



Standard program

Special program (on request)

with Hall sensors		496660	496661	488607			
Motor Data							
Values at nominal voltage							
1 Nominal voltage	V	18	36	48			
2 No load speed	rpm	4540	4550	5000			
3 No load current	mA	352	176	150			
4 Nominal speed	rpm	3920	3950	4390			
5 Nominal torque (max. continuous torque)	mNm	207	207	222			
6 Nominal current (max. continuous current)	Α	5.46	2.72	2.39			
7 Stall torque ¹	mNm	2860	3160	4330			
8 Stall current	Α	76.3	42.2	47.5			
9 Max. efficiency	%	87	87	89			
Characteristics							
10 Terminal resistance phase to phase	Ω	0.236	0.853	1.01			
11 Terminal inductance phase to phase	mH	0.169	0.675	0.995			
12 Torque constant	mNm/A	37.5	74.9	91			
13 Speed constant	rpm/V	255	127	105			
14 Speed/torque gradient rp	m/mNm	1.6	1.45	1.16			
15 Mechanical time constant	ms	0.739	0.669	0.537			
16 Rotor inertia	gcm ²	44	44	44			

Specifications Thermal data Thermal resistance housing-ambient

7.17 K/W 1.35 K/W 20.7 s 1400 s 0...+100°C 18 Thermal resistance winding-housing 19 Thermal time constant winding 20 Thermal time constant motor 21 Ambient temperature 22 Max. winding temperature +155°C

Mechanical data (preloaded ball bearings)

23 Max. speed		8000 rpm
24 Axial play at axial load	< 9.0 N	0 mm
	> 9.0 N	0.15 mm
25 Radial play		preloaded
26 Max. axial load (dynami	7 N	
27 Max. force for press fits	87 N	
(static, shaft supported)	3000 N
28 Max. radial load, 5 mm	29.9 N	

Operating Range

Planetary Gearhead

Ø42 mm

3-15 Nm

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390 g

n [rpm] 9000 100 W 8000 7000 6000 4000 3000 2000 1000 0 0 0.18 M [mNm]

Continuous operation

Comments

In observation of above listed thermal resistance (lines 17 and 18) the maximum permissible winding temperature will be reached during continuous operation at 25°C ambient. = Thermal limit.

Short term operation

The motor may be briefly overloaded (recurring).

Assigned power rating

Other specifications

- 29 Number of pole pairs 30 Number of phases 31 Weight of motor

Values listed in the table are nominal.

Connection motor (Cable AWG 20) red black Motor winding 1 Motor winding 2 white Motor winding 3 N.C. Connector Article number
Molex 39-01-2040
Connection sensor (Cable AWG 26)
yellow Hall sensor 1 Pi
brown Hall sensor 2 Pi Hall sensor 3 grey blue GND V_{Hall} 4.5...24 VDC N.C.

Pin 6 Connector Article number
Molex 430-25-0600
Wiring diagram for Hall sensors see p. 59

¹Calculation does not include saturation effect (p. 71/178)

maxon Modular System

Recommended Electronics: Page **42** Notes ESCON 36/3 EC 501 ESCON Mod. 50/4 EC-S 501 ESCON Module 50/5 501 ESCON Mod. 50/8 (HE) 502 ESCON 50/5 503 ESCON 70/10 503 DEC Module 50/5 505 EPOS4 Mod./Comp. 50/5 510 EPOS4 Mod./Comp. 50/8 513 EPOS4 50/5 515 EPOS4 70/15 515

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Encoder 16 EASY Absolute/XT

Encoder AEDL 5810 1024-5000 CPT, 3 channels Page 485

Encoder HEDL 5540 500 CPT, 3 channels Page 492

green