

Mathematical background

Inner product of vectors

standard inner product on \mathbf{R}^n

$$x, y \in \mathbf{R}^n \quad \Rightarrow \quad \langle x, y \rangle = x^T y = \sum_{i=1}^n x_i y_i,$$

Euclidean norm, or ℓ_2 -norm, of a vector $x \in \mathbf{R}^n$

$$\|x\|_2 = (x^T x)^{1/2} = (x_1^2 + \cdots + x_n^2)^{1/2}.$$

$$|x^T y| \leq \|x\|_2 \|y\|_2 \text{ for any } x, y \in \mathbf{R}^n$$

Angle between vectors

$$x, y \in \mathbf{R}^n \quad \Rightarrow \quad \angle(x, y) = \cos^{-1} \left(\frac{x^T y}{\|x\|_2 \|y\|_2} \right)$$

x and y are *orthogonal* if $x^T y = 0$.

Inner product of matrices

trace of a matrix: the sum of its diagonal elements.

standard inner product on $\mathbf{R}^{m \times n}$

$$X, Y \in \mathbf{R}^{m \times n}$$



$$\langle X, Y \rangle = \mathbf{tr}(X^T Y) = \sum_{i=1}^m \sum_{j=1}^n X_{ij} Y_{ij},$$

Frobenius norm of a matrix $X \in \mathbf{R}^{m \times n}$

$$\|X\|_F = (\mathbf{tr}(X^T X))^{1/2} = \left(\sum_{i=1}^m \sum_{j=1}^n X_{ij}^2 \right)^{1/2}.$$

Norms

A function $f : \mathbf{R}^n \rightarrow \mathbf{R}$ with $\mathbf{dom} f = \mathbf{R}^n$ is called a *norm* if

- f is nonnegative: $f(x) \geq 0$ for all $x \in \mathbf{R}^n$
- f is definite: $f(x) = 0$ only if $x = 0$
- f is homogeneous: $f(tx) = |t|f(x)$, for all $x \in \mathbf{R}^n$ and $t \in \mathbf{R}$
- f satisfies the triangle inequality: $f(x + y) \leq f(x) + f(y)$, for all $x, y \in \mathbf{R}^n$

$$f(x) = \|x\| \qquad \|x\|_{\text{symb}} \qquad \mathbf{dist}(x, y) = \|x - y\|$$

unit ball of the norm $\|\cdot\|$

$$\mathcal{B} = \{x \in \mathbf{R}^n \mid \|x\| \leq 1\},$$

Norms (vectors)

sum-absolute-value, or ℓ_1 -norm,

$$\|x\|_1 = |x_1| + \cdots + |x_n|,$$

Chebyshev or ℓ_∞ -norm

$$\|x\|_\infty = \max\{|x_1|, \dots, |x_n|\}.$$

ℓ_p -norm

A family of norms

$$p \geq 1$$

$$\|x\|_p = (|x_1|^p + \cdots + |x_n|^p)^{1/p}$$

Norms (vectors)

quadratic norms.

Another important family of norms

$P \in \mathbf{S}_{++}^n$ define the P -quadratic norm as

$$\|x\|_P = (x^T P x)^{1/2}$$

Norms (Matrices)

common norms on $\mathbf{R}^{m \times n}$

Frobenius norm

sum-absolute-value norm

$$\|X\|_{\text{sav}} = \sum_{i=1}^m \sum_{j=1}^n |X_{ij}|$$

maximum-absolute-value norm

$$\|X\|_{\text{max}} = \max\{|X_{ij}| \mid i = 1, \dots, m, j = 1, \dots, n\}$$

Norms (Matrices)

max- column-sum norm

$$\|X\|_1 = \max_{j=1,\dots,n} \sum_{i=1}^m |X_{ij}|$$

max- row-sum norm

$$\|X\|_\infty = \max_{i=1,\dots,m} \sum_{j=1}^n |X_{ij}|$$

Norms (Matrices)

L2 norm

$$\|X\|_2 = \sigma_{\max}(X) = (\lambda_{\max}(X^T X))^{1/2}$$

Functions

Function notation and continuity

$$f : A \rightarrow B$$

$$f : \mathbf{R}^n \rightarrow \mathbf{R}^m$$

f maps (some) n -vectors into m -vectors

Continuity

whenever the sequence x_1, x_2, \dots

in **dom** f converges to a point $x \in \mathbf{dom} f$, the sequence $f(x_1), f(x_2), \dots$ converges to $f(x)$

A function f is *continuous* if it is continuous at every point in its domain

Derivatives

$$f : \mathbf{R}^n \rightarrow \mathbf{R}^m$$

derivative (or *Jacobian*) of f at x

is the matrix $Df(x) \in \mathbf{R}^{m \times n}$, given by

$$Df(x)_{ij} = \frac{\partial f_i(x)}{\partial x_j}, \quad i = 1, \dots, m, \quad j = 1, \dots, n,$$

If the partial derivatives exist, we say f is differentiable at x .

Derivatives

Gradient

f is
real-valued

$$f : \mathbf{R}^n \rightarrow \mathbf{R}$$

derivative $Df(x)$ is a $1 \times n$ matrix

gradient of the function:

$$\nabla f(x) = Df(x)^T$$

$$\nabla f(x)_i = \frac{\partial f(x)}{\partial x_i}, \quad i = 1, \dots, n.$$

The first-order approximation of f at a point x

$$f(x) + \nabla f(x)^T (z - x)$$

Derivatives

Example:

quadratic function

$$f : \mathbf{R}^n \rightarrow \mathbf{R}$$

$$f(x) = (1/2)x^T P x + q^T x + r$$

$P \in \mathbf{S}^n$, $q \in \mathbf{R}^n$, and $r \in \mathbf{R}$

$$Df(x) = x^T P + q^T$$

$$\nabla f(x) = Px + q$$

Derivatives

Chain rule

$f : \mathbf{R}^n \rightarrow \mathbf{R}^m$ is differentiable at x

$g : \mathbf{R}^m \rightarrow \mathbf{R}^p$ is differentiable at $f(x)$

$$h : \mathbf{R}^n \rightarrow \mathbf{R}^p \quad h(z) = g(f(z))$$

$$Dh(x) = Dg(f(x))Df(x)$$

Special case:

$f : \mathbf{R}^n \rightarrow \mathbf{R}$, $g : \mathbf{R} \rightarrow \mathbf{R}$, and $h(x) = g(f(x))$

$$\nabla h(x) = g'(f(x))\nabla f(x)$$

Second derivative

$$f : \mathbf{R}^n \rightarrow \mathbf{R}$$

second derivative or Hessian matrix $\nabla^2 f(x)$

$$\nabla^2 f(x)_{ij} = \frac{\partial^2 f(x)}{\partial x_i \partial x_j}, \quad i = 1, \dots, n, \quad j = 1, \dots, n,$$

If f is differentiable gradient mapping is the function

$$\nabla f : \mathbf{R}^n \rightarrow \mathbf{R}^n$$

The derivative of this mapping is

$$D\nabla f(x) = \nabla^2 f(x)$$

Second derivative

$$f(x) + \nabla f(x)^T (z - x)$$

second-order approximation of f , at or near x

$$\hat{f}(z) = f(x) + \nabla f(x)^T (z - x) + (1/2)(z - x)^T \nabla^2 f(x) (z - x)$$

Example:

$$f(x) = (1/2)x^T P x + q^T x + r$$



$$P \in \mathbf{S}^n, q \in \mathbf{R}^n, \text{ and } r \in \mathbf{R}$$

$$\nabla f(x) = P x + q$$

$$\nabla^2 f(x) = P$$

Second derivative

Chain rule for second derivative

$f : \mathbf{R}^n \rightarrow \mathbf{R}$, $g : \mathbf{R} \rightarrow \mathbf{R}$, and $h(x) = g(f(x))$

$$\nabla^2 h(x) = g'(f(x)) \nabla^2 f(x) + g''(f(x)) \nabla f(x) \nabla f(x)^T$$

Linear Algebra

Vector space

Linear Independence of vectors

$$v_1, v_2, \dots, v_n \Leftrightarrow \sum_{i=1}^n \alpha_i v_i = 0 \Rightarrow \alpha_i = 0$$

Vector space

The set V is a vector space if

for $\forall x, y \in V$ and $\forall \alpha, \beta \in R$



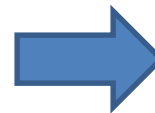
$$\alpha x + \beta y \in V$$

Base of a vector space

$\{v_1, v_2, \dots, v_k\} \subseteq V$ is a base for vector space V if

● v_1, v_2, \dots, v_k are linear independent

● $\forall x \in V, \exists \alpha_1, \alpha_2, \dots, \alpha_k \in R \Rightarrow x = \sum_{i=1}^k \alpha_i v_i$



$$\dim V = k$$

Rank and range of matrices

Rank of A

$$A \in \mathbf{R}^{m \times n}$$

The number of independent columns or the number of independent rows

The rank of A can never be greater than the minimum of m and n.

A has full rank if $\text{rank } A = \min\{m, n\}$.

Range of A

$$\mathcal{R}(A) = \{Ax \mid x \in \mathbf{R}^n\}$$

The range $\mathcal{R}(A)$ is a subspace of \mathbf{R}^m

Its dimension is the rank of A

Kernel of matrices

Nullspace or kernel of a matrix

The *nullspace* (or *kernel*) of A , denoted $\mathcal{N}(A)$, is the set of all vectors x mapped into zero by A :

$$\mathcal{N}(A) = \{x \mid Ax = 0\}.$$

The nullspace is a subspace of \mathbf{R}^n

Eigenvalue and vector

λ is an eigenvalue of matrix A if there exists a non-zero vector x such that

$$A \in \mathbb{R}^{n \times n}$$

$$Ax = \lambda x$$

Eigenvectors are not unique

Eigenvalues can be real or complex

the roots of the characteristic polynomial
 $\det(A - \lambda I)$

All eigenvalues of symmetric matrices are real

for $\lambda_i \neq \lambda_j$, their corresponding eigenvectors x_i and x_j are orthogonal

Eigenvalue and vector

$$\lambda_1 \geq \lambda_2 \geq \cdots \geq \lambda_n \qquad \lambda_1(A) = \lambda_{\max}(A) \qquad \lambda_n(A) = \lambda_{\min}(A)$$

$$\det A = \prod_{i=1}^n \lambda_i$$

$$\mathbf{tr} A = \sum_{i=1}^n \lambda_i$$

Symmetric eigenvalue decomposition

$A \in \mathbf{S}^n$, *i.e.*, A is a real symmetric $n \times n$ matrix

$$A = Q\Lambda Q^T$$

$$\Lambda = \mathbf{diag}(\lambda_1, \dots, \lambda_n)$$

The columns of Q form an orthonormal set of eigenvectors of A . $Q^T Q = I$

spectral decomposition or eigenvalue decomposition of A .

Singular value decomposition(SVD)

$A \in \mathbf{R}^{m \times n}$ with $\text{rank } A = r$.

$$A = U\Sigma V^T$$

$U \in \mathbf{R}^{m \times r}$ satisfies $U^T U = I$, $V \in \mathbf{R}^{n \times r}$ satisfies $V^T V = I$

$\Sigma = \text{diag}(\sigma_1, \dots, \sigma_r) \quad \sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_r > 0$

- ✓ columns of U are called left singular vectors of A
- ✓ columns of V are right singular vectors
- ✓ the numbers σ_i are the singular values.

SVD

singular value decomposition of a matrix A is closely related to the eigenvalue decomposition of $A^T A$.

$$A = U \Sigma V^T \quad \Rightarrow \quad A^T A = V \Sigma^2 V^T = \begin{bmatrix} V & \tilde{V} \end{bmatrix} \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} V & \tilde{V} \end{bmatrix}^T$$

where \tilde{V} is any matrix for which $\begin{bmatrix} V & \tilde{V} \end{bmatrix}$ is orthogonal

eigenvalue decomposition of $A^T A$

- ✓ its nonzero eigenvalues are the singular values of A squared
- ✓ associated eigenvectors of $A^T A$ are the right singular vectors of A .
- ✓ A similar analysis of AA^T