



# A Generic Method For Estimating System Reliability Using Bayesian Networks

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# Overview

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## 2.K2 algorithm

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## 4.Experimental analysis

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# Introduction

12/25/2018

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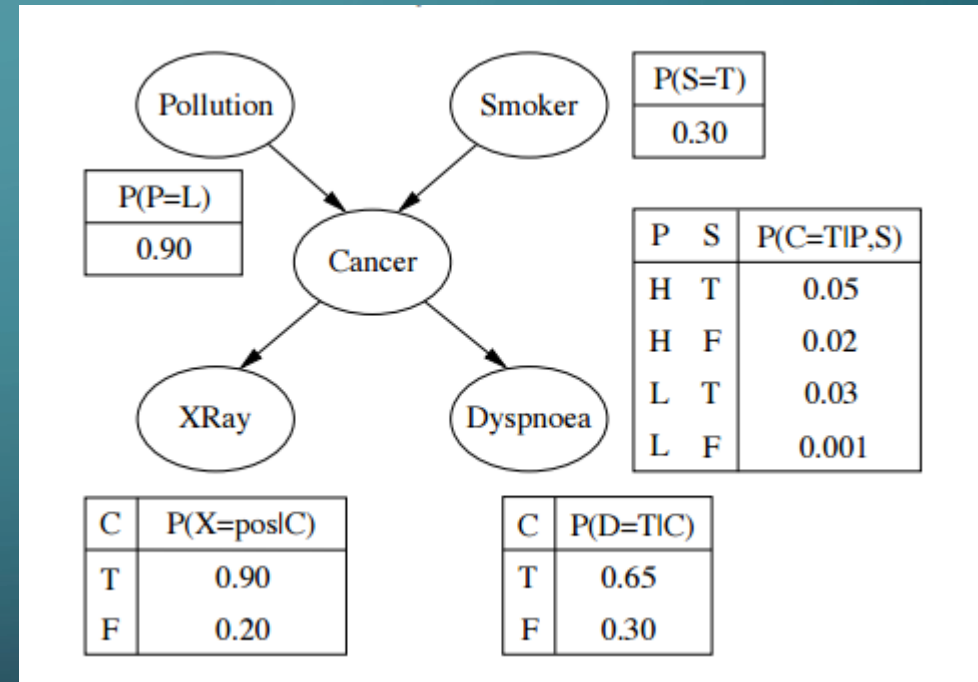
# Bayesian Networks

What is a Bayesian Network ?

DAG: Directed Acyclic Graph

Nodes: System Components

Edges: Relations



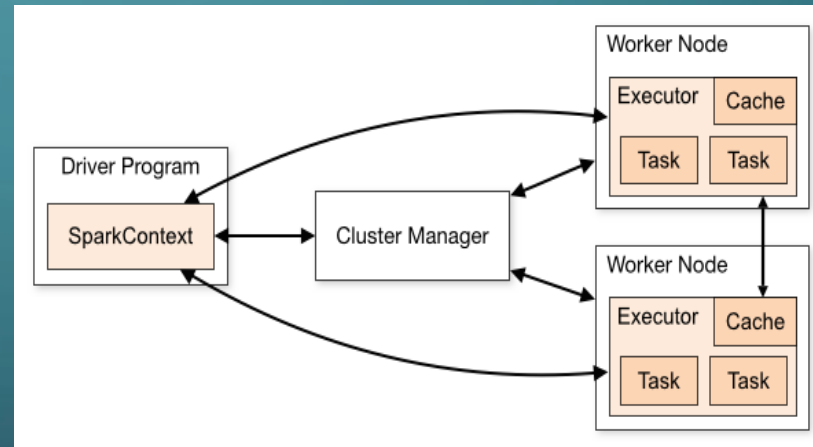
[www.math.stackexchange.com/questions/1709832/confusion-in-a-simple-bayesian-network](https://www.math.stackexchange.com/questions/1709832/confusion-in-a-simple-bayesian-network)

# System Reliability



[www.verifyrecruitment.com/blog/index.php/site-reliability-engineer/](http://www.verifyrecruitment.com/blog/index.php/site-reliability-engineer/)

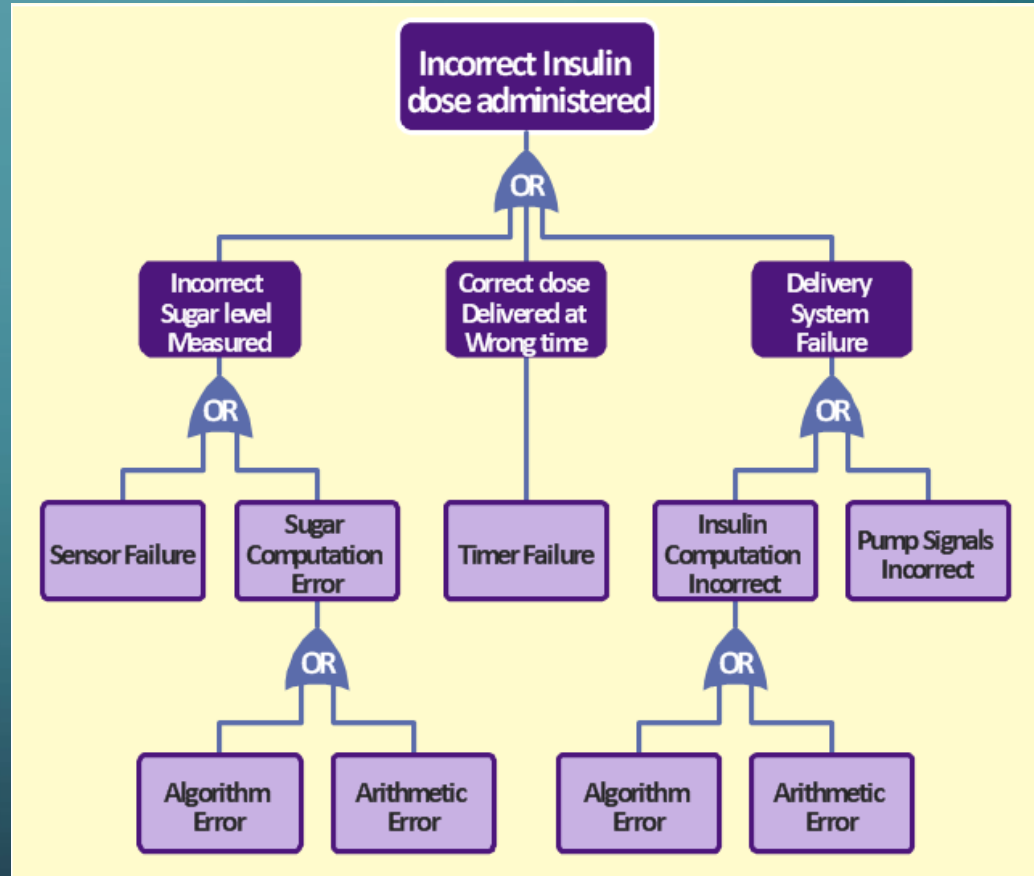
- Probability
- Intended function
- Specific period of time
- Stated condition



[www.spark.apache.org/docs/latest/cluster-overview.html](http://www.spark.apache.org/docs/latest/cluster-overview.html)

# Traditional Approaches

- **Fault trees**
  - Minimal cut sets
  - Minimal path sets
- **Gran and Helminen**
  - Nuclear power plants
    - Software system
    - Plant hardware
- Halden project (HRP)
- Amasaki – software quality assessment
- Requires domain experts to
  - Evaluate prior probabilities
  - Understand the structure of BN.
  - Construct the BN



# Challenges

- System domain specific
- Finding relations between components
- Systems evolve
- Finding domain expert
  - Difficult
  - Costly
  - Unintentional mistakes
  - Need for keeping same expert



[www.technologynetworks.com/informatics/lists/7-data-challenges-in-the-life-sciences-288265](http://www.technologynetworks.com/informatics/lists/7-data-challenges-in-the-life-sciences-288265)



# K2 Algorithm



# Notations

- $\alpha_{ijk}$
- $\alpha_{ij}$
- $\pi_i$
- $q_i$
- $d_i$
- $P(A)$
- $P(A|B) = \frac{P(A,B)}{P(B)}$
- $P(A|B, C) = \frac{P(A,B,C)}{P(B,C)}$
- $P(A|B, C) = P(B, C|A) * \frac{P(A)}{P(B,C)}$

# Pseudo Code

- Machine learning algorithm
- Scoring function
- Heuristic function
- Efficient (polynomial time)  $O(n^2)$
- ~~System specific~~
- Historical data about the system

Output depends on initial linear ordering of components.

## Algorithm K2 ( $T, u$ )

**Input:** A dataset  $T$  of historical observations on system  $S$ , an upper bound  $u$  for the number of parents

**Output:** A full BN  $B$ .

1. For each column  $i$  in dataset  $T$ 
  - Create node  $X_i$  and add it to  $B$ .
  - $\pi_i = \phi$  for node  $X_i$ .
  - Calculate  $f(i, \pi_i)$  using empty set  $\phi$
  - While the size of  $\pi_i \leq u$ 
    - Let  $X_z$  be a node preceding node  $X_i$
    - Calculate  $f(i, \pi_i \cup \{X_z\})$  using  $X_z$
    - If the new score is better than the previous score
      - Add  $X_z$  to  $\pi_i$  permanently
2. Return  $B$

$$f(i, \pi_i) = \prod_{j=1}^{q_i} \frac{(d_i - 1)!}{(\alpha_{ij} + d_i - 1)!} \prod_{k=1}^{d_i} \alpha_{ijk}!$$

# Illustrative Step By Step Example

# Dataset for example

observation	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$	system behavior
1	1	1	0	0	0	0
2	0	1	1	1	1	1
3	1	1	0	1	1	1
4	0	0	0	0	0	0
5	1	0	1	0	0	1
6	0	0	0	0	0	0
7	1	1	0	1	1	1
8	0	1	1	1	1	1
9	1	0	1	0	0	1
0	0	0	0	0	0	0

# f score for all possible candidate parent sets

parent set	f score
$\{\}$	1/2772
$\{X_1\}$	1/3600
$\{X_2\}$	1/3600
$\{X_1, X_2\}$	1/144

$$f(X_2, \phi) = \frac{(2-1)!}{(10+2-1)!} \prod_{k=1}^2 \alpha_{i0k}! = \frac{1!}{11!} \times 5! \times 5! = \frac{1}{2772}$$

$$f(X_2, \{X_1\}) = \frac{(2-1)!}{(5+2-1)!} \prod_{k=1}^2 \alpha_{21k}! \times \frac{(2-1)!}{(5+2-1)!} \prod_{k=1}^2 \alpha_{22k}! = \frac{1}{3600}$$

# Result Of K2 Algorithm

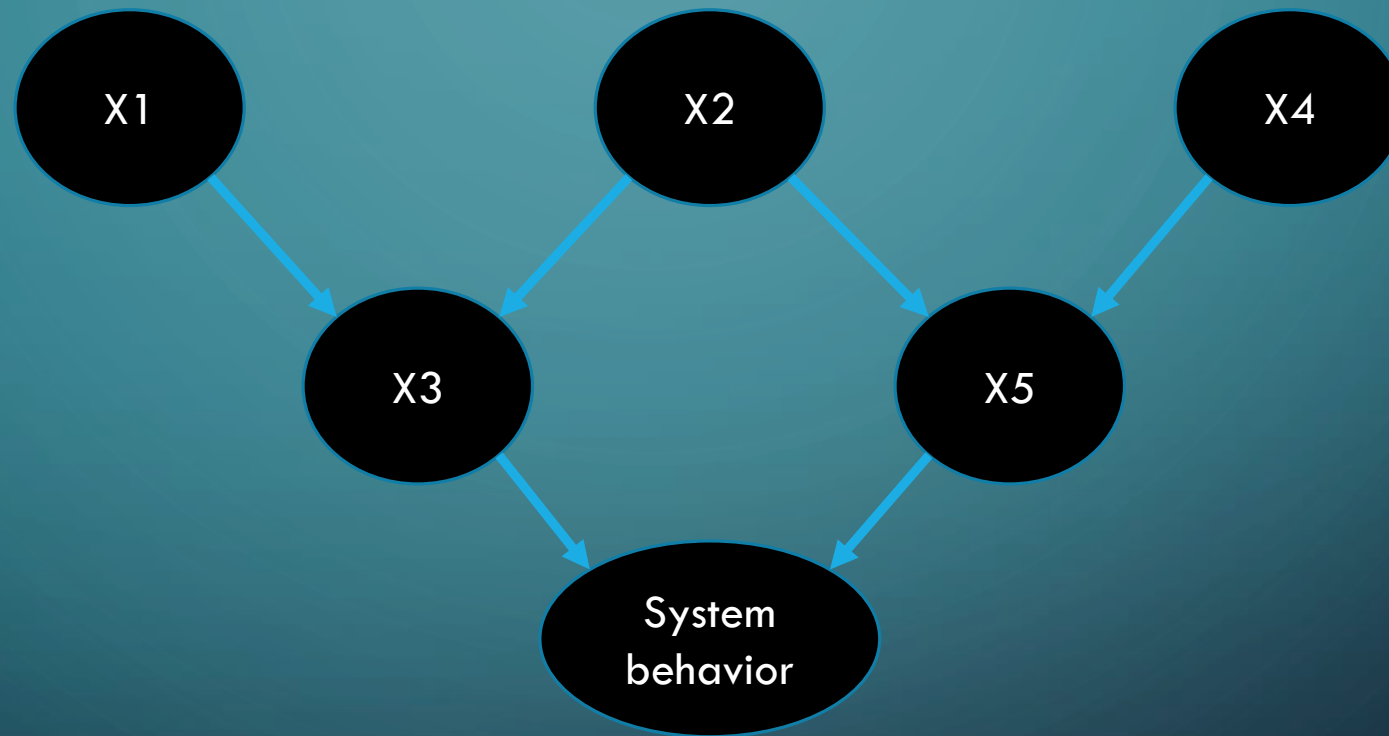


Fig. 1

# CPT Of The $X_3$ Node

parents		probability	
$X_1$	$X_2$	$X_3 = 0$	$X_3 = 1$
0	0	1	0
0	1	0	1
1	0	0	1
1	1	1	0



# Probability Of Success Calculation For Node $X_3$

$$p(X_3 = 1) = \sum p(X_1, X_2, X_3 = 1) =$$

$$\begin{aligned} & p(X_1 = 0, X_2 = 0, X_3 = 1) + p(X_1 = 0, X_2 = 1, X_3 = 1) \\ & + p(X_1 = 1, X_2 = 0, X_3 = 1) + p(X_1 = 1, X_2 = 1, X_3 = 1) \\ & = 0.5 * 0.5 * 0 + 0.5 * 0.5 * 1 + 0.5 * 0.5 * 1 + 0.5 * 0.5 * 0 = 0.5 \end{aligned}$$

# CPT Of The System Behavior Node

parents		probability	
$X_3$	$X_5$	System Behavior = 0	System Behavior = 1
0	0	1	0
0	1	0	1
1	0	0	1
1	1	0	1

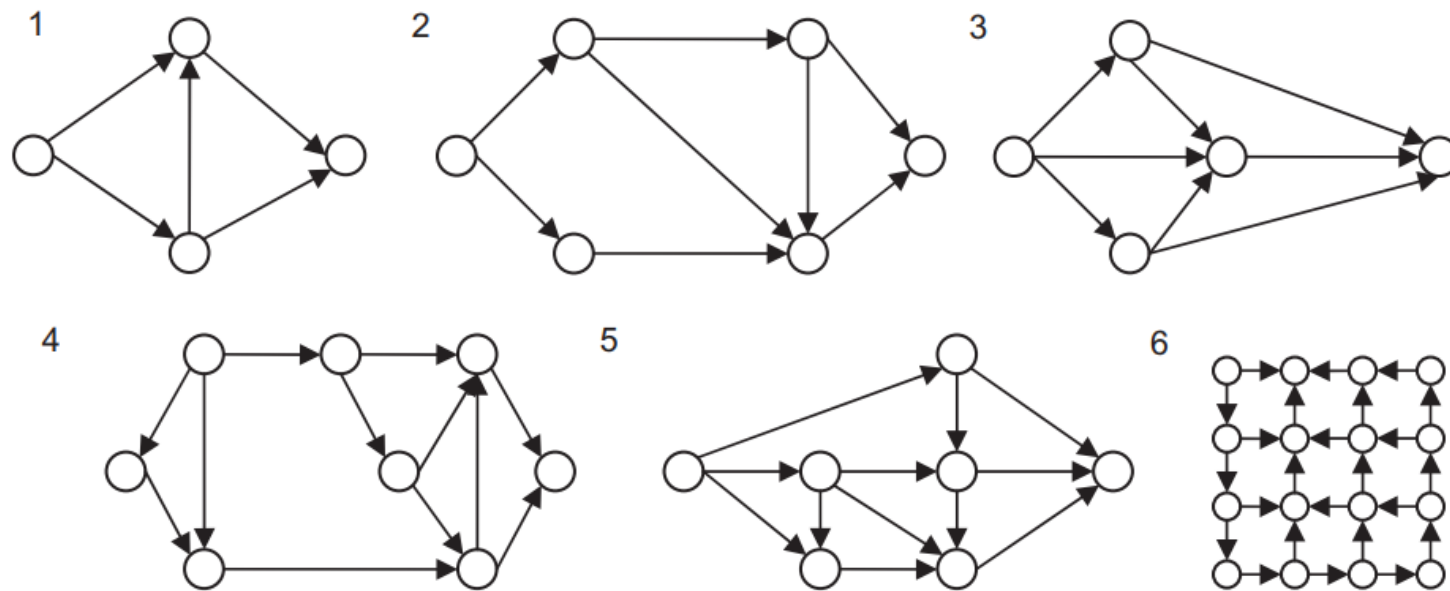
# Experimental Analysis

# How To Increase Performance ?

## How To Reduce Error Rate ?

- More observations (more data) results more accuracy.
- More observations (more data) increases computation time.
- Trade OFF
  - $A_{FP}$
  - $A_{FN}$
  - $A_T$
  - $p = (A_{PF} + A_{PN}) / A_T$

# Some BNs For Test K2 Algorithm



**Fig. 2.** Case BN tested on the K2 algorithm.

# Performance-Runtime Chart

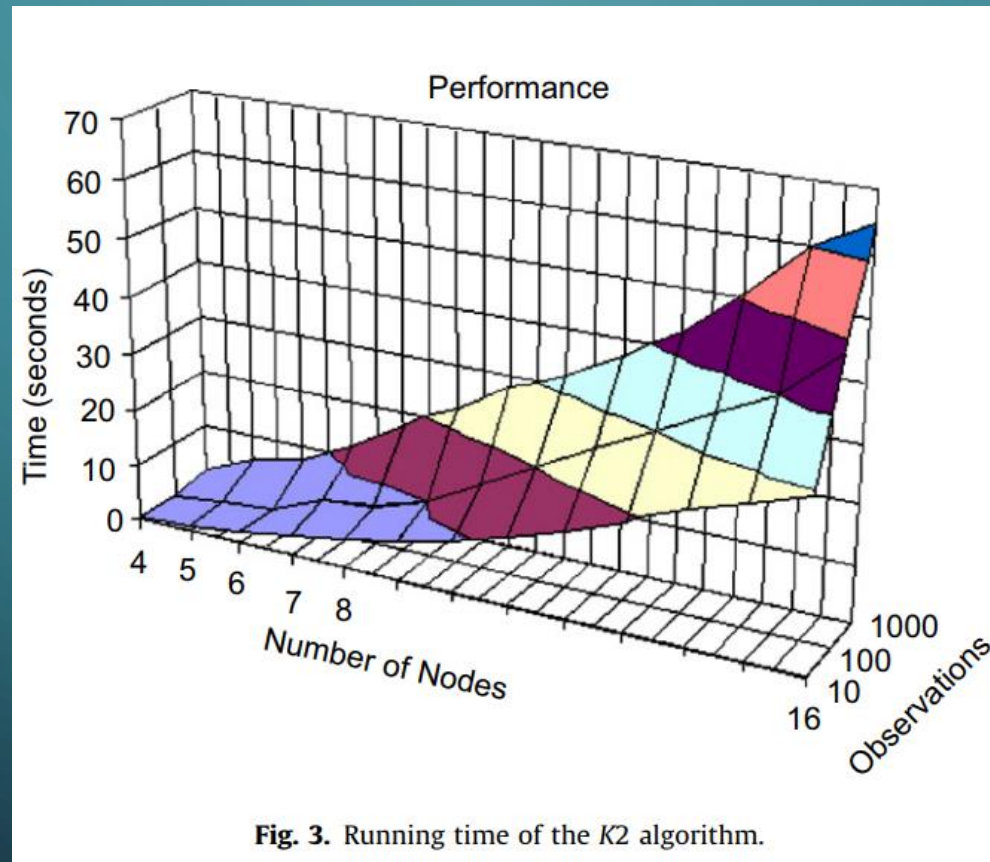


Fig. 3. Running time of the *K2* algorithm.

# Accuracy-Association Chart

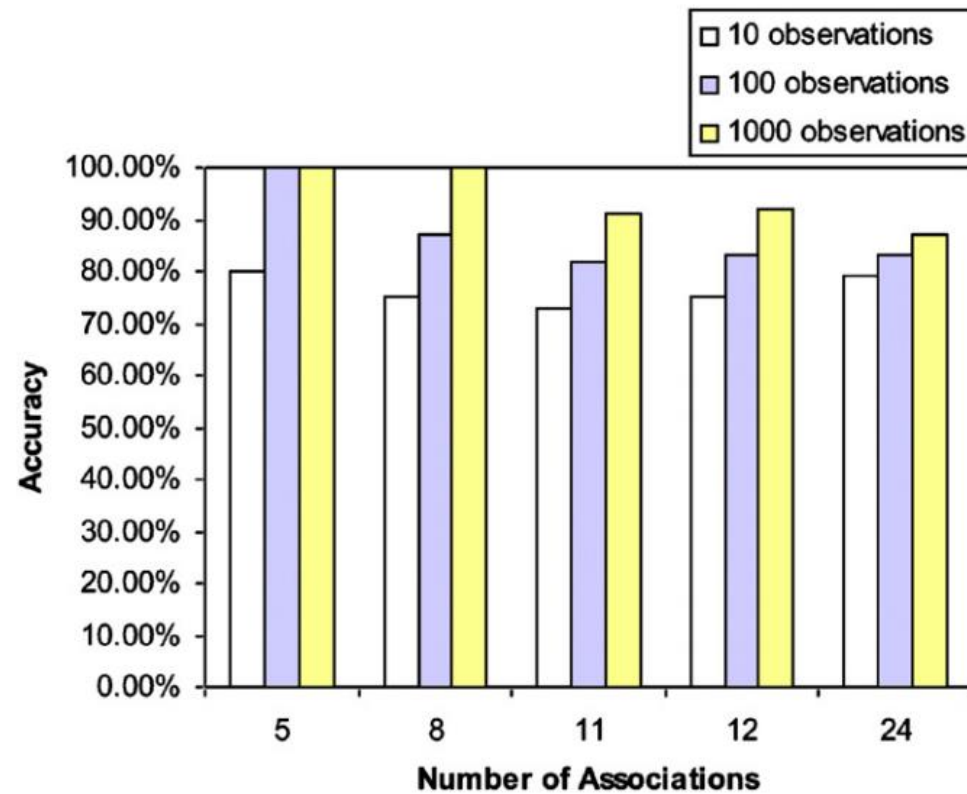
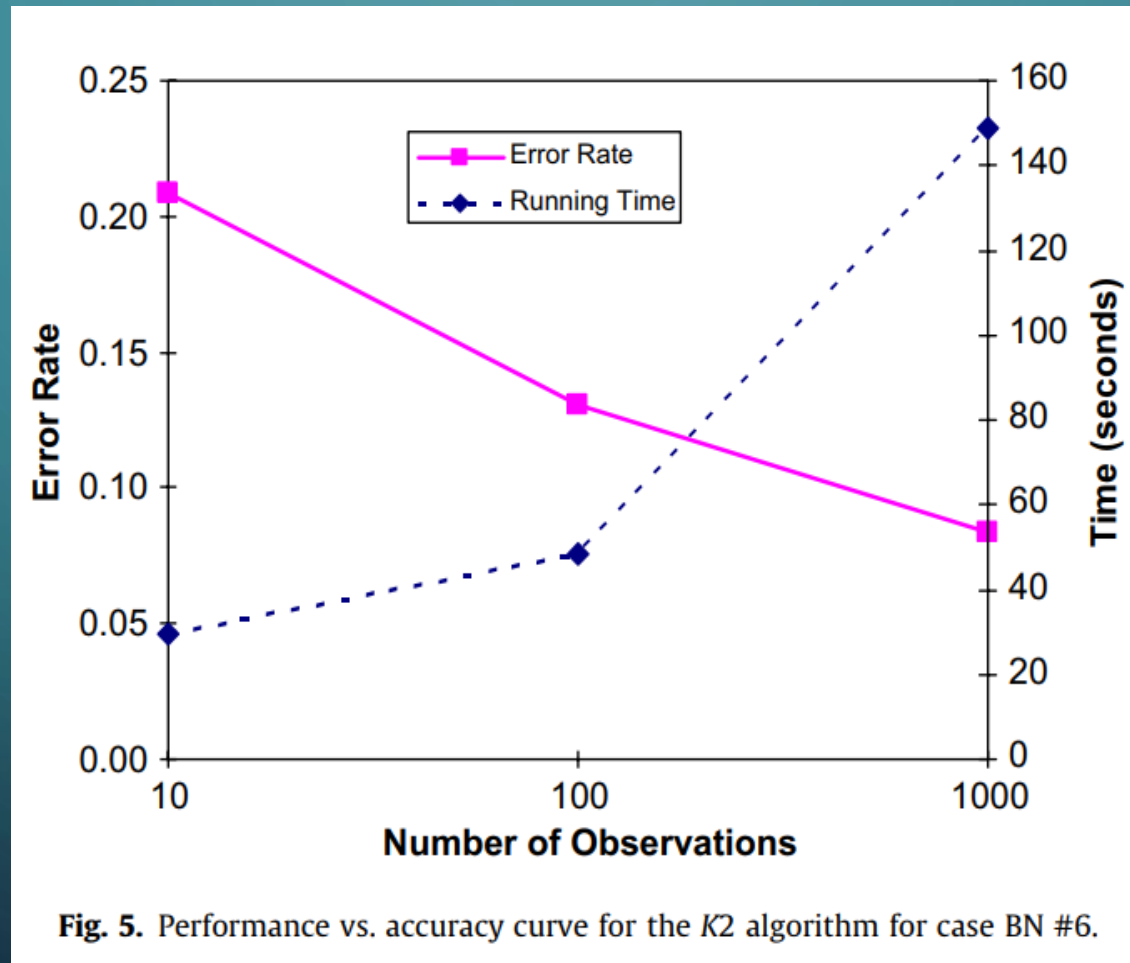


Fig. 4. Accuracy of results in BN construction.



# Error Rate - Time Chart



# Conclusion

# Conclusion

- Numerous method for estimating reliability but challenges still remained
- K2 algorithm:
  - No need to domain expert
  - But needs historical data about the system
  - Efficient for substantially large systems
- Can further be improved when the already existing associations between components are taken in to account(needs a domain expert of the system)

# References

1. Ozge Doguc , Jose Emmanuel Ramirez-Marquez.A generic method for estimating system reliability using Bayesian networks.(February 2009).
2. Christopher M. Bishop.(2006).Pattern Recognition and Machine Learning.
3. Stuart J. Russell and Peter Norvig. Artificial Intelligence A Modern Approach 3th Edition.
4. Helge Langseth , Luigi Portinale. Bayesian networks in reliability.(19 January 2006).
5. Sankaran Mahadevan ,Ruoxue Zhang , Natasha Smith.Bayesian networks for system reliability reassessment.(2001).



The background is a dark teal gradient. In the corners, there are white line-art illustrations of circuit boards or neural networks, with lines and small circles representing nodes.

# THANK YOU