

## Assignment #9 (revised)

**Due Wednesday, 30 November 2022, at the start of class**

Please read sections 12.3, 12.4, 13.5, 14.1, 14.2, and 14.3 from the textbook.<sup>1</sup>

DO THE FOLLOWING EXERCISES from section 12.3, pages 420–421:

- Exercise 3.1 *Please write your own code, or modify `sr1bt.m` to use exact line search.*
- Exercise 3.3
- Exercise 3.4 *Hint. What do you know about a rank one matrix? Thus you can write it as an outer product.*
- Exercise 3.8

DO THE FOLLOWING EXERCISES from section 13.5, pages 473–474:

- ~~Exercise 5.5~~ *Removed. Old hint: Assume matrix  $B_k$  has a known inverse  $H_k = B_k^{-1}$ . Let  $v = y_k - B_k s_k$ . Then set  $u = -v/(v^\top s_k)$  in Sherman-Morrison.*

DO THE FOLLOWING EXERCISES from section 14.2, pages 489–491:

- Exercise 2.1

**Problem P18.** *This problem simplifies/clarifies Exercise 4.4 in section 12.4.*

Apply the forward difference formula  $f'(x) \approx (f(x+h) - f(x))/h$  to estimate the gradient of the function

$$f(x) = \exp(10x_1 + 2x_2^2),$$

at the point  $x = (-1, 1)$ . (Obviously,  $f : \mathbb{R}^2 \rightarrow \mathbb{R}$ .) Assuming that  $\epsilon_{\text{mach}} = 2.2204 \times 10^{-16}$  on the computer you used, how accurate is the approximated gradient when you actually compute using the “best” value of  $h$  and the “simpler” value of  $h$ , from page 425? (Use a norm to quantify the error in the gradient.)

**Problem P19.** Suppose a user wants to solve  $\min_{x \in \mathbb{R}^n} f(x)$  for a smooth objective function  $f : \mathbb{R}^n \rightarrow \mathbb{R}$ , but they do not provide a gradient function  $\nabla f(x)$ . We can still use quasi-Newton if we apply finite differences to replace the missing gradient (section 12.4). Use this idea to write a new code

```
function [xk, xklist] = sr1btfd(x0, f, tol, maxiters)
```

which replaces the user-provided gradient in `sr1bt.m` with a finite-difference gradient. Test it on the Rosenbrock example, as is done in `rosencompare.m`, and give iterations. (Don’t worry about visualizing, or the contours.) How would it help if the user provided values for the typical scales of the gradient and the Hessian?

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<sup>1</sup>Griva, Nash, and Sofer, *Linear and Nonlinear Optimization*, 2nd ed., SIAM Press 2009.