

In[*]:= ddtheta1 =

```
FullSimplify[(789212160 * 2^(1/2) * Sin[2 * theta1] - 60963840 * 2^(1/2) * Sin[2 * theta2] -
31079786880 * Cos[2 * theta1 + 2 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
1847370240 * Cos[2 * theta1 + 3 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
921225600 * Cos[3 * theta1 + 2 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
1544590080 * Cos[3 * theta1 + 3 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
132321600 * Cos[4 * theta1 + 2 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
247510080 * Cos[3 * theta1 + 4 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
539654400 * Cos[4 * theta1 + 3 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
428068800 * Cos[4 * theta1 + 4 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
7094016000 * 2^(1/2) * Cos[2 * theta1 + 2 * theta2] +
933120000 * 2^(1/2) * Cos[2 * theta1 + 3 * theta2] -
63590400 * 2^(1/2) * Cos[3 * theta1 + 2 * theta2] -
352512000 * 2^(1/2) * Cos[3 * theta1 + 3 * theta2] -
10368000 * 2^(1/2) * Cos[4 * theta1 + 2 * theta2] +
55987200 * 2^(1/2) * Cos[3 * theta1 + 4 * theta2] -
62208000 * 2^(1/2) * Cos[4 * theta1 + 3 * theta2] -
93312000 * 2^(1/2) * Cos[4 * theta1 + 4 * theta2] - 2983910400 * thetadot1 *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
2621652480 * thetadot2 * (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] -
30 * Sin[theta1] + 95)^(1/2) - 27575935872 * Sin[2 * theta1 + 2 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
616465728 * Sin[2 * theta1 + 3 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
2474530560 * Sin[3 * theta1 + 2 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
7331757120 * Sin[3 * theta1 + 3 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
260323200 * Sin[4 * theta1 + 2 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
4665600 * Sin[3 * theta1 + 4 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
1053388800 * Sin[4 * theta1 + 3 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
817257600 * Sin[4 * theta1 + 4 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
6293237760 * 2^(1/2) * Sin[2 * theta1 + 2 * theta2] -
245099520 * 2^(1/2) * Sin[2 * theta1 + 3 * theta2] -
557107200 * 2^(1/2) * Sin[3 * theta1 + 2 * theta2] -
1665100800 * 2^(1/2) * Sin[3 * theta1 + 3 * theta2] -
```

```

20736000 * 2^(1/2) * Sin[4 * theta1 + 2 * theta2] -
124416000 * 2^(1/2) * Sin[4 * theta1 + 3 * theta2] -
186624000 * 2^(1/2) * Sin[4 * theta1 + 4 * theta2] - 35022112320 *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
7560576000 * 2^(1/2) + 83714100480 * Cos[theta1 + theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
17828812800 * 2^(1/2) * Cos[theta1 + theta2] + 5951332800 * Sin[theta1 + theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
1666483200 * 2^(1/2) * Sin[theta1 + theta2] - 2617727550 * thetadot1^2 *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
(6036926475 * thetadot2^2 * (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] -
30 * Sin[theta1] + 95)^(1/2)) / 2 + 74359120320 * Cos[theta1] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
21502302720 * Cos[theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
36725760 * (54 * Cos[theta2] - 90 * 5^(1/2) * Cos[theta1 + theta2 - ArcTan[2]] -
30 * 5^(1/2) * Cos[theta1 - ArcTan[2]] + 215)^(1/2) *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
7461504000 * 2^(1/2) * Cos[theta1] + 3048192000 * 2^(1/2) * Cos[theta2] +
4699641600 * Sin[theta1] * (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] -
30 * Sin[theta1] + 95)^(1/2) - 18303003840 * Sin[theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
2294784000 * 2^(1/2) * Sin[theta1] - 363340800 * 2^(1/2) * Sin[theta2] +
8009683200 * Cos[theta1 - theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
7438279680 * Cos[theta1 + 2 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
19864669440 * Cos[2 * theta1 + theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
235068480 * Cos[theta1 + 3 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
252423360 * Cos[3 * theta1 + theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
635904000 * 2^(1/2) * Cos[theta1 - theta2] - 1975449600 * 2^(1/2) *
Cos[theta1 + 2 * theta2] + 2052864000 * 2^(1/2) * Cos[2 * theta1 + theta2] +
18662400 * 2^(1/2) * Cos[theta1 + 3 * theta2] +
20044800 * 2^(1/2) * Cos[3 * theta1 + theta2] - 11931840 * Sin[theta1 - theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
3004957440 * Sin[theta1 + 2 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
36506531712 * Sin[2 * theta1 + theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
51321600 * Sin[theta1 + 3 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
10376640 * Sin[3 * theta1 + theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
148608000 * 2^(1/2) * Sin[theta1 - theta2] + 1737676800 * 2^(1/2) *
Sin[theta1 + 2 * theta2] + 4492615680 * 2^(1/2) * Sin[2 * theta1 + theta2] +

```

$$\begin{aligned}
& 149\,299\,200 * 2^{(1/2)} * \sin[\theta_1 + 3 * \theta_2] - \\
& 691\,200 * 2^{(1/2)} * \sin[3 * \theta_1 + \theta_2] - 4\,443\,742\,080 * \cos[2 * \theta_1] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} + 187\,721\,280 * \\
& \cos[2 * \theta_2] * (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} + 186\,624\,000 * 2^{(1/2)} * \cos[2 * \theta_1] - \\
& 176\,256\,000 * 2^{(1/2)} * \cos[2 * \theta_2] - 8\,894\,308\,032 * \sin[2 * \theta_1] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} - 248\,346\,432 * \\
& \sin[2 * \theta_2] * (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} + 1\,007\,884\,800 * \theta_1 * \cos[\theta_1] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} - \\
& 2\,320\,081\,920 * \theta_2 * \cos[\theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} + \\
& 620\,524\,800 * \theta_2 * \cos[\theta_1] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} - \\
& 1\,414\,402\,560 * \theta_2 * \cos[\theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} - \\
& 2\,286\,331\,668 * \theta_1^2 * \sin[2 * \theta_1 + 2 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} + \\
& 42\,231\,942 * \theta_1^2 * \sin[2 * \theta_1 + 3 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} + \\
& 787\,251\,240 * \theta_1^2 * \sin[3 * \theta_1 + 2 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} - \\
& (4\,916\,185\,281 * \theta_2^2 * \sin[2 * \theta_1 + 2 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)}) / 2 + \\
& 749\,954\,430 * \theta_1^2 * \sin[3 * \theta_1 + 3 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} + \\
& 18\,924\,300 * \theta_1^2 * \sin[4 * \theta_1 + 2 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} + \\
& (75\,972\,411 * \theta_2^2 * \sin[2 * \theta_1 + 3 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)}) / 2 + \\
& (424\,015\,065 * \theta_2^2 * \sin[3 * \theta_1 + 2 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)}) / 2 + \\
& 5\,832\,000 * \theta_1^2 * \sin[3 * \theta_1 + 4 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} + \\
& 79\,477\,200 * \theta_1^2 * \sin[4 * \theta_1 + 3 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} - \\
& 6\,998\,400 * \theta_2^2 * \sin[2 * \theta_1 + 4 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} + \\
& (1\,415\,734\,065 * \theta_2^2 * \sin[3 * \theta_1 + 3 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)}) / 2 - \\
& 36\,450 * \theta_2^2 * \sin[4 * \theta_1 + 2 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} + \\
& 68\,112\,900 * \theta_1^2 * \sin[4 * \theta_1 + 4 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} + \\
& 17\,860\,500 * \theta_2^2 * \sin[3 * \theta_1 + 4 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} + \\
& 21\,811\,275 * \theta_2^2 * \sin[4 * \theta_1 + 3 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} +
\end{aligned}$$

```

62505675 * thetadot2^2 * Sin[4 * theta1 + 4 * theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
656100 * thetadot2^2 * Sin[4 * theta1 + 5 * theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
364500 * thetadot2^2 * Sin[5 * theta1 + 4 * theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
1093500 * thetadot2^2 * Sin[5 * theta1 + 5 * theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
18155520 * Sin[2 * theta1 + 2 * theta2] *
  (54 * Cos[theta2] - 90 * 5^(1/2) * Cos[theta1 + theta2 - ArcTan[2]] -
    30 * 5^(1/2) * Cos[theta1 - ArcTan[2]] + 215)^(1/2) *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
691200 * Sin[3 * theta1 + 2 * theta2] *
  (54 * Cos[theta2] - 90 * 5^(1/2) * Cos[theta1 + theta2 - ArcTan[2]] -
    30 * 5^(1/2) * Cos[theta1 - ArcTan[2]] + 215)^(1/2) *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
2073600 * Sin[3 * theta1 + 3 * theta2] *
  (54 * Cos[theta2] - 90 * 5^(1/2) * Cos[theta1 + theta2 - ArcTan[2]] -
    30 * 5^(1/2) * Cos[theta1 - ArcTan[2]] + 215)^(1/2) *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
1362424320 * thetadot1 * Sin[theta1] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
165196800 * thetadot1 * Sin[theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
963719424 * thetadot2 * Sin[theta1] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
165265920 * thetadot2 * Sin[theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
130636800 * thetadot1 * Cos[theta1 - theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
645004800 * thetadot1 * Cos[theta1 + 2 * theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
58544640 * thetadot1 * Cos[2 * theta1 + theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
52876800 * thetadot2 * Cos[theta1 - theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
21772800 * thetadot1 * Cos[theta1 + 3 * theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
3110400 * thetadot1 * Cos[3 * theta1 + theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
293932800 * thetadot2 * Cos[theta1 + 2 * theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
41990400 * thetadot2 * Cos[2 * theta1 + theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
1555200 * thetadot2 * Cos[theta1 + 3 * theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
1555200 * thetadot2 * Cos[3 * theta1 + theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
7921619520 * thetadot1^2 * Cos[theta1 + theta2] *

```

$$\begin{aligned} & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{\frac{1}{2}} + \\ & (14678749125 * \theta_2^2 * \cos[\theta_1 + \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{\frac{1}{2}}) / 2 - \\ & 136857600 * \cos[\theta_1 + \theta_2] * (54 * \cos[\theta_2] - 90 * 5^{\frac{1}{2}} * \\ & \cos[\theta_1 + \theta_2 - \arctan[2]] - 30 * 5^{\frac{1}{2}} * \cos[\theta_1 - \arctan[2]] + 215)^{\frac{1}{2}} \\ & (1/2) * (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{\frac{1}{2}} + \\ & 211880448 * \theta_1 * \sin[\theta_1 - \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{\frac{1}{2}} + \\ & 678136320 * \theta_1 * \sin[\theta_1 + 2 * \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{\frac{1}{2}} - \\ & 250145280 * \theta_1 * \sin[2 * \theta_1 + \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{\frac{1}{2}} + \\ & 105940224 * \theta_2 * \sin[\theta_1 - \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{\frac{1}{2}} + \\ & 6594048 * \theta_1 * \sin[\theta_1 + 3 * \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{\frac{1}{2}} - \\ & 6220800 * \theta_1 * \sin[3 * \theta_1 + \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{\frac{1}{2}} + \\ & 347860224 * \theta_2 * \sin[\theta_1 + 2 * \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{\frac{1}{2}} - \\ & 166821120 * \theta_2 * \sin[2 * \theta_1 + \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{\frac{1}{2}} + \\ & 3297024 * \theta_2 * \sin[\theta_1 + 3 * \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{\frac{1}{2}} - \\ & 3110400 * \theta_2 * \sin[3 * \theta_1 + \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{\frac{1}{2}} - \\ & 1101307950 * \theta_1^2 * \sin[\theta_1 + \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{\frac{1}{2}} + \\ & (1133606205 * \theta_2^2 * \sin[\theta_1 + \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{\frac{1}{2}}) / 2 + \\ & 72576000 * \sin[\theta_1 + \theta_2] * (54 * \cos[\theta_2] - 90 * 5^{\frac{1}{2}} * \\ & \cos[\theta_1 + \theta_2 - \arctan[2]] - 30 * 5^{\frac{1}{2}} * \cos[\theta_1 - \arctan[2]] + 215)^{\frac{1}{2}} \\ & (1/2) * (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{\frac{1}{2}} \\ & (1/2) - 7810560 * \theta_1 * \cos[2 * \theta_1] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{\frac{1}{2}} - \\ & 204595200 * \theta_1 * \cos[2 * \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{\frac{1}{2}} + \\ & 3006720 * \theta_2 * \cos[2 * \theta_1] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{\frac{1}{2}} - \\ & 95385600 * \theta_2 * \cos[2 * \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{\frac{1}{2}} + \\ & 6858064530 * \theta_1^2 * \cos[\theta_1] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{\frac{1}{2}} - \\ & 2500376600 * \theta_1^2 * \cos[\theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{\frac{1}{2}} + \\ & (336877965 * \theta_2^2 * \cos[\theta_1] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{\frac{1}{2}}) / 2 - \\ & (1687460175 * \theta_2^2 * \cos[\theta_2] * (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{\frac{1}{2}}) / 2 \end{aligned}$$

$$\begin{aligned}
& 30 * \sin[\theta_1] + 95)^{(1/2)} / 2 - 47001600 * \cos[\theta_1] * \\
& (54 * \cos[\theta_2] - 90 * 5^{(1/2)} * \cos[\theta_1 + \theta_2 - \arctan[2]] - \\
& 30 * 5^{(1/2)} * \cos[\theta_1 - \arctan[2]] + 215)^{(1/2)} * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} - \\
& 46080 * \cos[\theta_2] * (54 * \cos[\theta_2] - 90 * 5^{(1/2)} * \cos[\theta_1 + \theta_2 - \arctan[2]] - \\
& 30 * 5^{(1/2)} * \cos[\theta_1 - \arctan[2]] + 215)^{(1/2)} * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} - \\
& 27855360 * \theta_{\text{dot1}} * \sin[2 * \theta_1] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} + \\
& 27440640 * \theta_{\text{dot1}} * \sin[2 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} - \\
& 103680 * \theta_{\text{dot2}} * \sin[2 * \theta_1] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} - \\
& 103680 * \theta_{\text{dot2}} * \sin[2 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} - \\
& 1203768000 * \theta_{\text{dot1}}^2 * \sin[\theta_1] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} - \\
& 1922621210 * \theta_{\text{dot1}}^2 * \sin[\theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} + \\
& 1346796000 * \theta_{\text{dot2}}^2 * \sin[\theta_1] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} + \\
& 2959334190 * \theta_{\text{dot2}}^2 * \sin[\theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} + 12441600 * \\
& \sin[\theta_1] * (54 * \cos[\theta_2] - 90 * 5^{(1/2)} * \cos[\theta_1 + \theta_2 - \arctan[2]] - \\
& 30 * 5^{(1/2)} * \cos[\theta_1 - \arctan[2]] + 215)^{(1/2)} * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} + \\
& 92160 * \sin[\theta_2] * (54 * \cos[\theta_2] - 90 * 5^{(1/2)} * \cos[\theta_1 + \theta_2 - \arctan[2]] - \\
& 30 * 5^{(1/2)} * \cos[\theta_1 - \arctan[2]] + 215)^{(1/2)} * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} - \\
& 98288640 * \theta_{\text{dot1}} * \cos[2 * \theta_1 + 2 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} + \\
& 23016960 * \theta_{\text{dot1}} * \cos[2 * \theta_1 + 3 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} - \\
& 19699200 * \theta_{\text{dot1}} * \cos[3 * \theta_1 + 2 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} - \\
& 105546240 * \theta_{\text{dot2}} * \cos[2 * \theta_1 + 2 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} + \\
& 5598720 * \theta_{\text{dot1}} * \cos[2 * \theta_1 + 4 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} - \\
& 34214400 * \theta_{\text{dot1}} * \cos[3 * \theta_1 + 3 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} + \\
& 39709440 * \theta_{\text{dot2}} * \cos[2 * \theta_1 + 3 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} - \\
& 13996800 * \theta_{\text{dot2}} * \cos[3 * \theta_1 + 2 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} - \\
& 9331200 * \theta_{\text{dot1}} * \cos[3 * \theta_1 + 4 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{(1/2)} + \\
& 2799360 * \theta_{\text{dot2}} * \cos[2 * \theta_1 + 4 * \theta_2] *
\end{aligned}$$

$$\begin{aligned}
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1 + 95])^{1/2} - \\
& 29548800 * \theta_2 * \cos[3 * \theta_1 + 3 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1 + 95])^{1/2} - \\
& 4665600 * \theta_2 * \cos[3 * \theta_1 + 4 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1 + 95])^{1/2} + \\
& 807397200 * \theta_1^2 * \cos[\theta_1 - \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1 + 95])^{1/2} + \\
& 873742320 * \theta_1^2 * \cos[\theta_1 + 2 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1 + 95])^{1/2} - \\
& 3885873800 * \theta_1^2 * \cos[2 * \theta_1 + \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1 + 95])^{1/2} - \\
& 266130360 * \theta_2^2 * \cos[\theta_1 - \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1 + 95])^{1/2} - \\
& 19461870 * \theta_1^2 * \cos[\theta_1 + 3 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1 + 95])^{1/2} + \\
& 123708510 * \theta_1^2 * \cos[3 * \theta_1 + \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1 + 95])^{1/2} + \\
& (3360490965 * \theta_2^2 * \cos[\theta_1 + 2 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1 + 95])^{1/2}) / 2 - \\
& (830642175 * \theta_2^2 * \cos[2 * \theta_1 + \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1 + 95])^{1/2}) / 2 + \\
& 8275365 * \theta_2^2 * \cos[\theta_1 + 3 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1 + 95])^{1/2} + \\
& 7649235 * \theta_2^2 * \cos[3 * \theta_1 + \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1 + 95])^{1/2} + \\
& 1382400 * \cos[\theta_1 + 2 * \theta_2] * \\
& (54 * \cos[\theta_2] - 90 * 5^{1/2} * \cos[\theta_1 + \theta_2 - \arctan[2]] - \\
& 30 * 5^{1/2} * \cos[\theta_1 - \arctan[2]] + 215)^{1/2} * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1 + 95])^{1/2} + \\
& 46080 * \cos[2 * \theta_1 + \theta_2] * \\
& (54 * \cos[\theta_2] - 90 * 5^{1/2} * \cos[\theta_1 + \theta_2 - \arctan[2]] - \\
& 30 * 5^{1/2} * \cos[\theta_1 - \arctan[2]] + 215)^{1/2} * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1 + 95])^{1/2} - \\
& (1115882375 * \theta_1 * \theta_2 * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1 + 95])^{1/2}) / 2 - \\
& 527592960 * \theta_1 * \sin[2 * \theta_1 + 2 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1 + 95])^{1/2} - \\
& 83566080 * \theta_1 * \sin[2 * \theta_1 + 3 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1 + 95])^{1/2} - \\
& 39398400 * \theta_1 * \sin[3 * \theta_1 + 2 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1 + 95])^{1/2} - \\
& 499633920 * \theta_2 * \sin[2 * \theta_1 + 2 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1 + 95])^{1/2} - \\
& 68428800 * \theta_1 * \sin[3 * \theta_1 + 3 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1 + 95])^{1/2} - \\
& 311040 * \theta_2 * \sin[2 * \theta_1 + 3 * \theta_2] * \\
& (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1 + 95])^{1/2} - \\
& 27993600 * \theta_2 * \sin[3 * \theta_1 + 2 * \theta_2] *
\end{aligned}$$

```

(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
18662400 * thetadot1 * Sin[3 * theta1 + 4 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
59097600 * thetadot2 * Sin[3 * theta1 + 3 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
9331200 * thetadot2 * Sin[3 * theta1 + 4 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
2543190 * thetadot1^2 * Sin[theta1 - theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
177699240 * thetadot1^2 * Sin[theta1 + 2 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
2413901668 * thetadot1^2 * Sin[2 * theta1 + theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
194077215 * thetadot2^2 * Sin[theta1 - theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
4860000 * thetadot1^2 * Sin[theta1 + 3 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
174804810 * thetadot1^2 * Sin[3 * theta1 + theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
(2234584935 * thetadot2^2 * Sin[theta1 + 2 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2)) / 2 -
(1757087559 * thetadot2^2 * Sin[2 * theta1 + theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2)) / 2 -
58320000 * thetadot2^2 * Sin[theta1 + 3 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
4213215 * thetadot2^2 * Sin[3 * theta1 + theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
11750400 * Sin[theta1 + 2 * theta2] *
(54 * Cos[theta2] - 90 * 5^(1/2) * Cos[theta1 + theta2 - ArcTan[2]] -
30 * 5^(1/2) * Cos[theta1 - ArcTan[2]] + 215)^(1/2) *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
92160 * Sin[2 * theta1 + theta2] *
(54 * Cos[theta2] - 90 * 5^(1/2) * Cos[theta1 + theta2 - ArcTan[2]] -
30 * 5^(1/2) * Cos[theta1 - ArcTan[2]] + 215)^(1/2) *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
725114700 * thetadot1^2 * Cos[2 * theta1] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
157041450 * thetadot1^2 * Cos[2 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
70290450 * thetadot2^2 * Cos[2 * theta1] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
69134175 * thetadot2^2 * Cos[2 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
601523658 * thetadot1^2 * Sin[2 * theta1] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
63421758 * thetadot1^2 * Sin[2 * theta2] *
(27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
25801713 * thetadot2^2 * Sin[2 * theta1] *

```


$$\begin{aligned} & (54 * \cos[\theta_2] - 90 * 5^{1/2} * \cos[\theta_1 + \theta_2 - \arctan[2]] - 30 * 5^{1/2} * \cos[\theta_1 - \arctan[2]] + 215)^{1/2} * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{1/2} + \\ & 1382400 * \cos[3 * \theta_1 + 2 * \theta_2] * \\ & (54 * \cos[\theta_2] - 90 * 5^{1/2} * \cos[\theta_1 + \theta_2 - \arctan[2]] - 30 * 5^{1/2} * \cos[\theta_1 - \arctan[2]] + 215)^{1/2} * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{1/2} + \\ & 4147200 * \cos[3 * \theta_1 + 3 * \theta_2] * \\ & (54 * \cos[\theta_2] - 90 * 5^{1/2} * \cos[\theta_1 + \theta_2 - \arctan[2]] - 30 * 5^{1/2} * \cos[\theta_1 - \arctan[2]] + 215)^{1/2} * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{1/2} - \\ & 9388633350 * \theta_{\dot{1}} * \theta_{\dot{2}} * \cos[2 * \theta_1 + 2 * \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{1/2} - \\ & (1194217425 * \theta_{\dot{1}} * \theta_{\dot{2}} * \cos[2 * \theta_1 + 3 * \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{1/2}) / 2 + \\ & (955295775 * \theta_{\dot{1}} * \theta_{\dot{2}} * \cos[3 * \theta_1 + 2 * \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{1/2}) / 2 + \\ & (175253355 * \theta_{\dot{1}} * \theta_{\dot{2}} * \cos[3 * \theta_1 + 3 * \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{1/2}) / 2 + \\ & 16193925 * \theta_{\dot{1}} * \theta_{\dot{2}} * \cos[4 * \theta_1 + 2 * \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{1/2} - \\ & (233312805 * \theta_{\dot{1}} * \theta_{\dot{2}} * \cos[3 * \theta_1 + 4 * \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{1/2}) / 2 + \\ & (226781775 * \theta_{\dot{1}} * \theta_{\dot{2}} * \cos[4 * \theta_1 + 3 * \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{1/2}) / 2 + \\ & (388854675 * \theta_{\dot{1}} * \theta_{\dot{2}} * \cos[4 * \theta_1 + 4 * \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{1/2}) / 2 - \\ & (13846223457 * \theta_{\dot{1}} * \theta_{\dot{2}} * \sin[2 * \theta_1 + 2 * \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{1/2}) / 2 - \\ & (66855537 * \theta_{\dot{1}} * \theta_{\dot{2}} * \sin[2 * \theta_1 + 3 * \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{1/2}) / 2 + \\ & (2027734785 * \theta_{\dot{1}} * \theta_{\dot{2}} * \sin[3 * \theta_1 + 2 * \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{1/2}) / 2 - \\ & 13996800 * \theta_{\dot{1}} * \theta_{\dot{2}} * \sin[2 * \theta_1 + 4 * \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{1/2} + \\ & (3194643645 * \theta_{\dot{1}} * \theta_{\dot{2}} * \sin[3 * \theta_1 + 3 * \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{1/2}) / 2 + \\ & 18887850 * \theta_{\dot{1}} * \theta_{\dot{2}} * \sin[4 * \theta_1 + 2 * \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{1/2} + \\ & 46656000 * \theta_{\dot{1}} * \theta_{\dot{2}} * \sin[3 * \theta_1 + 4 * \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{1/2} + \\ & 121481775 * \theta_{\dot{1}} * \theta_{\dot{2}} * \sin[4 * \theta_1 + 3 * \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{1/2} + \\ & 194454675 * \theta_{\dot{1}} * \theta_{\dot{2}} * \sin[4 * \theta_1 + 4 * \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{1/2} + \\ & (43479934005 * \theta_{\dot{1}} * \theta_{\dot{2}} * \cos[\theta_1 + \theta_2] * \\ & (27 * \cos[\theta_2] - 90 * \sin[\theta_1 + \theta_2] - 30 * \sin[\theta_1] + 95)^{1/2}) / 2 - \end{aligned}$$

```

(7 775 853 975 * thetadot1 * thetadot2 * Sin[theta1 + theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2)) / 2 +
(13 954 482 945 * thetadot1 * thetadot2 * Cos[theta1] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2)) / 2 -
(6 636 664 975 * thetadot1 * thetadot2 * Cos[theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2)) / 2 +
118 944 000 * thetadot1 * thetadot2 * Sin[theta1] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
4018 387 780 * thetadot1 * thetadot2 * Sin[theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
276 416 280 * thetadot1 * thetadot2 * Cos[theta1 - theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
(8 345 372 805 * thetadot1 * thetadot2 * Cos[theta1 + 2 * theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2)) / 2 -
(10 367 476 975 * thetadot1 * thetadot2 * Cos[2 * theta1 + theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2)) / 2 -
2 943 945 * thetadot1 * thetadot2 * Cos[theta1 + 3 * theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
139 133 745 * thetadot1 * thetadot2 * Cos[3 * theta1 + theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
328 812 405 * thetadot1 * thetadot2 * Sin[theta1 - theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
(3 441 673 215 * thetadot1 * thetadot2 * Sin[theta1 + 2 * theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2)) / 2 -
(7 778 480 327 * thetadot1 * thetadot2 * Sin[2 * theta1 + theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2)) / 2 -
59 292 000 * thetadot1 * thetadot2 * Sin[theta1 + 3 * theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
166 703 595 * thetadot1 * thetadot2 * Sin[3 * theta1 + theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
654 565 050 * thetadot1 * thetadot2 * Cos[2 * theta1] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
88 166 475 * thetadot1 * thetadot2 * Cos[2 * theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) -
619 808 571 * thetadot1 * thetadot2 * Sin[2 * theta1] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) +
448 104 879 * thetadot1 * thetadot2 * Sin[2 * theta2] *
  (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2)) /
(12 * (27 * Cos[theta2] - 90 * Sin[theta1 + theta2] - 30 * Sin[theta1] + 95)^(1/2) *
  (1 458 000 * Cos[theta1 + 3 * theta2] - 79 777 770 * Cos[theta1 + 2 * theta2] -
    499 064 878 * Cos[2 * theta1 + theta2] - 49 698 135 * Cos[theta1 - theta2] +
    1 692 135 * Cos[3 * theta1 + theta2] - 154 662 960 * Sin[theta1 - theta2] -
    322 174 440 * Sin[theta1 + 2 * theta2] + 386 207 350 * Sin[2 * theta1 + theta2] -
    4 617 405 * Sin[theta1 + 3 * theta2] + 4 722 915 * Sin[3 * theta1 + theta2] -
    108 706 743 * Cos[2 * theta1] + 43 114 293 * Cos[2 * theta2] + 92 014 650 * Sin[2 * theta1] +
    2 750 625 * Sin[2 * theta2] - 583 752 578 * Cos[2 * theta1 + 2 * theta2] -
    46 048 743 * Cos[2 * theta1 + 3 * theta2] + 21 041 040 * Cos[3 * theta1 + 2 * theta2] -
    1 166 400 * Cos[2 * theta1 + 4 * theta2] + 42 115 905 * Cos[3 * theta1 + 3 * theta2] +
    3 154 050 * Cos[4 * theta1 + 2 * theta2] + 2 916 000 * Cos[3 * theta1 + 4 * theta2] +

```

```

13 246 200 * Cos[4 * theta1 + 3 * theta2] + 11 352 150 * Cos[4 * theta1 + 4 * theta2] +
334 663 950 * Sin[2 * theta1 + 2 * theta2] + 1 891 350 * Sin[2 * theta1 + 3 * theta2] +
55 721 250 * Sin[3 * theta1 + 2 * theta2] + 100 216 980 * Sin[3 * theta1 + 3 * theta2] -
2 702 025 * Sin[4 * theta1 + 2 * theta2] + 7 779 645 * Sin[3 * theta1 + 4 * theta2] -
11 348 100 * Sin[4 * theta1 + 3 * theta2] - 9 726 075 * Sin[4 * theta1 + 4 * theta2] -
1 104 787 905 * Cos[theta1 + theta2] - 2 978 386 140 * Sin[theta1 + theta2] -
593 067 270 * Cos[theta1] + 1 409 792 221 * Cos[theta2] -
1 707 400 845 * Sin[theta1] - 43 634 900 * Sin[theta2] + 2 673 262 828) ) ]

```

Out[]= \$Aborted