

# Pre-Bootcamp Setup Instructions

Deep Reinforcement Learning Bootcamp

August 26-27, Berkeley CA

## 1 Introduction

This document will prepare your environment for the labs. Section 2 is needed for Lab 1 and Lab 2, and subsequent sections are needed for Lab 3, Lab 4, and Lab 5.

## 2 Installing Anaconda

You can download the installer for Python 3.6 at <https://www.continuum.io/downloads> (either the graphical or the command line is fine). More detailed instruction is available [here](#).

After installing it, open up a new terminal and navigate to the root of the setup folder, obtained by decompressing the zip file (there should be a file named `environment.yml` in it). Then, run

```
conda env create -f environment.yml
```

This should create a new conda environment and install a list of packages. If you see an error in the installation process due to missing dependency, you should install missing dependency and then run the following command to continue installation of required packages:

```
conda env update -f environment.yml
```

## 3 Installing Docker

- macOS users: You can download the dmg file at <https://download.docker.com/mac/stable/Docker.dmg>. Then, click on the file and follow the standard software installation procedure. Note: some old versions of Docker are known to be unstable, and make sure you have the latest version installed.
- For all other users, refer to the official instructions at <https://docs.docker.com/engine/installation/>.

After installation, open a new terminal window, and run the following command:

```
docker pull dementrock/deeprlbootcamp:latest
```

This will take a while as it needs to download several gigabytes of data.

## 4 Setting up XQuartz

This step is only needed if you are on macOS. To get visualizations on most of the environments, you need to have XQuartz installed. We provided a setup script, and all you need to do is to run the following:

```
./scripts/setup_xquartz.sh
```

After running the script, log out of your account and log back in for some of the initialization changes to take effect. Then, launch XQuartz and keep it running (you can do so by finding the application from the Launchpad, or type `open -a XQuartz` in the terminal. After that, proceed to the next step.

## 5 Testing environment setup

Run the following test script from the project folder to verify if everything works:

```
./docker_run.sh scripts/test_environment_setup.py
```

Ideally, a message should be displayed on the screen saying **Your environment has been successfully set up!**.

## 6 Testing Visualization

Run the following command from the project folder:

```
./docker_run.sh simplepg/rollout.py
```

Ideally, a screen should be displayed like the following:

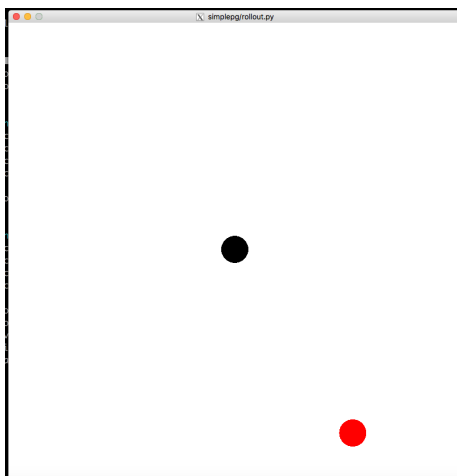


Figure 1: X11 / XQuartz displaying content inside Docker.

You may see an error like “libGL error: No matching fbConfigs or visuals found; libGL error: failed to load driver: swrast.” As long as the display shows up, this can be safely ignored.

Common issues:

- If you see an error saying “pyglet.gl.ContextException: Could not create GL context” and if you are on Linux: try follow the instructions [here](#) to install **nvidia-docker**, and then run the program again.
- If you see an error saying “pyglet.canvas.xlib.NoSuchDisplayException: Cannot connect to None” and if you are on macOS: Try running the following in the terminal:

```
defaults write org.macosforge.xquartz.X11 nolisten_tcp -bool false
defaults write org.macosforge.xquartz.X11 no_auth -bool false
defaults write org.macosforge.xquartz.X11 enable_iglx -bool true
```

Then, restart XQuartz, and see if this fixes the issue.

To exit the program, press **Ctrl+C** in the terminal.

## 7 Setting up VNC Viewer (Optional)

This step is only needed if you want to enable visualization on Roboschool environments.

Since Roboschool environments use advanced OpenGL features for the 3D viewer, which aren’t supported in all X11 versions, we need to use VNC as an alternative way to visualize the program. To do this we need to install a VNC

client. We recommend **RealVNC** if you are running on Ubuntu 16.04 and above, or macOS 10.10 and above. For older systems, we recommend **TurboVNC**.

After setting up the client, run the following command in a terminal:

```
./docker_run_vnc.sh simplepg/rollout.py
```

Note the first line displayed in the terminal. It should be something similar to the following:

```
Connect to this VNC address to view the display: localhost:3000 Password: 3284
```

Open your VNC client and connect to the address, using the password that's displayed. A screen should be displayed similar to the following (the UI around the window may be different depending on the client you used):

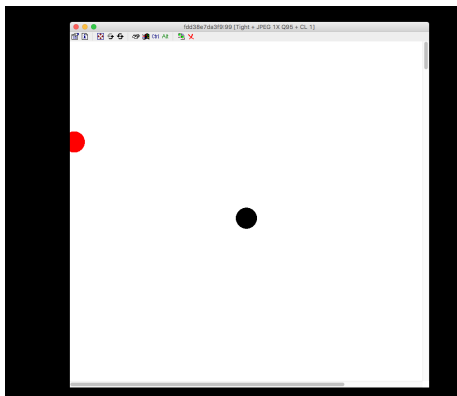


Figure 2: VNC viewer displaying content inside Docker.

The connection will stay up as long as the program is running. You will need to establish a new connection every time a program is launched. To exit the program, close the VNC viewer and press **Ctrl+C** in the terminal.