

# Introduction to Deep Learning (CS474)

## Lecture 15

# Outline

- **Module 2**
  - More on Convolution

# Strided Convolution

2 <sup>3</sup>	3 <sup>4</sup>	7 <sup>4</sup>	4	6	2	9
6 <sup>1</sup>	6 <sup>0</sup>	9 <sup>2</sup>	8	7	4	3
3 <sup>-1</sup>	4 <sup>0</sup>	8 <sup>3</sup>	3	8	9	7
7	8	3	6	6	3	4
4	2	1	8	3	4	6
3	2	4	1	9	8	3
0	1	3	9	2	1	4

7x7

\*

3	4	4
1	0	2
-1	0	3

3x3

Stride = 2

=

91		

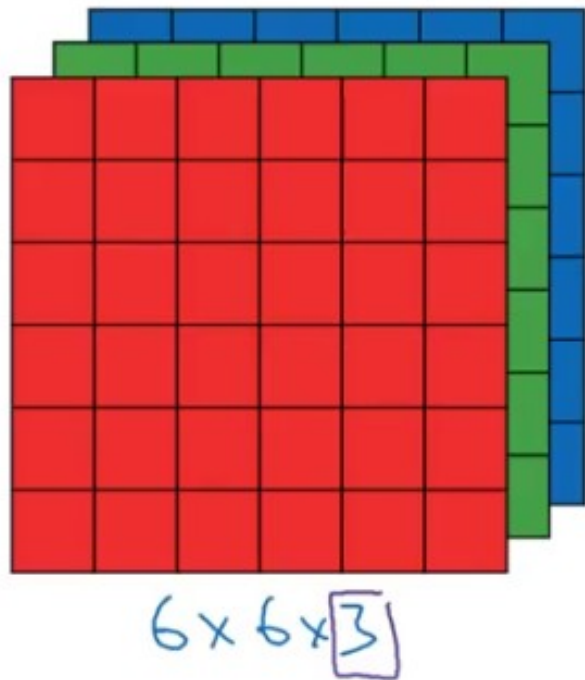
# Strided Convolution

$n \times n$  image       $f \times f$  filter

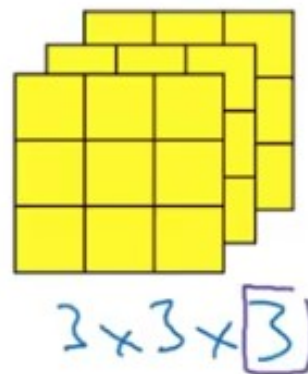
padding  $p$       stride  $s$

$$\left\lfloor \frac{n+2p-f}{s} + 1 \right\rfloor \times \left\lfloor \frac{n+2p-f}{s} + 1 \right\rfloor$$

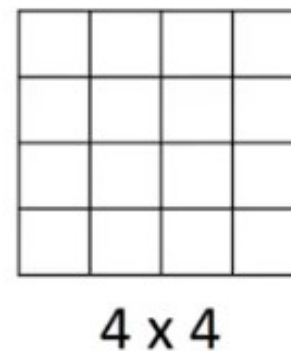
# Convolution over Volumes



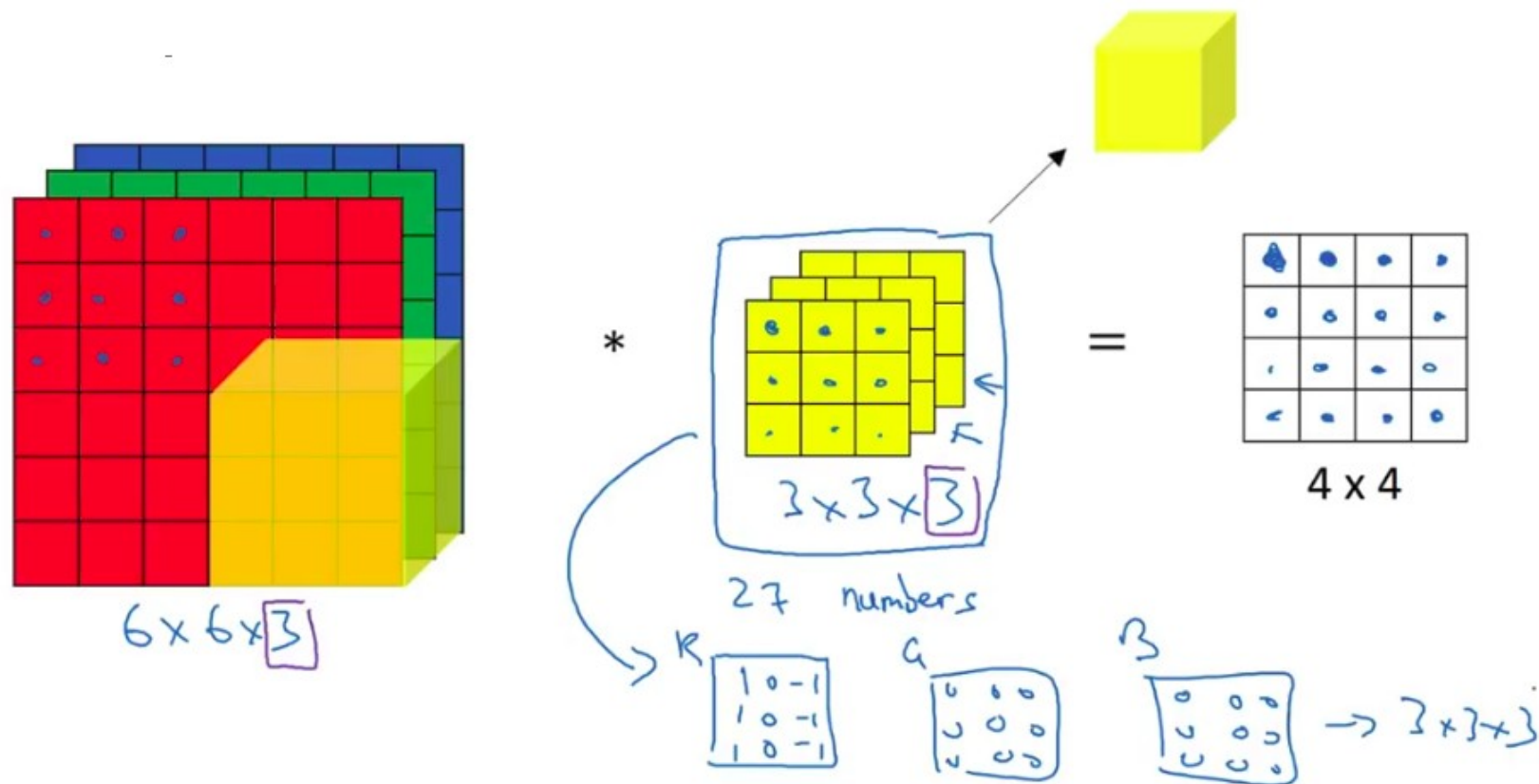
\*



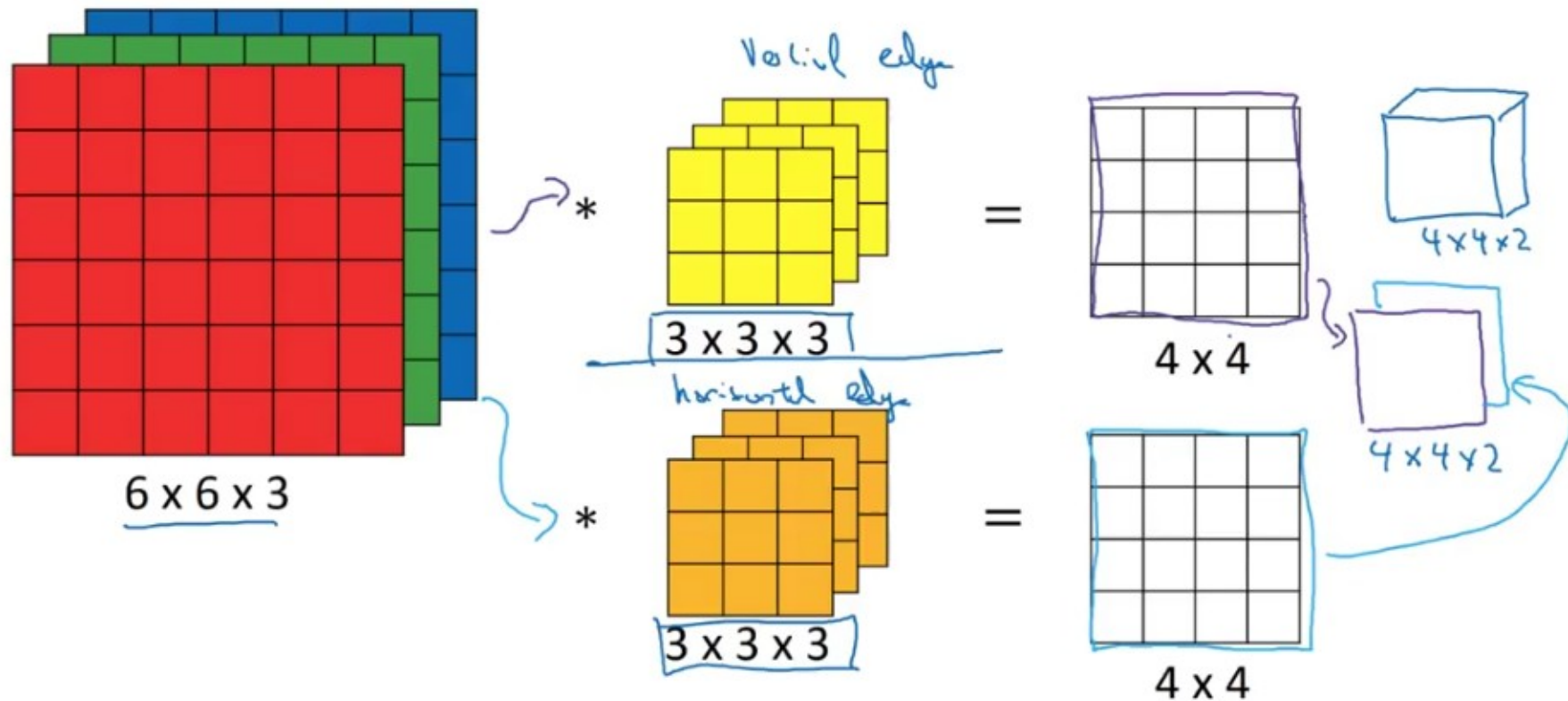
=



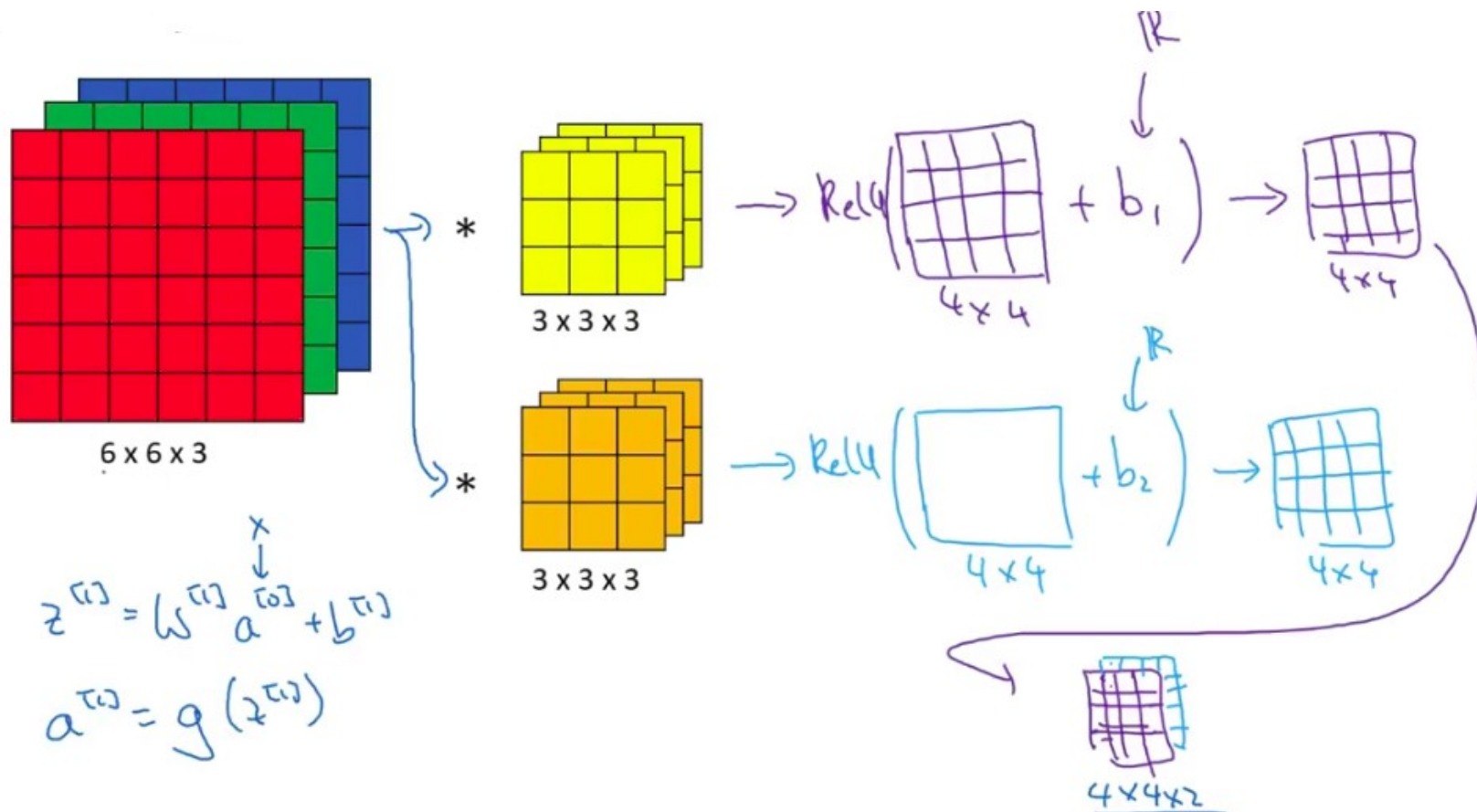
# Convolution over Volumes



# Convolution over Volumes (Multiple Filters)



# One Layer of a Convolutional Net





# Summary of Notation

If layer l is a convolution layer:

$f^{[l]}$  = filter size

$p^{[l]}$  = padding

$s^{[l]}$  = stride

Input:  $n_H^{[l-1]} \times n_W^{[l-1]} \times n_C^{[l-1]} \leftarrow$

Output:  $n_H^{[l]} \times n_W^{[l]} \times n_C^{[l]}$

# Summary of Notation

If layer l is a convolution layer:

$f^{[l]}$  = filter size

$p^{[l]}$  = padding

$s^{[l]}$  = stride

Input:  $n_H^{[l-1]} \times n_W^{[l-1]} \times n_C^{[l-1]} \leftarrow$

Output:  $n_H^{[l]} \times n_W^{[l]} \times n_C^{[l]}$

$$n_H^{[l]} = \left\lfloor \frac{n_H^{[l-1]} + 2p^{[l]} - f^{[l]}}{s^{[l]}} + 1 \right\rfloor$$

# Summary of Notation

If layer l is a convolution layer:

$f^{[l]}$  = filter size

$p^{[l]}$  = padding

$s^{[l]}$  = stride

$n_c^{[l]}$  = number of filters

Each filter is:  $f^{[l]} \times f^{[l]} \times n_c^{[l]}$

Activations:  $a^{[l]} \rightarrow n_H^{[l]} \times n_W^{[l]} \times n_c^{[l]}$

Input:  $n_H^{[l-1]} \times n_W^{[l-1]} \times n_c^{[l-1]}$   $\leftarrow$

Output:  $n_H^{[l]} \times n_W^{[l]} \times n_c^{[l]}$   $\leftarrow$

$$n_H^{[l]} \times n_W^{[l]} = \left\lfloor \frac{n_H^{[l-1]} + 2p^{[l]} - f^{[l]}}{s^{[l]}} + 1 \right\rfloor \times \left\lfloor \frac{n_W^{[l-1]} + 2p^{[l]} - f^{[l]}}{s^{[l]}} + 1 \right\rfloor$$

# Summary of Notation

If layer l is a convolution layer:

$f^{[l]}$  = filter size

$p^{[l]}$  = padding

$s^{[l]}$  = stride

$n_c^{[l]}$  = number of filters

→ Each filter is:  $f^{[l]} \times f^{[l]} \times n_c^{[l-1]}$

Activations:  $a^{[l]} \rightarrow n_H^{[l]} \times n_W^{[l]} \times n_c^{[l]}$

Weights:  $f^{[l]} \times f^{[l]} \times n_c^{[l-1]} \times n_c^{[l]}$

bias:  $n_c^{[l]}$

← #filters in layer l.

Input:  $n_H^{[l-1]} \times n_W^{[l-1]} \times n_c^{[l-1]}$  ←  
 Output:  $n_H^{[l]} \times n_W^{[l]} \times n_c^{[l]}$  ←

# References

- All the contents present in the slides are taken from various online resources. Due credit is given in the respective slides. These slides are used for *academic* purposes only.