

# **LJMD Case Study: Optimization and Parallelization**

**Dr. Axel Kohlmeyer**

Assistant Dean for High-Performance Computing

Associate Director, ICMS

Associate Director, TMI

College of Science and Technology

Temple University, Philadelphia

**[axel.kohlmeyer@temple.edu](mailto:axel.kohlmeyer@temple.edu)**

External Scientific Associate

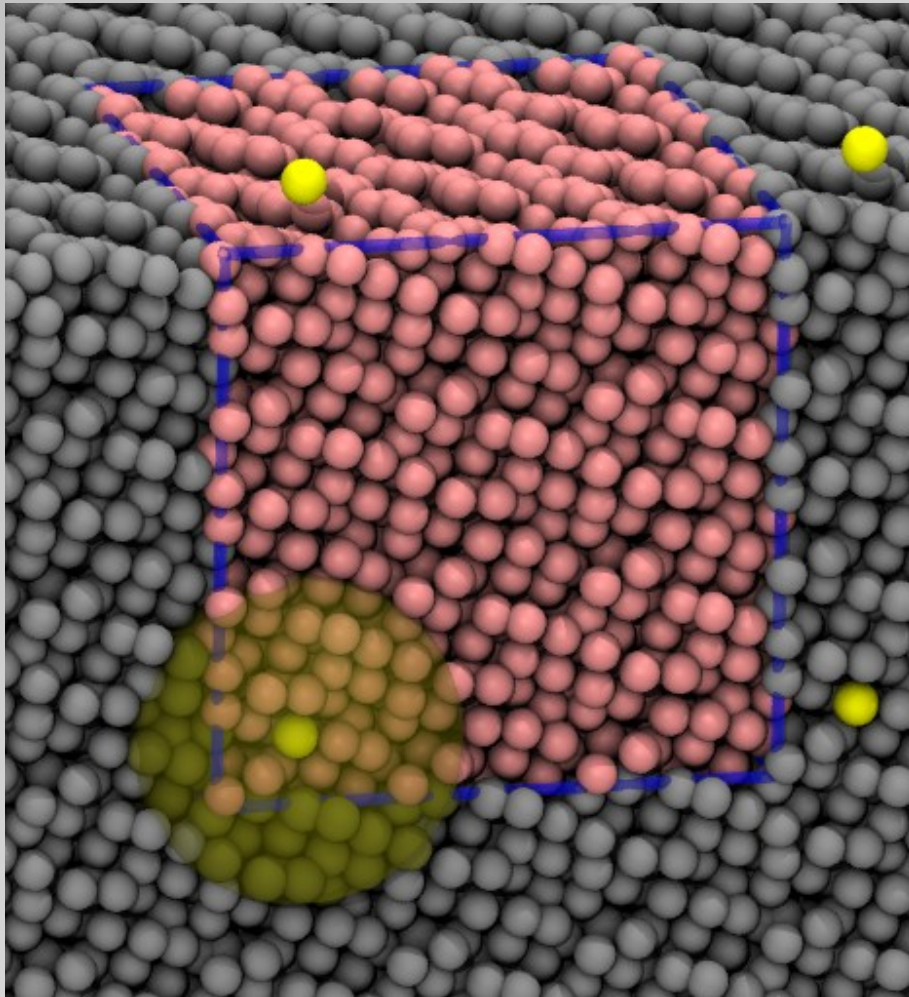
International Centre for Theoretical Physics, Trieste, Italy

**[akohlmey@ictp.it](mailto:akohlmey@ictp.it)**

# Today's Show

- 0) Overture: the physics of the model
- 1) First Act: writing and optimizing a serial code
- 2) Intermezzo: improve scaling with system size
- 3) Second Act: MPI parallelization
- 4) Third Act: OpenMP parallelization
- 5) Finale: Hybrid MPI/OpenMP parallelization
- 6) Encore: further options for improvement
- 7) Last dance: lessons learned

# 0) The Model for Liquid Argon



- Cubic box of particles with a Lennard-Jones type pairwise additive interaction potential

$$U(r) = \sum_{i,j} \begin{cases} 4\epsilon \left[ \left( \frac{\sigma}{r_{ij}} \right)^{12} - \left( \frac{\sigma}{r_{ij}} \right)^6 \right], & r_{ij} < r_c \\ 0, & r_{ij} \geq r_c \end{cases}$$

- Periodic boundary conditions to avoid surface effects

# Newton's Laws of Motion

- We consider our particles to be *classical objects* so Newton's laws of motion apply:
  1. In absence of a force a body rests or moves in a straight line with constant velocity
  2. A body experiencing a force  $\mathbf{F}$  experiences an acceleration  $\mathbf{a}$  related to  $\mathbf{F}$  by  $\mathbf{F} = m\mathbf{a}$ , where  $m$  is the mass of the body.
  3. Whenever a first body exerts a force  $\mathbf{F}$  on a second body, the second body exerts a force  $-\mathbf{F}$  on the first body

# Velocity-Verlet Algorithm

- The Velocity-Verlet algorithm is used to propagate positions and velocities of the atoms

$$\vec{v}_i(t + \frac{\Delta t}{2}) = \vec{v}_i(t) + \frac{1}{2} \vec{a}_i(t) \Delta t$$

$$\vec{x}_i(t + \Delta t) = \vec{x}_i(t) + \vec{v}_i(t + \frac{\Delta t}{2}) \Delta t$$

$$\vec{a}_i(t + \Delta t) = -\frac{1}{m} \nabla V(\vec{x}_i(t + \Delta t))$$

Force calculation

$$\begin{cases} 4\epsilon \left[ -12 \left( \frac{\sigma}{r_{ij}} \right)^{13} + 6 \left( \frac{\sigma}{r_{ij}} \right)^7 \right], & r_{ij} < r_c \\ 0, & r_{ij} \geq r_c \end{cases}$$

$$\vec{v}_i(t + \Delta t) = \vec{v}_i(t + \frac{\Delta t}{2}) + \frac{1}{2} \vec{a}_i(t + \Delta t) \Delta t$$

L. Verlet, Phys. Rev. 159, 98 (1967); Phys. Rev. 165, 201 (1967).



# What Do We Need to Program?

1. Read in parameters and initial status and compute what is missing (e.g. accelerations)
2. Integrate Equations of motion with Velocity Verlet for a given number of steps
  - a) Propagate all velocities for half a step
  - b) Propagate all positions for a full step
  - c) Compute forces on all atoms to get accelerations
  - d) Propagate all velocities for half a step
  - e) Output intermediate results, if needed

# 1) Initial Serial Code: Velocity Verlet

```
void velverlet(mdsys_t *sys) {  
    for (int i=0; i<sys->natoms; ++i) {  
        sys->vx[i] += 0.5*sys->dt / mvsq2e * sys->fx[i] / sys->mass;  
        sys->vy[i] += 0.5*sys->dt / mvsq2e * sys->fy[i] / sys->mass;  
        sys->vz[i] += 0.5*sys->dt / mvsq2e * sys->fz[i] / sys->mass;  
        sys->rx[i] += sys->dt*sys->vx[i];  
        sys->ry[i] += sys->dt*sys->vy[i];  
        sys->rz[i] += sys->dt*sys->vz[i];  
    }  
  
    force(sys);  
  
    for (int i=0; i<sys->natoms; ++i) {  
        sys->vx[i] += 0.5*sys->dt / mvsq2e * sys->fx[i] / sys->mass;  
        sys->vy[i] += 0.5*sys->dt / mvsq2e * sys->fy[i] / sys->mass;  
        sys->vz[i] += 0.5*sys->dt / mvsq2e * sys->fz[i] / sys->mass;  
    }  
}
```

# Initial Code: Force Calculation

```
for(i=0; i < (sys->natoms); ++i) {  
    for(j=0; j < (sys->natoms); ++j) {  
        if (i==j) continue;
```

```
        rx=pbcc(sys->rx[i] - sys->rx[j], 0.5*sys->box);  
        ry=pbcc(sys->ry[i] - sys->ry[j], 0.5*sys->box);  
        rz=pbcc(sys->rz[i] - sys->rz[j], 0.5*sys->box);  
        r = sqrt(rx*rx + ry*ry + rz*rz);
```

Compute distance  
between atoms i & j  
in box with periodic  
boundary conditions

```
        if (r < sys->rcut) {
```

Compute energy and force

```
            ffac = -4.0*sys->epsilon*(-12.0*pow(sys->sigma/r,12.0)/r  
                +6*pow(sys->sigma/r,6.0)/r);  
            sys->epot += 0.5*4.0*sys->epsilon*(pow(sys->sigma/r,12.0)  
                -pow(sys->sigma/r,6.0));
```

```
            sys->fx[i] += rx/r*ffac;  
            sys->fy[i] += ry/r*ffac;  
            sys->fz[i] += rz/r*ffac;
```

Add force contribution  
of atom j on atom i

```
        }}
```



# How Well Does it Work?

- Compiled with:

```
gcc -o ljmd.x ljmd.c -lm
```

Test input: 108 atoms, 10000 steps: 49s

Let us get a profile:

| %<br>time | cumulative<br>seconds | self<br>seconds | calls     | self<br>ms/call | total<br>ms/call | name    |
|-----------|-----------------------|-----------------|-----------|-----------------|------------------|---------|
| 73.70     | 13.87                 | 13.87           | 10001     | 1.39            | 1.86             | force   |
| 24.97     | 18.57                 | 4.70            | 346714668 | 0.00            | 0.00             | pbc     |
| 0.96      | 18.75                 | 0.18            |           |                 |                  | main    |
| 0.37      | 18.82                 | 0.07            | 10001     | 0.01            | 0.01             | ekin    |
| 0.00      | 18.82                 | 0.00            | 30006     | 0.00            | 0.00             | azzero  |
| 0.00      | 18.82                 | 0.00            | 101       | 0.00            | 0.00             | output  |
| 0.00      | 18.82                 | 0.00            | 12        | 0.00            | 0.00             | getline |

# Step One: Compiler Optimization

- Use of pbc() is convenient, but costs 25% time  
=> compiling with -O3 will inline it, no overhead
- Loops should be unrolled for superscalar CPUs  
=> compiling with -O2 or -O3 should do it for us

Time now: 39s (1.3x faster)    Only a bit faster than 49s

- Now try more aggressive optimization options:  
-ffast-math -fexpensive-optimizations

Time now: 10s (4.9x faster)    Much better!

- Compare to LAMMPS: 3.6s => need to do more

# Now Modify the Code

- Use physics! Newton's 3<sup>rd</sup> law:  $F_{ij} = -F_{ji}$

```
for(i=0; i < (sys->natoms)-1; ++i) {  
    for(j=i+1; j < (sys->natoms); ++j) {  
        rx=pbcc(sys->rx[i] - sys->rx[j], 0.5*sys->box);  
        ry=pbcc(sys->ry[i] - sys->ry[j], 0.5*sys->box);  
        rz=pbcc(sys->rz[i] - sys->rz[j], 0.5*sys->box);  
        r = sqrt(rx*rx + ry*ry + rz*rz);  
        if (r < sys->rcut) {  
            ffac = -4.0*sys->epsilon*(-12.0*pow(sys->sigma/r,12.0)/r  
                                +6*pow(sys->sigma/r,6.0)/r);  
            sys->epot += 0.5*4.0*sys->epsilon*(pow(sys->sigma/r,12.0)  
                                -pow(sys->sigma/r,6.0));  
            sys->fx[i] += rx/r*ffac;    sys->fx[j] -= rx/r*ffac;  
            sys->fy[i] += ry/r*ffac;    sys->fy[j] -= ry/r*ffac;  
            sys->fz[i] += rz/r*ffac;    sys->fz[j] -= rz/r*ffac;  
        }  
    }  
}
```

Time now: 5.4s (9.0x faster) **Another big improvement**

# More Modifications

- Avoid expensive math: pow(), sqrt(), division

```
c12=4.0*sys->epsilon*pow(sys->sigma,12.0);  
c6 =4.0*sys->epsilon*pow(sys->sigma, 6.0);  
rcsq = sys->rcut * sys->rcut;  
for(i=0; i < (sys->natoms)-1; ++i) {  
    for(j=i+1; j < (sys->natoms); ++j) {  
        rx=pbcc(sys->rx[i] - sys->rx[j], 0.5*sys->box);  
        ry=pbcc(sys->ry[i] - sys->ry[j], 0.5*sys->box);  
        rz=pbcc(sys->rz[i] - sys->rz[j], 0.5*sys->box);  
        rsq = rx*rx + ry*ry + rz*rz;  
        if (rsq < rcsq) {  
            double r6,rinv; rinv=1.0/rsq; r6=rinv*rinv*rinv;  
            ffac = (12.0*c12*r6 - 6.0*c6)*r6*rinv;  
            sys->epot += r6*(c12*r6 - c6);  
            sys->fx[i] += rx*ffac; sys->fx[j] -= rx*ffac;  
            sys->fy[i] += ry*ffac; sys->fy[j] -= ry*ffac;  
            sys->fz[i] += rz*ffac; sys->fz[j] -= rz*ffac;  
        }  
    }  
}
```

=> 108 atoms: 4.0s (12.2x faster) **still worth it**

# Improvements So Far

- Use the optimal compiler flags => ~5x faster but some of it: inlining, unrolling could be coded
- Use our knowledge of physics => ~2x faster since we need to compute only half the data.
- Use our knowledge of computer hardware => 1.35x faster. There could be more: vectorize

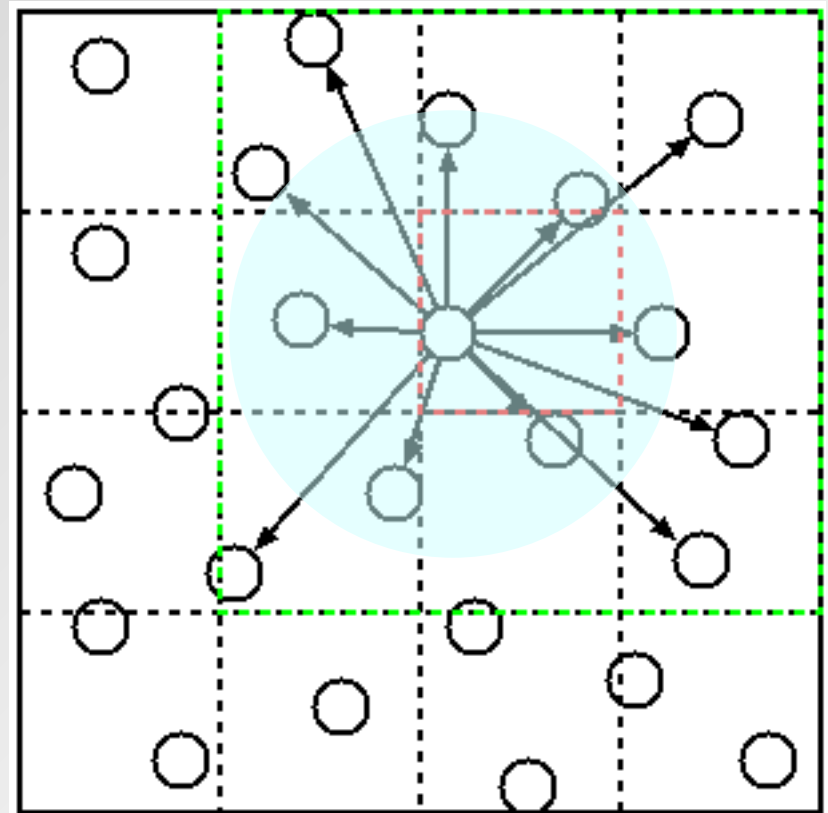
We are within 10% (4s vs. 3.6s) of LAMMPS.

- Try a bigger system: 2916 atoms, 100 steps  
Our code: 13.3s    LAMMPS: 2.7s    => Bad scaling with system size



## 2) Making it Scale with System Size

- Lets look at the algorithm again:  
We compute all distances between pairs
- But for larger systems not all pairs contribute and our effort is  $O(N^2)$
- So we need a way to avoid looking at pairs that are too far away  
=> Sort atoms into cell lists, which is  $O(N)$



# The Cell-List Variant

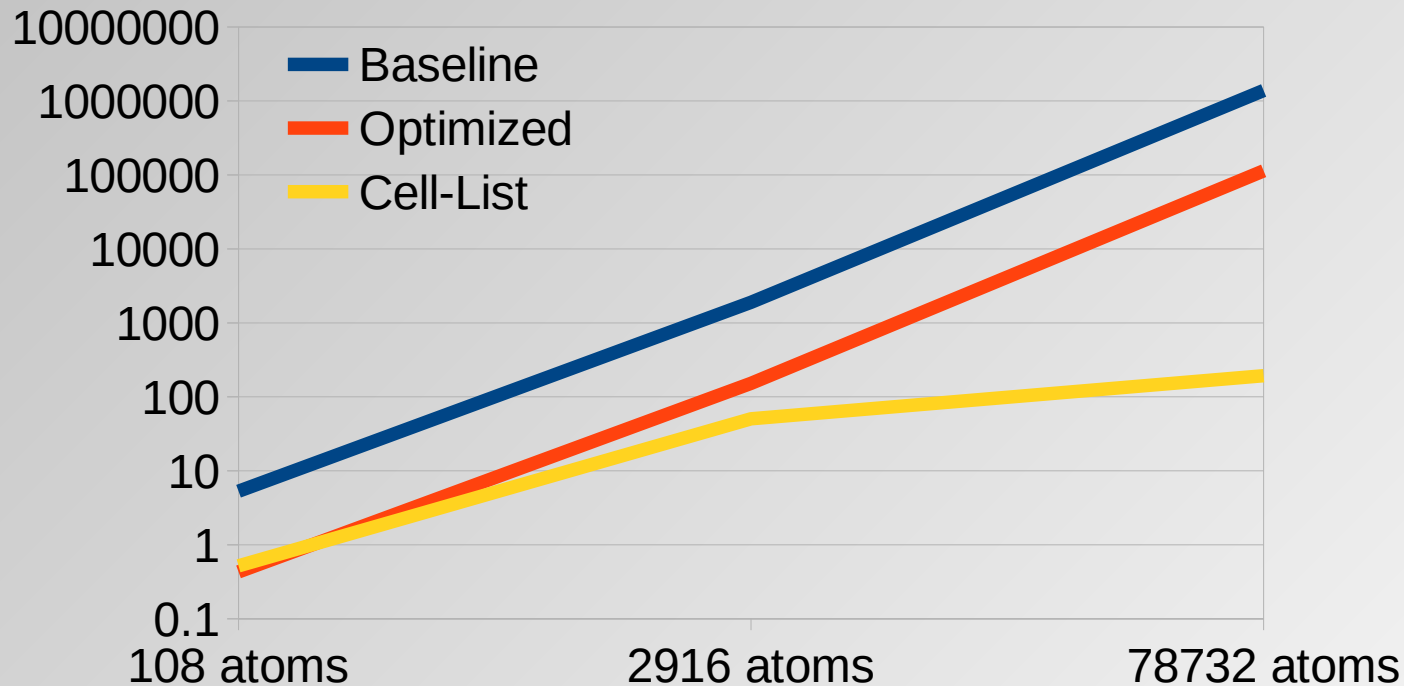
- At startup build a list of lists to store atom indices for atoms that “belong” to a cell
- Compute a list of pairs between cells which contain atoms within cutoff. **Doesn't change!**
- During MD sort atoms into cells
- Then loop over list of “close” pairs of cells  $i$  and  $j$
- For pair of cells loop over pairs of atoms in them
- Now we have linear scaling with system size at the cost of using more memory and an  $O(N)$  sort

# Cell List Loop

```
for(i=0; i < sys->npair; ++i) {  
    cell_t *c1, *c2;  
    c1=sys->clist + sys->plist[2*i];  
    c2=sys->clist + sys->plist[2*i+1];  
  
    for (int j=0; j < c1->natoms; ++j) {  
        int ii=c1->idxlist[j];  
        double rx1=sys->rx[ii];  
        double ry1=sys->ry[ii];  
        double rz1=sys->rz[ii];  
  
        for(int k=0; k < c2->natoms; ++k) {  
            double rx,ry,rz,rsq;  
            int jj=c2->idxlist[k];  
            rx=pbcc(rx1 - sys->rx[jj], boxby2, sys->box);  
            ry=pbcc(ry1 - sys->ry[jj], boxby2, sys->box);  
            ...  
        }  
    }  
}
```

- 2916 atom time: 3.4s (4x faster), LAMMPS 2.7s

# Scaling with System Size



- Cell list does not help (or hurt) much for small inputs, but is a huge win for larger problems  
=> Lesson: always pay attention to scaling

### 3) What if optimization is not enough?

- Having linear scaling is nice, but twice the system size is still twice the work and takes twice the time. => Parallelization
- Simple MPI parallelization first
  - MPI is “share nothing” (replicated or distributed data)
  - Run the same code path with the same data but insert a few MPI calls in the force() routine
    - Broadcast positions from rank 0 to all ranks
    - Compute forces on different atoms for each rank
    - Collect (reduce) forces from all ranks to rank 0 at the end

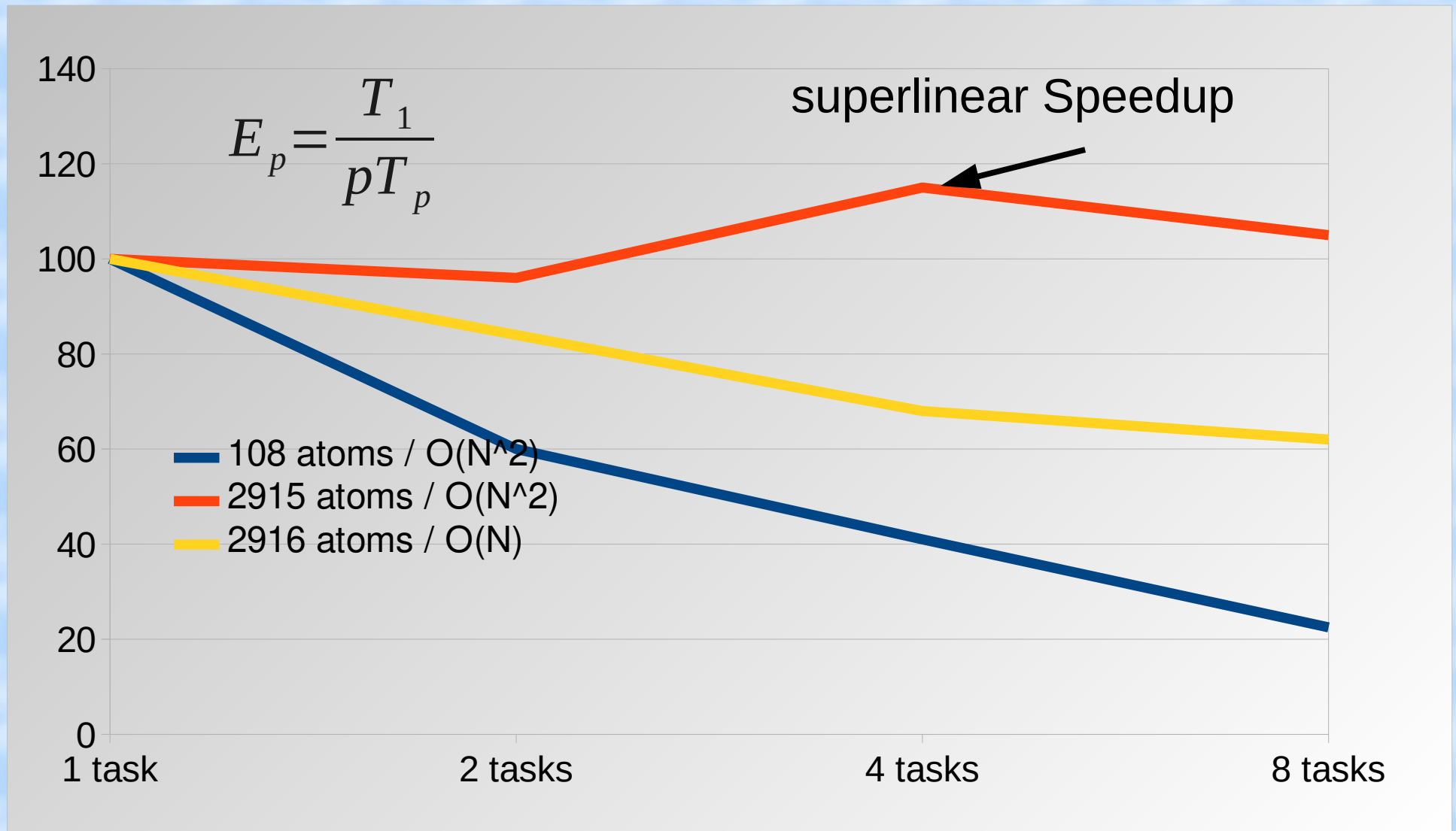


# Replicated Data MPI Version

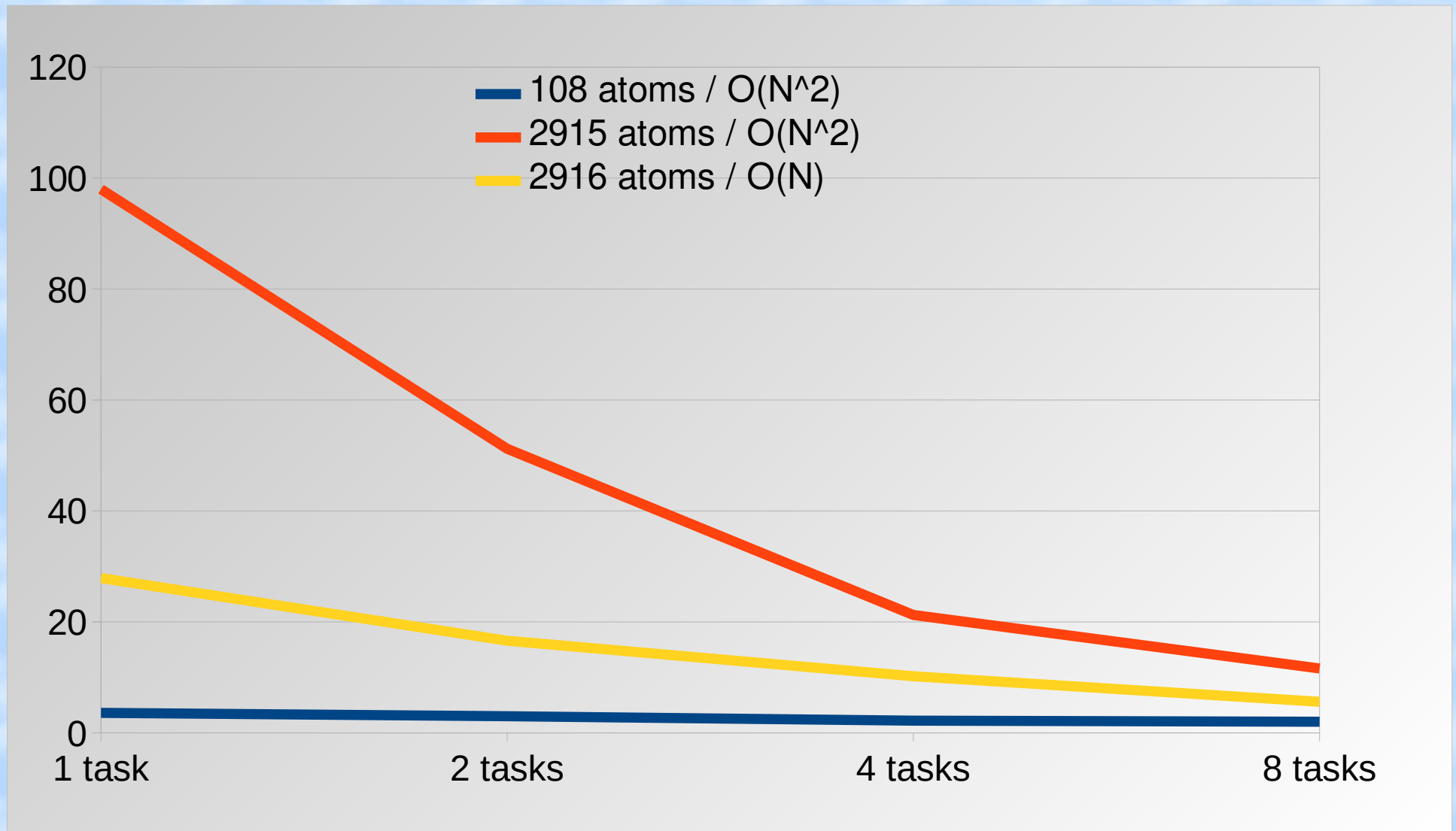
```
static void force(mdsys_t *sys) {  
    double epot=0.0;  
    azero(sys->cx,sys->natoms); azero(sys->cy,sys->natoms); azero(sys->cz,sys->natoms);  
    MPI_Bcast(sys->rx, sys->natoms, MPI_DOUBLE, 0, sys->mpicomm);  
    MPI_Bcast(sys->ry, sys->natoms, MPI_DOUBLE, 0, sys->mpicomm);  
    MPI_Bcast(sys->rz, sys->natoms, MPI_DOUBLE, 0, sys->mpicomm);  
    for (i=0; i < sys->natoms-1; i += sys->nsiz) {  
        ii = i + sys->mpirank;  
        if (ii >= (sys->natoms - 1)) break;  
        for (j=i+1; j < sys->natoms; ++j) {  
            [...]  
            sys->cy[j] -= ry*ffac;  
            sys->cz[j] -= rz*ffac;  
        }  
        MPI_Reduce(sys->cx, sys->fx, sys->natoms, MPI_DOUBLE, MPI_SUM, 0, sys->mpicomm);  
        MPI_Reduce(sys->cy, sys->fy, sys->natoms, MPI_DOUBLE, MPI_SUM, 0, sys->mpicomm);  
        MPI_Reduce(sys->cz, sys->fz, sys->natoms, MPI_DOUBLE, MPI_SUM, 0, sys->mpicomm);  
        MPI_Reduce(&epot, &sys->epot, 1, MPI_DOUBLE, MPI_SUM, 0, sys->mpicomm);  
    }  
}
```

- Easy to implement, but lots of communication

# MPI Parallel Efficiency



# MPI Parallel Execution Times



## 4) OpenMP Parallelization

- OpenMP is directive based  
=> code (can) work without them
- OpenMP can be added incrementally
- OpenMP only works in shared memory  
=> multi-socket nodes, multi-core processors
- OpenMP hides the calls to a threads library  
=> less flexible, but much less programming
- **Caution:** write access to shared data can easily lead to race conditions

# Naive OpenMP Version

```
#if defined(_OPENMP)
#pragma omp parallel for default(shared) \
    private(i) reduction(+:epot)
#endif
    for(i=0; i < (sys->natoms)-1; ++i) {
        double rx1=sys->rx[i];
        double ry1=sys->ry[i];
        double rz1=sys->rz[i];
        [...]
```

Each thread will  
work on different  
values of “i”

```
{
```

```
    sys->fx[i] += rx*ffac;
    sys->fy[i] += ry*ffac;
    sys->fz[i] += rz*ffac;
    sys->fx[j] -= rx*ffac;
    sys->fy[j] -= ry*ffac;
    sys->fz[j] -= rz*ffac;
```

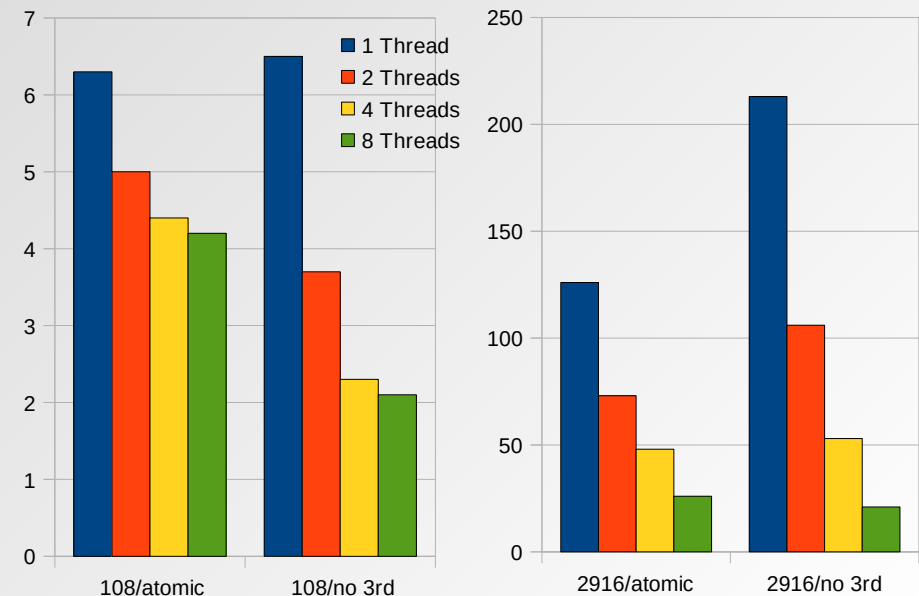
```
}
```

Race condition:  
“i” will be unique for  
each thread, but not “j”  
=> multiple threads may  
write to the same location  
concurrently



# Handling the Race Condition

- Use **omp critical** to let only one thread access  
=> correct result but kills parallelism
- Use **omp atomic** to protect each force update  
=> faster than 'critical' but slower with 1 thread
- No Newton's 3<sup>rd</sup> Law:  
=> no race condition  
=> better scaling but we lose 2x serial speed  
=> need 8 threads to be faster than **atomic**



# MPI-like Approach with OpenMP

```
#if defined(_OPENMP)
#pragma omp parallel reduction(+:epot)
#endif
    { double *fx, *fy, *fz;
#if defined(_OPENMP)
    int tid=omp_get_thread_num();
#else
    int tid=0;
#endif
    fx=sys->fx + (tid*sys->natoms); azero(fx,sys->natoms);
    fy=sys->fy + (tid*sys->natoms); azero(fy,sys->natoms);
    fz=sys->fz + (tid*sys->natoms); azero(fz,sys->natoms);
    for(int i=0; i < (sys->natoms -1); i += sys->nthreads) {
        int ii = i + tid;
        if (ii >= (sys->natoms -1)) break;
        rx1=sys->rx[ii];
        ry1=sys->ry[ii];
        rz1=sys->rz[ii];
    }
```

Thread Id is like MPI rank

sys->fx holds storage for one full fx array for each thread  
=> race condition is eliminated; need to program reduction operation.

# MPI-like Approach with OpenMP (2)

- OpenMP has no equivalent to MPI\_Reduce():

```
#if defined (_OPENMP)
#pragma omp barrier
#endif
```

Need to make certain, all threads  
are done with computing forces

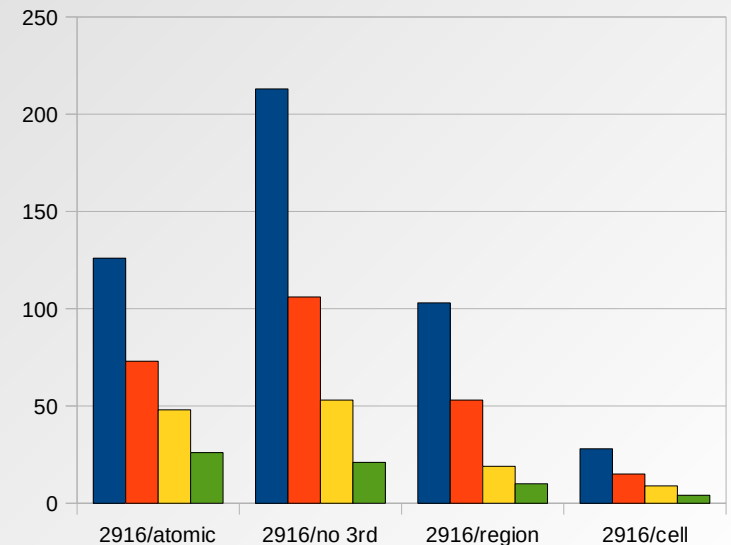
```
i = 1 + (sys->natoms / sys->nthreads);
fromidx = tid * i;
toidx = fromidx + i;
if (toidx > sys->natoms) toidx = sys->natoms;
```

```
for (i=1; i < sys->nthreads; ++i) {
    int offs = i*sys->natoms;
    for (int j=fromidx; j < toidx; ++j) {
        sys->fx[j] += sys->fx[offs+j];
        sys->fy[j] += sys->fy[offs+j];
        sys->fz[j] += sys->fz[offs+j];
    }
}
```

Use threads to  
parallelize the  
reductions

# More OpenMP Timings

- The **omp parallel** region timings  
2916: 1T: 103s, 2T: 53s, 4T: 19s, 8T: 10s  
=> better speedup, but serial is faster for 108,  
at 2916 atoms we are often beyond cutoff
- This approach also works with cell lists  
=> with 8 threads:  
4.1s = 6.8x speedup vs.  
serial cell list version (28s).  
That is **62x** faster than  
the first naive serial version



## 5) Hybrid OpenMP/MPI Version

- With multi-core nodes, communication between MPI tasks becomes a problem
  - => all communication has to use one link
  - => reduced bandwidth, increased latency
- OpenMP and MPI parallelization are orthogonal and can be used at the same time
  - Caution:** don't call MPI from threaded region!
- Parallel region OpenMP version is very similar to MPI version, so that would be easy to merge



# Hybrid OpenMP/MPI Kernel

- Now scatter loops over MPI tasks and threads
- Need to reduce forces/energies first across threads and then across all MPI tasks

```
[...]
    incr = sys->mpisize * sys->nthreads;
    /* self interaction of atoms in cell */
    for(n=0; n < sys->ncell; n += incr) {
        int i,j;
        const cell_t *c1;

        i = n + sys->mpirank*sys->nthreads + tid;
        if (i >= sys->ncell) break;
        c1=sys->clist + i;

        for (j=0; j < c1->natoms-1; ++j) {
[...]
```

# Hybrid OpenMP/MPI Timings

2916 atoms system:

78732 atoms system:

Cell list serial code: 18s

50.1s

16 MPI x 1 Threads: 14s

19.8s

8 MPI x 2 Threads: 5.5s

8.9s

4 MPI x 4 Threads: 4.3s

8.2s

2 MPI x 8 Threads: 4.0s

7.3s

=> Best speedup: 4.5x

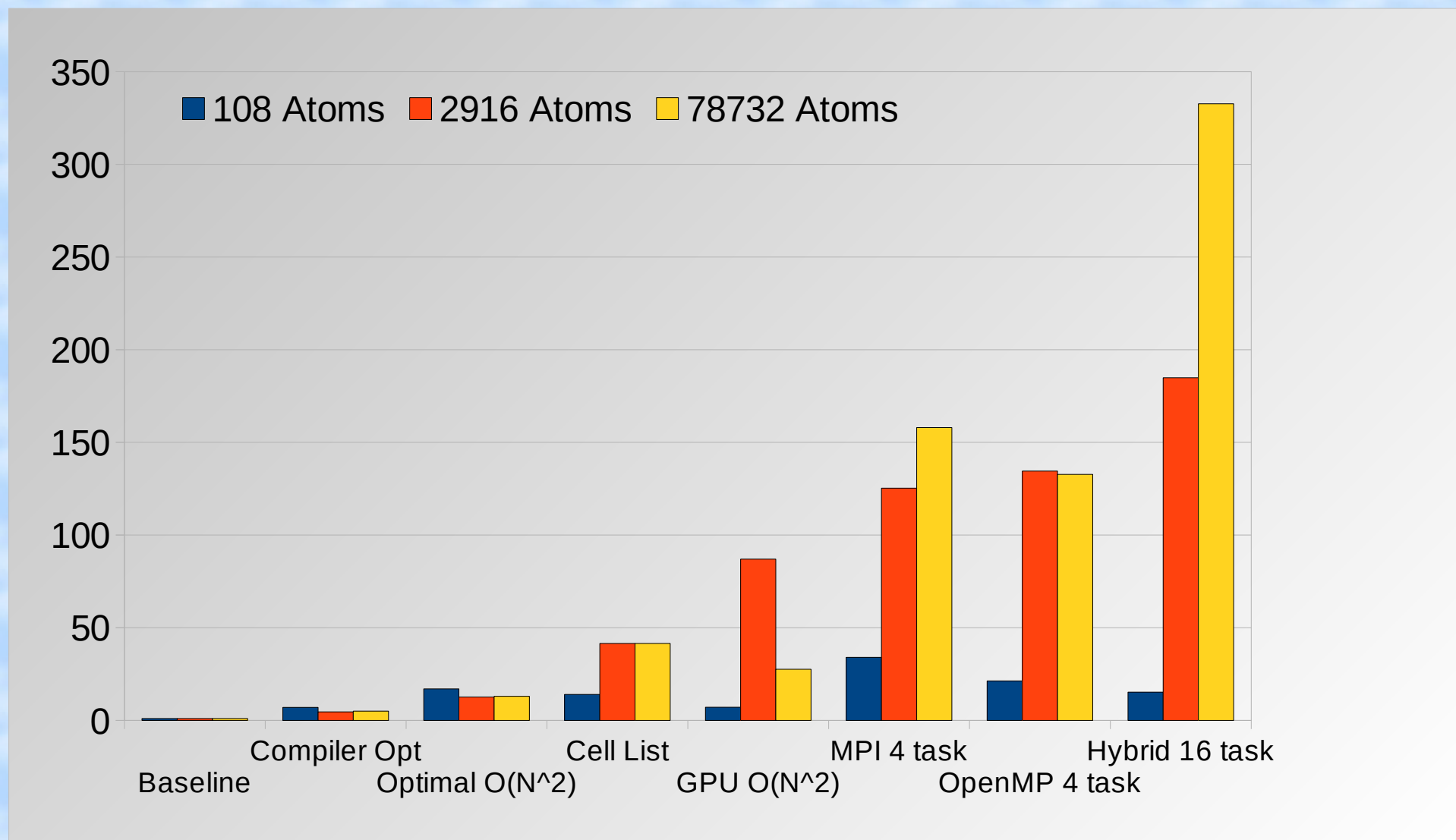
6.9x

=> Total speedup: **185x**

**333x**

Two nodes with 2x quad-core

# Total Speedup Comparison



## 6) Further Options for Improvements

- Use domain decomposition
  - => Better weak scaling, better cache locality
  - => Complex communication (use LAMMPS)
- Use neighbor lists (aka Verlet lists)
  - => Avoid even more distance computations
  - => Increases memory use (use LAMMPS)
- Add vectorization support
  - => Significant speedup with Intel compiler
  - => Even more speedup with single precision
  - => Increased code complexity (use LAMMPS)

## 7) Conclusions

- Make sure that you exploit the physics of your problem well => Newton's 3<sup>rd</sup> law gives a 2x speedup for free (but interferes with threading!)
- Find strategies that have favorable scaling with system size; avoid unneeded computations
- Let the compiler help you (more readable code), but also make it easy to the compiler  
=> unrolling, inlining can be offloaded
- Understand the properties of your hardware and adjust your code to match it

# **LJMD Case Study: Optimization and Parallelization**

**Dr. Axel Kohlmeyer**

Assistant Dean for High-Performance Computing

Associate Director, ICMS

Associate Director, TMI

College of Science and Technology

Temple University, Philadelphia

**[axel.kohlmeyer@temple.edu](mailto:axel.kohlmeyer@temple.edu)**

External Scientific Associate

International Centre for Theoretical Physics, Trieste, Italy

**[akohlmey@ictp.it](mailto:akohlmey@ictp.it)**