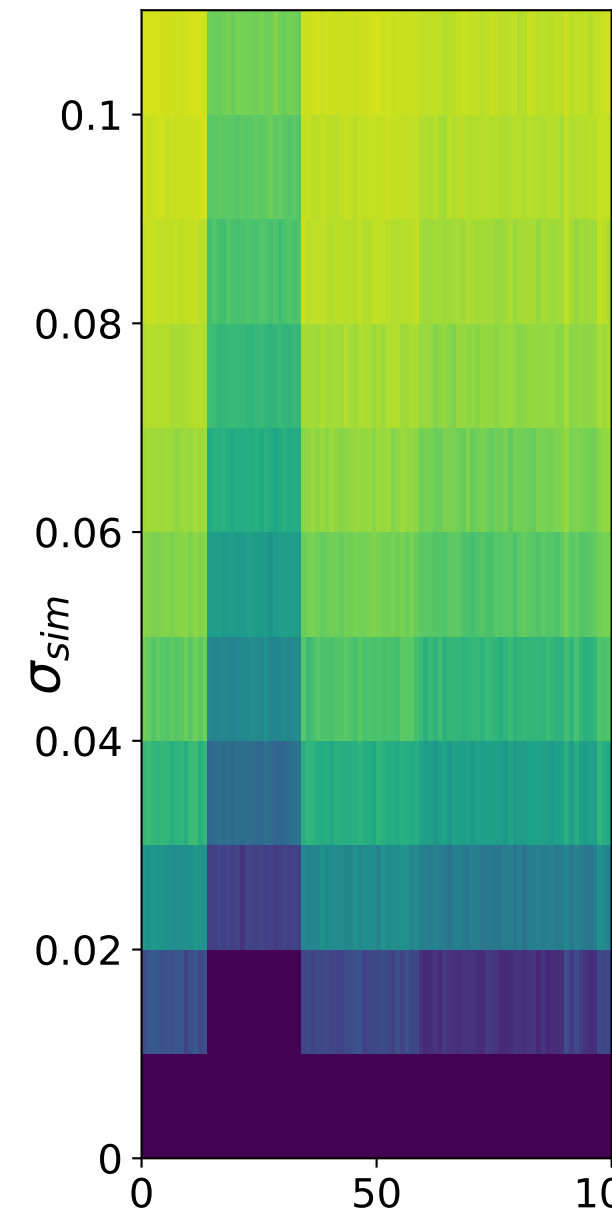
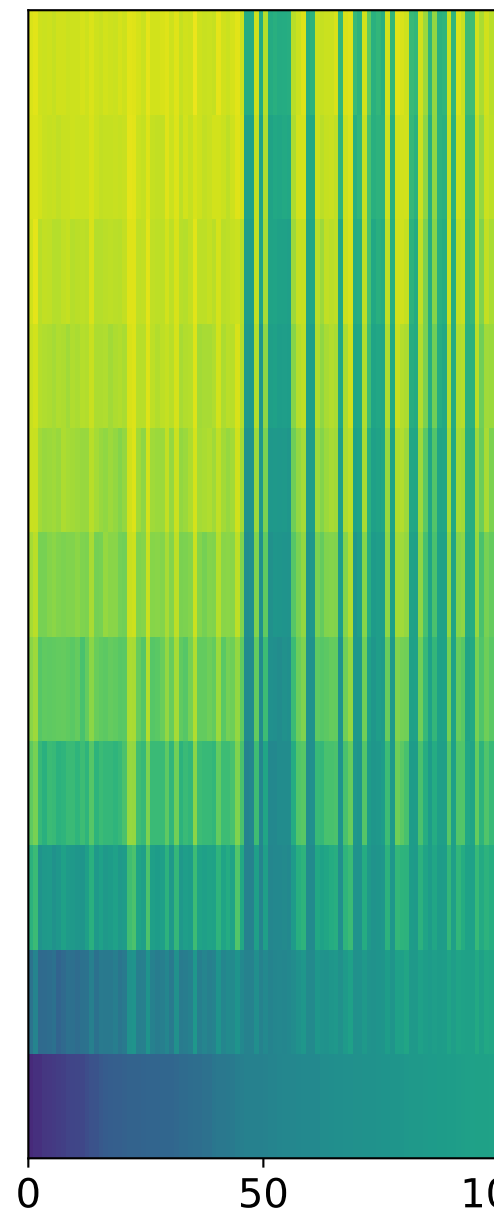
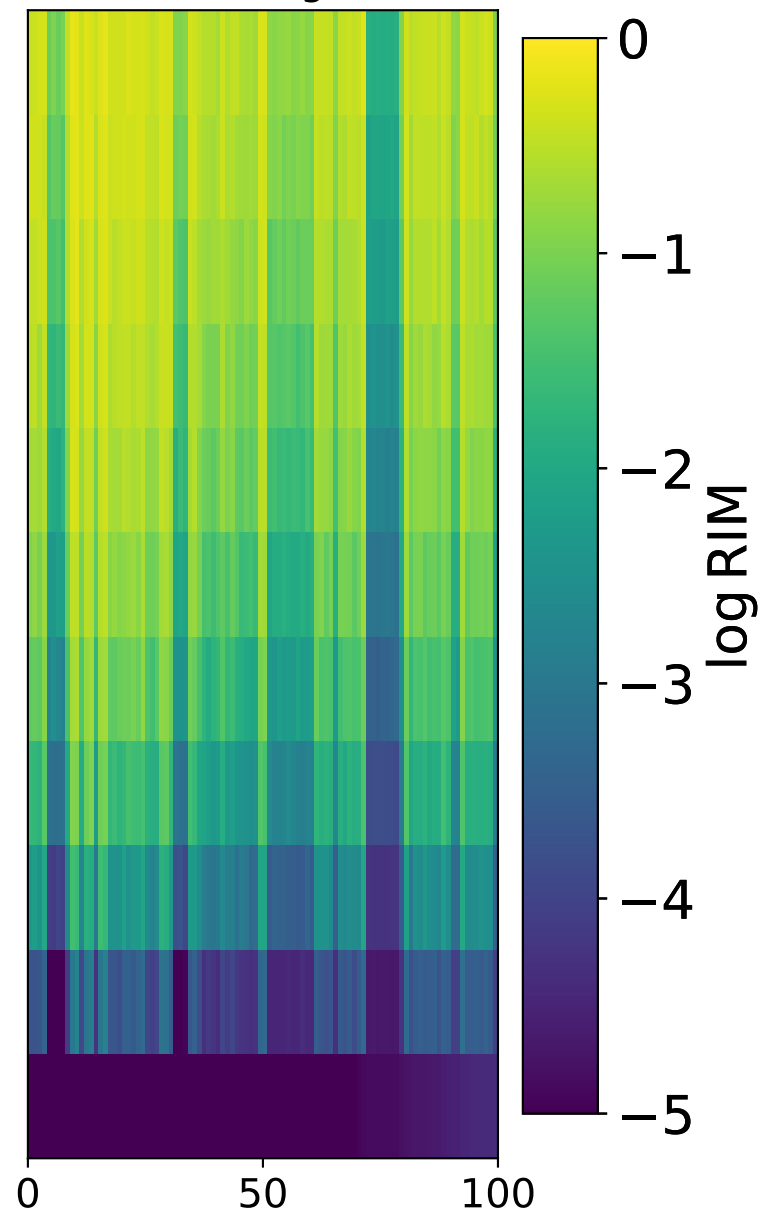


(a) nm $\sigma_{train}=0.0$ (b) snob $\sigma_{train}=0.0$ (c) ppo $\sigma_{train}=0.0$ 

(d) lbfgs



controller