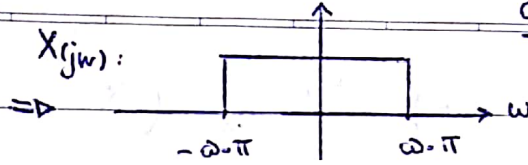
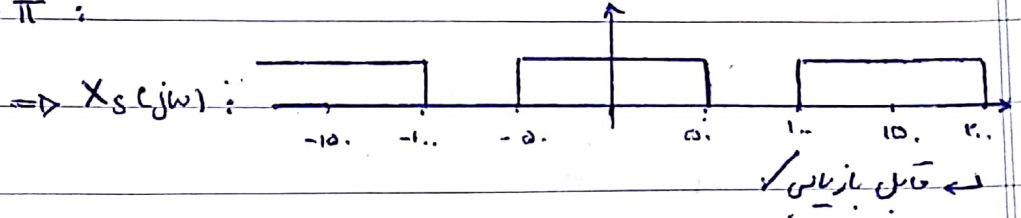


۵. تعیین سری د

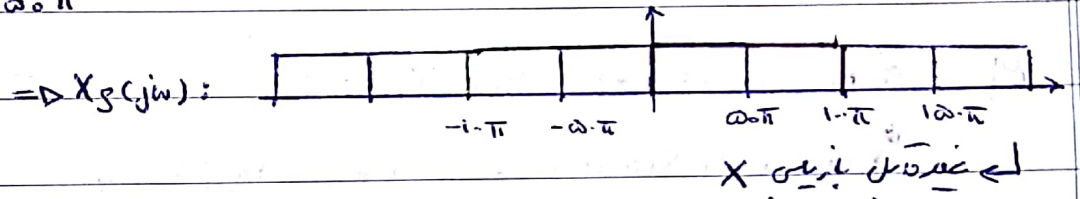
۱)  $x(t) = \frac{\sin \omega_0 \pi t}{\pi t}$   
(الف)



$\rightarrow \omega_s = 1\omega_0 \pi$ :



$\rightarrow \omega_g = \omega_0 \pi$



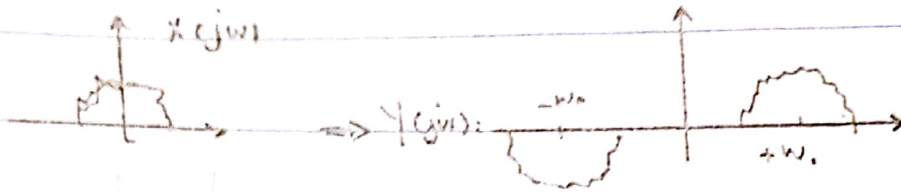
ب)  $\omega_{g \min} = \omega_m = 1\omega_0 \pi$

۲)  $y(t) = x(t) + x(t-1) \xrightarrow{FT} X(j\omega) + e^{-j\omega} X(j\omega) = X(j\omega)(1 + e^{-j\omega})$   
 ۱.  $\omega = \omega_0$  ← مقدار کنای با پس آشی ندارد

۲.  $\frac{dx(t)}{dt} \xrightarrow{FT} j\omega X(j\omega) \rightarrow$  در طول یاس  
 $\Rightarrow \omega = \omega_0$  ← در سری ندارد

۳.  $x^2(t) \xrightarrow{FT} \frac{1}{\pi} X(j\omega) * X(j\omega) \rightarrow$  کنای باندین سینال، ۲ برابر کنای  
 $\omega = 2\omega_0$  ← کنای ۲ برابر می شود.

$$F: x(t) \sin(\omega_0 t) \xrightarrow{FT} \frac{1}{j} (X(\omega - \omega_0) - X(\omega + \omega_0))$$



$$\rightarrow \omega = F \omega_0$$

$$F) \quad x(t) = \cos(F_0 \pi t) + F \sin(F_0 \pi t)$$

$$X(j\omega) = \pi (\delta(\omega + F_0 \pi) + \delta(\omega - F_0 \pi)) + F \pi j (\delta(\omega + F_0 \pi) - \delta(\omega - F_0 \pi))$$

$$g(t) = x(t) \sin(F_0 \pi t)$$

$$\rightarrow G(j\omega) = X(j\omega) * \frac{\pi}{j} (\delta(\omega - F_0 \pi) - \delta(\omega + F_0 \pi))$$

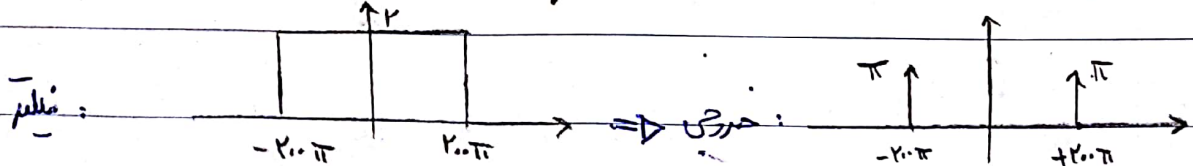
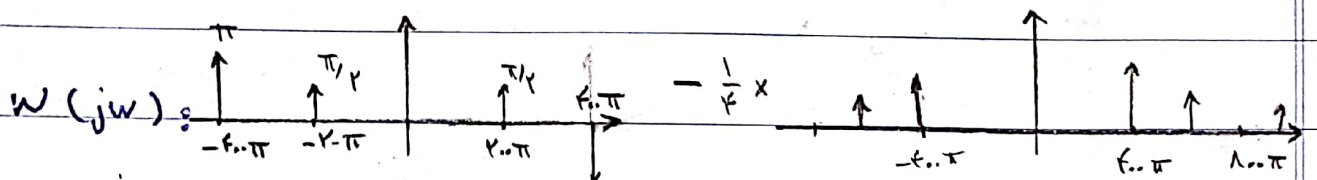
$$w(t) = g(t) \sin(F_0 \pi t)$$

$$\rightarrow W(j\omega) = G(j\omega) * \frac{\pi}{j} (\delta(\omega - F_0 \pi) - \delta(\omega + F_0 \pi))$$

$$\rightarrow \underline{w(t)} = x(t) \sin^2(F_0 \pi t) = x(t) \left( \frac{1}{2} (1 - \cos(2F_0 \pi t)) \right)$$

$$= \frac{x(t)}{2} - \frac{x(t) \cos(2F_0 \pi t)}{2}$$

$$\Rightarrow W(j\omega) = \frac{X(j\omega)}{2} - \frac{1}{2} (X(j(\omega + 2F_0 \pi)) + X(j(\omega - 2F_0 \pi)))$$



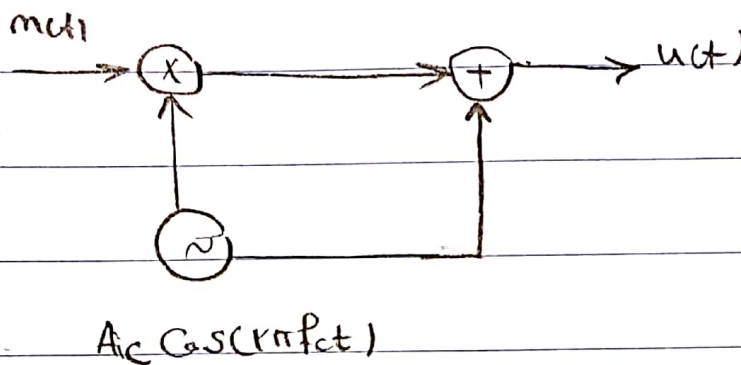
$$\Downarrow$$

$$\text{Output: } \cos(2F_0 \pi t)$$

$$F) \quad m(t) = \sin(1000\pi t) + 0.5 \cos(1400\pi t)$$

$$u(t) = 100(1 + m(t)) \cos(1400\pi t)$$

AM signal  $\leftarrow$



$$\begin{aligned}
 & \Rightarrow u_{AM}(t) = A_c (1 + m(t)) \cos \underbrace{1400\pi t}_{\omega_c} \\
 \text{F.T} \quad & \Rightarrow U_{AM}(\omega) = \frac{A_c}{r} M(\omega - \omega_c) + \frac{A_c}{r} M(\omega + \omega_c) \\
 & + \frac{A_c}{r} \delta(\omega - \omega_c) + \frac{A_c}{r} \delta(\omega + \omega_c)
 \end{aligned}$$

--- 200