## **MIRCV** questions:

13.01.2021

### Gennaro:

- vector space model
- text surrogate

#### Falchi:

- local detectors: an introduction, harris, does harris compute the eigenvalues?
- features matching (every step to match 2 images)( filtering for binary and not binary descriptors, ransac for transformation, evaluation metrics. example of the shampoo logo seen at lesson)
- semantic segmentation, object detection
- Tell me about the detectors of features....
- o Cascade classifier for face recognition
- False positives and false negatives (do you have several? Why?)
- Deep learning in general, when we need it and when only
- Representation learning? (seen in class!)
- o The features in which learning algorithm are classified?
- o The use of features extracted from a level of machine learning, at which level
- are they classified? (also seen in class → I think it was the last level)
- o Algorithm to be used for the aggregation of local features
- • Where do the features come from? What is that algorithm called?
- • Convolutional network in deep learning, what is convolution? the filters inside it
- layer (relative to a single window?) How big are they?

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## Amato:

- PP index
- MI file
- M tree
- M tree knn search

#### 29.01.2021

## Amato:

- object-pivot
- pivot-filtering
- AESA
- LSH
- PSR

# Falchi:

- Segmentation vs Object Detection, Deep learning methods to implement them
- Transfer Learning

#### Gennaro:

- Precision, Recall, Accuracy, MAP, Average Precision
- How to use Lucene with Permutations

- -LSH index made on main or secondary memory? (Project) -Vantage Point -Vantage Point Forest
- -LSH index: Buckets stored on disk? (Project) -How would create an LSH index -What involves the variation of the parameters g or h
- -LSH: how are buckets implemented? (Project) -What structure would you use to make the buckets? What other hashing-based indices have we seen? -D-Index
- -LSH: how are buckets made? where to store them? RAM or disk? (Project) -ESA / EASA indices
- -D-Index and hashing-based indexes -Cost (in terms of disk accesses) of an index insert (D-Index) -Index search algorithm (D-Index)
- -PP-Index: how the search algorithm was created (Project) -PP-Index index construction PP-Index optimization -Similarities / Differences with respect to hashing-based indices
- -LSH: How did you perform the index search (Project) -PP-Index -Vantage Point Tree

between local features and various distances 2) convolutional NN (pooling, conv-layer, stride) 3) detection and segmentation, object detection (RNN, fastRNN, fasterRNN) 4) transfer learning, domain adaptation 5) detection of local features (blob, corner and a third)

- 6) features matching, overlapping 7) aggregation of local features (Bag of words, vlad, and a third)
- 1. Detection and segmentation approach that doesn't work fully convolutional NN transpose convolution RCNN, fastRCNN, ... 2. How to detect local features types of regions (flat, corner, ...) Harris and the index R to not calculate the eigenvalues Surf and sift 3. How to match the local features after the extraction phase hamming distance to compute the distance binary descriptor & NON binary descriptor

## Gennaro - Elastic search SRT - Evaluation of a classifier through confusion matrix - Audio Retrieval (done to a complete oral (without project)) - Boolean Retrieval, merge algorithm for and retrieval - How do you evaluate information retrieval system? ------------1) boolean retrieval: what is the merge algorithm, what is it for -> AND between two far terms and contextualization, what is it for in general, what is the goal of this algorithm we imagine that they are sets: what kind of set operation are we doing? -> INTERSECTION if the lists are not ordered what complexity do we have? What algorithm should I apply (stupid) -> POLYNOMIAL complexity; I order the docld and I have complexity N (linear) 2) When we talked about the cosine similarity with vector model (tf-idf ..), we saw two algorithms: the merge alg. remember one of the two, which one? And what about the other one? 3) What are positional indexes and what are they for 4) Precision and recall 5) approximate search neighbors: starting from permutations, how do you get to this approach? types of index? ppindex, inverted-file surrogate (text representation), what is the goal? Compared to the mi-file technique, what have I optimized (big practical advantage)? 6) Do you remember anything about the audio retrieval? 7) Permutations for the approximate search neighbors How the mi-file works 8) Technique used by Shazam for the audio retrieval 9) Difference between boolean retrieval & vector space model 10) What is document frequency and the inverse doc.freq.