## Introduction to Deep Learning (CS474)

Lecture 26





# **Outline**

#### Module 4

Introduction to Generative Adversarial Networks (GANs)





### Recap

- We have talked about how to make predictions.
- We used deep neural networks learned mappings from data examples to labels.

- This kind of learning is called discriminative learning, as in, we'd like to be able
  to discriminate between photos cats and photos of dogs.
- Classification accuracies on high-resolution images has gone from useless to human-level (with some caveats) in just 5-6 years.





### **Motivation**

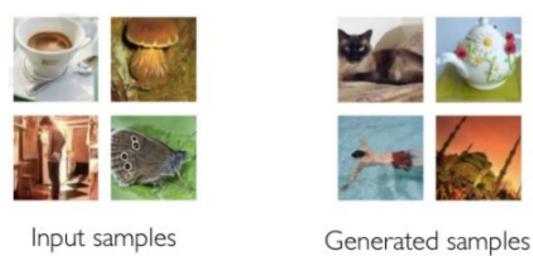
- But there is **more** to machine learning than just solving discriminative tasks.
- For example, given a large dataset, <u>without any labels</u>, we might want to learn a model that concisely captures the *characteristics* of this data.
- Given such a model, we could sample synthetic data examples that resemble the distribution of the training data.
- For example, given a large corpus of photographs of faces, we might want to be able to **generate** a new **photorealistic image** that looks like it might plausibly have come from the same dataset.
- This kind of learning is called generative modeling.





### **Generative Modeling**

• In 2014, a breakthrough paper introduced Generative adversarial networks (GANs), a clever new way to leverage the power of discriminative models to get good generative models.



- How can we learn  $P_{model}(x)$  similar to  $P_{data}(x)$ ?





### **Generative Modeling**

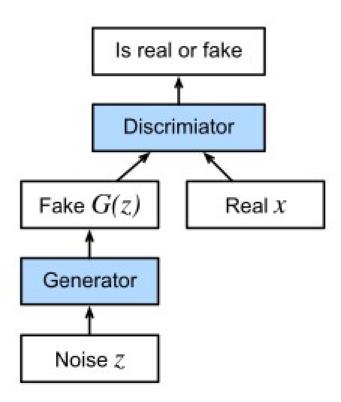
 At their heart, GANs rely on the idea that a data generator is good if we cannot tell fake data apart from real data.

- In statistics, this is called a two-sample test a test to answer the question whether datasets  $X = \{x_1, \ldots, x_n\}$  and  $X' = \{x'_1, \ldots, x'_n\}$  were drawn from the same distribution.
- No explicit model but allows one to sample the model distribution
- Sampling is done using a deep neural network





### **GAN Architecture**







### **GAN Architecture**

- As you can see, there are two pieces in GAN architecture -
- first off, we need a device (say, a deep network but it really could be anything, such as a game rendering engine) that might potentially be able to generate data that looks just like the real thing.
- If we are dealing with images, this needs to generate images. If we are dealing with speech, it needs to generate audio sequences, and so on.
- We call this the generator network.





#### **GAN Architecture**

The second component is the discriminator network.

 It attempts to distinguish fake and real data from each other. Both networks are in competition with each other.

• The generator network attempts to fool the discriminator network. At that point, the discriminator network adapts to the new fake data.

This information, in turn is used to improve the generator network, and so on.





#### **MiniMax Game**

■ Discriminator (D) and Generator (G) are playing a "minimax" game.

$$\min_{D} \{-y \log D(\mathbf{x}) - (1-y) \log(1 - D(\mathbf{x}))\}.$$

• 
$$\max_{G} \{-(1-y)\log(1-D(G(\mathbf{z})))\} = \max_{G} \{-\log(1-D(G(\mathbf{z})))\}$$

## References

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