

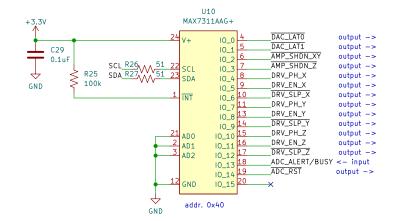
0-2.5Vout check for pulldowns on DAC lines MCP47FVB24-E/MQ X_Vs_2.5V TP2 Vout0 Vout1 Vout2 Vout2 Vout2 Vout2 2.5V_Vref 14 Vref1 DAC_LAT0_R30____100_18 DAC_LAT1_R31_____100_19 LAT0_LAT1 1 A0 A1 VSS 7 addr. 0x60

DAC STAGE

any way to get a super accurate 5V reference? always a dropout voltage

SCLD SDA SDAD-

IO EXPANDER

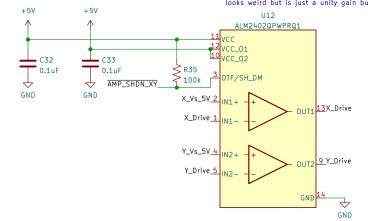


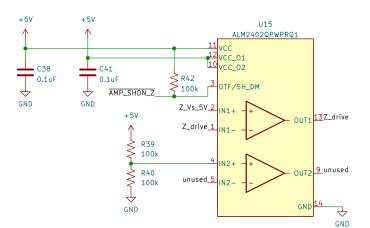
1.3.1 Technical specification

Danamatan .		
Parameter	Typical Value	Comments
Environmenta	l Characteristics	
Qualified operational temperature range	-40 to +70°C	
Storage temperature range	-50 to +85°C (RH<60%)	
Electrical C	haracteristics	
Torquer supply voltage (design)	5V	
Nominal magnetic dipole (per actuator)	0.2 Am ²	
Actuation power (rods)	0.2 W	5V, 20 C, 0.2 Am ²
Actuation power (air core)	0.57 W	5V, 20 C, 0.2 Am ²
Temperature sensor current consumption	<150 uA	
Physical Cl	naracteristics	
Dimensions (Main)	95.9 x 90.1 mm	
External height	15 mm	
Weight	194 grams	
Table 1-2 iMTQ Overall Specification		•

DRIVE AMPLIFIER

Magnetotorquer voltage source just a high current op amp as a unity buffer looks weird but is just a unity gain buffer





HALF BRIDGE DRIVER & **CURRENT SENSE**

5V AMPLIFIER

X_Vs_2.5V OUT_5V X_Vs_5V

— ⊃IN_2.5V OUT_5V<

Z_Vs_2.5V OUT_5V Z_Vs_5V

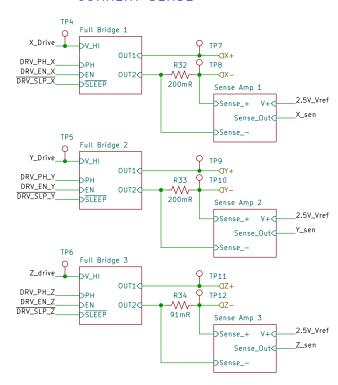
5V Amp 1

5V Amp 2

5V Amp 3

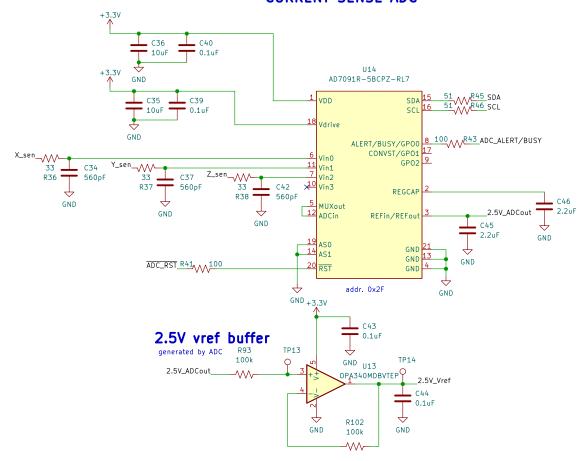
Y_Vs_2.5V

take 0-2.5V DAC signal to 0-5V



max rod current = 50mA max air core current = 110mA max current will be flowing both directions biased at mid supply lets say current will cause a +/- 1.0v defelection $r_rod = 1/(50mA)/100 = 200mR$ $r_air = 1/110mA/100 = 91mR$

CURRENT SENSE ADC



Sheet: /Magnetotorquer Drivers/ File: magnetotorquer-driver kicad_sch Title: Size: B ld: 4/22

KiCad E.D.A. kicad (6.0.5)

