

Algorithm inspired by [Ignatiev et al., 2015].

Algorithm 1: OMUS($\mathcal{F}, \mathcal{H}_0, f_o$)

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input :  $\mathcal{F}$  a CNF formula
input :  $\mathcal{H}_0$  set of disjoint Minimum Correction Sets
input :  $f$  a cost function
1 begin
2    $\mathcal{H} \leftarrow \emptyset$  ;
3   while true do
4     // minimum hitting set with cost function
5      $h \leftarrow \text{OMinHS}(\mathcal{H}, f)$ ;
6      $\mathcal{F}' \leftarrow \{c_i | e_i \in h\}$  ;
7     if not SAT( $\mathcal{F}'$ ) then
8       | return OMUS  $\leftarrow \mathcal{F}'$  ;
9     else
10    | // written as grow( $\mathcal{F}'$ ) which is Minimum Correction Set of  $\mathcal{F}'$ 
11    |  $\mathcal{C} \leftarrow \mathcal{F} \setminus \text{grow}(\mathcal{F}', \mathcal{F}, f)$  ;
12    end
13     $\mathcal{H} \leftarrow \mathcal{H} \cup \{\mathcal{C}\}$  ;
14  end
15 end

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Definition 1. Let Γ be a collection of sets and $MHS(\Gamma)$ the set of all minimal hitting sets on Γ and let f be an objective function with input a set of constraints. Then a hitting set $h \in \Gamma$ is said to be an **minimum cost** hitting set if $\forall h' \in MHS(\Gamma)$ we have that $|h| \leq |h'|$ and $f(h) \leq f(h')$ [Davies and Bacchus, 2011].

Property 1. The **minimum cost** hitting set of a collection of sets Γ is denoted by $OMHS(\Gamma)$.

1. Parallelize OMUS with parallel calls to OMHS
2. Ideas from [Davies and Bacchus, 2011] and from [De La Banda et al., 2014]:
 - (a) Formalize : Dissociate SAT from minimum cost hitting set using Design model
 - (b) OMHS can be written as a Integer Linear Program:
3. Ideas from [Ignatiev et al., 2015]:
 - (a) Reducing the number of SAT Calls

OMHS ILP

$$\min_{x_i} \sum_{i \in [1..|C|]} \text{cost}(c_i) \times x_i \quad (1)$$

x_i is a boolean decision variable if constraint/clause c_i is chosen or not.

$$x_i = \{0, 1\} \quad (2)$$

Every constraint has to appear at least once in the hitting set.

$$\sum_{i \in [1..|w_j|]} x_i \times w_{ij} \geq 1 \quad (3)$$

References

- [Davies and Bacchus, 2011] Davies, J. and Bacchus, F. (2011). Solving maxsat by solving a sequence of simpler sat instances. In *International conference on principles and practice of constraint programming*, pages 225–239. Springer.
- [De La Banda et al., 2014] De La Banda, M. G., Stuckey, P. J., Van Hentenryck, P., and Wallace, M. (2014). The future of optimization technology. *Constraints*, 19(2):126–138.
- [Ignatiev et al., 2015] Ignatiev, A., Previti, A., Liffiton, M., and Marques-Silva, J. (2015). Smallest mus extraction with minimal hitting set dualization. In *International Conference on Principles and Practice of Constraint Programming*, pages 173–182. Springer.