

chapter 4

- thread \rightarrow basic unit of CPU utilization

context

\hookrightarrow Private: thread ID, stack, register set, Program counter

\hookrightarrow shared with other threads of the same process:

code, data, resources (memory and I/O)

- single threaded process \equiv heavy weight
- use processes instead of threads \Rightarrow overhead and time consuming
- in RPC the server creates a thread for each request

Adv \rightarrow responsiveness: allows a program to ~~remain~~ continue running even if part of it is blocked or running a lengthy operation \Rightarrow UI

\hookrightarrow resource sharing: have several threads within the same address space sharing code, data and resources

\hookrightarrow economy: context switch between threads is faster than processes

\hookrightarrow scalability: threads may be running in parallel on processing cores

* Multicore Programming

- systems with multiple cores across or within CPU chips \Rightarrow Multicore

Multicore Programming \rightarrow improves concurrency \neq Parallelism

\hookrightarrow more efficient use of multiple cores

- it's possible to have concurrency without parallelism.
- parallelism \rightarrow data parallelism: distributing data across cores executing the same operation
 \hookrightarrow task // : distributing different operations across cores

• Amdahl's law

S: the portion of the application that must be performed serially

N: number of processing cores

- $N \rightarrow \infty \Rightarrow \text{speed up} \leq \frac{1}{S}$

$$\Rightarrow \text{Speed up} \leq \frac{1}{S + \frac{(1-S)}{N}}$$

* Programming challenges

- application programmers must design multithreaded programs
- O.S. designers must write algorithms to use multiple cores

1. Identifying tasks: Find areas of app that can be divided into separate concurrent tasks

2. Balance: Find valuable tasks and assigning cores to them

3. Data splitting: between tasks running on different cores

4. Data dependency: Synchronize task so that one can use the result of others

5. Testing & debugging: controlling execution paths

* Multithreading Models

threads $\begin{cases} \text{kernel threads} \\ \text{user} \end{cases}$

- Many-to-one model \rightarrow thread management done by thread library in user-space \Rightarrow efficient

\rightarrow the entire process will block if a thread makes a blocking system call

\rightarrow multiple threads may not run in parallel

\rightarrow used in few systems (Solaris & Green threads)

- one-to-one model \rightarrow more concurrency than many-to-one

disadv \rightarrow overhead by creating kernel threads \Rightarrow restrict # of threads

\rightarrow linux and windows family

- Many-to-many model \rightarrow Multiplexing

\rightarrow # of threads depends on app and machine

\rightarrow more concurrency than many-to-one (sufficient number of threads)

\rightarrow user-thread blocking solved by creating new kernel threads

\rightarrow user thread bound to kernel thread \Rightarrow two-level model

allowing multitasking to be

done at the user-level

* Thread state → spawn

↳ blocked: waiting for an event

ready queue

↳ unblocked: ↳ done. thread is moved to the ✓

↳ finish: thread's register context and stacks are deallocated

* Thread local storage (TLS)

- allows each thread to have its own copy of data
- useful when you don't have control over thread's creation (thread pool)
- different from local variables and similar to static data
- visible across function invocations
- unique to each thread

* Thread cancellation → terminating a thread before it has completed
target thread ←

1. asynchronous: one thread immediately terminates target thread

2. deferred: target thread periodically checks whether it should be terminated. → flag checking

→ may not free a necessary system-wide resource.

* Linux threads → tasks instead of threads

↳ thread creation using clone() system call

↳ flags control behaviour over address space of parent