Antonio Pucciarelli

Politecnico di Milano

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- 2 Mean Line
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Initial conditions & constraints

Inlet conditions

- $P_{T0} = 1bar$
- $T_{T0} = 300K$

Constraints

- $r_{max} = 0.45m$
- $\beta_{TT} = 1.45$
- $\dot{m} = 100 \frac{kg}{s}$
- max η

Due to the **course track** and **preference**, the turbomachinery design will be on an **axial** compressor.

2 Mean Line

Problem setup Main design quantities $V_{t_{mean}}$, $V_{a_{mean}}$, U_{mean} & velocity triangles

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- 2 Mean Line
 - Problem setup

Main design quantities

Mean Line

0.0000000000

 $V_{t_{mean}}$, $V_{a_{mean}}$, U_{mean} & velocity triangles

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Problem setup: hypothesis

Hypothesis

- not using an inlet guide vane for simplicity of design
- keeping, in the similarity/adimensional analysis of the compressor, $V_{a_{mean}}$ constant¹
- keeping the blade height, b_0 , **constant** both in rotor and stator
- using a mixed vortex model for the rotor velocity triangles
- using a second order function for the stator velocity triangles
- neglecting inlet entropy generation and assuming rotor inlet quantities constant
- shrouding at blade tip not present
- rotor-stator losses neglected

 $^{^{1}\}dot{m}$ corrections will be made later on in the **radial equilibrium** solution.

Main procedural steps:

- λ and ψ computation from χ and V_{t0}
- ϕ and η computation
- $V_{a_{mean}}$ and L_{eu} computation from ϕ , eta_{TT} and η
- computing mean velocity triangles, using the above hypothesis
- computing mean thermodynamic quantities
- computing blade height



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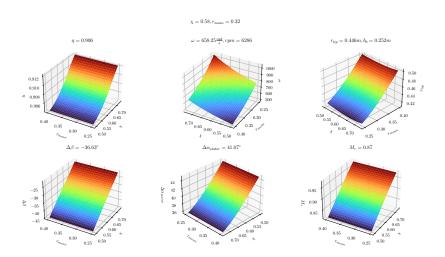
Problem setup

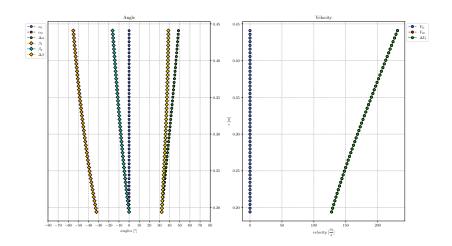
Main design quantities

 $V_{t_{mean}}$, $V_{a_{mean}}$, U_{mean} & velocity triangles

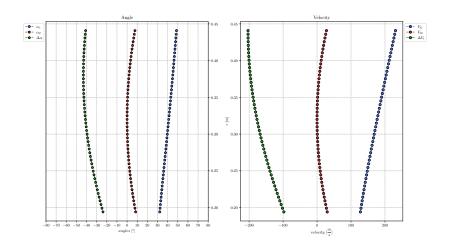
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Graph analysis: **stator** $\alpha \& V_t$





From the previous graphs:

- $^{2}\gamma = 0.58$
- $r_{mean} = 0.32m$
- $\frac{V_{t0}}{U_{t0}} = 0$

Taking into account the previous modeling **hypothesis**:

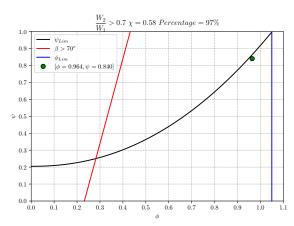
$$\lambda = \left(1 - \chi - rac{V_{t0}}{U_{mean}}
ight) \cdot 4$$
 $\psi = rac{\lambda}{2}$

$${}^{2}\chi = \frac{h_{1} - h_{0}}{h_{T1} - h_{T0}} = \frac{\frac{W_{0}^{2} - \frac{W_{1}^{2}}{2}}{\frac{2}{U_{mean}(V_{t1} - V_{t0})}} = \frac{\frac{W_{2}^{2}}{\frac{2}{2}} + \frac{W_{1}^{2}}{\frac{2}{2}} - \frac{W_{3}^{2}}{\frac{2}{2}} - \frac{W_{1}^{2}}{\frac{2}{2}}}{\frac{2}{U_{mean}(V_{t1} - V_{t0})}} = \frac{\frac{W_{2}^{2} - \frac{W_{1}^{2}}{2}}{\frac{2}{2}} - \frac{W_{1}^{2}}{\frac{2}{2}}}{\frac{W_{1}^{2} - \frac{W_{1}^{2}}{2}}{\frac{2}{2}}} = \frac{W_{1}^{2} - \frac{W_{1}^{2}}{2}}{U_{mean}(V_{t1} - V_{t0})}$$

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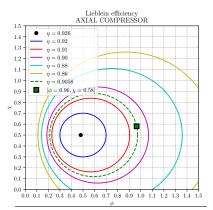


From [Aun04, Sec. 10.4] it is imposed that $\frac{W_2}{W_1} \ge 0.7$ with a *safety* margin of 3%. ϕ_{lim} line is related to the **surge safety margin**.





 η is computed from an **Lieblein** efficiency chart³ given ϕ and χ . This parameter will be used for the computation of L_{eu} given the β_{TT} target.



$$egin{align} L_{is} &= rac{\gamma}{\gamma} rac{R}{T} \ T_{T0} \ (eta_{TT}^{rac{\gamma-1}{\gamma}} - 1) \ L_{eu} &= rac{L_{is}}{\eta} \ \end{array}$$



³This chart has been interpolated from the course slides charts.

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$$egin{aligned} U_{mean} &= rac{L_{eu}}{\psi} \ V_{a_{mean}} &= \phi \ U_{mean} \ U_{t1_{mean}} &= U_{t1_{mean}} \ V_{t1_{mean}} &= U_{t0_{mean}} \ V_{t0_{mean}} \ V_{t0_{mean}} \ \end{array}$$

- $\Delta V_{t_{mean}}$ computation allows us to get a *first sketch* of the **velocity triangles**⁴ using ϕ , ψ and L_{eu}^{5} definitions. V_{a} is assumed **constant** all through the stage.
- The first analysis results are stored in compressor_0.58_0.32_45_35.txt



References

⁴Mixed vortex model and second order function based.

 $^{^{5}}L_{eu} = U_{1} V_{t1} - U_{0} V_{t0}$

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Losses modeling

Profile losses
Compressibility losses
Secondary flow losses
End wall losses
Shock losses
Tip leackage losses
adial equilibrium





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The profile losses used are related to the **Leiblein modeling** approach⁶.

The model is based on the equivalent diffusion factor⁷, D_{eq} :

$$\begin{split} \frac{W_{max}}{W_1} &= 1.12 + 0.61 \ \frac{\cos(\beta_1)^2}{\sigma} \cdot \frac{r_1 \ V_{t1} - r_2 \ V_{t2}}{r_1 \ V_{a1}} \\ D_{eq} &= \frac{W_{max}}{W_1} \cdot \frac{W_1}{W_2} \end{split}$$

 D_{eq} will be used for the computation of $\bar{\omega}_{profile}$ as:

$$\bar{\omega}_{\textit{profile}} = \frac{0.004\,\left(1 + 3.1\,\left(D_{\textit{eq}} - 1\right)^2 + 0.4\,\left(D_{\textit{eq}} - 1\right)^8\right)\,2\,\,\sigma}{\cos(\beta_2)\,\left(\frac{W_1}{W_2}\right)^2}$$

⁶The following equations are interpolated data from [Aun04, Sec. 6.4].

⁷It describes how important is the **velocity change** along the blade. It can be seen as an *indicator* of the **blade loading**.

These losses can be seen as a **correction** of the **profile** losses due to the compressibility of the gas along its *journey* in the stage.

The correction refers to a Leiblein correction model that uses the **positive** and **negative** blade section incidence angle⁸, i_c and i_s .

These new stall incidence angles will build a new mean incidence angle, i_m , that can be seen as the **optimum** incidence angle related to the inlet Mach conditions⁹.

 $^{^8}i_c$ and i_s are related to the total pressure losses, $\bar{\omega}_c$ and $\bar{\omega}_s$, that are **twice** the minimum total pressure loss, $\bar{\omega}$, obtained at the **design incidence angle**, i^* .

⁹The implemented model follows [Aun04, Sec. 6.6]

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 $\bar{\omega}_{compressibility}$ setup:

• R_c and R_s computation¹⁰:

$$R_c = 9 - \left[1 - \left(\frac{30}{\beta_1}\right)^{0.48}\right] \frac{\theta}{8.2}$$

$$R_s = 10.3 + \left(2.92 - \frac{\beta_1}{15.6}\right) \frac{\theta}{8.2}$$

• i_c and i_s computation due to **compressibility** effects:

$$i_c = i^* - \frac{R_c}{1 + 0.5 M_1^3}$$
 $i_s = i^* + \frac{R_s}{1 + 0.5 (K_{sh} M_1)^3}$

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 $^{^{10}}R_c$ and R_s are range indices for the computation of i_c and i_s .

Compressibility losses – III

- i_m computation¹¹: $i_m = i_c + (i_s i_c) \frac{R_c}{R_c + R_c}$
- $\bar{\omega}_m$ computation: $\bar{\omega}_m = \bar{\omega}_{profile} \left[1 + \frac{\left(i_m i^*\right)^2}{R_s^2} \right]$
- $\bar{\omega}_{compressibility}$ computation¹²:

$$\bar{\omega}_{compressibility} = \bar{\omega}_m + \bar{\omega}_m \left[\frac{i - i_m}{i_c - i_m} \right]^2, \text{ if } i \leq i_m$$

$$\bar{\omega}_{compressibility} = \bar{\omega}_m + \bar{\omega}_m \left[\frac{i - i_m}{i_s - i_m} \right]^2, \text{ if } i \geq i_m$$

 $^{^{11}}i_m$ is the incidence angle at wich corresponds, having accounted the compressibility, the minimum pressure loss, $\bar{\omega}_m$.

 $^{^{12}}$ After having computed i_c , i_s , i_m and $\bar{\omega}_m$. $\bar{\omega}_{compressibility}$ is a function of i. In the total pressure losses study: $\bar{\omega}_{compressibility} = \bar{\omega}_{compressibility_{(i*)}}$.

Secondary flow losses

These losses are relative to the **secondary flow** inside the compressor and are usually greater than the other losses. These losses are related to eddies generated with the blade-flow interaction and streamlines displacement due to the presence of pressure gradients.

These losses are computed with **Howell**'s model [Aun04, Ch. 6]¹³:

$$egin{aligned} ar{eta} &= rac{\mathsf{arctan}(\mathsf{tan}(eta_1) + \mathsf{tan}(eta_2))}{2}; \ C_L &= 2 \; cos(ar{eta}) \cdot rac{\mathsf{tan}(eta_1) - \mathsf{tan}(eta_2)}{\sigma}; \end{aligned}$$

$$C_D = 0.18 C_I^2;$$
 III

$$\bar{\omega}_{secondary} = C_D \ \sigma \cdot \frac{\cos(\beta_1)^2}{\cos(\bar{\beta})^3};$$
 loss computation

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¹³Howell computed a secondary flow loss model that is automatically embedded into $\bar{\omega}_{profile}$: this model is used for the **estimation** of the stator/rotor

These losses are related the interaction between the flow and the **compressor case**. They are *lower* than the **secondary flow** losses. It has been used a simple and fast relation made by **Howell** [Aun04, Ch. 6]¹⁴:

$$C_D=0.02~rac{s}{b_0}$$

$$ar{\omega}_{endWall}=C_D~\sigma\cdotrac{cos(eta_1)^2}{cos(ar{eta})^3}; \qquad \qquad ext{loss computation}$$



¹⁴This loss is kept into account in the **blade numbering** study.

Shock losses – L

The **relative** Mach number at the rotor inlet is slightly above sonic speed; a shock wave will be present at the rotor tip. From [MF20], shock pattern is related to Mach number and airfoil shape.

The **shock** losses modeling is related to **König losses** modeling approach. This model describes a 2 shock waves loss using a **single normal shock** with respect to a computed Mach number, M_{in} .

König model depends mainly on blade deflection angle, θ , and relative inlet Mach¹⁵, M_1 .



¹⁵Leading edge radius is not taken into account due to the approximated nature of the model.

Swan and Miller, [Aun04, Sec. 6.7], derived a shock loss formulation from König model.

The following are the steps made for the computation of the **shock** loss, $\bar{\omega}_{shock}$, at each blade section:

• computation of the **expansion wave** angle, ϕ :

$$\phi = \frac{s \cos(\psi)}{s \sin(\psi) R_u}$$
; where $\psi = \psi_{(\beta_1, \gamma, \theta)}$

computation of W_s and M_s using **Prandtl-Meyer** expansion:

$$\phi = \int_{W_1}^{W_s} \sqrt{M^2 - 1} \; \frac{dW}{W}$$

- M_{in} computation: $M_{in} = \sqrt{M_1 M_s}$
- normal shock solution and computation of ΔP_T
- from ΔP_T , computation of $\bar{\omega}_{shock}$

Again these losses are computed from [Aun04, Sec. 6.9]. The main concept is: computing a **total** blade pressure loss and **assuming linear distribution** of losses from the hub to the tip¹⁶.

$$\begin{split} \tau &= \pi \ \delta_c \left[r_1 \rho_1 V_{a1_{mean}} + r_2 \rho_2 V_{a2_{mean}} \right] \left[r_2 V_{t2_{mean}} - r_1 V_{t1_{mean}} \right] \\ \Delta P &= \frac{\tau}{Z \ r_{tip} \delta_c \ c \ cos(\gamma)} \\ U_c &= 0.816 \frac{\sqrt{\frac{2\Delta P}{\rho_{mean}}}}{N_{row}^{0.2}} \\ \dot{m_c} &= \rho_{mean} \ U_c \ Z \ \delta_c \ c \ cos(\gamma) \\ \Delta P_T &= \frac{\Delta P \ \dot{m_c}}{\dot{m}} \end{split}$$

 ΔP_T is the **overall** total pressure loss due to **tip leackage**.

 $^{^{16}}Z$ is the number of blades. δ_c is the tip clearance. \textit{N}_{row} is the number of blade rows in the compressor.

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The **radial equilibrium** equation: $\frac{\partial h_t}{\partial r} = T \frac{\partial s}{\partial r} + V_a \frac{\partial V_a}{\partial r} + V_t \frac{\partial r V_t}{\partial r}$ is converted into, for the exit station¹⁷ of the blade, a **1st order ODE**:

$$\begin{split} -\frac{1}{2}\frac{\partial V_{a2}^2}{\partial r} + \frac{V_{a2}^2}{2\frac{\partial s_2}{c_P}}\frac{\partial s_2}{\partial r} &= -c_P\frac{\partial T_{T1}}{\partial r} - \omega \frac{\partial rV_{t2}}{\partial r} + \omega \frac{\partial rV_{t1}}{\partial r} \\ + T_{T1}\frac{\partial s_2}{\partial r} + \frac{\omega}{c_P}rV_{t2}\frac{\partial s_2}{\partial r} - \frac{\omega}{c_P}rV_{t1}\frac{\partial s_2}{\partial r} - \frac{1}{2\frac{c_P}{c_P}}V_{t2}^2\frac{\partial s_2}{\partial r} + \frac{V_{t2}}{r}\frac{\partial rV_{t2}}{\partial r} \end{split}$$

- The **ODE** will be solved for V_{a2}^2
- s_2 is computed from $\sum_i \bar{\omega}_i$ treated earlier
- ω , V_{t1} , V_{t2} and T_{T1} are known



¹⁷1 is the blade inlet station and 2 is the blade outlet section.

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Δs computation

From pressure loss coefficients it is possible compute the **outlet** total pressure as:

$$P_{T2,r} = P_{T1,r} + \sum_{i} \bar{\omega}_{i} (P_{T1,r} - P_{1,r})$$

The **entropy variation** is computed as:

$$\Delta s = s_2 - s_1 = c_P \log \frac{T_{T2,r}}{T_{T1,r}} - R \log \frac{P_{T2,r}}{P_{T1,r}}$$

Frames

- $T_{T2} = T_{T1}$ in stators and $T_{T2,r} = T_{T1,r}$ in rotors
- $\bar{\omega}_*$ have to be computed using **relative** quantities for **rotors** and absolute quantities for stators

•
$$T_{T,r} = T + \frac{W^2}{2c_P} = T_T + \frac{W^2 - V^2}{2c_P}$$

•
$$P_{T,r} = P_T \left(\frac{T_{T,r}}{T_T}\right)^{\frac{\gamma}{\gamma-1}}$$



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Blade shape setup

The **Leiblein model** from [Aun04, Ch. 6] has been used for the blade shape computation.

NACA – 65 profile has been chosen for the blade generation 18 .

The **main contraints** are: $\frac{t_b}{c} \approx 0.1$ and σ is related just to s^{19} .

Due to the many possible blade configurations, an **optimization** procedure has been used for the computation of i^* , δ and θ .

Each section airfoil shape is **computed** from θ and NACA – 65 C_{I0} surface coordinates.

 $^{19} rac{t_b}{c} pprox 0.1$ allows setting $K_{sh} pprox 0.1$. The blade chord, c, is set up as constant during the **blade numbering** study: using $AR = \frac{b_0}{c}$.

¹⁸Due to the low tip sonic Mach number it has been chosen to use this profile as well for the blade tip instead of a supersonic adapted profile shape.

The **incidence angle**, i^* , is computed using:

$$\begin{split} \mathcal{K}_{t,i} &= \left(10 \ \frac{t_b}{c}\right)^q \text{; where } q = \frac{0.28}{0.1 + \left(\frac{t_b}{c}\right)^{0.3}} \\ (i_0^*)_{10} &= \frac{\beta_0^p}{5 + 46 \cdot e^{-2.3\sigma}} - 0.1 \ \sigma^3 \ e^{\frac{\beta_0 - 70}{4}} \text{; where } p = 0.914 + \frac{\sigma^3}{160} \\ n &= 0.025\sigma - 0.06 - \frac{\left(\frac{\beta_0}{90}\right)^{1 + 1.2\sigma}}{1.5 + 0.43\sigma} \\ i^* &= \mathcal{K}_{sh} \ \mathcal{K}_{t,i} \ (i_0^*)_{10} + n \ \theta \end{split}$$



The **deviation angle**, δ , is computed using:

$$K_{t,\delta} = 6.25 \frac{t_b}{c} + 37.5 \left(\frac{t_b}{c}\right)^2$$

$$(\delta_0^*)_{10} = 0.01 \sigma \beta_0 + (0.74 \sigma^{1.9} + 3\sigma) \left(\frac{\beta_0}{90}\right)^{1.67 + 1.09\sigma}$$

$$b = 0.9625 - 0.17 \frac{\beta_0}{100} - 0.85 \left(\frac{\beta_0}{100}\right)^3$$

$$m=rac{m_{1.0}}{\sigma^b}$$
 ; where $m_{1.0}=0.17-0.0333rac{eta_0}{100}+0.333igg(rac{eta_0}{100}igg)^2$

$$\delta = K_{sh} K_{t,\delta} (\delta_0^*)_{10} + m \theta$$

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θ computation

Starting from the **known** flow deflection angle²⁰, ε , it is necessary to compute:

$$\theta = \varepsilon - i^* + \delta$$

Since i^* and δ are functions of θ , the computation of θ is made by an **iterative process**:

$$\theta = \varepsilon - i_{(\theta)}^* + \delta_{(\theta)}$$

Once found θ , the **total pressure loss** coefficients, $\bar{\omega}_*$, are computed.



 $^{^{20}}arepsilon=eta_{inlet}-eta_{outlet}.$ eta_1 and eta_2 change with respect to the axial speed.

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 turboLIB



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turboLIB

Blade number NISRE .stl & .scad generatio





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The preliminary compressor design model program turboLIB can be downloaded from GitHub.

Main objects and modules

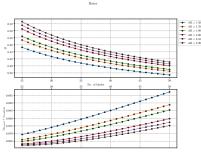
- turboClass.turboBlade.blade: blade object
- turboCoeff: engineering coefficients module
 - losses: losses modeling
 - similarity: adimensional analysis
 - lieblein: blade modeling
- geometry.bladeGeometry.geometryData: airfoil object

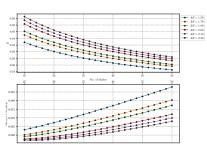


Blade number

In order to define a proper number of blades for the rotor and the stator, Howell's relations have been used for the estimation of the losses. These relations, [Aun04, Ch. 6], are:

- $\bar{\omega}_{profile+secondary}$, this is a relation that takes into account profile and 3D losses
- $\bar{\omega}_{endWall}$, this is previous expalined **end wall** loss





The NISRE is solved through a double nested loop:

- continuity loop. Inside the continuity loop the scipy.integrate.odeint function is used for the solution of the V_{a2}^2 ODE.
- entropy loop. Inside the entropy loop the scipy.optimize.minimize function is used for the computation of the blade shape.



At the end of the NISRE, all the main blade quantities are avaliable for the **generation** of the **3D geometry**. This geometry can be converted into a .stl file that can be used in OpenFOAM for the flow properties study. In addition a .scad file is made for understanding position and checking possible contacts between rotor and stator blades.

[Bas06] suggested that a good distance between rotor and stator blades is half of the rotor chord²¹.



 $^{^{21}}$ In the radial equilibrium study losses between rotor and stator blades are **neglected**.

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turboLIB

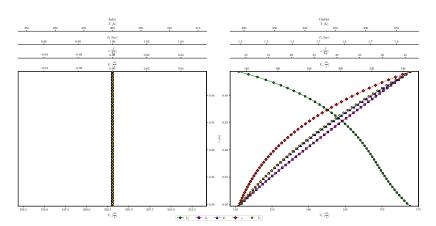
Results

NISRE and main quantities Efficiency



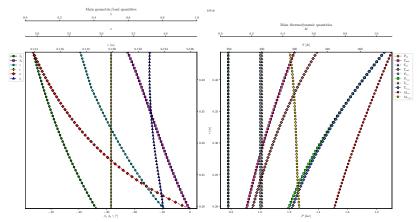
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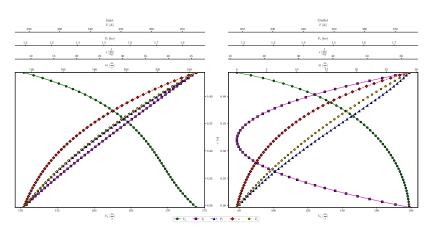


Rotor equilibrium results: main quantities



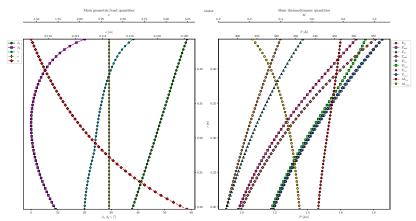


Stator equilibrium results: NISRE



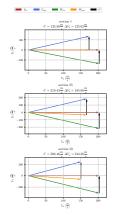


Stator equilibrium results: main quantities



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- Inlet: axial velocity
- Outlet: mixed vortex model



- Inlet: mixed vortex model
- Outlet: second order function

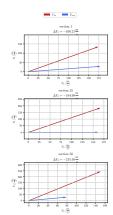


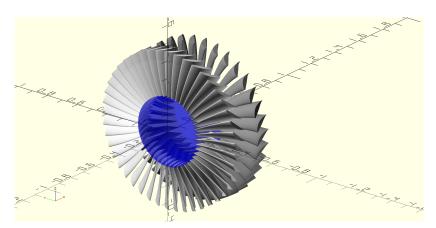






Figure 2: Stator blade.







The **rotor** efficiency is computed with:

$$\eta_{is_{rotor}} = rac{W_1^2 - W_{2_{is}}^2}{W_1^2 - W_2^2}$$

The **stator** efficiency is computed with:

$$\eta_{is_{stator}} = rac{\Delta h_{is}}{\Delta h_{real}}$$

The modeling results are stored into compressor_0.58_0.32_45_35.txt.



- [Aun04] Ronald H. Aungier. "Axial-Flow Compressors: a Strategy for Aerodynamic Design and Analysis". In: *Appl. Mech. Rev.* 57.4 (2004).
- [Bas06] Erian A. Baskharone. *Principles of turbomachinery in air-breathing engines*. Cambridge University Press, 2006.
- [MF20] Marco Manfredi and Fabrizio Fontaneto. "Transonic Axial Compressors Loss Correlations: Part I—Analysis and Update of Loss Models". In: Turbo Expo: Power for Land, Sea, and Air. Vol. 84065. American Society of Mechanical Engineers. 2020, V02AT32A029.



Antonio Pucciarelli

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