

CHUCK => A CONCURRENT, ON-THE-FLY AUDIO PROGRAMMING LANGUAGE

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WHAT IS CHUCK?

- GENERAL-PURPOSE AUDIO PROGRAMMING LANGUAGE
 - STRONGLY TYPED AND STRONGLY TIMED
 - OBJECT ORIENTED
 - PLATFORM INDEPENDENT
 - DESIGNED FROM THE GROUND UP
 - NOT BASED ON A SINGLE EXISTING LANGUAGE
- A NEW PROGRAMMING MODEL
- SOLVES A NUMBER OF PROBLEMS

AUDIO PROGRAMMING

- CONSIDERATIONS
 - DEVELOPMENT
 - FLEXIBILITY & PROGRAMMABILITY
 - ELEGANT MAPPING OF AUDIO CONCEPTS TO LANGUAGE
 - LEVELS OF ABSTRACTION
 - TIMING (AND CONCURRENCY?)

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 - RUN-TIME
 - REAL-TIME
 - USABILITY / CONTROL
 - PERFORMANCE

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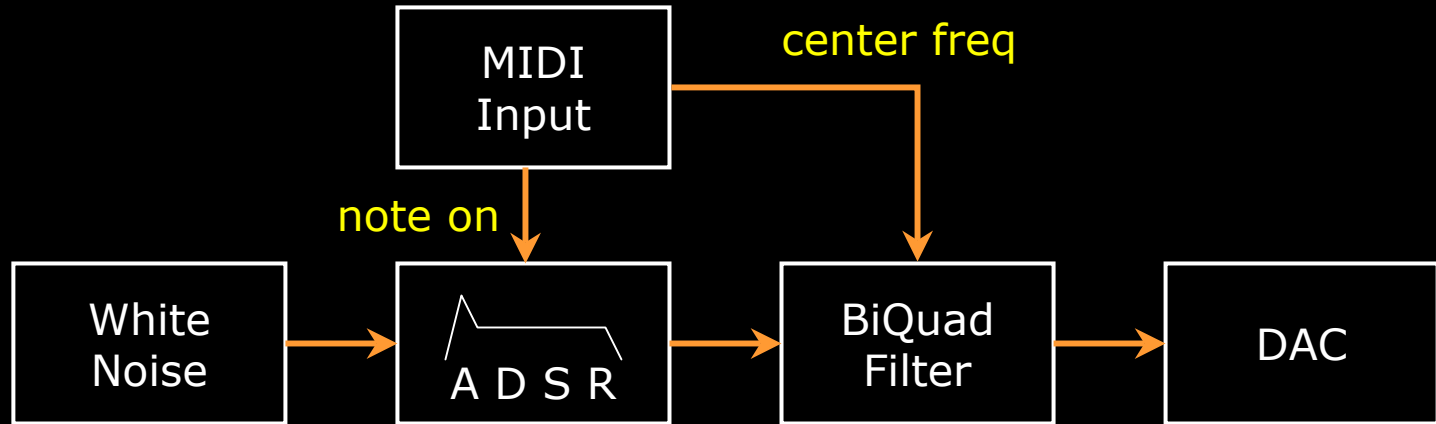
- PROBLEM:

DIFFICULT TO INCORPORATE INTO A SINGLE LANGUAGE

QUESTION: CAN WE DESIGN ONE LANGUAGE THAT SUPPORTS:

- REPRESENTATION OF AUDIO CONCEPTS
 - REASON ABOUT FLOW FROM CODE
- BOTH HIGH AND LOW LEVELS OF ABSTRACTION
 - DATA AND TIME
 - REASON ABOUT TIME DIRECTLY FROM CODE
- CONCURRENCY
 - CAN BE USEFUL (BUT HARD!)
 - TIMING
 - SYNCHRONIZATION
 - PERFORMANCE

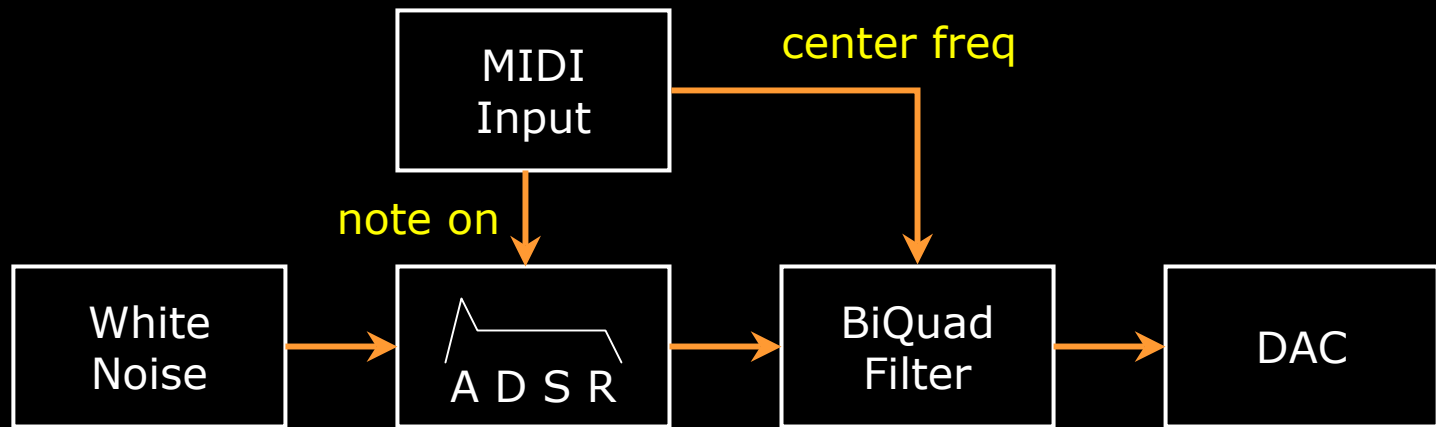
PROBLEM 1 : REPRESENTATION



```
dacOut.tick(biQuad.tick(adsr.tick() * noise.tick()));
```

```
if( timeCount % 44 == 0 )
{
    if( midi.nextMessage() == __SK_NoteOn_ )
    {
        (midi.getBytesThree() ? adsr.noteOn() : adsr.noteOff());
        biQuad.setFreq( MD2Freq(midi.getBytesTwo()) );
    }
}
```

SOLUTION 1 : REPRESENTATION



```
noise3 ==> ADSR ==> biquad1 ==> dac;  
midi ==> ( ADSR, biquad1 );
```


SOLUTION 1 : REPRESENTATION



\Rightarrow SYNTAX

- SIMPLE CHUCK: $x \Rightarrow y;$
- CHAIN CHUCK: $w \Rightarrow x \Rightarrow y \Rightarrow z;$
- NESTED CHUCK: $w \Rightarrow (x \Rightarrow y) \Rightarrow z;$
- CROSS CHUCK: $w \Rightarrow (x, y);$
 $(w, v) \Rightarrow (x, y, z);$
- UN-CHUCK: $x =< y =< z;$
- RE-CHUCK: $x =<> y;$

=> SEMANTICS

- ACTION-ORIENTED
- OVERLOADED ON TYPES
 - DEFINED FOR PRIMITIVES
 - UNIT GENERATORS
 - SYSTEM MECHANISMS
- CHUCK OPERATOR HELPS REPRESENT FLOW

PROBLEM 2: LEVEL OF CONTROL

- WHAT IS THE APPROPRIATE LEVEL OF CONTROL FOR...
 - DATA? (BITS, BYTES, OBJECTS, ...)
 - TIME & CONTROL RATE? (SAMPLE, MS, ...)
- SOLUTION: PROVIDE MANY LEVELS OF CONTROL!
 - WORK AT MULTIPLE LEVELS OF ABSTRACTION FOR BOTH DATA AND TIME

PROBLEM 2: LEVEL OF CONTROL

```
noise => env => biQuad => dac;
```

```
while( true )  
{  
    500 + (300 * sin(now*FC)) => biQuad.freq;  
    100:ms => now;  
}
```

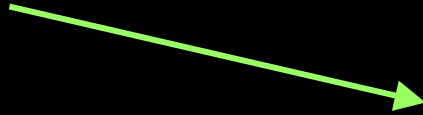
DEMO 1

CHUCK TIMING CONSTRUCTS

- **dur** IS A NATIVE TYPE
 - UNITS:
 - samp, ms, second, minute, hour, day, week
 - ARITHMETIC:
 - 3:second + 100:ms => dur quarter;
- **time** IS A NATIVE TYPE
 - **now** KEYWORD HOLDS CURRENT CHUCK TIME
 - ARITHMETIC:
 - 5:second + now => time later;

TIME EXAMPLE

```
4:second + now => time later;  
while( now < later )  
{  
    now => stdout;  
    1:second => now;  
}
```

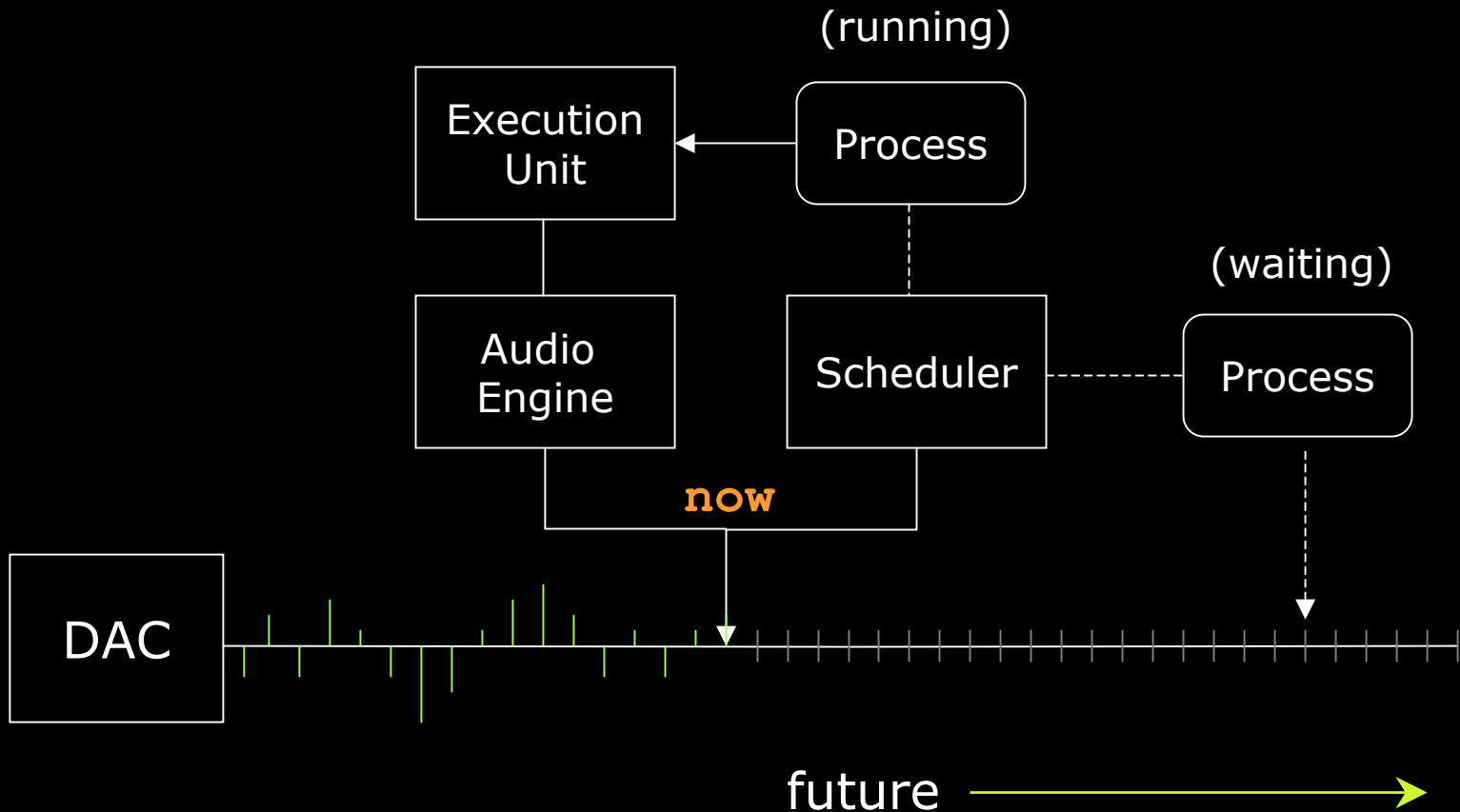


```
> chuck foo.ck  
0  
1  
2  
3
```

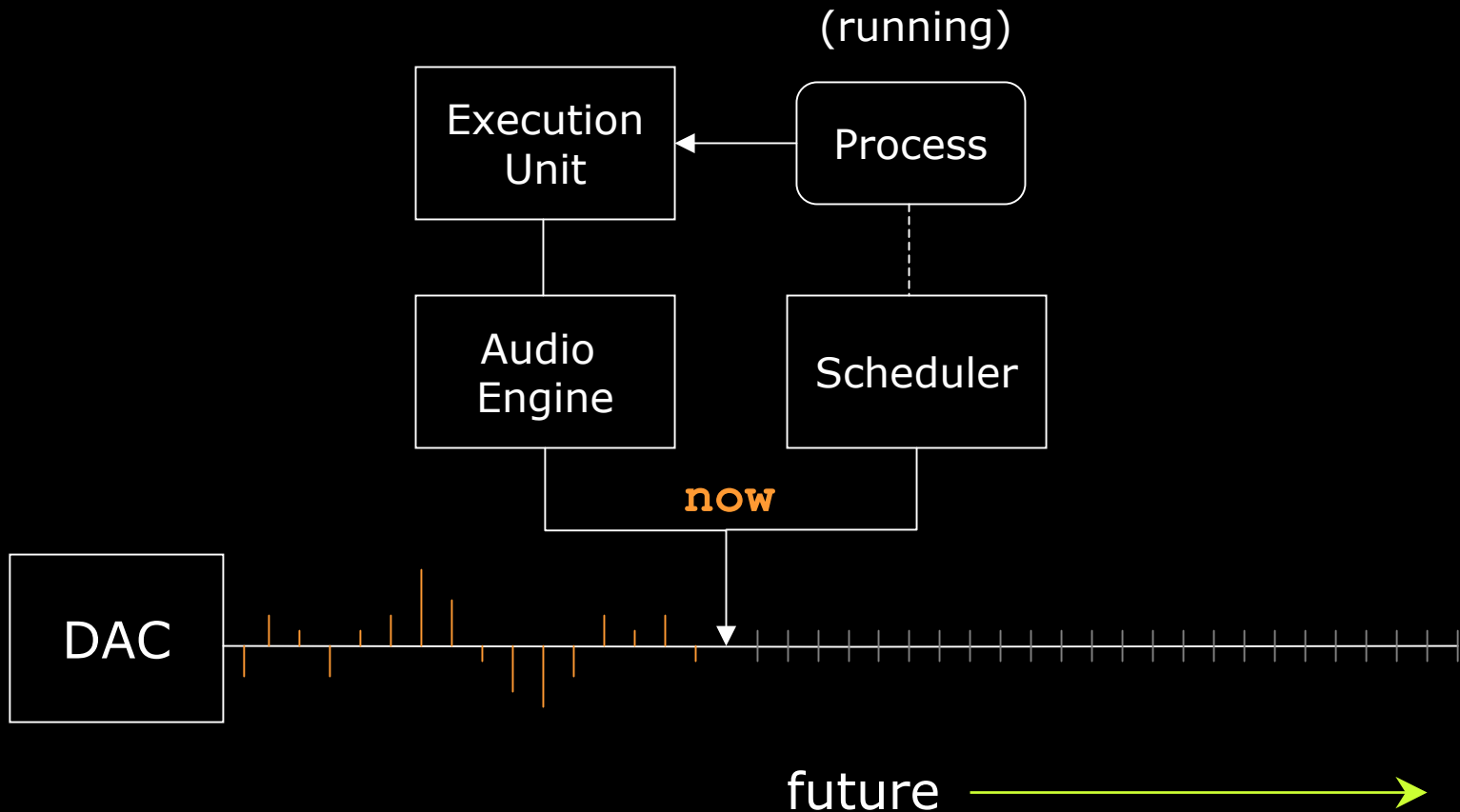
ADVANCING TIME

- TIME STANDS STILL UNTIL YOU “ADVANCE” IT
- TWO SEMANTICS FOR ADVANCING TIME
 - CHUCK TO NOW
`1:second => now;`
 - WAIT ON EVENT
`midi_event => midi_handler;`
- YOU ARE RESPONSIBLE FOR KEEPING UP WITH TIME
- TIMING EMBEDDED IN PROGRAM FLOW

HOW IT WORKS



HOW IT WORKS



DYNAMIC CONTROL RATE

```
"snare" => sndbuf sbuf => dac;
```

```
50 => int r;
```

```
0 => float a;
```

```
while( true )
```

```
{
```

```
    0 => sbuf;
```

```
    70 + (30 * sin(a)) => r;
```

```
    .1 +=> a;
```

```
    r::ms => now;
```

```
}
```

DEMO 2

CONSEQUENCES OF TIMING MECHANISM

- CONSISTENT, DETERMINISTIC NOTION OF TIME
- STRONG CORRESPONDENCE OF PROGRAM FLOW
AND TIMING
- CONTROL RATE
 - ARBITRARY
 - DYNAMIC
 - SAMPLE-SYNCHRONOUS

TIMING MODEL MAKES CHUCK MORE POWERFUL BY
ALLOWING DETERMINISTIC CONCURRENCY...

PROBLEM 3: CONCURRENT AUDIO PROGRAMMING

noise => env => biQuad => dac;

0.0 => float v;

while(true)

{

sin(v*FC) => biQuad.freq;

1.0 +=> v;

100:ms => **now**;

}

while(true)

{

if(midiin.noteOn())
midiin.vel => env;

13:ms => **now**;

}

CONCURRENCY IS HARD!

- SYNCHRONIZATION AND TIMING
- OVERHEAD
- PROGRAMMING MODEL
 - EXPRESSING CONCURRENCY IN CODE

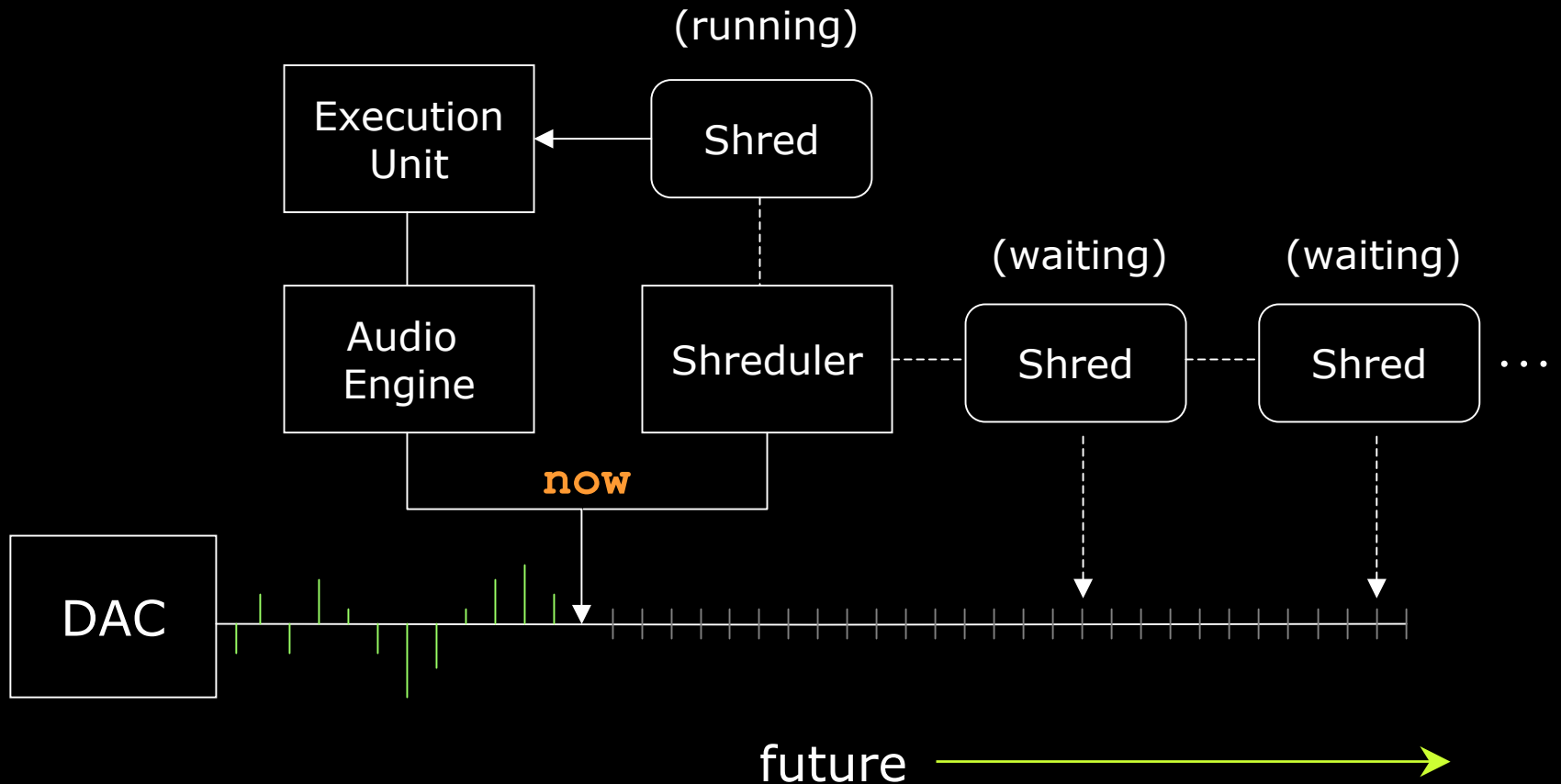
PROGRAMMING WITH SHREDS

- THREADS
 - PREEMPTIVE / NON-DETERMINISTIC
 - USE A FORK()
 - NO TIMING GUARANTEES
- SHREDS
 - DETERMINISTIC SHRED OF COMPUTATION
 - USE A SPORK()
 - SAMPLE-SYNCHRONOUS PRECISION

PROPERTIES OF SHREDS

- RESEMBLE NON-PREEMPTIVE THREADS
- USER-LEVEL CONSTRUCTS (NO KERNEL INTERACTION)
 - HIGH-PERFORMANCE
 - CONTEXT SWITCH
 - SYNCHRONIZATION / SHREDULING
- AUTOMATICALLY SYNCHRONIZED BY TIME!
- MANAGED BY THE CHUCK SHREDULER
- DETERMINISTIC EXECUTION

HOW IT WORKS



CONTROL RATES AND SHREDS

- DETERMINED BY PROGRAMMER PER SHRED
- CHUCK CONTROL RATES ARE:
 - ARBITRARY
 - DYNAMIC
 - SIMULTANEOUS

DEMO 3

3-shred example:

```
500::ms => now;          750::ms => now;          625::ms => now;
"bass" => sndbuf sb => dac; "snare" => sndbuf sb => dac; "hatcl" => sndbuf sb => dac;

while( 1 )               while( 1 )               while( 1 )
{
    0 => sb;              0 => sb;                  0 => sb;
    500::ms => now;        500::ms => now;            250::ms => now;
}                          }                          }
```

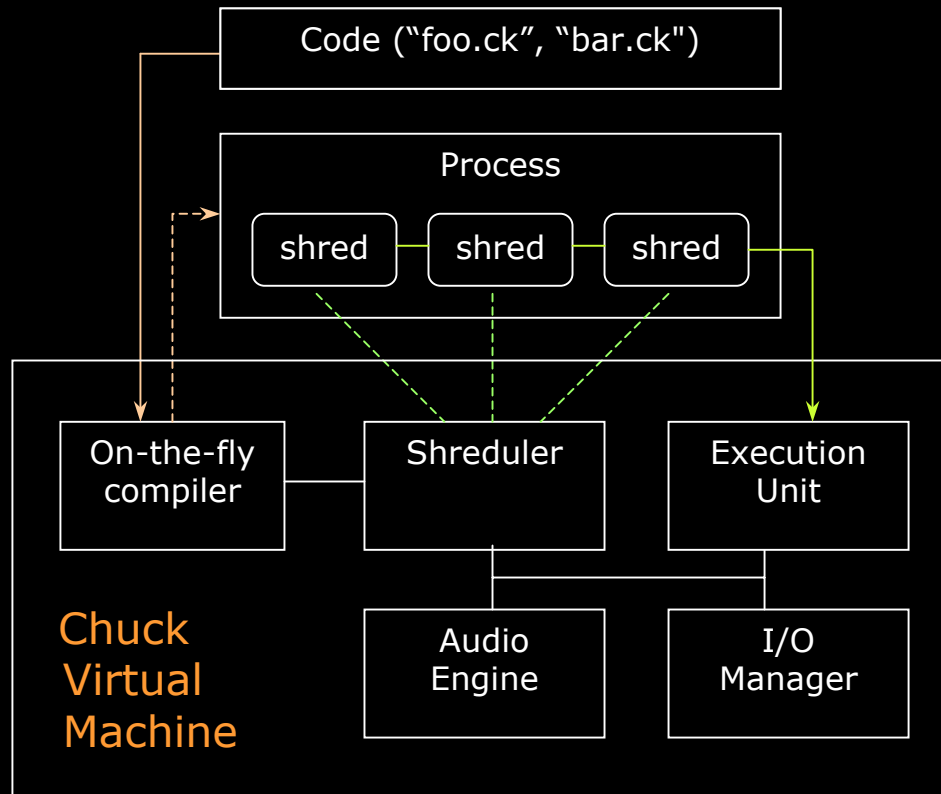
CONSEQUENCES OF CONCURRENCY WITH TIMING

- POSSIBLE TO WRITE TRULY PARALLEL,
SAMPLE-SYNCHRONOUS AUDIO CODE
- CAN WORK AT LOW AND HIGH LEVEL
 - FINE GRANULARITY == POWER AND CONTROL
 - ARBITRARY GRANULARITY == FLEXIBILITY
AND EFFICIENCY
- PROGRAM ON-THE-FLY...

ON-THE-FLY PROGRAMMING

- GOAL: ADD/MODIFY/REMOVE PARTS OF THE PROGRAM AS IT IS RUNNING
- EXPERIMENTATION & PERFORMANCE POSSIBILITIES
- USE THE SHRED MECHANISM
 - ADD AND REMOVE SHREDS FROM THE VIRTUAL MACHINE
 - USE NETWORKING, GUI, OR COMMAND LINE

CHUCK VIRTUAL MACHINE



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CHUCK IS FREE FROM THE AUTHORS:

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QUESTIONS?



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