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Soft Margin SVN vs Loss function-minimizing hyperplane

Recall that the soft margin problem is as follows:

The corresponding dual problem is

[latex](#)
$$\begin{aligned} \text{min} \quad & \frac{1}{2} D^2 \lambda - [1_{\{1 \times n\}} 0_{\{1 \times n\}}] \lambda \\ \text{s.t.} \quad & \lambda_i \geq 0, 1 \leq i \leq 2n \quad \sum_{i=1}^n \lambda_{i+n} = 0 \quad \lambda_{i+n} = C - \lambda_i \end{aligned}$$

`%</latex>`

`%`

`% Here $\lambda \in \mathbb{R}^{2n}$, $D' =$`

`% $\begin{bmatrix} Y Y^T \\ 0 \end{bmatrix} \odot (X X^T)$ & $0_{\{n \times n\}}$`

`% $\end{bmatrix}$. We can eliminate the equality constraint`

`% $\lambda_i + \lambda_{i+n} = C$ by setting`

`% $\lambda_{i+n} = C - \lambda_i$ and combining it with non-negativity`

`% to get $C \geq \lambda_i$ for $1 \leq i \leq n$.`

`% We can thus drop to solving for the first n λ ; the initial guess is $\lambda = 0_{\{n \times 1\}}$ and all the constraints are active.`

`% We also set the penalty constant C to be 0.1 .`

Setting up arguments for ASM.m

`c = 0.2; %Constant in the penalty function`

`y = label; % the label vector`

`n = length(y); % number of data points`

`%D = [(y*y').*((XX * XX')) zeros(n,n); zeros(n,n) zeros(n,n)]; %SPD matrix`

`%`

`% quadratic`

`%`

`D = (y*y').*((XX * XX'));`

`%d = [ones(n,1); zeros(n,1)]; % linear term in Q.P`

`d = ones(n,1);`

`%Ap = [eye(n,n) eye(n,n)]; % the matrix A'`

`%App = [y' zeros(1,n)]; % the matrix A`

`App = y';`

`C = [eye(n,n); -eye(n,n); App]; %matrix of constraints`

`%b = [zeros(2*n + 1,1); c*ones(n,1)]; % vector of constraints`

`b = [zeros(n,1); -c*ones(n,1); 0];`

```

gfun = @(x) D*x - d; %gradient
Hfun = @(x) D; %hessian
%init = [zeros(n,1); c*ones(n,1)]; % initial guess
init = zeros(n,1);
%W = [1:n (2*n + 1):(3*n + 1)]; %set of working constraints at the
    initial point
W = 1:n;
W = W';
% The constraints matrix is a 2n+1 by n matrix
% All constraints are active.
% Time to run the solver!
[lambs, lm] = ASM(init, gfun, Hfun, C, b, W);
soln = lambs(:,end); % extracting the lambda vector
wASM = (XX')*(y .* soln); % optimal w
%Computing B via soft margin support vectors
avg = XX(find(soln == max(soln(find(y==1)))),: ) ...
    + XX(find(soln == max(soln(find(y== -1)))),: );
B = -0.5*(avg * wASM);
wASM = [wASM; B];

```

Plotting the classifier

```

% Plotting the data
idem = find(y== -1);
igop = find(y== 1);
figure;
hold on; grid;
xmin = min(XX(:,1)); xmax = max(XX(:,1));
ymin = min(XX(:,2)); ymax = max(XX(:,2));
zmin = min(XX(:,3)); zmax = max(XX(:,3));
X1 = (XX(:,1)-xmin)/(xmax-xmin);
X2 = (XX(:,2)-ymin)/(ymax-ymin);
X3 = (XX(:,3)-zmin)/(zmax-zmin);
XX = [X1,X2,X3];
plot3(XX(idem,1),XX(idem,2),XX(idem,3),'.','color','b','Markersize',20);
plot3(XX(igop,1),XX(igop,2),XX(igop,3),'.','color','r','Markersize',20);
view(3)
fsz = 16;
set(gca,'FontSize',fsz);
xlabel(str(i1),'FontSize',fsz);
ylabel(str(i2),'FontSize',fsz);
zlabel(str(i3),'FontSize',fsz);

%Plotting the hyperplane

xmin = min(XX(:,1)); xmax = max(XX(:,1));
ymin = min(XX(:,2)); ymax = max(XX(:,2));
zmin = min(XX(:,3)); zmax = max(XX(:,3));
nn = 50;
[xx,yy,zz] =
    meshgrid(linspace(xmin,xmax,nn),linspace(ymin,ymax,nn),...
        linspace(zmin,zmax,nn));
plane = wASM(1)*xx+wASM(2)*yy+wASM(3)*zz+wASM(4);

```

```

plane2 = w(1)*xx+w(2)*yy+w(3)*zz+w(4);
p = patch(isosurface(xx,yy,zz,plane,0));
q = patch(isosurface(xx,yy,zz,plane2,0));
p.FaceColor = 'green';
p.EdgeColor = 'none';
q.FaceColor = 'red';
q.EdgeColor = 'none';
camlight
lighting gouraud
alpha(0.3);
%
```

```

A local solution is found, iter = 351
```

```

x = [
0
2.000000e-01
1.931488e-15
2.000000e-01
2.000000e-01
2.000000e-01
2.000000e-01
2.000000e-01
2.000000e-01
-9.609228e-16
2.000000e-01
2.000000e-01
2.000000e-01
2.000000e-01
2.000000e-01
2.000000e-01
1.708555e-15
2.000000e-01
2.000000e-01
2.000000e-01
2.000000e-01
6.838316e-02
5.431399e-16
2.000000e-01
2.000000e-01
9.395453e-18
2.000000e-01
1.405835e-17
2.000000e-01
2.000000e-01
2.000000e-01
2.000000e-01
2.000000e-01
2.000000e-01
2.000000e-01
-7.658025e-16
2.000000e-01
2.000000e-01
2.000000e-01
2.000000e-01
2.000000e-01
2.000000e-01
2.000000e-01
```

[illegible]

]



Implementing Stochastic Gradient Descent

```
N = 15;
NN = 10;
for ii = 1 : NN
    s = step/2^ii;
    nsteps = ceil(N*2^ii/ii);
    for i = 1 : nsteps
        k = randi(n);
        g = grad(k,x);
        x = x - g*s;
    end
end
end
```

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