Data Dependent Priors for Stable Learning

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PAC-Bayesian Workshop, NIPS 2017



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- Show that SVM weight vectors produced by random training sets are concentrated
- Gives tighter bounds based on data distribution defined prior
- Begin by reviewing PAC-Bayes and introducing data dependence



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- The distribution P must be chosen before learning, but the bound holds for all choices of Q, hence Q does not need to be the classical Bayesian posterior
- The bound holds for all (prior) choices of P hence it's validity is not affected by a poor choice of P though the quality of the resulting bound may be – contrast with standard Bayes analysis which only holds if the prior assumptions are correct



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The empirical generalisation error is denoted ĉ_S:

$$\hat{c}_S = \frac{1}{m} \sum_{(x,y) \in S} I[c(x) \neq y]$$
 where $I[\cdot]$ indicator function.

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- The result is concerned with bounding the performance of a probabilistic classifier that given a test input x chooses a classifier c ~ Q (the posterior) and returns c(x)
- We are interested in the relation between two quantities:

$$Q_{\mathcal{D}} = \mathbb{E}_{c \sim Q}[c_{\mathcal{D}}]$$

the true error rate of the probabilistic classifier and

$$\hat{Q}_{\mathcal{S}} = \mathbb{E}_{c \sim Q}[\hat{c}_{\mathcal{S}}]$$

its empirical error rate



Definitions for main result Generalisation error

 Note that this does not bound the posterior average but we have

$$\Pr_{(x,y)\sim\mathcal{D}}(\operatorname{sgn}(\mathbb{E}_{c\sim Q}[c(x)])\neq y)\leq 2Q_{\mathcal{D}}.$$

since for any point x misclassified by $\operatorname{sgn}\left(\mathbb{E}_{c\sim Q}[c(x)]\right)$ the probability of a random $c\sim Q$ misclassifying is at least 0.5.

PAC-Bayes Theorem

• Fix an arbitrary \mathcal{D} , arbitrary prior P, and confidence δ , then with probability at least $1 - \delta$ over samples $S \sim \mathcal{D}^m$, all posteriors Q satisfy

$$\mathrm{KL}(\hat{Q}_{\mathcal{S}} \| Q_{\mathcal{D}}) \leq \frac{\mathrm{KL}(Q \| P) + \ln((m+1)/\delta)}{m}$$

where KL is the KL divergence between distributions

$$\mathrm{KL}(Q\|P) = \mathbb{E}_{c \sim Q} \left[\ln \frac{Q(c)}{P(c)} \right]$$

with \hat{Q}_S and Q_D considered as distributions on $\{0, +1\}$.



Linear classifiers

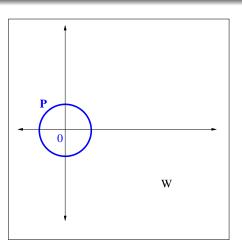
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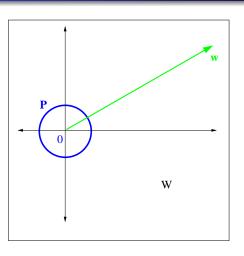
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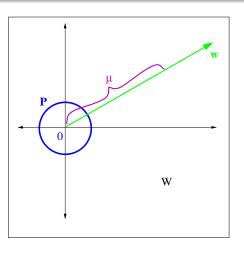
- We will choose the prior and posterior distributions to be Gaussians with unit variance.
- The prior P will be centered at the origin with unit variance
- The specification of the centre for the posterior $Q(\mathbf{w}, \mu)$ will be by a unit vector \mathbf{w} and a scale factor μ .



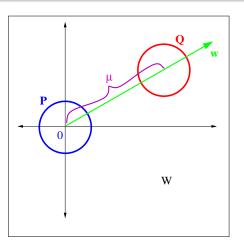
- **Prior** P is Gaussian $\mathcal{N}(0,1)$
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- Posterior Q is Gaussian

Form of the SVM bound

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- Note that bound holds for all posterior distributions so that we can choose μ to optimise the bound
- If we define the inverse of the KL by

$$\mathrm{KL}^{-1}(q, A) = \max\{p : \mathrm{KL}(q \| p) \le A\}$$

then have with probability at least $1 - \delta$

$$Pr\left(\langle \mathbf{w}, \phi(\mathbf{x}) \rangle \neq y\right) \leq 2 \min_{\mu} KL^{-1} \left(\mathbb{E}_{m}[\tilde{F}(\mu \gamma(\mathbf{x}, y))], \frac{\mu^{2}/2 + \ln \frac{m+1}{\delta}}{m} \right)$$

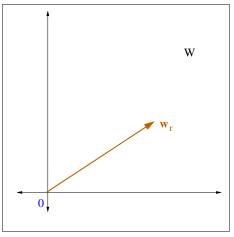
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- Better prior (closer to posterior) would lead to tighter bound

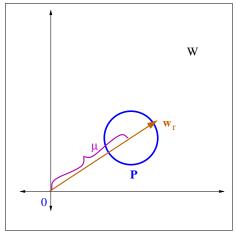
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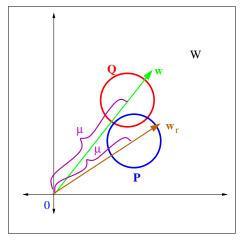
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- Introduce the learnt prior in the bound
- Compute stochastic error with remaining data



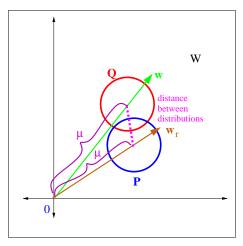
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 - New bound proportional to KL(P||Q)

SVM performance may be tightly bounded by

$$\mathsf{KL}(\hat{Q}_{S}(\boldsymbol{w},\mu)\|\underline{Q_{\mathcal{D}}(\boldsymbol{w},\mu)}) \leq \frac{0.5\|\mu\boldsymbol{w} - \eta\boldsymbol{w}_{r}\|^{2} + \ln\frac{(m-r+1)J}{\delta}}{m-r}$$

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• $Q_D(\mathbf{w}, \mu)$ true performance of the classifier

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• $\hat{Q}_{S}(\mathbf{w}, \mu)$ stochastic measure of the training error on remaining data

$$\hat{Q}(\boldsymbol{w}, \mu)_{\mathcal{S}} = \mathbb{E}_{\boldsymbol{m}-\boldsymbol{r}}[\tilde{F}(\mu\gamma(\boldsymbol{x}, y))]$$

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• $0.5 \|\mu \mathbf{w} - \eta \mathbf{w}_r\|^2$ distance between prior and posterior

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• Penalty term only dependent on the remaining data m-r

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- **3** Margin for the stochastic classifier \hat{Q}_s

$$\gamma(\mathbf{x}_j, y_j) = \frac{y_j \mathbf{w}^T \phi(\mathbf{x}_j)}{\|\phi(\mathbf{x}_j)\| \|\mathbf{w}\|} \qquad j = 1, \dots, m - r$$

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- **Margin** for the stochastic classifier \hat{Q}_s

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Linear search to obtain the optimal value of μ . This introduces an insignificant extra penalty term

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- Resulting bound depends on a benign parameter τ determining the variance in the direction \mathbf{w}_r

$$\begin{split} \mathsf{KL}(\hat{Q}_{\mathcal{S}\backslash R}(\mathbf{w},\mu)\|\mathcal{Q}_{\mathcal{D}}(\mathbf{w},\mu)) \leq \\ & \frac{0.5(\ln(\tau^2) + \tau^{-2} - 1 + P_{\mathbf{w}_r}^{\parallel}(\mu\mathbf{w} - \mathbf{w}_r)^2/\tau^2 + P_{\mathbf{w}_r}^{\perp}(\mu\mathbf{w})^2) + \ln(\frac{m-r+1}{\delta})}{m-r} \end{split}$$

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Results

		Classifier						
		SVM				η Prior SVM		
Problem		2FCV	10FCV	PAC	PrPAC	PrPAC	au-PrPAC	
digits	Bound	_	_	0.175	0.107	0.050	0.047	
	CE	0.007	0.007	0.007	0.014	0.010	0.009	
waveform	Bound	_	_	0.203	0.185	0.178	0.176	
	CE	0.090	0.086	0.084	0.088	0.087	0.086	
pima	Bound	_	-	0.424	0.420	0.428	0.416	
	CE	0.244	0.245	0.229	0.229	0.233	0.233	
ringnorm	Bound	_	-	0.203	0.110	0.053	0.050	
	CE	0.016	0.016	0.018	0.018	0.016	0.016	
spam	Bound	_	-	0.254	0.198	0.186	0.178	
	CE	0.066	0.063	0.067	0.077	0.070	0.072	

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- P and Q are Gibbs-Boltzmann distributions

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 These distributions are hard to work with since we cannot apply the bound to a single weight vector, but the bounds can be very tight:

$$\mathit{KL}_+(\hat{Q}_{\mathcal{S}}(\gamma)||Q_{\mathcal{D}}(\gamma)) \leq \frac{1}{m} \left(\frac{\gamma}{\sqrt{m}} \sqrt{\ln \frac{8\sqrt{m}}{\delta}} + \frac{\gamma^2}{4m} + \ln \frac{4\sqrt{m}}{\delta} \right)$$

as it appears we can choose γ small even for complex classes.

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- Note that we do not know this vector, but it is nonetheless fixed independently of the training sample.
- We can compute a sample based estimate of this vector as

$$\hat{\mathbf{w}}_p = \mathbb{E}_{\mathcal{S}}[y\phi(\mathbf{x})]$$



Estimating the KL divergence

• With probability $1 - \delta/2$ we have

$$\|\hat{\mathbf{w}}_{p} - \mathbf{w}_{p}\| \leq rac{R}{\sqrt{m}} \left(2 + \sqrt{2 \ln rac{2}{\delta}}
ight).$$

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- Proof relies on independence of examples and the fact the vector is a simple sum
- We can therefore w.h.p. upper bound KL divergence between prior P, an isotropic Gaussian at wp, and posterior Q, an isotropic Gaussian at w by

$$\frac{1}{2} \left(\|\mathbf{w} - \hat{\mathbf{w}}_{p}\| + \frac{R}{\sqrt{m}} \left(2 + \sqrt{2 \ln \frac{2}{\delta}} \right) \right)^{2}$$

Resulting bound

Giving the following bound on generalisation:

$$\begin{aligned} \textit{KL}_{+}(\hat{Q}_{\mathcal{S}}(\mathbf{w},\mu)||Q_{\mathcal{D}}(\mathbf{w},\mu)) \leq \\ & \frac{\frac{1}{2}\left(\|\mu\mathbf{w} - \eta\hat{\mathbf{w}}_{p}\| + \eta\frac{R}{\sqrt{m}}\left(2 + \sqrt{2\ln\frac{2}{\delta}}\right)\right)^{2} + \ln\frac{2(m+1)}{\delta}}{m} \end{aligned}$$

with probability $1 - \delta$.

Values of the bounds for an SVM.

Prob.	PAC-Bayes	PrPAC	au-PrPAC		$ au$ - $\mathbb E$ PrPAC
han	0.175 ± 0.001	0.107 ± 0.004	0.108 ± 0.005	0.157 ± 0.001	0.176 ± 0.001
wav	0.203 ± 0.001	0.185 ± 0.005	0.184 ± 0.005	0.202 ± 0.001	0.205 ± 0.001
pim	0.424 ± 0.003	0.420 ± 0.015	0.423 ± 0.014	0.428 ± 0.003	0.433 ± 0.003
rin	0.203 ± 0.000	0.110 ± 0.004	0.110 ± 0.004	0.201 ± 0.001	0.204 ± 0.000
spa	0.254 ± 0.001	0.198 ± 0.006	0.198 ± 0.006	0.249 ± 0.001	0.255 ± 0.001



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$$A_{S} = \arg\min_{\mathbf{w}} \frac{1}{m} \sum_{i=1}^{m} \ell(g_{\mathbf{w}}, (\mathbf{x}_{i}, y_{i})) + \frac{\lambda}{2} \|\mathbf{w}\|^{2}$$
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• Loss function is 1-Lipschitz and $\lambda > 0$ gives concentration of SVM weight vectors: with prob at least $1 - \delta$

$$g(S) = \left\|A_S - \mathbb{E}_{\tilde{S}}[A_{\tilde{S}}]\right\| \leq \frac{1}{\lambda \sqrt{m}} \left(3 + \sqrt{\frac{1}{2} \ln \frac{1}{\delta}}\right)$$

Proof outline

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 - observe SVM weight has dual representation as sum, but dual variables vary
 - can bound sum of expected values of dual variables
 - can also show this sum is close to true SVM vector



Resulting bound

• We obtain a bound for which the KL term is $O(1/m^2)$: with probability $1 - \delta$:

$$\mathsf{KL}_{+}(\hat{Q}_{\mathcal{S}}(A_{\mathcal{S}},1)||Q_{\mathcal{D}}(A_{\mathcal{S}},1)) \leq \frac{1}{2\lambda^{2}m^{2}}\left(3+\sqrt{\frac{1}{2}\ln\frac{2}{\delta}}\right)^{2}+\frac{1}{m}\ln\left(\frac{2(m+1)}{\delta}\right)$$

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Compared with Bousquet et al bound:

$$R \le R_{\mathrm{emp}} + \frac{1}{\lambda m} + \left(1 + \frac{2}{\lambda}\right) \sqrt{\frac{\ln(1/\delta)}{2m}}$$



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- This suggests we may be able to learn in very flexible spaces such as those used in Deep Learning provided we can show weights are concentrated around an expected value
- Given the many equivalent solutions in deep architectures this will not be true from the beginning of learning but stability suggests will hold after initial 'burn in'



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- Suggests we might be able to extend the analysis to the weight updates given by SGD in Deep Learning

