M.Sc Nestor D. **Pereira Neto**

ELECTRONIC ENGINEER · 38

Address: Rua Eduardo Campos n° 10, Boca do Rio, Salvador - BA, Brazil, 41705-230

☎ (71) 9 9698-6755 | ✉ nestor-dp@hotmail.com | 🌐 lattes.cnpq.br/8490310764316084 | 💼 nestorpneto | 🐙 NestorDP

"I have a degree in Electronic Engineering (2013) and a specialization in Biomedical Engineering (2019). I have experience in the maintenance of diagnostic imaging hospital equipment. In 2011, I started to work as a teacher in technical and higher education courses. I am Master in Electrical Engineering in the computing and robotics area, at the Federal University of Bahia (2022). Since 2019 I have had the pleasure of working with research and development in the field of robotics. Main areas of interest: Hardware decription, Digital Signal Processing, C/C++ Programming; Embedded systems and Mobile robotics localization and navigation."

Education

Federal University of Bahia - UFBA
Salvador, BA

DOCTORATE DEGREE IN ELECTRICAL ENGINEERING - RESEARCH LINE: COMPUTING AND ROBOTICS
Fev. 2023 - Mar. 2027

Federal University of Bahia - UFBA
Salvador, BA

MASTER'S DEGREE IN ELECTRICAL ENGINEERING - RESEARCH LINE: COMPUTING AND ROBOTICS
Apr. 2018 - Dec. 2022

- Communication between *Robot Operating System - ROS* and *System-on-a-chip - SoC* with integrated FPGA.

Estácio de Sá University
Salvador, BA

SPECIALIZATION IN BIOMEDICAL ENGINEERING
Oct. 2017 - Feb. 2019

- Convolutional Neural Network for Detection of QRS Complexes in Electrocardiogram Signals

Faculty of Science and Technology - ÁREA1
Salvador, BA

BACHELOR'S DEGREE IN ELECTRONIC ENGINEERING
Feb. 2008 - Jul. 2013

- Command prototype to fit X-ray equipment to the standards required by the National Health Surveillance Agency - ANVISA.
- Undergraduate research scholarship for two years

Professional Experiences

SENAI - CIMATEC
Salvador, BA

SPECIALIST II - ROBOTIC ENGINEERING
Apr. 2022 - currently

- ROS2 robotics framework: Gazebo Simulation, URDF/Xacro, SLAM Techniques for UGV.
- Programming C/C++ and python.
- Hardware and software integration.
- Hardware and firmware development for embedded systems.

CONSULTANT II - ROBOTIC ENGINEERING
Apr. 2019 - Apr. 2022

- ROS robotics framework: Gazebo Simulation, URDF/Xacro.
- Programming C/C++ and python.
- Hardware and software integration.
- Hardware and firmware development for embedded systems.

PROFESSOR PART TIME - 20H
Nov. 2018 - Apr. 2019

- Teach class for the course: Industrial Mechatronics.
- Subjects: Analog Electronics and Digital Eletronic.

ÁREA1|Wyden College
Salvador, BA

LABORATORY TECHNICIAN
Jul. 2013 - Aug. 2017

- Prepare and teach practical classes for the courses: Computer Engineering, Electrical Engineering and Automation Engineering.
- Test new tools used in laboratories and provide training.
- Provide extension courses and the experience program.

Alfamed Eletromedicina
Salvador, BA

ENGINEER - TECHNICAL RESPONSIBLE
Aug. 2013 - Feb. 2015

- Technical responsible for the company.
- Electronic maintenance in hospital bio-imaging equipment.

Centro Territorial de Educação Profissional da Região Metropolitana CETEP-RM
Camaçari, BA

TEACHER - 40H
jun. 2011 - jun. 2013

- Teach classes in the following subjects: Analog and digital electronics; Microcontrollers; Electric circuits.
- Guide students in their course completion work.

Languages

Portuguese	Native.
English	B1 level - CEFR.

Courses

2021	**FPGA INTEL Training(20h)**, Macnica DHW - Official Training Center FPGA INTEL	*Florianópolis, SC*
2018	**NucLi - English. listening comprehension (32h)**, Federal University of Bahia - UFBA	*Salvador, BA*
2018	**Programa Idiomas sem Fronteiras: My English Online - Level 4 (120h)** , Ministry of Education - MEC.	*Brasil*
2010	**Study of Device Control via parallel, serial and USB ports (60h)**, Faculdade ÁREA1.	*Salvador, BA*
2010	**Applied Analog Electronics (30h)**, Faculdade ÁREA1.	*Salvador, BA*

Projects and Research

SENAI CIMATEC   *Salvador, BA*

FLATFISH - SIPEM   *Oct. 2023 - currently*

- Mobile underwater robotics development project.
- Development in C/C++ language.
- Tools: Gitlab, Docker, Hyro.

SUBOT - CTG BRASIL (CHINA THREE GORGES CORPORATION)   *Oct. 2021 - Sep. 2023*

- Mobile robotics development project for inspection of high voltage substations.
- Development of ROS nodes in C/C++ and Python language.
- Hardware and firmware development for actuator systems and peripheral communication.
- Electronic and mechanical project development.

DIGISUB - PETROBRAS   *Apr. 2019 - Oct. 2021*

- 3D digitizer development project of underwater surfaces in deep water.
- Development of ROS nodes in C/C++ and Python language.
- Hardware and firmware development for actuator systems and peripheral communication.
- Prototype power system sizing: sources, AC-DC/DC-DC converters, batteries.

Polytechnic School of the Federal University of Bahia - UFBA   *Salvador, BA*

MASTER'S PROJECT   *Dec. 2018 - Dec. 2022*

- 1 GigE communication development between FPGA and ROS.
- Hardware project in verilog for implementation in SOC/FPGA (Cyclone V - Intel).
- Socket programming in C/C++ language for linux.
- Development of ROS nodes in C/C++ language.
- Paper presented at *IBERCHIP 2022*.

Faculty of Science and Technology - ÁREA1   *Salvador, BA*

UNDERGRADUATE RESEARCH SCHOLARSHIP   *Jul. 2011 - Jul. 2013*

- Development of a microcontrolled command to fit old X-ray equipment to current technical standards.
- Programming 8051 family microcontrollers in assembly language.
- Research of the technical standards established by ANVISA in relation to X-ray equipment.
- Presentation of monthly reports with activities developed in the period.
- Publication of the results in an article in the journal *Cientefico ISSN 1677-1591, jul/dez 2013*.

Skills and Abilities

Basic	Verilog HDL, Cyclone V, Sockets, Cmake, GDB, Nios II, Embedded Linux, SimuLink.
Intermediate	Python, 3D CAD, Quartus Prime, RTOS, OOP, Linux, Git/Github, PIC, AutoCAD, ROS/Gazebo.
Advanced	PCB/KiCad, Matlab, C/C++, AVR, 8051, ARM Cortex M, GNU-Make, LaTeX.

Honors & Awards

2022	**PETROBRAS**, Prêmio Inventor 2022 - Award for filing a patent for an underwater 3D scanner	*Rio de Janeiro, Brasil*

Presentation

- Communication between Robot Operating System - ROS and SoC with integred FPGA