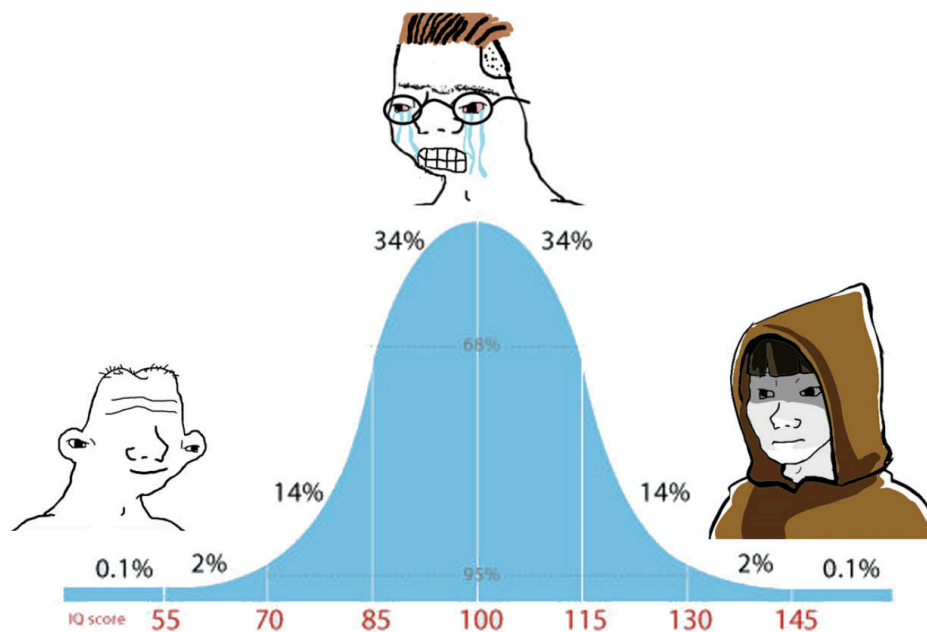


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# 1. Introduction

## 1.1. Statistics

The discipline of statistics instructs how to make intelligent judgments and informed decisions in the presence of uncertainty and variation.

Collections of facts are called **data**: statistics provides methods for organizing, summarizing and drawing conclusions based on information contained in the data.

A statistical enquiry will typically focus on a well-defined collection of objects constituting a **population**. When desired information is available for all objects in the population, a **census** is available.

In general, such a situation is hardly possible, either because it would be too expensive or too time consuming to do so or simply because the population has an infinite amount of members. A more reasonable approach is to extract a subset of the population, called **sample** that is both sufficiently small to be able to work with and sufficiently large to capture all the nuances of the population as a whole.

Each object of the population possesses many features, some of which may or may not be of interest. Any feature whose value might change from object to object in the population and that has relevance with respect to a statistical enquiry is called a **variable**.

Variables are generally distinct in **numerical** variables and **categorical** variables. Numerical variables are distinct in **discrete** and **continuous**. Numerical variables are discrete if the set of its possible values is either finite or countably infinite. Numerical variables are continuous if the set of its possible values is uncountably infinite. Categorical variables are distinct in **ordinal** and **nominal**. Categorical variables are ordinal if the set of its possible values obeys an objective hierarchy or ordering of some sort, otherwise are called **nominal**.

**Exercise 1.1.1:** Provide an example for each of the four types of variables.

*Solution:*

- A numerical discrete variable could be the number of items sold in a store, since such number is necessarily an integer (it's not possible to sell, say, half an item, or three quarters of an item). Another example is the number of attempts necessary to win the lottery: it could be infinite, but it's still countable;
- A numerical continuous variable could be the temperature measured in a certain meteorological station, since such value is a real number (it could be approximated to an integer, but it would entail losing much information);
- A categorical ordinal variable could be the ranks in an army, such as general, private, captain, etcetera. Such ranks can be arranged in a (very) strict hierarchy, for example corporal is lower than general while corporal is higher than private;
- A categorical nominal variable could be the colors of a dress. It would make little sense to say that, for example, red scores higher than green or that pink scores lower than blue, at least in an objective way.

□

When referring to “statistics”, it often entails two distinct concepts. The first one is **descriptive statistics**, that consists in summarizing and describing the data, in general through graphical representations (called **plots**) or through **summary measures**, numbers that on their own represent an aspect of the data as a whole.

The second one is **inferential statistics**, that consists in drawing conclusions about the population as a whole from the sample extracted from such population. In this case, a sampling is a means to an end, not an end in itself.

Given a discrete numerical variable  $x$ , let  $x_1, x_2, \dots, x_n$  be the observations collected from the sample of such variable, with  $n$  being the cardinality of the sample. The **sample mean**  $\bar{x}$  is a summary measure that describes its average value, and is calculated as:

$$\bar{x} = \frac{x_1 + x_2 + \dots + x_n}{n} = \frac{\sum_{i=1}^n x_i}{n}$$

Given a discrete numerical variable  $x$ , let  $x_1, x_2, \dots, x_n$ , be the observations collected from the sample of such variable, arranged from lowest to highest (including duplicates). The **sample median**  $\tilde{x}$  is a summary measure that describes the central value, and is calculated as either the middle value of such sequence if  $n$  is odd or the average of the two middle values if  $n$  is even:

$$\tilde{x} = \begin{cases} \text{The } (\frac{n+1}{2})^{\text{th}} \text{ value if } n \text{ is odd} \\ \text{The average of the } (\frac{n}{2})^{\text{th}} \text{ and the } (\frac{n}{2} + 1)^{\text{th}} \text{ value if } n \text{ is even} \end{cases}$$

The **sample variance**  $s^2$  is a summary measure that describes how “spread out” are the values of the sample, or equivalently how close its values are to the sample mean, and is defined as:

$$s^2 = \frac{\sum_{i=1}^n (x_i - \bar{x})^2}{n - 1} = \frac{n \sum_{i=1}^n x_i^2 - (\sum_{i=1}^n x_i)^2}{n(n - 1)}$$

The **sample standard deviation** is defined as the square root of the sample variance:

$$s = \sqrt{s^2}$$

**Theorem 1.1.1:** Given a discrete numerical variable  $x$ , let  $x_1, x_2, \dots, x_n$ , be the observations collected from the sample of such variable, and let  $c$  be a numerical constant. Then:

1. If, for each  $1 \leq i \leq n$ , the  $y$  variable is constructed as  $y_i = x_i + c$ , it is true that  $s_y^2 = s_x^2$ ;
2. If, for each  $1 \leq i \leq n$ , the  $y$  variable is constructed as  $y_i = cx_i$ , it is true that  $s_y^2 = c^2 s_x^2$ ;

Where  $s_x^2$  is the sample variance of the “original” variable  $x$  and  $s_y^2$  is the sample variance of the “transformed” variable  $y$ .

## 1.2. Probability

**Probability theory** is a mathematical framework providing methods that describe situations and events having an unforeseeable outcome, quantifying chance and randomness related to said results.

Any activity or process having at least one (unknowable in advance) outcome is called an **experiment**. The set containing all possible outcomes of an experiment, denoted as  $\mathcal{S}$ , is called **sample space**. The sample space can be either discrete or continuous.

**Exercise 1.2.1:** Provide some examples of experiments.

*Solution:*

- The roll of a six-sided dice is an experiment, since the resulting value of the dice is unknown until the dice is rolled. The sample space  $\mathcal{S}$  contains 6 elements:

$$\mathcal{S} = \{1, 2, 3, 4, 5, 6\}$$

- The drawing of a card from a (standard) deck is an experiment, since the value of the card is unknown until the card is drawn. The sample space  $\mathcal{S}$  contains 52 elements:

$$\mathcal{S} = \{A\heartsuit, 2\heartsuit, \dots, Q\heartsuit, K\heartsuit, A\diamondsuit, 2\diamondsuit, \dots, Q\diamondsuit, K\diamondsuit, A\clubsuit, 2\clubsuit, \dots, Q\clubsuit, K\clubsuit, A\spadesuit, 2\spadesuit, \dots, Q\spadesuit, K\spadesuit\}$$

- The gender assigned to the offspring of a couple is an experiment, since their gender is unknown until (roughly) 4 months since conception. The sample space  $\mathcal{S}$  contains 8 elements:

$$\mathcal{S} = \{MMM, MMF, MFM, FMM, MMF, FFM, FMF, FFF\}$$

□

Any subset of the sample space is called an **event**. An event can be either **simple** if it's a singleton (it contains a single outcome of the experiment) or **compound** otherwise (it contains multiple outcomes). An event can either occur or not occur, depending on the outcome of the experiment.

**Exercise 1.2.2:** Provide some examples of events.

*Solution:*

- Consider the roll of a six-sided dice. The subset  $A = \{1, 3, 5\}$  of the sample space  $\mathcal{S}$  corresponds to the event “an even number”. It is a compound event;
- Consider the drawing of a card from a deck. The subset  $B = \{A♥, A♦, A♣, A♠, K♥, K♦, K♣, K♠\}$  of the sample space  $\mathcal{S}$  corresponds to the event “either an ace or a king of any set”. It is a compound event;
- Consider the gender assigned to the offspring of a couple. The subset  $C = \{FFF\}$  of the sample space  $\mathcal{S}$  corresponds to the event “exclusively female offspring”. It is a simple event.

□

Being sets, events can be manipulated using set algebra. In particular, given two events  $A$  and  $B$ :

- The **complement** of  $A$ , denoted as  $A^c$ , corresponds to the event containing all outcomes not contained in  $A$ . That is,  $A^c$  occurs if and only if  $A$  does not occur.  $A^c$  is also called the **complementary event** of  $A$ ;
- The **intersection** of  $A$  and  $B$ , denoted as  $A \cap B$ , corresponds to the event containing all outcomes contained both in  $A$  and in  $B$ . That is,  $A \cap B$  occurs if and only if both  $A$  and  $B$  occur at the same time;
- The **union** of  $A$  and  $B$ , denoted as  $A \cup B$ , corresponds to the event containing all outcomes contained either in  $A$ , in  $B$  or in both. That is,  $A \cup B$  occurs if at most  $A$  or  $B$  occurs.

**Exercise 1.2.3:** Provide some examples of complemented, intersected and unified events.

*Solution:*

- Consider the roll of a six-sided dice. The subset  $A = \{1, 2, 3, 4, 5\}$  of the sample space  $\mathcal{S}$  corresponds to the event “any number but 6”. It is the complement of the event “exactly six”;
- Consider the drawing of a card from a deck. The subset  $B = \{A♥, A♦, A♣, A♠, K♥, K♦, K♣, K♠\}$  of the sample space  $\mathcal{S}$  is actually a union of two smaller events, the first being “an ace of any set” and the second being “a king of any set”;
- Consider the gender assigned to the offspring of a couple. Consider the two events “a male as first born” and “a female as third born”. Their intersection, representing the event “a male as first born and a female as third born” is given by:

$$\{MMM, MMF, MFM, MFF\} \cap \{MMF, MFF, FMF, FFF\} = \{MMF, MFF\}$$

□

The empty set  $\emptyset$  denotes the event of having no outcome whatsoever, also called the **null event**. If the intersection of two events is the null event, such events are said to be **mutually exclusive** events, or **disjoint** events. In other words, two events are said to be mutually exclusive if they have no way of happening at the same time.

Modern probability theory, like set theory, is defined axiomatically. Such axioms are also called **Kolmogorov axioms**, and are (supposed to be) the minimum amount of axioms that are needed to construct a theory of probability free of contradictions.

To an event  $A$ , it is possible to associate a value called its **probability**, denoted as  $P(A)$ , that represents a measure of likelihood, certainty or confidence of such event to occur (intuitively, the higher the value of probability, the higher the likelihood). Probabilities obey three axioms, here stated:

1. For any event  $A$ ,  $P(A) \geq 0$ . That is, the probability of an event happening is non negative;
2.  $P(\mathcal{S}) = 1$ . That is, the probability of any even happening at all is fixed as 1;
3. If  $A_1, A_2, \dots$  is a collection of countably infinite disjoint events, the following equality holds:

$$P(A_1 \cup A_2 \cup \dots) = \sum_{i=1}^{\infty} P(A_i)$$

That is, given a set of events where no event can occur if at most another one of them occurs, the probability of any such event to occur is the sum of the individual probabilities.

From such axioms, it is possible to derive many useful consequences.

**Theorem 1.2.1:**  $P(\emptyset) = 0$ . That is, the null event cannot occur.

*Proof:* Consider the countably infinite collection of events  $\emptyset, \emptyset, \dots$ . By definition, the null event is disjoint with itself, since set algebra gives  $\emptyset \cap \emptyset = \emptyset$ . The collection  $\emptyset, \emptyset, \dots$  is therefore made up of disjoint events, and by set algebra  $\emptyset \cup \emptyset \cup \dots = \emptyset$ , therefore  $P(\emptyset \cup \emptyset \cup \dots) = P(\emptyset)$ . Since by axiom 3  $P(\emptyset \cup \emptyset \cup \dots) = \sum_{i=1}^{\infty} P(\emptyset)$ , by transitive property  $\sum_{i=1}^{\infty} P(\emptyset) = P(\emptyset)$ . Since by axiom 1 the value of  $P(\emptyset)$  has to be non negative, such equality can hold exclusively if  $P(\emptyset) = 0$ .  $\square$

**Theorem 1.2.2:** If  $A_1, A_2, \dots, A_n$  is a collection of finitely many disjoint events, the following equality holds:

$$P(A_1 \cup A_2 \cup \dots \cup A_n) = \sum_{i=1}^n P(A_i)$$

*Proof:* Consider the countably infinite collection of events  $A_1, A_2, \dots, A_n, A_{n+1} = \emptyset, A_{n+2} = \emptyset, \dots, \emptyset$ , that is, a collection constructed by encoding countably infinitely many null events to the original collection. Applying axiom 3 to such collection gives:

$$P(A_1 \cup A_2 \cup \dots \cup A_n \cup \emptyset \cup \emptyset \cup \dots \cup \emptyset) = \sum_{i=1}^{\infty} P(A_i)$$

It is possible to split the summation in two like so:

$$P(A_1 \cup A_2 \cup \dots \cup A_n) + P(\emptyset \cup \emptyset \cup \dots \cup \emptyset) = \sum_{i=1}^n P(A_i) + \sum_{i=n+1}^{\infty} P(\emptyset)$$

But by Theorem 1.2.1,  $P(\emptyset) = 0$ . Therefore:

$$P(A_1 \cup A_2 \cup \dots \cup A_n) + P(\emptyset \cup \emptyset \cup \dots \cup \emptyset) = P(A_1 \cup A_2 \cup \dots \cup A_n) + 0 = \sum_{i=1}^n P(A_i)$$

$\square$

**Theorem 1.2.3:** For any event  $A$ ,  $P(A) + P(A^c) = 1$ .

*Proof:* By definition of complementary event,  $A \cup A^c = \mathcal{S}$ . They are also disjoint events, since one cannot happen if the other one happened. It is therefore possible to apply Theorem 1.2.2 and state that  $\sum_{i=1}^2 P(A_i) = P(A) + P(A^c) = P(A \cup A^c)$ . But, as stated,  $A \cup A^c = \mathcal{S}$ , and by axiom 2  $P(\mathcal{S}) = 1$ . Therefore, by transitive property,  $P(A) + P(A^c) = 1$ .  $\square$

**Theorem 1.2.4:** For any event  $A$ ,  $0 \leq P(A) \leq 1$ .

*Proof:* By Theorem 1.2.3,  $P(A) + P(A^c) = 1$ . By axiom 1, both probabilities are greater or equal than 0, therefore, for the equality to hold, both probabilities have to be lower or equal than 1. Combining the two boundaries,  $0 \leq P(A) \leq 1$ .  $\square$

**Theorem 1.2.5:** For any two events  $A$  and  $B$ ,  $P(A \cup B) = P(A) + P(B) - P(A \cap B)$ .

*Proof:* By set algebra, the event  $A \cup B$  can itself be seen as the union of two disjoint events,  $A$  and  $A^c \cap B$ . It is therefore possible to apply Theorem 1.2.2, resulting in:

$$P(A \cup B) = P(A \cup (A^c \cap B)) = P(A) + P(A^c \cap B)$$

In the same fashion, the event  $B$  can be seen as the union of the disjoint events  $A \cap B$  and  $A^c \cap B$ . Applying Theorem 1.2.2 gives:

$$P(B) = P((A \cap B) \cup (A^c \cap B)) = P(A \cap B) + P(A^c \cap B)$$

Moving  $P(A \cap B)$  to the left side gives  $P(B) - P(A \cap B) = P(A^c \cap B)$ . Substituting such expression in the first equation gives  $P(A \cup B) = P(A) + P(B) - P(A \cap B)$ .  $\square$

**Theorem 1.2.6:** For any three events  $A$ ,  $B$  and  $C$ :

$$P(A \cup B \cup C) = P(A) + P(B) + P(C) - P(A \cap B) - P(A \cap C) - P(B \cap C) + P(A \cap B \cap C)$$

*Proof:* Works similarly as Theorem 1.2.5.  $\square$

**Theorem 1.2.7** (Boole's inequality): Given any countable set of events  $A_1, A_2, \dots, A_n$ :

$$P\left(\bigcup_{i=1}^{\infty} A_i\right) \leq \sum_{i=1}^{\infty} P(A_i)$$

It should be stressed that the Kolmogorov axioms simply describe the rules by which probability works, but do not define the probability of any event itself. Infact probabilities can be assigned to any event in any possible way that is constrained by the axioms, but such value can have no bare on reality or on intuition and yet construct a model that is consistent.

**Exercise 1.2.4:** Provide an example of a probability model that constrasts with reality but obeys Kolmogorov's axioms.

*Solution:* Consider the toss of a coin. Such action can be conceived as an experiment, since whose side the coin is gonna land when tossed is unknown until the coin lands. Only two events are possible, heads or tails; since a coin cannot land on both sides at the same time, such events are disjoint.

It is a known fact that the probability of both events is 0.5, and indeed such assignment respects all of three axioms. But by choosing the assignment, say, 0.2 to the landing on heads and 0.8 to the landing on tails, no axiom is violated, even though such an assignment has very little resonance with experience or common sense.

This does not mean that probabilities can be assigned at libitum, since they still ought to comply with the axioms. For example, assigning 0.4 to the probability of the coin to land on heads and 0.3 to the probability of the coin to land on tails won't do, since axiom 2 would be violated. As another example, assigning 1.5 to

the probability of the coin to land on heads and  $-0.5$  to the probability of the coin to land on tails would violate axiom 1, and therefore invalid.  $\square$

The appropriate or correct assignment depends on how one *interprets* probability, that is to say how one intends the link between the mathematical treatment of probability and the physical world. This quest is just as philosophical as mathematical.

The oldest definition of probability, also called **classical probability**, states that the probability of an event  $A$  is the ratio of the number of favorable events and the entire number of outcomes, assuming all outcomes are equally likely.

Said definition is considered outdated mainly for two reasons. On the one hand, the definition lies on a circular argument, since it presupposes the notion of “equally likely outcomes”. On the other hand, an event does not necessarily have many outcomes all of them equally likely.

One possible and often invoked interpretation of probability is the **objective** interpretation, also called **frequentist** interpretation. Consider an experiment that can be repeatedly performed in an identical and independent fashion, and let  $A$  be an event consisting of a fixed set of outcomes of the experiment. If the experiment is performed  $n$  times, the event  $A$  will occur  $n(A)$  times (with  $0 \leq n(A) \leq n$ ) and will not occur  $n - n(A)$  times. The ratio  $n(A)/n$  is called the **relative frequency** of occurrence of the event  $A$  in the sequence of  $n$  attempts.

Empirical data suggests that the relative frequency fluctuates considerably if  $n$  is a small number, while tends to stabilize itself as  $n$  grows. Ideally, repeating such experiment infinitely many times, it would be possible to obtain a “perfect” frequency, called **limiting relative frequency**. The objective interpretation of probability states that this limiting relative frequency is indeed the probability of  $A$  to occur.

This interpretation of probability is said to be objective in the sense that it rests on a property of the experiment and not on the concerns of the agent performing it (ideally, two agents performing the same experiment the same number of times would obtain the same relative limiting frequency, and therefore the same probability).

This interpretation has limited applicability, since not all events can be performed  $n$  number of times to draw similar conclusions. In situations such as these, it makes more sense to interpret probability in a **subjective** way, which can be thought of as the “degree of confidence” with which an agent believes an event to occur.

The simplest situation to model is the one where to each simple event  $E_1, E_2, \dots, E_N$  is assigned the same value of probability  $P(E_i)$ :

$$1 = \sum_{i=1}^N P(E_i) \Rightarrow P(E_i) = \frac{1}{N}$$

That is, if there are  $N$  equally likely outcomes, the probability of one of such outcomes to happen is  $1/N$ .

More generally, consider an event  $A$  containing  $N(A)$  number of outcomes. Then the task of computing probabilities reduces itself to **counting**:

$$P(A) = \sum_{E_i \in A} P(E_i) = \sum_{E_i \in A} \frac{1}{N} = \frac{N(A)}{N}$$

Given two events  $A$  and  $B$  with  $P(B) > 0$ , the probability of  $A$  to occur given that  $B$  occurred is called the **conditional probability** of  $A$  given  $B$ , and is given as:

$$P(A | B) = \frac{P(A \cap B)}{P(B)}$$

**Theorem 1.2.8** (Law of total probability): Let  $A_1, A_2, \dots, A_n$  be a finite partition of a sample space  $\mathcal{S}$  such that no event has assigned zero probability, and let  $B$  be any event in  $\mathcal{S}$ . Then:

$$P(B) = P(B | A_1)P(A_1) + \dots + P(B | A_n)P(A_n) = \sum_{i=1}^n P(B | A_i)P(A_i)$$

**Theorem 1.2.9** (Bayes' theorem): Let  $A_1, A_2, \dots, A_n$  be a finite partition of a sample space  $\mathcal{S}$ . Each event  $A_j$  has a probability  $P(A_j)$ , also called its **prior probability**, that is non zero. Let  $B$  be any event in  $\mathcal{S}$  whose probability is non zero. The probability  $P(A_j | B)$ , also called the **posterior probability**, is given as:

$$P(A_j | B) = \frac{P(A_j \cap B)}{P(B)} = \frac{P(B | A_j)P(A_j)}{\sum_{i=1}^{\infty} P(B | A_i)P(A_i)}$$

**Exercise 1.2.5:** An electronics store sells three different brands of DVD players. Of its DVD player sales, 50% are brand 1 (the least expensive), 30% are brand 2, and 20% are brand 3. Each manufacturer offers a 1-year warranty on parts and labor. It is known that 25% of brand 1's DVD players require warranty repair work, whereas the corresponding percentages for brands 2 and 3 are 20% and 10%, respectively.

1. What is the probability that a randomly selected purchaser has bought a brand 1 DVD player that will need repair while under warranty?
2. What is the probability that a randomly selected purchaser has a DVD player that will need repair while under warranty?
3. If a customer returns to the store with a DVD player that needs warranty repair work, what is the probability that it is a brand 1 DVD player?

Consider two events,  $A$  and  $B$ , the second happening after the first. The fact that  $B$  occurred may or may not influence the probability of  $A$  to occur. If the probability of  $A$  to happen is the same whether or not  $B$  happened, that is to say if  $P(A)$  and  $P(A | B)$  are equal, The event  $A$  is said to be **independent** of  $B$ . Otherwise, it's said to be **dependent** of  $B$ .

**Theorem 1.2.10:** Event independence is symmetric. In other words, given two events  $A$  and  $B$ , if  $A$  is independent of  $B$ , then  $B$  is independent of  $A$ .

*Proof:* If  $A$  is independent of  $B$ , then  $P(A | B) = P(A)$ . Applying Theorem 1.2.9 gives:

$$P(A | B) = \frac{P(B | A)P(A)}{P(B)} \Rightarrow P(B | A) = P(B)$$

Which, by definition, means that  $B$  is independent of  $A$  as well. □

An equivalent definition of independent events is as follows. Given two independent events  $A$  and  $B$ , by the previous definition  $P(A) = P(A | B)$ , so:

$$P(A | B) = \frac{P(A \cap B)}{P(B)} \Rightarrow P(A) = \frac{P(A \cap B)}{P(B)} \Rightarrow P(A \cap B) = P(A)P(B)$$

Event independence can be extended to a situation with more than two events. Given a collection of  $n$  events  $A_1, A_2, \dots, A_n$ , such events are said to be **mutually independent** if for every  $k = 2, 3, \dots, n$  and for every subset of indices  $i_1, i_2, \dots, i_k$ :

$$P(A_{i,1} \cap A_{i,2} \cap \dots \cap A_{i,k}) = P(A_{i,1}) \cdot P(A_{i,2}) \cdot \dots \cdot P(A_{i,k})$$

Kolmogorov axioms define the properties of probability but do not offer a method for assigning them to events. The simplest approaches, such as assigning the same probability to each event, are far too weak to model reality. Also, the sample space and the events are different from experiment to experiment, making it hard to generalize a coherent theory of probability. A more powerful concept to be introduced which can help model probability is the **random variable**.



A random variable can be conceived as a mapping from the sample space to the real line. In other words, a random variable is a function that assigns a probability to any possible event of the sample space. Given a sample space  $\mathcal{S}$ , a random variable  $X$  for such sample space is defined as  $X : \mathcal{S} \mapsto \mathbb{R}$ , and the probability of such variable to assume a certain value  $x$  of the sample space, called its **realization**, is denoted as  $P(X = x)$ .

**Exercise 1.2.6:** Suppose a real estate investment has been carried out, and there are three apartments of different value ready to be sold. Assuming that the probability of selling one, two or three of those is the same, model this situation using a random variable.

*Solution:* It is possible to model this scenario using a random variable  $X$ , whose realizations correspond to which and how many apartments were sold. Each realization can be conceived as a triple  $(a_1, a_2, a_3)$ , where each  $a_i$  has value 1 if the  $i$ -th apartment was sold and 0 otherwise:

$$\Omega = \{(0, 0, 0), (0, 0, 1), (0, 1, 0), (0, 1, 1), (1, 0, 0), (1, 0, 1), (1, 1, 0), (1, 1, 1)\}$$

The realizations of  $X$  correspond to the events with a matching number of 1s. To each value of  $X$  is then possible to assign a value of probability by equally dividing the total probability among the events, such that  $P(\Omega) = 1$ .

$$\begin{array}{ll} X(0, 0, 0) = 0 & P(X = 0) = P(\{(0, 0, 0)\}) = 12.5\% \\ X(0, 0, 1) = X(1, 0, 0) = X(0, 1, 0) = 1 & P(X = 1) = P(\{(0, 0, 1), (1, 0, 0), (0, 1, 0)\}) = 37.5\% \\ X(1, 1, 0) = X(0, 1, 1) = X(1, 0, 1) = 2 & P(X = 2) = P(\{(1, 1, 0), (0, 1, 1), (1, 0, 1)\}) = 37.5\% \\ X(1, 1, 1) = 3 & P(X = 3) = P(\{(1, 1, 1)\}) = 12.5\% \end{array}$$

□

Random variables fall in two broader categories: **discrete** and **continuous**. A random variable is said to be discrete if the set of values it can assume is either finite or countably infinite. A random variable is said to be continuous if the two following properties apply:

1. Its set of possible values consists either of all numbers in a single (possibly infinite) interval on the real line or all numbers in a disjoint union of such intervals;
2. The probability of the random variable to assume a specific value is always zero.

The set of values that a random variable can assume is called its **support**.

### 1.3. Combinatorics

**Combinatorics** is an area of mathematics primarily concerned with counting, that is the enumeration of the possible arrangements or configurations of specified structures.

The most important building block of combinatorics is the **fundamental principle of counting**. Consider an experiment having  $n$  components, with each  $i$ -th component having  $x_i$  possible outcomes. The number of outcomes of the experiment as a whole is given by:

$$\prod_{i=1}^n x_i = x_1 \cdot x_2 \cdot (\dots) \cdot x_n$$

**Exercise 1.3.1:** Consider an experiment consisting in the toss of a coin followed by the roll of a die. How many outcomes does this experiment have?

*Solution:* A coin toss has two possible outcomes, while the roll of a die has six. Therefore, the experiment as a whole has  $6 \cdot 2 = 12$  possible outcomes. Indeed:

$$\begin{aligned}\Omega_1 &= \{H, T\} & \Omega &= \{\{H, 1\}, \{T, 1\}, \{H, 2\}, \{T, 2\}, \{H, 3\}, \{T, 3\}, \\ & & & \{H, 4\}, \{T, 4\}, \{H, 5\}, \{T, 5\}, \{H, 6\}, \{T, 6\}\} \\ \Omega_2 &= \{1, 2, 3, 4, 5, 6\}\end{aligned}$$

□

Starting from the fundamental principle of counting, it is possible to describe many common counting situations.

A **sequence with repetition** is a situation dealing with ordered sequences of  $k$  elements (possibly repeated) chosen among  $n$ , such that:

$$n \cdot n \cdot n \cdot (\dots) \cdot n = n^k$$

**Exercise 1.3.2:** What are the possible arrangements of birthdays of three people?

*Solution:* A year is constituted of 365 days, so the birthdays of three people can be arranged in  $365 \cdot 365 \cdot 365 = 365^3 = 48627125$  possible ways. □

A **sequence without repetition** is a situation dealing with ordered sequences of  $k$  elements (none repeated) chosen among  $n$  with  $k \leq n$ , such that:

$$n \cdot (n-1) \cdot (n-2) \cdot (\dots) \cdot (n-k+1) = \frac{n!}{(n-k)!}$$

**Exercise 1.3.3:** In how many ways is it possible to arrange the birthdays of 23 people such that no two people have birthday the same day?

*Solution:*

$$\frac{n!}{(n-k)!} = \frac{365!}{(365-23)!} = \frac{365!}{342!} = \frac{365 \cdot 364 \cdot (\dots) \cdot 344 \cdot 343 \cdot \cancel{342!}}{\cancel{342!}} \approx 4.22 \times 10^{58}$$

□

A **permutation** is a situation dealing with ordered sequences of  $k$  elements (none repeated) chosen among  $n$  with  $k = n$ , such that:

$$n \cdot (n-1) \cdot (n-2) \cdot (\dots) \cdot 2 \cdot 1 = n!$$

**Exercise 1.3.4:** In how many ways is it possible to arrange a deck of playing cards?

*Solution:*

$$52! = 52 \cdot 51 \cdot 50 \cdot (\dots) \cdot 2 \cdot 1 \approx 8.06 \times 10^{67}$$

□

A **combination** is a situation dealing with unordered sequences of  $k$  elements (none repeated) chosen among  $n$  with  $k \leq n$ , such that:

$$\binom{n}{k} = \frac{n!}{k!(n-k)!} = \frac{n \cdot (n-1) \cdot (n-2) \cdot (\dots) \cdot (n-k+1)}{k!}$$

**Exercise 1.3.5:** In how many ways is it possible to arrange 20 people in groups of 4?

*Solution:* This is a combination, since the ways each group is arranged is irrelevant:

$$\binom{20}{4} = \frac{20!}{4!(20-4)!} = \frac{20!}{4! \cdot 16!} = \frac{20 \cdot 19 \cdot 18 \cdot 17 \cdot 16!}{4! \cdot 16!} = \frac{20 \cdot 19 \cdot 18 \cdot 17}{24} = \frac{116280}{24} = 4845$$

□

## 1.4. Discrete random variables

The **probability mass function** (abbreviated as pmf) of a discrete random variable  $X$ , denoted as  $p(X)$ , is a function that assigns a probability to each possible value that such random variable can assume. More formally, given a random variable  $X$ , for each value  $x$  of its sample space the pmf of  $X$  is defined as:

$$p(x) = P(X = x) = P(\omega : \omega \in \mathcal{S}, X(\omega) = x)$$

The **cumulative distribution function** (abbreviated as cdf) of a discrete random variable  $X$ , denoted as  $F(X)$ , is defined as the probability of such random variable to assume a value less than or equal to a threshold. More formally, given a random variable  $X$ , for each value  $x$  of its sample space the cdf of  $X$  is defined as:

$$F(x) = P(X \leq x) = \sum_{y: y \leq x} p(y)$$

Let  $X$  be a discrete random variable with support  $D$  and probability mass function  $p(X)$ . The **expected value** (or **mean value**) of  $X$ , denoted as  $E(X)$  or  $\mu_X$  is given by:

$$E(X) = \mu_X = \sum_{x \in D} x \cdot p(x)$$

When the variable  $X$  is known, the pedix  $X$  in  $\mu_X$  is omitted.

The expected value of a random variable is the equivalent of the mean with respect to populations.

**Exercise 1.4.1:** Let  $X$  be the Apgar score of a randomly selected child born at a certain hospital during the next year, with pmf as follows:

$X$	0	1	2	3	4	5	6	7	8	9	10
$p(X)$	0.002	0.001	0.002	0.005	0.02	0.04	0.18	0.37	0.25	0.12	0.01

What is the expected value of  $X$ ?

*Solution:*

$$E(X) = \sum_{x \in D} x \cdot p(x) = 0 \cdot 0.002 + 1 \cdot 0.001 + 2 \cdot 0.002 + 3 \cdot 0.005 + 4 \cdot 0.02 + 5 \cdot 0.04 + 6 \cdot 0.18 + 7 \cdot 0.37 + 8 \cdot 0.25 + 9 \cdot 0.12 + 10 \cdot 0.01 = 7.15$$

□

The expected value is oblivious to whether its argument is a random variable or a function whose input is a random variable. In other words, let  $X$  be a discrete random variable with support  $D$  and probability mass function  $p(X)$ , and let  $h(X)$  be a function whose argument is (the realization of) the random variable  $X$ . The expected value of  $h(X)$  is still defined as:

$$E(h(X)) = \mu_{h(X)} = \sum_{x \in D} h(x) \cdot p(x)$$

**Theorem 1.4.1:** Let  $X$  be a discrete random variable with support  $D$  and probability mass function  $p(X)$ . Given two coefficients  $a$  and  $b$ , the following equality holds:

$$E(aX + b) = aE(X) + b$$

*Proof:* Let  $D$  be the support of  $X$  and  $p(X)$  its probability mass function. Let  $Y$  be the random variable  $Y = aX + b$ . The probability of  $Y$  to assume a particular value  $ax + b$  does not depend on  $a$  and  $b$ , but only on  $x$ . Therefore,  $P(Y = ax + b) = P(X = x)$ . Computing the expected value for  $Y$  gives:

$$\begin{aligned} E(Y) &= \sum_{x \in D} (ax + b) \cdot P(Y = ax + b) = \sum_{x \in D} (ax + b) \cdot P(X = x) = \sum_{x \in D} ax \cdot P(X = x) + b \cdot P(X = x) = \\ &= a \sum_{x \in D} x \cdot P(X = x) + b \sum_{x \in D} P(X = x) = aE(X) + b \cdot 1 = aE(X) + b \end{aligned}$$

Where  $\sum_{x \in D} P(X = x) = 1$  stems from the fact that said summation is the sum of the probabilities of the entire sample space, which is 1 by definition.  $\square$

**Theorem 1.4.2:** Let  $X$  and  $Y$  be two random variables.  $E[X + Y] = E[X] + E[Y]$ .

Let  $X$  be a discrete random variable with support  $D$  and probability mass function  $p(X)$ . The **variance** of  $X$ , denoted as  $V(X)$  or  $\sigma_X^2$  is given by:

$$V(X) = \sigma_X^2 = \sum_{x \in D} (x - E(X))^2 \cdot p(x) = E((X - E(X))^2)$$

When the variable  $X$  is known, the pedix  $X$  in  $\sigma_X^2$  is omitted.

The square root of the variance is called the **standard deviation**:

$$SD(X) = \sigma_X = \sqrt{V(X)}$$

The variance and the standard deviation measure how a random variable is “spread out”, in the sense of how much the values of the support of said variable are detached from its expected value.

**Lemma 1.4.1:** Let  $X$  be a discrete random variable with support  $D$  and probability mass function  $p(X)$ . The following equality holds:

$$V(X) = \left( \sum_{x \in D} x^2 \cdot p(x) \right) - (E(X))^2 = E(X^2) - (E(X))^2$$

**Theorem 1.4.3:** Let  $X$  be a discrete random variable with support  $D$  and probability mass function  $p(X)$ . Given two coefficients  $a$  and  $b$ , the following equality holds:

$$V(aX + b) = a^2 V(X)$$

*Proof:* Let  $Y$  be the random variable  $Y = aX + b$ . From Theorem 1.4.1,  $E(Y) = E(aX + b) = aE(X) + b$ . Substituting this expression in the variance one gives:

$$\begin{aligned}
V(Y) &= E((Y - E(Y))^2) = E((ax + b - aE(X) - b)^2) = \sum_{x \in D} (ax - aE(X))^2 P(Y = ax + b) = \\
&= \sum_{x \in D} a^2 (x - E(X))^2 P(X = x) = a^2 \sum_{x \in D} (x - E(X))^2 P(X = x) = a^2 V(X)
\end{aligned}$$

□

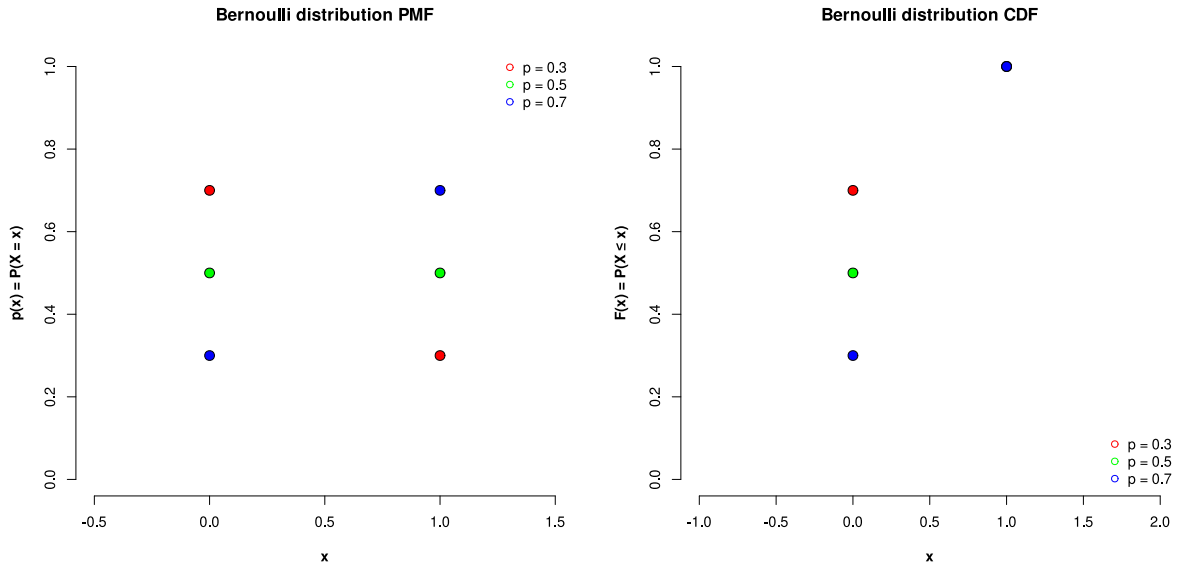
**Theorem 1.4.4:** Let  $X$  and  $Y$  be two random variables.  $V[X + Y] = V[X] + V[Y]$  if  $X$  and  $Y$  are independent.

## 1.5. Known discrete random variables

Some specific discrete random variables have been studied extensively, mostly because they model very well many phenomena in the real world. For this reason, such random variables have proper names. To denote that a random variable  $X$  has the same distribution as a known random variable  $F$ , the notation  $X \sim F$  is used.

### 1.5.1. Bernoulli random variable

A discrete random variable  $X$  is distributed as a **Bernoulli random variable** of parameter  $p \in [0, 1]$  (denoted as  $X \sim B(p)$ ) if it can assume exclusively the values 1 and 0, with probabilities  $p$  and  $1 - p$  respectively. The pdf and cdf of a Bernoulli random variable  $X$  of parameter  $p$  are therefore as follows:



$$p(x) = P(X = x) = \begin{cases} p & \text{if } x = 1 \\ 1 - p & \text{if } x = 0 \\ 0 & \text{otherwise} \end{cases}$$

$$F(x) = P(X \leq x) = \begin{cases} 0 & \text{if } x < 0 \\ 1 - p & \text{if } 0 \leq x < 1 \\ 1 & \text{if } x \geq 1 \end{cases}$$

Bernoulli random variables model experiments that have two mutually exclusive results: success ( $X = 1$ ) or failure ( $X = 0$ ), with nothing in between.

**Theorem 1.5.1.1:** The expected value and variance of a random variable  $X \sim B(p)$  are as follows:

$$E(X) = p$$

$$V(X) = p(1 - p)$$

*Proof:*

$$E(X) = 0 \cdot (1 - p) + 1 \cdot p = 0 + p = p$$

$$\begin{aligned} V(X) &= (0 - p)^2 \cdot (1 - p) + (1 - p)^2 \cdot p = \\ &= p^2(1 - p) + p(1 - p)^2 = (p^2 + p(1 - p))(1 - p) = \\ &= (p^2 + p - p^2)(1 - p) = p(1 - p) \end{aligned}$$

□

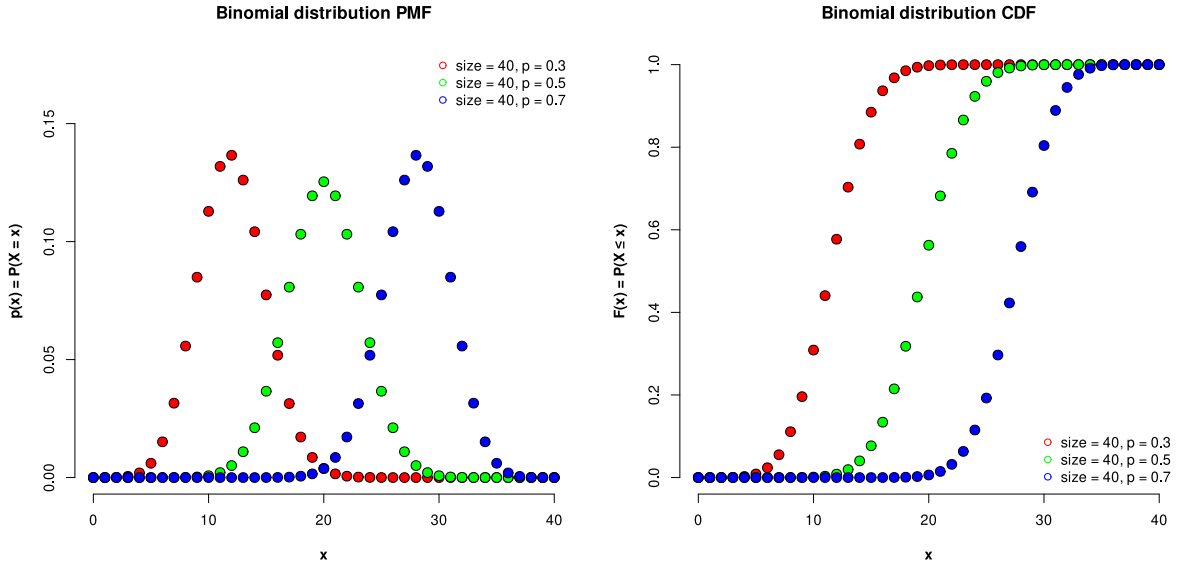
### 1.5.2. Binomial random variable

Let  $Y_1, Y_2, \dots, Y_n$  be  $n$  independent and identically distributed Bernoulli random variables (all having the same parameter  $p$ ). Let  $X$  be the random variable defined as the sum of all said variables:

$$X = \sum_{i=1}^n Y_i = Y_1 + Y_2 + \dots + Y_n$$

The random variable  $X$  defined as such is distributed as a **binomial random variable** of parameters  $p$  and  $n$  (denoted as  $X \sim Bi(n, p)$ ).

Since a specific realization of  $X$  is a sum of 0s and 1s, a realization  $k$  is simply the number of Bernoulli variables that define  $X$  that had assumed value 1. The pdf and cdf of a binomial random variable  $X$  of parameters  $n$  and  $p$  are therefore as follows:



$$p(x) = P(X = x) = \begin{cases} \binom{n}{x} p^x (1-p)^{n-x} & \text{if } \begin{cases} x \in \mathbb{N} \\ x \leq n \end{cases} \\ 0 & \text{otherwise} \end{cases}$$

$$F(x) = P(X \leq x) = \sum_{k=0}^{\lfloor x \rfloor} \binom{n}{k} p^k (1-p)^{n-k}$$

**Theorem 1.5.2.1:** The expected value and variance of a random variable  $X \sim Bi(p, n)$  are as follows:

$$E(X) = np$$

$$V(X) = np(1 - p)$$

*Proof:* This result can be proved by applying Theorem 1.4.2 and Theorem 1.4.4 (the latter can be applied since the Bernoulli random variables that constitute  $X$  are independent).

$$E(X) = E(Y_1 + Y_2 + \dots + Y_n) = E(Y_1) + E(Y_2) + \dots + E(Y_n) = nE(Y_i) = np$$

$$V(X) = V(Y_1 + Y_2 + \dots + Y_n) = V(Y_1) + V(Y_2) + \dots + V(Y_n) = nV(Y_i) = np(1 - p)$$

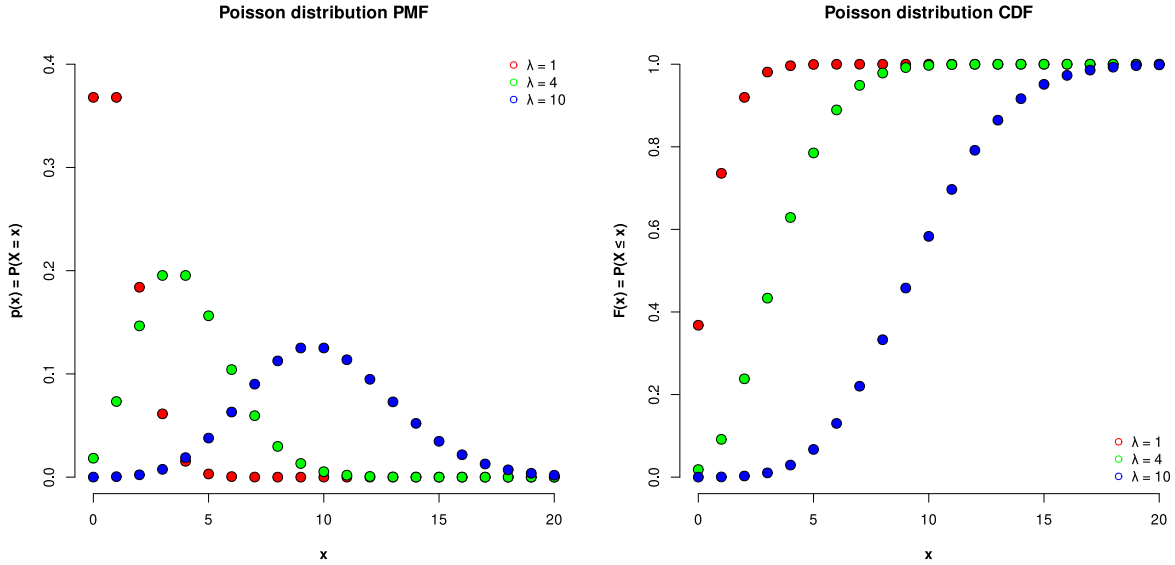
Where  $E(Y_i)$  and  $V(Y_i)$  are retrieved from Theorem 1.5.1.1.

□

Binomial random variables model experiments composed by many mutually exclusive results.

### 1.5.3. Poisson random variable

Let  $Y$  a binomial random variable, and let  $\lambda \in \mathbb{R}^+$  be the product of its parameters  $n$  and  $p$ . By applying the double limit  $n \rightarrow \infty, p \rightarrow 0$  while keeping their product constant a new random variable  $X$  is constructed, called a **Poisson random variable** (denoted as  $X \sim \text{Pois}(\lambda)$ ). The pdf and cdf of a Poisson random variable  $X$  of parameter  $\lambda$  are therefore as follows:



$$p(x) = P(X = x) = \begin{cases} \frac{\lambda^x}{x!} e^{-\lambda} & \text{if } x \in \mathbb{N} \\ 0 & \text{otherwise} \end{cases}$$

$$F(x) = P(X \leq x) = \sum_{k \in \mathbb{N}, k \leq x} \frac{\lambda^k}{k!} e^{-\lambda}$$

**Theorem 1.5.3.1:** The expected value and variance of a random variable  $X \sim \text{Pois}(\lambda)$  are as follows:

$$E(X) = \lambda$$

$$V(X) = \lambda$$

*Proof:* Let  $Y \sim \text{Bi}(n, p)$  be a random variable to which the double limit  $n \rightarrow \infty, p \rightarrow 0$  is applied, and let  $\lambda = np$ . This results in:

$$E(X) = \lim_{\substack{n \rightarrow \infty \\ p \rightarrow 0}} E(Y) = \lim_{\substack{n \rightarrow \infty \\ p \rightarrow 0}} np = \lambda \quad V(X) = \lim_{\substack{n \rightarrow \infty \\ p \rightarrow 0}} V(Y) = \lim_{\substack{n \rightarrow \infty \\ p \rightarrow 0}} np(1-p) = \lambda(1-0) = \lambda$$

□

**Exercise 1.5.3.1:** Let  $X$  be the number of traps occurring in a particular type of transistor. Suppose  $X \sim \text{Pois}(2)$ ; what is the probability of retrieving 3 traps? What is the probability of retrieving 3 or less traps?

*Solution:*

$$p(3) = P(X = 3) = \frac{2^3}{3!}e^{-2} = \frac{8}{6}e^{-2} \approx 0.18$$

$$\begin{aligned} F(3) = P(X \leq 3) &= \sum_{k \in \mathbb{N}, k \leq 3} \frac{2^k}{k!}e^{-2} = \\ &= \frac{2^0}{0!}e^{-2} + \frac{2^1}{1!}e^{-2} + \frac{2^2}{2!}e^{-2} + \frac{2^3}{3!}e^{-2} = \\ &= e^{-2} \left( \frac{1}{1} + \frac{2}{1} + \frac{4}{2} + \frac{8}{6} \right) = e^{-2} \frac{19}{3} \approx 0.86 \end{aligned}$$

□

The Poisson distribution model events where the size of the population is very large and the probability of the event to occur is very small. This is why the Poisson distribution is used to model *rare events*, events that have a very slim, but still relevant, probability to occur in a certain span of time. More formally, a rare event can be modeled as such if the following properties hold:

1. There exist a parameter  $\alpha > 0$  such that for any short time interval of length  $\Delta t$ , the probability that exactly one event occurs is  $\alpha \Delta t \cdot o(\Delta t)$ , where  $o(\Delta t)$  is a little-o of  $\Delta t$ ;
2. The probability of more than one event occurring during  $\Delta t$  is  $o(\Delta t)$ . In other words, it is much more likely that a single event happens during  $\Delta t$  than multiple events occur;
3. The number of events occurring during the time interval  $\Delta t$  is independent of the number that occur prior to this time interval.

The probability mass function of a Poisson distribution can be adapted in this sense if, instead of the expected value  $\lambda$ , one is given  $\alpha$ , the expected number of events occurring in a unitary time interval, and a time interval  $\Delta t$ . The probability of  $k$  events to occur in a time slice  $\Delta t$  is then as follows:

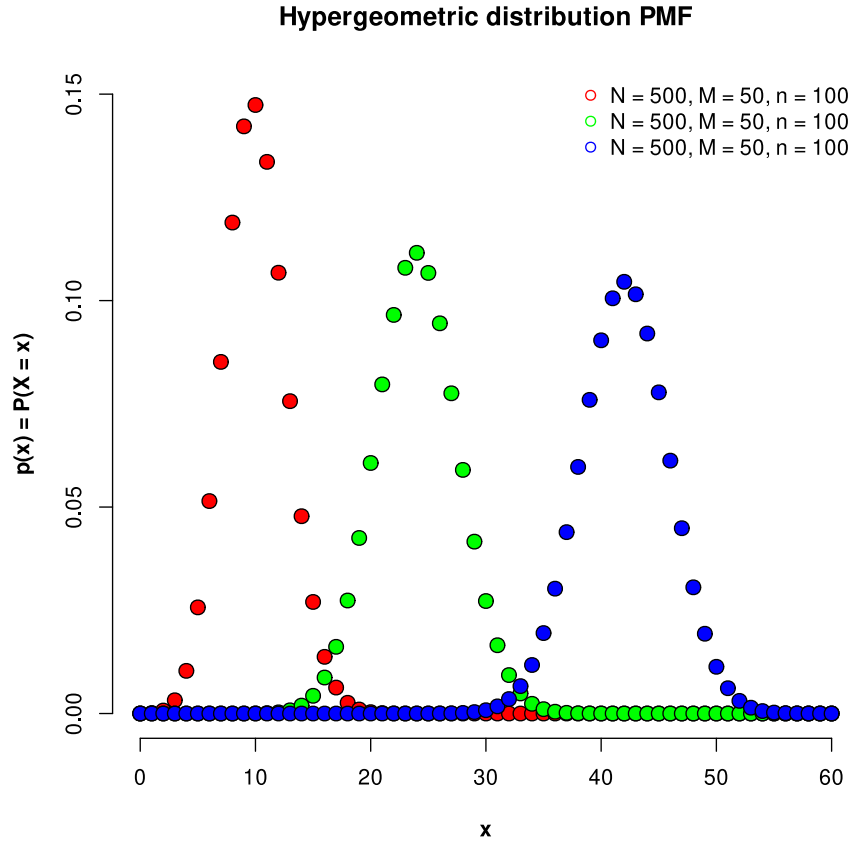
$$p_k(\Delta t) = \frac{(\alpha \Delta t)^k}{k!} e^{-\alpha \Delta t}$$

The occurrence of events over time as described is called a **Poisson process** and the parameter  $\alpha$  specifies the *rate* of said process.

#### 1.5.4. Hypergeometric random variable

Let  $N$  be the size of a population of individuals, each of them having associated either a value of 1 (success) or 0 (failure). Let  $M$  be the number of individuals whose value is 1, and therefore  $N - M$  is the number of individuals whose number is 0. Let  $n \leq N$  be the size of a sample extracted from the population. The random variable  $X$  whose values are the number of successes (of 1s) found in a sample of size  $n$  is said to be distributed as an **hypergeometric random variable** (denoted  $X \sim H(n, N, M)$ ). The pdf of an hypergeometric random variable  $X$  of parameters  $M$ ,  $N$  and  $n$  is therefore as follows:





$$p(x) = P(X = x) = \begin{cases} \frac{\binom{M}{x} \binom{N-M}{n-x}}{\binom{N}{n}} & \text{if } \max(0, n - N + M) \leq x \leq \min(n, M) \\ 0 & \text{otherwise} \end{cases}$$

The binomial  $\binom{M}{x}$  is the number of ways it is possible to extract a sample where there are  $x$  individuals whose value is 1, while the binomial  $\binom{N-M}{n-x}$  is the number of ways it is possible to extract a sample where there are  $n - x$  individuals whose value is 0. The binomial  $\binom{N}{n}$  is the number of combinations of elements of  $N$  of size  $n$  (without any requirement on the number of individuals having a particular value).

The constraint  $x \leq \min(n, M)$  denotes that the number of observed successes cannot be greater than the size of the entire sample (and, of course, cannot be greater than the size of the entire population).

**Exercise 1.5.4.1:** A university IT office received 20 service orders for issues with printers, out of which 8 were laser printers and 12 were inkjet printers. A sample of 5 of these service orders were selected to perform a customer satisfaction survey. What is the probability that, out of those 5, 2 were inkjet printers?

*Solution:* It is possible to model this situation with an hypergeometric random variable. Since the outcome of interest is the one related to inkjet printers, the parameters of said variable  $X$  will be 5 for the sample size, 20 for the population size and 12 for the favorable population size. Therefore,  $X \sim (5, 20, 12)$ . Evaluating the pdf for  $X = 2$  gives:

$$\begin{aligned}
 p(2) = P(X=2) &= \frac{\binom{12}{2} \binom{20-12}{5-2}}{\binom{20}{5}} = \frac{\frac{12!}{2!(12-2)!} \frac{8!}{3!(8-3)!}}{\frac{20!}{5!(20-5)!}} = \frac{\frac{12 \cdot 11 \cdot 10!}{2 \cdot 1!} \frac{8 \cdot 7 \cdot 6 \cdot 5!}{6 \cdot 5!}}{\frac{20 \cdot 19 \cdot 18 \cdot 17 \cdot 16 \cdot 15!}{120 \cdot 15!}} = \\
 &= \frac{12 \cdot 11 \cdot 8 \cdot 7 \cdot 6}{12} \cdot \frac{20 \cdot 6}{20 \cdot 19 \cdot 18 \cdot 17 \cdot 16} = \frac{22176}{93024} \approx 0.238
 \end{aligned}$$

□

**Theorem 1.5.4.1:** The expected value and variance of a random variable  $X \sim H(n, N, M)$  are as follows:

$$E(X) = n \cdot \frac{M}{N} \qquad V(X) = \left( \frac{N-n}{N-1} \right) \cdot n \cdot \frac{M}{N} \cdot \left( 1 - \frac{M}{N} \right)$$

The hypergeometric distribution is distinguished from the binomial distribution because the trials are not independent, since each time an individual is “inspected” it is removed from the sample, and therefore the subsequent probabilities are influenced by the outcome (since the number of individuals is decreased). By contrast, in the binomial distribution each trial is independent from the others.

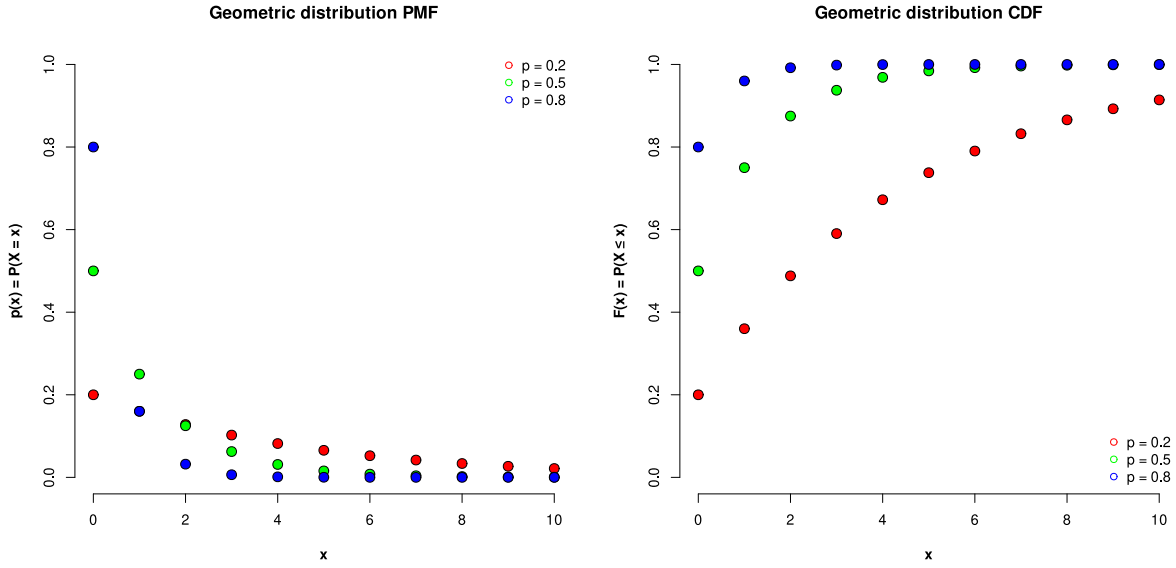
Another similarity between the two comes from observing the equations in Theorem 1.5.4.1. The ratio  $M/N$  is the proportion of successes in the population, meaning that it’s the probability of picking an element of the entire population that has a value 1. This ratio has the same role that the parameter  $p$  has in the binomial distribution. Indeed, substituting  $M/N$  with  $p$  in said equations gives:

$$E(X) = np \qquad V(X) = \left( \frac{N-n}{N-1} \right) \cdot np(1-p)$$

Where the expected value is identical to the one of a binomial distributed random variable (Theorem 1.5.2.1), while the variance differs for a factor  $(N-n)/(N-1)$ . Since this factor, called **finite population correction factor**, is always less than 1, the variance of an hypergeometric random variable will always be smaller than a binomial random variable where  $p = M/N$ .

### 1.5.5. Geometric random variable

Let  $X$  be a random variable that represents the number of (failed) attempts necessary to have a Bernoulli random variable with parameter  $p$  to assume value 1. The random variable  $X$  is said to be distributed as a **geometric random variable** (denoted  $X \sim G(p)$ ). The pdf and cdf of a geometric random variable  $X$  of parameter  $p$  are therefore as follows:



$$p(x) = P(X = x) = \begin{cases} p(1-p)^x & \text{if } x \in \mathbb{N} \\ 0 & \text{otherwise} \end{cases}$$

$$F(x) = P(X \leq x) = \sum_{k \in \mathbb{N}, k \leq x} p(1-p)^k$$

The factor  $(1-p)^x$  represents the probability of obtaining a failure for exactly  $x$  times. This factor is then multiplied by  $p$ , which is the probability of obtaining a single success.

A geometric distribution  $X \sim G(p)$  has a property called **memorylessness**, expressed mathematically as  $P(X > x + y \mid X > y) = P(X > x)$  with  $x$  and  $y$  positive integers. In other words, the number of attempts necessary for an experiment to have a specific result does not depend on the previous ones.

**Theorem 1.5.5.1:** The expected value and variance of a random variable  $X \sim G(p)$  are as follows:

$$E(X) = \frac{1-p}{p}$$

$$V(X) = \frac{1-p}{p^2}$$

*Proof:* This result can be proven by applying known theorems concerning geometric functions:

$$\begin{aligned} E(X) &= p(1-p)^0 \cdot 0 + p(1-p)^1 \cdot 1 + p(1-p)^2 \cdot 2 + \dots = p(1-p) + 2p(1-p)^2 + 3p(1-p)^3 + \dots = \\ &= \sum_{i=0}^{\infty} ip(1-p)^i = p \sum_{i=0}^{\infty} i(1-p)^i = p(1-p) \sum_{i=0}^{\infty} i(1-p)^{i-1} = p(1-p) \left[ \frac{d}{dp} \left( -\sum_{i=0}^{\infty} (1-p)^i \right) \right] = \\ &= p(1-p) \frac{d}{dp} \left( -\frac{1}{p} \right) = p(1-p) \left( \frac{1}{p^2} \right) = \frac{1-p}{p} \end{aligned}$$

Then, applying Lemma 1.4.1:

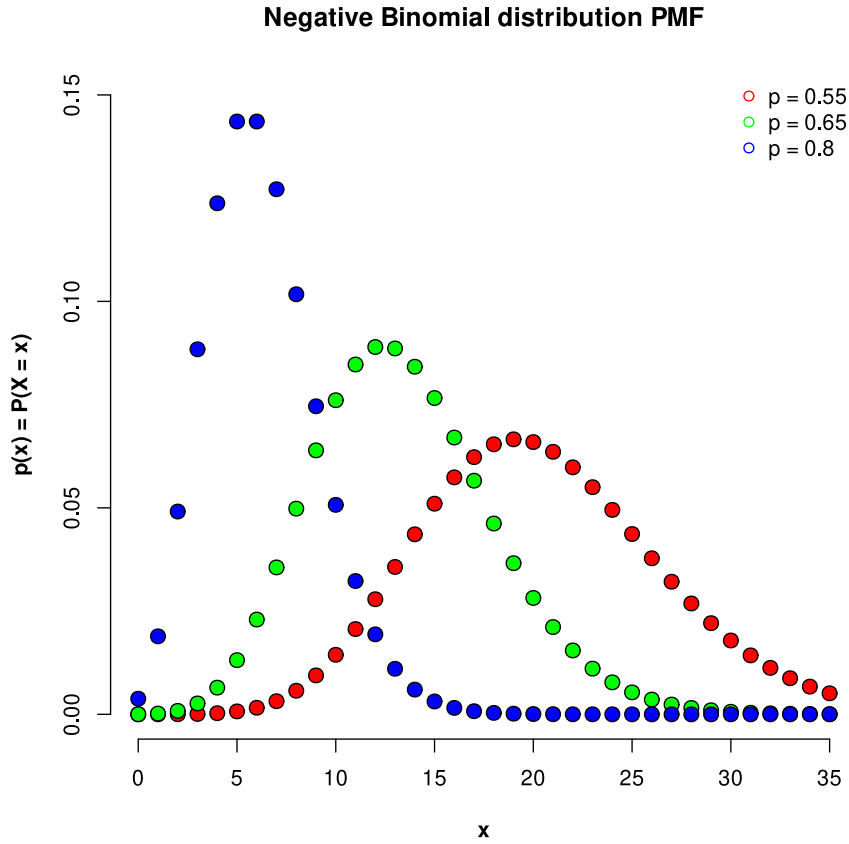
$$\begin{aligned} V(X) &= E(X^2) - (E(X))^2 = \frac{(2-p)(1-p)}{p^2} - \left( \frac{1-p}{p} \right)^2 = \frac{2-2p-p+p^2}{p^2} - \frac{1+p^2-2p}{p^2} = \\ &= \frac{2-3p+p^2-1-p^2+2p}{p^2} = \frac{1-p}{p^2} \end{aligned}$$

□

### 1.5.6. Negative binomial random variable

Let  $X$  be a random variable that represents the number of (failed) attempts necessary to have a Bernoulli random variable with parameter  $p$  to assume value 1 for  $r$  times. The random variable  $X$  is said to be distributed as a

**negative binomial random variable** (denoted  $X \sim NB(r, p)$ ). The pdf of a negative binomial random variable  $X$  of parameters  $r$  and  $p$  is therefore as follows:



$$p(x) = P(X = x) = \begin{cases} \binom{x+r-1}{r-1} p^r (1-p)^x & \text{if } x \in \mathbb{N} \\ 0 & \text{otherwise} \end{cases}$$

The factor  $(1-p)^x$  represents the probability of obtaining a failure for exactly  $x$  times. The factor  $p^r$  represents the probability of obtaining a success  $r$  times. The factor  $\binom{x+r-1}{r-1}$  represents the number of ways that  $r-1$  successes out of  $x+r-1$  attempts can be arranged.

Of course, if  $r$  is set to 1 said random variable reduces itself to a geometric random variable:

$$\binom{x+1-1}{1-1} p^1 (1-p)^x = \binom{x}{0} p (1-p)^x = \left( \frac{x!}{0!(x-0)!} \right) p (1-p)^x = \left( \frac{x!}{x!} \right) p (1-p)^x = p (1-p)^x$$

## 1.6. Continuous random variables

The **probability density function** (abbreviated as pdf) of a continuous random variable  $X$  is a function  $f(x)$  such that, for any pair of numbers  $a$  and  $b$ :

$$P(a \leq X \leq b) = \int_a^b f(x) dx$$

That is, the probability of the random variable  $X$  to assume a value that lies in the  $[a, b]$  interval is equal to the integral of  $f(x)$  with said points as extremes, which is also the area under the curve of  $f(x)$  in the interval  $[a, b]$ .

Any function can be a pdf as long as it satisfies the following two conditions:

$$\forall x, f(x) \geq 0$$

$$\int_{-\infty}^{+\infty} f(x)dx = 1$$

**Exercise 1.6.1:** Suppose that the chance of having imperfection on the surface of a tire can be described as a random variable. Let  $X$  be the angle induced by any vector that goes from the centre of the tire to its surface. Suppose the probability distribution function of  $X$  is given by:

$$f(x) = \begin{cases} \frac{1}{360} & \text{if } 0 \leq x \leq 360 \\ 0 & \text{otherwise} \end{cases}$$

Is this probability distribution function well-defined? If it is, what is the probability of finding an imperfection between the angles 90 and 180?

*Solution:* This pdf can assume either 0 or  $\frac{1}{360}$  as its values, therefore the first condition is satisfied. As for the second condition:

$$\int_{-\infty}^{+\infty} f(x)dx = \int_{-\infty}^0 0dx + \int_0^{360} \frac{1}{360}dx + \int_0^{+\infty} 0dx = \frac{1}{360} \int_0^{360} 1dx = \frac{1}{360}(360 - 0) = \frac{360}{360} = 1$$

The requested probability is:

$$P(90 \leq X \leq 180) = \int_{90}^{180} \frac{1}{360}dx = \frac{1}{360} \int_{90}^{180} 1dx = \frac{1}{360}(180 - 90) = \frac{90}{360} = 0.25$$

□

The **cumulative distribution function** (abbreviated as cdf) of a continuous random variable  $X$ , denoted as  $F(X)$ , is defined as the probability of such random variable to assume a value less than or equal to a threshold. Given a random variable  $X$ , its cdf is defined as:

$$F(x) = P(X \leq x) = \int_{-\infty}^x f(t)dt$$

Given  $F(a)$ , the probability of a random variable to assume a value less than or equal to  $a$ , it is possible to compute  $P(X > a)$ , the probability of said random variable to assume a value greater than  $a$ , since the two events are the complement of each other:

$$P(X > a) = 1 - P(X \leq a) = 1 - F(a)$$

**Lemma 1.6.1:** Let  $X$  be a random variable, and let  $a$  and  $b$  be two real numbers (suppose  $a < b$ ). The following holds:

$$P(a < X \leq b) = F(b) - F(a)$$

*Proof:* By definition, the events  $A = \text{“the realization of } X \text{ lies in } (-\infty, a] \text{”}$  and  $B = \text{“the realization of } X \text{ lies in } (a, b] \text{”}$  are incompatible. Therefore:

$$\begin{aligned} P(-\infty < X \leq a) + P(a < X \leq b) - P(\{-\infty < X \leq a\} \cap \{a < X \leq b\}) = \\ P(-\infty < X \leq a) + P(a < X \leq b) - 0 = P(\{-\infty < X \leq a\} \cup \{a < X \leq b\}) \end{aligned}$$

From which stems:

$$\begin{aligned} F(b) = P(-\infty < X \leq b) = P(\{-\infty < X \leq a\} \cup \{a < X \leq b\}) = \\ P(-\infty < X \leq a) + P(a < X \leq b) = F(a) + P(a < X \leq b) \Rightarrow F(b) - F(a) = P(a < X \leq b) \end{aligned}$$

□

**Corollary 1.6.1:** The probability of a continuous random variable  $X$  to assume a specific value  $c$  is always 0.

*Proof:*  $P(X = c)$  is equivalent to  $P(c < X \leq c)$ . Therefore Lemma 1.6.1 applies:

$$P(c < X \leq c) = F(c) - F(c) = 0$$

□

Corollary 1.6.1 is sound even from a logical perspective: the probability of choosing a specific value in (a subset of)  $\mathbb{R}$  is necessarily infinitesimal, since  $\mathbb{R}$  is not a countable set. Therefore, when dealing with the realization of a continuous random variables, it only makes sense to think in terms of intervals.

Let  $X$  be a continuous random variable probability distribution function  $f(x)$ . The **expected value** (or **mean value**) of  $X$ , denoted as  $E(X)$  or  $\mu_X$  is given by:

$$E(X) = \mu_X = \int_{-\infty}^{+\infty} x \cdot f(x) dx$$

When the variable  $X$  is known, the pedix  $X$  in  $\mu_X$  is omitted.

Let  $X$  be a continuous random variable probability distribution function  $f(x)$ . The **variance** of  $X$ , denoted as  $V(X)$  or  $\sigma_X^2$  is given by:

$$V(X) = \sigma_X^2 = \int_{-\infty}^{+\infty} (x - E(X))^2 \cdot f(x) dx = E((X - E(X))^2)$$

When the variable  $X$  is known, the pedix  $X$  in  $\sigma_X^2$  is omitted.

The square root of the variance is called the **standard deviation**:

$$SD(X) = \sigma_X = \sqrt{V(X)}$$

Let  $p$  be a real number between 0 and 1. The **(100p)-th percentile** of the distribution of a continuous random variable  $X$ , denoted as  $\eta(p)$  is defined by:

$$p = F(\eta(p)) = \int_{-\infty}^{\eta(p)} f(t) dt$$

That is, the cumulative distribution function of  $X$  evaluated at  $\eta(p)$ .

**Exercise 1.6.2:** The amount of gravel (in tons) sold by a particular construction supply company in a given week can be modeled as a continuous random variable  $X$  with pdf:

$$f(x) = \begin{cases} \frac{3}{2}(1 - x^2) & \text{if } 0 \leq x \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

What is the cdf of  $X$ ? What are the expected value and the variance of  $X$ ? What is the 50-th percentile?

*Solution:* The cdf of  $X$  is clearly 0 for any  $x$  lower than 0 and 1 for any  $x$  greater than 1. As for  $x \in [0, 1]$ :

$$\begin{aligned}
F(x) &= \int_{-\infty}^x f(t)dt = \int_{-\infty}^0 f(t)dt + \int_0^x f(t)dt = 0 + \int_0^x \frac{3}{2}(1-t^2)dt = \frac{3}{2} \left( \int_0^x 1dt - \int_0^x t^2 dt \right) = \\
&\quad \frac{3}{2} \left[ (x-0) - \left( \frac{x^3}{3} - \frac{0^3}{3} \right) \right] = \frac{3}{2} \left( x - \frac{x^3}{3} \right) = \frac{1}{2}x(3-x^2)
\end{aligned}$$

The expected value is given by computing the integral:

$$\begin{aligned}
E(X) &= \int_{-\infty}^{+\infty} x \cdot f(x)dx = \int_{-\infty}^0 x \cdot f(x)dx + \int_0^1 x \cdot f(x)dx + \int_1^{+\infty} x \cdot f(x)dx = \\
&= 0 + \int_0^1 x \cdot \frac{3}{2}(1-x^2)dx + 0 = \frac{3}{2} \int_0^1 x - x^3 dx = \frac{3}{2} \left( \int_0^1 x dx - \int_0^1 x^3 dx \right) = \\
&\quad \frac{3}{2} \left( \left( \frac{1^2}{2} - \frac{0^2}{2} \right) - \left( \frac{1^4}{4} - \frac{0^4}{4} \right) \right) = \frac{3}{2} \left( \frac{1}{2} - \frac{1}{4} \right) = \frac{3}{8}
\end{aligned}$$

As for the variance:

$$\begin{aligned}
V(X) &= E(X^2) - (E(X))^2 = -\left(\frac{3}{8}\right)^2 + \int_{-\infty}^{+\infty} x^2 \cdot f(x)dx = -\frac{9}{64} + \int_{-\infty}^0 x^2 \cdot f(x)dx + \\
&\quad \int_0^1 x^2 \cdot f(x)dx + \int_1^{+\infty} x^2 \cdot f(x)dx = -\frac{9}{64} + 0 + \int_0^1 x^2 \cdot \frac{3}{2}(1-x^2)dx + 0 = -\frac{9}{64} + \frac{3}{2} \int_0^1 x^2 - x^4 dx = \\
&= -\frac{9}{64} + \frac{3}{2} \left( \int_0^1 x^2 dx - \int_0^1 x^4 dx \right) = -\frac{9}{64} + \frac{3}{2} \left( \left( \frac{1^3}{3} - \frac{0^3}{3} \right) - \left( \frac{1^5}{5} - \frac{0^5}{5} \right) \right) = -\frac{9}{64} + \frac{3}{2} \left( \frac{1}{3} - \frac{1}{5} \right) = \frac{19}{320}
\end{aligned}$$

The 50-th percentile is given when  $p = 0.5$ . Applying the formula gives:

$$0.5 = F(\eta(p)) = \frac{1}{2}\eta(p)(3 - (\eta(p))^2) \Rightarrow (\eta(p))^3 - 3\eta(p) + 1 = 0 \Rightarrow \eta(p) \approx 0.347$$

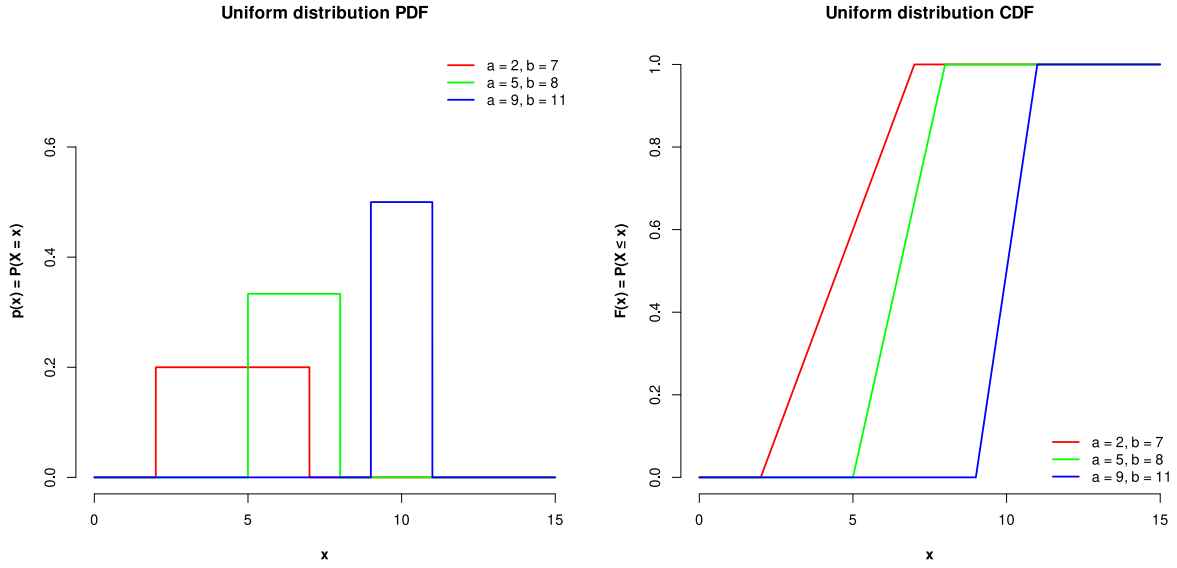
□

## 1.7. Known continuous random variables

Some specific continuous random variables have been studied extensively, mostly because they model very well many phenomena in the real world. For this reason, such random variables have proper names. To denote that a random variable  $X$  has the same distribution as a known random variable  $F$ , the notation  $X \sim F$  is used.

### 1.7.1. Uniform random variable

A continuous random variable  $X$  is distributed as a **uniform random variable** of parameters  $a$  and  $b$  (denoted as  $X \sim U(a, b)$ ) if the pdf and cdf of said variable are:



$$f(x) = \begin{cases} \frac{1}{b-a} & \text{if } a \leq x \leq b \\ 0 & \text{otherwise} \end{cases}$$

$$F(x) = \begin{cases} 0 & \text{if } x < a \\ \frac{x-a}{b-a} & \text{if } a \leq x \leq b \\ 1 & \text{if } x > b \end{cases}$$

Indeed, the relation between the two holds:

$$\int_{-\infty}^x f(t)dt = \int_{-\infty}^a f(t)dt + \int_a^x f(t)dt = 0 + \int_a^x \frac{1}{b-a}dt = \frac{1}{b-a} \int_a^x 1dt = \frac{1}{b-a}(x-a) = \frac{x-a}{b-a}$$

**Theorem 1.7.1.1:** The expected value and variance of a random variable  $X \sim U(a, b)$  are as follows:

$$E(X) = \frac{b+a}{2}$$

$$V(X) = \frac{(b-a)^2}{12}$$

*Proof:*

$$\begin{aligned} E(X) &= \int_{-\infty}^{+\infty} x \cdot f(x)dx = \int_{-\infty}^a x \cdot f(x)dx + \int_a^b x \cdot f(x)dx + \int_b^{+\infty} x \cdot f(x)dx = \\ &= 0 + \int_a^b x \left( \frac{1}{b-a} \right) dx + 0 = \frac{1}{b-a} \int_a^b x dx = \frac{1}{b-a} \left( \frac{b^2}{2} - \frac{a^2}{2} \right) = \frac{1}{(b-a)} \frac{(b-a)(b+a)}{2} = \frac{b+a}{2} \end{aligned}$$

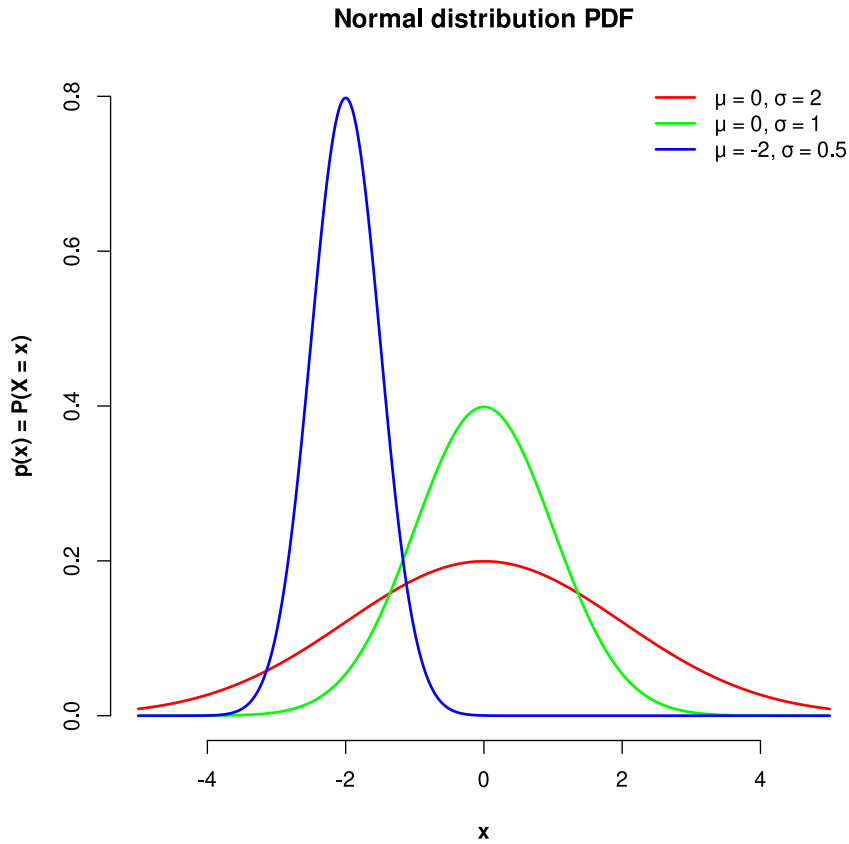


$$\begin{aligned}
V(X) &= \int_{-\infty}^{+\infty} (x - E(X))^2 \cdot f(x) dx = \int_{-\infty}^a (x - E(X))^2 \cdot f(x) dx + \int_a^b (x - E(X))^2 \cdot f(x) dx + \\
&\quad \int_b^{+\infty} (x - E(X))^2 \cdot f(x) dx = 0 + \int_a^b \left(x - \frac{b+a}{2}\right)^2 \left(\frac{1}{b-a}\right) dx + 0 = \\
&\quad \frac{1}{b-a} \int_a^b x^2 + \frac{(b+a)^2}{4} - (b+a)x dx = \frac{1}{b-a} \left( \int_a^b x^2 dx + \int_a^b \frac{(b+a)^2}{4} dx - \int_a^b (b+a)x dx \right) = \\
&\quad \frac{1}{b-a} \int_a^b x^2 dx + \frac{(b+a)^2}{4(b-a)} \int_a^b 1 dx - \frac{b+a}{b-a} \int_a^b x dx = \frac{1}{b-a} \left( \frac{b^3}{3} - \frac{a^3}{3} \right) + \frac{(b+a)^2}{4(b-a)} (b-a) - \\
&\quad \frac{b+a}{b-a} \left( \frac{b^2}{2} - \frac{a^2}{2} \right) = \frac{1}{(b-a)} \frac{(b-a)(b^2 + ba + a^2)}{3} + \frac{(b+a)^2}{4} - \frac{b+a}{(b-a)} \frac{(b-a)(b+a)}{2} = \\
&\quad \frac{(b+a)^2 - ba}{3} + \frac{(b+a)^2}{4} - \frac{(b+a)^2}{2} = \frac{4(b+a)^2 - 4ba + 3(b+a)^2 - 6(b+a)^2}{12} = \\
&\quad \frac{(b+a)^2 - 4ba}{12} = \frac{b^2 + a^2 + 2ba - 4ba}{12} = \frac{b^2 + a^2 - 2ba}{12} = \frac{(b-a)^2}{12}
\end{aligned}$$

□

### 1.7.2. Normal random variable

A continuous random variable  $X$  is distributed as a **normal random variable** (or **Gaussian random variable**) of parameters  $\mu$  and  $\sigma$  with  $-\infty < \mu < +\infty$  and  $\sigma > 0$  (denoted as  $X \sim N(\mu, \sigma)$ ) if the pdf of said variable is:



$$f(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

Where  $\mu$  and  $\sigma$  are respectively the expected value and the standard deviation of the random variable. The normal random variable is the most important distribution in statistics, since it models many real world phenomena (IQ score, anthropometric measures, economic indicators, ecc...).

The distribution  $Z \sim N(0, 1)$ , that is to say the normal distribution of parameters  $\mu = 0$  and  $\sigma = 1$ , is called the **standard normal distribution**, having pdf:

$$f(z) = \frac{e^{-\frac{z^2}{2}}}{\sqrt{2\pi}}$$

Even though it is possible to compute the cdf of a normal random variable  $X$  by integrating its pdf, said computation is very hard since it's not approachable with standard integration techniques. Despite this, the values of the cdf of the standard normal distribution for most common values are known and provided in table form. The cdf of  $Z \sim N(0, 1)$  evaluated at  $z$  is denoted as  $\Phi(z)$ .

The cdf of the standard normal distribution is sufficient to also compute the cdf for any given random variable  $X \sim N(\mu, \sigma)$ . Infact, the **standardized** version of any  $X$ , which is given by subtracting the expected value of  $X$  from  $X$  and dividing the result by its standard deviation, is a standard normal distribution:

$$Z = \frac{X - \mu}{\sigma} \sim N(0, 1)$$

Infact, subtracting  $E(X) = \mu$  from  $X$  sets its new expected value to 0 and dividing the result by  $SD(X) = \sigma$  sets its new variance to 1:

$$E(Z) = E\left(\frac{X - E(X)}{SD(X)}\right) = \frac{1}{SD(X)}E(X - E(X)) = \frac{1}{SD(X)}(E(X) - E(X)) = \frac{0}{SD(X)} = 0$$

$$SD(Z) = V\left(\frac{X - E(X)}{SD(X)}\right) = \frac{1}{(SD(X))^2}V(X - E(X)) = \frac{V(X) - 0}{(SD(X))^2} = \frac{V(X)}{V(X)} = 1$$

Since the values of the cdf of  $Z$  are known, it is possible to compute the values for the cdf (and pdf) of  $X$  by computing the ones for  $(X - \mu)/\sigma$ :

$$P(a < X \leq b) = P\left(\frac{a - \mu}{\sigma} < \frac{X - \mu}{\sigma} \leq \frac{b - \mu}{\sigma}\right) = P\left(\frac{a - \mu}{\sigma} < Z \leq \frac{b - \mu}{\sigma}\right) = \Phi\left(\frac{b - \mu}{\sigma}\right) - \Phi\left(\frac{a - \mu}{\sigma}\right)$$

$$F(a) = P(X \leq a) = P\left(\frac{X - \mu}{\sigma} \leq \frac{a - \mu}{\sigma}\right) = P\left(Z \leq \frac{a - \mu}{\sigma}\right) = \Phi\left(\frac{a - \mu}{\sigma}\right)$$

**Exercise 1.7.2.1:** Suppose that the time a car driver takes to react to the brake lights on a decelerating vehicle can be modeled as a normal distribution of parameters  $\mu = 1.25$  seconds and  $\sigma = 0.46$  seconds. What is the probability that the reaction time lies between 1 second and 1.75 seconds? And the probability of it being greater than 2 seconds?

*Solution:*

$$P(1 < X \leq 1.75) = P\left(\frac{1 - 1.25}{0.46} < \frac{X - 1.25}{0.46} \leq \frac{1.75 - 1.25}{0.46}\right) = P\left(\frac{-0.25}{0.46} < Z \leq \frac{0.5}{0.46}\right) \approx$$

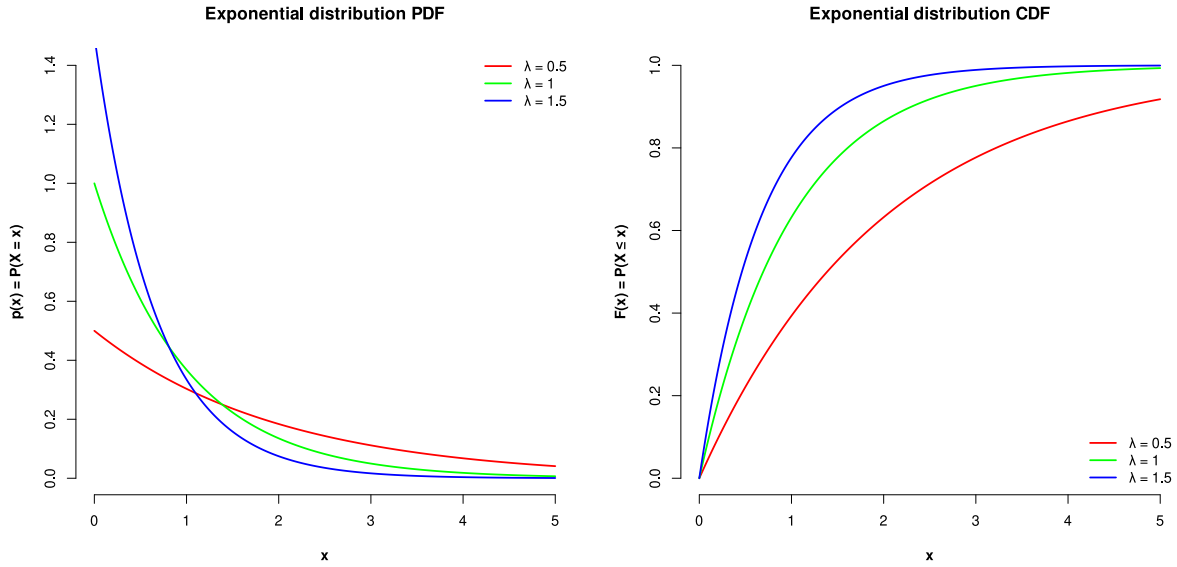
$$\Phi(1.09) - \Phi(-0.54) = \Phi(1.09) - (1 - \Phi(0.54)) = 0.8621 - 0.2946 = 0.5675$$

$$P(X > 2) = 1 - P(X \leq 2) = 1 - P\left(\frac{X - 1.25}{0.46} \leq \frac{2 - 1.25}{0.46}\right) \approx 1 - \Phi(1.63) = 1 - 0.9484 = 0.0516$$

□

### 1.7.3. Exponential random variable

A continuous random variable  $X$  is distributed as an **exponential random variable** of parameter  $\lambda$  with  $\lambda > 0$  (denoted as  $X \sim E(\lambda)$ ) if the pdf and cdf of said variable are:



$$f(x) = \begin{cases} \lambda e^{-\lambda x} & \text{if } x \geq 0 \\ 0 & \text{otherwise} \end{cases}$$

$$F(x) = \begin{cases} 1 - e^{-\lambda x} & \text{if } x \geq 0 \\ 0 & \text{otherwise} \end{cases}$$

Indeed, the relation between the two holds:

$$\int_{-\infty}^x f(t)dt = \int_{-\infty}^0 f(t)dt + \int_0^x f(t)dt = 0 + \int_0^x \lambda e^{-\lambda t}dt = \int_0^{-\lambda x} X \frac{-1}{X} e^u du = -(e^{-\lambda x} - e^0) = 1 - e^{-\lambda x}$$

**Theorem 1.7.3.1:** The expected value and variance of a random variable  $X \sim E(\lambda)$  are as follows:

$$E(X) = \frac{1}{\lambda}$$

$$V(X) = \frac{1}{\lambda^2}$$

*Proof:*

$$\begin{aligned} E(X) &= \int_{-\infty}^{+\infty} x \cdot f(x)dx = \int_{-\infty}^0 x \cdot f(x)dx + \int_0^{+\infty} x \cdot f(x)dx = 0 + \int_0^{+\infty} \lambda x e^{-\lambda x} dx = \\ &= - \int_0^{+\infty} x (-\lambda e^{-\lambda x}) dx = -[x e^{-\lambda x}]_0^{+\infty} + \int_0^{+\infty} e^{-\lambda x} dx = -(\infty \cdot e^{-\lambda \cdot \infty} - 0 \cdot e^{-\lambda \cdot 0}) + \int_0^{+\infty} \frac{e^u}{-\lambda} du = \\ &= -0 - \frac{1}{\lambda} \int_0^{+\infty} e^u du = \frac{1}{\lambda} \int_{-\infty}^0 e^u du = \frac{1}{\lambda} (e^0 - e^{-\infty}) = \frac{1}{\lambda} (1 - 0) = \frac{1}{\lambda} \end{aligned}$$

$$\begin{aligned}
V(X) &= E(X^2) - (E(X))^2 = -\left(\frac{1}{\lambda}\right)^2 + \int_{-\infty}^{+\infty} x^2 \cdot f(x) dx = -\frac{1}{\lambda^2} + \int_{-\infty}^0 x^2 \cdot f(x) dx + \\
&\int_0^{+\infty} x^2 \cdot f(x) dx = -\frac{1}{\lambda^2} + 0 + \int_0^{+\infty} \lambda x^2 e^{-\lambda x} dx = -\frac{1}{\lambda^2} - \int_0^{+\infty} x^2 (-\lambda e^{-\lambda x}) dx = \\
&-\frac{1}{\lambda^2} - [x^2 e^{-\lambda x}]_0^{\infty} + \int_0^{+\infty} 2x e^{-\lambda x} dx = -\frac{1}{\lambda^2} - (\infty^2 \cdot e^{-\lambda \cdot \infty^2} - 0^2 \cdot e^{-\lambda \cdot 0^2}) - \\
&\frac{2}{\lambda} \int_0^{+\infty} x (-\lambda e^{-\lambda x}) dx = -\frac{1}{\lambda^2} - 0 - \frac{2}{\lambda} \int_0^{+\infty} x (-\lambda e^{-\lambda x}) dx = -\frac{1}{\lambda^2} - \frac{2}{\lambda} [x e^{-\lambda x}]_0^{\infty} \\
&+ \frac{2}{\lambda} \int_0^{+\infty} e^{-\lambda x} dx = -\frac{1}{\lambda^2} - \frac{2}{\lambda} (\infty \cdot e^{-\lambda \cdot \infty} - 0 \cdot e^{-\lambda \cdot 0}) + \frac{2}{\lambda} \int_0^{-\infty} \frac{e^u}{-\lambda} du = -\frac{1}{\lambda^2} - 0 - \\
&\frac{2}{\lambda^2} \int_0^{-\infty} e^u du = -\frac{1}{\lambda^2} + \frac{2}{\lambda^2} \int_{-\infty}^0 e^u du = -\frac{1}{\lambda^2} + \frac{2}{\lambda^2} (e^0 - e^{-\infty}) = -\frac{1}{\lambda^2} + \frac{2}{\lambda^2} = \frac{1}{\lambda^2}
\end{aligned}$$

□

**Exercise 1.7.3.1:** Suppose that the stress range of a certain bridge connection (measured in Megapascal) can be modeled as an exponential distribution  $X$  with expected value equal to 6. What is the probability of the stress to be less than or equal to 10 Megapascal?

*Solution:* If the expected value of  $X$  is 6, since the expected value of an exponential distribution is  $1/\lambda$  the lambda parameter of  $X$  is  $\lambda = 0.1667$ .

$$P(X \leq 10) = F(10) = 1 - e^{-0.1667 \cdot 10} = 1 - e^{-1.667} \approx 1 - 0.189 = 0.811$$

□

The exponential distribution and the Poisson distribution are closely related. Indeed, suppose that the number of events occurring in any time interval of length  $\Delta t$  has a Poisson distribution with parameter  $\alpha \Delta t$  (where alpha, the rate of the event process, is the expected number of events occurring in 1 unit of time) and that number of occurrences in nonoverlapping intervals are independent of one another. Then the distribution of elapsed time between the occurrence of two successive events is exponential with parameter  $\lambda = \alpha$ .

**Theorem 1.7.3.2:** The geometric distribution function has the memorylessness property.

*Proof:* Let  $X \sim E(\lambda)$ . Then:

$$\begin{aligned}
P(X \geq t + t_0 \mid X \geq t_0) &= \frac{P[(X \geq t + t_0) \cap (X \geq t_0)]}{P(X \geq t_0)} = \frac{P(X \geq t + t_0)}{P(X \geq t_0)} = \\
&= \frac{1 - F(t + t_0)}{1 - F(t)} = e^{-\lambda t} = P(X \geq t)
\end{aligned}$$

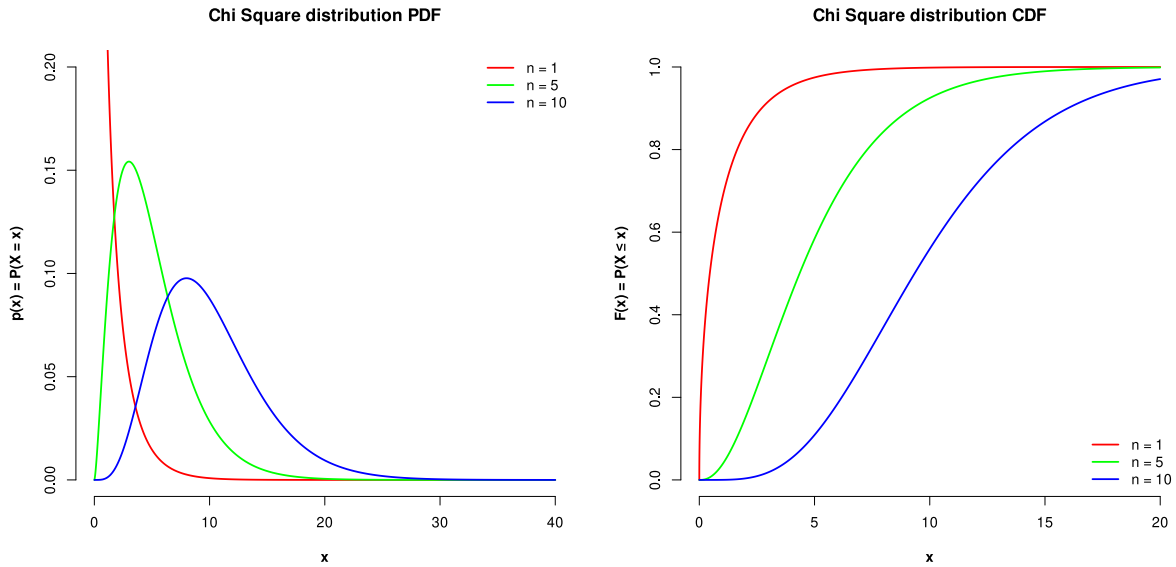
□

#### 1.7.4. Chi-square random variable

Given an integer  $n$ , let  $X$  be a random variable constructed by summing the squares of  $n$  independent standard normal random variables:

$$X = \sum_{i=1}^n Z_i^2 = Z_1^2 + Z_2^2 + \dots + Z_n^2$$

The random variable  $X$  defined as such is called a **Chi-squared random variable** with  $n$  degrees of freedom (denoted as  $X \sim \chi^2(n)$ ). Being the result of a sum of squared values, a Chi-squared random variable is always positive.



**Theorem 1.7.4.1:** The expected value and variance of a random variable  $X \sim \chi(n)$  are as follows:

$$E(X) = n$$

$$V(X) = 2n$$

*Proof:* The expected value of  $X$  can be computed by applying Theorem 1.4.2 and Lemma 1.4.1:

$$E(X) = E(Z_1^2 + Z_2^2 + \dots + Z_n^2) = \sum_{i=1}^n E(Z_i^2) = \sum_{i=1}^n V(Z_i) + (E(Z_i))^2 = n(1 + 0^2) = n$$

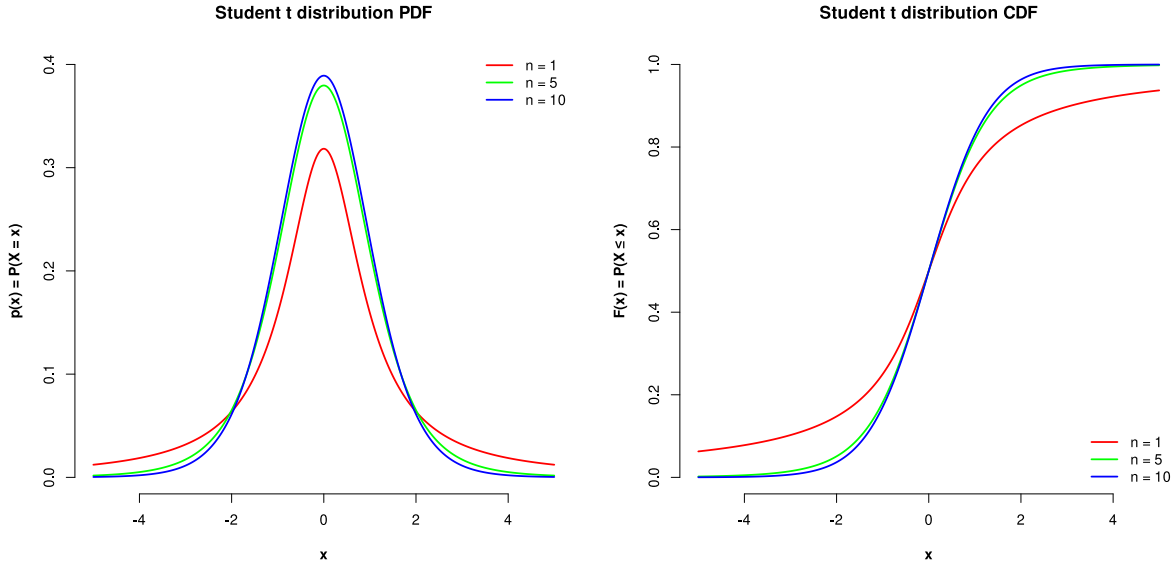
□

### 1.7.5. Student t random variable

Given an integer  $n$ , let  $Z$  be a standard normal distribution and  $Y_n$  a Chi-square distribution with  $n$  degrees of freedom, independent of each other. Let  $X$  be a random variable constructed by computing the ratio of  $Z$  and the square root of  $Y_n$ :

$$X = \frac{Z}{\sqrt{Y_n}}$$

The random variable  $X$  defined as such is called a **Student t random variable** with  $n$  degrees of freedom (denoted as  $X \sim T(n)$ ).



**Theorem 1.7.5.1:** The expected value and variance of a random variable  $X \sim T(n)$  are as follows:

$$E(X) = \begin{cases} 0 & \text{if } n > 1 \\ \text{undefined} & \text{otherwise} \end{cases}$$

$$V(X) = \begin{cases} \frac{n}{n-2} & \text{if } n > 2 \\ \text{undefined} & \text{otherwise} \end{cases}$$

As for the (standard) normal distribution, the values of its quantiles have been tabulated, since their calculations are generally unfeasible to be performed by hand.

The degrees of freedom of a Student t random variable are related to how “heavy” the tails of its pdf are. In particular, with  $n$  approaching  $\infty$ , the Student t distribution effectively becomes a normal distribution.

## 1.8. Joint probability distributions

Observing a single attribute is often too restrictive to analyze a problem. In general, a complex scenario is the result of an interplay between many phenomena, that ought to be observed simultaneously. In the realm of probability, this is equivalent to observing more than one random variable at once.

Let  $X$  and  $Y$  be two discrete random variables defined on the same sample space  $\Omega$  of an experiment. The **joint probability mass function**  $p(x, y)$  (joint pmf, for short) is defined for each couple  $(x, y)$  as:

$$p(x, y) = P(\{X = x\} \cap \{Y = y\})$$

That is, the probability that  $x$  is the realization of  $X$  and at the same time that  $y$  is the realization of  $Y$ . Of course, just as the pmf of a discrete random variable:

$$p(x, y) \geq 0$$

$$\sum_{x \in D(X)} \sum_{y \in D(Y)} p(x, y) = 1$$

Let  $A$  be a set consisting of pairs of  $(x, y)$  values. The probability  $P((X, Y) \in A)$  that the random pair  $(X, Y)$  lies in  $A$  is obtained by summing the joint pmf over pairs in  $A$ :

$$P((X, Y) \in A) = \sum_{(X, Y) \in A} p(x, y)$$

The **marginal probability mass functions** of  $X$  and  $Y$ , denoted respectively by  $p_X(x)$  and  $p_Y(y)$ , are given by:

$$p_X(x) = \sum_{y: p(x, y) > 0} p(x, y) \forall x \in D(X)$$

$$p_Y(y) = \sum_{x: p(x, y) > 0} p(x, y) \forall y \in D(Y)$$

That is, the sum of all values of a probabilities “locking” one variable and “moving” along the other

**Exercise 1.8.1:** Suppose that a particular company offers insurance policies for home and automobile in such a way that there exist different possible detractions for both policies:

- For automobile insurance: 100€, 500€, 1000€;
- For home insurance: 500€, 1000€, 5000€.

Consider randomly selecting a customer having both home and automobile insurance. Let  $X$  be the amount of automobile insurance policy deductible and let  $Y$  be the amount of home insurance policy deductible. Consider the following joint pmf for said variables:

$p(x, y)$	500	1000	5000
100	0.3	0.05	0
500	0.15	0.2	0.05
1000	0.1	0.1	0.05

Is is well defined? What are the marginal probability mass functions of  $X$  and  $Y$ ? What is the probability of  $X$  being greater or equal than 500? What is the probability of  $X$  and  $Y$  being equal?

*Solution:* The joint pmf is indeed well defined, because each probability is greater or equal than 0 and:

$$\sum_{x \in D(X)} \sum_{y \in D(Y)} p(x, y) = 0.3 + 0.05 + 0 + 0.15 + 0.2 + 0.05 + 0.1 + 0.1 + 0.05 = 1$$

The marginal probability mass function of  $X$  is given by:

$$\sum_{y \in D(Y)} p(X = 100, Y) = P(X = 100, Y = 500) + P(X = 100, Y = 1000) + P(X = 100, Y = 5000) = 0.3 + 0.05 + 0 = 0.35$$

$$\sum_{y \in D(Y)} p(X = 500, Y) = P(X = 500, Y = 500) + P(X = 500, Y = 1000) + P(X = 500, Y = 5000) = 0.15 + 0.2 + 0.05 = 0.4$$

$$\sum_{y \in D(Y)} p(X = 1000, Y) = P(X = 1000, Y = 500) + P(X = 1000, Y = 1000) + P(X = 1000, Y = 5000) = 0.1 + 0.1 + 0.05 = 0.25$$

$$\sum_{x \in D(X)} p(X, Y = 500) = P(X = 100, Y = 500) + P(X = 500, Y = 500) + P(X = 1000, Y = 500) = 0.3 + 0.15 + 0.1 = 0.55$$

$$\sum_{x \in D(X)} p(X, Y = 1000) = P(X = 100, Y = 1000) + P(X = 500, Y = 1000) + P(X = 1000, Y = 1000) = 0.05 + 0.2 + 0.1 = 0.35$$

$$\sum_{x \in D(X)} p(X, Y = 5000) = P(X = 100, Y = 5000) + P(X = 500, Y = 5000) + P(X = 1000, Y = 5000) = 0 + 0.05 + 0.05 = 0.1$$

$$p_X(x) = \begin{cases} 0.35 & \text{if } x = 100 \wedge (y = 500 \vee y = 1000 \vee y = 5000) \\ 0.4 & \text{if } x = 500 \wedge (y = 500 \vee y = 1000 \vee y = 5000) \\ 0.25 & \text{if } x = 1000 \wedge (y = 500 \vee y = 1000 \vee y = 5000) \end{cases}$$

$$p_Y(y) = \begin{cases} 0.55 & \text{if } y = 500 \wedge (x = 100 \vee x = 500 \vee x = 1000) \\ 0.35 & \text{if } y = 1000 \wedge (x = 100 \vee x = 500 \vee x = 1000) \\ 0.1 & \text{if } y = 5000 \wedge (x = 100 \vee x = 500 \vee x = 1000) \end{cases}$$

The probability of  $X$  being greater than 500 can be retrieved by focusing on the values of  $X$  and ignoring the ones of  $Y$ :

$$P(X \geq 500) = 0.15 + 0.2 + 0.05 + 0.1 + 0.1 + 0.05 = 0.65$$

The only values that  $X$  and  $Y$  can both assume are 500 and 1000. Therefore:

$$\begin{aligned} P(X = Y) &= P(\{X = 500 \wedge Y = 500\} \cup \{X = 1000 \wedge Y = 1000\}) = \\ P(X = 500 \wedge Y = 500) &+ P(X = 1000 \wedge Y = 1000) = 0.15 + 0.1 = 0.25 \end{aligned}$$

□

In the more general case of having  $n$  discrete random variables  $X_1, X_2, \dots, X_n$ , the joint pmf of said variables is given by the function:

$$p(x_1, x_2, \dots, x_n) = P(X_1 = x_1, X_2 = x_2, \dots, X_n = x_n)$$

Let  $X$  and  $Y$  be two continuous random variables defined on the same sample space  $\Omega$  of an experiment. The **joint probability density function**  $f(x, y)$  (joint pmf, for short) is a function such that, for any two-dimensional set  $A$ :

$$P((X, Y) \in A) = \int_A \int f(x, y) dx dy$$

Of course, just as the pdf of a continuous random variable:

$$f(x, y) \geq 0 \quad \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} f(x, y) dx dy = 1$$

In particular, if  $A$  is the two-dimensional rectangle  $\{(x, y) : a \leq x \leq b, c \leq y \leq d\}$ , then:

$$P((X, Y) \in A) = P(a \leq X \leq b, c \leq Y \leq d) = \int_a^b \int_c^d f(x, y) dx dy$$

The **marginal probability density functions** of  $X$  and  $Y$ , denoted respectively by  $f_X(x)$  and  $f_Y(y)$ , are given by:

$$f_X(x) = \int_{-\infty}^{+\infty} f(x, y) dy \text{ for } -\infty < x < +\infty \quad f_Y(y) = \int_{-\infty}^{+\infty} f(x, y) dx \text{ for } -\infty < y < +\infty$$

In the more general case of having  $n$  continuous random variables  $X_1, X_2, \dots, X_n$ , the joint pdf of said variables is the function  $f(x_1, x_2, \dots, x_n)$  such that for any  $n$  intervals  $[a_1, b_1], \dots, [a_n, b_n]$ :

$$P(a_1 \leq X_1 \leq b_1, \dots, a_n \leq X_n \leq b_n) = \int_{a_1}^{b_1} \dots \int_{a_n}^{b_n} f(x_1, \dots, x_n) dx_1, \dots, dx_n$$

The notion of dependence and independence of two random variables can be phrased in the language of joint probability mass/density functions. Two random variables  $X$  and  $Y$  are said to be independent if, for any pair  $(x, y)$  with  $x$  being a realization of  $X$  and  $y$  being a realization of  $Y$ , the following holds:

$$p(x, y) = p_X(x) \cdot p_Y(y) \text{ with } X, Y \text{ discrete} \quad f(x, y) = f_X(x) \cdot f_Y(y) \text{ with } X, Y \text{ continuous}$$

Otherwise,  $X$  and  $Y$  are dependent (not independent).

**Exercise 1.8.2:** Consider Exercise 1.8.1. Are  $X$  and  $Y$  dependent or independent?

*Solution:*  $X$  and  $Y$  are not independent, and it can be shown with a single counterexample. Consider  $X = 1000$  and  $Y = 5000$ :

$$P(X = 1000 \wedge Y = 5000) = 0.05 \quad P(X = 1000) \cdot P(Y = 5000) = 0.25 \cdot 0.1 = 0.025$$

Since the two values differ,  $X$  and  $Y$  ought to be dependent. □



In the more general case of having  $n$  random variables  $X_1, X_2, \dots, X_n$ , said variables are independent if for any subset  $X_{i_1}, X_{i_2}, \dots, X_{i_k}$  of size  $k \in [2, n]$ , the joint pmfs or pdfs is equal to the product of the marginal pmfs or pdfs.

Let  $X$  and  $Y$  be two discrete random variables with joint pmf  $p(x, y)$  and marginal pmf of  $X$   $p_X(x)$ . Then, for any  $X$  value  $x$  for which  $p_X(x) > 0$ , the **conditional probability mass function of  $Y$  given that  $X = x$**  is:

$$p_{Y|X}(y|x) = \frac{p(x, y)}{p_X(x)} \forall y \in D(Y)$$

Let  $X$  and  $Y$  be two continuous random variables with joint pdf  $f(x, y)$  and marginal pdf of  $X$   $f_X(x)$ . Then, for any  $X$  value  $x$  for which  $f_X(x) > 0$ , the **conditional probability density function of  $Y$  given that  $X = x$**  is:

$$f_{Y|X}(y|x) = \frac{f(x, y)}{f_X(x)} \text{ for } -\infty < y < +\infty$$

Let  $X$  and  $Y$  be two random variables having a joint pmf  $p(x, y)$  or joint pdf  $f(x, y)$  (according to whether they are discrete or continuous). Then the expected value of a function  $h(X, Y)$ , denoted as  $E[h(X, Y)]$  or  $\mu_{h(X, Y)}$ , is given by:

$$E[h(X, Y)] = \begin{cases} \sum_{x \in D(X)} \sum_{y \in D(Y)} h(x, y) \cdot p(x, y) & \text{if } X \text{ and } Y \text{ are discrete} \\ \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} h(x, y) \cdot f(x, y) dx dy & \text{if } X \text{ and } Y \text{ are continuous} \end{cases}$$

The **covariance** between two random variables  $X$  and  $Y$  is given by:

$$\text{Cov}(X, Y) = \begin{cases} \sum_{x \in D(X)} \sum_{y \in D(Y)} (x - E(X))(y - E(Y))p(x, y) & \text{if } X \text{ and } Y \text{ are discrete} \\ \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} (x - E(X))(y - E(Y))f(x, y) dx dy & \text{if } X \text{ and } Y \text{ are continuous} \end{cases}$$

The covariance is particularly useful for analyzing the linear similarity of two dependent random variables.

**Exercise 1.8.3:** Consider Exercise 1.8.1. Compute the covariance of  $X$  and  $Y$ .

*Solution:* First, the expected value of  $X$  and  $Y$  have to be computed:

$$E(X) = \sum_{x \in D(X)} x \cdot P(X = x) = 100 \cdot 0.35 + 500 \cdot 0.4 + 1000 \cdot 0.25 = 485$$

$$E(Y) = \sum_{y \in D(Y)} y \cdot P(Y = y) = 500 \cdot 0.55 + 1000 \cdot 0.35 + 5000 \cdot 0.1 = 1125$$

It is then possible to compute the covariance as:

$$\begin{aligned} \text{Cov}(X, Y) &= \sum_{x \in D(X)} \sum_{y \in D(Y)} (x - E(X))(y - E(Y))p(x, y) = (100 - 485)(500 - 1125)(0.3) + \\ & (100 - 485)(1000 - 1125)(0.05) + (100 - 485)(5000 - 1125)(0) + (500 - 485)(500 - 1125)(0.15) + \\ & (500 - 485)(1000 - 1125)(0.2) + (500 - 485)(5000 - 1125)(0.05) + (1000 - 485)(500 - 1125)(0.1) + \\ & (1000 - 485)(1000 - 1125)(0.1) + (1000 - 485)(5000 - 1125)(0.05) = 136875 \end{aligned}$$

□

**Theorem 1.8.1:** Let  $X$  and  $Y$  be two random variables, and let  $a$  and  $b$  be two real numbers. The following equality holds:

$$\text{Cov}(aX, bY) = ab \text{ Cov}(X, Y)$$

**Theorem 1.8.2:** Let  $X$  and  $Y$  be two random variables. The following equality holds:

$$\text{Cov}(X, Y) = E(XY) - E(X) \cdot E(Y)$$

Since the covariance has no minimum and no maximum, it isn't really indicative of the order of magnitude of the random variables.

A better measure of the relationship between two random variables  $X$  and  $Y$  is given by the **correlation coefficient**, denoted as  $\text{Corr}(X, Y)$  or  $\rho_{X,Y}$  and given by:

$$\text{Corr}(X, Y) = \frac{\text{Cov}(X, Y)}{V(X)V(Y)}$$

**Theorem 1.8.3:** For any pair of random variables  $X$  and  $Y$ ,  $-1 \leq \text{Corr}(X, Y) \leq 1$ .

The correlation coefficient is more descriptive of the relationship between two random variables than their variance because, as stated in Theorem 1.8.3, it is bounded, and therefore is indicative of the scale of the values of the variables.

**Theorem 1.8.4:** Let  $X$  and  $Y$  be two random variables. If  $\text{Corr}(X, Y) = \pm 1$ , there exist two real numbers  $a$  and  $b$ , with  $a \neq 0$ , such that  $Y = aX + b$ .

Theorem 1.8.4 can be generalized by stating that if  $\text{Corr}(X, Y)$  is close to  $\pm 1$ , it means that the two random variables are almost linearly correlated, while if it is close to 0 it means that the two random variables are poorly linearly correlated, or not correlated at all.

**Lemma 1.8.1:** If  $X$  and  $Y$  are two independent random variables,  $\text{Corr}(X, Y) = 0$ .

**Theorem 1.8.5:** Let  $X$  and  $Y$  be two random variables, and let  $a, b, c$  and  $d$  be four real numbers. If  $a$  and  $c$  have the same sign, the following equality holds:

$$\text{Corr}(aX + b, cY + d) = \text{Corr}(X, Y)$$

An example of a bivariate distribution is the **bivariate normal distribution**, an extension of the normal distribution in two dimensions:

$$f(x, y) = \frac{1}{\pi\sigma_x\sigma_y\sqrt{1-\rho^2}} \exp\left(-\frac{1}{2(1-\rho^2)}\left[\left(\frac{x-\mu_x}{\sigma_x}\right)^2 + \left(\frac{y-\mu_y}{\sigma_y}\right)^2 - 2\rho\left(\frac{x-\mu_x}{\sigma_x}\right)\left(\frac{y-\mu_y}{\sigma_y}\right)\right]\right)$$

## 1.9. Random sampling

Consider a certain population, assuming to be distributed as a certain random variable, and a sample drawn from said population of size  $n$ . Let  $x_1, x_2, \dots, x_n$  be the values obtained from said sample; since it's not possible to know said values before the sampling, they can be conceived as  $n$  random variables.

If  $X_1, X_2, \dots, X_n$  are said random variables and a sample is drawn  $k$  times, the realizations of each  $i$ -th sample are  $x_{1,i}, x_{2,i}, \dots, x_{n,i}$ . If for any of these samples a point estimate (mean, median, ecc...) is computed, unless

the exact same values are drawn in more than one sample, each computation of said point estimate will yield a different result. Point estimates can therefore be conceived as random variables as well, since their value is unknown until a sample is drawn and the probability of retrieving a certain values for the estimate depends on how likely a sample with those traits is drawn.

Any value that can be calculated from a sample is called a **statistic**. Prior to the act of sampling the value of a statistic is unknown, and therefore conceivable as a random variable. For this reason, a statistic is often denoted with an uppercase letter while its specific realization (dependent on the sample drawn) with a lowercase letter. Being a random variable, it can be endowed with a probability distribution; the probability distribution of a statistic (interpreted as a random variable) is often referred to as a **statistic distribution**. The name emphasizes the fact that the value of the realization of the statistic depends on which sample is drawn from the distribution it's computed on.

The probability distribution of a statistic depends both on the probability distribution of the population from which the sample is drawn (normal, exponential, binomial, ecc...) and on the size  $n$  of the sample, but it also depends on *how* the sample is performed. The sampling procedure that allows the statistics to be computed with the least effort is what is called a **random sample**: the  $n$  random variables  $X_1, X_2, \dots, X_n$  are said to form a random sample if they are **independent and identically distributed** (i.i.d for short), that is, if they are all independent and they have the same probability distribution.

One way to obtain information about a statistic's sampling distribution involves performing calculations based on probability rules.

**Exercise 1.9.1:** A certain brand of MP3 player comes in three sizes: the revenue in a given day is denoted by the random variable  $X$ . For each size, the percentage of customers buying said size has been computed:

Size	Price	% of customers
2GB	80\$	20%
4GB	100\$	30%
8GB	120\$	50%

Suppose that 2 MP3s were sold today.  $X_1$  and  $X_2$  be the random variables denoting respectively the revenue of the first sale and the revenue of the second sale. Assume that  $X_1$  and  $X_2$  constitute a random sample, and are therefore independent and identically distributed. What is the joint probability distribution of  $X$  and  $Y$ ? What are all the possible sample means and sample variances?

*Solution:* The expected value and variance of  $X$  are given by:

$$\mu = \sum xp(x) = 80 \cdot 0.2 + 100 \cdot 0.3 + 120 \cdot 0.5 = 106$$

$$\sigma^2 = (80^2 \cdot 0.2 - 106^2) + (100^2 \cdot 0.3 - 106^2) + (120^2 \cdot 0.5 - 106^2) = 244$$

$X_1$	$X_2$	$p(X_1, X_2)$	$\bar{X}$	$s^2$
80	80	$0.2 \cdot 0.2 = 0.04$	$\frac{80+80}{2} = 80$	$(80 - 80)^2 + (80 - 80)^2 = 0 + 0 = 0$
80	100	$0.2 \cdot 0.3 = 0.06$	$\frac{80+100}{2} = 90$	$(80 - 90)^2 + (100 - 90)^2 = 100 + 100 = 200$
80	120	$0.2 \cdot 0.5 = 0.1$	$\frac{80+120}{2} = 100$	$(80 - 100)^2 + (120 - 100)^2 = 400 + 400 = 800$
100	80	$0.3 \cdot 0.2 = 0.06$	$\frac{100+80}{2} = 90$	$(100 - 90)^2 + (80 - 90)^2 = 100 + 100 = 200$
100	100	$0.3 \cdot 0.3 = 0.09$	$\frac{100+100}{2} = 100$	$(100 - 100)^2 + (100 - 100)^2 = 0 + 0 = 0$
100	120	$0.3 \cdot 0.5 = 0.15$	$\frac{100+120}{2} = 110$	$(100 - 110)^2 + (120 - 110)^2 = 100 + 100 = 200$
120	80	$0.5 \cdot 0.2 = 0.1$	$\frac{120+80}{2} = 100$	$(120 - 100)^2 + (80 - 100)^2 = 400 + 400 = 800$
120	100	$0.5 \cdot 0.3 = 0.15$	$\frac{120+100}{2} = 110$	$(120 - 110)^2 + (100 - 110)^2 = 100 + 100 = 200$

120	120	$0.5 \cdot 0.5 = 0.25$	$\frac{120+120}{2} = 120$	$(120 - 120)^2 + (120 - 120)^2 = 0 + 0 = 0$
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Sample mean:

$$P(\bar{X} = 80) = P(\{X_1 = 80\} \wedge \{X_2 = 80\}) = 0.04$$

$$P(\bar{X} = 90) = P(\{X_1 = 80\} \wedge \{X_2 = 100\} \vee \{X_1 = 100\} \wedge \{X_2 = 80\}) = 0.06 + 0.06 = 0.12$$

$$P(\bar{X} = 100) = P(\{X_1 = 100\} \wedge \{X_2 = 100\} \vee \{X_1 = 80\} \wedge \{X_2 = 120\} \vee \{X_1 = 120\} \wedge \{X_2 = 80\}) = 0.1 + 0.1 + 0.09 = 0.29$$

$$P(\bar{X} = 110) = P(\{X_1 = 100\} \wedge \{X_2 = 120\} \vee \{X_1 = 120\} \wedge \{X_2 = 100\}) = 0.15 + 0.15 = 0.3$$

$$P(\bar{X} = 120) = P(\{X_1 = 120\} \wedge \{X_2 = 120\}) = 0.25$$

Sample variance:

$$P(s^2 = 0) = P(\{X_1 = 80\} \wedge \{X_2 = 80\} \vee \{X_1 = 100\} \wedge \{X_2 = 100\} \vee \{X_1 = 120\} \wedge \{X_2 = 120\}) = 0.04 + 0.09 + 0.25 = 0.38$$

$$= P(\{X_1 = 80\} \wedge \{X_2 = 100\} \vee \{X_1 = 100\} \wedge \{X_2 = 80\} \vee \{X_1 = 100\} \wedge \{X_2 = 120\} \vee \{X_1 = 120\} \wedge \{X_2 = 100\}) = 0.06 + 0.06 + 0.15 + 0.15 = 0.42$$

$$P(s^2 = 800) = P(\{X_1 = 120\} \wedge \{X_2 = 80\} \vee \{X_1 = 80\} \wedge \{X_2 = 120\}) = 0.1 + 0.1 = 0.2$$

□

When the computation is too difficult, another approach is to try (often with the aid of a software) to approximate the distribution of the statistic by performing a **simulation experiment**, that consists in sampling the population many times and analyzing the values obtained for said statistic across all samples. The bigger the sample size (the number of samples), the greater the precision of the estimation: for any practical application, a sample size of 500 or 1000 is generally enough.

Let  $X_1, X_2, \dots, X_n$  be a random sample. The **sample mean** of said sample is given by:

$$\bar{X} = \frac{1}{n} \sum_{i=1}^n X_i$$

Interestingly, the sample mean does not depend on the distribution of  $X_1, X_2, \dots, X_n$ .

**Theorem 1.9.1:** Let  $X_1, X_2, \dots, X_n$  be a random sample from a (known) distribution with mean value  $\mu$  and standard deviation  $\sigma$ . Then:

$$E(\bar{X}) = \mu$$

$$V(\bar{X}) = \frac{\sigma^2}{n}$$

Also, let  $T_0 = X_1 + X_2 + \dots + X_n$ . Then:

$$E(T_0) = n\mu$$

$$V(T_0) = n\sigma^2$$

## 1.10. Confidence intervals

A point estimate is not indicative of how reliable said estimation is. Also, since the value of a point estimate depends on the values of the sample drawn, there's no indication on why one value should be preferred over another, and no estimation will ever be exactly equal to the "true" value.

An alternative to reporting a single value for the parameter to be estimated is to report an *interval* of plausible values, an **interval estimate** or **confidence interval** (CI for short) endowed with a measure of its reliability.

To illustrate how a confidence interval is constructed, it is useful to start from a very simple (and unrealistic) situation and then introduce more and more complications.

The simplest scenario is the one where the parameter of interest is the population mean (the “true” mean), the population is known to be normally distributed and the value of the population standard deviation (the “true” standard deviation) is known.

Let  $X_1, X_2, \dots, X_n$  be the random variables denoting the observations and  $x_1, x_2, \dots, x_n$  be their realizations, resulting from a random sample having normal distribution with known mean  $\mu$  and unknown standard deviation  $\sigma$ . Then, irrespective of the sample size  $n$ , the sample mean  $\bar{X}$  is normally distributed with expected value  $\mu$  and standard deviation  $\frac{\sigma}{\sqrt{n}}$ .

Standardizing the sample mean allows to express it in terms of the population mean and standard deviation:

$$Z = \frac{\bar{X} - \mu}{\frac{\sigma}{\sqrt{n}}} = \frac{\sqrt{n}(\bar{X} - \mu)}{\sigma}$$

Suppose one requires the value of  $Z$  to possess a probability of 95%. The value for the standard normal random variable with said percentage is 1.96. Therefore:

$$\begin{aligned} P\left(-1.96 < \frac{\sqrt{n}(\bar{X} - \mu)}{\sigma} < 1.96\right) &= 0.95 \Rightarrow P\left(-1.96\left(\frac{\sigma}{\sqrt{n}}\right) < \bar{X} - \mu < 1.96\left(\frac{\sigma}{\sqrt{n}}\right)\right) = 0.95 \Rightarrow \\ P\left(-1.96\left(\frac{\sigma}{\sqrt{n}}\right) - \bar{X} < -\mu < 1.96\left(\frac{\sigma}{\sqrt{n}}\right) - \bar{X}\right) &= 0.95 \Rightarrow P\left(\bar{X} - 1.96\left(\frac{\sigma}{\sqrt{n}}\right) < \mu < \bar{X} + 1.96\left(\frac{\sigma}{\sqrt{n}}\right)\right) = 0.95 \end{aligned}$$

The interval  $\left(\bar{X} - 1.96\left(\frac{\sigma}{\sqrt{n}}\right), \bar{X} + 1.96\left(\frac{\sigma}{\sqrt{n}}\right)\right)$  is called a **confidence interval at 95%**. The value of 95% is called the **level of confidence**, while the value  $2 \cdot 1.96\left(\frac{\sigma}{\sqrt{n}}\right)$  is the **width** of the interval. Such interval is a random interval because its endpoints depend on  $\bar{X}$ , which is a random variable.

After drawing the sample and collecting the realizations  $X_1 = x_1, X_2 = x_2, \dots, X_n = x_n$ , it is possible to compute the (realization of the) sample mean  $\bar{x}$ , obtaining an *actual* interval.

**Exercise 1.10.1:** Industrial engineers study ergonomics to design keyboards that are comfortable to use and make people using them as productive as possible. Assume that a sample of  $n = 31$  trained typists was selected and of them gave their evaluation of the best keyboard height. The sample average resulted in  $\bar{x} = 80$  cm while the population mean, denoted by  $\mu$ , is unknown. Assuming that the population standard deviation is known and equal to 2 cm, derive a confidence interval at 95%.

*Solution:*

$$\left(80 - 1.96\left(\frac{2}{\sqrt{31}}\right), 80 + 1.96\left(\frac{2}{\sqrt{31}}\right)\right) \approx (80 - 1.96 \cdot 0.36, 80 + 1.96 \cdot 0.36) \approx (79.3, 80.7)$$

□

It would be wrong to interpret a 95% confidence for  $\mu$  as the probability that  $\mu$  lies in  $\left(\bar{X} - 1.96\left(\frac{\sigma}{\sqrt{n}}\right), \bar{X} + 1.96\left(\frac{\sigma}{\sqrt{n}}\right)\right)$ . The correct interpretation for a 95% confidence is that, by obtaining an interval from a drawn sample, there's a 95% chance that said interval will contain  $\mu$  somewhere.

The choice of 95% is, of course, arbitrary. In general, any percentage can be chosen by picking a quantile  $\alpha$ . A  $100(1 - \alpha)\%$  confidence interval for the mean  $\mu$  of a normal population when the value of  $\sigma$  is known is given by<sup>1</sup>:

$$P\left(\bar{x} - z_{1-\alpha/2}\left(\frac{\sigma}{\sqrt{n}}\right) < \mu < \bar{x} + z_{1-\alpha/2}\left(\frac{\sigma}{\sqrt{n}}\right)\right) = 1 - \alpha$$

<sup>1</sup>The notation for the quantile is very confusing. In some literature it is denoted as  $z_{\alpha/2}$  and in others is  $z_{1-\alpha/2}$ .

**Exercise 1.10.2:** A production process for engine control housing units underwent a modification such that previously the hole diameter for bushing on the housing was distributed as a normal random variable with unknown mean and standard deviation 0.1 mm. It is believed that the modification did not alter the distribution of the hole diameter and the value of the standard deviation, while the mean might have changed. A sample of  $n = 40$  housing units is selected and the hole diameter has been measured for each unit, obtaining a sample mean of  $\bar{x} = 5.426$  mm. Construct a confidence interval for the average true diameter with confidence level of 90%.

*Solution:* If 90% is  $1 - \alpha$ , then  $\alpha$  is 0.1. By looking at the tables it is possible to derive a value for  $z_{0.95}$  of 1.645

$$\left( \bar{x} - z_{1-\alpha/2} \left( \frac{\sigma}{\sqrt{n}} \right) \right) < \mu < \bar{x} + z_{1-\alpha/2} \left( \frac{\sigma}{\sqrt{n}} \right) = \left( 5.426 - z_{0.95} \left( \frac{0.1}{\sqrt{40}} \right) \right) < \mu < 5.426 + z_{0.95} \left( \frac{0.1}{\sqrt{40}} \right) = (5.426 - 1.645 \cdot 0.016 < \mu < 5.426 + 1.645 \cdot 0.016) = (5.4, 5.452)$$

□

The choice of a certain confidence level induces a certain interval size: if the confidence level is increased, the value of the quantile is also increased. This means that if the probability that the interval obtained from the sample contains the real value of the parameter is increased, the size of the interval is also increased. In other words, a gain in reliability entails a loss of precision, and it's not possible to be both precise and reliable.

If one is to explicitly pick both a confidence level and an interval size, it is necessary to derive the sample size. If the size of the interval is denoted by  $w$ , it is possible to derive it by rearranging the expression of the width:

$$w = 2z_{1-\alpha/2} \left( \frac{\sigma}{\sqrt{n}} \right) \Rightarrow w\sqrt{n} = 2z_{1-\alpha/2}\sigma \Rightarrow \sqrt{n} = \frac{2z_{1-\alpha/2}\sigma}{w} \Rightarrow n = \left( \frac{2z_{1-\alpha/2}\sigma}{w} \right)^2$$

To get a reasonable result, the value of  $n$  may or may not have to be ceiled.

**Exercise 1.10.3:** Suppose that the response time to a particular computer program is distributed as a normal random variable with unknown mean and standard deviation 25  $\mu$  s. When a new operating system is installed, there's interest in estimating the true average response time  $\mu$  for such new environment. What sample size is needed to ensure that the confidence level is 95% and has width 10  $\mu$  s?

*Solution:*

$$n = \left( \frac{2z_{0.975}\sigma}{w} \right)^2 = \left( \frac{2 \cdot 1.96 \cdot 25}{10} \right)^2 = (1.96 \cdot 5)^2 \approx 97$$

□

Consider a more general case where  $X_1, X_2, \dots, X_n$  are the random variables denoting the observations and  $x_1, x_2, \dots, x_n$  be their realizations, resulting from a random sample having unknown distribution with unknown mean  $\mu$  and unknown standard deviation  $\sigma$ .

Even though the distribution of the  $X_i$  variable is unknown, if the sample size is sufficiently large, it is possible to apply the Central Limit Theorem and derive that their sum has a normal distribution (no matter the distribution of  $X_i$ ). Also, the “real” standard deviation can still be substituted with its estimator  $s$ . Standardizing:

$$Z = \frac{\bar{X} - \mu}{\frac{s}{\sqrt{n}}} = \frac{\sqrt{n}(\bar{X} - \mu)}{s}$$

By picking a value of  $\alpha$  and deriving a quantile  $z_{1-\alpha/2}$ , it is possible to construct a confidence interval with confidence level  $100(1 - \alpha)\%$  and the associated probability:

$$\begin{aligned}
P\left(-z_{1-\alpha/2} < \frac{\sqrt{n}(\bar{X} - \mu)}{s} < z_{1-\alpha/2}\right) &= 1 - \alpha \Rightarrow P\left(-z_{1-\alpha/2} \cdot s < \sqrt{n}(\bar{X} - \mu) < z_{1-\alpha/2} \cdot s\right) = 1 - \alpha \Rightarrow \\
P\left(-z_{1-\alpha/2} \left(\frac{s}{\sqrt{n}}\right) < \bar{X} - \mu < z_{1-\alpha/2} \left(\frac{s}{\sqrt{n}}\right)\right) &= 1 - \alpha \Rightarrow P\left(-z_{1-\alpha/2} \left(\frac{s}{\sqrt{n}}\right) - \bar{X} < -\mu < z_{1-\alpha/2} \left(\frac{s}{\sqrt{n}}\right) - \bar{X}\right) = 1 - \alpha \Rightarrow \\
P\left(\bar{X} - z_{1-\alpha/2} \left(\frac{s}{\sqrt{n}}\right) < \mu < \bar{X} + z_{1-\alpha/2} \left(\frac{s}{\sqrt{n}}\right)\right) &= 1 - \alpha
\end{aligned}$$

The large sample intervals  $\bar{X} \pm z_{1-\alpha/2} \cdot s/\sqrt{n}$  are a special case of a general large sample confidence interval for a parameter  $\theta$ . Suppose that  $\hat{\theta}$ , an estimator for  $\theta$ , has the three following properties:

1. It is normally distributed;
2. It's **unbiased**, meaning that  $\mu_{\hat{\theta}} = \theta$ ;
3.  $\sigma_{\hat{\theta}}$  the standard deviation of  $\hat{\theta}$ , is a known value.

For example, if  $\theta$  is the (population) mean  $\mu$ , the estimator  $\hat{\theta} = \bar{X}$  possesses all three properties, since it is normally distributed, it is unbiased and the value of  $\sigma_{\hat{\theta}}$  is known to be  $\sigma/\sqrt{n}$ . Standardizing  $\hat{\theta}$  gives:

$$Z = \frac{\hat{\theta} - \mu_{\hat{\theta}}}{\sigma_{\hat{\theta}}} = \frac{\hat{\theta} - \theta}{\sigma_{\hat{\theta}}}$$

By picking a value of  $\alpha$  and deriving a quantile  $z_{1-\alpha/2}$ , it is possible to construct a confidence interval with confidence level  $100(1 - \alpha)\%$  and the associated probability:

$$P\left(-z_{1-\alpha/2} < \frac{\hat{\theta} - \theta}{\sigma_{\hat{\theta}}} < z_{1-\alpha/2}\right) \approx 1 - \alpha$$

**Exercise 1.10.4:** Let  $B \sim \text{Binom}(n, p)$ , with both parameters unknown. Derive an estimator  $\hat{p}$  for  $p$  and a confidence interval for  $\hat{p}$  by performing a random sampling.

*Solution:* Let  $X_1, X_2, \dots, X_k$  be the random variables corresponding to the sampling. If  $k \ll n$ , each  $X_i$  is itself distributed as a binomial distribution. Recall that:

$$E(X) = np \qquad \text{SD}(X) = \sqrt{np(1-p)}$$

If  $\bar{X}$  is an estimator of  $E(X)$ , and  $E(X) = np$ , then a natural choice for an estimator for  $p$  is  $\bar{p} = \bar{X}/n$ . Since  $\bar{X}$  is normally distributed, then  $\bar{X}/n$  is also normally distributed (dividing by  $n$  is a linear transformation). Also,  $E(\hat{p}) = p$  and the expression for  $\sigma_{\hat{\theta}}$  is known, because  $\sigma_{\hat{\theta}} = \sqrt{p(1-p)/n}$ . Standardizing, gives:

$$P\left(-z_{1-\alpha/2} < \frac{\hat{p} - p}{\sqrt{p(1-p)/n}} < z_{1-\alpha/2}\right) \approx 1 - \alpha$$

From which it is possible to derive a confidence interval:

$$\begin{aligned}
-z_{1-\alpha/2} < \frac{\hat{p} - p}{\sqrt{p(1-p)/n}} < z_{1-\alpha/2} &\Rightarrow -z_{1-\alpha/2} \sqrt{\frac{p(1-p)}{n}} < \hat{p} - p < z_{1-\alpha/2} \sqrt{\frac{p(1-p)}{n}} \Rightarrow \\
\hat{p} - z_{1-\alpha/2} \sqrt{\frac{p(1-p)}{n}} < p < \hat{p} + z_{1-\alpha/2} \sqrt{\frac{p(1-p)}{n}} &\Rightarrow \hat{p} \pm z_{1-\alpha/2} \sqrt{\frac{p(1-p)}{n}}
\end{aligned}$$

□

As long as the population size  $n$  is large, the CLT can be applied to aid the calculations. But if the size of the sample is small, it cannot be applied. In particular, with  $n$  being small, the random variable  $\sqrt{n}(\bar{X} - \mu)/s$  is more “unstable” and spread out than a standard normal distribution.

When  $\bar{X}$  is the mean of a random sample of (small) size  $n$  retrieved from a normal distribution with (unknown) mean  $\mu$  and (unknown) standard deviation  $\sigma$ , the random variable defined as:

$$T = \frac{\bar{X} - \mu}{s/\sqrt{n}} = \frac{\sqrt{n}(\bar{X} - \mu)}{S}$$

Is distributed as a Student  $t$  distribution with  $n - 1$  degrees of freedom. A confidence interval with confidence level  $100(1 - \alpha)\%$  can then be constructed as:

$$\left( \bar{x} - t_{1-\alpha/2, t-1} \cdot \frac{s}{\sqrt{n}}, \bar{x} + t_{1-\alpha/2, t-1} \cdot \frac{s}{\sqrt{n}} \right)$$

### 1.11. Hypothesis testing

A parameter can be estimated either by a single number (point estimate) or by an interval of admissible values (a confidence interval). However, the objective of an investigation can also be putting a claim concerning the parameter to the test, and see if such claim is plausible or not. The methods for accomplishing this comprise the part of statistical inference called **hypothesis testing**.

A **statistical hypothesis** is an assertion concerning the value of a single parameter (“The value of this parameter is 0.5”, “The value of this parameter is lower than 3”, ...), the value of several parameters (“Parameter one is greater than parameter two”, “Parameters one and two are equal”, ...), or about the form of a probability distribution (“This sample was drawn from a normal distribution”, “This sample was drawn from a Poisson distribution”, ...).

In any hypothesis testing problem, there are two mutually exclusive hypothesis under consideration: one is the one that is thought to be true, called the **null hypothesis**, and the other is its logical complement, called the **alternative hypothesis**. The null hypothesis is often denoted as  $H_0$ , while the alternative hypothesis as  $H_a$  or  $H_1$ . The objective is to decide, based on the information collected from a sample, which of the two is to be taken.

The alternative hypothesis should be taken into account if and only if the test says that the sample contradicts the null hypothesis with enough margin, and stick with the null hypothesis otherwise. If the sample is in line with the null hypothesis, this does not necessarily mean that the null hypothesis is true, it just means that there is not enough evidence to disprove it.

The simplest structure of a null hypothesis is  $H_0 : \theta = \theta_0$ . That is to say, the hypothesis is stating that the parameter  $\theta$  is equal to the specific value  $\theta_0$ . In this case, the alternative hypothesis is stating one of the following:

- $\theta$  is greater than  $\theta_0$ , that is  $H_a : \theta > \theta_0$
- $\theta$  is less than  $\theta_0$ , that is  $H_a : \theta < \theta_0$
- $\theta$  is different from  $\theta_0$ , that is  $H_a : \theta \neq \theta_0$

The first two are called **unilateral**, while the last one is called **bilateral**.

In an hypothesis testing problem, the rejection or confirmation of the null hypothesis is decided with respect to a **test statistic**. This statistic is a function of the sample data (a random variable) whose value obtained from the sample should be very different with respect to whether the null hypothesis is assumed to be true or to be false. If the value of the test statistic deviates decisively from the values expected from the null hypothesis, then the null hypothesis is rejected in favour of the alternative hypothesis. If the value of the test statistic is consistent with what is stated in the null hypothesis, then the null hypothesis is not rejected.

The issue is that a null hypothesis of the form  $H_0 : \theta = \theta_0$  will never be confirmed with exact precision from the sample data, because the value of  $\theta$  extracted from the sample will always be different from sample to sample. Therefore, the null hypothesis ought to be rejected when the value of  $\theta$  retrieved from the sample deviates from  $\theta_0$  only within a small margin.

Such “closeness” to  $\theta_0$  is quantified in the **p-value**. Such value is the probability, calculated assuming that the null hypothesis is true, of obtaining a value of the test statistic at least as contradictory to what is stated in  $H_0$  as the value calculated from the sample. A conclusion is reached by picking a number  $\alpha$  called **significance level**, reasonably close to 0:  $H_0$  is rejected in favour of  $H_a$  if the p-value is less than or equal to the level of significance, whereas  $H_0$  will not be rejected if the p-value is greater than the level of significance. Even though  $\alpha$  can be any value, it is customary to pick either 0.05, 0.01, 0.001 or 0.1.



The idea is that if the probability that the value of the test statistic computed from the sample is so extreme under the null hypothesis is very low, then such value cannot be justified by a fluctuation in the data, but ought to be interpreted as the null hypothesis poorly interpreting the scenario.

As stated before, if the data does not provide enough evidence to disprove the null hypothesis it does not necessarily mean that the null hypothesis is true: the data could be the result of a sample having very biased (unlikely, but still possible) outcome, that happened to agree with the null hypothesis. The values of the sample might also be biased in the other sense, appearing to favour the rejection of the null hypothesis simply because the sample was extremely favorable.

In both cases, a mistake is made. These two scenarios are summed up as:

- **Type I error:** rejecting  $H_0$  even though it's true;
- **Type II error:** not rejecting  $H_0$  even though it's false.

**Theorem 1.11.1:** In an hypothesis test, the probability of incurring in a type I error is equal to the level of significance of the test.

*Proof:* Let  $Y$  be the test statistic, with cdf given by  $F$  when  $H_0$  is true. Suppose that  $Y$  has a continuous distribution over some interval, such that  $F$  is strictly increasing over such interval. If this is the case,  $F^{-1}$  is well defined.

Consider the case in which only values of  $Y$  are smaller than the computed value  $y$  are more contradictory to  $H_0$  than  $y$  itself. Then:

$$\text{p-value} = P\left(\begin{array}{c} \text{A value for the test statistic at least as} \\ \text{contradictory to the null hypothesis is obtained} \end{array} \mid H_0\right) = F(y)$$

Before having the sample data:

$$\begin{aligned} P(\text{Type I Error}) &= P(\text{p-value} \leq \alpha \mid H_0) = P(F(y) \leq \alpha) = P[F^{-1}(F(y)) \leq F^{-1}(\alpha)] = \\ &= P[Y \leq F^{-1}(\alpha)] = P[Y \leq F^{-1}(\alpha)] = F[F^{-1}(\alpha)] = \alpha \end{aligned}$$

The case in which only values of  $Y$  are greater than the computed value  $y$  are more contradictory to  $H_0$  than  $y$  itself is analogous. The bilateral case is also analogous.

The theorem still holds for  $Y$  being a discrete distribution as long as it is possible to provide a well defined inverse function of the cdf.  $\square$

A formula for computing the probability of committing a type II error (often denoted with  $\beta$ ) depends on the test statistic, and isn't always available.

If the probability of committing one of the two errors decreases, the probability of committing the other increases. Therefore, there's a tradeoff to be made. Out of the two errors, the type I error is generally considered to be more problematic than the type II error, because rejecting an hypothesis generally mean establishing an entire new framework, while not rejecting an hypothesis simply means keeping things as they are<sup>2</sup>.

### 1.11.1. Z tests about $\mu$ , known $\sigma$

Let  $X_1, \dots, X_n$  be a random sample retrieved from a normal distribution with mean value  $\mu$  and (known) standard deviation  $\sigma$ . Then, since the sum of normal distributions is itself normal, the sample mean  $\bar{X}$  is normally distributed with expected value  $\mu$  and standard deviation  $\sigma/\sqrt{n}$ .

Let  $H_0 : \mu = \mu_0$ , where  $\mu_0$  is referred to as the **null value**. The alternative hypothesis can either be  $H_1 : \mu > \mu_0$ ,  $H_1 : \mu < \mu_0$  or  $H_1 : \mu \neq \mu_0$ .  $\bar{X}$  can be standardized to get  $Z = (\bar{X} - \mu_0)/(\sigma/\sqrt{n})$ .

<sup>2</sup>This is analogous to a trial: it is better to absolve a criminal than to condemn an innocent.

When  $H_0$  is true,  $\mu_{\bar{X}} = \mu_0$ . The statistic  $Z$  is a natural measure of the distance between  $\bar{X}$ , the estimator of  $\mu$ , and its expected value when  $H_0$  is true ( $\mu_{\bar{X}}$ ). If the realization  $\bar{x}$  of the sample mean  $\bar{X}$  considerably exceeds  $\mu_0$  in a direction consistent with  $H_1$ , there is sufficient evidence to reject  $H_0$ .

Let  $H_1 : \mu > \mu_0$ . The null hypothesis ought to be rejected if a very large value  $z = (\bar{x} - \mu_0)/(\sigma/\sqrt{n})$  from  $Z$  is retrieved. If this is the case, this implies that any value exceeding  $z$  is even more inconsistent with  $H_0$  than  $z$  itself. The p-value of the test is therefore the probability of retrieving a value for  $Z$  greater or equal than  $z$  assuming  $H_0$  to be true.

**Exercise 1.11.1.1:** In a certain city, it has been calculated 10 years ago that the amount of toxins in a battery of water is distributed with mean  $\mu_0 = 2.0$  g. A random sample of 51 batteries gave a sample mean of 2.06 g and a sample standard deviation of 0.141 g. The two hypothesis are as follows:

$$H_0 : \mu = \mu_0$$

$$H_1 : \mu > \mu_0$$

Does this data provide compelling evidence that the claim  $\mu = 2.0$  g still holds true to this day? Use a significance level of  $\alpha = 0.01$ .

*Solution:* Since the distribution of the population is not known and the standard deviation of the population is also not known, it is possible to apply the CLT and get:

$$Z = \frac{\bar{X} - \mu_0}{S/\sqrt{n}} = \frac{2 - 2.06}{1.41/\sqrt{51}} = 3.04$$

Which is the standardized version of  $\bar{X}$  assuming the null hypothesis to be true. This means that the evidence obtained from the data is roughly 3 standard deviation larger than the expected value under  $H_0$ . The p-value is given by:

$$p = P(Z \geq 3.04) = 1 - \Phi(3.04) = 1 - 0.9988 = 0.0012$$

Which is lower than the chosen  $\alpha$  (and extremely low in general). Therefore, the null hypothesis ought to be rejected.  $\square$

Let  $H_1 : \mu < \mu_0$ . The null hypothesis ought to be rejected if a very small value  $z = (\bar{x} - \mu_0)/(\sigma/\sqrt{n})$  from  $Z$  is retrieved. If this is the case, this implies that any value lower than  $z$  is even more inconsistent with  $H_0$  than  $z$  itself. The p-value of the test is therefore the probability of retrieving a value for  $Z$  smaller or equal than  $z$  assuming  $H_0$  to be true.

Let  $H_1 : \mu \neq \mu_0$ . The null hypothesis ought to be rejected if a very small or very large value  $z = (\bar{x} - \mu_0)/(\sigma/\sqrt{n})$  from  $Z$  is retrieved. If this is the case, this implies that any value lower than  $z$  in the first case and a value greater than  $z$  in the second case is even more inconsistent with  $H_0$  than  $z$  itself. The p-value of the test is therefore the probability of retrieving a value for  $|Z|$  greater or equal than  $z$  assuming  $H_0$  to be true.

The z tests with known  $\sigma$  are among the few for which there are simple formulas for computing  $\beta$ , the probability of a type II error to occur. Let  $H_1 : \mu > \mu_0$ , and let  $\mu'$  be any value of  $\mu$  that exceeds  $\mu_0$ . If  $H_0$  is not rejected when  $\mu = \mu'$  then, by definition, a type II error occurred. Denote with  $\beta(\mu')$  the probability of not rejecting  $H_0$  when  $\mu = \mu'$ . This results in:

$$\begin{aligned} \beta(\mu') &= P(H_0 \text{ is not rejected when } \mu = \mu') = P(\bar{X} < \mu_0 + z_\alpha \cdot \sigma/\sqrt{n} \text{ when } \mu = \mu') = \\ &P\left(\frac{\bar{X} - \mu'}{\sigma/\sqrt{n}} < z_\alpha + \frac{\mu_0 - \mu'}{\sigma/\sqrt{n}} \text{ when } \mu = \mu'\right) = \Phi\left(z_\alpha + \frac{\mu_0 - \mu'}{\sigma/\sqrt{n}}\right) \end{aligned}$$

In the case of  $H_1 : \mu < \mu_0$ , it is easy to see that:

$$\beta(\mu') = 1 - \Phi\left(-z_\alpha + \frac{\mu_0 - \mu'}{\sigma/\sqrt{n}}\right)$$

In the same fashion, if  $H_1 : \mu \neq \mu_0$  then:

$$\beta(\mu') = \Phi\left(z_{\alpha/2} + \frac{\mu_0 - \mu'}{\sigma/\sqrt{n}}\right) - \Phi\left(-z_{\alpha/2} + \frac{\mu_0 - \mu'}{\sigma/\sqrt{n}}\right)$$

When the alternative hypothesis is either  $H_1 : \mu > \mu_0$  or  $H_1 : \mu < \mu_0$ , the sample size  $n$  should be chosen to satisfy:

$$\Phi\left(z_{\alpha} + \frac{\mu_0 - \mu'}{\sigma/\sqrt{n}}\right) = \Phi(-z_{\beta}) = \beta$$

This is because  $-z_{\beta}$  represents the  $z$  critical value that captures lower-tail area  $\beta$ . Solving for  $n$  gives:

$$n = \left[ \frac{\sigma(z_{\alpha} + z_{\beta})}{\mu_0 - \mu'} \right]^2$$

In the case of  $H_1 : \mu \neq \mu_0$ , it is still possible to retrieve an approximate solution:

$$n = \left[ \frac{\sigma(z_{\alpha/2} + z_{\beta})}{\mu_0 - \mu'} \right]^2$$