# M.Sc Nestor D. Pereira Neto

ELECTRONIC ENGINEER · 38

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"Graduated in Electronic Engineering (2013) and specializing in Biomedical Engineering (2019). My professional journey includes practical experience in the maintenance of diagnostic imaging hospital equipment, along with a stint in teaching technical and higher education courses since 2011. Recently, I earned a Master's in Electrical Engineering with a focus on computing and robotics (2022), propelling me into the realm of research and development in robotics since 2019. My expertise spans hardware description, digital signal processing, C/C++ programming, embedded systems, and mobile robotics."

# **Education**

### Federal University of Bahia - UFBA

Salvador, BA

DOCTORATE DEGREE IN ELECTRICAL ENGINEERING - RESEARCH LINE: MACHINE LEARNING AND DIGITAL SIGNAL PROCESSING

Fev. 2023 - Mar. 2027

Development triggered event algorithm based on FPGA for the ATLAS experiment at the Large Hadron Collider (LHC-CERN).

MASTER'S DEGREE IN ELECTRICAL ENGINEERING - RESEARCH LINE: COMPUTING AND ROBOTICS

Apr. 2018 - Dec. 2022

Oct. 2017 - Feb. 2019

• Communication between *Robot Operating System - ROS* and *System-on-a-chip - SoC* with integrated FPGA.

Estácio de Sá University

Salvador, BA

Convolutional Neural Network for Detection of QRS Complexes in Electrocardiogram Signals

# Faculty of Science and Technology - ÁREA1

Salvador, BA

BACHELOR'S DEGREE IN ELECTRONIC ENGINEERING

SPECIALIZATION IN BIOMEDICAL ENGINEERING

Feb. 2008 - Jul. 2013

• Command prototype to fit X-ray equipment to the standards required by the National Health Surveillance Agency - ANVISA.

# **Professional Experiences**

Oceaneering Rio de Janeiro, RJ

Software Engineer R&D

Dec. 2023 - currently

· Development robotics solutions using the ROS2 with expertise in Gazebo Simulation, ROS2 control, SLAM and URDF/Xacro.

SENAI - CIMATEC Salvador, BA

SPECIALIST II - ROBOTIC ENGINEERING

Apr. 2022 - Dec. 2023

- $\bullet \ \ \, \text{Development robotics solutions using the ROS2 with expertise in Gazebo Simulation, ROS2 control, SLAM and URDF/Xacro.}$
- Software and firmware development using C/C++ and python, to ensure integration and functionality of robotic systems.
- Collaborating closely with cross-functional teams guiding trainees and fellows.

CONSULTANT II - ROBOTIC ENGINEERING

Apr. 2019 - Apr. 2022

Nov. 2018 - Apr. 2019

- Development robotics solutions using the ROS2 with expertise in Gazebo Simulation, ROS2 control, SLAM and URDF/Xacro.
- Software and firmware development using C/C++ and python, to ensure integration and functionality of robotic systems.

PROFESSOR PART TIME - 20H

• Teach class for the course: Industrial Mechatronics. Subjects: Analog Electronics and Digital Eletronic.

Salvador, BA

ÁREA1|Wyden College
Laboratory technician

Jul. 2013 - Aug. 2017

- Prepare and teach practical classes for the courses: Computer Engineering, Electrical Engineering and Automation Engineering.
- Test new tools used in laboratories and provide training, extension courses

### Alfamed Eletromedicina

Salvador, BA

ENGINEER - TECHNICAL RESPONSIBLE

Aug. 2013 - Feb. 2015

- Technical responsible for the company.
- · Electronic maintenance in hospital bio-imaging equipment.

### Centro Territorial de Educação Profissional da Região Metropolitana CETEP-RM

Camaçari, BA

TEACHER - 40H

jun. 2011 - jun. 2013

- Teach classes in the following subjects: Analog and digital electronics; Microcontrollers; Electric circuits.
- Guide students in their course completion work.

# **Languages**

Portuguese Native.

**English** B1 level - CEFR.

### Courses\_

2021	FPGA INTEL Training(20h), Macnica DHW - Official Training Center FPGA INTEL	Florianópolis, SC
2018	NucLi - English. listening comprehension (32h), Federal University of Bahia - UFBA	Salvador, BA
2018	Programa Idiomas sem Fronteiras: My English Online - Level 4 (120h), Ministry of Education - MEC.	Brasil
2010	Study of Device Control via parallel, serial and USB ports (60h), Faculdade ÁREA1.	Salvador, BA
2010	Applied Analog Electronics (30h), Faculdade ÁREA1.	Salvador, BA

# **Projects and Research**

**SENAI CIMATEC** Salvador, BA

Oct. 2023 - Dec. 2023 FLATFISH - SIPEM

- Mobile underwater robotics development project.
- Development in C/C++ language.
- Tools: Gitlab, Docker, Robotic Framework, Fast DDS.

#### SuBot - CTG Brasil (China Three Gorges Corporation)

Oct. 2021 - Sep. 2023

- Mobile robotics development project for inspection of high voltage substations.
- Development in C/C++; firmware for peripheral communication; Electrical design.
- Tools: GitHub, ROS2, Gazebo, Mbed, SolidWorks Electrical.

DIGISUB - PETROBRAS Apr. 2019 - Oct. 2021

- 3D digitizer development project of underwater surfaces in deep water.
- $\bullet \ \ \text{Development in C/C++; firmware for peripheral communication; Electrical design.}$
- Tools: GitHub, ROS1, Gazebo, PCL, KiCad.

#### Polytechnic School of the Federal University of Bahia - UFBA

Salvador, BA

MASTER'S PROJECT

Dec. 2018 - Dec. 2022

- 1 GigE communication development between FPGA and ROS.
- Development in C/C++ language; Hardware project in verilog for SOC/FPGA; Paper presented at IBERCHIP 2022.
- Tools: Quartus, GitHub, C/C++ Socket, Cyclone V Intel, Network protocols.

#### Faculty of Science and Technology - ÁREA1

Salvador BA

UNDERGRADUATE RESEARCH SCHOLARSHIP

Jul. 2011 - Jul. 2013

- · Development of a microcontrolled command to fit old X-ray equipment to current technical standards established by ANVISA.
- Programming 8 bits microcontrollers; Electronic project; Hardware prototipe; Publication in Cientefico ISSN 1677-1591, jul/dez 2013.
- Tools: 8051, KiCad, Assembly programming language.

# Skills and Abilities

Basic Verilog HDL, Cyclone V, Sockets, Cmake, GDB, Nios II, Embedded Linux, SimuLink.

Intermediate Python, 3D CAD, Quartus Prime, RTOS, OOP, Linux, Git/Github, PIC, AutoCAD, ROS/Gazebo.

**Advanced** PCB/KiCad, Matlab, C/C++, AVR, 8051, ARM Cortex M, GNU-Make, LaTeX.

## **Presentation**

### 28th IBERCHIP Workshop IEEE CIRCUITS AND SYSTEMS SOCIETY IN LATIN AMERIACA

Santiago, Chile

1-4 Mar. 2022

• Communication between Robot Operating System - ROS and SoC with integred FPGA

### **Honors & Awards**

2022 PETROBRAS, Prêmio Inventor 2022 - Award for filing a patent for an underwater 3D scanner Rio de Janeiro Brasil