Eksikler

- IR- Demo (last one) [With the other group]
- Laser security cover
- Cabling (minor)
- Robustness to direct sun light.
- Leave and rejoin (fail safe algorithms) *
  - Does not see
  - The leading robot fails etc.
- Fusion of IR camera
- Robustness tests.
- Leave signal range?
- Trials with the other group!
- Robot Safety!

Eksikler

- IR- Demo (lost one) [with the other group]
- Laser security cover
- Cabling (minor)
- Robustness to direct sun light.
- Leave and rejoin (fail safe algorithms) *
- Fusion of IR camera.
  ↳ Does not see (.)
  ↳ The robot leading robot fails etc.
- Robustness tests.
- Leave signal range?
- Trials with the other group!

→, Robot Safety!