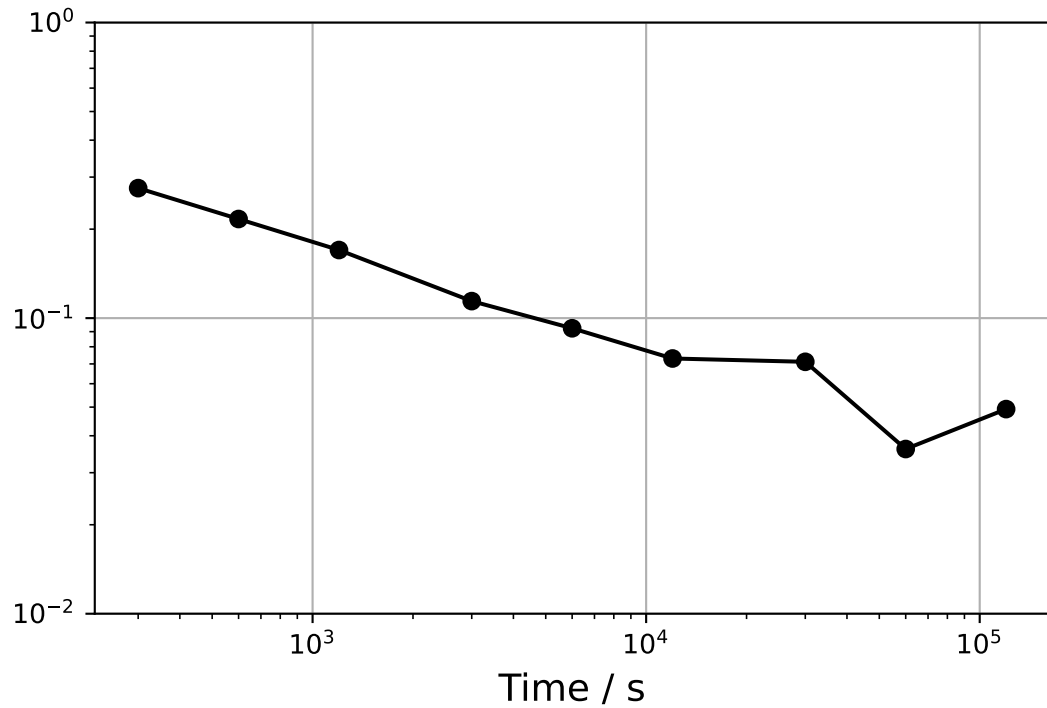


Time deviation / ns



P1 / ns

