

Week 4: Kernel Density Estimation

MATH-517 Statistical Computation and Visualization

Tomas Masak

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The Problem

Setup: X_1, \dots, X_n is a random sample from a density $f(x)$

Goal: Estimate f nonparametrically.

We already know of **histogram**, which requires a specification of

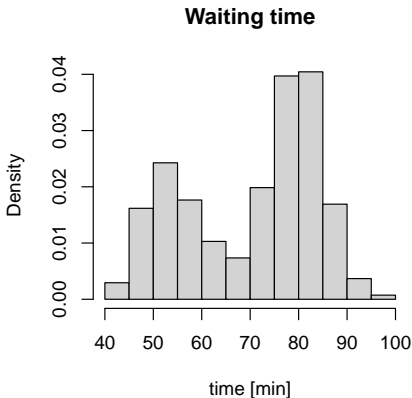
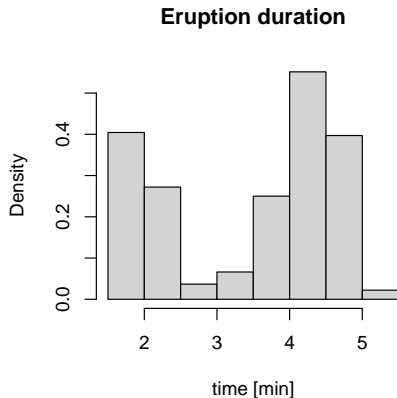
- *origin* and *binwidth*, or
- *breaks* - more general, but non-equidistant binning is bad anyway, so think only about origin and binwidth

Running Ex.: Yellowstone's Old Faithful geyser - faithful data:

- *waiting* - time between eruptions
- *eruptions* - duration of the eruptions

Basic Histogram

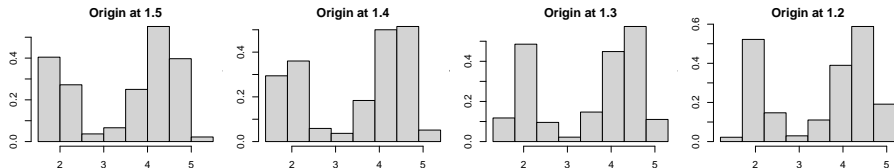
```
data(faithful)
par(mfrow=c(1,2))
hist(faithful$eruptions, probability=T, main = "Eruption duration", xlab="time [min]")
hist(faithful$waiting, probability=T, main = "Waiting time", xlab="time [min]")
```



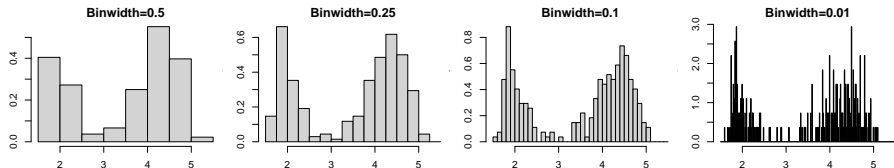
- breaks specified, so a rule of thumb used to choose origin and binwidth

Changin Origin and Binwidth

```
par(mfrow=c(1,4), mar = c(3.2, 3, 1.6, 0.2)) # reduce the white space around individual plots
hist(faithful$eruptions, probability=T, main="Origin at 1.5");
hist(faithful$eruptions, breaks=seq(1.4,5.4,by=0.5), probability=T, main="Origin at 1.4", xlab="time [min]");
hist(faithful$eruptions, breaks=seq(1.3,5.3,by=0.5), probability=T, main="Origin at 1.3", xlab="time [min]");
hist(faithful$eruptions, breaks=seq(1.2,5.2,by=0.5), probability=T, main="Origin at 1.2", xlab="time [min]");
```



```
par(mfrow=c(1,4), mar = c(3.2, 3, 1.6, 0.2))
hist(faithful$eruptions, probability=T, main="Binwidth=0.5")
hist(faithful$eruptions, breaks=seq(1.5,5.5,by=0.25), probability=T, main="Binwidth=0.25")
hist(faithful$eruptions, breaks=seq(1.5,5.5,by=0.1), probability=T, main="Binwidth=0.1")
hist(faithful$eruptions, breaks=seq(1.5,5.5,by=0.01), probability=T, main="Binwidth=0.01")
```



Issues with Histogram

Histogram is great for quick visualization, but does not pass as a density estimator.

- *origin* is completely arbitrary
- *binwidth* relates to smoothness of f , but histogram cannot be smooth anyway

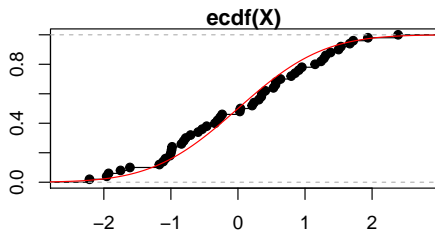
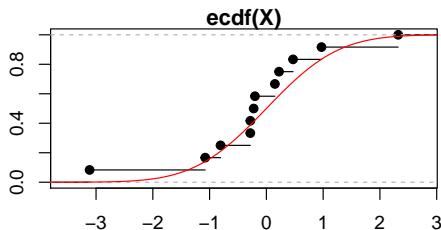
Let us now address these two issues by a naive version of kernel density estimation (KDE).

Prerequisite: empirical (cumulative) distribution function (ECDF):

$$\hat{F}_n(x) = \frac{1}{n} \sum_{i=1}^n \mathbb{I}_{[X_i \leq x]}$$

ECDF

```
edf_plot <- function(N){  
  X <- rnorm(N)  
  EDF <- ecdf(X)  
  plot(EDF)  
  x <- seq(-4,4,by=0.01)  
  points(x,pnorm(x),type="l",col="red")  
}  
  
set.seed(517)  
par(mfrow=c(1,2), mar=c(2,2,1,1))  
edf_plot(12)  
edf_plot(50)
```



- The ECDF $\hat{F}_n(x) = \frac{1}{n} \sum_{i=1}^n \mathbb{I}_{[X_i \leq x]}$ is an estimator of F
 - by [Glivenko-Cantelli theorem](#) uniformly almost surely consistent:

$$\sup_x |\hat{F}_n(x) - F(x)| \xrightarrow{a.s.} 0$$

- f is the derivative F : $f(x) = \lim_{h \rightarrow 0+} \frac{F(x+h) - F(x-h)}{2h}$
- Fix $h = h_n$ as something small depending on n and plug it in:

$$\hat{f}(x) = \frac{\hat{F}_n(x + h_n) - \hat{F}_n(x - h_n)}{2h_n}$$

- we need $h_n \rightarrow 0+$ for $n \rightarrow \infty$ in order to have any hope in consistency

Consistency

- $\mathbb{E}\hat{f}(x) = \frac{F(x+h_n)-F(x-h_n)}{2h_n} \rightarrow f(x) \quad \text{if } h_n \rightarrow 0_+$

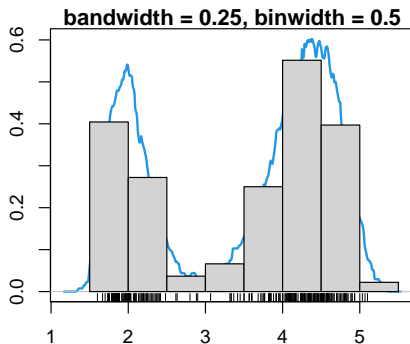
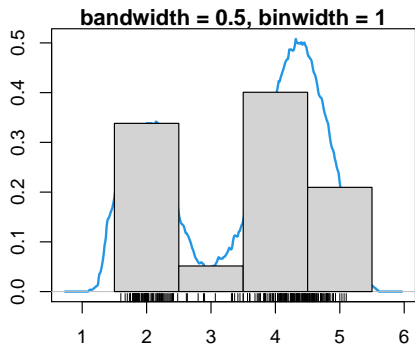
- since $\hat{f}(x) = \frac{1}{2nh_n} \sum_{i=1}^n \underbrace{\mathbb{I}[X_i \in (x-h_n, x+h_n)]}_{\text{Ber}(F(x+h_n)-F(x-h_n))} :$

$$\begin{aligned} \text{var}(\hat{f}(x)) &= \frac{1}{4nh_n^2} [F(x+h_n) - F(x-h_n)] [1 - F(x+h_n) + F(x-h_n)] \\ &= \frac{F(x+h_n) - F(x-h_n)}{2h_n} \frac{1 - F(x+h_n) + F(x-h_n)}{2nh_n} \rightarrow 0 \end{aligned}$$

\Rightarrow consistency if $h_n \rightarrow 0$ and $nh_n \rightarrow \infty$

Naive KDE \equiv Moving Histogram

- when *binwidth* for the histogram is taken as $2h$, the naive KDE gives exactly the histogram value in the middle of every bin
 - *origin* does not matter anymore



Naive KDE Rewritten

The naive KDE can be written as

$$\begin{aligned}\hat{f}(x) &= \frac{1}{2nh_n} \sum_{i=1}^n \mathbb{I}[X_i \in (x-h_n, x+h_n)] \\ &= \frac{1}{2nh_n} \sum_{i=1}^n \mathbb{I}\left[-1 \leq \frac{X_i - x}{h_n} \leq 1\right] \\ &= \frac{1}{nh_n} \sum_{i=1}^n K\left(\frac{X_i - x}{h_n}\right)\end{aligned}$$

where $K(\cdot)$ is the density of $U[-1, 1]$.

Next step: replace $K(\cdot)$ for something else.

KDE - Definition and Properties

Definition. KDE of f based on X_1, \dots, X_N is

$$\hat{f}(x) = \frac{1}{nh_n} \sum_{i=1}^n K\left(\frac{X_i - x}{h_n}\right),$$

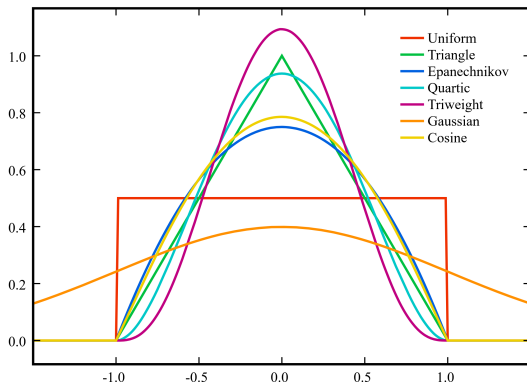
where the **kernel** $K(\cdot)$ satisfies:

- 1 $K(x) \geq 0$ for all $x \in \mathbb{R}$
- 2 $K(-x) = K(x)$ for all $x \in \mathbb{R}$
- 3 $\int_{\mathbb{R}} K(x) dx = 1$
- 4 $\lim_{|x| \rightarrow \infty} |x| K(x) = 0$
- 5 $\sup_x |K(x)| < \infty$

- $K(\cdot)$ is usually taken to be a density, and the assumptions
 - 1-3 hold if it is symmetric
 - 4 holds if it has a finite absolute moment
 - 5 holds if it is uniformly bounded
- if $h_n \rightarrow 0$ and $nh_n \rightarrow \infty$ we have pointwise consistency
 - we will show this in a bit
 - also uniform consistency, but tricky to show

Common Kernels

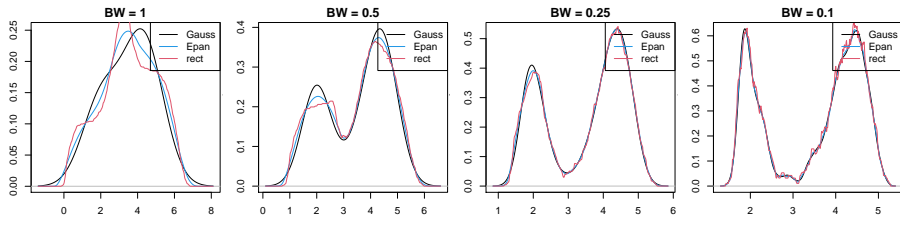
Kernel Name	Formula
Epanechnikov	$K(x) \propto (1 - x^2) \mathbb{I}_{[x \leq 1]}$
Tricube (a.k.a. Triweight)	$K(x) \propto (1 - x ^3)^3 \mathbb{I}_{[x \leq 1]}$
Gaussian	$K(x) \propto \exp(-x^2/2)$
...	...



Bandwidth $>$ Kernel

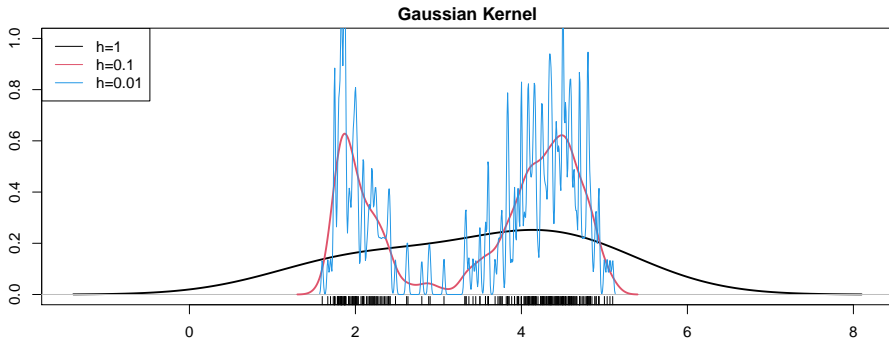
While there is some improvement when not using the naive rectangular kernel, choosing good bandwidth h is much more important.

```
# This is only a handle, not a proper function! Why?
plot_kdes <- function(bw){
  plot(density(faithful$eruptions, kernel="gaussian", bw=bw),
       main=paste("BW = ",bw,sep=""), xlab="time [min]")
  lines(density(faithful$eruptions, kernel="epanechnikov", bw=bw), col=4)
  lines(density(faithful$eruptions, kernel="rectangular", bw=bw), col=2)
  legend("topright", col=c(1, 4, 2), lty=1, legend=c("Gauss", "Epan", "rect"))
}
par(mfrow=c(1,4), mar = c(3.2, 3, 1.6, 0.2))
plot_kdes(1); plot_kdes(0.5); plot_kdes(0.25); plot_kdes(0.1)
```



Bandwidth

- the bandwidth h is a *tuning parameter* and needs to be chosen somehow in practice
 - h small \rightarrow wiggly estimator
 - h large \rightarrow slowly-varying estimator



Bias-variance Trade-off

Goal: choose the tuning parameter h so that the mean squared error of the estimator is minimized:

$$\underbrace{\mathbb{E}[\hat{f}(x) - f(x)]^2}_{MSE} = \mathbb{E}[\hat{f}(x) \pm \mathbb{E}\hat{f}(x) - f(x)]^2 = \underbrace{[\mathbb{E}\hat{f}(x) - f(x)]^2}_{bias^2} + \underbrace{\text{var}(\hat{f}(x))}_{variance}$$

Blackboard calculations (available in the lecture notes) give

$$\begin{aligned}\text{bias}(\hat{f}(x)) &= \frac{1}{2}h^2f''(x) \int z^2K(z)dz + o(h^2) \\ \text{var}(\hat{f}(x)) &= \frac{1}{nh}f(x) \int [K(z)]^2dz + o\left(\frac{1}{nh}\right)\end{aligned}$$

This shows consistency for $h = h_n \rightarrow 0$ and $nh_n \rightarrow \infty$ and encapsulates the trade-off:

- small $h \Rightarrow$ small bias but large variance
- large $h \Rightarrow$ large bias but small variance

Optimal Bandwidth

Plugging this back in the MSE formula ignoring the *little-o* terms, deriving the MSE by h and setting it to zero leads to asymptotically optimal bandwidth choice:

$$h_{opt}(x) = n^{-1/5} \left(\frac{f(x) \int K(z)^2 dz}{[f''(x)]^2 [\int z^2 K(z) dz]^2} \right)^{-1/5}$$

- ① $h_{opt}(x)$ is a local choice - depends on x
- ② global choice can be obtained by integrating out x
- ③ $h_{opt}(x)$ cannot be directly used, since depends on the unknown f
 - reference method: assume a known f for this formula
 - two-step method: f in the formula estimated by a pilot fit (e.g. visually appealing one)
- ④ $h_{opt}(x) \asymp n^{-1/5}$ and with this choice

$$MSE \asymp bias^2 \asymp variance = \mathcal{O}(n^{-4/5})$$

- optimal non-parametric rate

Section 1

Computational Considerations

Computational Considerations

Evaluating

$$\hat{f}(x_j) = \frac{1}{nh} \sum_{i=1}^n K\left(\frac{X_i - x_j}{h}\right)$$

on a grid of points x_1, \dots, x_m takes naively $\mathcal{O}(mn)$.

- for $n \asymp m$, this means quadratic complexity $\mathcal{O}(n^2)$
- we will show how to reduce this to log-linear complexity $\mathcal{O}(n \log n)$

Circulants and DFT

Definition: A matrix $\mathbf{C} = (c_{jk})_{j,k=0}^{p-1} \in \mathbb{R}^{p \times p}$ is called *circulant* if $c_{jk} = c_{|j-k|}$, where $\mathbf{c} = (c_j) \in \mathbb{R}^p$ is the *symbol* of \mathbf{C} (the first column of \mathbf{C}).

$$\mathbf{C} = \begin{bmatrix} c_0 & c_{n-1} & \cdots & c_2 & c_1 \\ c_1 & c_0 & c_{n-1} & & c_2 \\ \vdots & c_1 & c_0 & \ddots & \vdots \\ c_{n-2} & & \ddots & \ddots & c_{n-1} \\ c_{n-1} & c_{n-2} & \cdots & c_1 & c_0 \end{bmatrix}$$

Definition: The *discrete Fourier basis* in \mathbb{R}^p is (in the columns of) the matrix $\mathbf{E} = (e_{jk})_{j,k=0}^{p-1} \in \mathbb{R}^{p \times p}$ with entries given by

$$e_{jk} = \frac{1}{\sqrt{p}} e^{2\pi i j k / p}, \quad j, k = 0, \dots, p-1$$

- straightforward to check that \mathbf{E} is unitary \Rightarrow really a basis.

Definition: The *discrete Fourier transform* (DFT) of $\mathbf{x} \in \mathbb{R}^p$ is $\mathbf{E}^* \mathbf{x}$ with \mathbf{E} being the discrete Fourier basis from the previous definition. The inverse DFT is the same without the complex conjugate $\mathbf{E} \mathbf{x}$.

FFT: Any algorithm allowing to perform DFT of $\mathbf{x} \in \mathbb{R}^p$ with the log-linear complexity $\mathcal{O}(p \log p)$ is referred to as the fast Fourier transform (FFT).

- think of a function `fft(x)` that returns $\mathbf{E}^* \mathbf{x}$
- the original algorithm due to John W. Tukey

Circulants and DFT

Claim: Circulant matrices are diagonalizable by the DFT. Specifically, the eigendecomposition of a circulant matrix \mathbf{C} (with a symbol \mathbf{c}) is given by $\mathbf{C} = \mathbf{E} \text{diag}(\mathbf{q}) \mathbf{E}^*$, where $\mathbf{q} = \mathbf{E}^* \mathbf{c}$.

Proof: In the lecture notes, if interested.

Now we know that every circulant matrix can be applied efficiently thanks to the FFT:

$$\begin{aligned} \mathbf{C}\mathbf{x} &= \mathbf{E} \underbrace{\text{diag}\left(\underbrace{\mathbf{q}}_{=\text{FFT}(\mathbf{c})}\right) \underbrace{\mathbf{E}^*\mathbf{x}}_{=\text{FFT}(\mathbf{x})}}_{\substack{\text{entry-wise prod of those 2 vectors} \\ \text{inverse FFT of that product}}} \end{aligned}$$

KDE after Initial Histogram

$$\hat{f}(x) = \frac{1}{nh} \sum_{i=1}^n K\left(\frac{X_i - x}{h}\right)$$

Round data $X_1, \dots, X_n \in (a, b]$ to a common equidistant grid
 $a = t_0 < t_1 < \dots < t_{p-1} < t_p = b$

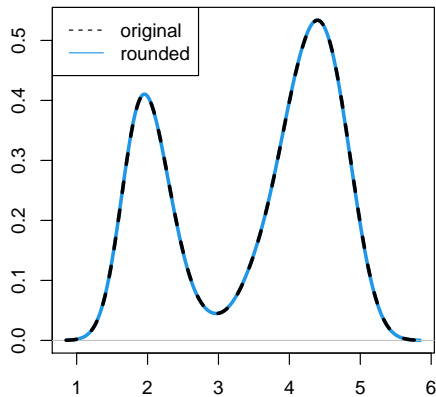
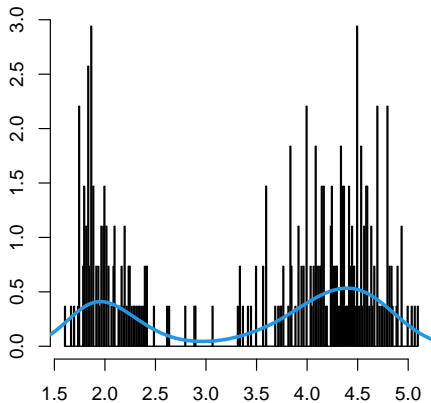
- let $\tilde{X}_1, \dots, \tilde{X}_n$ denote rounded data and $\mathbf{y} \in \mathbb{R}^p$ the counts, i.e. $y_j = \sum_{i=1}^n \mathbb{I}_{[X_i \in (t_{j-1}, t_j]}$
- this is nothing but a histogram (only an initial one, with a small binwidth)

KDE of the rounded data \equiv linear smoother of the initial histogram:

$$\hat{f}(x) = \frac{1}{nh_n} \sum_{i=1}^n K\left(\frac{\tilde{X}_i - x}{h_n}\right) = \frac{1}{nh_n} \sum_{j=1}^p K\left(\frac{t_j - x}{h_n}\right) y_j$$

Effect of Rounding is Small

By rounding, we only commit negligible (numerical) error:



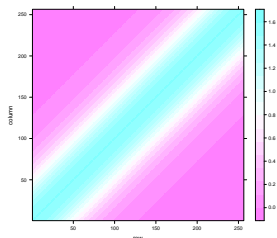
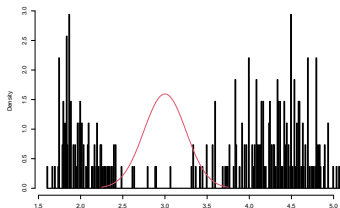
KDE as a Linear Smoother

$$\hat{f}(x) = \frac{1}{nh_n} \sum_{j=1}^p K\left(\frac{t_j - x}{h_n}\right) y_j$$

Say we want to evaluate \hat{f} on the grid t_1, \dots, t_p . Then

$$(\hat{f}(t_1), \dots, \hat{f}(t_p))^T = \mathbf{S}\mathbf{y}, \quad \text{with} \quad s_{ij} = \frac{1}{nh_n} K\left(\frac{t_j - t_i}{h_n}\right)$$

- matrix transformation of the input (here \mathbf{y}) \equiv linear smoother

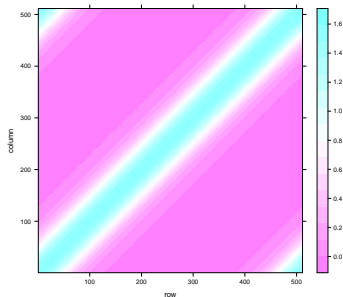


Toeplitz into Circulant

The hat matrix \mathbf{S} is a Toeplitz (stationary) matrix.

Any Toeplitz matrix \mathbf{S} of dimensions $n \times n$ can be embedded into a circulant matrix \mathbf{C} of dimensions at most $(2n - 1) \times (2n - 1)$. The easiest way is to wrap the first row of \mathbf{S} , denoted \mathbf{s} , to form the first row of \mathbf{C} as

$$\mathbf{c} = (s_1, s_2, \dots, s_{n-1}, s_n, s_{n-1}, \dots, s_2)^\top$$



Toeplitz and FFT

Calculating $\mathbf{S}\mathbf{y}$ with \mathbf{S} Toeplitz can be done fast by

- embedding \mathbf{S} into a circulant \mathbf{C}
- noticing that

$$\mathbf{C} \begin{pmatrix} \mathbf{y} \\ \mathbf{0} \end{pmatrix} = \left(\begin{array}{c|c} \mathbf{S} & \cdot \\ \hline \cdot & \cdot \end{array} \right) \begin{pmatrix} \mathbf{y} \\ \mathbf{0} \end{pmatrix} = \begin{pmatrix} \mathbf{S}\mathbf{y} \\ \cdot \end{pmatrix}$$

- calculating $\mathbf{C}\mathbf{y}$ using FFT

Summary - Computations

Fast KDE calculation:

- 1 round up the original data to a common equidistant grid
 - equivalent to calculating initial histogram (with a small binwidth)
 - KDE is now reduced to a linear smoother with a Toeplitz hat matrix
- 2 Embed the Toeplitz hat matrix into a circulant matrix
- 3 Use FFT to apply the circulant matrix

From a high-level point of view, disregarding FFT:

- rounding data induces structure (Toeplitz)
- this structure can be used to speed up computations

Summary - Overall

Motivation:

- 1 On Week 2, we introduced the histogram as a data exploratory tool.
- 2 On Week 3, we noticed some issues of the histogram.
- 3 Histogram is a poor estimator of density, because it
 - is never smooth and requires a choice of *origin*
- 4 Today, we introduced naive KDE by generalizing histogram to its *origin*-free version.
- 5 Then, we generalized naive KDE by allowing for better kernels.
- 6 Now we have a decent nonparametric density estimation tool: KDE.
 - in exploratory analysis, histograms often overlaid with KDEs.

Main takeaways:

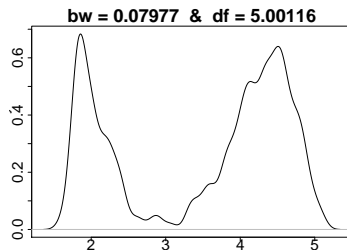
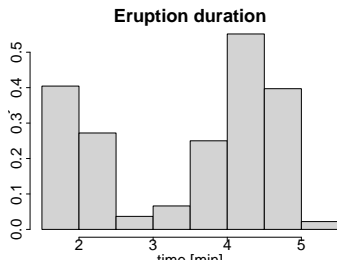
- 7 Asymptotic properties analyzed using Taylor expansions.
 - suggest a way to choose *bandwidth*
 - the bias-variance trade-off made explicit
- 8 Working on a grid and using FFT is the key to computational feasibility.

Degrees of Freedom (df)

- in linear models, the model df is the dimension of the space where the model is free to vary
 - equals number of regressors p if no linear dependence between regressors
 - generally $\text{tr}(\mathbf{H})$, i.e. the trace of the hat matrix $\mathbf{H} = \mathbf{X}(\mathbf{X}^\top \mathbf{X})^\dagger \mathbf{X}^\top$
- more generally for linear smoothers: $\text{df} := \text{tr}(\mathbf{S})$

Example: think of a Gaussian mixture model for the Old Faithful eruption data:

$$f(x) = \tau \varphi_{\mu_1, \sigma_1^2}(x) + (1 - \tau) \varphi_{\mu_2, \sigma_2^2}(x)$$



Assignment [5%]

Slide “Bandwidth $>$ Kernel” above gives a vague statement, that choosing bandwidth h is more important than choosing a proper kernel. See this for yourself using a small simulation study. Specifically:

- use Manual 09 to generate data from the Gaussian mixture f
 - use the parameter values provided in the manual
- repeat the following 200 times:
 - generate $N = 100$ samples from the Gaussian mixture
 - perform density estimation, i.e. obtain \hat{f} , for
 - Gaussian, Epanechnikov, and rectangular kernels
 - bandwidth values $h = 0.1, 0.15, 0.2, 0.25, \dots, 0.9$
 - calculate the error measure $\|f - \hat{f}\|_2$
- report your findings as a single (well commented) figure

Note: Please check again Section 5 of the Course Organization for submission instructions.