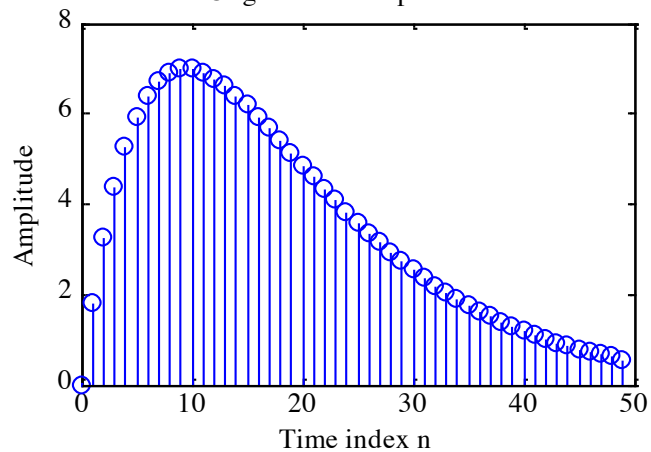
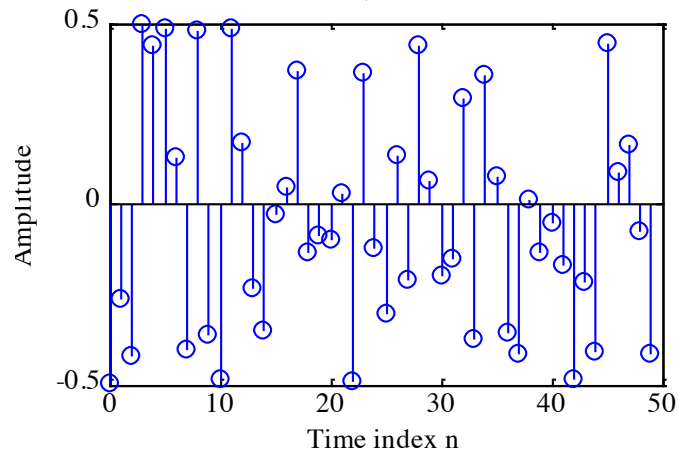


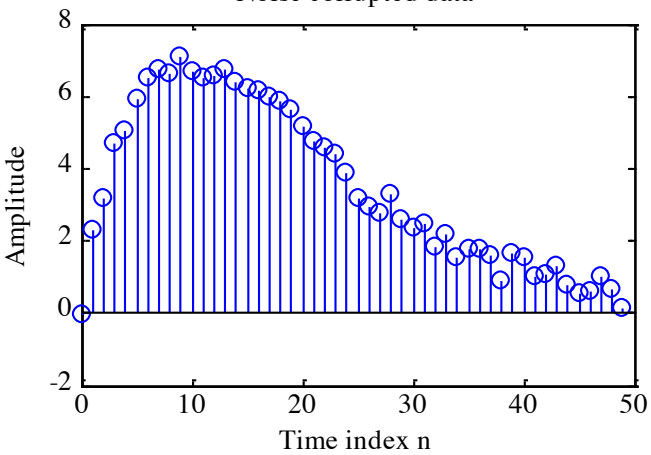
Original uncorrupted data



Noise



Noise corrupted data



Ensemble average

