## **Assignment #10**

## Due Friday, 9 December 2022, at the start of class

Please read sections 14.1–14.7 and 15.1–15.4 from the textbook.<sup>1</sup>

DO THE FOLLOWING EXERCISES from section 14.2, pages 489–491:

• Exercise 2.7 You may use techniques from either section 14.2 or 14.3.

**Problem P21.** Suppose  $c \in \mathbb{R}^n$  is a nonzero vector and consider the problem

minimize 
$$z = c^{\mathsf{T}} x$$

subject to 
$$\sum_{i=1}^{n} x_i^2 = 1$$

where  $x \in \mathbb{R}^n$ . Note that the single equality constraint can be written as  $||x||^2 = 1$ .

(a) By arguing informally explain why the solution is

$$x_* = -\frac{c}{\|c\|}.$$

Use a sketch of the n = 2 case to explain.

- **(b)** The necessary optimality conditions for this problem are addressed by Theorem 14.15 on page 504 of the textbook. Compute the Lagrangian and state the first-order necessary conditions in detail. (*Note that you do* not *need to compute a null-space matrix in order to do this.*)
- (c) Solve the conditions in (b) algebraically to confirm the solution in part (a). How many points  $(x_*, \lambda_*)$  are there which satisfy the first-order necessary conditions?

**Problem P22.** Before doing this problem read Example 14.20 on pages 506–507. This problem asks for a similar analysis.

Consider the problem

minimize 
$$f(x) = (x_1 - 1)^2 + (x_2 + 1)^2$$
  
subject to  $x_1^2 + x_2^2 \le 9$   
 $x_2 \ge 0$ 

- (a) Sketch the feasible set and explain informally, perhaps using contours of f, why  $x_* = (1,0)^{\top}$  is the solution.
- (b) Write the constraints in the form  $g_i(x) \ge 0$ . Compute the Lagrangian and its gradient. For each of the points  $A = (0,0)^{\top}$ ,  $B = (0,3)^{\top}$ , and  $C = (1,0)^{\top}$  compute

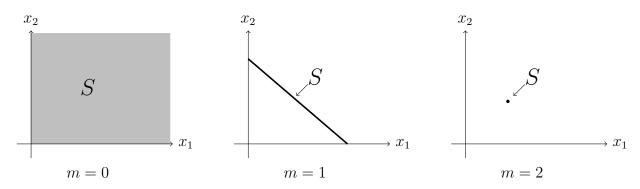
<sup>&</sup>lt;sup>1</sup>Griva, Nash, and Sofer, *Linear and Nonlinear Optimization*, 2nd ed., SIAM Press 2009.

the values of  $\lambda_i$  satisfying the zero-gradient condition. Address whether these points satisfy the first-order optimality conditions, that is, whether they are candidates for a local minimizer. Show in particular that C satisfies all the first-order conditions in Theorem 14.18. (You do not need to find null-space matrices to answer this question.)

**Problem P23.** Consider nonlinear optimization problems on  $x \in \mathbb{R}^n$  which have standard-form linear constraints:

Assume that there are m scalar constraint equations and that A has full row rank. Thus  $A \in \mathbb{R}^{m \times n}$ ,  $b \in \mathbb{R}^m$ , and  $m \le n$  (as usual).

We want to visualize the possible feasible sets for such problems. In 2D (n=2) there are exactly three possibilities for the dimension of the feasible set. The cartoons below illustrate these possibilities when the feasible set S is non-empty and bounded. (Except that for m=0 the set is unbounded.)



For 3D (n=3) there are four nonempty, and bounded if m>0, possibilities. Sketch the four corresponding cartoons. These cartoons should have the same annotations as the 2D versions above.

**Problem P24.** This problem asks you to write the general KKT conditions.

Consider the general nonlinear constrained optimization problem over  $x \in \mathbb{R}^n$ :

minimize 
$$f(x)$$
  
subject to  $g_i(x)=0, \quad i=1,\ldots,\ell$   
 $h_i(x)\geq 0, \quad i=1,\ldots,m$ 

- (a) In section 14.5 the meaning of the phrase " $x_*$  is a regular point of the constraints" is given. State this definition precisely for the above problem.
- **(b)** State the Lagrangian for this problem.
- (c) Suppose  $x_*$  is a local minimizer of the above problem which is also a regular point. State the first-order necessary conditions for the above problem. (*Again*, you do not need to find null-space matrices to answer this question.)