Christos Axelos, AEM 1814, 2nd Assignment in High Performance computing 2017/18

OBSERVATIONS

- We add the **-qopenmp** flag to include the openMP libraries
- We run each time our program using the command: ./seq_main -i Image_data/texture17695.bin -o -b -n 10000, so the number of clusters is 10000.
- Flag - $\mathbf{O0}$ gave very bad performance, so I used only the - \mathbf{fast} flag

SYSTEM SPECS

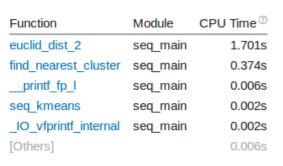
- All the measurements were done using the below characteristics:
- a) OS: Ubuntu LTS 16.04
- b) Core Edition: 4.4.0-97-generic
- c) CPU: Intel Core i5d) NumOfProcessors: 4
- e) Compiler: icc
- f) Compiler's edition: 18.0.0

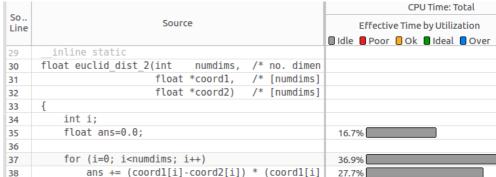
RESULTS

- We begin with our **initial** code, trying to find the loops that increase the execution time. The bellow code is the initial code that we want to parallelize. It is from file **seq_kmeans.c**

```
Function: seq_kmeans()
 do {
     delta = 0.0:
     for (i=0; i<numObjs; i++) {</pre>
         /* find the array index of nestest cluster center */
         index = find_nearest_cluster(numClusters, numCoords, objects[i],
                                        clusters);
          /* if membership changes, increase delta by 1 */
         if (membership[i] != index) delta += 1.0;
         /* assign the membership to object i */
         membership[i] = index;
         /* update new cluster center : sum of objects located within */
         newClusterSize[index]++;
         for (j=0; j<numCoords; j++)</pre>
              newClusters[index][j] += objects[i][j];
     }
     /* average the sum and replace old cluster center with newClusters */
     for (i=0; i<numClusters; i++) {</pre>
         for (j=0; j<numCoords; j++) {
    if (newClusterSize[i] > 0)
                  clusters[i][j] = newClusters[i][j] / newClusterSize[i];
              newClusterSize[i] = 0;  /* set back to 0 */
     }
     delta /= numObjs;
 } while (delta > threshold && loop++ < 500);</pre>
Function find_nearest_cluster()
    /* find the cluster id that has min distance to object */
            = 0;
   min_dist = euclid_dist_2(numCoords, object, clusters[0]);
    for (i=1; i<numClusters; i++) {</pre>
        dist = euclid_dist_2(numCoords, object, clusters[i]);
        /* no need square root */
        if (dist < min_dist) { /* find the min and its array index */</pre>
            min_dist = dist;
            index
                     = i;
    return(index);
Function euclid_dist_2()
   float euclid_dist_2(int numdims, /* no. dimensions */
                       float *coord1, /* [numdims] */
float *coord2) /* [numdims] */
   {
       int i;
       float ans=0.0;
       for (i=0; i<numdims; i++)</pre>
           ans += (coord1[i]-coord2[i]) * (coord1[i]-coord2[i]);
       return(ans);
```

- After running the sequential code, the timing that we get at **Venus** is 7.288691 seconds. Let's see where is the biggest latency, using the **vtune amplifier**
- In the left image, we see the functions that cause the biggest latency. At first, we have to focus at the function **euclid_dist_2**





- The 36.9% of total time is wasted in **line 37**, so we try here our first optimizations.
- I tried to optimizise, applying paralelism to the for-loop with 2 different ways

```
code (a)
 float ans=0.0;
 float ans i;
 #pragma omp parallel private (ans_i)
   ans_i = 0;
   #pragma omp for
   for (i=0; i<numdims; i++) {</pre>
      ans_i += (coord1[i]-coord2[i]) * (coord1[i]-coord2[i]);
   #pragma omp critical
      ans += ans i;
 }
code (b)
 int i;
 float ans=0.0;
 #pragma omp parallel for reduction (+:ans)
 for (i=0; i<numdims; i++) {</pre>
    ans += (coord1[i]-coord2[i]) * (coord1[i]-coord2[i]);
```

- However the performance is getting a lot worser. The reason why the above optimizations increase so much the latency is the extremely big **overhead** that we add by creating and destroying threads each time we call function **euclid_dist_2**. And this function is called 884750000 times! Furthermore we can't use the **nowait** keyword, because we must wait all threads to finish and then write the results

- So we must find a way to parallelize that function without destroying our threads each time we return from that function. We will not create our threads inside **euclid_dist_2**, but inside the function **find_nearest_cluster()**
- Lets try now parallelizing the code in **find_nearest_cluster()**
- After running the code for different number of threads and using different type of scheduling, we improved the performance , but still is **worser** a lot more than the sequential

