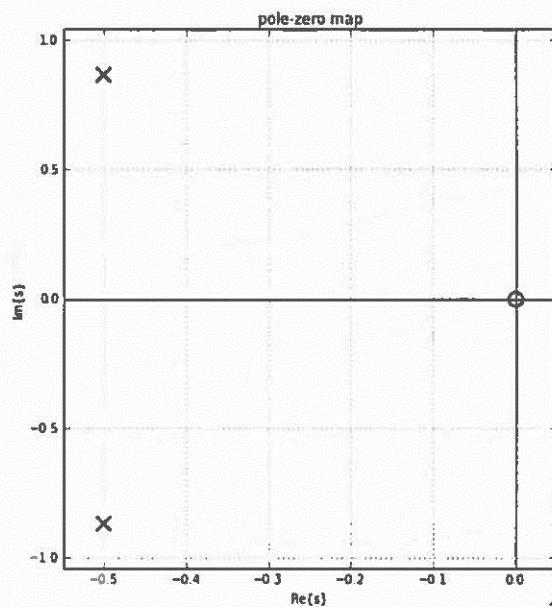
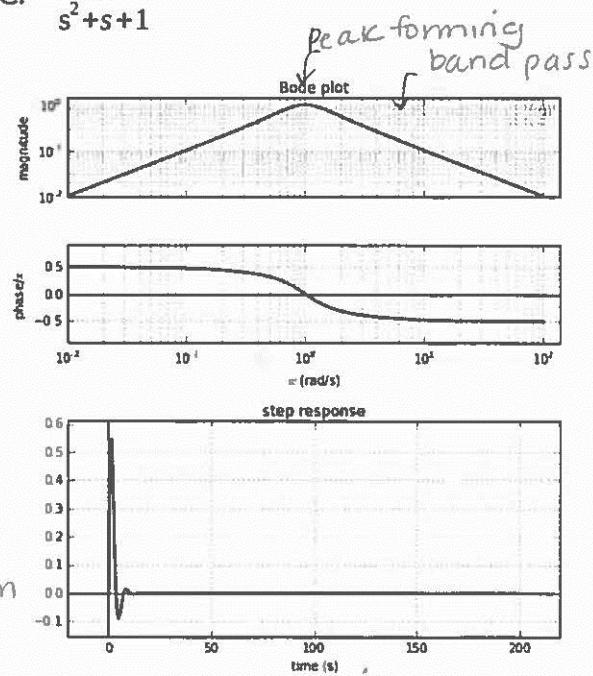
↳ should be
second order



two poles with
different real
components

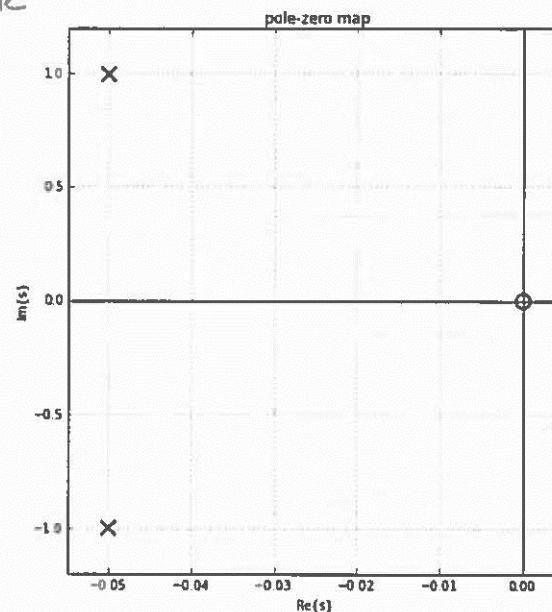
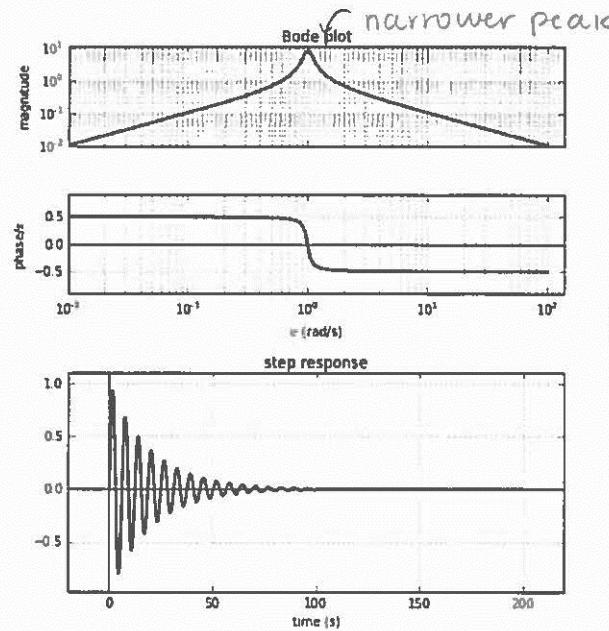
The Bode plot of this system shows a band-pass behavior, and the step response shows a first-order shape, although the system is second-order. The pole-zero map has two real poles and a zero at $(0,0)$.

C. $\frac{s}{s^2+s+1}$



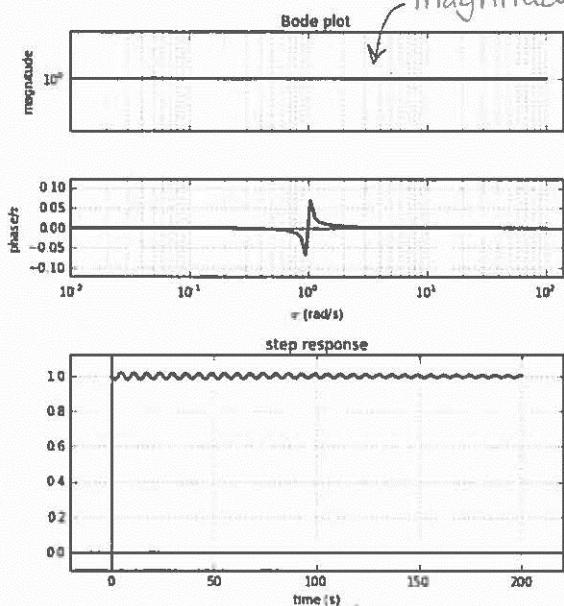
The Bode plot of this system has a band-pass behavior with a peak in the middle, and the step response appropriately shows a second-order shape. The pole-zero map has two poles with real components and opposite imaginary components. It also has a zero at (0,0).

D. $\frac{s}{s^2+0.1s+1}$ similar to C, but with more oscillations in step response



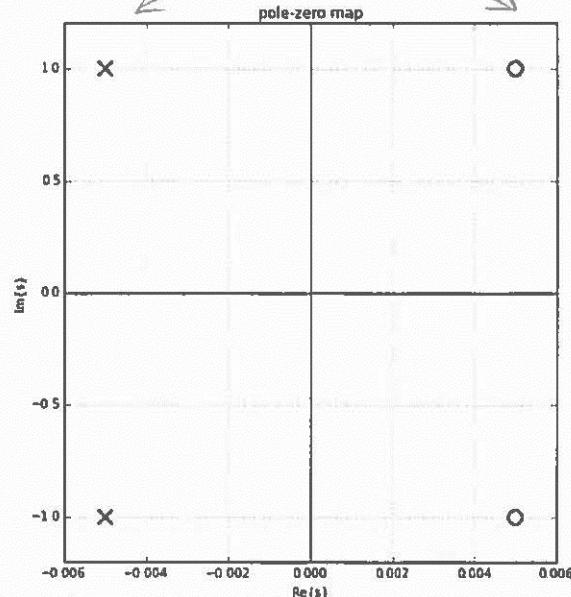
The Bode plot of this system has a band-pass behavior with an even narrower peak than C. The step response shows a second-order shape with more oscillations than C. The pole-zero map looks similar to C, with two poles that have a real component and opposite imaginary components, and a zero at (0,0).

E. $\frac{s^2 - 0.01s + 1}{s^2 + 0.01s + 1}$



second order system

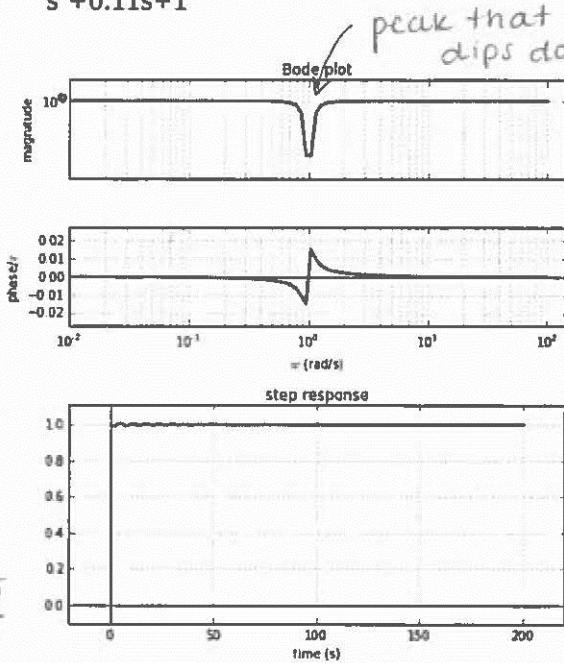
doesn't seem to amplify frequencies
magnitude 1



two poles with different imaginary components, and two zeros with different imag. components.

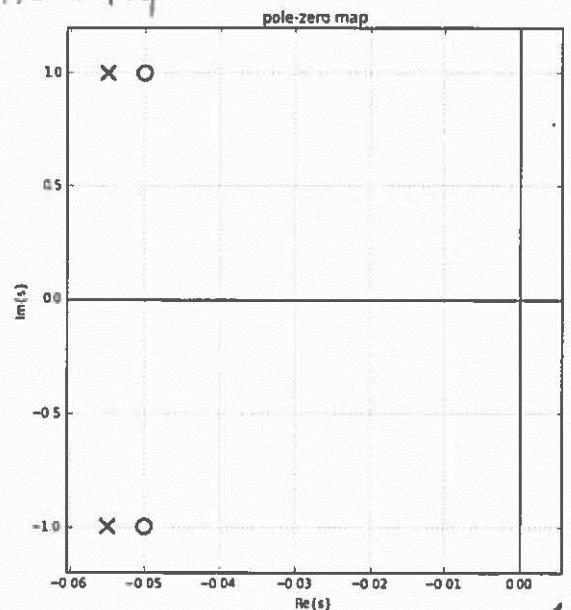
The Bode plot of this system appears flat at 1, implying that the system doesn't amplify the frequencies. The step response shows a second-order system and oscillates for a long time. The pole-zero map has two poles with a real component and opposite imaginary components, as well as two zeros with a real component and opposite imaginary components.

F. $\frac{s^2 + 0.1s + 1}{s^2 + 0.11s + 1}$



second order system
↓
dampens quicker than E

peak that dips down sharply



about the same as above

The Bode plot of this system has a band-stop behavior with a fairly narrow peak, and the step response has a second-order shape with a quicker damping behavior (less oscillations) than E. The pole-zero map also is very similar to E, with two poles and two zeros containing real and imaginary components.

Problem 4

$$H(s) = \frac{1}{s^2 - 0.01s + 1}$$

A. step response = $\frac{1}{s} H(s) = \frac{1}{s} \cdot \frac{1}{s^2 - 0.01s + 1}$

$$\frac{1}{s} \cdot \frac{1}{s^2 - 0.01s + 1} = \frac{A}{s} + \frac{B}{s^2 - 0.01s + 1}$$

$$1 = s(s^2 - 0.01s + 1) \frac{A}{s} + s(s^2 - 0.01s + 1) \frac{B}{s^2 - 0.01s + 1}$$

$$1 = A(s^2 - 0.01s + 1) + Bs$$

$$\underset{s=0}{\cancel{1}} = A$$

$$1 = s^2 - 0.01s + 1 + Bs$$

$$\underset{s=1}{\cancel{1}} = 1 - 0.01 + 1 + B$$

$$B = -0.99$$

✓ partial fraction expansion again

$$\text{step response} = \frac{1}{s} - \frac{0.99}{s^2 - 0.01s + 1}$$

$$\frac{0.99}{s - 0.005 + 0.999987i} \cdot \frac{1}{s - 0.005 - 0.999987i} = \frac{A}{s - 0.005 + 0.999987i} + \frac{B}{s - 0.005 - 0.999987i}$$

$$0.99 = (s - 0.005 + 0.999987i) \frac{A}{s - 0.005 + 0.999987i} + (s - 0.005 - 0.999987i) \frac{B}{s - 0.005 - 0.999987i}$$

$$0.99 = (s - 0.005 + 0.999987i) A + (s - 0.005 - 0.999987i) B$$

$$\underset{s=0.005+0.999987i}{\cancel{0.99}} = (0.005 + 0.999987i) - (0.005 + 0.999987i) B$$

$$0.99 = 1.999974i B \rightarrow B = -0.495006435i$$

$$\underset{s=0.005-0.999987i}{\cancel{0.99}} = (0.005 - 0.999987i) - (0.005 - 0.999987i) A$$

$$0.99 = -1.9999874i A \rightarrow A = 0.495006435i$$

$$\text{step response} = \frac{1}{s} - \frac{0.495006435i}{s - 0.005 + 0.999987i} - \frac{0.495006435i}{s - 0.005 - 0.999987i}$$

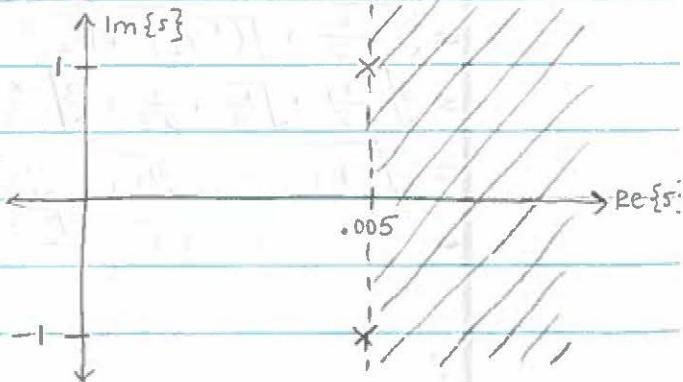
see Python plot of step response plot

Anyway,

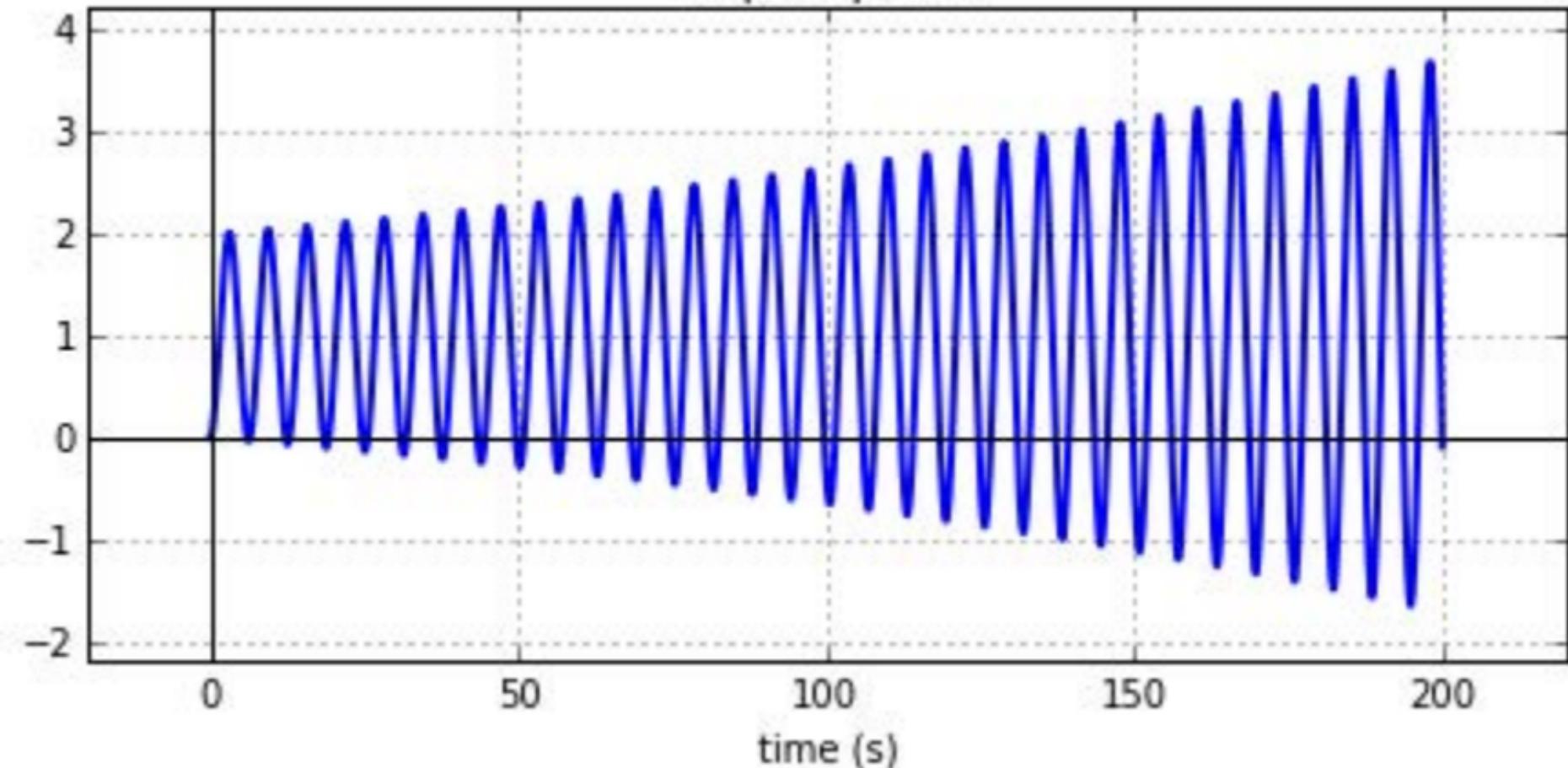
no zeros, poles @:

$$0 = s^2 - 0.01s + 1$$

$$\frac{0.01 \pm \sqrt{-0.02 - 4}}{2} \approx 0.005 \pm j$$

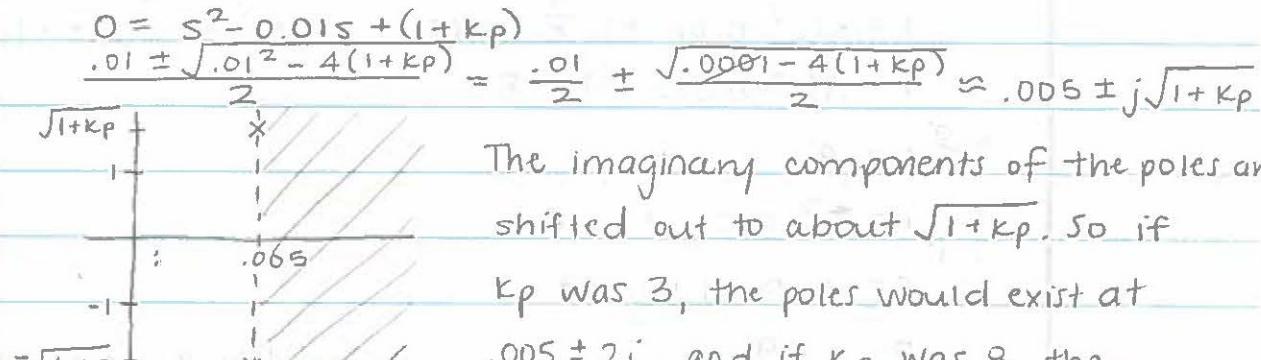


step response



$$\begin{aligned}
 \text{B. gain} &= \frac{Y}{Y_{sp}} = \frac{KH}{1+KH} \\
 &= \frac{K_p \left(\frac{1}{s^2 - 0.01s + 1} \right)}{1 + K_p \left(\frac{1}{s^2 - 0.01s + 1} \right)} = \frac{K_p}{s^2 - 0.01s + 1} \cdot \frac{s^2 - 0.01s + 1}{s^2 - 0.01s + 1 + K_p} \\
 &= \frac{K_p}{s^2 - 0.01s + 1 + K_p}
 \end{aligned}$$

no zero, pole @:



The imaginary components of the poles are shifted out to about $\sqrt{1+K_p}$. So if K_p was 3, the poles would exist at $.005 \pm 2j$, and if K_p was 8, the poles would be $.005 \pm 3j$.

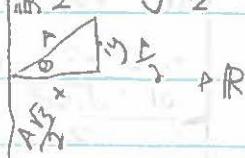
$$\begin{aligned}
 \text{C. gain} &= \frac{Y}{Y_{sp}} = \frac{KH}{1+KH} = \frac{K_1 H}{s + K_1 H} \quad \checkmark \text{ from Problem 2} \\
 &= \frac{K_1 \left(\frac{1}{s^2 - 0.01s + 1} \right)}{s + K_1 \left(\frac{1}{s^2 - 0.01s + 1} \right)} = \frac{K_1}{s^2 - 0.01s + 1} \cdot \frac{s^2 - 0.01s + 1}{s(s^2 - 0.01s + 1) + K_1} \\
 &= \frac{K_1}{s(s^2 - 0.01s + 1) + K_1}
 \end{aligned}$$

no zero, pole @ \checkmark Yay, cubic formula...

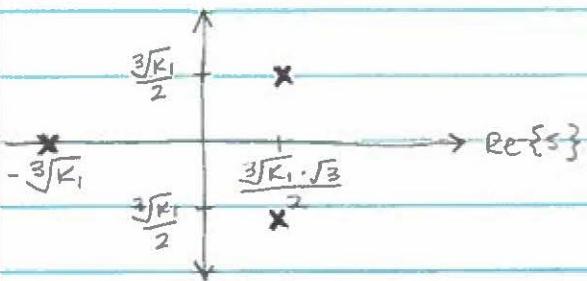
$$0 = s^3 - 0.01s^2 + s + K_1$$

$$\sqrt[3]{\left(\frac{-0.01^3}{27} - \frac{0.01}{6} - \frac{K_1}{2}\right)} + \sqrt{\left(\frac{-0.01^3}{27} - \frac{0.01}{6} - \frac{K_1}{2}\right)^2 + \left(\frac{1}{3} - \frac{-0.01^2}{4}\right)^3} + \sqrt[3]{1} - \sqrt[3]{1} \leftarrow \text{wtf?}$$

$$\begin{aligned}
 &\approx \sqrt[3]{-\frac{K_1}{2} + \sqrt{\left(\frac{K_1}{2}\right)^2 + \left(\frac{1}{3}\right)^3}} + \sqrt[3]{\frac{-K_1}{2} + \sqrt{\left(\frac{K_1}{2}\right)^2 + \frac{1}{3}}} \\
 &\approx \sqrt[3]{-\frac{K_1}{2} + \sqrt{\frac{K_1^2}{4} + \frac{1}{27}}} + \sqrt[3]{\frac{-K_1}{2} - \sqrt{\frac{K_1^2}{4} + \frac{1}{27}}} \approx \sqrt[3]{\frac{-K_1}{2} + \frac{K_1}{2} + \sqrt{\frac{-K_1}{2} - \frac{K_1}{2}}} \\
 &\approx \sqrt[3]{-K_1} = -\sqrt[3]{K_1}, \sqrt[3]{K_1} \cdot e^{\frac{\pi i}{3}}, \sqrt[3]{K_1} \cdot e^{-\frac{\pi i}{3}} \\
 &= -\sqrt[3]{K_1}, \frac{\sqrt[3]{K_1} \cdot \sqrt{3}}{2} \pm \frac{\sqrt[3]{K_1}}{2}
 \end{aligned}$$



lots of estimating..



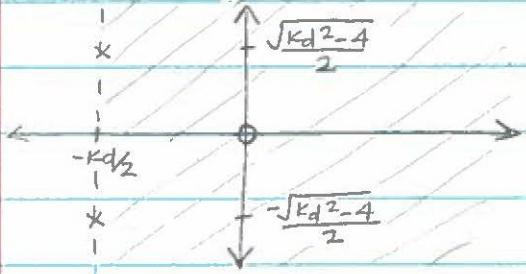
There are now three poles -
one real pole at $-\frac{3\sqrt{K_1}}{2}$, and
the poles $\frac{\frac{3\sqrt{K_1} \cdot \sqrt{3}}{2}}{2} \pm \frac{\frac{3\sqrt{K_1}}{2}}{2}$.
I'm not sure why this happens
conceptually

$$\begin{aligned}
D. \text{ gain} &= \frac{Y}{Y_{sp}} = \frac{KH}{1+KH} = \frac{sK_d H}{1+sK_d H} \\
&= \frac{sK_d \left(\frac{1}{s^2 - 0.01s + 1} \right)}{1+sK_d \left(\frac{1}{s^2 - 0.01s + 1} \right)} = \frac{sK_d}{s^2 - 0.01s + 1} \cdot \frac{s^2 - 0.01s + 1}{s^2 - 0.01s + 1 + sK_d} \\
&\therefore \\
&= \frac{sK_d}{s^2 + (K_d - 0.01)s + 1}
\end{aligned}$$

zero @ $s = 0$, pole @ :

$$0 = s^2 + (K_d - 0.01)s + 1$$

$$\frac{(-0.01 - K_d) \pm \sqrt{(K_d - 0.01)^2 - 4}}{2} = \frac{-0.01 - K_d}{2} \pm \frac{\sqrt{K_d^2 - 4}}{2} \approx -\frac{K_d}{2} \pm \frac{\sqrt{K_d^2 - 4}}{2}$$



The poles now exist at $-\frac{K_d}{2} \pm \frac{\sqrt{K_d^2 - 4}}{2}$. So if K_d was 2,
there would be one pole at -1 , and
if K_d was 1, the poles would be
at $\frac{-1}{2} \pm j \frac{\sqrt{3}}{2}$. Again, don't
understand this on a
conceptual level.