NX MOM Architecture

001 - Introduction

Purpose of a CAM system

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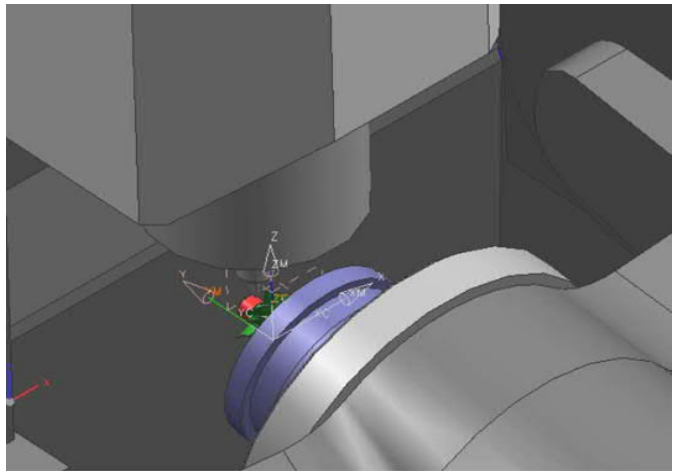
Use of software to control machine tools and related ones in the manufacturing of workpieces. The system define and generate sequences of tool positions (**Toolpath**) that can be used to guide a NC machine in order to produce the desired shape of a part.



NX CAM Tool Path

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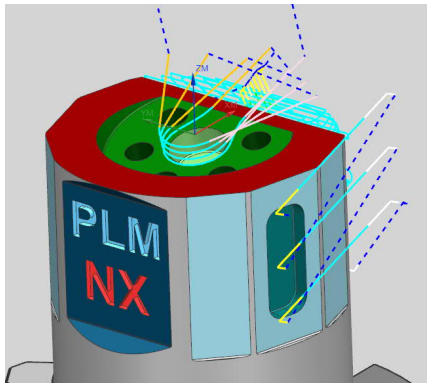
- Tool path contains data that represents the sequence of tool movements and other machine control instructions
- Tool path can be output in different formats in NX CAM




```
TOOL PATH/FACE_TOP,TOOL,UGT0202_001
TLDATA/MILL,40.0000,0.8000,34.6900,0.0000,0.0000
MSYS/0.0000,0.0000,100.0000,1.0000000,0.0000000,0.
$$ centerline data
PAINT/PATH
PAINT/SPEED,10
LOAD/TOOL,1,ADJUST,1
PAINT/COLOR,186
RAPID
GOTO/-79.5990,42.0000,50.0000,0.0000000,0.0000000,
PAINT/COLOR,211
RAPID
GOTO/-79.5990,42.0000,3.0000
PAINT/COLOR,6
FEDRAT/MMPM,1203.1000
GOTO/-79.5990,42.0000,0.0000
GOTO/-56.0000,42.0000,0.0000
PAINT/COLOR,31
GOTO/56.0000,42.0000,0.0000
```

Cutter Location Source Files (CLSF)

```
N110 SUPA X=_X_HOME Y=_Y_HOME A=_A_HOME C=_C_HOME D1
N120 T="UGT0202_001" M6
N130 MSG("MILL_FINISH")
N140 TRAFOOF
N150 SUPA Z=_Z_HOME D0
N160 SUPA X=_X_HOME Y=_Y_HOME A=_A_HOME C=_C_HOME D1
N170 CYCLE832(_camtolerance,1,1)
N180 COMPOF
N190 G54
N200 TRANS X0. Y0. Z0.
N210 G0 A0. C0.
N220 AROT Z0.0
N230 AROT Y0.0
N240 AROT X0.0
N250 TRAORI
N260 G17 X-79.599 Y42. Z50. S2228 D1 M3
N270 Z3.
N280 G1 G90 Z0. F1203.
N290 X-56.
N300 X56.
N310 X79.599
```

Post Processor (controller/ machine specific NC code)

```
switch (camPathToolpathEventType)
{
    case CamPathToolpathEventType.Motion:
        path.IsToolpathEventAMotion(j, out camPathMotionType,
        //theSession.ListingWindow.WriteLine(j.ToString() + "

        switch (camPathMotionType)
        {
            case CamPathMotionType.From:
            case CamPathMotionType.Rapid:
            case CamPathMotionType.Approach:
            case CamPathMotionType.Engage:
            case CamPathMotionType.FirstCut:
            case CamPathMotionType.Cut:
            case CamPathMotionType.SideCut:
            case CamPathMotionType.Stepover:
            case CamPathMotionType.InternalLift:
            case CamPathMotionType.Retract:
            case CamPathMotionType.Traversal:
            case CamPathMotionType.Gohome:
```

Processed with NXOpen API

Data Model -OM

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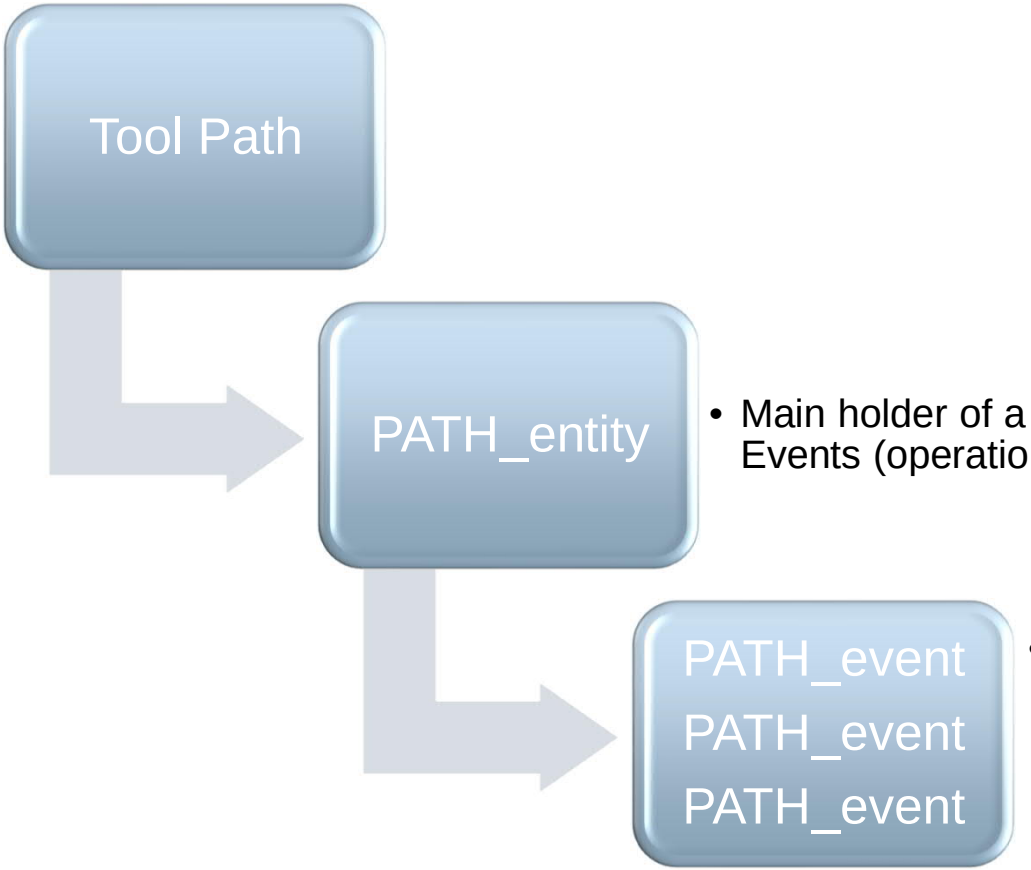
- The data model of CAM utilizes the Object Manager (OM) architecture of NX
- OM is an object oriented data structure
- It is written in C but has many concepts of Object Oriented Languages like C++
- OM has classes, creator, methods, method overriding
- The specialty of the OM is that it provides a way to establish relationships between different objects

Tool Path Data Structure



- Main holder of a list of Path Events (operation)

- Super class of all other types of tool path events (i.e. motion, machine control)

MOM (Manufacturing Output Manager)

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Mechanism to access UG data and generate formatted output. UG data includes

- Part information
- CAM data
- **Tool Path**

CAM applications based on MOM

- **UG/Post**
- UG/Shop Docs
- UG Library Mechanism

MOM contain a Tcl interface to extend/ access the data

- **< NX12.0.1 MP1 Tcl8.4**
- **> NX12.0.1 MP1 Tcl8.6**

What is NX CAM/Post ?

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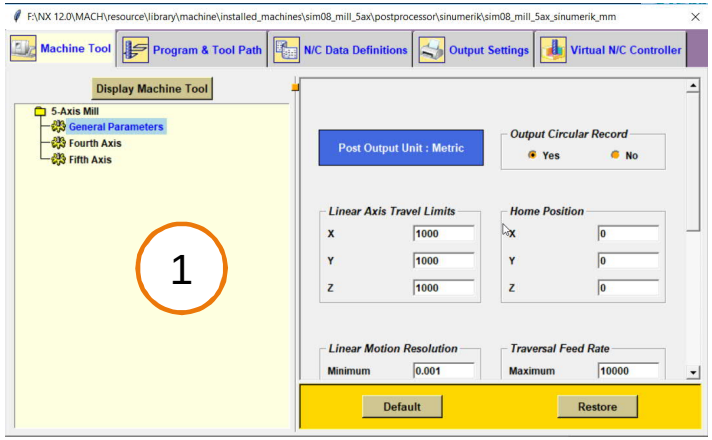
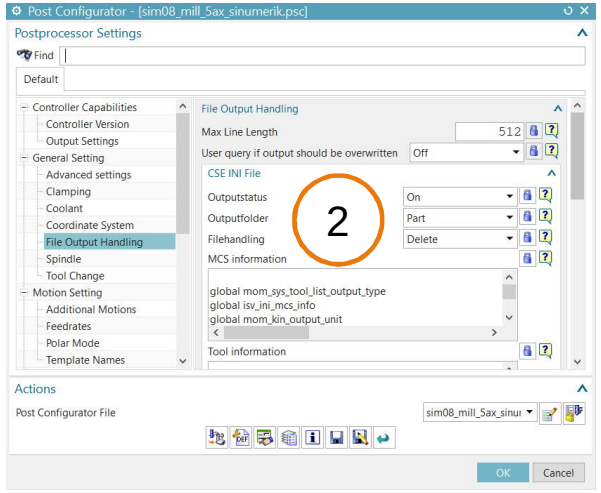
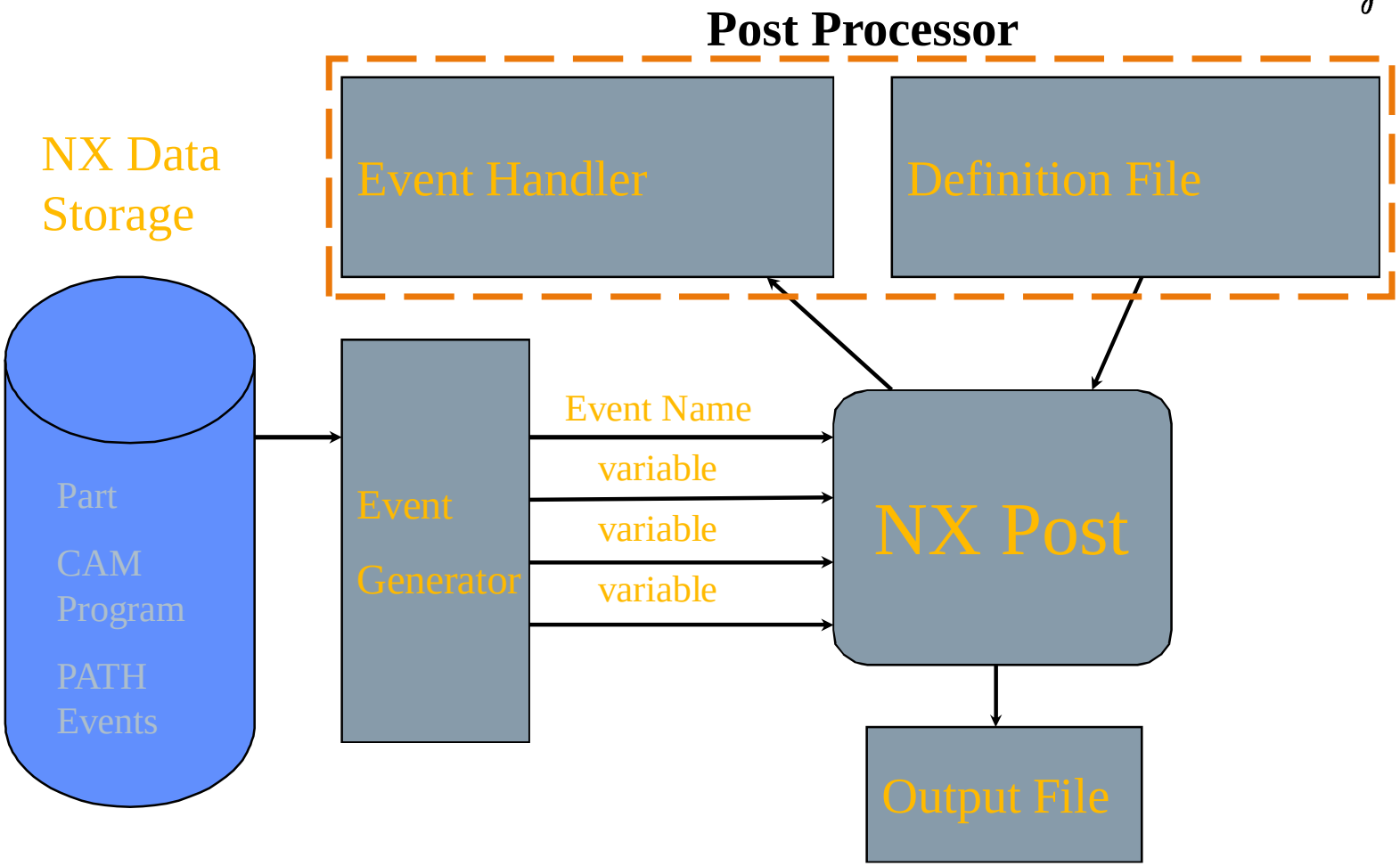
- Application based on MOM architecture
- Innovative approach (unique in CAM industry)
- Completely customizable & highly extensible
- Full capability postprocessor
- Complementary Modules
  - UG/Post Execute
  - UG/Post Builder 1
  - **NX/Post Configurator** 2

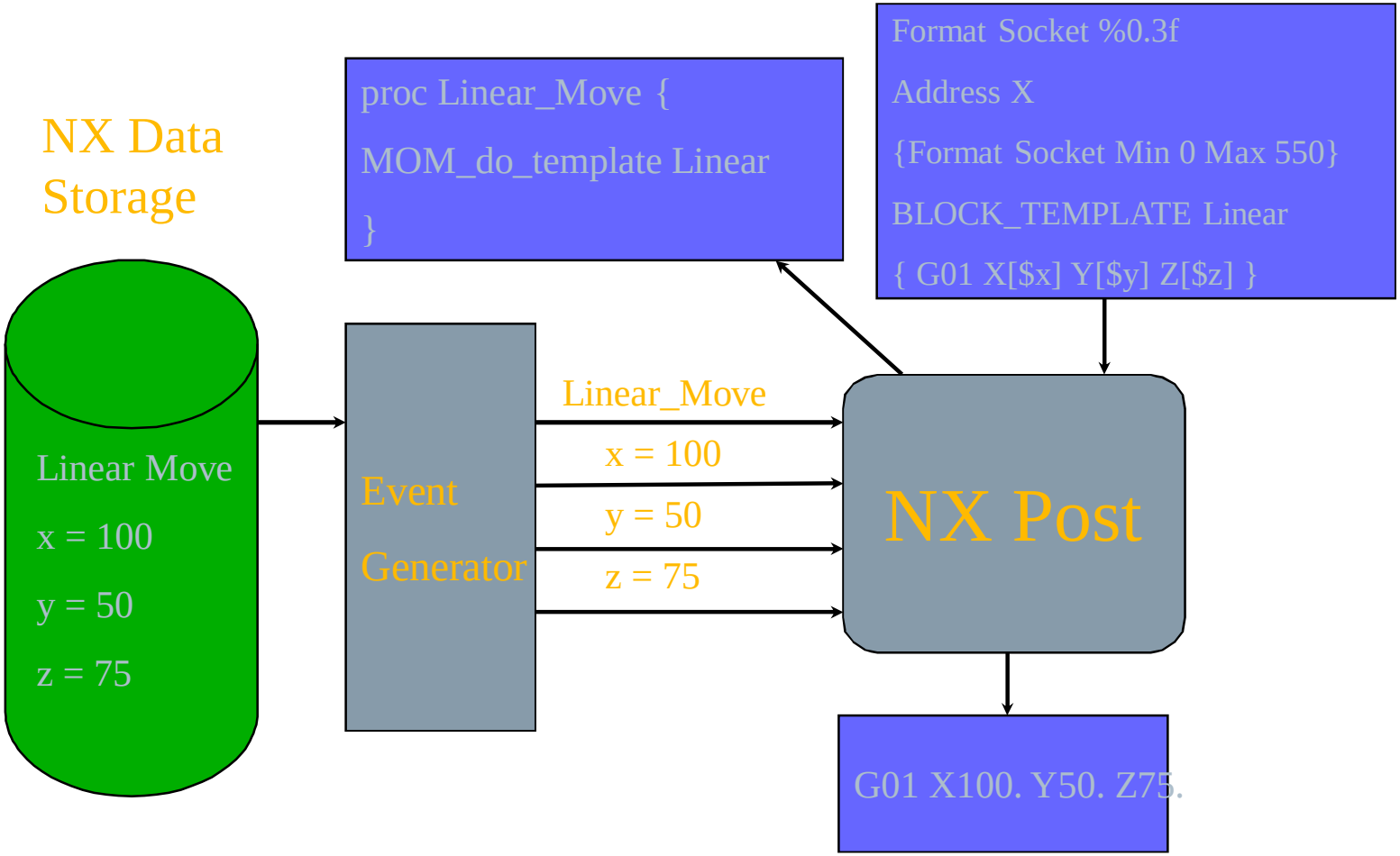




Post Data Flow



Post Data Flow



The MOM object

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```
mom_obj = NXPost( definition_file, event_handler_file, output_file )
```

- Creates a new Tcl interpreter in background and execute the Tcl code
- Creates a Definition parser for definition elements (Words, Formats, Block Templates)
- Creates a new output file with content from the Tcl coding

The created MOM object contains predefined Tcl commands, e.g.:

- MOM_output_literal ….
- MOM_output_to_listing_device ….

And variables, e.g.:

- mom_tool_name
- mom_pos(0)

Based on the used Tcl version in NX this interpreter is extended with multiple extensions, called MOM commands. These commands are not available in a native Tcl interpreter. It‘s also possible to extend the Tcl interpreter in NX with additional commands with C++.

Exercise 1 – MOM Tcl

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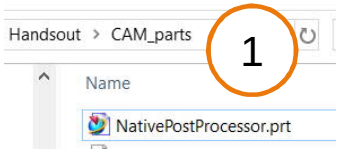
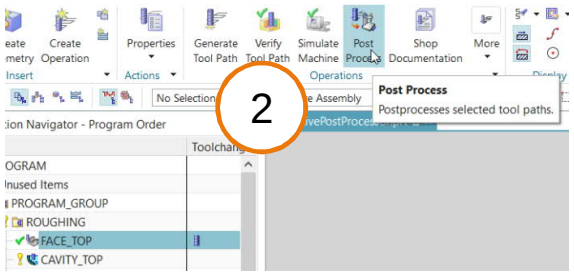
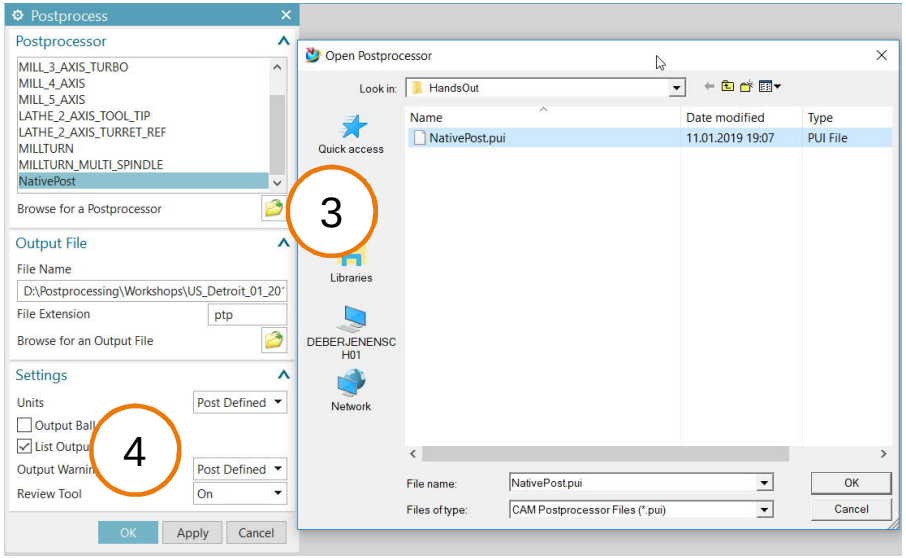


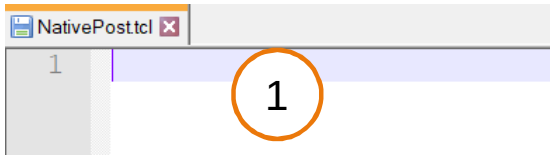


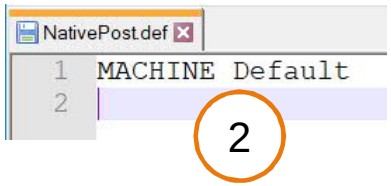


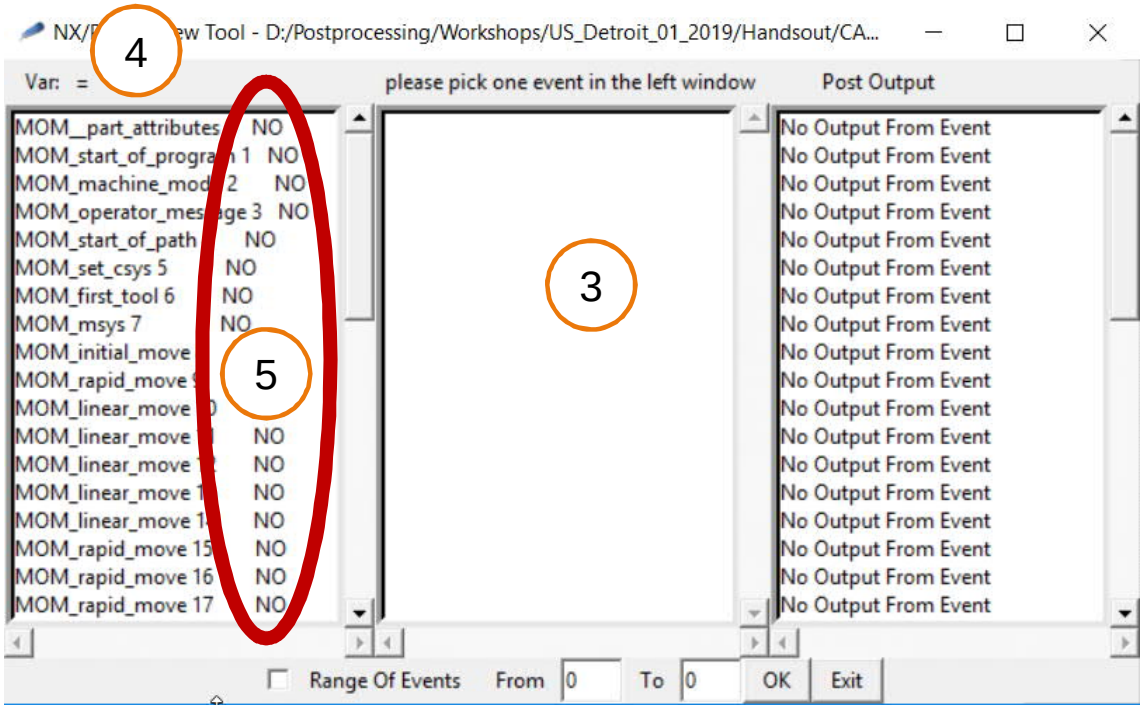
1. Open **NativePostprocessor.prt** from \CAM_parts
2. Select FACE_TOP operation and click Post Process
3. Browse for post processor and select the **NativePost.pui** from \001_Snippet\HandsOut\
4. Switch on the Review Tool

The .pui-file was initally created for Post Builder and contains the Post Builder information. The dialog **not expect any information** in that file, in background it search for the filename with .tcl and .def extension and load the files.

Exercise 1 – MOM Tcl







1. Tcl-file is empty
2. Def-file contains mininum the MACHINE default line
3. Run the post processor and Review Tool will open
4. Generated MOM Events from Tool Path
5. **NO** indicates that **no Tcl eventhandler** exists for this MOM Event

Exercise 1 – MOM Tcl

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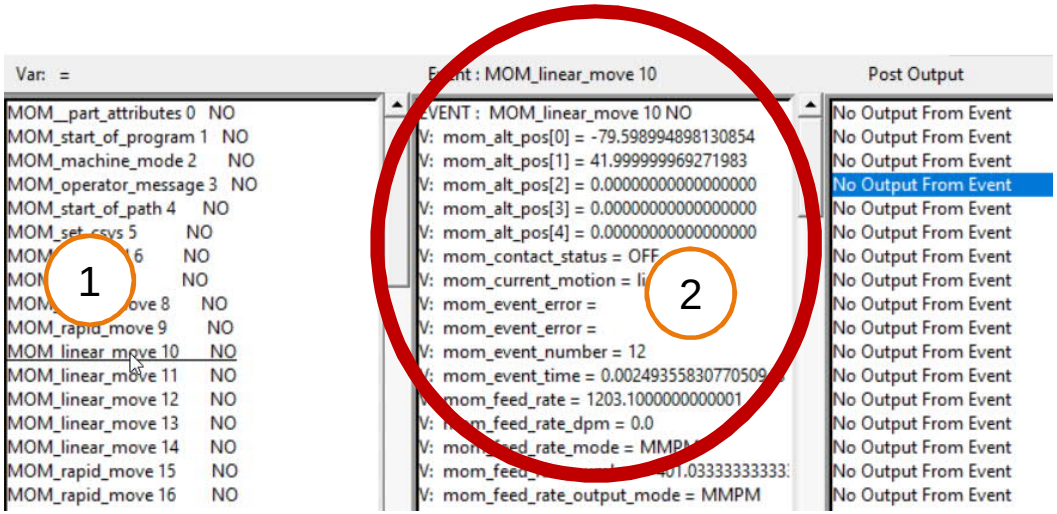
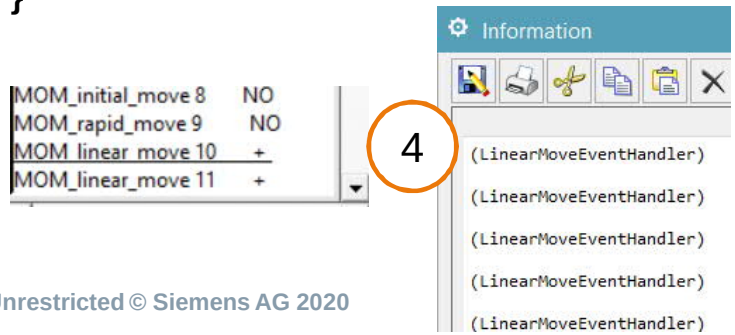



```
proc MOM_linear_move {} {
MOM_output_literal "(LinearMoveEventHandler)"
}
```

3



1. Select a MOM event, e.g. MOM_linear_move
2. The available mom variables will be listed which are created from the Tool Path
3. Extend the NativePost.tcl with an Eventhandler for the MOM_linear_move
4. Run post process again with Review Tool, notice that the Event indicates the Tcl eventhandler and in listing window appears the output

Not all MOM Events are shown in the Review Tool. Most of MOM events can be found in the help collection: https://docs.plm.automation.siemens.com/tdoc/nx/12.0.2/nx_help#uid:xid1128418:index_xid917284:id1319759:xid1398609

Exercise 1 – MOM Tcl

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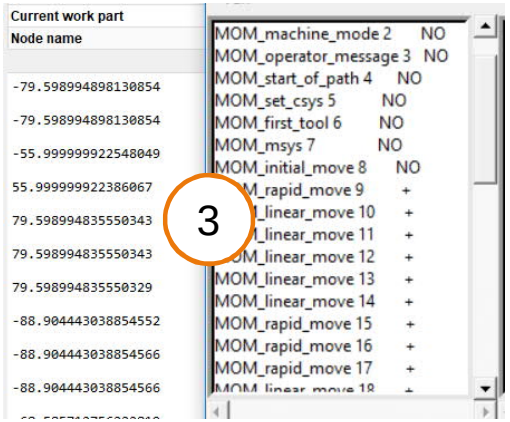
1

```
proc MOM_linear_move {} {
MOM_output_literal "$::mom_pos(0)"
}

proc MOM_rapid_move {} {
MOM_output_literal "$::mom_pos(0)"
}
```

2



3

4

```
proc MOM_before_motion {} {
MOM_output_text "----->Before Motion"
}
```

1. Add MOM_rapid_move eventhandler in NativePost.tcl
2. Output the mom_pos(0) value for MOM_linear_move and MOM_rapid_move
3. Run post process to validate the commands
4. Add MOM_before_motion eventhandler

Output directly the values of variables happens unformatted. With native Tcl command „format“ this can be changed or using integrated functionality of MOM core.

Some MOM Events are not visible in the Review Tool, e.g. the MOM_before_motion.

Exercise 1 – MOM Def

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```
MACHINE Default
FORMATTING
{
  FORMAT AbsCoord "&__5.3_"
  ADDRESS X
  {
      FORMAT      AbsCoord
      FORCE       off
      MAX         99999.999 Abort
      MIN         -99999.999 Abort
      LEADER      "X"
      TRAILER     ""
  }
  BLOCK_TEMPLATE linear_move
  {
     X[$mom_pos(0)]
  }
}
```

1 2 3

1. Open NativePost.def and add Format Abscoord
2. Add Address X
3. Add Blocktemplate linear_move

The .def file contains information for:

- Formats
- Addresses
- Block Templates
- Sequence

It‘s based on a LexYacc parser and can be extended easily. A .def-file is sourced during the selection of the post processor. A .def-file must contain „**MACHINE xxx**“ and all definitions must be between the **FORMATTING{xxx}**

Exercise 1 – MOM Def/ Tcl

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```
FORMAT String "%s"

ADDRESS Text
{
    FORMAT    String
    FORCE     always
    LEADER    ""
}
```

1

```
BLOCK_TEMPLATE linear_move
{
    Text[G1]
    X[$mom_pos(0)]
}
BLOCK_TEMPLATE rapid_move
{
    Text[G0]
    X[$mom_pos(0)]
}
```

3 2 3

```
proc MOM_linear_move {} {
#MOM_output_literal "$::mom_pos(0)"
MOM_do_template linear_move
}
proc MOM_rapid_move {} {
#MOM_output_literal "$::mom_pos(0)"
MOM_do_template rapid_move
}
```

4

5

```
----->Before Motion
----->Before Motion
G0 X-79.599

----->Before Motion
G1

----->Before Motion
G1 X-56.

----->Before Motion
G1 X56.
```

1. Add Address **Text** and Format **String**
2. Add a Block Template for rapid_move
3. Extend linear and rapid move with a Text element, e.g. G0 and G1
4. Call the Block Template in NativePost.tcl for linear and rapid moves
5. Run post process to validate result, values are formatted due the definitions in the .def file

NX Tcl commands 1/2

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MOM_output_literal „text“

- Output text automtically with sequence number, can be used for information to the user or for debugging purpose

MOM_output_text „text“

- Output text without sequence number

MOM_do_template [Block template name]

- Output a defined Block Template from the definition file

MOM_set_seq_on

- Switch on the sequence numbers

MOM_set_seq_off

- Switch off the sequence numbers

Online Documentation:

https://docs.plm.automation.siemens.com/tdoc/nx/12.0.2/nx_help#uid:xid1128418:index_xid917284:id1319759:xid916798

NX Tcl commands 2/2

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MOM_enable_address [Address1] [Address2]

- Enable an address from the definition file

MOM_disable_address [Address1] [Address2]

- Disable an address from the definition file

MOM_suppress <Always|Once|Off> [Address1] [Address2]

- Suppress the output of an adress once or always in next Block Template

MOM_force <Always|Once|Off> [Address1] [Address2]

- Force the output of an adress once or always in next Block Template

MOM_output_to_listing_device [Text]

- Very useful for debugging purposes, will generate an output in the beginning of the listing window, no output in the output file

Online Documentation:

https://docs.plm.automation.siemens.com/tdoc/nx/12.0.2/nx_help#uid:xid1128418:index_xid917284:id1319759:xid916798

Useful Tcl snippet

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```
proc name {optional arg} {
#code
}
```

- Procedure body, arguments are optional. To call a procedure from use the name in calling proc, e.g. name

```
if {$var == $value} {
#do something
}
```

- If commands can be used for easy matching of conditions (==,!=,<,>), take care of comparing values with expr command

```
switch $var {
„Value1“ {#do something}
„Value2“ {#do something}
default {#do default}
}
```

- Switch commands allows multiple conditions matching, e.g. ask the mom_motion_type

```
foreach value {#list} {
   # do something
}
```

- Cycle through a list of elements, very useful e.g. to collect data during a post process run and output it at the end

Online Documentation:

https://wiki.tcl-lang.org/

For native Tcl programming and commands the Tcl Wiki is a good starting point. The site includes tutorials and descriptions of all available Tcl commands.

Tcl basics

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```
set myvar „text“
set myvar2 $myvar
```

- A local or global variable can be set with a value or the value of a different variable
- To read the value of a variable use the $

```
global myvar
MOM_output_literal „$myvar“
Is equal to
MOM_output_literal „$::myvar“
```

- The started Tcl interpreter has a global namespace
- It‘s possible to have multiple namespace (additional extensions)
- in NX Post normally one global namespace is used
- To get a variable from a different procedure this variable must be declared as global
- The :: is a shorten form of writing

```
lappend ::mytoollist $::mom_tool_name
…
foreach toolname $::mytoollist {
MOM_output_literal "--->$toolname"
}
```

- Append the tool name to a list, e.g. in MOM_end_of_program output all elements of the list

Error handling:

For debugging and avoid crashes of the Tcl interpreter the **<u>info exists</u>** can be used to avoid such situations e.g.:

```
If {[info exists ::mytoollist]} {
#do something
}
```

Exercise 2 – MOM Tcl Toolname list

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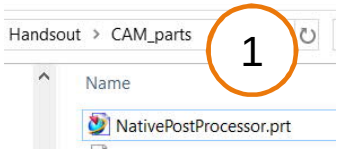

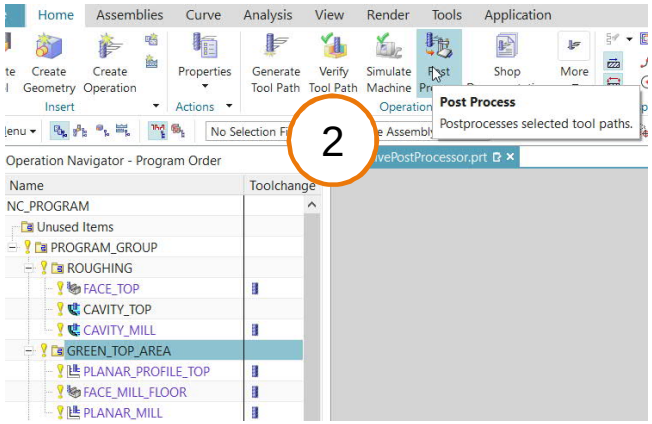

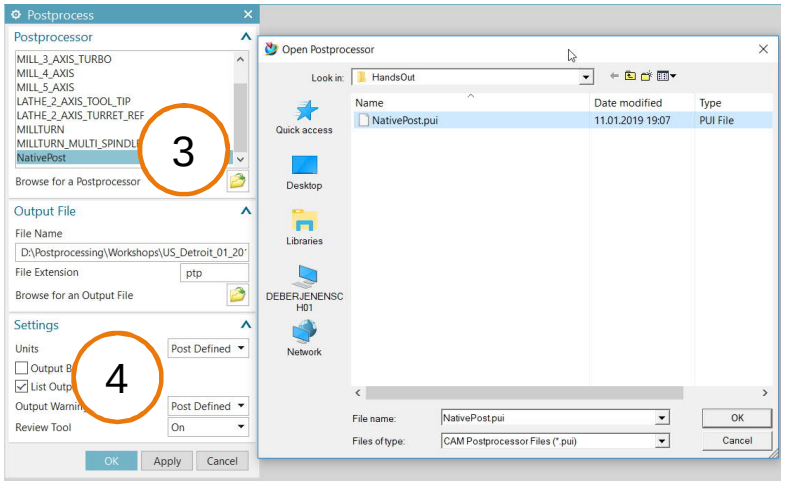

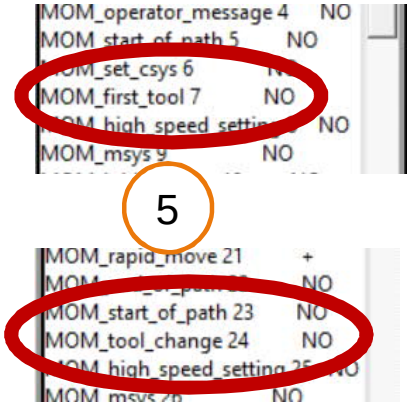

1. Open **NativePostprocessor.prt** from \CAM_parts
2. Select GREEN_TOP_AREA program group and click Post Process
3. Browse for post processor and select the **NativePost.pui** from \001_Snippet\HandsOut\
4. Switch on the Review Tool
5. Run the post process and notice the MOM tool change events

In MOM two events are generated for the Toolchange. The first toolchange in a postprocessor run is named **MOM_first_tool**, for additional tool changes the **MOM_tool_change** event is generated.

Exercise 2 – MOM Tcl Toolname list

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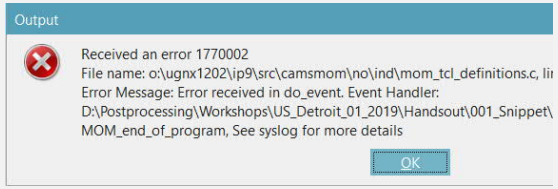
```
proc MOM_first_tool {} {
lappend ::mytoollist $::mom_tool_name
}

proc MOM_tool_change {} {
lappend ::mytoollist $::mom_tool_name
}

proc MOM_end_of_program {} {
if {[info exists ::mytoollist]} {
        foreach toolname $::mytoollist {
                MOM_output_literal "--->$toolname"
        }
}
}
```

2 3 2 3 4 5 6

```
--->UGT0201_088
--->UGT0201_015
--->UGT0201_092
```

1. Open **NativePost.tcl** in editor
2. Add MOM_first_tool and MOM_tool_change events
3. Append the provided NX Post value for the tool name to a list
4. Add MOM_end_of_program event
5. Cycle thru the list and output all the tool names
6. Run post process and validate result

Using of „info exists“ avoid crashes if the tool list variable not exists.



Final exercise (optional)

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- Add the sequence number from MOM
- Create the sequence command
- Create a sequence address
- Create a Block template for sequence numbering

```
N278 G1 X-2.068
----->Before Motion
N280 G1 X-3.113
----->Before Motion
N282 G1 X-3.794
----->Before Motion
N284 G1 X-4.
----->Before Motion
----->Before Motion
N286 G1 X2.
----->Before Motion
N288 G1
----->Before Motion
N290 G1
N292 ->UGT0201_088
N294 ->UGT0201_015
N296 ->UGT0201_092
```

Hint:

- ➢Take a look into existing Post Builder or Post Configurator post processor to find the correct implementation
- ➢The sequence is a standard implementation in MOM, it‘s not needed to add any Tcl

Q&A

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Thomas Jenensch
Product Portfolio Lead NX CAM Infrastructure
Manufacturing Engineering Software

Nonnendammallee 101 5. OG, Bauteil C
D-13629 Berlin, Germany
Tel. :+49 (30) 46777 535

thomas.jenensch@siemens.com
www.siemens.com/plm

Siemens Manufacturing Forum
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