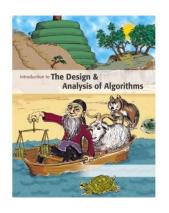




Introduction to

Algorithm Design and Analysis

[13] Undirected Graph



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In the Last Class...

- Directed Acyclic Graph
 - o Topological Order
 - o Critical Path Analysis

- Strongly Connected Component
 - Strong Component and Condensation
 - o Finding SCC based on DFS



DFS on Undirected Graph

Undirected Graph

- o Symmetric Digraph
- o Undirected Graph DFS Skeleton

Biconnected Components

- o Articulation Points
- o Bridge

Other undirected graph problems

- o Orientation of an undirected graph
- o Simplified Minimum Spanning Tree



What is Different for "Undirected"

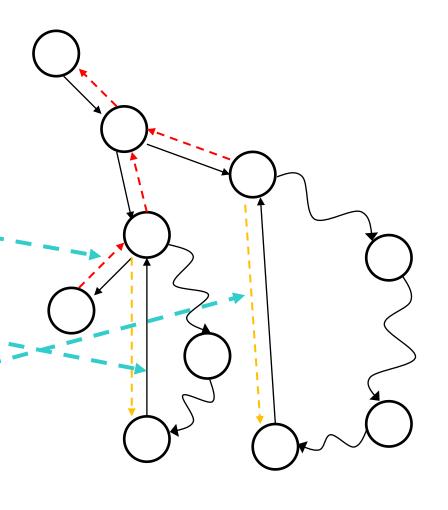
- Characteristics of undirected graph traversal
 - o One edge may be traversed for two times in opposite directions.
- For an undirected graph, DFS provides an orientation for each of its edges
 - o Oriented in the direction in which they are first encountered.



Edges in DFS

- CE
 - o Not existing
- BE
 - Back to the direct parent:
 second encounter
 - Otherwise: first encounter
- DE
 - Always second

 encounter, and first time
 as back edge





Modifications to the DFS Skeleton

- All the second encounter are bypassed.
- So, the *only substantial modification* is for the possible back edges leading to an ancestor, but not direct parent.
- We need know the *parent*, that is, the direct ancestor, for the vertex to be processed.

DFS Skeleton for Undirected Graph

- int dfsSweep(IntList[] adjVertices,int n, ...)
- int ans;
- <Allocate color array and initialize to white>
- For each vertex v of G, in some order
- if (color[v]==white)
- int vAns=dfs(adjVertices, color, v,(-1,)...);
- <Process vAns>
- // Continue loop
- return ans;

Recording the parent



DFS Skeleton for Undirected Graph

```
int dfs(IntList[] adjVertices, int[] color, int v, int p, ...)
  int w; IntList remAdj; int ans;
  color[v]=gray;
  <Pre><Pre>reorder processing of vertex v>
  remAdj=adjVertices[v];
  while (remAdj≠nil)
    w=first(remAdj);
    if (color[w]==white)
      <Exploratory processing for tree edge vw>
      int wAns=dfs(adjVertices, color, w, v ...);
      < Backtrack processing for tree edge vw , using wAns>
    else if (color[w]==gray && w≠p)
      <Checking for nontree edge vw>
    remAdj=rest(remAdj);
  <Postorder processing of vertex v, including final computation of ans>
  color[v]=black;
  return ans;
```



Complexity of Undirected DFS

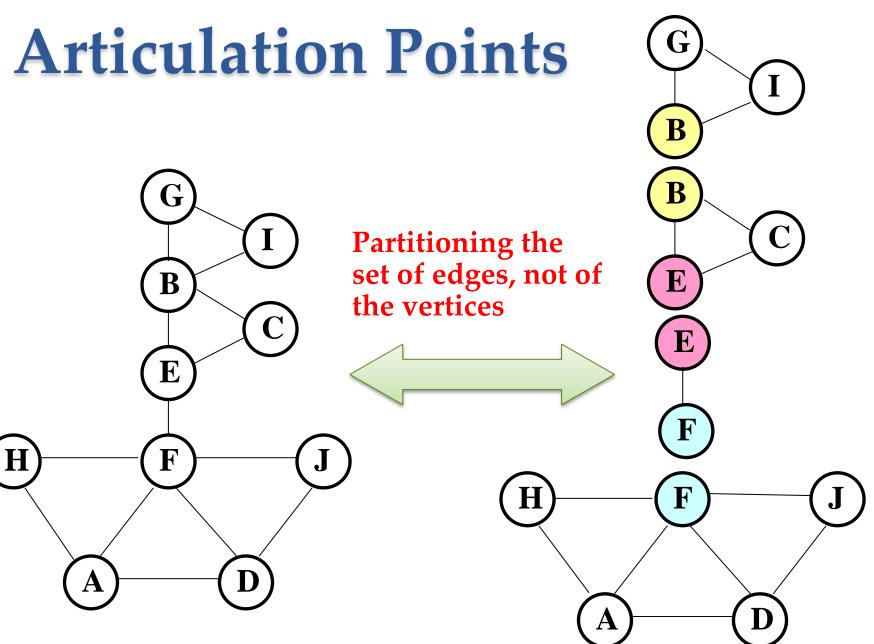
- $\Theta(m+n)$
 - If each inserted statement for specialized application runs in constant time
 - o The same with directed graph DFS
- Extra space $\Theta(n)$
 - o For array *color*, or activation frames of recursion.



Biconnected Graph

- Being connected
 - o Tree: acyclic, least (cost) connected
 - o Node/edge connected: fault-tolerant connection
- Articulation point (2-node connected)
 - o *v* is an articulation point if deleting *v* leads to disconnection
- Bridge (2-edge connected)
 - o *uv* is a bridge if deleting *uv* leads to disconnection



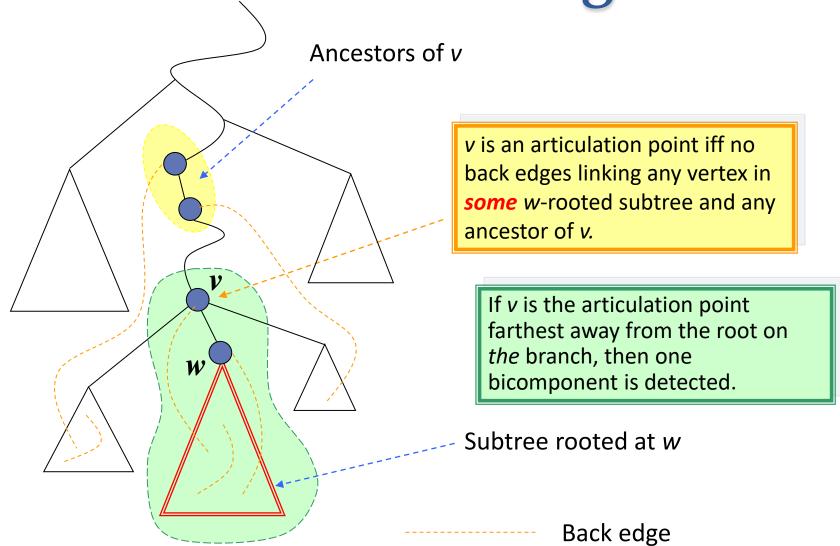


Definition Transformation

- "Short definition"
 - o Deleting v leads to disconnection
- "Long definition"
 - o If there **exist** nodes *w* and *x*, such that *v* is in **every** path from *w* to *x* (*w* and *x* are vertices different from *v*)
- "Longer definition" or "DFS definition"
 - No back edges linking any vertex in some w-rooted subtree and any ancestor of v



Articulation Point Algorithm



Updating the value of back

- v first discovered back=discoverTime(v)
- Trying to explore, but a back edge vw from v encountered

back=min(back, discoverTime(w))

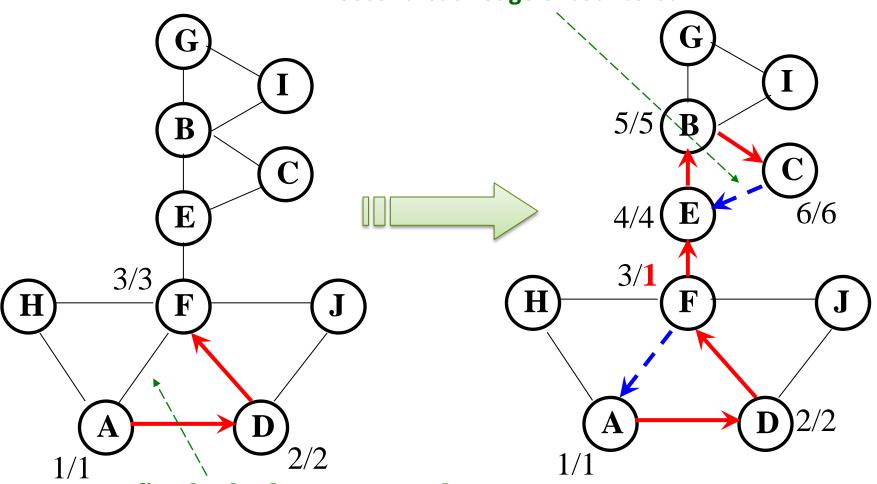
Backtracking from w to v

back=min(back, wback)

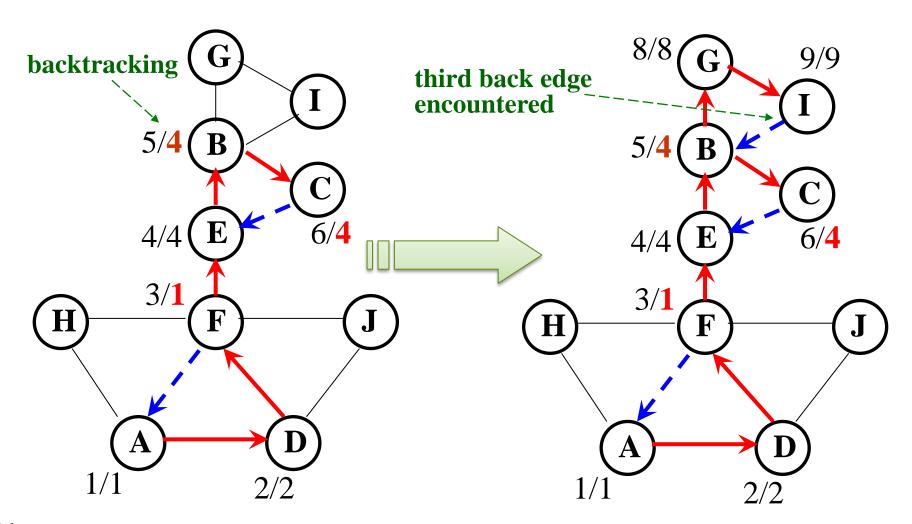
The back value of v is the smallest discover time a back edge "sees" from any subtree of v.



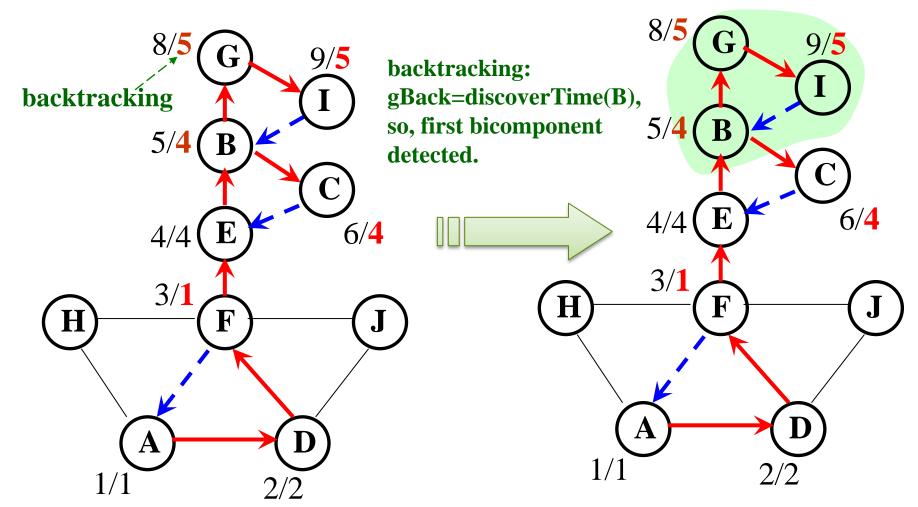
second back edge encountered













Keeping the Track of Backing

Tracking data

o For each vertex v, a local variable back is used to store the required information, as the value of discoverTime of some vertex.

Testing for bicomponent

 At backtracking from w to v, the condition implying a bicomponent is:

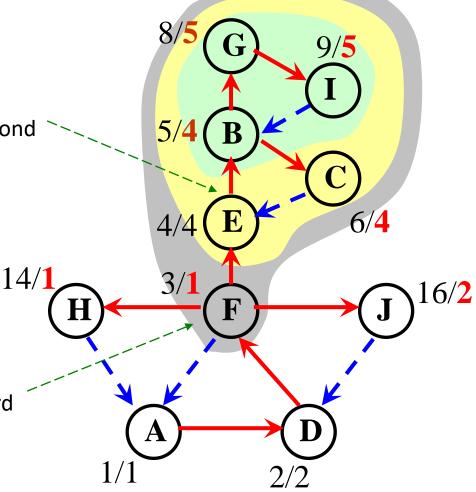
wBack ≥ discoverTime(v)
 (where wBack is the returned back value for w)

when back is no less than the discover time of v, there is at least one subtree of v connected to other part of the graph only by v.



Backtracking from B to E: bBack=discoverTime(E), so, the second bicomponent is detect

Backtracking from E to F: eBack>discoverTime(F), so, the third bicomponent is detect





Articulation Point Algorithm

Algorithm 12: ARTICULATION-POINT-DFS(v)

```
1 v.color := \mathsf{GRAY};
2 time := time + 1;
v.discoverTime := time;
4 v.back := v.discoverTime;
5 foreach neighbor w of v do
      if w.color = WHITE then
 6
         w.back := ARTICULATION-POINT-DFS(w);
 7
         if w.back \geq v.discoverTime then
 8
            Output v as an articulation point ;
 9
         v.back := min\{v.back, w.back\};
10
      else
11
                                                    /* w 是 v 非父节点的祖先节点 */
         if vw is BE then
12
            v.back := min\{v.back, w.discoverTime\} \ ;
13
14 return back;
```



Correctness

We have seen that:

o If v is the articulation point farthest away from the root on the branch, then one bicomponent is detected.

So, we need only prove that:

 In a DFS tree, a vertex(not root) v is an articulation point if and only if (1) v is not a leaf; (2) some subtree of v has no back edge incident with a proper ancestor of v.

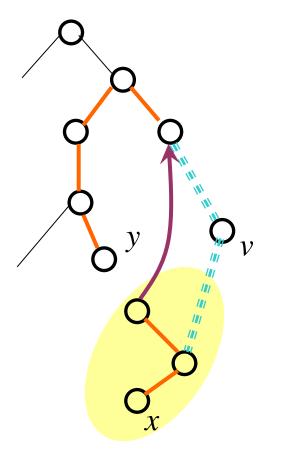


Characteristics of Articulation Point

- In a DFS tree, a vertex(not root) v is an articulation point if and only if (1)v is not a leaf; (2) some subtree of v has no back edge incident with a proper ancestor of v.
- ← Trivial
- **⇒**
 - o By definition, v is on **every** path between some x,y(different from v).
 - At least one of x,y is a proper descendent of v(otherwise, $x \leftrightarrow root \leftrightarrow y$ not containing v).
 - o By contradiction, suppose that **every** subtree of *v* has a back edge to a proper ancestor of *v*, we can find a *xy*-path not containing *v* for all possible cases(only 2 cases)

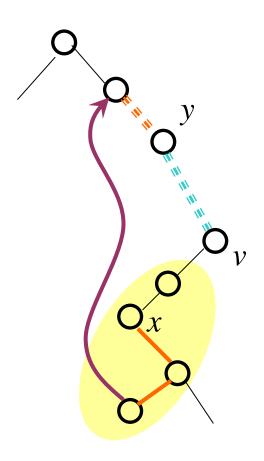


Case 1



every subtree of v has a back edge to a proper ancestor of v, and, exactly one of x, y is a descendant of v.

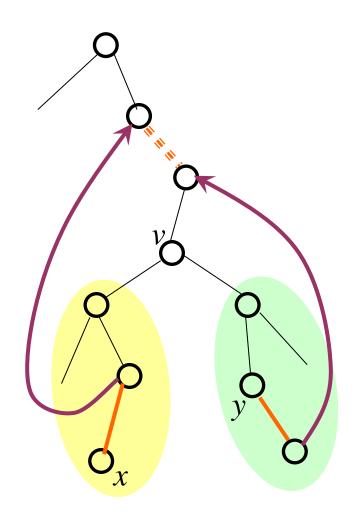
Case 1.2: another is an ancestor of *v*



Case 1.1: another is not an ancestor of *v*

Case 2

suppose that **every**subtree of *v* has a back
edge to a proper ancestor
of *v*, and, both *x*, *y* are
descendants of *v*.

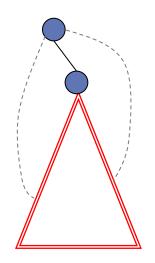


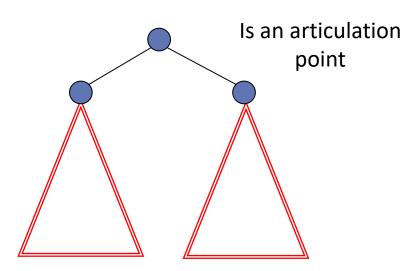


What about the root?

- One single DFS tree
 - We only consider each connected component
- Root $AP \equiv Two \text{ or more sub-tree}$
 - o The root is an articulation point

Not an articulation point







Defining the Bridge

Short definition

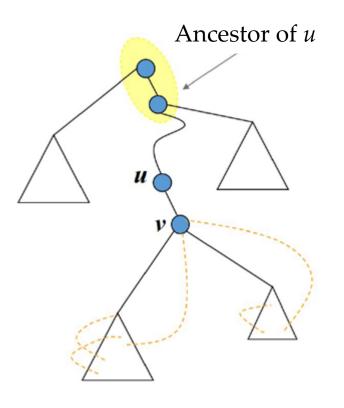
o Removing *uv* leading to disconnection

Long definition

Edge uv is a bridge iff node u
 and v are connected only by uv

DFS Definition

- o Edge uv is a tree edge in DFS
- There is **no** subtree rooted at v to any proper ancestor of v (including u)





Bridge Algorithm

Algorithm 11: BRIDGE-DFS(u)

```
1 u.color := \mathsf{GRAY};
2 time := time + 1;
u.discoverTime := time;
u.back := u.discoverTime;
5 foreach neighbor v of u do
      if v.color = WHITE then
 6
         BRIDGE-DFS(v);
 7
         u.back := min\{u.back, v.back\};
         if v.back > u.discoverTime then
 9
            Output uv as a bridge;
10
      else
11
                                                    /* v 是 u 非父节点的祖先节点 */
         if uv is BE then
12
            u.back := min\{u.back, v.discoverTime\} \ ;
13
```



Other Traversal Problems

Orientation of an undirected graph

- o Give each edge a direction
- o Satisfying pre-specified constraints
 - E.g., the "in-degree of each vertex is at least 1"

Possible or not?

- o If possible, how to?
- As for "in-degree ≥ 1"
 - o Orientation possible iff. the graph has at least a circle
 - Find the end point of some back edge
 - A second DFS from this end point



Other Traversal Problems

MST: Minimum Spanning Tree

- Get MST in O(m+n) time
 - o Given that edges weights are only 1 and 2
- Graph traversal is sufficient
 - o DFS over "weight 1 edges" only
 - o DFS over "weight 2 edges" only



Thank you!

Q & A

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