



## 19CSE337 Social Networking Security

Lecture 12



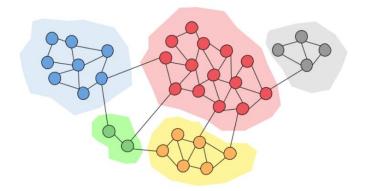
#### **Topics to Discuss**

- Community
- Clustering
- Girvan-Newman Algorithm



#### Community

 A community, with respect to graphs, can be defined as a subset of nodes that are densely connected to each other and loosely connected to the nodes in the other communities in the same graph.



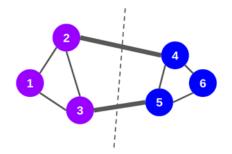


#### Community

- Think about social media platforms such as Facebook, Instagram, or Twitter, where we try to connect with other people.
- Eventually, after a while, we end up being connected with people belonging to different social circles.
- These social circles can be a group of relatives, school mates, colleagues, etc.
- These social circles are nothing but communities!

### Community Detection

- Community detection in a social network is identifying sets of nodes in such a way that the connections of nodes within a set are more than their connection to other network nodes.
- Community detection techniques are useful for social media algorithms to discover people with common interests.

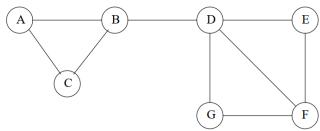


#### Clustering

- Often clustering and community detection are used interchangeably.
- Both focus on grouping of nodes.
- In short, clustering group nodes based on its features whereas community detection group nodes based on its connectivity.
- Community not partition nodes into sets rather overlap.

### Clustering Algorithms

- There are many popular clustering algorithms like hierarchical clustering, K-means clustering etc. These algorithms can be used to detect communities.
- In the given graph, we can identify two communities {A,B,C} and {D,E,F,G}.
   Also, two sub communities {D,E,F} and {D,F,G} of {D,E,F,G}.
- Unfortunately, a pure clustering algorithm sometimes fails to detect overlapping communities, sometimes fails to place nodes in appropriate groups.
- Say for example in the given graph, node D may be placed as part of community I or II.



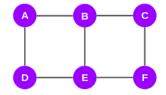


#### Clustering

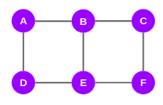
- Since there are problems with standard clustering algorithms, we need more specialised algorithms.
- One such algorithm is Girvan-Newman algorithm.
- It works based on finding the edges that are least likely to be inside a community.

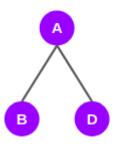
- The Girvan-Newman algorithm finds the communities in a graph by iteratively removing the edges of the graph, based on the edge betweenness centrality value.
- The edge with the highest edge betweenness is removed first.
- The edge betweenness centrality (EBC) can be defined as the number of shortest paths that pass through an edge in a network.
- Each and every edge is given an EBC score based on the shortest paths among all the nodes in the graph.
- The betweenness of an edge (a,b) is the number of pairs of nodes (x,y) such that the edge (a,b) lies on the shortest path between x and y.

- Let's take an example to find how EBC scores are calculated.
- Consider the given graph. It has 6 nodes and 7 edges.
- Steps:
  - Take one node at a time and plot the shortest paths to the other nodes from the selected node
  - Based on the shortest paths, compute the EBC scores for all the edges
  - Repeat this process for every node in the graph.
  - After all iterations, every edge will get EBC scores. These scores will be added edge-wise
  - Finally, the total score of each edge will be divided by 2 to get the EBC score since it is an undirected graph.

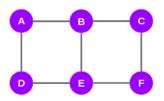


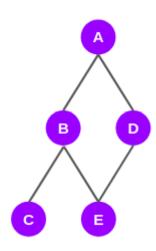
 Let's start with node A. The directly connected nodes to node A are nodes B and D. So, the shortest paths to B and D from A are AB and AD respectively.



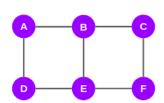


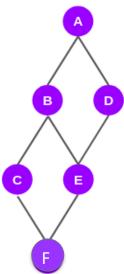
 It turns out that the shortest paths to nodes C and E from A go through B and D.





 The shortest paths to the last node F from node A, pass through nodes B, D, C, and E.

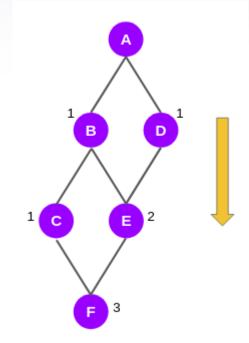




- The graph above depicts only the shortest paths from node A to all the other nodes.
- Now edge scores need to be assigned.
- Before giving scores to the edges, assign a score to the nodes in the shortest-path-graph.
- To assign these scores, traverse the graph from the root node. (i.e., node A to the last node F).

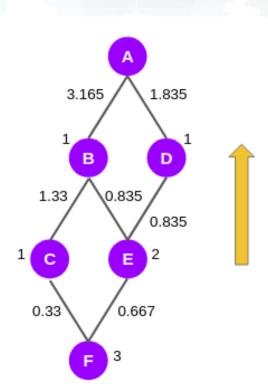
#### Assigning scores to nodes

- Nodes B and D have been given a score of 1 each.
  This is because the shortest path to either node
  from node A is only one. For the very same reason,
  node C has been given a score of 1 as there is only
  one shortest path from node A to node C.
- Moving on to node E. It is connected to node A through two shortest paths, ABE and ADE. Hence, it gets a score of 2.
- The last node F is connected to A through three shortest paths — ABCF, ABEF, and ADEF. So, it gets a score of 3.



#### **Computing Scores for Edges**

- Next, proceed with computing scores for the edges. Here computation begins in the backward direction from node F to node A.
- Firstly, compute the score for the edges FC and FE. The edge score for edge FC is the ratio of the node scores of C and F, i.e. 1/3 or 0.33. Similarly, for FE the edge score is 2/3.
- Now, calculate the edge score for the edges CB, EB, and ED. According to the Girvan-Newman algorithm, from this level onwards, every node will have a default value of 1 and the edge scores computed in the previous step will be added to this value.
- So, the edge score of CB is (1 + 0.33)/1. Similarly, edge score EB or ED is (1 + 0.667)/2. Then we move to the next level to calculate the edge scores for BA and DA.



FC = 
$$\frac{1}{3}$$
 = 0.33  
FE =  $\frac{2}{3}$  = 0.667

$$CB = 1 + 0.33 = 1.33$$

$$EB = (1 + 0.667)/2 = 0.835$$

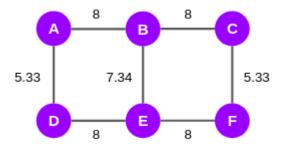
$$ED = (1 + 0.667)/2 = 0.835$$

$$BA = (1 + 1.33 + 0.835)/1 = 3.165$$

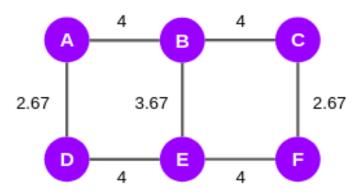
$$DA = (1 + 0.835)/1 = 1.835$$

#### **Computing Final Scores for Edges**

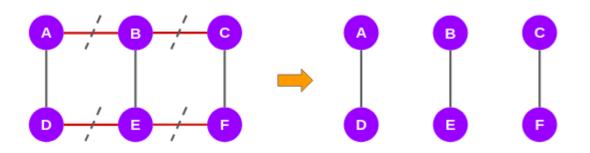
- So far, we have computed the edge scores of the shortest paths with respect to node
   A. We need to repeat the same steps again from the other remaining five nodes.
- In the end, we will get a set of six scores for all the edges in the network. Then add these scores and assign them to the original graph as shown in diagram.



 Since it is an undirected graph, divide these scores by two and finally, we will get the EBC scores.



- According to the Girvan-Newman algorithm, after computing the EBC scores, the edges with the highest scores will be taken off till the point the graph splits into two.
- So, in the graph above, we can see that the edges AB, BC, DE, and EF have the highest score, i.e., 4.
- We will strike off these edges and it gives us 3 subgraphs that we can call communities.





#### Thanks.....