CES-27 Processamento Distribuído

Termination Detection

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Outline

- Motivation
- Dijkstra's Token Algorithm
- Dijkstra-Scholten Algorithm
- Shavit-Francez Algorithm
- Rana's Algorithm

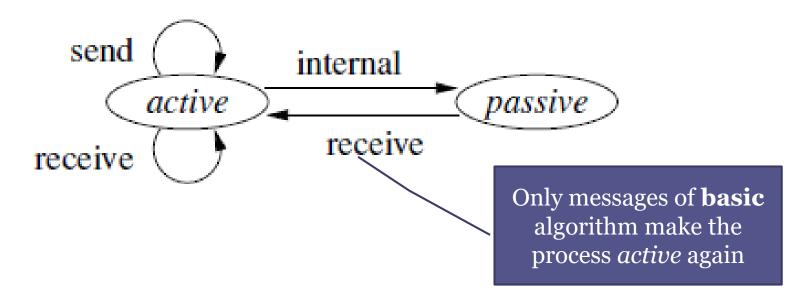
Motivation

Termination detection for <u>diffusing computation</u>

- "The activity of a finite computation may propagate over a network of machines, when machines may delegate (repeatedly) subtasks to their neighbors; when such a computation is fired from a single machine, we call it a <u>diffusing computation</u>" (Dijkstra & Scholten, 1979)
- A <u>distributed algorithm</u> is **terminated** if all **processes are in a** terminal state and no messages (basic) are in transit
 - The **basic** algorithm is the algorithm for which termination is being detected
 - The **control** algorithm is the termination detection algorithm employed
- The control algorithm in general consists of two parts:
 - Termination detection ⇒ our focus
 - Announcement ⇒ simple
 - The process, which detects termination, can act as a master
 - Send a terminate message to everyone
 - Collect the results and print them
 - Send a shutdown message to everyone
 - Stop

Motivation

- Termination detection is a fundamental and challenging problem in distributed computing, because no process has complete knowledge of the global configuration of the network
 - A terminated process may be reactivated by a message from another process
 - Ideally, termination detection does not require freezing the basic execution
 - Process model:



The way the wave flows is up to you! It depends on the chosen topology.

E.g. Directed ring

E.g. Undirected ring

Concept: Wave Algorithms

- In wave algorithms, each computation gives rise to one or more decisions in which all processes have a say
 - They can not complete if any process p refuses to take part in its execution
 - In this case, *p* refused because *p* did something (after the wave algorithm started) that not characterizes the decision
- A wave is **initiated by one process**, and in the end one *decide event* happens at the initiator
 - There can be concurrent calls of a wave algorithm, initiated by different processes
 - Then usually for each wave the messages are marked with the ID of its initiator
 - If a wave does not complete, then typically another wave will complete successfully later on

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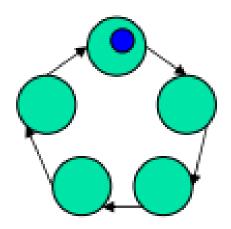
Dijkstra's Token Algorithm

An initial idea:

- Imagine the processes to be arranged in a ring
- Process 1 inserts a token, traveling from process i to process
 i + 1 and back to process 1
- The token only leaves a process if the process turns inactive
- Process 1 determines whether the system can be shut down

That does not work...

- A process may become active after having sent the token
- To fix this: Dijkstra's Token Algorithm!



Remember:

- The ring is used only by the control algorithm (i.e. termination detection)
- In the basic algorithm, processes can communicate with each other (without the ring)

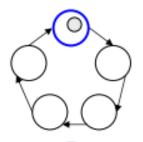
Dijkstra's Token Algorithm

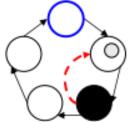
• Algorithm:

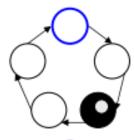
1) When P1 turns inactive, it turns white and sends a white token to P2

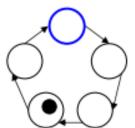


- 2) If Pi sends a message to Pj and j < i, then Pi turns black
 - Pi is a suspect for reactivating process Pj
- 3) If Pi has the token and it is idle, it passes the token. The <u>token</u> becomes <u>black</u> if Pi is <u>black</u>
- 4) After passing tokens, processes become white
 - Indicating that the process is inactive
- 5) The algorithm terminates when P1 receives a white token and it is idle









Dijkstra's Token Algorithm

- Performance: O(N) in time
 - N is the number of processes
- P1 may become active again before getting back the token
 - Is it possible to detect termination wrongly? No!
- For a small number of processes, algorithm is acceptable.
- For large numbers of processes, this becomes a significant overhead
- Messages must be delivered in order for the protocol to work!
- There are similar approaches for this algorithm:
 - J. Misra, "Detecting Termination of Distributed Computations Using Markers", 2nd ACM Symposium on PODC, Aug. 1983.

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Reference: E. W. Dijkstra and C. S. Scholten
 "Termination Detection for Diffusing
 Computations", Information Processing Letters, Vol. 11, No. 1, Aug. 1980.

• Termination detection algorithm for a **centralized basic algorithm** on an **undirected network**.

One process initiated the basic algorithm

We will track messages of the basic algorithm

A process can send/receive messages to/of any other process

An use of spanning tree, where processes are nodes of tree and edges are connections

- The main idea:
 - To build a tree, rooted in the initiator of the basic algorithm
 - The tree contains:
 - all active processes, and
 - passive processes that have active descendants in the tree
 - If a <u>basic</u> message from a process *p* makes a process *q* active, then *q* becomes a child of *p* in the tree
 - A process can quit the tree only if it is passive and has no children left in the tree
 - In that case, it informs its parent that it is no longer a child
 - Termination is detected by the initiator when the tree has disappeared

There are other algorithms that use the concept of spanning tree!

You decide how to implement the tree!

Algorithm:

- Initially the tree T consists only of the initiator
- When p sends a <u>basic</u> message, $cc_p' = cc_p + 1$.

To count my children

- Let this message be received by q:
 - If q isn't yet in T, it joins T with parent p and $cc_q = o$
 - If q is already in T, it sends a <u>control</u> message to p that it isn't a new child of p. Upon receipt of this message, $cc_p = cc_p 1$
- When a **non-initiator** p is **passive** and $\mathbf{cc_p} = \mathbf{o}$, it quits T and informs its parent that it is no longer a child
 - Note: *p* informs its parent using a <u>control</u> message. So its parent decreases cc
- When the **initiator** is passive and cc_{initiator} = 0, termination is detected

Drawback: Requires one control message for every basic message Note: In the next examples, control message is the *ack* (acknowledgement)

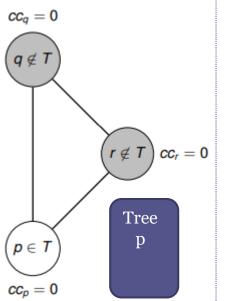
active

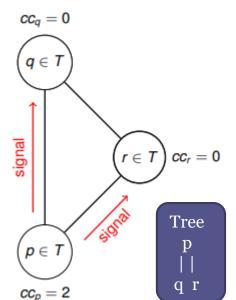


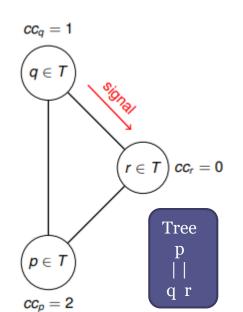
) passive

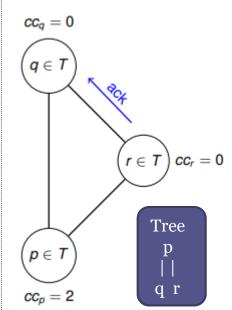
Example:

- Three processes p, q, and r
- Chosen topology: undirected ring
- At the start, the initiator p sends basic messages to q and r, and sets cc_p to 2
 - Upon receipt of these messages, q and r both become active, and join T with parent p
- $^{\circ}$ q sends a basic message to r, and sets cc_q to 1.
- Upon receipt of this message, r sends back an acknowledgment,
 which causes q to decrease cc_q to o

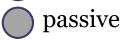






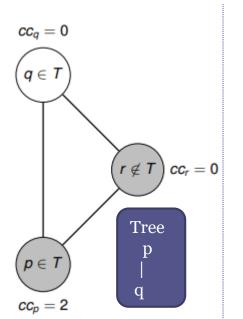


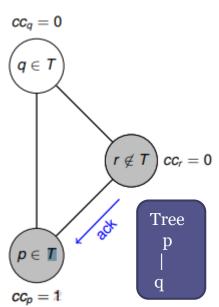
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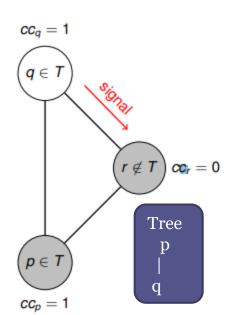


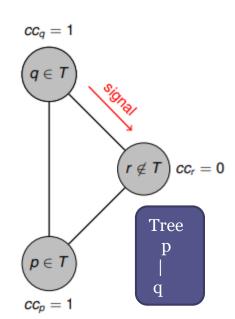
• Example (cont):

- □ p becomes passive. (Since cc_p = 2, it remains in T)
- □ r becomes passive. Since cc_r = 0, it sends an acknowledgment to its parent \vec{p} , which causes p to decrease cc_n to 1
- q sends a basic message to r, and sets cc_q to 1
 q becomes passive (Since cc_q = 1, it remains in T)
- Note that all three processes are now passive, but there is still a message traveling from q to r

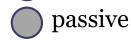






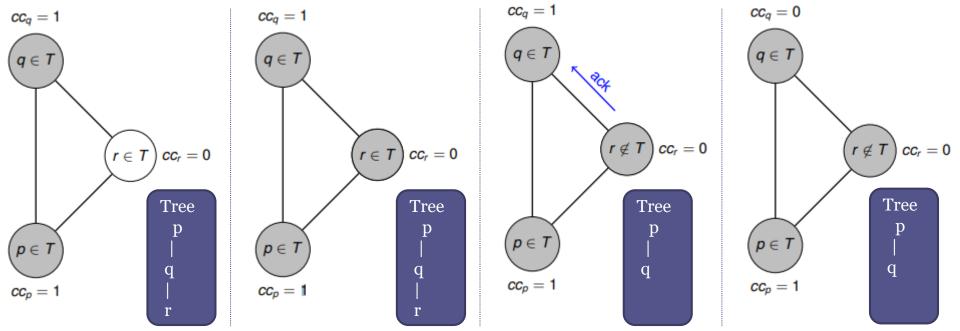


active

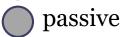


• Example (cont):

- Upon receipt of message from q to r, r becomes active again, and joins T with parent q
- ^p r becomes passive. Since $cc_r = o$, it sends an acknowledgment to its parent q which causes q to decrease cc_q to o



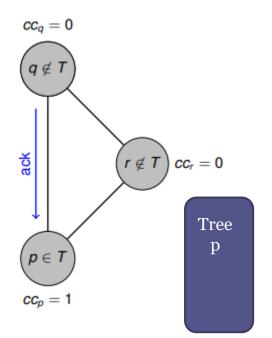
active

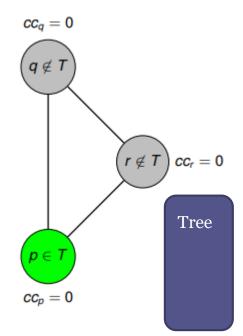


• Example (cont):

Since q is passive and $cc_q = 0$, it sends an acknowledgment to its parent p, which causes p to decrease cc_p to o

• Since p is passive and $cc_p = o$, it detects termination





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Shavit-Francez Algorithm

 It generalizes Dijkstra-Scholten Algorithm to decentralized basic computations (multiple initiators)

• The idea:

- To maintain not one tree, but a forest of (disjoint) trees, one for each initiator
- Initially, each initiator constitutes a tree in the forest
- A process can only join a tree if it is not yet in a tree in the forest
- For the rest, the algorithm proceeds exactly as the Dijkstra-Scholten algorithm

Shavit-Francez Algorithm

• The difference:

- When an initiator detects that its tree has disappeared, it cannot immediately detect termination
 - There can be other trees (with active processes)
- Instead, this initiator starts a wave, tagged with its
 ID
 - · Only processes, which are not in a tree, participate
 - If such a wave does not complete
 - Another initiator of which the tree has not yet disappeared will start a subsequent wave
 - And the last tree to disappear is guaranteed to start a wave that will complete

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 Termination detection algorithm for a decentralized basic algorithm on an undirected network

Any process can initiate the termination detection

A process can send/receive messages to/of any other process

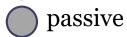
It is an example of a wave algorithm

- The idea:
 - Each <u>basic</u> message is **acknowledged**
 - Lamport's logical clock provides (<u>basic</u> and <u>control</u>) events with a timestamp
 - The timestamp of a process is the **highest timestamp** of its events so far (initially it is 0)
 - Let process p at time t become quiet, i.e. (1) p is passive, and (2) all basic messages it sent have been acknowledged
 - Then *p* starts a wave (of <u>control</u> messages), tagged with *t* (and *p*)
 - Only processes that have been quiet in a time ≤ t take part in the wave
 - If the wave completes, termination is detected

So basic messages do not contribute to logical clocks To avoid a full-blown logical clock!

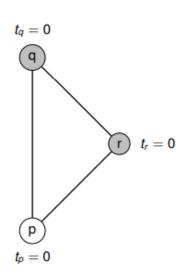
- It suffices that only the <u>control</u> messages (acknowledgments and wave messages) are taken into account in logical clocks
 - A wave tagged with timestamp *t* puts the clock of each recipient to *t* (if its value is not ≥ *t* already)
 - Each acknowledgment is tagged with the timestamp t of the sender and puts the clock of the receiver to t + 1 (if its value is not $\geq t + 1$ already)

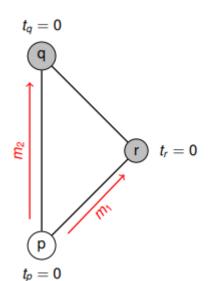
active

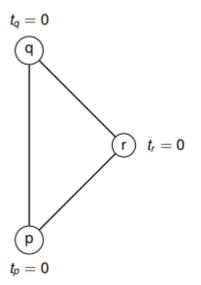


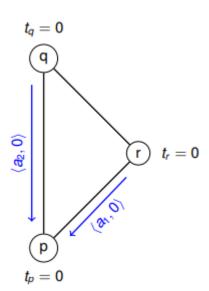
Example

- Consider three processes p, q, and r
- Chosen topology: undirected ring
- Initially, all processes have logical time o, and only p is active
- p sends <u>basic</u> messages m_1 to r and m_2 to q, which make q and r active.
- Next, q and r send an acknowledgment $\langle a_2, o \rangle$ and $\langle a_1, o \rangle$ respectively



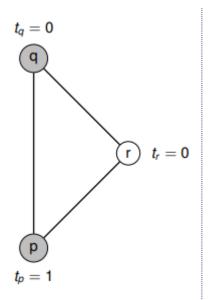


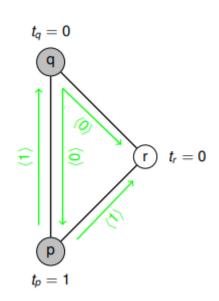


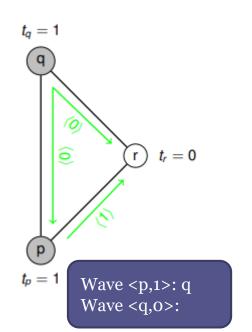


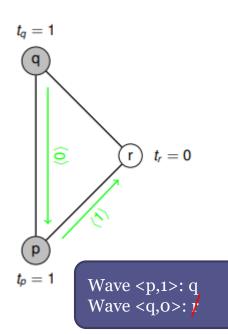
activepassive

- Example (cont)
 - p receives both acknowledgments, setting its time to 1
 - p and q become passive.
 - Next, p and q both start a wave, tagged with 1 and 0, respectively
 - The wave of p first visits q, setting its time to 1
 - q takes part in the wave, because it is quiet from time o onward
 - The wave of *q* first visits *r*
 - r refuses to take part in the wave, because it is active

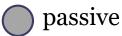




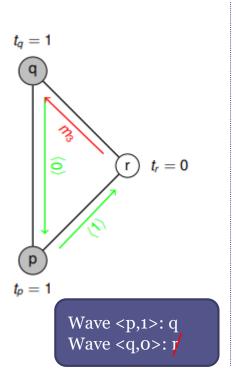


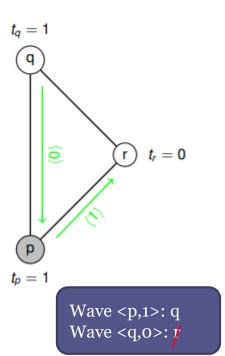


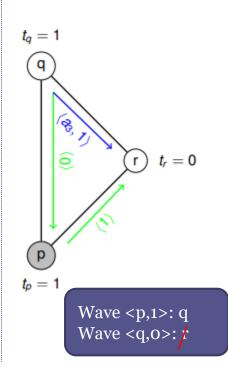
active

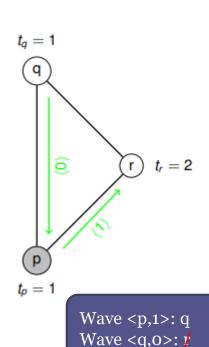


- Example (cont)
 - r sends a basic message m_3 to q
 - Upon receipt of this message, q becomes active and sends back an acknowledgment $\langle a_3, 1 \rangle$.
 - When r receives this acknowledgment, its clock value becomes 2





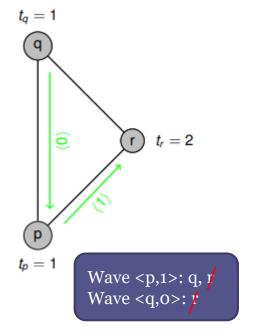


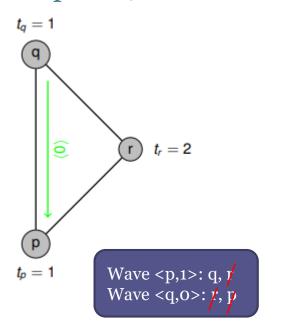


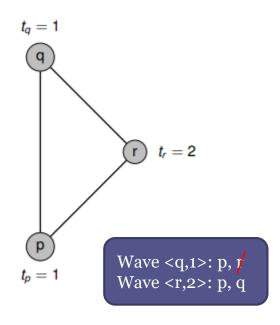
activepassive

Example

- q and r become passive.
- r refuses to take part in p's wave, because r is quiet from time 2 onward, while the wave is tagged with 1
- p refuses to take part in q's wave. Similar reason!
- q and r both start a wave, tagged with 1 and 2, respectively.
- The wave of r completes, and r detects termination







Other algorithms in literature

• Papers:

 Matocha, J. and Camp, T. A taxonomy of distributed termination detection algorithms. The Journal of Systems and Software, 43, 1998

More recent papers

 Hasrat, I.R. and Atif, M. <u>Formal Specification</u> and Analysis of Termination Detection by Weight-throwing Protocol. International Journal of Advanced Computer Science and Applications(IJACSA), Volume 9 Issue 4, 2018.