Distributed Computing Problem Set #1

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Problem 1

The protocol works as follows:

- (a) We color the process with two kinds of color: blue and red.
- (b) When sending a message, if the process is blue, then it sends the message with a blue flag; and if the process is red, then it sends the message with a red flag.
- (c) At first, all processes are colored blue except p0(p0 is red). p0 sends "take a snapshot" to all the other processes.
- (d) Every blue process records the messages which is sent by itself and the blue messages it receives.
- (e) When pi receives a red message, if pi is blue, then it takes its snapshot, changes its color to red, sends both the snapshot and the messages it has recorded to p0, and sends "take a snapshot" to the other processes.
- (f) p0 collects the messages until it has received the messages from all the other processes. Then it has collected all the states: local states are the snapshots; channel states can be calculated (for any channel i -> j, its states = {messages sent by pi} {messages received by pj}).

Proof of correctness:

Need to prove $e_i \in C \land e_i \rightarrow e_i \Rightarrow e_i \in C$

We prove it by contradiction. If it does not hold, then there exists i and j s.t $e_j \in C \land e_i \rightarrow e_j$ and $e_i \notin C$. Let t be the time that process i takes its snapshot on process i. Because $e_i \notin C$, the following two claims are true: (1) t is earlier than the time e_i is executed (2) all the messages sent by process i after t are red. Because $e_i \rightarrow e_j$, e_j is executed conditioned on process j having received the message that tells e_i has been executed. So before e_j is executed on process j, j must have received a red message from i, which makes process j take its snapshot. But that snapshot does not include e_j which leads to a paradox.

Problem 2

- 1. (3)
- 2. (1)
- 3. (2)
- 4. (4)
- 5. (1)
- 6. (2)

Problem 3

- 1.
- (a)

If Inp="ready"

Send "yes" for 11 times.

If "yes" from the other general is delivered, decide "attack".

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If "no" from the other general is delivered, decide "not attack"

If Inp="not ready"

Send "no" for 11 times

Decide "not attack"
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It is obvious that the above protocol satisfies Agreement, Validity and Termination.

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(b)
If Inp="ready"
Keep sending "yes"
If "yes" from the other general is delivered, decide "attack".
If "no" is delivered, decide "not attack".
If Inp="not ready"
Keep sending "no"
Decide "not attack"
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Validity: It is easy to check the above protocol that If both inputs are "not ready" to attack, then no general decides "attack". And If both inputs are "ready" and every message sent is delivered, then no general decides "not attack".

Agreement: We prove by contradiction. WLOG, assume general A decides "attack" and general B decides "not attack", we can separately check the following 4 cases and all of them lead to a paradox:

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(i)A is ready and B is not ready(ii)A is not ready and B is ready(iii)A is ready and B is ready(iv)neither A nor B is ready
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Termination:

Our protocol will terminate after everyone delivers one message, so termination is clear.

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2.
(a)
If Inp="ready"
Send "yes" for 11 times.
If "yes" from the other general is delivered, decide "attack".
If "no" from the other general is delivered, decide "not attack"
Halt
If Inp="not ready"
Send "no" for 11 times
Decide "not attack"
Halt
```

Same as 1, it is obvious that the above protocol satisfies Agreement, Validity, Termination. And it is also obvious that the above protocol satisfies Halt.

(b)No such algorithm exists.

We prove by contradiction.

Assume we have a solution and n is the smallest number of messages needed.

Let $\,m\,$ be the n-th message.

The state of the m's sender does not depend on whether m is delivered.

The state of the m's receiver cannot depend on whether m is delivered because whether m is delivered may be different in different execution.

So without m, both the sender and the receiver can also get their decisions, which implies that we can construct a solution which needs only n-1 messages. But n is the smallest number!

Problem 4

X: If a process broadcasts m and a process delivers a message m before broadcasting a message m', no (correct) process delivers m' unless it has delivered m.

Proof:

Causal Order => FIFO Order + X:

By definition of Casual Order, FIFO Order and X, we can see that Casul Order implies and FIFO Order and X.

FIFO Order + X=>Causal Order:

If the broadest of a message m causally precedes the broadcast of a message m', there must exist a finite sequence of messages $m=m_1,m_2,\ldots,m_k=m'$ such that for any i, one of the following happens:

- (1) m_i and m_{i+1} are broadcasted by the same process and m_i is broadcasted before m_{i+1}
- (2) A process delivers m_i before it broadcasts m_{i+1}

In the first case, according to FIFO Order, no process delivers m_{i+1} before delivering m_i . As we assume that there are no failures, every (correct) process delivers m_i before m_{i+1} . In the second case, according to X, no process delivers m_{i+1} before delivering m_i . As we assume that there are no failures, every (correct) process delivers m_i before m_{i+1} .

By (1)(2), we know that for every i, every (correct) process delivers m_i before m_{i+1} . So every correct process delivers m before delivering m', which is Causal Order.

Problem 5

We can modify the vector clock as follows:

When broadcasting messages:

VC(e)[i]:=VC[i]+1

When delivering messages m:

VC(e):=max(VC, TS(m))

And in the other cases:

VC(e)[i]:=VC[i]

Then for each process i, maintains an array D[1..n] of counters

 $D[i]=TS(m_i)[i]$ where m_i is the last message delivered from process i;

Process k delivers m from p_i as soon as both of the following conditions are satisfied:

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D[j]=TS(m)[j]-1
D[k]>=TS(m)[k], \forall k \neq j
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