

Numerical Methods in Engineering and Applied Science

Lecture 3.

Let $f(x)$ be a sufficiently smooth function of $x \in \mathcal{R}$. To derive a first-order one-sided finite-difference approximation to its first derivative at a point $x = x_0$, let us evaluate f at $x_1 = x_0 + h$, where h is small. Consider the Taylor series

$$f(x_1) = f(x_0) + hf'(x_0) + \frac{h^2}{2}f''(x_0) + \frac{h^3}{6}f'''(x_0) + \frac{h^4}{24}f''''(\xi). \quad (1)$$

After rearranging the terms we obtain

$$hf'(x_0) = f(x_1) - f(x_0) - \frac{h^2}{2}f''(x_0) - \frac{h^3}{6}f'''(x_0) - \frac{h^4}{24}f''''(\xi). \quad (2)$$

Then we divide by h :

$$f'(x_0) = \frac{f(x_1) - f(x_0)}{h} - \frac{h}{2}f''(x_0) - \frac{h^2}{6}f'''(x_0) - \frac{h^3}{24}f''''(\xi). \quad (3)$$

Let us introduce the notation $R(x)$ for the truncation error,

$$R(x_0) = \frac{h}{2}f''(x_0) + \frac{h^2}{6}f'''(x_0) + \frac{h^3}{24}f''''(\xi). \quad (4)$$

Then we obtain

$$f'(x_0) = \frac{f(x_1) - f(x_0)}{h} - R(x_0) \quad (5)$$

and

$$\frac{f(x_1) - f(x_0)}{h} = f'(x_0) + R(x_0). \quad (6)$$

Let's consider again the truncation error,

$$R(x_0) = \frac{h}{2}f''(x_0) + \frac{h^2}{6}f'''(x_0) + \frac{h^3}{24}f''''(\xi). \quad (7)$$

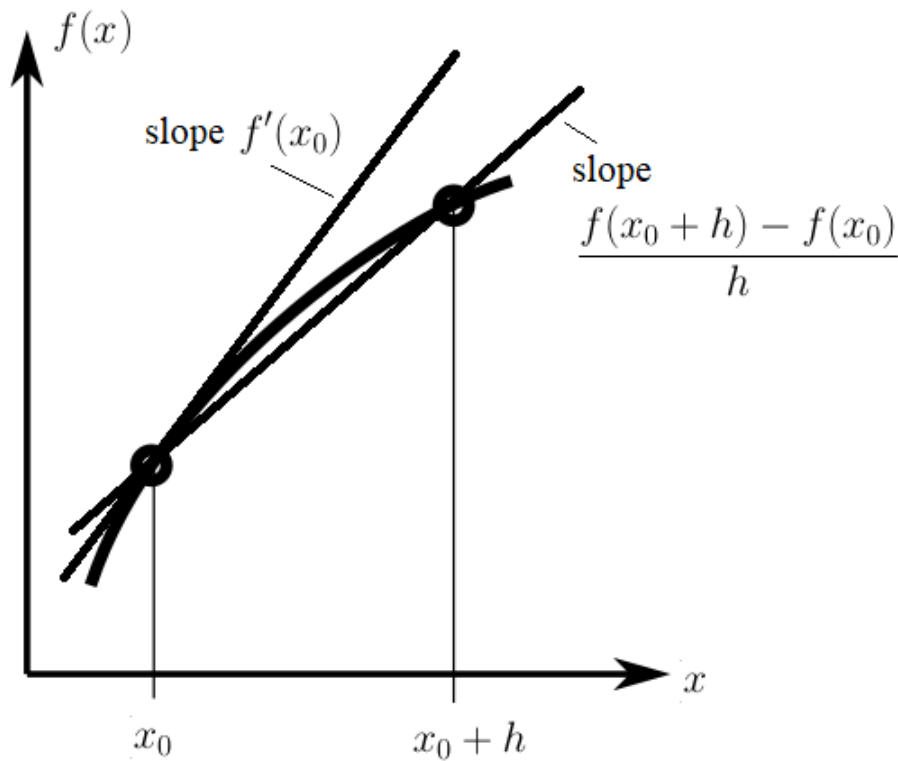
When h is sufficiently small, the second and third terms are negligibly small, compared to the first term in the right-hand side. In other words,

$$R(x_0) \sim \frac{h}{2}f''(x_0) \quad (8)$$

as $h \rightarrow 0$. We can rewrite this as

$$\left| \frac{f(x_0 + h) - f(x_0)}{h} - f'(x_0) \right| \sim \frac{h}{2}|f''(x_0)| \quad (9)$$

This is a first-order one-sided FD scheme: $D_+f(x) = (f(x+h) - f(x))/h$



A central scheme can be derived similarly.

$$f(x_0 + h) = f(x_0) + hf'(x_0) + \frac{h^2}{2}f''(x_0) + \frac{h^3}{6}f'''(x_0) + \frac{h^4}{24}f''''(\xi_1), \quad (10)$$

$$f(x_0 - h) = f(x_0) - hf'(x_0) + \frac{h^2}{2}f''(x_0) - \frac{h^3}{6}f'''(x_0) + \frac{h^4}{24}f''''(\xi_2). \quad (11)$$

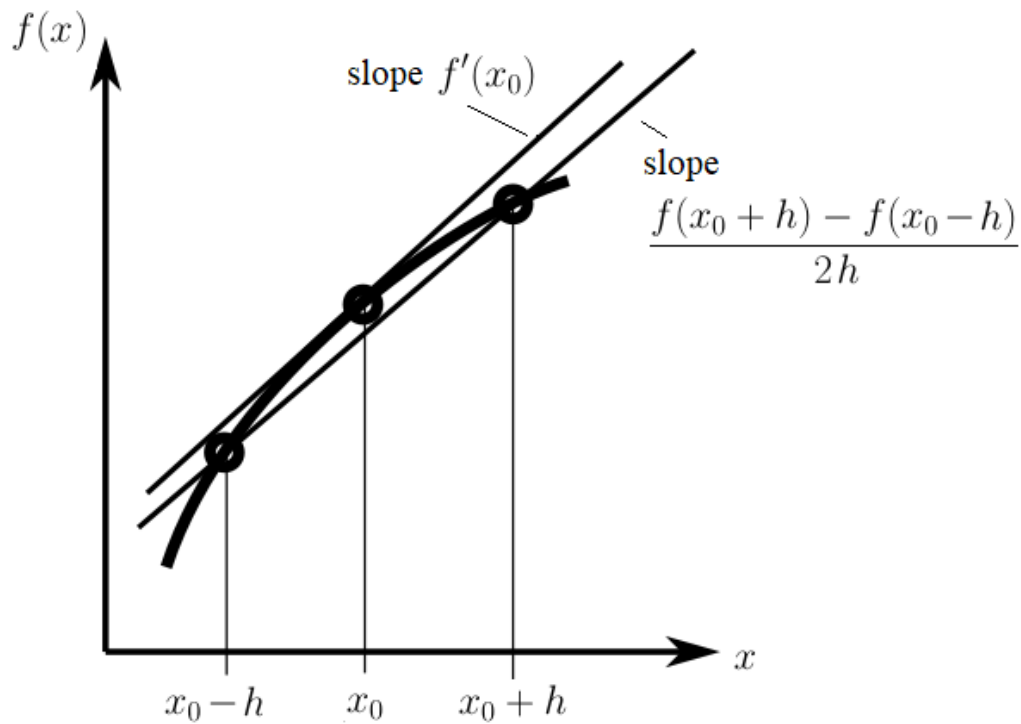
Therefore,

$$f(x_0 + h) - f(x_0 - h) = 2hf'(x_0) + \frac{h^3}{3}f'''(x_0) + O(h^5) \quad (12)$$

and

$$\frac{f(x_0 + h) - f(x_0 - h)}{2h} - f'(x_0) = \frac{h^2}{6}f'''(x_0) + O(h^4). \quad (13)$$

This is a second-order central FD scheme: $D_0 f(x) = (f(x+h) - f(x-h))/2h$



We found that

$$|D_+f(x) - f'(x)| \sim \frac{h}{2}|f''(x)| \quad (14)$$

$$|D_0f(x) - f'(x)| \sim \frac{h^2}{6}|f'''(x)|, \quad (15)$$

In general, for any finite-difference approximation,

$$|Df(x) - f'(x)| \sim Ch^p, \quad (16)$$

where C and p do not depend on h .

By taking the logarithm, we obtain

$$\log |Df(x) - f'(x)| \sim \log C + p \log h, \quad (17)$$

therefore, the plot of $\log |Df(x) - f'(x)|$ versus $\log h$ looks like a straight line.

One can use a similar approach to derive a central scheme for the second derivative.

We will obtain

$$D^{(2)}f(x) = \frac{\alpha f(x-h) + \beta f(x) + \gamma f(x+h)}{h^2} \quad (18)$$

and

$$\left| D^{(2)}f(x) - f''(x) \right| \sim Ch^p. \quad (19)$$

Question: $\alpha = ?$ $\beta = ?$ $\gamma = ?$ $C = ?$ Maximum possible $p = ?$

One can derive finite-difference schemes by the process of local interpolation and differentiation.

For example, $D_0 f(x)$ can be derived as follows:

- *Let $p(x)$ be the unique polynomial of degree ≤ 2 with $p(x_0 - h) = f(x_0 - h)$, $p(x_0) = f(x_0)$ and $p(x_0 + h) = f(x_0 + h)$.*
- Set $D_0 f(x) = p'(x_0)$.

The interpolant is given by

$$p(x) = f(x_0 - h)a_{-1}(x) + f(x_0)a_0(x) + f(x_0 + h)a_1(x), \quad (20)$$

where

$$a_{-1}(x) = \frac{(x - x_0)(x - (x_0 + h))}{2h^2}, \quad a_0(x) = -\frac{(x - (x_0 - h))(x - (x_0 + h))}{h^2},$$

$$a_1(x) = \frac{(x - (x_0 - h))(x - x_0)}{2h^2}. \quad (21)$$

$p(x)$ is a *Lagrange polynomial*. Higher degree Lagrange polynomials can be used to construct finite-difference schemes of higher order. For example, a fourth-order central scheme: For example, a fourth-order scheme can be derived as follows:

- Let $p(x)$ be the unique polynomial of degree ≤ 4 with $p(x_0 \pm 2h) = f(x_0 \pm 2h)$, $p(x_0 \pm h) = f(x_0 \pm h)$ and $p(x_0) = f(x_0)$.
- Set $D_{0IV}f(x) = p'(x_0)$.

The interpolant is given by

$$p(x) = \sum_{j=-2}^2 f(x_0 + jh)a_j(x), \quad (22)$$

where

$$a_j(x) = \prod_{\substack{-2 \leq m \leq 2 \\ m \neq j}} \frac{x - (x_0 + mh)}{(j - m)h}. \quad (23)$$

We obtain

$$D_{0IV}f(x) = \frac{-f(x+2h) + 8f(x+h) - 8f(x-h) + f(x-2h)}{12h}. \quad (24)$$

Wikipedia page on Lagrange polynomials:

https://en.wikipedia.org/wiki/Lagrange_polynomial

Wikipedia page on finite difference coefficients:

https://en.wikipedia.org/wiki/Finite_difference_coefficient

For the original source, see B. Fornberg, "Generation of Finite Difference Formulas on Arbitrarily Spaced Grids", *Mathematics of Computation*, **51** (184): 699–706 (1988).

Let us now consider the following boundary-value problem:

$$\begin{aligned} -u''(x) &= f(x), & \forall x \in]0, 1[, \\ u(0) &= u(1) = 0 \end{aligned} \tag{25}$$

We divide the domain using a set of discrete points

$$x_0 = 0 < x_1 < x_2 < \dots < x_N < x_{N+1} = 1 \tag{26}$$

with a constant step $h = x_{i+1} - x_i$, $\forall i \in [0, N]$.

We then write the differential at the discrete points,

$$-u''(x_i) = f(x_i), \quad \forall i \in 1, \dots, N. \tag{27}$$

Consider the Taylor series

$$u(x_{i+1}) = u(x_i) + hu'(x_i) + \frac{h^2}{2}u''(x_i) + \frac{h^3}{6}u'''(x_i) + \frac{h^4}{24}u''''(\xi_i), \tag{28}$$

and

$$u(x_{i-1}) = u(x_i) - hu'(x_i) + \frac{h^2}{2}u''(x_i) - \frac{h^3}{6}u'''(x_i) + \frac{h^4}{24}u''''(\eta_i), \quad (29)$$

where $\xi_i \in [x_i, x_{i+1}]$ and $\eta_i \in [x_{i-1}, x_i]$. After summing up the two series, we obtain

$$u(x_{i+1}) + u(x_{i-1}) = 2u(x_i) + h^2u''(x_i) + O(h^4), \quad (30)$$

which suggests that it may be reasonable to approximate $u''(x_i)$ with the finite difference

$$\frac{u(x_{i-1}) - 2u(x_i) + u(x_{i+1}))}{h^2}. \quad (31)$$

This constitutes a second-order accurate approximation to the second derivative operator, as it can be shown that

$$R_i = u''(x_i) - \frac{u(x_{i-1}) - 2u(x_i) + u(x_{i+1}))}{h^2} = O(h^2). \quad (32)$$

R_i is the **consistency** error.

Let us now consider the following finite difference equation

$$-\frac{u_{i-1} - 2u_i + u_{i+1}}{h^2} = f_i, \quad i = 1, \dots, N, \quad (33)$$

where $f_i = f(x_i)$ and u_i are unknowns. It can be shown that finite-difference solution u_i **converges with the second order** to the exact solution $u(x_i)$ of the boundary-value problem:

$$|u_i - u(x_i)| \leq \frac{1}{12} \|u'''\|_{\infty} h^2. \quad (34)$$

The finite-difference problem can be written in an alternative form

$$u_{i-1} \left(-\frac{1}{h^2} \right) + u_i \left(\frac{2}{h^2} \right) + u_{i+1} \left(-\frac{1}{h^2} \right) = f_i, \quad i = 1, \dots, N, \quad (35)$$

$$u_0 = 0, \quad (36)$$

$$u_{N+1} = 0. \quad (37)$$

It is written the matrix form as

$$D^{(2)}\mathbf{U} = \mathbf{b} \quad (38)$$

where

$$D^{(2)} = \frac{1}{h^2} \begin{pmatrix} 2 & -1 & & & & \\ -1 & 2 & -1 & & & \\ & -1 & 2 & -1 & & \\ & & & \dots & & \\ & & & & -1 & 2 & -1 \\ & & & & & -1 & 2 \end{pmatrix} \quad (39)$$

$$\mathbf{U} = \begin{pmatrix} u_1 \\ u_2 \\ u_3 \\ \vdots \\ u_{N-1} \\ u_N \end{pmatrix}, \quad \mathbf{b} = \begin{pmatrix} f_1 \\ f_2 \\ f_3 \\ \vdots \\ f_{N-1} \\ f_N \end{pmatrix} \quad (40)$$

This tri-diagonal linear system can be solved by Gaussian elimination.

Note that the same matrix $D^{(2)}$ can be used to compute the derivative of u by matrix-vector multiplication when the values of \mathbf{U} are given. It is called a *differentiation matrix*. The differentiation matrix (41) in this case assumes that $u_0 = 0$ and $u_{N+1} = 0$. If this is not the case, the first and the last lines in $D^{(2)}$ should be modified such as to use one-sided schemes or different boundary conditions.

For example, let us introduce periodic boundary conditions, such that $x_0 = x_N$ and $x_{N+1} = x_1$. In that case we obtain

$$D^{(2)} = \frac{1}{h^2} \begin{pmatrix} 2 & -1 & & & & -1 \\ -1 & 2 & -1 & & & \\ & -1 & 2 & -1 & & \\ & & & \dots & & \\ & & & & -1 & 2 & -1 \\ -1 & & & & & -1 & 2 \end{pmatrix} \quad (41)$$