1 point

1. What do you think applying this filter to a grayscale image will do?

$$\begin{bmatrix} 0 & 1 & -1 & 0 \\ 1 & 3 & -3 & -1 \\ 1 & 3 & -3 & -1 \\ 0 & 1 & -1 & 0 \end{bmatrix}$$

- ○ Detect horizontal edges
- ◉ Detect vertical edges
- ○ Detect image contrast
- ○ Detect 45 degree edges

---

1 point

2. Suppose your input is a 300 by 300 color (RGB) image, and you are not using a convolutional network. If the first hidden layer has 100 neurons, each one fully connected to the input, how many parameters does this hidden layer have (including the bias parameters)?

- ○ 9,000,001
- ○ 9,000,100
- ○ 27,000,001
- ◉ 27,000,100

---

1 point

3. Suppose your input is a 300 by 300 color (RGB) image, and you use a convolutional layer with 100 filters that are each 5x5. How many parameters does this hidden layer have (including the bias parameters)?

- ○ 2501
- ○ 2600
- ○ 7500
- ◉ 7600

---

1 point

4. You have an input volume that is 63x63x16, and convolve it with 32 filters that are each 7x7, using a stride of 2 and no padding. What is the output volume?

- ○ 16x16x16
- ○ 29x29x16
- ◉ 29x29x32
- ○ 16x16x32

---

1 point

5. You have an input volume that is 15x15x8, and pad it using "pad=2." What is the dimension of the resulting volume (after padding)?

- ○ 19x19x12
- ○ 17x17x8
- ◉ 19x19x8
- ○ 17x17x10

---

1 point

6. You have an input volume that is 63x63x16, and convolve it with 32 filters that are each 7x7, and stride of 1. You want to use a "same" convolution. What is the padding?

- ○ 1
- ○ 2
- ◉ 3
- ○ 7

---

1 point

7. You have an input volume that is 32x32x16, and apply max pooling with a stride of 2 and a filter size of 2. What is the output volume?

- ◉ 16x16x16
- ○ 15x15x16
- ○ 32x32x8
- ○ 16x16x8

---

1 point

8. Because pooling layers do not have parameters, they do not affect the backpropagation (derivatives) calculation.

- ○ True
- ◉ False

---

1 point

9. In lecture we talked about "parameter sharing" as a benefit of using convolutional networks. Which of the following statements about parameter sharing in ConvNets are true? (Check all that apply.)

- ☑ It allows a feature detector to be used in multiple locations throughout the whole input image/input volume.
- ☑ It reduces the total number of parameters, thus reducing overfitting.
- ☐ It allows gradient descent to set many of the parameters to zero, thus making the connections sparse.
- ☐ It allows parameters learned for one task to be shared even for a different task (transfer learning).

---

1 point

10. In lecture we talked about "sparsity of connections" as a benefit of using convolutional layers. What does this mean?

- ○ Each layer in a convolutional network is connected only to two other layers
- ○ Regularization causes gradient descent to set many of the parameters to zero.
- ○ Each filter is connected to every channel in the previous layer.
- ◉ Each activation in the next layer depends on only a small number of activations from the previous layer.

☑ I, **NAN XIAO**, understand that submitting work that isn't my own may result in permanent failure of this course or deactivation of my Coursera account.

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