view_frames Result Recorded at time: 916.600 utm Broadcaster: /jackal0/navsat_transform_node Average rate: 10000.000 Hz Most recent transform: 0.000 (916.600 sec old) Buffer length: 0.000 sec map Broadcaster: /jackal0/global_ekf_localization Average rate: 50.161 Hz Most recent transform: 916.684 (-0.084 sec old) Buffer length: 4.964 sec jackal0/odom Broadcaster: /jackal0/local_ekf_localization Average rate: 50.202 Hz Most recent transform: 916.680 (-0.080 sec old) Buffer length: 4.960 sec jackal0/base_link Broadcaster: /jackal0/robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (916.600 sec old) Buffer length: 0.000 sec jackal0/chassis_link Broadcaster: /jackal0/robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 50.202 Hz Average rate: 50.202 Hz Average rate: 50.202 Hz Average rate: 50.202 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (916.600 sec old) Most recent transform: 916.584 (0.016 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.960 sec Buffer length: 4.960 sec Buffer length: 4.960 sec Buffer length: 4.960 sec jackal0/fenders_link jackal0/mid_mount jackal0/imu_link jackal0/front_left_wheel_link jackal0/front_right_wheel_link jackal0/rear_left_wheel_link jackal0/rear_right_wheel_link jackal0/navsat_link Broadcaster: /jackal0/robot_state_publisher Broadcaster: /jackal0/robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (916.600 sec old) Most recent transform: 0.000 (916.600 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec jackal0/front_mount jackal0/rear_mount Broadcaster: /jackal0/robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (916.600 sec old) Buffer length: 0.000 sec jackal0/front_laser_mount Broadcaster: /jackal0/robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (916.600 sec old) Buffer length: 0.000 sec jackal0/front_laser