COMP 557	MIDTERM	Prof. Paul Kry
Mike Gao		October 11, 2020
260915701		# 1 – Coordinate Frame

```
// normal vector is n, n dot p is the point, let s, t be coordinates
Matrix4d coordFrame( const Vec3f &n, const Vec3f &p)
 Vec3f s,t;
  // if n is near x axis
  if(n.x > 0.9f) {
   s = Vec3f (0.0 f, 1.0 f, 0.0 f);
  } else {
    s = Vec3f (1.0 f, 0.0 f, 0.0 f);
  }
  s -= n* dot(s, n); // make s orthogonal to n
  s *= rsqrt(dot(s, s)); // normalize s
  t = cross(n, s);
  return (new double[] {
   t.x, s.x, n.x, p.x,
   t.y, s.y, n.y, p.y,
   t.z, s.z, n.z, p.z
   0, 0, 0, 1
 })
}
```

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260915701	# 2 – Rotation	Using Similarity Transform

Assume the axis pass through two points, $P_1 = (x_1, y_1, z_1)$ and $P_2 = (x_2, y_2, z_2)$

(1) Create the axis passing through origin by translating space by $-P_1$ for example

$$T = \begin{pmatrix} 1 & 0 & 0 & -x_1 \\ 0 & 1 & 0 & -y_1 \\ 0 & 0 & 1 & -z_1 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

(2) Rotate space about the x axis so that the rotation axis lies in the xz plane.

Let u be a unit vector (p, q, r) along the rotation axis.

Project u onto yz-plane, let $s=\sqrt{q^2+r^2}$ be the length of the projection. Rotate by α in order to get u in xz-plane

2

$$\cos\alpha = \frac{r}{s} \sin\alpha = \frac{q}{s} Rx = \begin{pmatrix} 1 & 0 & 0 & 0\\ 0 & \frac{r}{s} & -\frac{q}{s} & 0\\ 0 & \frac{q}{s} & \frac{r}{s} & 0\\ 0 & 0 & 0 & 1 \end{pmatrix}$$

(3) We then rotate by β so the axis overlap the z-axis:

$$\cos\beta = \frac{s}{||u||} = s \sin\beta = \frac{-p}{||u||} = -p$$

$$Ry = \begin{pmatrix} s & 0 & -p & 0 \\ 0 & 1 & 0 & 0 \\ p & 0 & s & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

(4) We then rotate around z-axis by the given angle θ

$$Rz = \begin{pmatrix} \cos\theta & -\sin\theta & 0 & 0\\ \sin\theta & \cos\theta & 0 & 0\\ 0 & 0 & 1 & 0\\ 0 & 0 & 0 & 1 \end{pmatrix}$$

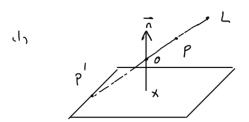
Finally, $p' = T^{-1}R_x^{-1}R_y^{-1}R_zR_yR_xTp$

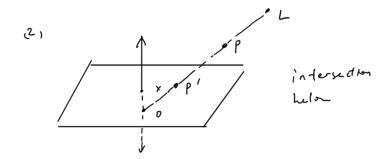
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260915701		# 3 – Perspective Projection Matrix

$$P = \begin{pmatrix} n & 0 & 0 & 0 \\ 0 & n & 0 & 0 \\ 0 & 0 & n & 0 \\ 0 & 0 & -1 & 0 \end{pmatrix}$$

Where this will take in point $(x, y, z, 1)^T$ to $(nx, ny, nz, -z)^T$, After dividing by the z coordinate we have (-nx/z, -ny/z, -n, 1) which is the desired point of the near plane

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260915701	# 4 – Creating Similarity Transform to Provide Ch	eap Shadow Projection





As shown in (1) a point light project point $p \in \mathbb{R}^3$ onto the plane with normal n at p'. We let x be the origin of the canonical basis and n be the z-axis

$$L_{LP} = L + (p - L)t$$

$$L_n = x + nt$$

We let $L_{LP} = L_n$ and find their intersection point o.

Case 1: If o above x, then by Q1 we can construct a new frame, and its frame matrix F by point o and \vec{n} then consider the plane to be the near plane with distance n.

The coordinate of p is $F^{-1}p$, and projection $PF^{-1}p$, where P is the projection matrix from Q3. Using similarity transform, $p' = FPF^{-1}p$ in the canonical basis

Case 2: If o is below x then construct F with o and $-\vec{n}$, we can get $p' = FPF^{-1}p$

Case 3: If o is at x, then p' = x

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260915701	# 5 – What is the closes	st near plane you can set?

Let
$$s = \begin{pmatrix} 0 \\ 0 \\ -1 \\ 1 \end{pmatrix}$$
 be a point on the quadrilateral, and $t = \begin{pmatrix} 0 \\ 0 \\ -2 \\ 1 \end{pmatrix}$ be a point on the wall.

$$P = \begin{pmatrix} n & 0 & 0 & 0 \\ 0 & n & 0 & 0 \\ 0 & 0 & n+10 & 10n \\ 0 & 0 & -1 & 0 \end{pmatrix}$$

$$P_s = \begin{pmatrix} 0 \\ 0 \\ -n - 10 + 10n \\ 1 \end{pmatrix}$$

$$P_t = \begin{pmatrix} 0 \\ 0 \\ -2n - 20 + 10n \\ 2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ -n - 10 + 5n \\ 1 \end{pmatrix}$$

We are only concerned about the z coordinates of those points

$$z_{P_s} = -n - 10 + 10n$$

$$z_{P_t} = -n - 10 + 5n$$

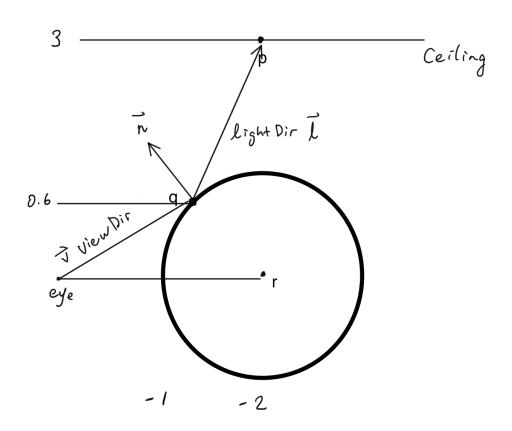
We want to minimize, i.e $|z_{P_s} - z_{P_t}| = \epsilon$ so:

$$|-n-10+10n-(-n-10+5n)|=\epsilon$$

$$|5n| = \epsilon$$

$$n = \frac{\epsilon}{5}$$

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260915701	# 6 – Where Should the	e Point Light Be Placed?



Where p is the light position (unknown), r is the center of the circle, q is the brightest spot of a Blinn-Phong specular highlight.

We need to find the position of q first. Since we know $y_q = 0.6$, we get:

$$x_q^2 + 0.6^2 = 1$$

$$x_q = 0.8$$

Thus,
$$z_q = -2 + 0.8 = 1.2$$

Now we can find the view direction v and the normal n.

$$n = q - r = \begin{pmatrix} 0 \\ 0.6 \\ 0.8 \\ 0 \end{pmatrix}$$

$$v = eye - q = \begin{pmatrix} 0\\ -0.6\\ 1.2\\ 0 \end{pmatrix}$$

Now let's find l. Suppose u is a vector such that v - 2u = l

$$u = v - proj_n v = \begin{pmatrix} 0 \\ -0.6 \\ 1.2 \\ 0 \end{pmatrix} - \begin{pmatrix} 0 \\ 0.36 \\ 0.48 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ -0.96 \\ 0.72 \\ 0 \end{pmatrix}$$

$$l = v - 2u = \begin{pmatrix} 0 \\ -0.6 \\ 1.2 \\ 0 \end{pmatrix} - 2 \begin{pmatrix} 0 \\ -0.96 \\ 0.72 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 1.32 \\ -0.24 \\ 0 \end{pmatrix}$$

Now let's find out the location of the Light

Parametric equations of the direction: x = 0 y = 0.6 + 1.32t z = -1.2 - 0.24t

Equation of the ceiling:y = 3

$$3 = 0.6 + 1.32t$$

$$t = \frac{20}{11}$$

$$z = -1.2 - 0.24t$$

$$z = -\frac{18}{11}$$

So the light should be at
$$\begin{pmatrix} 0\\3\\-\frac{18}{11}\\1 \end{pmatrix}$$

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260915701	# 7 – Debug the Given Bling 1	Phong Implementation

Vertex Shader

```
#version 400 core
uniform mat4 M;
uniform mat4 V;
uniform mat4 P;
uniform mat3 MinvT;
uniform mat3 VinvT;
in vec3 VertexNormal;
in vec4 VertexPosition;
out vec4 PositionForFP;
out vec3 NormalForFP;
void main() {
// FIX: VinvT is used instead of V
// Should change to
// vec4 tmp = V*MinvT* vec4(VertexNormal,0);
// NormalForFP= normalize(tmp.xyz)
NormalForFP = MinvT * VinvT * VertexNormal;
// FIX: PositionForFP = VinvT * VertexPosition
PositionForFP = V * M * VertexPosition;
gl_Position = P * V * M * VertexPosition;
}
```

Fragment Shader

```
#version 400 core
uniform vec3 LightColor;
uniform vec3 LightPosition;
uniform float Shininess;
uniform vec3 kd;
in vec4 PositionForFP;
in vec3 NormalForFP;
out vec4 FragColor;
void main() {
// FIX: Direction should go to the light.
// Should change to normalize(LightPosition - PositionForFP)
vec3 LightDirection = PositionForFP - LightPosition;
// FIX: Diffuse may go negative in the original implementation.
// Should change to max(dot(NormalForFP, LightDirection), 0)
float diffuse = dot( NormalForFP, LightDirection );
// FIX: Should change to normalize (vec3(0,0,0) - PositionForFP)
vec3 ViewDirection = vec3(0,0,0) - PositionForFP;
// FIX: HalfVector not unit verctor, also shouldn't divide by 2.
// Should change to normalize (LightDirection + ViewDirection)
HalfVector = (LightDirection + ViewDirection) / 2;
float specular = max(0.0, dot(NormalForFP, HalfVector));
if (diffuse == 0.0) {
specular = 0.0;
} else {
specular = pow( specular, Shininess );
vec3 scatteredLight = kd * LightColor * diffuse;
// FIX: ks default to 1
vec3 reflectedLight = LightColor * specular;
vec3 rgb = min( scatteredLight + reflectedLight, vec3(1,1,1) );
FragColor = vec4( rgb, 1 );
```

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260915701		#8 – Ken Museth Keynote

Yes, I actually looked into his work of OpenVDB, apparently its very widely used as a library of manipulating sparse volumetric data. In addition to Ken Museth's Keynote, I also attended Papers 2 - Waves. I was only familiar with J. Tessendorf's Work (Clemson) prior to coming to SCA 2020, its very refreshing to see new development on procedural generation of ocean waves.