

Symmetric tensor networks and practical simulation algorithms to sharply identify classes of quantum phases distinguishable by short-range physics

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Phases of matter are sharply defined in the thermodynamic limit. One major challenge of accurately simulating quantum phase diagrams of interacting quantum systems is due to the fact that numerical simulations usually deal with the energy density, a local property of quantum wave functions, while identifying different quantum phases generally relies on long-range physics. In this paper, we construct generic fully symmetric quantum wave functions under certain assumptions using a type of tensor networks (projected entangled pair states), and provide practical simulation algorithms based on them. We find that quantum phases can be organized into crude classes distinguished by short-range physics, which is related to the fractionalization of both onsite symmetries and space-group symmetries. Consequently, our simulation algorithms, which are useful to study long-range physics as well, are expected to be able to sharply determine crude classes in interacting quantum systems efficiently. Examples of these crude classes are demonstrated in half-integer quantum spin systems on the kagome lattice. Limitations and generalizations of our results are discussed.

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I. INTRODUCTION

Reliably simulating quantum phase diagrams of realistic interacting systems has been one of the central issues in condensed matter physics. A number of numerical methods have been developed in the past decades, including exact diagonalization, quantum Monte Carlo (for a review, see Ref. [1]), variational Monte Carlo [1,2], the density matrix renormalization group method (DMRG) [3,4], and methods based on tensor network representations of quantum wave functions [5–9]. Although, with advantages and disadvantages, these methods have been demonstrated to be able to successfully simulate various interacting quantum models. For instance, an exotic quantum spin-liquid phase has been recently identified in the spin- $\frac{1}{2}$ Heisenberg model on the kagome lattice [10–12] using DMRG methods.

One major source of the challenges of accurately simulating realistic quantum models is the following fact. The full many-body quantum Hamiltonian cannot be exactly diagonalized as long as the sample size is not very small. Therefore, even for intermediate sample size, except for systems that do not suffer from the sign problem in quantum Monte Carlo, one has to come up with variational wave functions, using which to search for the true ground states of quantum systems. The guiding principle of all variational simulations is simply to minimize the energy density, a local property of quantum states, of a given sample. On the other hand, generally distinguishing different quantum phases relies on the long-range physics. Consequently, in these variational methods we are trying to determine long-range physics based on local physics. However, competing quantum phases could have similar energy densities. In fact, it can be shown that different quantum phases could give arbitrarily close energy densities [13,14].

To concretely demonstrate this challenge, let us consider frustrated quantum spin systems, for instance, nearest-neighbor spin- $\frac{1}{2}$ Heisenberg models on the triangular lattice and the kagome lattice. In the triangular lattice case, a good understanding of the ground state is known, based on results

from various numerical simulations [15–18] which show that the system has a long-range 120° coplanar magnetic order. To establish this long-range magnetic order, a statement about the long-range physics, it is important to perform finite-size scaling since most numerical simulations study samples with small to intermediate sizes. The successful identification of the long-range order in the triangular lattice model, to a large extent, is a consequence of the fact that the magnetic ordering in this system is quite strong.¹ Even the finite-size scalings performed quite some time ago [16] on small to intermediate sized samples give clear evidences of the order.

The situation for the kagome lattice model is drastically different. In the past it was known that even if a long-range order does exist in this system, it is very weak. Thus, in order to identify the presence or absence of a long-range order, which represent two different quantum phases (a symmetry-breaking phase and a quantum spin-liquid phase), one needs to perform finite-size scaling in samples with larger sizes. The simulations on these samples become possible only recently due to the progresses in DMRG methods.

Generally speaking, in order to fully determine the quantum phase diagrams of correlated systems in numerical simulations, one cannot avoid studying samples with large sizes, simply because general quantum phases are sharply defined by the long-range physics. But, practically the larger the system size is, the more challenging the simulation is.

But, are all quantum phases only distinguished by long-range physics? Before we provide an answer to this question, it is better to elaborate the question in a slightly sharper way. First, we emphasize that the phase is defined only when the global symmetry of the system is specified, which may or may not be *spontaneously* broken.² When limited to finite-size

¹For instance, the magnetic moment is found to be 0.205(10) in Ref. [16].

²We point out that many topological phases are defined even in the absence of any symmetry. However, when the global symmetry

samples, the ground-state wave functions necessarily form (generally, irreducible) representations of the global symmetry which is usually a combination of onsite symmetries like spin rotations and space-group symmetries like translations. This statement is true even when the global symmetry is spontaneously broken in the long-range physics.

We again demonstrate the above statement in the context of frustrated spin- $\frac{1}{2}$ models. In this context, quantum spin liquids (QSL) are states of matter that do not break translation and spin-rotation symmetries. In particular, evidences of a fully gapped Z_2 QSL were reported in the kagome lattice model mentioned above. Recent theoretical work [19] supports that this Z_2 QSL has a topological order which can be described as a usual Z_2 gauge theory (i.e., the same topological order as in Kitaev's toric code model [20]). In such a Z_2 QSL, quasiparticle excitations include bosonic spin- $\frac{1}{2}$ spinon- e , bosonic vison- m , and their fermionic bound state $f = em$. Suppose that we can tune certain parameters in the spin model, it is possible that either the spinon- e boson condenses, which gives rise to certain long-range magnetically ordered (MO) phase, or the vison- m boson condenses, which gives rise to certain valence bond solid (VBS) phase since visons transform nontrivially under lattice symmetries.

However, in this context, the boson condensations of e or m quasiparticles are only sharply defined in the long-range physics. For instance, imagine one does a numerical simulation for a phase transition between the Z_2 QSL and a nearby MO phase (VBS phase) via e (m) condensation. To avoid possible subtlety due to open boundary conditions, let us consider a finite-size torus sample. The ground-state wave functions on both sides of the phase transition must share the same quantum number in the vicinity of the phase transition. Basically, the quantum phase transition in the long-range physics is not visible on a finite-size sample unless a careful finite-size scaling is performed in large system sizes.³ For this reason, we say that the Z_2 QSL and the nearby MO phase (VBS phase) share the same short-range physics but are distinguished in the long-range physics.

On the other hand, there are lots of examples in which ground states of different candidate quantum phases give distinct symmetry representations on sequences of finite-size samples, which persist all the way to the thermodynamic limit [21–23]. Trivial examples include ferromagnetic phases and paramagnetic phases in spin systems. As a somewhat nontrivial example, in a recent investigation of correlated electronic models on the honeycomb lattice, two candidate quantum phases (the chiral spin density wave phase and the $d + id$ superconductor phase) are found to host distinct lattice

quantum numbers on $4N \times 4N \times 2$ symmetric samples [23]. In these cases, at least on these sequences of samples, clearly these candidate phases really give completely different ground-state wave functions which cannot be smoothly tuned from one to another. These quantum phases must be distinguished by short-range physics. Note that the energy density, minimizing which is the guideline of all variational methods, is also a short-range property of the wave function. *One should have the hope of generically being able to sharply identify candidate phases distinguishable by short-range physics even on small or intermediate sized samples, without worrying about finite-size scalings in larger system sizes.*

Note that we have made statements on “short-range physics” and “long-range physics” without sharply defining their meanings. Now, it is a good moment to comment on the sharp meanings of these terms used in this paper. By “long-range physics,” we really mean the long-range behavior of correlators measured in ground-state wave functions. Such long-range correlators, e.g., spin-spin correlation functions in a spin model, can be interpreted as the conventional Ginzburg-Landau order parameters of quantum phases.

The meaning of “short-range physics” in this paper is more unconventional, by which we really mean how global symmetries are implemented locally in a quantum wave function. We will provide a sharper definition of this term later since we first need to introduce some tools to diagnose a local patch of the whole quantum wave function. But, it is important to mention that this “short-range physics” is directly related to the quantum numbers of ground-state wave functions on finite-size samples. In addition, both short-range physics and long-range physics in this paper are referred to properties of quantum wave functions, even in the absence of specific quantum Hamiltonians.

As an interesting example, let us consider candidate Z_2 QSL that may be realized in the kagome lattice Heisenberg model. Previous studies showed that there exist many time-reversal-symmetric Z_2 QSL phases respecting the full space-group symmetry of the kagome lattice [24–26]. All these Z_2 QSL phases, by definition, are featureless in long-range correlators. So, their distinctions completely lie in the short-range physics.

The above discussions lead to the following intuitive picture. Different quantum phases may be organized into crude classes according to short-range physics. In each class, there may be multiple member phases that are distinguishable by long-range physics. Although identifying a particular quantum phase in a correlated model generally requires careful and challenging finite-size scaling, identifying a crude class should be easier, even without finite-size scaling in large samples. In addition, doing the latter is still very useful. First, it would give us sharp, although incomplete, information about the quantum phase diagram. Second, determining the crude class allows us to focus only on the candidate member phases within one class, which helps identifying the complete phase diagram significantly.

This picture motivates us to separate the task of simulating the quantum phase diagrams into a short-range part and a long-range part, and brings up the following questions. How to systematically, and hopefully completely, characterize these crude classes distinguishable by short-range physics? Can one construct generic variational wave functions for each given

is present, there will be more and finer classification of phases. For instance, consider the $Q_1 = Q_2$ QSL and $Q_1 = -Q_2$ QSL on the kagome lattice mentioned in the main text. If the global symmetry of the system is *not* specified, then both phases are the same. But, in the presence of the lattice symmetry, they are sharply defined as two different phases.

³There is a subtlety about the sharp meaning of the ground-state quantum number in the Z_2 QSL due to the topological ground-state degeneracy on a torus. We will carefully comment on this issue in Sec. VI.

crude class and provide simulation algorithms based on them? The answers to these questions would lead to an efficient numerical method to completely solve the short-range part of the simulation task, which is very useful for the long-range part of the task as well. We will comment further on the sharp information on long-range physics (i.e., spontaneous symmetry breaking) that can be obtained from short-range physics in Sec. VIB.

This paper is an attempt to address these questions to a certain level. Here, we rely on a recently developed language to construct quite generic and physically relevant quantum wave functions: the projected entangled pair states (PEPS) [7,27,28] that are a version of tensor networks. PEPS has been viewed as a powerful and efficient method to represent generic quantum states whose entanglement entropies do not violate the boundary law (see Ref. [29] for a recent review). In addition, in two spatial dimensions, PEPS provides a set of concrete numerical algorithms for practical simulations (for instance, Ref. [30] discusses details of many PEPS algorithms). In this work, we construct generic symmetric wave functions using PEPS under certain assumptions. We find that there are classes of symmetric PEPS which are sharply distinguished by short-range physics. More precisely, the symmetry requirements on PEPS lead to discrete number of solutions. Each solution corresponds to one crude class mentioned above, and constrains a sub-Hilbert space that the tensors in the PEPS must live within.

We find that these classes are related to, but not limited to, fractionalizations of both the onsite symmetries and the space-group symmetries of the system [21,31–40]. These classes are generally characterized by three sets of algebraic data, which are denoted as Θ 's, χ 's, and η 's in this paper. The first set of data (Θ 's) represents the direct contribution to the symmetry quantum numbers of quantum wave functions from each local tensor. The second set of data (χ 's) is related to projective representations of the global symmetry, or the second cohomology group $H^2[\text{SG}, \text{U}(1)]$ in mathematics, where SG is the symmetry group of the system that is generally a combination of onsite symmetries and lattice symmetries. The third set of data (η 's) is related to the so-called projective symmetry group (PSG) [31] characterizing symmetry fractionalizations of topological quasiparticles. Mathematically, η 's are related to the second cohomology group $H^2(\text{SG}, \text{IGG})$, where IGG is some invariant gauge group. We will explain the origin and constraints on IGG in detail later. Different possible IGG actually gives a hierarchical structure of the crude classes. As an example, half-integer spin systems on the square or kagome lattices have IGGs which at least contain a Z_2 subgroup.

Moreover, we provide concrete simulation algorithms based on these symmetric PEPS wave functions in two spatial dimensions (2D) and comment on possible algorithms in higher dimensions. We demonstrate the procedure of crude classifying and constructing symmetric PEPS wave functions for the half-integer spin system on the kagome lattice, in which case 32 distinct classes are found under the assumption that $\text{IGG} = Z_2$. Although we mainly consider 2D systems in this paper, the majority of our discussions can be easily generalized to other spatial dimensions except for the algorithms specific for 2D.

Not surprisingly, the choice of the kagome lattice spin system as the main example in this paper is motivated by the recent reports of a Z_2 QSL in the spin- $\frac{1}{2}$ Heisenberg model [10,11]. It remains an open question that which one of many candidate QSL may be realized in the kagome lattice model.⁴ And, very recently there have been a number of works [41,42] describing how to identify these distinct Z_2 QSL in numerical simulations, based on careful quantum number analysis. In our work, when $\text{IGG} = Z_2$ in a half-integer spin system, every crude class contains a distinct Z_2 QSL as a member phase. Therefore, part of our results can be viewed as a classification and construction of Z_2 QSL for half-integer spin systems on the kagome lattice, which is somewhat finer than the previous classifications for the spin- $\frac{1}{2}$ case [25,26] (see Sec. VII for details), and is generally applicable for other half-integer spins. In addition, the simulation algorithms proposed here can be used to identify the nature of the Z_2 QSL realized in the kagome lattice spin- $\frac{1}{2}$ Heisenberg model efficiently.

For each given crude class, the other member phases can be viewed as ordered phases in the vicinity of the Z_2 QSL member phase, but with a spontaneous symmetry breaking only sharply defined in the long-range physics, e.g., MO phases (via e -condensations) or VBS phases (via m -condensations). *The nonvanishing symmetry-breaking long-range order parameters in these phases are expected to be captured in the present symmetric PEPS construction after performing a scaling with respect to both the virtual bond dimension D (see Sec. II for definition) and system sizes.*

Note that the concepts of invariant gauge groups and projective symmetry groups (PSG) have been used to study and classify symmetry fractionalizations in topologically ordered phases. In this sense, it is not surprising that we find many non-symmetry-breaking Z_2 QSL phases distinct by short-range physics. But, in a conventional symmetry-breaking phase, such as the MO phases or VBS phases mentioned above, there is no topological order and the long-range gauge dynamics is confined. However, due to the generality of the PEPS language, this work suggests that the concepts of invariant gauge groups and projective symmetry groups are useful even in these conventional ordered phases.

This interesting question raised by this work can be rephrased in the following way. *Do the neighboring conventional symmetry-breaking phases still “remember” their parent non-symmetry-breaking liquid phase?* In many situations, the answer to this question is known to be positive. For example, consider the two-parent Z_2 QSL, Sachdev's $Q_1 = Q_2$ state and $Q_1 = -Q_2$ state [24,25,43]. After the spinon- e condensation, they lead distinct long-range MO phases, e.g., so-called $q = 0$ MO (for the $Q_1 = Q_2$ QSL) and $\sqrt{3} \times \sqrt{3}$ MO (for the $Q_1 = -Q_2$ QSL). However, in some other situations, the answer to this question is expected to be negative. For instance, the vison- m condensation in these two Z_2 QSL could lead to the same VBS phase [44]. This phenomenon is related to following fact: for the $Q_1 = Q_2$ state and $Q_1 = -Q_2$ state, the PSGs for the spinon- e are different, but the PSGs for the visons are the same.

⁴In fact, numerical evidences supporting a gapless $\text{U}(1)$ Dirac spin liquid have also been reported [99,100].

Therefore, within the framework proposed in this paper, although one non-symmetry-breaking phase only appears in a single crude class, we cannot rule out the situation that certain special symmetry-breaking phase appears as member phases in multiple crude classes. Namely, it seems possible that two distinct short-range implementations of global symmetry lead to the same symmetry-breaking phase in the thermodynamic limit. We will come back to this issue in Sec. VIB.

This work may be also useful regarding continuous quantum phase transitions. We have mentioned the phase transitions between member phases within one crude class, e.g., the transition between a Z_2 QSL and a nearby MO (VBS) phase. One may wonder whether it is possible to have a continuous phase transition between two phases belonging to distinct crude classes. We believe that this is possible and is related to the hierarchical structure of crude classes due to different IGGs. For instance, one may consider a parent crude class with $\text{IGG} = \text{U}(1)$ that has two distinct descendant $\text{IGG} = Z_2$ crude classes. Two phases belonging to these two distinct $\text{IGG} = Z_2$ crude classes, as a matter of principle, may be connected by a critical point described by the parent $\text{IGG} = \text{U}(1)$ crude class. We leave further discussions on this topic in Sec. VII.

Before moving on to the main body of the paper, we comment on the limitations of this work. First, due to the fact that we use PEPS to construct ground-state wave functions, the discussions in this paper are limited to those quantum phases whose entanglement entropies do not violate the boundary law. For instance, quantum phases with Fermi surfaces are beyond the scope of this work. Even within the PEPS language, our work makes a nontrivial basic assumption: the onsite symmetries are implemented as representations or projective representations on the virtual degrees of freedom in PEPS.⁵ This assumption, although it appears natural on the superficial level, is nontrivial and gives rise to limitations.

This problem is related to the recently developed understandings on symmetry-protected topological (SPT) phases [45] as well as phases with chiral edge states. SPT phases are gapped quantum phases without anyon excitations and protected by various global symmetries. They are generalizations of the topological insulators (see Refs. [46,47] for reviews) in noninteracting fermion systems. It is known that when attempting to represent SPT phases or states with chiral edge states using PEPS in two and higher spatial dimensions, the constraint that the onsite symmetry transforms as representations or projective representations on virtual degrees of freedoms lead to problems, at least in the long-range physics. For example, a fermion state with nonzero Chern number constructed using PEPS with a fixed bond dimension D under the above constraint is found to have power-law correlations in real space [48–50].

This paper is organized as follows. In Sec. II, we introduce some basics of PEPS. In particular, we discuss gauge redundancy as well as the implementation of symmetries in PEPS. We introduce a special kind of gauge transformation named as invariant gauge group (IGG). In phases with no symmetry breaking, IGG leads to low-energy gauge dynamics.

Further, for fractional filled systems, there are minimal required nontrivial IGGs for any symmetric PEPS under our basic assumption. This phenomenon is consistent with the Hastings-Oshikawa-Lieb-Schultz-Mattis theorem [51–53]. In Sec. III, we classify symmetric PEPS according to their distinct short-range physics, which is characterized by algebraic data Θ 's, χ 's, and η 's. Relations of the data χ 's and η 's to second cohomology are discussed. An introduction of relevant mathematics is given in Appendix C. As a main example, we give the classification result for symmetric PEPS on the kagome lattice with a half-integer spin per site and $\text{IGG} = Z_2$, and obtain the constraints on the sub-Hilbert spaces for local tensors for each given class. The detailed calculation is presented in Appendix B. A simpler and pedagogical example on the square lattice can be found in Appendix F. We also give efficient algorithms for minimization of energy density for a given class of PEPS, which can be used to identify these crude classes in interacting quantum systems. We give the physical interpretation of the algebraic data in Sec. IV. Particularly, we construct fractionalized symmetry operators to explicitly show that η 's are describing the symmetry fractionalization of spinons in the Z_2 QSL member phase. Detectable signatures of the data Θ 's, χ 's, and η 's are discussed. In Sec. V, we construct a decorated version for symmetric PEPS, which serves as a more convenient tool to study properties of visons in the Z_2 QSL member phase and the properties of the vison-condensed phases. Algebraic methods to extract the information of the symmetry fractionalization on visons are given. In Sec. VI, we discuss symmetry-breaking phases in the symmetric PEPS formulation, and study the effects of the symmetry-breaking orders in finite-size scaling on torus samples. In Sec. VII, we consider generalizations and limitations of our study, comment on relations with previous works, and conclude.

II. SYMMETRY, GAUGE, AND PEPS

In this section, we will give a brief introduction to PEPS. As we will see later, even for the same many-body wave function, the PEPS representations are not unique, and different representations are connected by gauge transformations. Further, we will study the implementation of symmetry on PEPS as well as the gauge dynamics in the PEPS language. Particularly, for certain systems, gauge structures will naturally emerge.

A. Introduction to PEPS

Projected entangled pair states (PEPS) are a type of tensor networks (TN). The basic ingredients of TN are “legs,” and every leg is associated with a Hilbert space, as seen in Fig. 1(a). In the following, we will use “leg” to denote the associated Hilbert space. As shown in Fig. 1(b), tensors formed by several legs simply describe quantum states living in the tensor product of these legs,

$$T^{abc\dots} \in \mathbb{V}^a \otimes \mathbb{V}^b \otimes \mathbb{V}^c \otimes \dots, \quad (1)$$

where \mathbb{V}^i labels Hilbert space associated with leg i . If two legs are the bra space and the ket space of the same set of quantum states, they are named as dual space to each other. New tensors can be obtained by contracting states in dual spaces, or by tracing out states in dual spaces, as shown in Fig. 1(c).

⁵It has been shown that injective PEPS will lead to our assumption [54], but not the other way around.

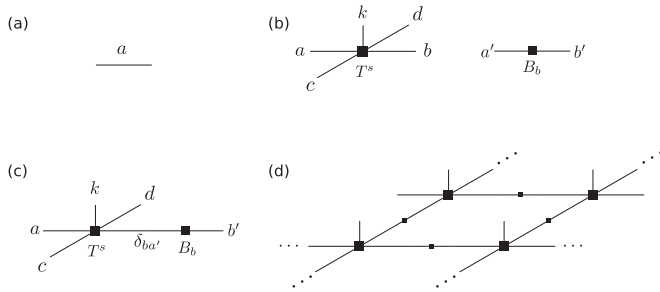


FIG. 1. (a) The leg a is associated with the Hilbert space \mathbb{V}^a . (b) The site tensor (left) and the bond tensor (right) label quantum states on Hilbert spaces of tensor products of corresponding legs. (c) A new tensor can be obtained by contraction of the leg b on T^s and the leg a' on B_b , which can be expressed as $(T^s)^k_{abcd}(B_b)_{a'b'}\delta_{ba'}$. Note that we require leg b and leg a' to be dual spaces. (d) The whole PEPS wave function is obtained by contracting all virtual legs of site tensors and bond tensors.

A TN representation of many-body wave function can be viewed as a large tensor, which is obtained by contracting small building block tensors. Thus, a TN is formed by uncontracted legs (physical legs) and contracted legs (virtual legs). From another point of view, we can also treat a TN as a combination of a linear map from the virtual Hilbert space (the tensor product of all virtual legs) to the physical Hilbert space, together with an “input” virtual state.

Let us construct a PEPS on a two-dimensional lattice. We first put tensors at both sites and bonds, named as site tensors (T^s) and bond tensors (B_b), respectively [see Fig. 1(b)]. Every site tensor can be viewed as a linear map from several virtual legs to one physical leg, while a bond tensor, which is in fact a matrix, labels a quantum state (bond state) in the tensor product space of two virtual legs. Thus, as shown in Fig. 1(d), by contracting virtual legs of site tensors with bond tensors, we get a PEPS as a combination of a linear map from the virtual Hilbert space to the physical Hilbert space together with an input virtual state, where the map is given by the tensor product of all site tensors and the input state is the tensor product of all bond states. We can express the PEPS representation of the wave function as

$$|\psi\rangle = \sum_{\{k_s\}} \text{tTr}[(T^1)^{k_1} \dots (T^{N_s})^{k_{N_s}} B_1 \dots B_{N_b}] |k_1 \dots k_{N_s}\rangle, \quad (2)$$

where $1, 2, \dots, N_s$ (N_b) label sites (bonds), while k_s is the physical index. tTr means tensor trace, namely, contraction of all virtual legs.

We define that a bond tensor (matrix) is a maximal entangled state, iff singular values of this matrix all equal some nonzero constant. By multiplying some constant, we can simply set singular values of maximal entangled states to be 1. When performing numerical simulations, it is more convenient to use maximal entangled bond states, or even set bond tensors to be identity matrices. As we will see later, by using the gauge redundancy of PEPS, it is always possible to do so.

In the following, we will assume that all virtual legs label Hilbert spaces with the same dimension D , while a physical leg is associated with a d -dimensional Hilbert space.

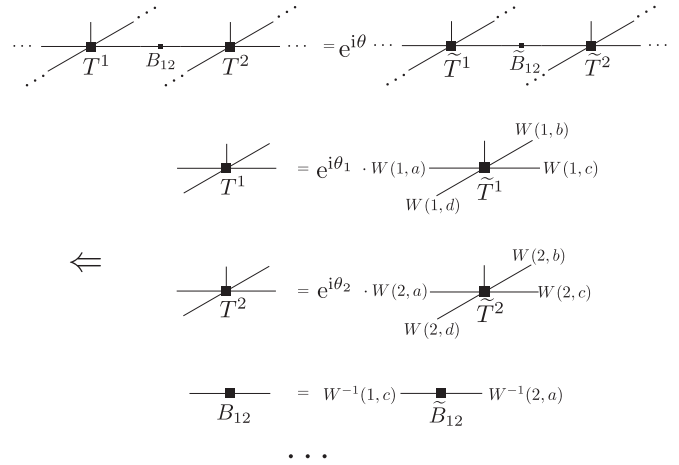


FIG. 2. Two PEPS describe the same quantum state, iff they differ by gauge transformation together with $U(1)$ phase factor. The origin of the gauge transformation is that we can multiply identity matrix $I = W W^{-1}$ between connected legs, which changes site tensors and bond tensors, but leave the whole wave function invariant. We can also view TN on the left as PEPS transformed by symmetry operation. Thus, this figure also expresses the condition for PEPS wave function to be symmetric.

B. Gauge transformation on PEPS

The representation of a many-body wave function on PEPS is far from unique. Particularly, as shown in Fig. 2, we are always allowed to multiply W and W^{-1} to two connected virtual legs, respectively. This action will change the connected small tensors while leaving the contracted tensor invariant:

$$(T^s)^k_{abcd} \delta_{ba'} (B_b)_{a'b'} = [(T^s)^k_{abcd} W_{bl}] \delta_{ll'} [(W^{-1})_{l'a'} (B_b)_{a'b'}]. \quad (3)$$

Every contracted pair of virtual legs will contribute a gauge redundancy $GL(D, \mathbb{C})$. All such gauge transformations form a group $[GL(D, \mathbb{C})]^{2N_b}$ which we call the gauge transformation group of the PEPS (N_b is the number of bond tensors in the TN). The meaning of the gauge transformation can be understood as a change of basis on virtual legs.

From another point of view, in general, for two PEPS whose tensors differ at most by gauge transformations defined above together with overall $U(1)$ phase factors, as shown in Fig. 2, the two PEPS must describe the same physical state [up a $U(1)$ phase]. In principle, these overall $U(1)$ phase factors can occur in gauge transformations on both site tensors and bond tensors. But, it is straightforward to redefine the gauge transformations such that the phase factors only appear on site tensors. Mathematically, two PEPS denoted by $\{\tilde{T}^s, \tilde{B}_b\}$ and $\{T^s, B_b\}$, respectively, describe the same physical state if there exist gauge transformations $\{W(s, i)\}$ and $U(1)$ phase factors $\{e^{i\theta(s)}\}$ (s labels a site and i labels a virtual leg on the site), such that

$$(T^s)^k_{\alpha\beta\dots} = e^{i\theta(s)} [W(s, 1)]_{\alpha\alpha'} [W(s, 2)]_{\beta\beta'} \dots (\tilde{T}^s)^k_{\alpha'\beta'\dots},$$

$$(B_b)_{\alpha\beta} = [W(b, 1)]_{\alpha\alpha'} [W(b, 2)]_{\beta\beta'} (\tilde{B}_b)_{\alpha'\beta'}. \quad (4)$$

Here, $W(b, j)$ represents a gauge transformation on the leg j of the bond tensor B_b , and if a site leg (s, i) and a bond leg (b, j)

are connected, then $W(s,i) = [W(b,j)^{-1}]^t$. (The superscript t stands for the matrix transpose.)

C. Symmetric PEPS

The purpose of this section is to introduce a generic way to implement both onsite symmetries [54–60] and lattice space-group symmetries [54] on PEPS. We first discuss the finite-size symmetric quantum state that can be represented by a single PEPS; i.e., such a state would form a one-dimensional representation of the symmetry group. Then, we define the symmetric PEPS on an infinite lattice, which is the main object to be (partially) classified in this study.

1. Onsite unitary symmetries

The action of a global onsite unitary symmetry S on a finite-size PEPS wave function is defined as

$$S|\psi\rangle = |\tilde{\psi}\rangle = \sum_{\{k_s\}} \text{tTr}[(T^1)^{k_1} \dots (T^{N_s})^{k_{N_s}} B_1 \dots B_{N_b}] \times U_S \otimes U_S \dots |k_1 k_2 \dots k_{N_s}\rangle. \quad (5)$$

U_S is the representation of S on Hilbert space of physical leg. These local actions of an onsite symmetry give a new TN, with site tensors \tilde{T}^s and bond tensors \tilde{B}_b defined as

$$\tilde{T}^s = S \circ T^s = \sum_l (U_S)_{kl} (T^s)^l, \quad \tilde{B}_b = S \circ B_b = B_b. \quad (6)$$

We focus on those PEPS that are invariant under the global symmetry up to an overall $U(1)$ phase factor. Following the discussion in the previous section, we consider the PEPS $|\psi\rangle$ that differs from the transformed PEPS $|\tilde{\psi}\rangle$ only by gauge transformations together with overall phase factors, as shown in Fig. 2:

$$T^s = \Theta_S W_S S \circ T^s, \quad B_b = W_S S \circ B_b \quad (7)$$

Here, gauge transformation W_S and phase factor Θ_S associated with symmetry S are defined as

$$\begin{aligned} \Theta_S \circ T^s &= e^{i\theta_S(s)} (T^s)_{\alpha\beta\gamma\delta}^k, \\ W_S \circ T^s &= [W_S(s,1)]_{\alpha\alpha'} [W_S(s,2)]_{\beta\beta'} \dots (T^s)_{\alpha'\beta'\dots}^k, \\ W_S \circ B_b &= [W_S(b,1)]_{\alpha\alpha'} [W_S(b,2)]_{\beta\beta'} (B_b)_{\alpha'\beta'}. \end{aligned} \quad (8)$$

According to the definition of a gauge transformation, if site virtual leg (s,i) and bond leg (b,j) are connected, then $W_S(s,i) = [W_S(b,j)^{-1}]^t$. Further, we always choose W_S such that only site tensors transform with extra $U(1)$ phase factors. Note that so far we do not require matrices on the leg (s,i) $W_S(s,i)$ to form a representation of the onsite symmetry group when S is tuned. We will come back to this shortly.

2. Time-reversal symmetry

The representation of the global time-reversal symmetry \mathcal{T} on a many-body wave function is $U_{\mathcal{T}} \otimes U_{\mathcal{T}} \dots K$, where K denotes the complex conjugation and $U_{\mathcal{T}}$ is a unitary matrix acting on local physical Hilbert space. Its action on PEPS is

defined as

$$\begin{aligned} \mathcal{T}|\psi\rangle &= \sum_{\{k_s\}} \text{tTr}[(T^1)^{k_1} \dots (T^{N_s})^{k_{N_s}} B_1 \dots B_{N_b}]^* \\ &\times U_{\mathcal{T}} \otimes U_{\mathcal{T}} \dots |k_1 k_2 \dots k_{N_s}\rangle, \end{aligned} \quad (9)$$

namely, the local actions on a single site or a bond tensor read as

$$\begin{aligned} \tilde{T}^s &= \mathcal{T} \circ T^s = \sum_l (U_{\mathcal{T}})_{kl} (T^s)^{*l}, \\ \tilde{B}_b &= \mathcal{T} \circ B_b = B_b^*. \end{aligned} \quad (10)$$

We consider the PEPS that is symmetric under \mathcal{T} . Similar to the previous discussion, we consider a PEPS satisfying

$$\begin{aligned} T^s &= \Theta_{\mathcal{T}} W_{\mathcal{T}} \mathcal{T} \circ T^s, \\ B_b &= W_{\mathcal{T}} \mathcal{T} \circ B_b, \end{aligned} \quad (11)$$

where $W_{\mathcal{T}}$ belongs to the gauge transformation group of the PEPS.

3. Lattice symmetry

The definition of a lattice space-group symmetry R on PEPS is

$$\begin{aligned} \tilde{T}^s &= R \circ (T^s)^k \equiv \sum_{\alpha\beta\dots} (T^{R^{-1}(s)})_{R^{-1}(\alpha\beta\dots)}^k, \\ \tilde{B}_b &= R \circ B_b \equiv \sum_{\alpha\beta} (B_{R^{-1}(b)})_{R^{-1}(\alpha\beta)}. \end{aligned} \quad (12)$$

The action of R on site and bond tensor follows the natural definition of lattice symmetries. For instance, for a square lattice, after a translation along the right direction by one lattice spacing, the transformed site tensor at a given position equals the original site tensor on the left neighboring site. Note that the symmetry R not only acts on site and bond indices; it may also act nontrivially on virtual legs. For example, the 90° rotation of a site tensor on the square lattice permute the four virtual legs. Again, we consider those PEPS symmetric under R satisfying the following conditions:

$$\begin{aligned} T^s &= \Theta_R W_R R \circ T^s, \\ B_b &= W_R R \circ B_b, \end{aligned} \quad (13)$$

where W_R belongs to the gauge transformation group of the PEPS.

4. Symmetric PEPS on infinite lattices

Space groups of lattices are usually defined for infinite lattices. This is because for a finite-size sample, the lattice symmetry group is a finite group whose group structure is nongeneric. In this paper, we will focus on PEPS on infinite lattices satisfying Eqs. (7), (11), and (13) under symmetry transformations. And, we define such PEPS as symmetric PEPS on infinite lattices, or simply as symmetric PEPS. They form the main object to be (partially) classified in the current investigation.

A natural question that arises at this point is as follows: Are symmetric PEPS defined above general enough to capture ground states of quantum phases? Let us limit our discussion

within those quantum phases whose entanglement entropies do not violate the boundary law so that in principle they may be represented as PEPS.

Basically, we expect that the symmetric PEPS on infinite lattices defined above are capable to capture all non-symmetry-breaking liquid phases. After putting on finite lattices and performing a scaling with respect to both the bond dimension D and lattice sizes, we expect the symmetric PEPS are also capable to capture the neighboring ordered phases of the liquid phases. Here, by “neighboring” (or “in the vicinity below”), we mean that the symmetry breaking in these phases is only sharply defined in the thermodynamic limit (namely, in the long-range physics). Note that we do not have a proof supporting the statement above. Nevertheless, we are not aware of any counterexamples, so at least it is a reasonable conjecture.⁶

Sometimes one is forced to use more than one PEPS to represent ground-state quantum wave functions. For instance, in a quantum spin system with SU(2) spin-rotation symmetry, this happens for the ferromagnetic phase, whose ground states form a large spin representation. However, such ferromagnetic phases are *not* in the vicinity of any non-symmetry-breaking liquid phases.

So far, we do not require the transformations matrices W 's on the virtual legs to form representations or even projective representations for the onsite unitary symmetries and the time-reversal symmetry. As mentioned before, such a requirement leads to difficulties to represent SPT phases in two and higher spatial dimensions (and SPT phases are non-symmetry-breaking liquid phases). Indeed, if one translates the ground states of the exact solvable models of SPT phases with onsite symmetries into the language of PEPS, one still finds PEPS satisfying Eq. (7) [61]. But, the transformation matrices W 's form neither representations nor projective representations of the onsite symmetry group.

Generally classifying symmetric PEPS defined here is a difficult task and we currently do not know how to solve. Next, we will introduce the invariant gauge group for PEPS and will make further assumptions so that we could make progress on this difficult task.

D. Invariant gauge group and gauge structure

Among the gauge transformations, there is a special subgroup which we call the invariant gauge group (IGG). Note that generally a gauge transformation will leave the physical wave function invariant while transforming the site tensors and bond tensors nontrivially in a PEPS. However, by definition, the action of IGG elements on PEPS even leaves all site tensors invariant up to overall U(1) phases and all bond tensors completely invariant.⁷ So, IGG can be viewed as the

“symmetry” of the building block tensors with actions only on virtual legs.⁸ In the following, we will see that IGG is directly related to gauge dynamics [13,62–64]. We will also give examples where nontrivial IGG's emerge naturally in fractional filled systems under a basic assumption.

Note that the collection of all gauge transformations that leave all site tensors invariant up to overall U(1) phases and bond tensors completely invariant forms an infinite group, which we denote as $\overline{\text{IGG}}$. These gauge transformations satisfy Eq. (4) with $\tilde{T}^s = T^s, \tilde{B}_b = B_b$. Namely, a gauge transformation $\{W(s,i)\}$ is in the $\overline{\text{IGG}}$ of a PEPS formed by $\{T^s, B_b\}$ iff it satisfies

$$(T^s)_{\alpha\beta\dots}^k = e^{i\theta(s)} [W(s,1)]_{\alpha\alpha'} [W(s,2)]_{\beta\beta'} \dots (T^s)_{\alpha'\beta'\dots}^k, \\ (B_b)_{\alpha\beta} = [W(b,1)]_{\alpha\alpha'} [W(b,2)]_{\beta\beta'} (B_b)_{\alpha'\beta'}, \quad (14)$$

for certain U(1) phase factors $\{e^{i\theta(s)}\}$. Here, $W(b,j)$ represents a gauge transformation on the leg j of the bond tensor B_b , and if a site leg (s,i) and a bond leg (b,j) are connected, then $W(s,i) = [W(b,j)^{-1}]^t$.

Clearly, if certain gauge transformation $\{W(s,i)\}$ belongs to $\overline{\text{IGG}}$, then one can straightforwardly multiply U(1) phases $\chi(s,i)$ to the $W(s,i)$ matrices: $\{W(s,i)\} \rightarrow \{\chi(s,i)W(s,i)\}$ and obtain another element in $\overline{\text{IGG}}$, if $\chi(s,i) = \chi^*(s',i')$ when (s,i) and (s',i') are the two virtual legs connected by one bond tensor. If we view the U(1) phase factors $\{\chi(s,i)\}$ leaving the bond tensors completely invariant as a special kind of gauge transformation, they form an infinite Abelian subgroup in the center of $\overline{\text{IGG}}$, which we denote as the χ group since they commute with any gauge transformations.

In general, one should work with the infinite group $\overline{\text{IGG}}$. In this paper, for simplicity, we define IGG as the quotient group

$$\text{IGG} \equiv \frac{\overline{\text{IGG}}}{\chi \text{ group}}. \quad (15)$$

In addition, we will mainly focus on the cases in which IGG is a simple finite Abelian group Z_n . In this situation, it is straightforward to show that $\overline{\text{IGG}} = \text{IGG} \times \chi \text{ group}$, indicating IGG is just a simpler way to express $\overline{\text{IGG}}$. This also means that we could equally view IGG as a Z_n subgroup of $\overline{\text{IGG}}$. In particular, there exist a generator $g \in \overline{\text{IGG}}$, but $g \notin \chi \text{ group}$ and g satisfies $g^n = I$ where I is the identity gauge transformation: the do-nothing gauge transformation.

Note that if IGG is a more complicated group, since the center extension with respect to χ group can be nontrivial, it is possible that $\overline{\text{IGG}} \neq \text{IGG} \times \chi \text{ group}$. In this situation, it is better to directly work with $\overline{\text{IGG}}$.

straightforwardly redefine the gauge transformation so that the bond tensors are completely invariant.

⁸IGG is closely related to the concept of G injectivity proposed in Ref. [54], which is used to characterize topological order of toric code type with gauge symmetry G in PEPS. Further, G injectivity is generalized to twisted G injectivity as well as MPO injectivity, which can characterize more exotic topological order [101,102] or even topological order with chiral edge states [103,104]. However, these phases are beyond the scope of the current IGG framework in our paper.

⁶On the other hand, this conjecture may be due to our current lack of understanding. For example, we are not aware how to construct a fully gapped (i.e., with correlators falling off exponentially) bosonic integer quantum Hall liquid using a symmetric PEPS with a finite bond dimension D . But, there is no known principle forbidding such a construction.

⁷One could consider a gauge transformation leaving both site tensors and bond tensors up to overall U(1) phases. However, one can always

1. IGG and gauge dynamics

Here, we will discuss the physical meaning of IGG. We use $\text{IGG} = Z_2$ as an example. The following discussion can be easily generalized to other IGG groups.

First, let us clarify the action of Z_2 IGG on PEPS. Every virtual leg accommodates a representation of $Z_2 = \{I, g\}$. Note that we do not require representations on different legs to be the same. However, we require two connected legs accommodate representations dual to each other, so that applying the g actions on connected legs is just a special gauge transformation. The nontrivial Z_2 IGG element is an action of g on all virtual legs. Following the definition of IGG, all site tensors are invariant up to ± 1 and all bond tensors are completely invariant under this action, as shown in Fig. 3(a). Further, it is straightforward to derive that any patch cut from PEPS is invariant up to ± 1 under the g actions on boundary virtual legs, as shown in Fig. 3(b).

The physical meaning of IGG is related to the gauge dynamics. To see this, let us first review the Z_2 gauge theory. There are two phases in the Z_2 gauge theory: the deconfined phase and the confined phase. In the deconfined phase, the Z_2 gauge theory describes Z_2 topological order (toric code). The low-energy excitations include four types of quasiparticles: the trivial particle 1, the chargin e , the fluxon m , and the bound state of chargin and fluxon $f = em$. e , m , and f can only be created in pairs. Each particle is its own antiparticle, $e^2 = m^2 = f^2 = 1$. e, m are bosons while f is a fermion. The braiding statistics of the three nontrivial particles are mutually fermionic. In the confined phase, topologically nontrivial quasiparticles are confined.

To see the connection between IGG and the gauge theory, let us create nontrivial excitations on PEPS with Z_2 IGG. We can define e particles living on sites while m particles living

on plaquettes. As shown in Fig. 3(c), to create two m particles in neighboring plaquettes, we simply multiply the nontrivial Z_2 element g on one of two contracted virtual legs shared by the two plaquettes. The insertion of g only on one side of contracted legs is not a gauge transformation, and in general will change the wave function. One can also create a pair of m particles spatially separated from each other by applying the single-sided g actions over a string of bonds. The fluxons are located at the end of the string. Note that although the positions of fluxons are physical, the position of the string connecting them is not physical since one can perform Z_2 gauge transformations on site tensors to move the string around while leaving the physical wave function invariant.

Now, let us turn to e particles. Let us first define Z_2 even/odd tensors. The action of g on boundary virtual legs of a tensor generally gives a phase factor ± 1 . If the phase factor is $+1/-1$, we call it Z_2 even/odd. The Z_2 parities of tensors depend on the representations of g on virtual legs. If we do not worry about the lattice symmetry for the moment, for a Z_2 even/odd tensor, we can simply redefine g on one virtual leg by -1 , thus this tensor becomes Z_2 odd/even. So, we can assume all tensors are Z_2 even for the remaining discussion in this section. Creating an e particle on a single site corresponds to changing the site tensor from Z_2 even to Z_2 odd, as seen in Fig. 3(d). To detect the number of chargons on a patch of PEPS, we simply apply g on all boundary virtual legs; namely, we create an m loop on the boundary. If there is an odd number of chargons on that patch, this patch tensor should be Z_2 odd and the g action on the boundary picks up a -1 [see Fig. 3(e)]. This -1 can be understood as the Berry phase from braiding e and m . One can easily convince oneself that an odd number of chargons cannot be created on a closed manifold.

If $\text{IGG} = Z_2$ PEPS describe deconfined phases, then separating topological quasiparticles is expected to cost zero tension. Consequently, one can insert m loops wrapping around torus holes to construct the fourfold-degenerate ground states on a torus. However, if $\text{IGG} = Z_2$ PEPS describe confined phases, which we expect to be possible after a scaling with both bond dimension D and system sizes, this is no longer true. We will comment further on this in Sec. VI.

As a final remark, there turns out to be two distinct types of Z_2 gauge theories: the toric code theory and the double-semion theory [20,65,66]. They have distinct topological orders; e.g., the topological spins (the exchange statistics phases) of quasiparticles are $[1, 1, 1, -1]$ ($[1, 1, i, -i]$) for the $[1, e, m, em]$ particles in a toric code (double-semion) topological order. We emphasize that the $\text{IGG} = Z_2$ PEPS discussed here, when describing a deconfined phase, hosts the toric code topological order. The simplest way to see this is to realize the self-braiding statistics phases of both the e and the m in the $\text{IGG} = Z_2$ PEPS are trivial, so they cannot be semions.

Indeed, when moving an e chargin around a loop by a sequence of hoppings, one realizes the Berry's phase is independent of whether there are other e chargons inside the loop. Similarly, when moving an m fluxon around a loop (giving rise to an m loop), the topological Berry's phase is simply ± 1 depending on the Z_2 parity of the PEPS patch inside the loop, independent of whether there are other m fluxons inside the loop.

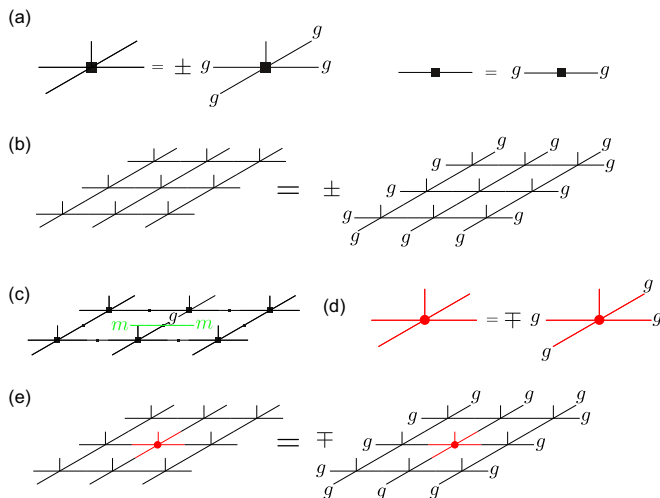


FIG. 3. (Color online) (a) Site tensor and bond tensor are both invariant under Z_2 action on all virtual legs of tensors. (b) Tensors obtained by contracting Z_2 invariant tensors are also Z_2 invariant. (c) Acting g on one virtual leg of single bond tensor creates two fluxons (m) in plaquettes sharing the bond. (d) Z_2 odd tensor indicates there sitting a chargin. (e) By applying g (or creating fluxon loop) on the boundary of a region, we are able to determine chargin number is even or odd inside this region.

2. Natural emergence of nontrivial IGG

We will show that, under a basic assumption, the symmetric PEPS for certain quantum systems must have nontrivial IGG's. *This basic assumption is that the W matrices on every virtual leg form (generally reducible) representations or projective representations for the onsite symmetries* [see Eqs. (7) and (11)]. Under this assumption, the nontrivial IGG in certain systems is a natural consequence of the global symmetry, even in the absence of specific Hamiltonians.

Consider a spin- $\frac{1}{2}$ system on a square lattice; i.e., the physical leg on every site tensor is a two-dimensional spin- $\frac{1}{2}$ Hilbert space. For this system, we will show a symmetric PEPS under the basic assumption must feature an IGG containing a Z_2 subgroup. Since $SU(2)$ spin-rotation group has no projective representations, the basic assumption ensures that every virtual leg must form a representation of $SU(2)$, which generally is a direct sum of a number of half-integer spin representations and a number of integer spin representations. Equation (7) now has the following simple interpretation: the site tensors are spin singlets formed by the virtual spins and the physical spin- $\frac{1}{2}$, and the bond tensors are spin singlets formed by the virtual spins only.

Now, we can consider the particular 2π $SU(2)$ rotation, and denote the corresponding $W(s,i)$ matrix on a virtual leg (s,i) as $J(s,i)$, which is simply a direct sum of the minus identity transformation in the half-integer spin subspace and the identity transformation in the integer spin subspace. Next, consider the combination of transformations $\{J(s,i)\}$ acting on the virtual legs only; this is a particular gauge transformation. Since the physical spin- $\frac{1}{2}$ only picks up an overall -1 in the 2π $SU(2)$ rotation, and the bond tensors are spin singlets, we know that the gauge transformation $\{J(s,i)\}$ is an element in IGG.

To see this system featuring a nontrivial IGG, we only need to show $\overline{\text{IGG}} \neq \chi$ group. We will demonstrate that the gauge transformation $\{J(s,i)\} \notin \chi$ group. To do this, we impose the C_4 rotational symmetry and the translation symmetry of the square lattice. Note that $\{J(s,i)\} \in \chi$ group if and only if for every virtual leg, the dimension of either the half-integer spin subspace or the integer spin subspace vanishes. However, this cannot be true. The site tensor is a spin singlet, which requires the virtual legs to combine into a spin- $\frac{1}{2}$ so that it can further combine with the physical spin- $\frac{1}{2}$ to form a singlet. Therefore, if $\{J(s,i)\} \in \chi$ group, on a single-site tensor, we must have an odd number of virtual legs which contain purely half-integer spins while the remaining virtual legs contain purely integer spins. This explicitly breaks the C_4 rotational symmetry.

Consequently, there is at least one element $J \equiv \{J(s,i)\}$ in $\overline{\text{IGG}}$ but not in χ group, and $J^2 = e$. This tells us that IGG at least contains a Z_2 subgroup $\{I, J\}$.

The above argument can be easily generalized to other symmetries, such as the time-reversal symmetry. For the time-reversal symmetry, consider a system with one Kramer doublet on every physical leg. To form a Kramer singlet PEPS, one must combine an odd number of Kramer doublets on virtual legs of every site tensor. However, for site tensors on a square lattice, there are even number (four) of virtual legs per site, and the C_4 symmetry dictates that the transformation

T^2 on virtual legs only gives a nontrivial element of the IGG which is at least Z_2 .

We point out that translational symmetry itself is enough for the above argument and one does not necessarily consider C_4 . This is because translational symmetry relates the left (down) virtual leg with the right (up) virtual leg connected to the same site tensor via the fact that the virtual legs connected by a bond need to form a spin singlet (or a Kramer singlet). What is really important for the above argument is the existence of a half-integer spin (or a Kramer doublet) per unit cell. One way to see this is to consider a honeycomb lattice with spin- $\frac{1}{2}$ per site, i.e., two spin- $\frac{1}{2}$'s per unit cell. In this case, every site has three virtual legs and it is possible to construct symmetric PEPS wave functions with purely half-integer spins on virtual legs, in which case the 2π spin rotation on the virtual legs only becomes an element in the χ group.

Next, let us consider a system with fractional filled hard-core bosons and see how a nontrivial IGG naturally emerges. As an exercise, we can simply translate the previous discussions on spin- $\frac{1}{2}$ systems into $\frac{1}{2}$ -filled hard-core boson systems on the square lattice. The physical leg for the hard-core bosons is two-dimensional Hilbert space with basis labeled as $|0\rangle$ and $|1\rangle$. When mapped to a spin- $\frac{1}{2}$ system, $|0\rangle$ ($|1\rangle$) is identified as the down spin (up spin). The $U(1)$ charge transformation for the hard-core boson system can be written as $\exp[i\theta(S_z^i + \frac{1}{2})]$ using the spin operator on the leg i . Note that spin-0 is identified as charge- $\frac{1}{2}$, a projective representation of the charge $U(1)$. Since a bond tensor is a spin singlet formed by two virtual spins in the spin language, the representation of $U(1)$ group in the hard-core boson language on a bond tensor is

$$[e^{i\theta(S_z^a + \frac{1}{2})} e^{i\theta(S_z^b + \frac{1}{2})}]^* = e^{-i\theta}, \quad (16)$$

where the complex conjugation comes from the fact that bond virtual legs transform as conjugate representation of site virtual legs, and we have used $S_z^a + S_z^b = 0$ for the two virtual legs a and b . So, every bond tensor carries charge -1 .

Further, since the site tensor is also a spin singlet, we require $\sum_{i=0}^5 S_z^i = 0$, where $i = 0$ labels the physical leg and other $i \neq 0$ label virtual legs. Therefore, the representation of $U(1)$ symmetry on a site tensor reads as

$$\prod_{i=0}^4 e^{i\theta(S_z^i + \frac{1}{2})} = e^{i\frac{5}{2}\theta}, \quad (17)$$

namely, every site tensor carries charge $\frac{5}{2}$. Consequently each unit cell carries charge $\frac{1}{2}$.

Note that in this exercise, the bond tensor transforms nontrivially under $U(1)$, so the virtual leg transformation $W = e^{i\theta(S_z + \frac{1}{2})}$ does not satisfy Eq. (7) in our definition of symmetric PEPS. But, one could easily redefine the virtual leg transformation W 's so that the charge carried by the bond is absorbed to a neighboring site, and Eq. (7) is satisfied using the redefined W 's.

The essential results from previous discussions on the spin- $\frac{1}{2}$ systems can now be translated as the following statement: the virtual leg hosts both integer charges and half-integer charges of $U(1)$, so 2π rotation of $U(1)$ symmetry on all virtual legs gives the nontrivial Z_2 IGG.

In the following, on the square lattice, we provide a general argument that a nontrivial minimal required IGG emerges for a symmetric PEPS with fractional-filled bosons under our basic assumption. Further, this minimal required IGG is given by the 2π rotation of the U(1) symmetry on the virtual legs only.

First, we have the physical legs carrying integer charges. And, if the tensor network is symmetric under the U(1) symmetry, for site tensors and bond tensors, we can rewrite Eq. (7) as

$$\begin{aligned} W_S S \circ T^S &= \Theta_S T^S, \\ W_S S \circ B_b &= \Theta_S B_b, \end{aligned} \quad (18)$$

where symmetry operation S can be any U(1) group element. Note that we put Θ_S operation on bond tensors as well to pick up the possible phase factors. As mentioned before, this phase factor on the bond can always be tuned away by redefining W_S . But, for the moment, let us keep it since we want to include the previous exercise.

We can view the left side as the U(1) action on a site/bond tensor. Under the basic assumption, the above equation indicates every site/bond tensor carries a fixed U(1) charge, which can be a fractional charge. In the presence of the lattice symmetry, we expect all virtual legs of site tensors share the same U(1) reducible projective representation. (Virtual legs of bond tensors have the conjugate representation.) Our plan is to assume the 2π rotation of U(1) symmetry is trivial (only a phase factor) on the virtual leg, and then demonstrate a contradiction. This assumption dictates that the irreducible charges carried by a virtual leg can only differ by integer numbers. Namely, the basis for virtual legs of site tensors can be written as

$$\{|x\rangle, |x+n_1\rangle, |x+n_2\rangle, \dots\}, \quad (19)$$

where x can be any fractional number and n_i are integers. Under symmetry operation U_θ , state $|x+i\rangle$ transform as

$$U_\theta |x+n_i\rangle = e^{i\theta(x+n_i)} |x+n_i\rangle. \quad (20)$$

So, 2π rotation on any state of the above Hilbert space will give the same phase factor $e^{ix\theta}$. Similarly, the basis for bond legs is

$$\{|-x\rangle, |-x-n_1\rangle, |-x-n_2\rangle, \dots\}. \quad (21)$$

Recall that a single tensor should carry a fixed charge. Consequently, a bond tensor should carry charge $-2x - n_b$, where n_b is some integer. And, a site tensor should carry charge $4x + n_s$. Since the physical leg only carries integer charges, n_s should also be an integer. We then conclude that, for a single unit cell, the charge should be $n_s - n_b$, which must be an integer. This contradicts with the fact that the system is at a fractional filling. Therefore, to construct a symmetric PEPS at a fractional filling under our basic assumption, the 2π rotation of U(1) symmetry must be nontrivial on all virtual legs, and the nontrivial IGG naturally emerges.

We discussed the naturally emerged IGG in certain quantum systems. It is possible for the ground-state symmetric PEPS to have a larger IGG which contains the naturally emerged IGG as a subgroup. We call the naturally emerged IGG as the *minimal required IGG*. A larger IGG than the minimal required IGG has important implications in both conceptual understandings

and numerical simulations. We will come back to this point in Secs. III and VII.

The minimal required IGGs in systems at fractional fillings are consistent with the Hastings-Oshikawa-Lieb-Schultz-Mattis (HOLSM) theorem. Consider a (2+1)D system with an odd number of spin- $\frac{1}{2}$ per unit cell, the HOLSM theorem states that it is impossible to have a featureless trivial insulator. In other words, the ground state must either be gapless, break the spin rotation or the lattice translation symmetry, or be topological ordered with a ground-state degeneracy.

In our formalism, a half-integer spin per site on the square lattice (and similarly on the kagome lattice) enforces a minimal Z_2 IGG, consistent with the HOLSM theorem. For instance, if $\text{IGG} = Z_2$, the system could be in either a deconfined phase with a toric code topological order, or a confined phase. But, the confined phase corresponds to either e or m condensation, which leads to spin-rotation or lattice translation symmetry breaking.

For a honeycomb lattice spin- $\frac{1}{2}$ system, there are two spin- $\frac{1}{2}$ per unit cell and the HOLSM theorem does not apply. As mentioned above, we expect that symmetric PEPS on the honeycomb with a trivial IGG can be constructed, which is consistent with the possible trivial symmetric insulator phase in this system as pointed out in Ref. [67].

E. An example

Here, we will give a simple PEPS with $\text{IGG} = Z_2$ defined on the kagome lattice. In particular, we will write the PEPS description for a nearest-neighboring (NN) resonating valence bond (RVB) state that preserves all lattice symmetry. The lattice symmetry generators for kagome lattice are shown in Fig. 4.

As shown in Ref. [68], there are four different kinds of symmetric NN RVB states defined on kagome lattice with spin- $\frac{1}{2}$ per site. Also, by solving projective symmetry group (PSG) equations for the Schwinger-boson mean field ansatz on the kagome lattice, one finds eight distinct PSG classes, and four of them can be realized by NN pairing terms [25]. One can check that the four NN RVB states are exactly representative states for these four PSG classes. Here, we will focus on one particular PSG class, named as $Q_1 = Q_2$ state in Refs. [24,25]. This particular PSG class is a promising candidate phase [26,43,69] for the Z_2 spin liquid reported in recent DMRG simulations [10–12]. Here, we will explicitly write this NN RVB state in the PEPS language.

In fact, this state has already been studied extensively in PEPS [70,71]. Here, we will slightly modify the construction. Every physical leg is a spin- $\frac{1}{2}$ and virtual leg accommodates spin representation $0 \oplus \frac{1}{2}$, with basis $\{|0\rangle, |\uparrow\rangle, |\downarrow\rangle\}$. Bond tensors are spin singlets, which can be written as a matrix in this basis,

$$B_b = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & -i \\ 0 & i & 0 \end{pmatrix}, \quad (22)$$

where the direction of bond tensor is shown in Fig. 4(c). A bond tensor with the inverse direction is transpose of the above matrix. Tensors for different sites are equal to each other, and

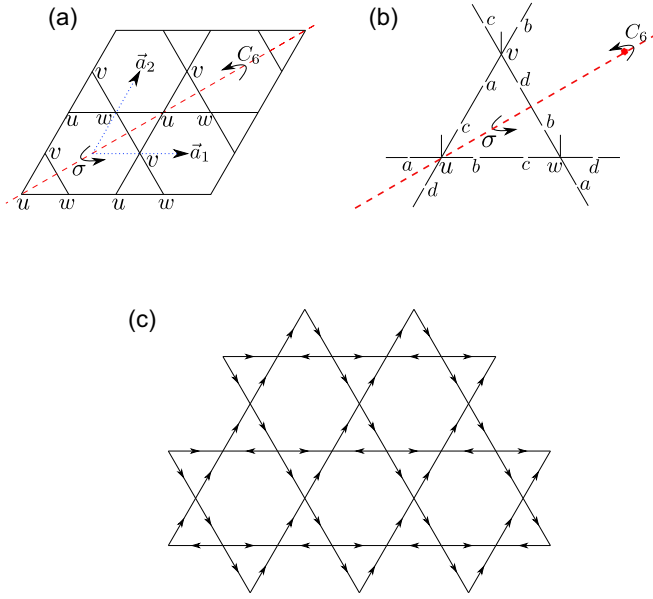


FIG. 4. (Color online) (a) Kagome lattice and the elements of its symmetry group. $\vec{a}_{1,2}$ are the translation unit vectors, C_6 denotes $\pi/3$ rotation around honeycomb center, and σ represents mirror reflection along the dashed red line. (b) Site tensor and bond tensor for kagome lattice in one unit cell. Virtual legs of site tensors are labeled as (x, y, s, i) , where (x, y) denotes the position of unit cell, $s = u, v, w$ is the sublattice index, and $i = a, b, c, d$ specifies one of four legs. (c) One possible orientation of kagome lattice. Particularly, for NN RVB state, the orientation of bonds denotes the direction of spin singlets.

can be written as

$$T^s = |\uparrow\rangle \otimes (|\downarrow 000\rangle + |0\downarrow 00\rangle - i|00\downarrow 0\rangle - i|000\downarrow\rangle) \\ - |\downarrow\rangle \otimes (|\uparrow 000\rangle + |0\uparrow 00\rangle - i|00\uparrow 0\rangle - i|000\uparrow\rangle), \quad (23)$$

where the order of site virtual legs is given in Fig. 4(b). We can view site tensors as superposition of singlets formed by one physical leg and one of the four virtual legs, while the coefficient of singlets needs to be carefully chosen to make PEPS symmetric under lattice symmetries. One can verify that the state defined above is consistent with the PEPS representation of NN RVB given in Ref. [71] up to a gauge transformation.

As discussed before, the Z_2 IGG here is generated by the 2π spin rotation of all virtual legs. Since all tensors are spin singlet, they are invariant under this operation up to -1 factors on the site tensors. This NN RVB PEPS belongs to one of the crude classes proposed in this paper. Roughly speaking, according to global symmetry, we can find the generic sub-Hilbert space that the building block tensors must live within for each given crude class, which vastly generalize the one-dimensional sub-Hilbert space defined as in Eq. (23).

III. ALGORITHM FOR SYMMETRIC PEPS

For a given quantum model with certain given symmetry groups, we propose a general simulation scheme to study its phase diagram as follows:

(1) One classifies symmetric PEPS according to their short-range physics. More precisely, crude classes are distinguished by ways of implementing symmetries on virtual legs.

(2) For each class, by enforcing symmetry transformation rules, one finds constraint Hilbert spaces for the building block tensors in the PEPS representation.

(3) One performs the energy density minimization for every class in the constrained Hilbert space, and determines the class which gives the lowest-energy density. The quantum phase of the model will be a member phase of this crude class. This finishes the short-range part of the simulation task.

(4) At last, one could try to completely determine the quantum phase diagram by studying the long-range physics, e.g., by measuring correlation functions for the symmetric PEPS with the minimal energy density. With a careful scaling analysis, together with the sharp information on the long-range physics obtained from the short-range physics (see Sec. VI for details), possible long-range symmetry-breaking orders may be identified.

As the main example, we will demonstrate this simulation scheme for a half-integer spin system on the kagome lattice. We will start with classifying and constructing generic symmetric PEPS with $\text{IGG} = Z_2$ that preserve the full lattice symmetry as well as the spin-rotation and the time-reversal symmetries. As we will show shortly, the condition $\text{IGG} = Z_2$ actually dictates that the virtual legs form (projective) representations of onsite symmetries. Therefore, when we consider $\text{IGG} = Z_2$ symmetric PEPS, we already made our basic assumption in an implicit way. In addition, although we focus on the minimal required IGG under our basic assumption, the discussions can also be easily generalized to symmetric PEPS with a larger IGG.

A. General framework for classification

From now on, we assume $\overline{\text{IGG}} = \text{IGG} \times \chi$ group, which is always true if IGG is a simple finite Abelian group Z_n .

Consider the gauge transformation associated with a symmetry R : W_R , and the corresponding phase on site tensors: Θ_R . We have $T^s = \Theta_R W_R R \circ T^s$ and $B_b = W_R \circ B_b$, as shown in Sec. II C. However, since both site tensors and bond tensors are invariant under the IGG action (up to phases for site tensors), we conclude that tensors are also invariant under a new symmetry operation defined as $W'_R \equiv \eta_R W_R$ and $\Theta'_R \equiv \mu_R \Theta_R$,

$$T^s = \Theta'_R W'_R R \circ T^s, \\ B_b = W'_R R \circ B_b, \quad (24)$$

where $\eta_R \in \text{IGG}$ and $\mu_R \equiv \{\mu_R(s)\}$ is a set of phase factors on site tensors associated with η_R , such that $\mu_R \eta_R \circ T^s = T^s$. For instance, for a half-integer spin system described by PEPS with $\text{IGG} = \{I, J\}$, if $\eta_R = J$ corresponds to the 2π SU(2) rotation on the virtual legs, then $\mu_R(s) = -1$ for all sites.

Similarly, one could modify W_R and Θ_R with any element in the χ group, i.e., bond-dependent phase factors $\{\varepsilon_R(s, i)\}$ as

$$W_R(s/b, i) \rightarrow \varepsilon_R(s/b, i) W_R(s/b, i), \\ \Theta_R(s) \rightarrow \prod_i \varepsilon_R^*(s, i) \Theta_R(s), \quad (25)$$

where we have $\varepsilon_R(s,i) = \varepsilon_R(b,j)^*$ if (s,i) and (b,j) are connected. Further, $\varepsilon_R(b,1) = \varepsilon_R(b,2)^*$ for the two legs of the same bond tensor, as required in the definition of the χ group.

Basically, the symmetry transformation on the virtual legs W_R is ambiguous since it can be combined with any element in IGG. Mathematically, the representation of R on the Hilbert space of PEPS (including both the virtual and physical Hilbert spaces) forms a new group, which is the original symmetry group SG extended by the $\overline{\text{IGG}}$. This extension is related to the 2-cohomology $H^2(\text{SG}, \text{IGG})$ and $H^2[\text{SG}, \text{U}(1)]$. (For details about projective representations and the 2-cohomology, see Appendix C.) Particularly, we can view those $\overline{\text{IGG}}$ elements as “representations” of the identity element in the symmetry group on virtual legs.

Keeping these discussions in mind, let us consider a discrete symmetry group SG as an example. SG is always defined by a collection of group identities. For instance, elements $R_1, R_2, \dots, R_n \in \text{SG}$ satisfy the following relation:

$$R_1 R_2 \dots R_n = e. \quad (26)$$

Then, acting $R_1 R_2 \dots R_n$ on a symmetric PEPS, one obtains a combined transformation sending every tensor back to the same tensor:

$$\begin{aligned} T^s &= \Theta_{R_1} W_{R_1} R_1 \Theta_{R_2} W_{R_2} R_2 \dots \Theta_{R_n} W_{R_n} R_n \circ T^s, \\ B_b &= W_{R_1} R_1 W_{R_2} R_2 \dots W_{R_n} R_n \circ B_b. \end{aligned} \quad (27)$$

By definition, the transformation leaving all tensors invariant (up to phases on site tensors) can only be an element in $\overline{\text{IGG}}$. Explicitly writing Eq. (27) on virtual legs of site tensors, we conclude that

$$\begin{aligned} &W_{R_1}(s,i) W_{R_2}[R_1^{-1}(s,i)] \dots, \\ &W_{R_n}[R_{n-1}^{-1} \dots R_1^{-1}(s,i)] = \eta(s,i) \chi(s,i), \end{aligned} \quad (28)$$

where $\eta(s,i)$ is the action of $\eta \in \text{IGG}$ on the virtual leg (s,i) . Further, $\{\chi(s,i)\}$ is an element in the χ group. We point out that since $W_R(s,i) = [W_R^{-1}(b,j)]^i$ if (s,i) and (b,j) are connected, W_R on virtual legs of bond tensor gives us no extra equation. However, phase factors on site tensors will give an extra condition, which reads as

$$\begin{aligned} &\Theta_{R_1}(s) \Theta_{R_2}[R_1^{-1}(s)] \dots \Theta_{R_n}[R_{n-1}^{-1} \dots R_1^{-1}(s)] \\ &= \mu(s) \prod_i \chi^*(s,i). \end{aligned} \quad (29)$$

Here, $\mu^*(s)$ is the phase factor obtained after applying η on the s -site tensor.

Our goal is to solve Eqs. (28) and (29) for all group identities and obtain the representations of symmetry operation on virtual legs (W_R) as well as phase factors on site tensors (Θ_R). Recall that the same physical wave function can be represented by many PEPS which differ from each other by gauge transformations (note that these are general gauge transformations which may not be in $\overline{\text{IGG}}$). One should really solve Eqs. (28) and (29) up to gauge equivalence.

Under a gauge transformation $V \equiv \{V(s,i)\}$ on virtual legs, $(T^s)' \equiv V \circ T^s$ and $B'_b \equiv V \circ B_b$ satisfy the following

conditions:

$$\begin{aligned} (T^s)' &= V \Theta_R W_R R \circ T^s \\ &= (V \Theta_R V^{-1})(V W_R R V^{-1} R^{-1}) R V \circ T^s \\ &= \Theta_R W'_R R \circ (T^s)' \end{aligned} \quad (30)$$

and

$$\begin{aligned} B'_b &= V W_R R \circ B_b \\ &= (V W_R R V^{-1} R^{-1}) R V \circ B_b \\ &= W'_R R B'_b. \end{aligned} \quad (31)$$

Here, we use the fact that V commutes with Θ_R in the last step of Eq. (30). Here, $W'_R \equiv V W_R R V^{-1} R^{-1}$. Writing the above expression explicitly on virtual leg (s,i) , we get

$$W_R(s,i) \rightarrow V(s,i) W_R(s,i) V^{-1}[R^{-1}(s,i)], \quad (32)$$

while Θ_R is invariant. Particularly, $\eta \in \text{IGG}$ changes as

$$\eta(s,i) \rightarrow V(s,i) \eta(s,i) V^{-1}(s,i), \quad (33)$$

and phase factors μ and χ in Eq. (29) are invariant.

Apart from the above gauge transformation, one can change site tensors by phase factors, which do not affect physical observables. Note that one could also change bond tensors by phase factors, but such a modification is always equivalent to a gauge transformation together with a changing of phase factors on site tensors. Unlike gauge transformations, a modification of phase factors on site tensors may change the physical wave function up to an overall phase. When site tensors change as $T^s \rightarrow \Phi \circ T^s = \Phi(s) T^s = e^{i\varphi(s)} T^s$, W_R associated with the symmetry R is invariant, but Θ_R goes to $\Phi \Theta_R R \Phi^{-1} R^{-1}$. Namely, the phase factor $\Theta_R \equiv \{e^{i\theta_R(s)}\}$ will change as

$$\Theta_R(s) \rightarrow \Theta_R(s) \Phi(s) \Phi^*[R^{-1}(s)]. \quad (34)$$

Basically, we should solve for the W_R and Θ_R in Eqs. (28) and (29) up to two kinds of equivalences. First, if two sets of W_R and Θ_R are related by Eqs. (32) and (34), they are equivalent and we denote this situation as the *gauge equivalence*. The gauge equivalence contains the V ambiguity in Eq. (32) and the Φ ambiguity in Eq. (34).

Second, if two sets of W_R and Θ_R are different by an IGG element, they are also equivalent and we denote this situation as the *group extension equivalence*. Summarizing our discussion in Eqs. (24) and (25), it means that one could modify W_R and Θ_R as $W_R \rightarrow W'_R = \eta_R \varepsilon_R W_R$ and $\Theta_R \rightarrow \Theta'_R = \mu_R \varepsilon_R \Theta_R$, where $\eta_R \in \text{IGG}$ and $\varepsilon_R \in \chi$ group and

$$\begin{aligned} W'_R(s,i) &= \eta_R(s,i) \varepsilon_R(s,i) W_R(s,i), \\ \Theta'_R(s) &= \mu_R(s) \prod_i \varepsilon_R^*(s,i) \Theta(s). \end{aligned} \quad (35)$$

Note that to save notation, we define $\varepsilon_R \Theta_R$ as multiplying $\prod_i \varepsilon_R^*(s,i)$ on $\Theta(s)$. The group extension equivalence contains an η ambiguity and an ε ambiguity in Eq. (35). *Note that different from the gauge equivalence, we have an η ambiguity and an ε ambiguity for each symmetry element R .*

We will solve Eqs. (28) and (29) for the whole symmetry group up to both the gauge equivalence and the group extension equivalence. Eventually, we will obtain many classes of PEPS satisfying inequivalent W_R and Θ_R transformation rules.

Among all combinations of W_R and Θ_R within the same equivalence class, we can choose a particular representative, and construct explicit forms of W_R and Θ_R by fixing the η ambiguity, the ε ambiguity, the V ambiguity, and the Φ ambiguity. These W_R and Θ_R specify the sub-Hilbert spaces for the building block tensors in each class. We sometimes call the whole procedure of fixing the four ambiguities as *gauge fixing*.

Practically, we often first use the group extension equivalence to simplify Eqs. (28) and (29). For instance, one can use the ε ambiguity to simplify $\{\chi(s,i)\}$ in Eqs. (28) and (29): under a transformation $W_{R_i} \rightarrow \varepsilon_{R_i} W_{R_i}$, according to Eq. (28), we find

$$\chi(s,i) \rightarrow \varepsilon_{R_1}(s,i) \dots \varepsilon_{R_n}[R_{n-1}^{-1} \dots R_1^{-1}(s,i)] \chi(s,i). \quad (36)$$

Moreover, one can use the η ambiguity to simplify the $\{\eta(s,i)\}$ and $\{\mu(s)\}$ in Eqs. (28) and (29). For example, if some symmetry operation R appears only once in the group identity $R_1 R_2 \dots R_n = e$, one could use the η ambiguity for R to make sure $\{\eta(s,i) = 1\}$ and $\{\mu(s) = 1\}$ for this group condition.

After the group extension equivalence is used, we will use the gauge equivalence (the V ambiguity and the Φ ambiguity) to solve for explicit forms of W_R and Θ_R . Note that the group extension equivalence and the gauge equivalence are not completely independent. For example, after fixing the V ambiguity and the Φ ambiguity, it is possible some parts of the ε ambiguity and the η ambiguity are also fixed. In the following, we demonstrate this procedure in an example: the half-integer spin systems on the kagome lattice.

B. Classification of kagome PEPS

Here, we will classify symmetric kagome PEPS wave function with a half-integer spin S per site, which preserves all lattice symmetries, the time-reversal symmetry, as well as the spin-rotation symmetry. We will only assume $\text{IGG} = Z_2 = \{I, J\}$ without specifying the physical meaning of J . Later, we will prove that J can always be chosen to be the 2π spin rotation on the virtual legs. Let us begin with setting up some useful facts.

First, we can use the V ambiguity to diagonalize $J(x,y,s,i)$ for every virtual leg (x,y,s,i) , where (x,y,s) labels a site on the lattice by the coordinates of the unit cell x,y and the sublattice index $s = u,v,w$, and $i = a,b,c,d$ labels one of the four virtual legs coming out of the site tensor (see Fig. 4 for illustrations). In this gauge, $\forall (x,y,s,i)$, the matrix $J(x,y,s,i)$ is a direct sum of an identity matrix and a minus identity matrix. Let us denote $J(x_0,y_0,s_0,i_0) = I_{D_1} \oplus (-I_{D_2})$ for some given virtual leg (x_0,y_0,s_0,i_0) , where $D_1 + D_2 = D$. We will consider the generic case in which $D_1 \neq D_2$.

Using the lattice symmetry, it is straightforward to prove that one can always redefine $\{J(x,y,s,i)\}$ by multiplying with an element ε in the χ group: $\varepsilon(x,y,s,i) = \pm 1$ so that $J(x,y,s,i) = I_{D_1} \oplus (-I_{D_2})$, $\forall (x,y,s,i)$. (Such a modification is allowed in our definition of IGG .) For example, consider a particular lattice symmetry operation R , which could be the 60° rotation C_6 or the lattice translation T_1 or T_2 of the kagome lattice (see Appendix A for precise definitions), we always have a group relation $R^{-1}eR = e$. Using Eq. (28) for this group relation and choosing J to replace the e on the

left-hand side,

$$\begin{aligned} W_R^{-1}[R(x,y,s,i)]J[R(x,y,s,i)]W_R[R(x,y,s,i)] \\ = \eta(x,y,s,i)\chi(x,y,s,i). \end{aligned} \quad (37)$$

The η on the right-hand side must be J , otherwise we would find J to be an element in the χ group, violating $\text{IGG} = Z_2$. Therefore, we know that $J[R(x,y,s,i)]$ and $J(x,y,s,i)$, which are generally on two different virtual legs, are related by a similarity transformation $W_R[R(x,y,s,i)]$ and an overall phase factor $\chi(x,y,s,i)$. But, we are already in a gauge such that $J(x,y,s,i)$ are all diagonal. We then conclude that $J[R(x,y,s,i)] = \pm J(x,y,s,i)$. Since all virtual legs are related by lattice symmetries, we know $J(x,y,s,i) = \varepsilon(x,y,s,i)J(x_0,y_0,s_0,i_0)$, where $\varepsilon(x,y,s,i) = \pm 1 \forall (x,y,s,i)$.

Next, we show $\{\varepsilon(x,y,s,i)\} \in \chi$ group. Namely, if (x,y,s,i) and (x',y',s',i') are connected by a bond tensor B_b , then $\varepsilon(x,y,s,i) = \varepsilon(x',y',s',i')$. This is because if $\varepsilon(x,y,s,i) = -\varepsilon(x',y',s',i')$, then the matrix $(B_b)_{\alpha\beta}$ satisfying Eq. (14) for $W = J$ would not have a full rank since $D_1 \neq D_2$. This means that some singular value of (B_b) vanishes, dictating an IGG larger than Z_2 . For instance, one can multiply an arbitrary $U(1)$ phase on the zero singular value eigenstate on one of the two virtual legs, leaving the bond tensor B_b invariant.

Therefore, $\{\varepsilon(x,y,s,i)\} \in \chi$ group and we can always redefine J such that $J(x,y,s,i) = I_{D_1} \oplus (-I_{D_2})$, $\forall (x,y,s,i)$. From now on, we will work within this gauge and denote the matrix $I_{D_1} \oplus (-I_{D_2})$ simply as J .

This allows us to denote the $\eta(x,y,s,i)$ transformation in Eq. (28) simply as η since it is site and virtual leg independent. In addition, according to Eq. (33), the remaining V ambiguity: $V(x,y,s,i)$ must commute with J . In other words, $V(x,y,s,i)$ are block diagonal with two blocks, and the sizes of blocks are D_1 and D_2 , respectively.

Now, we can consider an arbitrary symmetry transformation R , which could be either a lattice symmetry or an onsite symmetry. Equation (37) still holds for R and the η on the right-hand side must be J . Consequently, we have

$$\begin{aligned} W_R^{-1}[R(x,y,s,i)]JW_R[R(x,y,s,i)] \\ = \chi(x,y,s,i)J. \end{aligned} \quad (38)$$

Squaring this equation leads to $\chi(x,y,s,i) = \pm 1$. However, only the $+$ sign is possible since otherwise the matrix $W_R[R(x,y,s,i)]$ will not have a full rank, again due to $D_1 \neq D_2$. Thus, we have proved that $W_R(x,y,s,i)$ commutes with J , $\forall (x,y,s,i)$ and $\forall R$. Mathematically, this means that when we extend the symmetry group by $\overline{\text{IGG}} = \text{IGG} \times \chi$ group, $\overline{\text{IGG}}$ is in the center of the extended group.

Let us consider the phase factors $\mu_J(x,y,s)$ on site tensors obtained when applying the nontrivial element J on the virtual legs. This determines whether the site tensor is Z_2 even or Z_2 odd. Now, we are ready to show that $\mu_J(x,y,s)$ is site independent in the current gauge. Namely, if one site tensor is Z_2 even (odd), the same is true for all site tensors. Consider a lattice symmetry R which sends a site (x,y,s) to the site (x',y',s') . Equation (13) states that the two site tensors are related by a possible permutation of virtual indices (e.g., induced by a lattice rotation) together with multiplications of W_R matrices on the virtual legs as well as an overall phase factor $\Theta_R(x,y,s)$. Because W_R matrices all commute with J ,

it is straightforward to see that the $\mu_J(x, y, s) = \mu_J(x', y', s')$. Because all sites are related to each other by lattice symmetries, $\mu_J(x, y, s)$ are identical for all sites. Thus, in the discussion following we will simply denote the η in IGG associated phase factors $\mu(x, y, s)$ in Eq. (29) as μ since it does not depend on the site.

By applying the condition $IGG = Z_2$ to the kagome lattice with the symmetry group described in Appendix A, we are able to solve the equations for symmetry operations, i.e., Eqs. (28) and (29), by gauge fixing. For the purpose of presentation, here we only demonstrate the calculation for the translation symmetry, and list the full results of the classification. The calculation for other symmetries is in Appendix B. (We encourage interested readers to follow a simpler and pedagogical example on the square lattice in Appendix F before reading this more technical appendix for the kagome lattice.)

Let us consider the translation symmetry group. This group is isomorphic to $Z \times Z$: the group is defined by its generators T_1, T_2 as well as the relation between generators

$$T_2^{-1} T_1^{-1} T_2 T_1 = e. \quad (39)$$

As shown in Eq. (13), for PEPS symmetric under T_i ($i = 1, 2$), we have

$$\begin{aligned} T^{(x, y, s)} &= \Theta_{T_i} W_{T_i} T_i \circ T^{(x, y, s)}, \\ B_{(xys i | x' y' s' i')} &= W_{T_i} T_i \circ B_{(xys i | x' y' s' i')}. \end{aligned} \quad (40)$$

From the group relation $T_2^{-1} T_1^{-1} T_2 T_1 = e$, we have

$$\begin{aligned} W_{T_2}^{-1} [T_2(x, y, s, i)] W_{T_1}^{-1} [T_1 T_2(x, y, s, i)] W_{T_2} [T_1 T_2(x, y, s, i)] \\ \times W_{T_1} [T_1(x, y, s, i)] = \eta_{12} \chi_{12}(x, y, s, i) \end{aligned} \quad (41)$$

as well as

$$\begin{aligned} \Theta_{T_2}^* [T_2(x, y, s)] \Theta_{T_1}^* [T_1 T_2(x, y, s)] \Theta_{T_2} [T_1 T_2(x, y, s)] \\ \Theta_{T_1} [T_1(x, y, s)] = \mu_{12} \prod_i \chi_{12}^*(x, y, s, i), \end{aligned} \quad (42)$$

where $\eta_{12} \in \{I, J\}$, and $\{\chi_{12}(x, y, s, i)\} \in \chi$ group.

Under transformations $W_{T_i} \rightarrow \varepsilon_{T_i} W_{T_i}$ and $\Theta_{T_i} \rightarrow \varepsilon_{T_i} \Theta_{T_i}$, we have

$$\begin{aligned} \chi_{12} &\rightarrow \varepsilon_{T_2}^*(x, y + 1, s, i) \varepsilon_{T_1}^*(x + 1, y + 1, s, i) \\ &\times \varepsilon_{T_2}(x + 1, y + 1, s, i) \varepsilon_{T_1}(x + 1, y, s, i) \chi_{12}(x, y, s, i). \end{aligned} \quad (43)$$

Thus, we are able to set all $\chi_{12}(x, y, s, i) = 1$ via the ε_{T_i} ambiguity.

According to Eqs. (32) and (34), by doing a gauge transformation $V(x, y, s, i)$ and multiplying phase factors $\Phi(x, y, s)$,

$$\begin{aligned} W_{T_2}(x, y, s, i) &\rightarrow V(x, y, s, i) W_{T_2}(x, y, s, i) V^{-1}(x, y - 1, s, i), \\ \Theta_{T_2}(x, y, s) &\rightarrow \Theta_{T_2}(x, y, s) \Phi(x, y, s) \Phi^*(x, y - 1, s). \end{aligned} \quad (44)$$

We are able to set $W_{T_2}(x, y, s, i) = I$ as well as $\Theta_{T_2}(x, y, s, i) = 1$. Thus, we obtain $T^{(x, y, s)} = T^{(0, y, s)}$. The remaining V ambiguity preserving the form of W_{T_2} should satisfy $V(x, y, s, i) = V(x, 0, s, i)$, and the remaining Φ ambiguity preserving the form of Θ_{T_2} should satisfy $\Phi(x, y, s) = \Phi(x, 0, s)$. In addition, any nontrivial ε_{T_2} transformation will change the form of

$W_{T_2} = I$, so ε_{T_2} is fixed to be 1. Together with the condition $\chi_{12}(x, y, s, i) = 1$, the remaining ε_{T_1} ambiguity satisfies $\varepsilon_{T_1}(x, y, s, i) = \varepsilon_{T_1}(x, 0, s, i)$.

Similarly, for T_1 transformation, using the remaining V ambiguity and Φ ambiguity, we have

$$\begin{aligned} W_{T_1}(x, y, s, i) &\rightarrow V(x, 0, s, i) W_{T_1}(x, y, s, i) V^{-1}(x - 1, 0, s, i), \\ \Theta_{T_1}(x, y, s) &\rightarrow \Theta_{T_1}(x, y, s) \Phi(x, 0, s) \Phi^*(x - 1, 0, s). \end{aligned} \quad (45)$$

Thus, we can set $W_{T_1}(x, 0, s, i) = I$ and $\Theta_{T_1}(x, 0, s) = 1$. To maintain this form of W_{T_1} , we find that there is no remaining ε_{T_1} ambiguity: ε_{T_1} is fixed to be 1. The remaining V ambiguity and Φ ambiguity satisfy $V(x, y, s, i) = V(s, i)$ and $\Phi(x, y, s) = \Phi(s)$; namely, they are only dependent on the sublattice index and the virtual leg index from a site, but are independent of the unit-cell coordinates. Further, in this gauge, site tensors are translational invariant (but could be sublattice dependent):

$$T^{(x, y, s)} = T^{(x, 0, s)} = T^s \doteq T^{(0, 0, s)}, \quad s = u, v, w. \quad (46)$$

Thus, in the gauge that we choose so far, we can solve Eq. (41), and get the implementation of translation symmetry on PEPS as

$$\begin{aligned} W_{T_1}(x, y, s, i) &= \eta_{12}^y, \\ W_{T_2}(x, y, s, i) &= I, \\ \Theta_{T_1}(x, y, s) &= \mu_{12}^y, \\ \Theta_{T_2}(x, y, s) &= 1. \end{aligned} \quad (47)$$

So, for systems with translational symmetries and $IGG = Z_2$, there are at least two distinct classes of wave function. In the context of quantum spin liquids, these two classes are known as *zero flux state* and *π flux state*, corresponding to $\eta_{12} = I$ and J , respectively. Condensations of spinons in these two spin liquids lead to different types of magnetic orders [25]. In the above gauge, although all site tensors related by the translation symmetry share the same form, bond states related by the translation symmetry are in general *different* if η_{12} is nontrivial.

The calculation for other symmetries is similar as the above procedure. The basic idea is to keep fixing gauge by the four ambiguities. And, when we find certain algebraic data, such as the η_{12} introduced above, that cannot be removed by the ambiguities, they describe different symmetric PEPS classes. We only list the result here, and put details in Appendix B.

This classification scheme will always lead to three finite sets of algebraic indices η 's, χ 's, and Θ 's and we will discuss their physical meanings in Sec. IV. Although in general systems every set of indices is nonempty, for a half-integer spin system on the kagome lattice described by PEPS with $IGG = Z_2$, we have the following:

- (i) η_{12}, η_{C_6} , and η_σ , where $\eta \in \{I, J\}$. The corresponding $\mu_{12}, \mu_{C_6}, \mu_\sigma$ are determined by η 's.
- (ii) χ_σ and χ_T , where $\chi = \pm 1$.
- (iii) There turns out to be no tunable Θ indices in this example.

So, the number of classes equals to $2^5 = 32$. By choosing a gauge, the symmetry operations on PEPS can be

solved as

$$\begin{aligned}
W_{T_1}(x, y, s, i) &= \eta_{12}^y, \\
W_{T_2}(x, y, s, i) &= \mathbf{I}, \\
W_{C_6}(x, y, u, i) &= \eta_{12}^{xy + \frac{1}{2}x(x+1) + x+y} w_{C_6}(u, i), \\
W_{C_6}(x, y, v, i) &= \eta_{12}^{xy + \frac{1}{2}x(x+1) + x+y}, \\
W_{C_6}(x, y, w, i) &= \eta_{12}^{xy + \frac{1}{2}x(x+1)}, \\
W_{\sigma}(x, y, s, i) &= \eta_{12}^{x+y+xy} w_{\sigma}(s, i), \\
W_T(x, y, s, i) &= w_T(s, i), \\
W_{\theta\vec{n}}(x, y, s, i) &= \bigoplus_i (\mathbf{I}_{n_i} \otimes e^{i\theta\vec{n}\cdot\vec{S}_i}). \quad (48)
\end{aligned}$$

In this gauge, all W_R matrices are unitary. The last equation is for the $SU(2)$ spin rotation along the \vec{n} direction by an angle θ . In addition, in this gauge we choose $\mathbf{J} = W_{2\pi}(x, y, s, i) = \bigoplus_i (\mathbf{I}_{n_i} \otimes e^{i2\pi\vec{n}\cdot\vec{S}_i})$; namely, \mathbf{J} is the direct sum of \mathbf{I}_{D_1} for the integer spin subspace and $-\mathbf{I}_{D_2}$ for the half-integer spin subspace and $D_1 + D_2 = D$.

For the rotation transformation $w_{C_6}(u, i)$, we have

$$\begin{aligned}
w_{C_6}(u, a) &= w_{C_6}(u, c) = \mathbf{I}, \\
w_{C_6}(u, b) &= w_{C_6}(u, d) = \eta_{12}\eta_{C_6}. \quad (49)
\end{aligned}$$

For the reflection transformation $w_{\sigma}(s, i)$, we have

$$\begin{aligned}
w_{\sigma}(u, a) &= \mathbf{I}, & w_{\sigma}(u, b) &= \chi_{\sigma}\eta_{12}\eta_{C_6}, \\
w_{\sigma}(u, c) &= \chi_{\sigma}\eta_{12}\eta_{C_6}\eta_{\sigma}, & w_{\sigma}(u, d) &= \eta_{\sigma}; \\
w_{\sigma}(v, a) &= \eta_{12}, & w_{\sigma}(v, b) &= \chi_{\sigma}\eta_{12}, \\
w_{\sigma}(v, c) &= \eta_{C_6}\eta_{\sigma}, & w_{\sigma}(v, d) &= \chi_{\sigma}\eta_{C_6}\eta_{\sigma}; \\
w_{\sigma}(w, a) &= \chi_{\sigma}\eta_{C_6}, & w_{\sigma}(w, b) &= \eta_{C_6}, \\
w_{\sigma}(w, c) &= \eta_{12}\eta_{\sigma}, & w_{\sigma}(w, d) &= \chi_{\sigma}\eta_{12}\eta_{\sigma}. \quad (50)
\end{aligned}$$

For the time-reversal transformation w_T , we have

$$\begin{aligned}
w_T(u, a) &= w_T, & w_T(u, b) &= \eta_{12}\eta_{C_6}w_T, \\
w_T(u, c) &= \eta_{12}\eta_{C_6}\eta_{\sigma}w_T, & w_T(u, d) &= \eta_{\sigma}w_T; \\
w_T(v, a) &= \eta_{12}\eta_{C_6}w_T, & w_T(v, b) &= w_T, \\
w_T(v, c) &= \eta_{\sigma}w_T, & w_T(v, d) &= \eta_{12}\eta_{C_6}\eta_{\sigma}w_T; \\
w_T(w, a) &= w_T, & w_T(w, b) &= \eta_{12}\eta_{C_6}w_T, \\
w_T(w, c) &= \eta_{12}\eta_{C_6}\eta_{\sigma}w_T, & w_T(w, d) &= \eta_{\sigma}w_T, \quad (51)
\end{aligned}$$

where

$$w_T = \begin{cases} \bigoplus_i (\mathbf{I}_{n_i} \otimes e^{i\pi S_i^y}) & \text{if } \chi_T = 1, \\ \bigoplus_i (\Omega_{n_i} \otimes e^{i\pi S_i^y}) & \text{if } \chi_T = -1. \end{cases} \quad (52)$$

Here, n_i is dimension of the extra degeneracy associated with spin S_i . Namely, the total degeneracy for spin S_i living on one virtual leg equals $n_i \times (2S_i + 1)$. We have the virtual bond dimension

$$D = \sum_i n_i (2S_i + 1). \quad (53)$$

$\Omega_{n_i} = i\sigma_y \otimes \mathbf{I}_{n_i/2}$ is a n_i -dimensional antisymmetric matrix.

For Θ_R 's, we have

$$\begin{aligned}
\Theta_{T_1}(x, y, s) &= \mu_{12}^y, \\
\Theta_{T_2}(x, y, s) &= 1, \\
\Theta_{C_6}(x, y, u) &= \mu_{12}^{xy + \frac{1}{2}x(x+1) + x+y} \Theta_{C_6}(u), \\
\Theta_{C_6}(x, y, v) &= \mu_{12}^{xy + \frac{1}{2}x(x+1) + x+y}, \\
\Theta_{C_6}(x, y, w) &= \mu_{12}^{xy + \frac{1}{2}x(x+1)}, \\
\Theta_{\sigma}(x, y, s) &= \mu_{12}^{x+y+xy} \Theta_{\sigma}(s), \\
\Theta_T(x, y, u/w) &= 1, \\
\Theta_T(x, y, v) &= \mu_{12}\mu_{C_6}, \\
\Theta_{\theta\vec{n}} &= 1, \quad (54)
\end{aligned}$$

where

$$\begin{aligned}
\Theta_{C_6}(u) &= (\mu_{12}\mu_{C_6})^{\frac{1}{2}}; \\
\Theta_{\sigma}(u) &= (\mu_{\sigma})^{\frac{1}{2}}; \\
\Theta_{\sigma}(v) &= \mu_{C_6}\Theta_{C_6}(u)\Theta_{\sigma}(u); \\
\Theta_{\sigma}(w) &= \mu_{\sigma}\mu_{C_6}[\Theta_{C_6}(u)\Theta_{\sigma}(u)]^{-1}. \quad (55)
\end{aligned}$$

Note that in Eq. (55) $\Theta_{C_6}(u)$ and $\Theta_{\sigma}(u)$ contain square roots so there appear to be two possible values of each of them differing by a minus sign, giving rise to Θ indices. However, these minus signs can be tuned away using the η ambiguities in the definition of W_{C_6} and W_{σ} since every site tensor is Z_2 odd. So, one could simply fix an arbitrary choice for the square roots here. This is the reason why there turns out to be no tunable Θ indices in this example.

Even after all these transformation rules are determined by gauge fixing, we still have some remaining V ambiguity for each class. (Note that there are no remaining nontrivial η , ε , and Φ ambiguities.) To preserve the lattice symmetry, the remaining V ambiguity is independent of sites and legs. To preserve the form of $W_{\theta\vec{n}}$, the remaining V ambiguity must have the following form:

$$V = \bigoplus_i (\tilde{V}_{S_i} \otimes \mathbf{I}_{2S_i+1}), \quad (56)$$

where \tilde{V}_{S_i} is a n_i -dimensional matrix. In addition, the time-reversal transformation W_T further constrains the form of component matrices \tilde{V}_{S_i} . When $\chi_T = 1$, one can show that \tilde{V}_{S_i} must be a *real* matrix. For the purpose of presentation, we only consider $\chi_T = 1$ classes here. The $\chi_T = -1$ cases involve quaternion matrices and we leave the general and detailed discussions in Appendix B.

Next, we are at the stage to construct the constrained sub-Hilbert spaces for building block tensors for all classes, according to the W_R transformation rules. The basic idea is to determine the generic form of a single site/bond tensor using the W_R 's with R leaving the site/bond invariant, and then generate all other site/bond tensors using all W_R 's. The generic forms of site tensors are straightforwardly determined in this fashion, with a set of real continuous variational parameters whose number basically equals the dimension of the constrained site sub-Hilbert space. However, for bond tensors, we will use the remaining V ambiguity to bring them

into canonical forms which are maximal entangled bond states containing *no* continuous variational parameters.

To make sure a bond tensor B_b is invariant under the SU(2) spin rotation, it must have the following form:

$$B_b = \bigoplus_{i=1}^M (\tilde{B}_b^{S_i} \otimes K_{S_i}), \quad (57)$$

where $\tilde{B}_b^{S_i}$ is n_i -dimensional matrix, and K_{S_i} is the fixed $(2S_i + 1)$ -dimensional matrix representing the spin singlet formed by two spin S_i on the two virtual legs shared by B_b . For example, we get $K_{S=0} = 1$, $K_{S=\frac{1}{2}} = i\sigma_y$.

As shown in Appendix B, when $\chi_T = 1$ and a given S_i , depending on the four possible values of η_σ and χ_σ , the component matrix $\tilde{B}_b^{S_i}$ must be a purely real (imaginary) symmetric (antisymmetric) matrix. Then, we can use the remaining V ambiguity in Eq. (56) to simplify $\tilde{B}_b^{S_i}$ because under a \tilde{V}_{S_i} transformation, $\tilde{B}_b^{S_i}$ transforms as

$$\tilde{B}_b^{S_i} \rightarrow \tilde{V}_{S_i} \tilde{B}_b^{S_i} \tilde{V}_{S_i}^\dagger. \quad (58)$$

Clearly, we can use a real orthogonal \tilde{V}_{S_i} to diagonalize (block diagonalize) $\tilde{B}_b^{S_i}$ if $\tilde{B}_b^{S_i}$ is a symmetric (antisymmetric) matrix. After this, the eigenvalues of $\tilde{B}_b^{S_i}$ could have arbitrary norms. But, then we can use another real diagonal \tilde{V}_{S_i} matrix to normalize the eigenvalues so that they are only ± 1 (if $\tilde{B}_b^{S_i}$ is purely real) or $\pm i$ (if $\tilde{B}_b^{S_i}$ is purely imaginary).

This procedure fixes B_b to be maximal entangled states with no continuous variational parameters. However, the relative number of $+1$ ($+i$) eigenvalues and -1 ($-i$) eigenvalues cannot be further tuned away by gauge fixing and will serve as discrete variational parameters on the bond tensors.

The previous discussions in the subsection are general for any half-integer spin S . *Following, we focus on the case with $S = \frac{1}{2}$.* For simplicity, we demonstrate the results for with $D = 3$. The basis of virtual legs of site tensors is $\{|0\rangle, |\uparrow\rangle, |\downarrow\rangle\}$. Namely, virtual legs are formed by one spin singlet and one spin doublet. Note that virtual legs of bond tensors are dual to those of site tensors, so the basis is $\langle 0|, \langle \uparrow|, \langle \downarrow|$. Symmetric PEPS with larger D are also conceptually straightforward but technically involved to obtain, and we leave the general construction in Appendix B.

As discussed in Appendix B, only classes satisfying $\eta_\sigma = J$, $\chi_\sigma = 1$, and $\chi_T = 1$ can be realized with $D = 3$. So, the realizable classes reduce to $2^2 = 4$ with $D = 3$. At such a small D , it turns out that each class has only two continuous variational parameters. (Note that for $D = 6$, i.e., two spin singlets and two spin doublets on the virtual leg, we find that all the 32 classes can be realized. In addition, each class has 47 continuous variational parameters.) Following the above procedure, we can bring the bond tensor on a given bond b_0 into the canonical form

$$B_{b_0} = \begin{pmatrix} \pm 1 & 0 & 0 \\ 0 & 0 & -i \\ 0 & i & 0 \end{pmatrix}. \quad (59)$$

All other bond tensors are generated by combination of translation and rotation symmetries as

$$B_{R(b)} = R^{-1} W_R R \circ B_{b_0}, \quad (60)$$

where $R = T_1^{n_1} T_2^{n_2} C_6^{n_{C_6}}$ with $n_1, n_2, n_{C_6} \in \mathbb{Z}$.

One can view a bond tensor as a quantum state living in the Hilbert space formed by the tensor product of two virtual legs. Namely, we have

$$\hat{B}_{b_0} = \pm (|0,0\rangle - i|\uparrow, \downarrow\rangle + i|\downarrow, \uparrow\rangle). \quad (61)$$

Here, we use notation \hat{B}_{b_0} as the quantum state representation while B_{b_0} as the matrix (tensor) representation.

At a given site s_0 , the generic form of the site tensor for all classes can be summarized as

$$\begin{aligned} \hat{T}^{s_0} = & \{\hat{K}_0 + \hat{K}_{12}(p_1, p_2)\} + \Theta_{C_6}^{-1}(u) \{a \leftrightarrow b, c \leftrightarrow d\} + \Theta_\sigma^{-1}(u) \\ & \times \{a \leftrightarrow d, b \leftrightarrow c\} + \mu_{12} \mu_{C_6} [\Theta_{C_6}(u) \Theta_\sigma(u)]^{-1} \\ & \times \{a \leftrightarrow c, b \leftrightarrow d\} \end{aligned} \quad (62)$$

with real continuous parameters p_1, p_2 . Here, a, b, c, d denote virtual leg of sites, as shown in Fig. 4. \hat{K}_0 and \hat{K}_{12} denote linear-independent spin-singlet states, which can be expressed as

$$\begin{aligned} \hat{K}_0 = & |\uparrow\rangle \otimes |\downarrow 000\rangle - |\downarrow\rangle \otimes |\uparrow 000\rangle, \\ \hat{K}_{12} = & p_1(|\uparrow\rangle \otimes |0\downarrow\uparrow\downarrow\rangle + |\downarrow\rangle \otimes |0\uparrow\downarrow\uparrow\rangle) \\ & + p_2(|\uparrow\rangle \otimes |0\downarrow\downarrow\uparrow\rangle + |\downarrow\rangle \otimes |0\uparrow\uparrow\downarrow\rangle) \\ & - (p_1 + p_2)(|\uparrow\rangle \otimes |0\uparrow\downarrow\downarrow\rangle + |\downarrow\rangle \otimes |0\downarrow\uparrow\uparrow\rangle), \end{aligned} \quad (63)$$

where the first spin lives on the physical leg, while the following four spins live on virtual legs a, b, c, d , respectively. Note that we have chosen a particular gauge such that all site tensors share the same form.

By direct comparison, the NN RVB state ($Q_1 = Q_2$ state) given in Sec. II E is represented as the PEPS defined in Eqs. (59) and (62), with $p_1 = p_2 = 0$ and

$$\begin{aligned} \eta_{12} = \eta_{C_6} = I, \quad \eta_\sigma = J; \\ \chi_\sigma = \chi_T = 1. \end{aligned} \quad (64)$$

C. Algorithm for minimization

As demonstrated above, after the symmetry transformation rules are determined for each class, for a fixed bond dimension D together with the specified onsite symmetry (projective) representation on this virtual Hilbert space, we can construct the generic symmetric PEPS. The strategy is to first construct one site tensor and one bond tensor, and to use spatial symmetries to generate all site tensors and bond tensors. For each class, in general, the maximal entangled bond tensor will be completely fixed up to a finite number of ± 1 signs. These signs are physical (they could modify the energy density) and should be treated as discrete variational parameters. The site tensor, however, will be fixed in a sub-Hilbert space for each given class, whose dimension (minus one if one considers normalized PEPS) represents the number of continuous variational parameters. Different classes give different sub-Hilbert spaces for the site tensors.

For efficient PEPS simulations, one generally chooses an open-boundary sample and introduces certain boundary conditions. In order to determine which symmetric PEPS class that the ground state of a model Hamiltonian belongs to, one

needs to minimize the energy density *near the center* of the sample by tuning all the variational parameters of each given class. The ground-state crude class is identified as the class which gives the lowest-energy density. The effect of boundary conditions should decay quickly into the bulk of sample and the optimal energy density near sample center is expected to converge to a boundary condition independent value for intermediate sample sizes.

By construction, PEPS belonging to different classes has distinct short-range physics (the site tensors and bond tensors transform according to inequivalent algebraic equations), therefore, we expect that quite generically these optimal energy densities for different classes are significantly different. But, there are three scenarios in which the optimal energy densities for distinct classes can be identical, at least in the thermodynamic limit. The first scenario is that the quantum Hamiltonian under investigation is right at a phase transition point, so that the optimal energy densities for the two symmetric PEPS on the two sides of the phase transition are the same. This scenario, however, is expected to occur only at phase transition points.

The second scenario has a deeper physical origin: It is possible that the invariant gauge group of the PEPS representation of a quantum phase is larger than the assumed IGG for the symmetric PEPS classification. We will comment more on this scenario at the end of the paper. For instance, in the example of kagome spin- $\frac{1}{2}$ systems, we classify all the symmetric PEPS whose $\text{IGG} = Z_2$ in the previous section. But, it is possible that a given quantum phase actually requires IGG larger than Z_2 . A PEPS with a larger IGG indicates more invariance of the tensor network, and therefore it could be well approximated (with arbitrarily small wave-function differences) by PEPS with the minimal required Z_2 IGG. Physically, this is related to the Higgs mechanism breaking the large IGG down to Z_2 . In particular, it is possible that the same PEPS with a larger IGG can be well approximated by two or more distinct $\text{IGG} = Z_2$ PEPS classes. This picture can actually be used as a feature of the algorithm proposed here. Namely, if numerically one finds that two distinct classes of $\text{IGG} = Z_2$ PEPS give the same optimal energy densities over a finite region in the phase diagram, it could be due to the fact that the true IGG of the quantum phase is larger than Z_2 .

The third scenario is the one that we currently do not fully understand. It seems possible that certain symmetry-breaking conventional phases such as a valence bond solid phase that can be represented by distinct classes even with the minimal required IGG. It would be very interesting to perform numerical simulations on quantum models to understand whether this really occurs or not, and if this scenario occurs, how does it occur. We will comment further on this issue later in Sec. VI.

Note that although the bond tensors are position dependent in our construction, it is straightforward to absorb each bond tensor to a neighboring site tensor so that all the bond tensors become identity matrices. After this transformation, the PEPS is in the conventional form used in numerical simulations. As a result, for a PEPS with given variational parameters, the measurement of the energy density near the sample center, which is one or few terms in the translational-symmetric Hamiltonian, can be carried out in the same way as in the

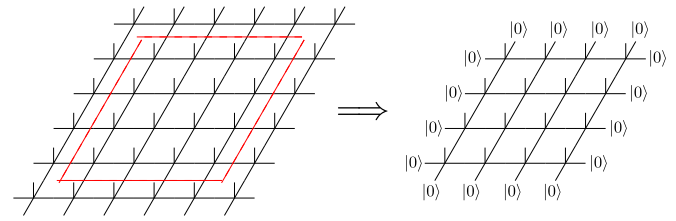


FIG. 5. (Color online) Illustration of truncating an infinite PEPS to a finite-size PEPS with a choice of boundary condition.

original PEPS algorithms [5,72]. The only new ingredient of the current minimization scheme is an algorithm to perform the energy density minimization by tuning the continuous variational parameters within each class. Following, we propose such an algorithm based on the conjugate gradient method. A similar minimization algorithm was investigated in the context of one-dimensional matrix product states with translational symmetry [73].

Before moving towards the minimization algorithm, we introduce the well-established numerical methods in PEPS to perform energy density measurements [5,72]. As a demonstration of principles, let us consider a spin- $\frac{1}{2}$ symmetric PEPS on the square lattice; namely, for any site (bond) on the infinite square lattice, we have a well-defined site (bond) tensor. We first cut the infinite square lattice to a $L_x \times L_y$ finite sample. The open-boundary condition around the edge of the sample is specified by a certain choice of the virtual quantum states living on the dangling bonds. For instance, one can choose a simple boundary condition by requiring all the virtual states on the dangling bonds to be the spin singlet $|0\rangle$ in virtual Hilbert space (see Fig. 5 for illustration).

With a well-defined finite-size PEPS, the computation of wave-function norm and the energy density near the center of the sample is illustrated in Fig. 6. Note that the total Hamiltonian H is a summation of many terms which are related to each other by lattice symmetry. For instance, one can consider $H = \sum_{\langle \vec{x}\vec{x}' \rangle} J \vec{S}_{\vec{x}} \cdot \vec{S}_{\vec{x}'} = \sum_{\langle \vec{x}\vec{x}' \rangle} h_{\vec{x}\vec{x}'}$, where $\langle \vec{x}\vec{x}' \rangle$ represents the nearest neighbors and each energy density term is given by $h_{\vec{x}\vec{x}'} = J \vec{S}_{\vec{x}} \cdot \vec{S}_{\vec{x}'}$. Because by construction the PEPS is lattice space-group symmetric, indicating that as system size increases, expectation values of all the energy density terms near the center of the sample would quickly converge to the same value. Therefore, it is legitimate to optimize only a single energy density term as shown in Fig. 6.

These measurements become the standard problem in PEPS, contracting a finite-size two-dimensional tensor network with the bond dimension D^2 . Here, the bond dimension is squared because we view a pair of a site tensor with its conjugate as a single tensor as shown in Fig. 6. In general, there is no way to exactly contract such a tensor network as long as the system size is not very small. However, PEPS [5] and other tensor network methods [74–76] provide efficient algorithms to approximately contract such tensor networks to high accuracies. The basic idea of the PEPS contraction algorithm is to view the first row of the 2D tensor network as a matrix product state (MPS), and view the other rows as matrix product operators acting on the MPS. Consequently, the existing algorithm of compressing a MPS allows one

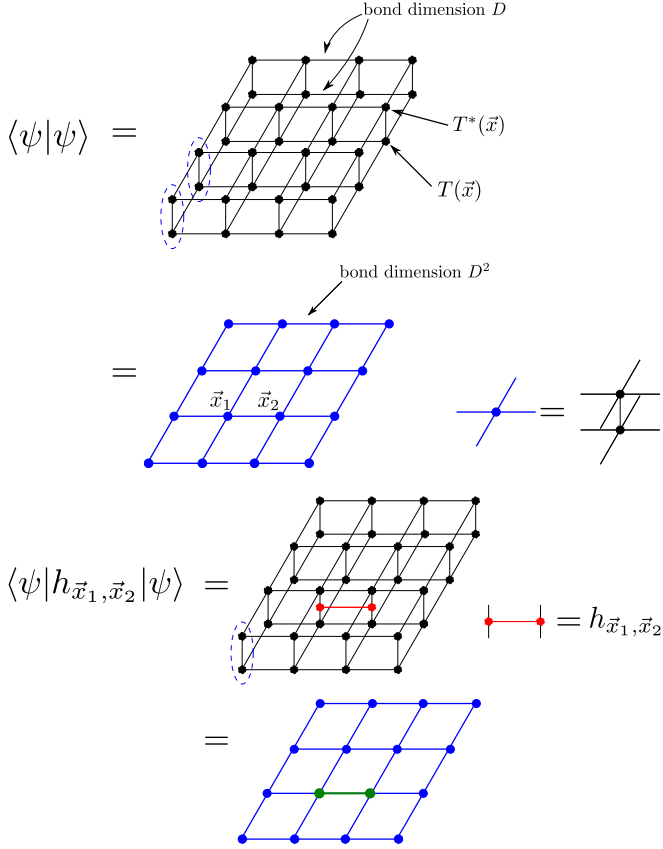


FIG. 6. (Color online) Illustration of measuring wave-function norm and energy density of a PEPS.

to approximately contract the whole 2D tensor network in a row-by-row fashion. The details of the PEPS contraction algorithm can be found in review articles such as Refs. [72,77].

Now, we present an algorithm to perform the energy density minimization, based on the well-established conjugate gradient minimization algorithm. Namely, the quantity we need to minimize is

$$E(\{p_i\}) = \frac{\langle \psi | h_{\vec{x}\vec{x}'} | \psi \rangle}{\langle \psi | \psi \rangle}, \quad (65)$$

where $\{p_i\}$ represents the finite collection of continuous variational parameters in a given symmetric PEPS class with a bond dimension D . When $\{p_i\}$ are tuned, every site tensor in the PEPS wave function $|\psi\rangle$ is modified. In order to apply the conjugate gradient minimization algorithm, one needs to compute the following derivatives:

$$\frac{\partial E}{\partial p_i} = \frac{1}{\langle \psi | \psi \rangle} \frac{\partial \langle \psi | h_{\vec{x}\vec{x}'} | \psi \rangle}{\partial p_i} - \frac{\langle \psi | h_{\vec{x}\vec{x}'} | \psi \rangle}{\langle \psi | \psi \rangle^2} \frac{\partial \langle \psi | \psi \rangle}{\partial p_i}. \quad (66)$$

The only new quantities that we need to compute are $\frac{\partial \langle \psi | \psi \rangle}{\partial p_i}$ and $\frac{\partial \langle \psi | h_{\vec{x}\vec{x}'} | \psi \rangle}{\partial p_i}$. But, these quantities can also be efficiently computed using PEPS algorithms.

Due to the symmetric PEPS construction, we know that each site tensor is a linear superposition of the states in the symmetry-constrained sub-Hilbert space (see Fig. 7 for

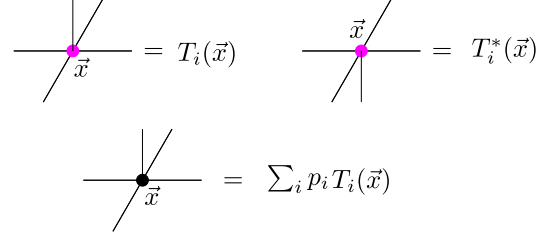


FIG. 7. (Color online) Each site tensor in a symmetric PEPS is a linear superposition of the states in a sub-Hilbert space.

illustration):

$$T(\vec{x}) = \sum_i p_i T_i(\vec{x}), \quad (67)$$

where \vec{x} labels the real-space position of the site tensor. (Because the overall factor of all p_i 's does not change the normalized wave function, it may be convenient to set one of the p_i 's, say p_0 , to be unity and only study the variation of other p_i 's.) Note that for different site \vec{x} , the form of $T_i(\vec{x})$ is generally different due to the nontrivial symmetry transformation rules of tensors and the fact that we absorb the bond tensors into neighboring site tensors.

It is then straightforward to see that to the linear order, the variation of $\langle \psi | \psi \rangle$ ($\langle \psi | h_{\vec{x}\vec{x}'} | \psi \rangle$) is a summation of $L_x \times L_y \times 2$ terms, as illustrated in Fig. 8, where the factor of 2 is due to the fact that both the variation of $|\psi\rangle$ and the variation of $\langle \psi|$ contribute. Each term can be computed by the standard PEPS contraction algorithm.

Basically, one needs to compute the derivatives $\frac{\partial \langle \psi | \psi \rangle}{\partial p_i}$ and $\frac{\partial \langle \psi | h_{\vec{x}\vec{x}'} | \psi \rangle}{\partial p_i}$ for each variational parameter p_i . For each derivative, one needs to compute $\sim L_x \times L_y$ terms. (This number can be reduced by a factor if one chooses an open-boundary sample respecting the point group symmetry.) However, one notes that every derivative term only involves one modified site tensor. So, one could program the contraction sequence

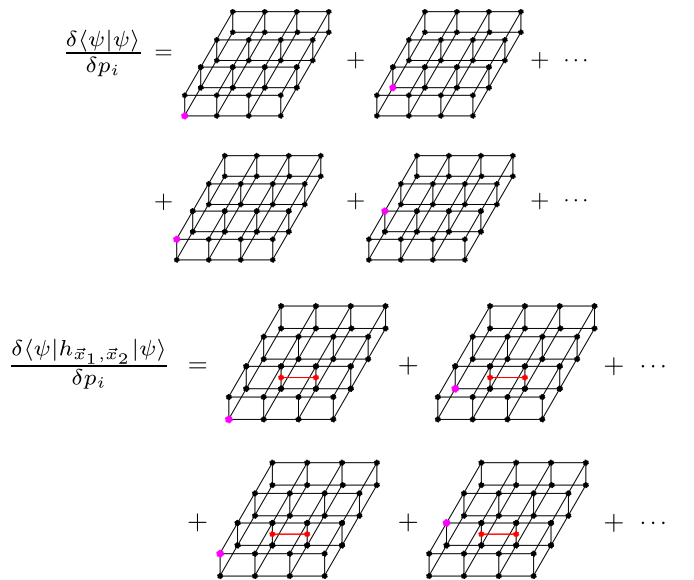


FIG. 8. (Color online) The linear order variations of $\partial \langle \psi | \psi \rangle$ and $\langle \psi | h_{\vec{x}\vec{x}'} | \psi \rangle$.

so that all the other tensors are contracted first, leaving an “environment tensor” $E(\vec{x})$ for the only remaining site tensor at \vec{x} , which is exactly the modified site tensor. Then, different p_i derivatives on the given site \vec{x} can be efficiently computed by contracting the different $T_i(\vec{x})$ with the same $E(\vec{x})$. We then end up with a factor of $\sim L_x \times L_y$ in the computation complexity due to the choices of modified sites. However, this factor $\sim L_x \times L_y$ in the computation cost can be straightforwardly parallelized on $\sim L_x \times L_y$ computer nodes, simply because no communication is needed between different contractions. Consequently, with a computing cluster, the minimization algorithm proposed here can be efficiently implemented.

Finally, we comment on possible algorithms in spatial dimensions higher than two. Although our scheme of constructing symmetric PEPS classes still works in higher dimensions, the PEPS algorithm to contract the tensor no longer applies. However, it is still possible to approximately contract tensor networks in higher dimensions while giving up certain accuracy, efficiency, and larger system sizes. For example, the tensor renormalization group techniques (TRG) [74–76] could be used to contract tensors in higher dimensions. It would be interesting to see whether the TRG algorithms, when combined with the symmetric PEPS construction studied here, can be used to efficiently study quantum phase diagrams in higher-dimensional systems. We leave this as a subject of future investigations.

IV. PHYSICAL INTERPRETATION OF CLASSES

We will discuss the physical meanings of different classes, which are labeled by Θ_R , χ_R , as well as η_R . In this section, we will focus on the non-symmetry-breaking liquid member phase in each crude class. We will comment on the meaning of these indices in the long-range ordered member phases in Sec. VI.

A. Interpretation of Θ_R and χ_R

Although it happens to be true that the kagome half-integer spin example has no tunable Θ_R indices, Θ_R indices do appear in general quantum systems. In Appendix F, we perform the crude classification for the half-integer spin systems on the square lattice with a space group generated by translation symmetries and the C_4 rotation symmetry only. Assuming IGG being the minimal required Z_2 , we find a tunable Θ_{C_4} index.

In fact, the Θ_R indices and the χ_R indices generally appear even when the IGG is trivial. For instance, we could consider a system on the kagome lattice with *no* onsite symmetry [i.e., remove the spin SU(2) rotation and the time-reversal symmetry in our main example], and consequently the minimal required IGG is trivial. Assuming IGG being trivial in this system, we will not have the η indices but still have the χ indices. The calculation procedure of transformation rules almost remains the same as before if we simply limit all the η 's to be identity. Eventually, we will arrive at Eq. (55) replacing all the μ_R by +1. Note that there are no η ambiguities to tune away the signs for the square roots as in the half-integer spin case. In this system, apart from the χ indices, we do have two tunable Θ indices in the PEPS classification: $\Theta_{C_6}(u) = \pm 1$ and $\Theta_\sigma(u) = \pm 1$.

Different Θ_R indices can be viewed as different symmetry quantum numbers (for either onsite symmetries or space-group symmetries) carried by each site tensor. These quantum numbers of the site tensors, generally speaking, directly contribute to the quantum numbers of a finite-size sample. The physics of Θ_R indices is similar to the physics of the so-called “fragile Mott insulator” discussed by Yao and Kivelson [22]. Similar indices in one-dimensional matrix product states have been investigated recently [78]. For instance, in the fragile Mott insulator example [22], a Mott insulator wave function is constructed on the checkerboard lattice which carries nontrivial point group quantum numbers on the odd-by-odd unit-cell lattices. This distinguishes the fragile Mott insulator from trivial insulators which carries trivial quantum numbers on the same lattices. Such nontrivial quantum numbers can be traced back to the quantum numbers carried by the wave function on every square cluster on the checkerboard lattice. If one tries to use a site tensor in PEPS to represent the square cluster wave function, it is clear that this site tensor forms a nontrivial representation of the point group symmetry.

The physical meaning of χ_R may be more well known. These are generalizations of the symmetry fractionalizations in the 2D Affleck-Kennedy-Lieb-Tasaki (AKLT) model [79]. Let us first briefly describe the PEPS construction of the SO(3) symmetric spin-2 AKLT state on the square lattice. In this construction, each virtual leg forms a spin- $\frac{1}{2}$ projective representation of the SO(3) symmetry group of the spin-2 system. Each site tensor is given by the only singlet state formed by the physical spin-2 and the four virtual spin- $\frac{1}{2}$'s, and each bond tensor is formed by the only spin singlet formed by the two spin- $\frac{1}{2}$'s on the two ends of the bond. Such an AKLT wave function can be shown to be the unique gapped ground state of the AKLT Hamiltonian on the square lattice with periodic boundary conditions [80].

However, when the system has an open boundary, one needs to specify a symmetric boundary condition. But, one encounters the following problem: each site tensor on the boundary has only three virtual spin- $\frac{1}{2}$'s and it is impossible for form a spin singlet with the physical spin-2. Basically, each site on the boundary can be viewed as a half-integer spin, which is a projective representation of the original SO(3) group. One sometimes calls this phenomenon as the symmetry fractionalization in 2D *in the absence of topological orders*. When coupled together along a translational symmetric edge, the low-energy dynamics of the edge states can be effectively described by a translational-symmetric half-integer spin chain, which would give a gapless excitation spectrum assuming no spontaneous translational-symmetry breaking. Clearly, in the PEPS construction, the origin of such symmetry fractionalization behavior is due to the fact that projective representations appear in the virtual legs.

For an onsite symmetry R , this is exactly the physics that χ_R captures. For instance, the χ_T index appearing in the kagome example is really about the projective representations of the symmetry group $SU(2) \times \mathcal{T}$ on the virtual legs. As mentioned before, when $\chi_T = 1$, the half-integer (integer) spins on the virtual legs form Kramer doublet (singlet) under the time-reversal transformation. This is the usual representation of $SU(2) \times \mathcal{T}$. However, when $\chi_T = -1$, the half-integer (integer) spins on the virtual legs form Kramer

singlet (doublet) under the time-reversal transformation. This is a nontrivial projective representation of $SU(2) \times \mathcal{T}$. We expect that $\chi_{\mathcal{T}} = -1$ would give rise to nontrivial signatures in entanglement spectra and physical edge states.

For a spatial symmetry R , the physical meaning of χ_R is less obvious. But, its one-dimensional analog has been investigated in the context of matrix product states [81–84]. In our example, the χ_{σ} is capturing similar physics in 2D kagome lattice, which basically describes how the tensor network forms possible projective representations of the spatial reflection. We speculate that nontrivial χ_{σ} would give rise to signatures in entanglement spectra when the partition of the system respects the σ reflection.

In summary, Θ_R is capturing local contributions to symmetry group quantum numbers, and χ_R is capturing the symmetry fractionalizations *not* due to topological orders.

B. η_R and symmetry fractionalization

Here, we will show that η 's are directly related to the symmetry fractionalization of spinon excitations (chargons). To see this, let us first introduce the concept of symmetry fractionalization in the presence of topological orders. We will use the unitary onsite symmetry as an example. Related discussions can be found in Refs. [35,38].

Starting from a topologically ordered ground state with a global symmetry group SG, consider an excited state, having n quasiparticles (which do not have to be of the same type) spatially located at position $\mathbf{r}_1, \mathbf{r}_2, \dots, \mathbf{r}_n$, far apart from one another. Let us denote this state by $|\psi(\mathbf{r}_1, \mathbf{r}_2, \dots, \mathbf{r}_n)\rangle$. For any symmetry transformation $U(g)$ by a group element $g \in \text{SG}$, $U(g)$ will generally transform this state to another state:

$$U(g) \circ |\psi(\mathbf{r}_1, \mathbf{r}_2, \dots, \mathbf{r}_n)\rangle \rightarrow |\tilde{\psi}(\mathbf{r}_1, \mathbf{r}_2, \dots, \mathbf{r}_n)\rangle. \quad (68)$$

One way to describe the symmetry fractionalization on quasiparticles is the following condition: there exist local operators $U_1(g), U_2(g), \dots, U_n(g)$, such that $U_i(g)$ is a local operator acting only in a finite region around the spatial position \mathbf{r}_i , and does not touch the other quasiparticles; in addition, $U_1(g), U_2(g), \dots, U_n(g)$ satisfy

$$U_1(g)U_2(g)\dots U_n(g)|\psi(\mathbf{r}_1, \mathbf{r}_2, \dots, \mathbf{r}_n)\rangle = U(g)|\psi(\mathbf{r}_1, \mathbf{r}_2, \dots, \mathbf{r}_n)\rangle = |\tilde{\psi}(\mathbf{r}_1, \mathbf{r}_2, \dots, \mathbf{r}_n)\rangle. \quad (69)$$

Pictorially, this condition is shown in Fig. 9.

Note that technically Eq. (69) is *not* a general condition for symmetry fractionalization phenomena. For example, let us consider SG to be an onsite U(1) symmetry, and assume that Eq. (69) holds for a wave function $|\psi(\mathbf{r}_1, \mathbf{r}_2, \dots, \mathbf{r}_n)\rangle$. We can then just add one extra U(1) charge outside the regions that $U_i(g)$ ($i = 1, \dots, n$) act and obtains a new wave function $|\tilde{\psi}(\mathbf{r}_1, \mathbf{r}_2, \dots, \mathbf{r}_n)\rangle$. It is perfectly fine to imagine the extra charge as if it already exists in the ground state. Physically, the local operators that transform quasiparticles $U_i(g)$ for $|\tilde{\psi}\rangle$ should be exactly the same as before since $|\psi\rangle$ and $|\tilde{\psi}\rangle$ are locally identical around $\mathbf{r}_1, \mathbf{r}_2, \dots, \mathbf{r}_n$. However, clearly Eq. (69) is no longer true for $|\tilde{\psi}\rangle$ because the global symmetry $U(g)$ picks up an extra U(1) phase from the added U(1) charge.

In fact, Eq. (69) implicitly assumes that, under a global symmetry transformation, there is no phase “locally accumulated” in the ground-state wave function. But, as demonstrated

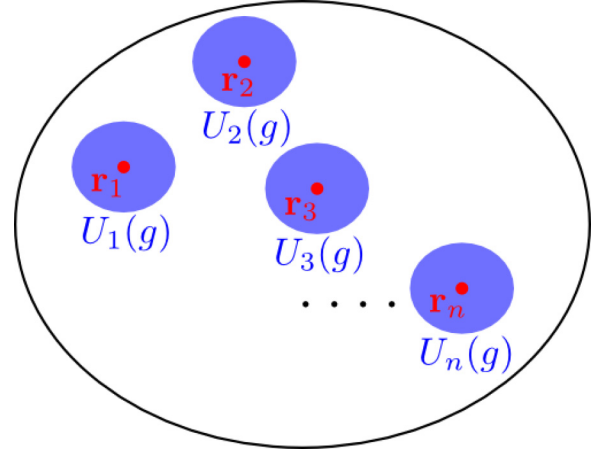


FIG. 9. (Color online) Illustration of symmetry fractionalization phenomena: Under a symmetry transformation $U(g)$ with $\forall g \in \text{SG}$, an excited state is transformed by the product of local transformation operators $U_i(g)$, with each operator only acting on one quasiparticle locally.

above, generally there could be such “locally accumulated” phases in the ground state, and Eq. (69) should be modified up to the “locally accumulated” phases outside the blue regions in Fig. 9.

How to sharply define such “locally accumulated” phases in general? The answer to this question is important to provide a general sharp definition of $U_i(g)$. But, to answer this question, one needs a tool capable to diagnose wave functions locally, which is exactly the power of PEPS. For the moment, let us postpone answering this question in the framework of PEPS, and have some further discussion on symmetry fractionalizations.

First, fractionalized symmetry transformations are local operators and cannot change the quasiparticle’s species (or, more precisely, the superselection sector of a quasiparticle). Thus, we can investigate the transformation rules of each anyon species individually. However, anyons do not need to form a representation of SG due to the nontrivial fusion rule. For example, in a Z_2 topological ordered phase, two chargons fuse to one trivial particle. We can multiply each chargon in the system by a fixed element in an $\text{IGG}' = Z_2 = \{1, -1\}$. Clearly, the total phase becomes unity, and physical wave function is invariant. Here IGG' is the subgroup of U(1) describing the fusion rule of chargons. Quite generally, for a Z_n topological order, $\text{IGG}' = Z_n$.

A PEPS with $\text{IGG} = Z_n$ can describe a deconfined phase with a Z_n topological order. We will only consider this case and we do have $\text{IGG}' = \text{IGG}$. So, IGG tells us that when we implement the global symmetry transformation on chargons, it is perfectly fine to have a phase ambiguity, if this phase ambiguity is an element in IGG . Consequently, a single quasiparticle could form a projective representation of SG with coefficient in IGG , which is classified by second cohomology $H^2(\text{SG}, \text{IGG})$ (see Appendix C for details).

Now, let us translate the above discussion into the PEPS language. The main task is to construct the local symmetry transformation operators for a small patch of PEPS with a nontrivial IGG . Here, we focus on $\text{IGG} = Z_2$ case. Without

loss of generality, we assume that tensors of the PEPS are all Z_2 even. Then, we cut a small patch \mathcal{A} from the PEPS. We can view the tensor associated with patch \mathcal{A} as a linear map from boundary virtual legs to physical legs living in the bulk of the patch, which is labeled as $\hat{T}_{\mathcal{A}}^0$. Here, 0 denotes that there are no quasiparticles inside \mathcal{A} . Namely,

$$\hat{T}_{\mathcal{A}}^0 = \sum_{I,V} (T_{\mathcal{A}}^0)_{IV} |I\rangle \langle V|, \quad (70)$$

where $|I\rangle$ labels ket states of all physical legs inside \mathcal{A} , while $\langle V|$ labels bra states of all boundary virtual legs.

Before studying excitations inside \mathcal{A} , we first discuss properties of $\hat{T}_{\mathcal{A}}^0$. As a tensor, $\hat{T}_{\mathcal{A}}^0$ is Z_2 even. Namely, action of the nontrivial Z_2 element g on the boundary legs of $\hat{T}_{\mathcal{A}}^0$ leaves the tensor invariant. This property implies that $\hat{T}_{\mathcal{A}}^0$, as a linear map, can never be injective. To see this, consider an arbitrary boundary state $|V\rangle$, we have

$$\hat{T}_{\mathcal{A}}^0 |V\rangle = \hat{T}_{\mathcal{A}}^0 |g \circ V\rangle. \quad (71)$$

So, the inverse map of $\hat{T}_{\mathcal{A}}^0$ is not well defined. To have a reasonable definition of the inverse map, one observes that an arbitrary boundary state $|V\rangle$ can be rewritten as

$$\begin{aligned} |V\rangle &= \frac{1}{2}(|V\rangle + |g \circ V\rangle) + \frac{1}{2}(|V\rangle - |g \circ V\rangle) \\ &= \Pi_{\mathcal{U}} |V\rangle + (1 - \Pi_{\mathcal{U}}) |V\rangle, \end{aligned} \quad (72)$$

where \mathcal{U} is the Z_2 even sector of boundary legs. Namely, $\forall |V\rangle \in \mathcal{U}$, we have $|g \circ V\rangle = |V\rangle$. $\Pi_{\mathcal{U}}$ is a projection operator which projects a boundary state into \mathcal{U} . Under $\hat{T}_{\mathcal{A}}^0$, the second term in the above equation is mapped to zero. For a generic PEPS with $\text{IGG} = Z_2$, we can further assume that $\hat{T}_{\mathcal{A}}^0$ is injective on the subspace \mathcal{U} when the patch \mathcal{A} is not too small. This is because the dimension of the physical Hilbert space increases parametrically faster than the dimension of the boundary virtual Hilbert space as the patch size increases. Such a PEPS is named as a Z_2 injective PEPS in Ref. [63]. Namely, generically one can find a linear map $(\hat{T}_{\mathcal{A}}^0)^{-1}$ from bulk physical legs to boundary virtual legs, such that

$$(\hat{T}_{\mathcal{A}}^0)^{-1} \hat{T}_{\mathcal{A}}^0 = \Pi_{\mathcal{U}}. \quad (73)$$

Next, let us study the case with topological excitations inside patch \mathcal{A} . One could create odd number of chargons near the center of the patch \mathcal{A} by modifying $\hat{T}_{\mathcal{A}}^0$ to some Z_2 odd tensor $\hat{T}_{\mathcal{A}}^e$. Opposite to the previous case, we have

$$\hat{T}_{\mathcal{A}}^e |V\rangle = 0, \quad \forall |V\rangle \in \mathcal{U}. \quad (74)$$

Generically, we can further assume $\hat{T}_{\mathcal{A}}^e$ is injective on the Z_2 odd sector of boundary legs. Namely, one can construct $(\hat{T}_{\mathcal{A}}^e)^{-1}$ as linear map from bulk legs to Z_2 odd sector of boundary legs, such that

$$(\hat{T}_{\mathcal{A}}^e)^{-1} \cdot \hat{T}_{\mathcal{A}}^e = \Pi_{\bar{\mathcal{U}}}, \quad (75)$$

where $\Pi_{\bar{\mathcal{U}}} \equiv 1 - \Pi_{\mathcal{U}}$.

Similarly, one can construct patch tensors with even number chargons inside the patch by modifying $\hat{T}_{\mathcal{A}}^0$ to any other Z_2 even and Z_2 injective tensors. For example, let us assume $\hat{T}_{\mathcal{A}}^1$ to be such a tensor. Then, one can find its inverse $(\hat{T}_{\mathcal{A}}^1)^{-1}$ on the subspace \mathcal{U} , such that $(\hat{T}_{\mathcal{A}}^1)^{-1} \cdot \hat{T}_{\mathcal{A}}^1 = \Pi_{\mathcal{U}}$.

In the following, we will study the local physical operator acting on small patches for a symmetry R . Starting with a PEPS wave function $|\Psi\rangle$ with topological excitations inside small patches $\mathcal{A}, \mathcal{B}, \dots$, while the region outside these patches shares the same tensors as the ground-state wave function $|\Psi_0\rangle$. The action of the symmetry R on $|\Psi\rangle$ is obtained by acting R on all tensors, which is defined in Eqs. (6), (10), and (12). Since we try to construct local symmetry operators only on patches $\mathcal{A}, \mathcal{B}, \dots$, we can apply gauge transformations W_R on all virtual legs in the region *outside* all small patches as well as on the boundaries of all small patches, but leave virtual legs inside small patches untouched. Note that this gauge transformation does *not* modify the R -transformed physical wave function at all. Because tensors outside small patches are the same as tensors of ground state, the following relations still hold for them:

$$\begin{aligned} T^s &= \Theta_R W_R R \circ T^s, \\ B_b &= W_R R \circ B_b. \end{aligned} \quad (76)$$

Thus, under the symmetry R together with the gauge transformation W_R defined above, tensors outside patches will be invariant up to a “locally accumulated” phase $\prod_{s \in \text{outside}} \Theta_R(s)$. We emphasize that this actually provides the sharp *definition* of the “locally accumulated” phases mentioned earlier in this section. As discussed in the previous subsection, $\Theta_R(s)$ ’s exactly capture the local phases picked up after applying a global symmetry transformation. Without the tool of PEPS, it is actually difficult to sharply define this object.

For tensors inside patches, we have

$$\hat{T}_{\mathcal{A}}^R = W_R R \circ \hat{T}_{\mathcal{A}}. \quad (77)$$

Here, $\hat{T}_{\mathcal{A}}$ is the linear map associated with patch \mathcal{A} , which is obtained by contraction of all tensors inside \mathcal{A} patch. W_R in Eq. (77) is defined to *only* act on boundary virtual legs of $\hat{T}_{\mathcal{A}}$. Note that $\hat{T}_{\mathcal{A}}$ is either Z_2 even or Z_2 odd, which corresponds to even number chargons or odd number chargons inside \mathcal{A} . Note that we should always choose the patch that is large enough so that all quasiparticles that exist in the patch before the transformation keep staying in the patch after the transformation. The above equation can be viewed as the *definition* of $\hat{T}_{\mathcal{A}}^R$.

In fact, Eq. (77) is a very general result which is applicable even when the condition of symmetry fractionalizations breaks down. For example, it is possible that certain symmetry transformation interchanges quasiparticle superselection sectors. In the PEPS formulation, this happens when $\hat{T}_{\mathcal{A}}^R$ and $\hat{T}_{\mathcal{A}}$ describe distinct quasiparticle species, and consequently there is no way to use a local physical operator in \mathcal{A} to send $\hat{T}_{\mathcal{A}}$ to $\hat{T}_{\mathcal{A}}^R$. For the kagome example, this would never happen. For example, we showed that W_R matrices all commute with the nontrivial IGG element $g = J$, and therefore the parity of the number of chargons would be the same in $\hat{T}_{\mathcal{A}}^R$ and $\hat{T}_{\mathcal{A}}$. But, in a symmetric PEPS with a larger IGG (e.g., $\text{IGG} = Z_2 \times Z_2$), we expect that it is possible that W_R does not commute with a $g \in \text{IGG}$. In this case, the R may interchange quasiparticle species.

In the following, we only consider the situation that $\hat{T}_{\mathcal{A}}^R$ and $\hat{T}_{\mathcal{A}}$ support the same superselection sector and consequently share the same Z_2 parity. This allows us to construct the

fractionalized local *physical* operator \hat{L}_R^A for the symmetry R acting on patch \mathcal{A} that realizes Eq. (77), namely,

$$\hat{L}_R^A \circ \hat{T}_A = W_R R \circ \hat{T}_A, \quad (78)$$

at least for those \hat{T}_A describing the relevant low-energy states. One should keep in mind that \hat{L}_R^A only acts on physical legs, without touching boundary legs, i.e.,

$$\hat{L}_R^A = \sum_{I, I'} (\hat{L}_R^A)_{I, I'} |I\rangle \langle I'|. \quad (79)$$

To obtain the explicit form of this local operator, let us consider a particular tensor \hat{T}_A^e , which supports an odd number of chargons in \mathcal{A} . We have

$$\hat{T}_A^{e, R} = [\hat{T}_A^{e, R} \cdot (\hat{T}_A^e)^{-1}] \cdot \hat{T}_A^e, \quad (80)$$

where $\hat{T}_A^{e, R} \equiv W_R R \circ \hat{T}_A^e$, and $(\hat{T}_A^e)^{-1}$ is defined in Eq. (75). In the above equation, we assume that both \hat{T}_A^e and $\hat{T}_A^{e, R}$ are Z_2 odd as well as injective in the Z_2 odd subspace of boundary legs, which is expected to be generically true. Note that $[\hat{T}_A^{e, R} \cdot (\hat{T}_A^e)^{-1}]$ can be viewed as an operator acting only on physical legs.

To study the transformation rules for a number of chargon excitations, let us consider a finite set Λ of tensors: $\Lambda \equiv \{\hat{T}_A^{(i)}, i = 0, 1, \dots\}$ in the patch \mathcal{A} . These tensors may describe states with chargon number equal to zero, one, two, etc., and are injective in the corresponding boundary Z_2 sectors, respectively. But, tensors in Λ contain *no* fluxon excitations in \mathcal{A} . (We will study the symmetry fractionalization of fluxons later in this paper.) We assume that any symmetry transformation as shown in Eq. (77) transforms within the linear space spanned by Λ .

In addition, we assume the tensors in Λ to satisfy $(\hat{T}_A^{(j)})^{-1} \cdot \hat{T}_A^{(i)} = \mathbf{0}, \forall i \neq j$. Physically, this can be achieved by choosing Λ so that all tensor states in it can be sharply distinguished from each other by a set of mutually commuting local physical measurements. Mathematically, these local physical measurements are Hermitian operators acting near the center of the patch where quasiparticles live. For instance, these measurements could include a measurement of the locations of chargons by inserting small fluxon loops. Then, $\{\hat{T}_A^{(i)}\}$ are chosen to be the eigenstates of these measurements with distinct eigenvalues. Since these measurements are locally near the center of the patch, the boundary condition (i.e., the virtual boundary state) will not affect the measurement when the patch is large enough, and the condition $(\hat{T}_A^{(j)})^{-1} \cdot \hat{T}_A^{(i)} = \mathbf{0}, \forall i \neq j$, is expected to hold.

We then can construct a local operator to transform states in Λ under a symmetry R :

$$\hat{L}_R^A = \sum_i [\hat{T}_A^{(i), R} \cdot (\hat{T}_A^{(i)})^{-1}] \quad (81)$$

as shown in Fig. 10(b). One can easily verify \hat{L}_R^A defined above indeed satisfies Eq. (78) for all states in Λ . Moreover, such local operators in patches $\mathcal{A}, \mathcal{B}, \dots$ satisfy the symmetry fractionalization condition (69) up to the “locally accumulated” phase outside these patches $\prod_{s \in \text{Outside}} \Theta_R(s)$.

After the local symmetry operator is defined, we are able to study the symmetry fractionalization of chargons. Consider a

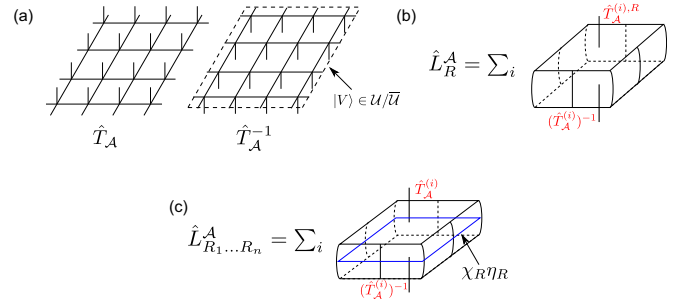


FIG. 10. (Color online) (a) Tensor \hat{T}_A and its “generalized inverse” \hat{T}_A^{-1} associated with patch \mathcal{A} . \hat{T}_A is obtained by contracting all bond tensors and site tensors inside patch \mathcal{A} . As a linear map from boundary legs to bulk legs, \hat{T}_A is either Z_2 even or Z_2 odd. (b) The local R -symmetry operator on patch \mathcal{A} , $\{\hat{T}_A^{(i)}\}$ is an orthonormal basis, where every state in the basis is either Z_2 even or Z_2 odd. (c) The local symmetry operator for a series of symmetry operations $R_1 \dots R_n$, where $R_1 \dots R_n = \mathbf{I}$. If η_R is nontrivial, action of this operator on Z_2 even or Z_2 odd tensor gives different phase factor. This indicates symmetry fractionalization of chargons.

relation between symmetry group elements $R_1 R_2 \dots R_n = \mathbf{e}$, we can construct a local symmetry operator $\hat{L}_{R_1 \dots R_n}^A$ as

$$\hat{L}_{R_1 \dots R_n}^A \equiv \hat{L}_{R_1}^A \dots \hat{L}_{R_n}^A. \quad (82)$$

By inserting Eq. (81) into the above equation, we get

$$\hat{L}_{R_1 \dots R_n}^A = \sum_i [(\hat{T}_A^{(i), R_1 \dots R_n}) \cdot (\hat{T}_A^{(i)})^{-1}], \quad (83)$$

where

$$\begin{aligned} \hat{T}_A^{(i), R_1 \dots R_n} &\equiv W_{R_1} R_1 \dots W_{R_n} R_n \circ \hat{T}_A^{(i)} \\ &= \chi_R \eta_R \circ \hat{T}_A^{(i)}. \end{aligned} \quad (84)$$

Here, the Z_2 element η_R and the phase factor χ_R act on boundary virtual legs, as shown in Fig. 10(c). The second line of the above equation is obtained by the following fact:

$$\eta_R(s, i) \chi_R(s, i) = W_{R_1}(s, i) \dots W_{R_n}(s, i) [R_{n-1}^{-1} \dots R_1^{-1}(s, i)]. \quad (85)$$

When $\eta_R = \mathbf{I}$, the action of $\hat{L}_{R_1 \dots R_n}^A$ on an arbitrary tensor $\hat{T}_A \in \Lambda$ gives the same phase. When η_R is the nontrivial Z_2 element, a Z_2 odd tensor \hat{T}_A^e picks up an extra -1 comparing to a Z_2 even tensor \hat{T}_A^1 under the action of $\hat{L}_{R_1 \dots R_n}^A$. This is exactly the phenomenon for symmetry fractionalization of chargons: for nontrivial η_R , under symmetry $R_1 \dots R_n$, a single chargon picks up an extra -1 comparing to topologically trivial excitations.

Note that χ_R only serves as a global phase, thus does not contribute to the symmetry fractionalization of chargons. It appears in Eq. (84) even for the ground-state tensor patch. In fact, this result is expected and is consistent with the physical interpretation of χ discussed in the previous subsection. One way to see this is to repeat the above analysis *only* for the ground states of the 1D spin-1 AKLT model on an open chain, with the patch \mathcal{A} covering one end of the chain. Here, one should instead consider an injective matrix project state since the IGG here is trivial. The appearance of χ in this example can be simply interpreted as the projective representation of the edge states in the AKLT model.

V. FLUXONS AND THE DECORATED PEPS

In this section, we will construct the decorated PEPS from the original symmetric PEPS with $\text{IGG} = Z_2$. The decorated PEPS explicitly captures all Z_2 gauge fluctuations, and is a good tool to study properties of fluxons. In particular, we can extract fractional lattice quantum numbers of fluxons by constructing local symmetry operators on a small patch of the decorated PEPS. The result shows that lattice quantum numbers of fluxons are completely determined by the chargon distribution.

A. Decorated PEPS

Given a symmetric PEPS with $\text{IGG} = Z_2$, we can create topological excitations such as chargons and fluxons. As shown in Sec. II D, creation of chargons is by locally changing site tensors from Z_2 even (odd) to Z_2 odd (even) and the wave function would vanish if we modify odd number of tensors on a closed manifold. Fluxons are always created in pairs as ends of strings of the nontrivial Z_2 action on virtual legs.

Note that *there is a major difference between chargons and fluxons in this symmetric PEPS language: chargon strings are always “hidden” while fluxon strings are explicitly present*. Fluxon strings, which are extended objects, will cause inconvenience as one tries to define local lattice symmetry operations on small patches with fluxons.

To overcome this inconvenience, we define a decorated PEPS, on which we can create fluxons by changing tensors “locally” without creating strings. The decorated PEPS can be viewed as a dual description of the original symmetric PEPS, and they represent the same physical state if one does not consider the boundary effects. In particular, we will show that *fluxon strings are always “hidden” while the chargon strings are explicitly present in the decorated PEPS*. For simplicity, we consider the decorated PEPS on the square lattice first, and develop the decoration method. Then, we apply the method to the kagome PEPS with Z_2 odd site tensors.

Now, let us discuss the method to obtain the decorated PEPS defined on the square lattice, as shown in Fig. 11. We will first discuss the case where all tensors are Z_2 even. The procedure to construct the decorated PEPS is as follows:

(1) One adds two new virtual legs pointing to plaquette centers for every bond tensor. A new leg has dimension $\tilde{D} = 2$, and we change the bond tensor B_b to \tilde{B}_b as

$$\tilde{B}_b = B_b \otimes |\tilde{1}, \tilde{1}\rangle + g B_b \otimes |-\tilde{1}, -\tilde{1}\rangle, \quad (86)$$

where $|\pm \tilde{1}\rangle$ labels the basis for the new virtual leg, and g is the nontrivial Z_2 element. Here, in Eq. (86), g is defined to act only on one end of the bond tensor B_b . This is shown in the second figure of Fig. 11(a).

(2) All site tensors T^s are the same as those in the undecorated PEPS, as shown in the first figure of Fig. 11(a).

(3) One adds plaquette tensors at all plaquette centers as shown in the third figure of Fig. 11(a). Plaquette tensors connect the modified bond tensors nearby with four new virtual legs. Plaquette tensors are simply superpositions of all (new) virtual states with even numbers of $-\tilde{1}$'s:

$$P_c = |\tilde{1}, \tilde{1}, \tilde{1}, \tilde{1}\rangle + |\tilde{1}, \tilde{1}, -\tilde{1}, -\tilde{1}\rangle + \dots, \quad (87)$$

where P_c labels the tensor at a plaquette center c .

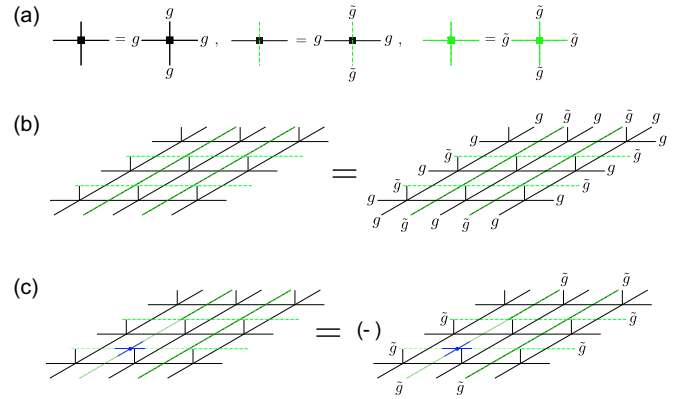


FIG. 11. (Color online) (a) We decorate the PEPS by changing bond tensors, adding plaquette tensors, while leaving site tensors invariant. New legs connecting plaquette tensors and bond tensors are depicted by green dashed-dotted line. These tensors are invariant under action of g on old virtual legs and \tilde{g} on new legs. (b) Any patch of PEPS is invariant under action of g and \tilde{g} on boundary of this patch. The whole PEPS is invariant under $\text{IGG} \times \tilde{\text{IGG}}$. (c) By changing a plaquette tensor from \tilde{Z}_2 even to \tilde{Z}_2 odd (blue tensor), one creates a fluxon at the plaquette center. Odd number of fluxons inside a patch can be detected by acting \tilde{g} loop around the boundary new legs, where one gets an extra minus sign. The physical meaning of \tilde{g} loop is the Wilson loop of chargons, and the extra minus sign encodes the braiding statistics of chargons and fluxons.

Let us visualize the decorated PEPS. Since only configurations with even number of $|\pm \tilde{1}\rangle$ contribute to plaquette tensors and bond tensors, we conclude that $|\pm \tilde{1}\rangle$ always forms loops. Further, every loop configuration contributes equally to the wave function. To see this, consider an arbitrary loop configuration \mathcal{L} . Then, we can transform the configuration to a PEPS wave function defined on the undecorated lattice. The PEPS wave function $|\Psi_{\mathcal{L}}\rangle$ associated with this loop configuration is obtained by modifying the undecorated PEPS $|\Psi\rangle$. For bond tensors intersecting with loops, according to Eq. (86), we have

$$B_b \rightarrow g B_b, \quad (88)$$

while all other tensors are unchanged. Namely, the action of g forms the same loop configuration \mathcal{L} . In fact, \mathcal{L} can be viewed as a fluxon loop in the original PEPS before decoration. Since the tensor obtained by contracting site tensors and bond tensors inside any region is also Z_2 even, the action of g on any loops gives the same quantum state. We then conclude that every loop configuration $|\Psi_{\mathcal{L}}\rangle$ contributes the same wave function as $|\Psi\rangle$. The decorated PEPS, which is the linear superposition of all $|\Psi_{\mathcal{L}}\rangle$, describes the same quantum state as the undecorated one up to normalization (for the moment, let us postpone the discussion on boundary conditions).

The decorated PEPS still has a $Z_2 = \{I, g\}$ invariance with g acting on the old virtual legs only. In addition, the single-sided g action along a loop of old virtual legs is equivalent to flipping all the new Ising variables $|\pm \tilde{1}\rangle \rightarrow \mp \tilde{1}$ along the corresponding loop \mathcal{L} of the new virtual legs.

In the following, we will study fluxon excitations in the decorated PEPS. First, let us point out that for the decorated

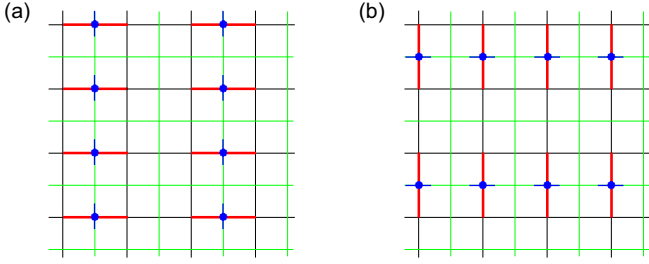


FIG. 12. (Color online) (a), (b) The decorated PEPS on square lattice with every site tensor to be Z_2 odd. Bond tensors with blue dot and blue line should be modified as $\tilde{B}'_b = \tilde{g}\tilde{B}_b$ to ensure that every site is the end of some chargon string. One can verify (a) and (b) are gauge equivalent, thus represent the same state.

PEPS, there is an additional \tilde{Z}_2 gauge transformation $\tilde{\text{IGG}}$ leaving all tensors invariant. We define the action \tilde{g} as

$$\tilde{g} \circ |\pm\tilde{1}\rangle = \pm|\pm\tilde{1}\rangle, \quad (89)$$

while \tilde{g} acts trivially on the original virtual legs. The nontrivial element in $\tilde{\text{IGG}} = \tilde{Z}_2$ is the action of \tilde{g} on all new virtual legs only. Then, if the action of \tilde{g} on all new virtual legs of a tensor leaves the tensor invariant, we call this tensor a \tilde{Z}_2 even tensor. Similarly, we can define the \tilde{Z}_2 odd tensor. To create a fluxon living on plaquette center c , one can simply change the plaquette tensor P_c from \tilde{Z}_2 even to \tilde{Z}_2 odd. For instance, a plaquette tensor P_c^m which supports one fluxon projects out quantum states with even numbers of $|\pm\tilde{1}\rangle$:

$$P_c^m = |-\tilde{1}, \tilde{1}, \tilde{1}, \tilde{1}\rangle + |-\tilde{1}, -\tilde{1}, -\tilde{1}, \tilde{1}\rangle + \dots \quad (90)$$

In order to see that P_c^m indeed supports a fluxon, we translate back to the undecorated PEPS. P_c only has configurations with odd numbers of $|\pm\tilde{1}\rangle$. Thus, in the undecorated lattice, there are always odd numbers of modified bond tensors gB_b around the plaquette c . In other words, a single fluxon lives at the plaquette c .

Fluxons inside a small patch can be detected by acting \tilde{g} on boundary of that patch [see Fig. 11(c)]. An odd number of fluxons contributes an additional (-1) due to the \tilde{Z}_2 oddness of the patch tensor. It is natural to interpret the loop of \tilde{g} (acting only on one end of an involved bond) as the chargon loop which detects fluxons. One can easily show that this is exactly true and the end points of an open \tilde{g} string are chargons. In the decorated PEPS, the chargon strings are explicit while the fluxon strings are “hidden.”

Before we discuss the symmetry fractionalization of fluxons, let us study the case with site tensors being Z_2 odd. In this case, if one exactly follows the above decoration procedure, one finds that the similarly constructed $|\Psi_{\mathcal{L}}\rangle$ wave function satisfies

$$|\Psi_{\mathcal{L}}\rangle = (-1)^{n_s} |\Psi\rangle, \quad (91)$$

where n_s is the number of sites enclosed by the loop \mathcal{L} . To construct a decorated PEPS with in-phase contributions from all $|\Psi_{\mathcal{L}}\rangle$, we require an additional -1 for loops enclosing odd numbers of sites, and need to modify the decoration procedure. As shown in Fig. 12, we simply modify some bond tensors by the action of \tilde{g} *only on one of the two new virtual legs*. More precisely, we can choose bond tensors in the x direction to be

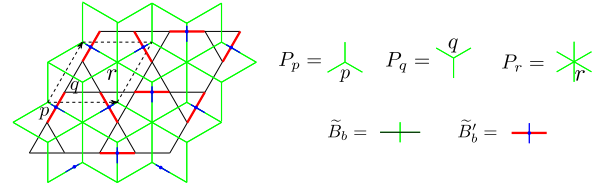


FIG. 13. (Color online) The decorated PEPS for the kagome lattice with Z_2 odd site tensors. Fluxons live on the dual lattice, which is the dice lattice in this case. There are three plaquette centers in one unit cell, labeled as p , q , and r . Green/blue legs are two-dimensional Hilbert space with basis as $|\pm\tilde{1}\rangle$. Plaquette tensors project out configurations with odd number of $|\pm\tilde{1}\rangle$. Bond tensors need to be modified in two different ways according to their color.

modified for every other column in the following way:

$$\tilde{B}'_b = \tilde{g}\tilde{B}_b = B_b \otimes |\tilde{1}, \tilde{1}\rangle - gB_b \otimes |-\tilde{1}, -\tilde{1}\rangle. \quad (92)$$

Note that the \tilde{g} action here is defined to only act on one of the two new virtual legs, and picks up the (-1) for the second term in the second line. One can easily verify that for the modified decorated PEPS, loop configurations enclosing odd numbers of sites contribute the same wave function as the undecorated PEPS.

As we pointed out before, \tilde{g} strings can be interpreted as chargon strings. Further, the Z_2 oddness of site tensors can be interpreted as one chargon per site. The action of \tilde{g} on modified bond tensors in fact creates short “chargon strings” connecting background chargons. A loop of $|\pm\tilde{1}\rangle$ enclosing an odd number of sites intersects with chargon strings for an odd number of times, and contributes an extra -1 . Keeping this in mind, one can easily construct other possible decorated PEPS, once ensuring that every background chargon (Z_2 odd tensor) is an end of a \tilde{g} string, as shown in Fig. 12. We point out that all different decorated PEPS obtained for the same quantum state are gauge equivalent, in the sense that they can be transformed to each other by acting \tilde{g} on both ends of a collection of virtual legs.

The above point of view is very useful for us to construct the decorated PEPS in more complicated lattices such as the kagome lattice. In the kagome lattice, plaquette centers form a dice lattice, as shown in Fig. 13. Following the similar procedure as in the square lattice case, we decorate the PEPS by adding plaquette tensors and changing bond tensors. The new virtual legs are two-dimensional Hilbert space, with basis $|\pm\tilde{1}\rangle$. Note that unlike the previous case, there are three kinds of plaquette tensors. Two lie at centers of triangles, while one lies at the honeycomb center. These tensors project out configurations with odd numbers of $|\pm\tilde{1}\rangle$. Further, due to the Z_2 oddness of site tensors, we should ensure that every site tensor in the decorated PEPS is connected with a chargon string. Thus, we can modify bond tensors as

$$\begin{aligned} \tilde{B}_b &= B_b \otimes |\tilde{1}, \tilde{1}\rangle + gB_b \otimes (|-\tilde{1}, -\tilde{1}\rangle), \\ \tilde{B}'_b &= B_b \otimes |\tilde{1}, \tilde{1}\rangle + gB_b \otimes \tilde{g}(|-\tilde{1}, -\tilde{1}\rangle) \\ &= B_b \otimes |\tilde{1}, \tilde{1}\rangle - gB_b \otimes (|-\tilde{1}, -\tilde{1}\rangle), \end{aligned} \quad (93)$$

where the pattern of bond tensors is shown in Fig. 13.

B. Symmetry fractionalization of fluxons

In this section, we will develop a general method to extract (fractional) quantum numbers carried by fluxons.

Comparing with the undecorated PEPS, there are more gauge freedoms associated with new virtual legs for the decorated PEPS. We call these new gauge freedoms as \tilde{V} . For the purpose of the discussion in this section, we only need to consider \tilde{V} gauge transformations such as acting \tilde{g} on both ends of a number of new virtual legs, which leave the physical wave function intact. If the quantum state is invariant under a symmetry R , tensors of the decorated PEPS should satisfy the following conditions:

$$\begin{aligned} T^s &= \Theta_R W_R R \circ T^s, \\ \tilde{B}_b &= \tilde{W}_R W_R R \circ \tilde{B}_b, \\ P_c &= \tilde{W}_R R \circ P_c, \end{aligned} \quad (94)$$

where W_R labels the gauge transformation associated with symmetry R on old virtual legs while \tilde{W}_R labels that on new legs. Here, W_R takes the same value as in the undecorated PEPS. We will solve \tilde{W}_R in the following.

Let us first consider a simple example: the translation symmetry group generated by T_1, T_2 for the decorated PEPS defined on the square lattice. For the case where site tensors are Z_2 even, we have \tilde{W}_{T_1} and \tilde{W}_{T_2} to be identity. While for the case with site tensors being Z_2 odd, \tilde{W}_{T_1} is nontrivial. If we decorate the PEPS as in Fig. 12(a), we get

$$\tilde{W}_{T_1}(x, y, i) = \tilde{J}^y, \quad \tilde{W}_{T_2}(x, y, i) = I, \quad (95)$$

where i labels the four new virtual legs coming out of the plaquette tensor at (x, y) , and $\tilde{J} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$ is the representation of \tilde{g} on new virtual legs. If the decoration has the form as in Fig. 12(b), we get

$$\tilde{W}_{T_1}(x, y, i) = I, \quad \tilde{W}_{T_2}(x, y, i) = \tilde{J}^x. \quad (96)$$

As we can see, values of \tilde{W}_{T_i} depend on the way to decorate the PEPS. However, similar to the undecorated case, we have

$$\begin{aligned} &\tilde{W}_{T_2}^{-1}[T_2(x, y, i)]\tilde{W}_{T_1}^{-1}[T_1 T_2(x, y, i)]\tilde{W}_{T_2}[T_1 T_2(x, y, i)] \\ &\times \tilde{W}_{T_1}[T_2^{-1} T_1 T_2(x, y, i)] = \tilde{\eta}_{12} \end{aligned} \quad (97)$$

as a gauge-invariant quantity. Inserting \tilde{W}_{T_i} into the above equation, we conclude that $\tilde{\eta}_{12} = I$ for the case with site tensors of undecorated PEPS being Z_2 even, while $\tilde{\eta}_{12} = \tilde{J}$ for the case with site tensors being Z_2 odd.

Next, we will show that $\tilde{\eta}_{12}$ is directly related to the translation symmetry fractionalization of fluxons. To see this, let us consider the decorated PEPS with *only* fluxon excitations inside some small patches. (Note that the decorated PEPS is inconvenient to study chargon excitations since chargon strings are explicit.) Following the similar procedure in Sec. IV B, one can construct local translation operators for a single patch $\tilde{\mathcal{A}}$ of the decorated PEPS, labeled as $\hat{L}_{T_i}^{\tilde{\mathcal{A}}}$, $i = 1, 2$. Labeling the state associated with $\tilde{\mathcal{A}}$ as $\hat{T}_{\tilde{\mathcal{A}}}$, we get

$$\hat{L}_{T_i}^{\tilde{\mathcal{A}}} \cdot \hat{T}_{\tilde{\mathcal{A}}} = \tilde{W}_{T_i} W_{T_i} T_i \circ \hat{T}_{\tilde{\mathcal{A}}}. \quad (98)$$

By series connecting local symmetry operators, we can define

$$\hat{L}_{T_2^{-1} T_1^{-1} T_2 T_1}^{\tilde{\mathcal{A}}} \equiv (\hat{L}_{T_2}^{\tilde{\mathcal{A}}})^{-1} \cdot (\hat{L}_{T_1}^{\tilde{\mathcal{A}}})^{-1} \cdot \hat{L}_{T_2}^{\tilde{\mathcal{A}}} \cdot \hat{L}_{T_1}^{\tilde{\mathcal{A}}} \quad (99)$$

as the local operator associated with $T_2^{-1} T_1^{-1} T_2 T_1$. Acting this operator on $\hat{T}_{\tilde{\mathcal{A}}}$, we have

$$\hat{L}_{T_2^{-1} T_1^{-1} T_2 T_1}^{\tilde{\mathcal{A}}} \cdot \hat{T}_{\tilde{\mathcal{A}}} = \chi_{12} \eta_{12} \tilde{\eta}_{12} \circ \hat{T}_{\tilde{\mathcal{A}}}. \quad (100)$$

For the case with nontrivial $\tilde{\eta}_{12}$, if there are odd numbers of fluxons inside the patch $\tilde{\mathcal{A}}$, $\hat{L}_{T_2^{-1} T_1^{-1} T_2 T_1}^{\tilde{\mathcal{A}}}$ will pick up an extra -1 . This indicates the nontrivial translational symmetry fractionalization of fluxons. Since $\tilde{\eta}_{12}$ only depends on the Z_2 parity of site tensors, we conclude that the translation symmetry fractionalization of fluxons is fully determined by the background chargon distribution. The above argument can be easily generalized to arbitrary lattice symmetry operations.

In the following, we will figure out \tilde{W}_R of the decorated PEPS for the kagome lattice example. As we discussed above, this directly implies the symmetry fractionalization pattern for fluxons. One can easily work out symmetry transformation rules directly from the decorated PEPS shown in Fig. 13. The result is listed as follows:

$$\begin{aligned} \tilde{W}_{T_1}(x, y, \tilde{s}, i) &= \tilde{J}^y, \\ \tilde{W}_{T_2}(x, y, \tilde{s}, i) &= I, \\ \tilde{W}_{C_6}(x, y, p/q, i) &= \tilde{J}^{xy + \frac{1}{2}x(x+1)+1}, \\ \tilde{W}_{C_6}(x, y, r, i) &= \tilde{J}^{xy + \frac{1}{2}x(x+1)+x+y}, \\ \tilde{W}_{\sigma}(x, y, p, i) &= \tilde{J}^{xy+1}, \\ \tilde{W}_{\sigma}(x, y, q/r, i) &= \tilde{J}^{xy}, \end{aligned} \quad (101)$$

where \tilde{s} can be any one of the plaquette sublattices labeled by $p/q/r$ as shown in Fig. 13, and i labels the new virtual legs coming out of the plaquette tensor. These symmetry transformation rules are not gauge invariant. The symmetry fractionalization of fluxons is determined by gauge-invariant quantities $\tilde{\eta}$'s. By replacing W_R in Eqs. (B2), (B11), (B17), (B31), (B35), and (B41) with \tilde{W}_R obtained above, we find

$$\begin{aligned} \tilde{\eta}_{12} &= \tilde{\eta}_{T_1\sigma} = \tilde{\eta}_{T_2\sigma} = \tilde{J}, \\ \tilde{\eta}_{T_1 C_6} &= \tilde{\eta}_{T_2 C_6} = \tilde{\eta}_{C_6} = \tilde{\eta}_{\sigma} = \tilde{\eta}_{\sigma C_6} = I. \end{aligned} \quad (102)$$

For onsite symmetries such as the spin rotation and the time-reversal symmetry, symmetry transformation rules on new virtual legs are trivial. In other words, we expect fluxons constructed here to be spin 0 as well as Kramer singlet. Our result for symmetry fractionalization of fluxons is consistent with earlier results in Refs. [44,69].

VI. SYMMETRIC PEPS ON TORUS AND LONG-RANGE ORDER

In the above discussion, we mainly focus on symmetric PEPS on infinite lattices. In this section, we will consider the symmetric PEPS on a finite torus. Namely, site tensors on the left (up) boundary are connected to sites on the right (down) boundary by bond tensors. Further, we will provide some of our partial understandings on how long-range ordered phases fit into the current symmetric PEPS formulation.

To make the discussion concrete, we will focus on *spin- $\frac{1}{2}$ systems to demonstrate the principle*. We first consider the PEPS description of a Z_2 spin-liquid phase on finite tori in

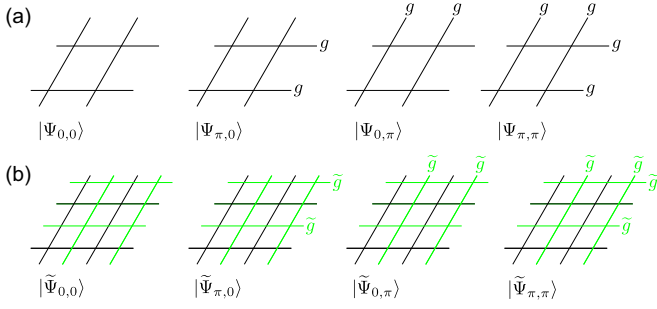


FIG. 14. (Color online) Topological degenerate ground states on finite torus. Site tensors at left (up) boundary are connected with those at right (down) boundary. (a) Labels m basis while (b) labels e basis.

Sec. VI A, and construct the topological degenerate ground-state sector. Then, we study the finite-size effects due to the spinon (vison) condensation in Sec. VI B, which gives rise to the MO (VBS order) in the long range. One result here is that the undecorated PEPS provides the natural basis to represent a MO state, while the decorated PEPS is the natural language to represent a VBS state.

A. Topological degeneracy in the PEPS formulation

It is well known that for the toric code topological ordered phase, the ground-state degeneracy (GSD) equals four on torus in the thermodynamic limit. As mentioned in Sec. IID 1, in the Z_2 -invariant PEPS, one can construct these four states on a finite torus by acting the nontrivial Z_2 element g on the noncontractible loops of torus, as shown in Fig. 14(a).⁹ We label these four states as $|\Psi_{0,0}\rangle$, $|\Psi_{\pi,0}\rangle$, $|\Psi_{0,\pi}\rangle$, and $|\Psi_{\pi,\pi}\rangle$. Recall that g strings can be interpreted as flux loop. So, these four ground-state bases can be visualized as different ways of inserting noncontractible flux loops. We call this set of bases for the ground-state manifold as the m basis. Note that, in general, these four states have different energies on any finite torus. However, if the system is in the deconfined phase, the energy difference between these four states goes to zero in the thermodynamic limit.

Now, let us consider decorated PEPS defined in Sec. V. The decorated PEPS describes the same wave function as the undecorated one on the infinite plane. However, this is not true if we consider finite samples on tori. Using the method developed in the last section, we can easily construct the decorated PEPS on a torus based on an undecorated PEPS state $|\Psi_{0,0}\rangle$. Similar to the infinite PEPS case, any configurations with all $|\tilde{1}\rangle$ forming loops will contribute to the wave function of the decorated PEPS. For a torus sample, we should consider both contractible loops and noncontractible loops of $|\tilde{1}\rangle$. First, any configurations with only contractible loops contribute $|\Psi_{0,0}\rangle$ to the decorated wave function. Note that for configurations with an even number of

noncontractible loops, one can always decompose them to only contractible loops. For configurations containing an odd number of noncontractible loops in the x/y /both direction(s), one gets $\pm|\Psi_{\pi,0}\rangle/\pm|\Psi_{0,\pi}\rangle/\pm|\Psi_{\pi,\pi}\rangle$. Here, the \pm signs depend on the way of decoration: as pointed out in Sec. V, to capture the background chargons of original PEPS, some bonds are modified to $\tilde{B}'_b = \tilde{g}\tilde{B}_b$. When loops of $|\tilde{1}\rangle$ intersect with bond \tilde{B}'_b , we will get an extra -1 . Thus, it is always possible to choose the distribution of \tilde{B}'_b such that the \pm signs are $+1$. The obtained decorated wave function $|\tilde{\Psi}_{0,0}\rangle$ is then

$$|\tilde{\Psi}_{0,0}\rangle = |\Psi_{0,0}\rangle + |\Psi_{\pi,0}\rangle + |\Psi_{0,\pi}\rangle + |\Psi_{\pi,\pi}\rangle \quad (103)$$

up to a normalization factor.

Other three states in the decorated language can be generated from $|\tilde{\Psi}_{0,0}\rangle$ by threading chargon strings on noncontractible loops of torus or, in other words, by acting nontrivial \tilde{Z}_2 element \tilde{g} on new virtual legs along noncontractible loops. We label them as $|\tilde{\Psi}_{\pi,0}\rangle$, $|\tilde{\Psi}_{0,\pi}\rangle$, and $|\tilde{\Psi}_{\pi,\pi}\rangle$, respectively, as shown in Fig. 14(b). It is straightforward to see that

$$\begin{aligned} |\tilde{\Psi}_{\pi,0}\rangle &= |\Psi_{0,0}\rangle + |\Psi_{\pi,0}\rangle - |\Psi_{0,\pi}\rangle - |\Psi_{\pi,\pi}\rangle, \\ |\tilde{\Psi}_{0,\pi}\rangle &= |\Psi_{0,0}\rangle - |\Psi_{\pi,0}\rangle + |\Psi_{0,\pi}\rangle - |\Psi_{\pi,\pi}\rangle, \\ |\tilde{\Psi}_{\pi,\pi}\rangle &= |\Psi_{0,0}\rangle - |\Psi_{\pi,0}\rangle - |\Psi_{0,\pi}\rangle + |\Psi_{\pi,\pi}\rangle. \end{aligned} \quad (104)$$

Here, the basis formed by four $|\tilde{\Psi}\rangle$ states is named as the e basis.

As concrete examples, in Appendix D, we explicitly constructed the fourfold ground-state sectors of the $Q_1 = Q_2$ QSL and $Q_1 = -Q_2$ QSL on an even by odd $(4n+2)$ unit-cell torus sample. Interestingly, on such samples, we find that the ground-state sectors of the two QSL share *no* identical lattice symmetry irreducible representations (irreps); namely, any irrep in the $Q_1 = Q_2$ QSL ground-state sector is different from any irrep in the $Q_1 = -Q_2$ QSL ground-state sector. This result is consistent with a recent study based on parton constructions [42].

B. Long-range ordered phases represented by symmetric PEPS

We claimed that each crude class contains many possible member phases, and these phases are distinguished by long-range physics. Here, we mention some concrete examples. In the 32 crude classes on the kagome lattice, we know that each crude class contains one Z_2 QSL member phase which has no spontaneous symmetry breaking. Let us consider the crude class which contains the $Q_1 = Q_2$ Z_2 QSL, first constructed using the Schwinger-boson approach [24]. There are a few known neighboring phases of this QSL in which symmetry is spontaneously broken in different fashions. These symmetry-breaking phases and the $Q_1 = Q_2$ Z_2 QSL are in the same crude class proposed in this work.

For example, the 120° $Q = 0$ long-range magnetic ordered (MO) state can be obtained if the spinons in the $Q_1 = Q_2$ QSL condense in the long range [24,25]. A valence bond solid (VBS) state with 12-site per unit cell, which breaks the translational symmetry, can be obtained if the visons in the $Q_1 = Q_2$ QSL condense in the long range [44]. To capture the long-range physics of these symmetry-breaking phases, we expect that scaling of bond dimension D and scaling

⁹Note that in the presence of lattice symmetries, sometimes a finite sample has a geometry which does not match the periodicity of the tensor transformation rules, and the lattice symmetry cannot be respected. For the discussion in this section, one does not have to worry about the lattice symmetry.

with system sizes need to be performed in our symmetric PEPS methods. For instance, it was shown that generically the entanglement entropy in symmetric states which breaks a continuous symmetry in the long-range contains additive logarithmic corrections [85]. To our knowledge, there is no known PEPS construction with a finite D that can be proven to host this behavior.

Next, let us try to understand the effects of the spinon or vison condensations in the PEPS formulation on finite tori. Note that practical PEPS simulations on a torus sample can be computationally very expensive, so the discussion here is mainly for conceptual purposes. Before the condensation, the system is in a Z_2 spin-liquid phase with a fourfold ground-state sector \mathcal{H}_{GS} . After the vison- m condensation, the system is expected to have a multifold ground-state sector due to the lattice symmetry breaking, and the number of ground states depend on the geometry of the sample and the VBS order pattern. On the other hand, after the spinon- e condensation, there will be gapless Goldstone excitations assuming spin-rotational symmetry. *Exactly how the ground-state sector on a torus evolves as the spinon or vison condenses?*

Following, we provide our partial answer to this interesting question. Note that, in the ordered phases, for the system to “know” the spinon or vison condensation, we always consider torus samples whose sizes are larger than the vison or spinon confinement length scale. For simplicity, we will focus on samples whose geometries are commensurate with the spatial patterns of the long-range orders. We can consider a Ginzburg-Landau theory describing the boson condensation phase transition. In the Ginzburg-Landau language, this commensuration is achieved by choosing the finite lattices together with a proper boundary condition such that the momentum space minima of the condensed bosons are available.

Here, one immediately sees that *the undecorated (decorated) m basis (e basis) is exactly suitable to describe the spinon (vison) condensation*. For instance, the existence of m loops trapped in the torus holes is explicit in the undecorated m basis. Consequently, the boundary conditions for the spinon condensation Ginzburg-Landau theory are sharply defined. We conclude that only one of the four states in the m basis is representing the true ground state in the MO phase. The spinon condensation minima in the momentum space are clearly *not* available for the other three states due to the $\frac{\pi}{L}$ momentum shift. Physically, we know that the other three states trap MO vortices in the torus holes. Therefore, they have finite excitation energies (but zero excitation energy density) in the MO phase based on simple nonlinear sigma model analysis.

Similarly, the decorated e basis is suitable to describe the VBS order since the boundary condition for the condensed visons is explicit. Only one of the four states in the e basis corresponds to a true ground state in the VBS phase, while the other three states host VBS domain walls wrapping around the torus holes. Note that the confined spinon e corresponds to a VBS vortex [86] and the e string corresponds to a VBS domain wall in the VBS phase. These three states are separated from the true ground state by excitation energies proportional to the linear sample size due to the energy cost of the domain wall.

Note that the decorated PEPS only captures one state in the true ground-state sector in the VBS phase. The other “cat states” in this symmetry-breaking phase are still missing

in the current construction. In fact, on a torus sample with even by even unit cells, our construction leads to physical states with the center-of-mass momentum at $\Gamma = (0,0)$ only. We expect that, in order to capture the other cat states at different center-of-mass momentum, one needs to perform the symmetric PEPS classification on finite tori instead of on the infinite plane.

Next, we discuss some general guiding principles about these symmetry-breaking member phases. It is crucial to note that these symmetry-breaking patterns in the vicinity of the $Q_1 = Q_2$ QSL are *not* arbitrary. In fact, the sharp way to understand how the symmetry-breaking patterns arise is exactly to use the Ginzburg-Landau theory, the golden tool to investigate symmetry breaking. *In order to write a Ginzburg-Landau theory for the spinon- e (vison- m) condensation, the only information that we need to know is how these particles transform under the global symmetry group, which is nothing but the projective symmetry group transformation rules for spinons and visons investigated in Secs. IV and V.* In the past, this is exactly how the 120° $Q = 0$ MO state and the VBS state with a 12-site unit cell were identified to be the neighboring phases of the $Q_1 = Q_2$ Z_2 QSL.

Therefore, even though we emphasize that our algorithm can be used to efficiently determine the crude class of the quantum ground states based on short-range physics, we still learn sharp constraints on candidate symmetry-breaking patterns in the long-range physics: these orders must be consistent with the Ginzburg-Landau theory of the given crude class. With a careful scaling with larger system sizes and bond dimension D , our algorithm could be practically useful to pin down the possible long-range orders in quantum phase diagrams.

Note that the spinon condensation and vison condensation in the 32 Z_2 QSL studied here are quite different: The η indices are really the symmetry transformation rules for spinons, while the symmetry transformation rules for visons are completely fixed. Consequently, two QSL with different η indices are expected to connect to different MO orders after spinon condensations since the Ginzburg-Landau theories are different. For instance, the $Q_1 = -Q_2$ Z_2 QSL is connected to the $\sqrt{3} \times \sqrt{3}$ MO [24], fundamentally different from the 120° $Q = 0$ order in the vicinity of the $Q_1 = Q_2$ QSL.

However, the same Ginzburg-Landau analysis indicates that all the 32 Z_2 QSL could give rise to the *same* long-range VBS order pattern after vison condensation. There are two possible explanations for this phenomenon: (1) It is possible that the long-range VBS orders emerging from different QSL, although sharing the same real-space pattern, are still in different quantum phases. (2) It is possible that certain VBS phase could appear in distinct crude classes.¹⁰

¹⁰There is a third possible explanation: In order to describe the VBS phase, the PEPS must be in a class with a larger invariance gauge group than Z_2 , which has many descendant IGG = Z_2 classes. This picture is related to the discussion on the hierarchical structure of the crude classes near the end of this paper. Although conceptually this explanation is self-consistent, our current knowledge contains no further evidence supporting it.

We tend to believe that either scenario could be correct under certain conditions, although we do not have rigorous understandings. It would be very helpful to perform numerical simulations based on the algorithms proposed here in models supporting relevant symmetry-breaking phases and see exactly what happens. But, we have to leave this as a subject of future investigations. At this moment, we only can provide some physical speculations.

First, the Ginzburg-Landau theory for vison or spinon condensations completely misses χ indices in the classification, and the long-range real-space VBS pattern does not capture the physics described by these indices. Consequently, we expect that scenario (1) is correct if different classes have different χ indices. In fact, we could compare two classes with $\chi_T = +1$ and $\chi_T = -1$, respectively. The Z_2 QSL member phase in the second class is expected to host nontrivial projective representations of $SU(2) \times T$ on the physical boundary. These boundary degrees of freedom are expected to lead to measurable effects even if the bulk VBS order is established, which is absent in the first class.

Second, we speculate that scenario (2) could be correct when different classes share the same χ indices but have different η indices, e.g., the $Q_1 = Q_2$ QSL and the $Q_1 = -Q_2$ QSL. Note that this speculation is not as naive as it appears. In particular, in Appendix D, we demonstrate that the fourfold ground-state sectors of these two QSL have completely different lattice symmetry irreps on $(4n + 2)$ unit-cell samples. Therefore, the symmetric PEPS of the two classes in the VBS ordered phase must be describing distinct ground-state wave functions on such samples. In Appendix E, we trace the origin of the lattice quantum number discrepancy of the two PEPS classes in the 12-site VBS phase, and show that it is related to the phase factor due to the quantum fluctuation of valence bonds along a VBS domain wall. However, we expect that this particular phase factor is *not* a universal feature, and the VBS orders in the two classes correspond to the same quantum phase.

VII. DISCUSSION AND CONCLUSIONS

In this paper, we attempt to construct generic symmetric ground-state wave functions for integer or fractionally filled correlated systems using PEPS, under certain assumptions. Here, we review the assumptions that we made and discuss the limitations and generalizations of our results.

We first highlight an assumption that is, to our knowledge, due to a more fundamental difficulty. We currently do not know how to solve this difficulty generally. This assumption is that the onsite symmetry is implemented as the simple tensor product of local representations or projective representations on the virtual legs in PEPS. For instance, this is the origin of the minimal required Z_2 IGG in the half-integer spin systems on the kagome lattice.

This assumption is known to have problems at least in the long-range physics when attempting to describe SPT phases as well as phases with chiral edge states. For instance, let us attempt to construct a $U(1)$ charge-conserving Chern insulator using the fermionic version of PEPS (fPEPS) [9,87–89]. Here, the exact constructions of free-fermion states with a

nonzero Chern number using Gaussian fPEPS [48,49], in which the virtual legs transform as $U(1)$ representations, are shown to host power-law correlation functions in the real space. It has been pointed out by Hastings [50] that for a general $U(1)$ symmetric PEPS with a bounded bond dimension D which is a fully gapped ground state of a local Hamiltonian, the assumption that the virtual legs transform as $U(1)$ representations and the assumption that the PEPS carries nonzero Chern number generically lead to contradictions.

Another important piece of information can be obtained by understanding the exact PEPS constructions of available short-range correlated SPT ground-state wave functions of exact solvable models [61]. In particular, for a finite onsite symmetry group, it is shown that the virtual legs do not form representation (or projective representations) of the symmetry. Instead, the virtual degrees of freedom transform in a “nononsite” fashion, which can be described by matrix product operators [61,90].

We currently do not know how to generically represent SPT states and chiral states in two and higher dimensions with correct long-range physics using PEPS. However, it is possible that our assumption about symmetry representations on virtual legs does not cause problems in capturing the short-range physics of SPT/chiral phases under certain conditions. For instance, given a finite-size sample, it is possible that the Chern insulator can be accurately approximated with a PEPS after a scaling with respect to bond dimension D is performed. As demonstrated in an example using Gaussian fPEPS in Ref. [49], the required bond dimension D in practical simulations on intermediate sized sample may not be very large.

Moreover, we speculate that even the short-range physics of a SPT/chiral phase may not be captured using the current symmetric PEPS construction. For example, it is known that for an inversion-symmetric system, the ground-state wave function of a Chern insulator with an odd Chern number is inversion odd [91]. The inversion quantum number should be completely short-range physics.

We made a second assumption: we study only those symmetric quantum ground states that can be represented by a single tensor network on the infinite lattice. This assumption is made here mainly for technical simplicity rather than fundamental difficulty. Note that this assumption is weaker than the assumption that the ground-state sector is composed of one-dimensional representations of the symmetry group on any finite-size samples. For instance, consider a Z_2 QSL studied in this paper with a fourfold ground-state sector on tori. When considering a finite-size torus, some of them could form multidimensional irreducible representations of the space group.

This assumption could be violated in general model simulations. As a trivial example, we could consider a ferromagnetic state in an $SU(2)$ symmetric model. In this case, the number of degenerate ground states scales linearly as the number of sites, which certainly cannot be represented by one or few PEPS.

As a slightly nontrivial example, we refer to the chiral-spin-charge Chern liquid (SCCL) in Ref. [23]. The spin dynamics in SCCL is described by a chiral Z_2 QSL, which is a Z_2 QSL breaking the time-reversal symmetry and has nonzero spin-

chirality order parameter (e.g., $\langle \vec{S}_i \cdot \vec{S}_j \times \vec{S}_k \rangle \neq 0$ for three nearby spins i, j, k). This state breaks both time-reversal and mirror reflection symmetries, but leaves the combination of the two respected. In this situation, we found $8 = 4 \times 2$ ground states on symmetric torus samples (compatible with the PSG transformations). The factor of 4 is related to the topological degeneracy of Z_2 gauge theory. The extra factor of 2 is due to the fact that the time reversal, the mirror reflection, and the lattice rotation form nontrivial two-dimensional irreducible representations. The latter fact dictates that it is impossible to represent such chiral liquids by a single symmetric PEPS, in which case the extra factor of 2 degeneracy cannot be captured. The simple way to proceed is to instead only consider the combination of the time reversal and the mirror reflection as a symmetry, which allows a description of one of the two time-reversal images using PEPS. The PEPS description of the other state can be obtained by the time-reversal transformation.

We now comment on another fact in our construction. In the half-integer spin systems on the kagome lattice, we show that a spin-singlet symmetric PEPS has an IGG that at least contains a Z_2 subgroup. If $\text{IGG} = Z_2$ for a PEPS, and if the PEPS is describing a fully gapped QSL, we showed that the topological order is toric-code-like in Sec. IID 1. This remains to be true if we construct some Z_2 QSL in the absence of the time-reversal symmetry, using our formulation. However, there are known constructions [92–94] of gapped Z_2 QSL on the kagome lattice in the absence of the time-reversal symmetry whose topological order is the same as the one in the double-semion model, fundamentally different from toric code.

Interestingly, in a PEPS construction of the double-semion QSL [94], in which spin rotation is still implemented as representations on the virtual legs, the constructed tensors are actually Z_4 invariant. Naively, such a state should have a 16-fold-degenerate ground-state sector on torus, but it was shown that only 4 of them are linearly independent.

Next, we comment on the connection between our work with previous works. For readers that are familiar with the parton constructions and projective symmetry group analysis of parton wave functions [25,26,31], clearly part of our results can be viewed as generalizations of these analyses into PEPS wave functions. In particular, in the kagome half-integer spin S example presented here, every crude class contains a distinct Z_2 QSL as a member phase. Part of our results can be viewed as a classification of Z_2 QSL on the kagome lattice. Comparing with previous investigations on this topic specifically for $S = \frac{1}{2}$, based on parton constructions [25,26], we find that our result captures every phase present in the Schwinger-boson construction [25], and finer than that. Basically, the previous PSG analysis of the Schwinger boson construction is related to the η indices and Θ indices in our formulation, while in this work χ indices are revealed.

However, comparing with the classification based on the Abrikosov-fermion construction of Z_2 QSL on the kagome lattice [26], we find that some of them cannot be described in our result. Similar observation was made by Ref. [69] when directly comparing Schwinger-boson and Abrikosov-fermion constructions. We currently do not have a full understanding of the physics behind this phenomenon. But, it is worth pointing

out that the missing Abrikosov-fermion Z_2 QSL are all found to be gapless (at least perturbatively) on the mean-field level [26].

Finally, we comment on the hierarchical structure of the crude classes. Sometimes, there are physical reasons to believe that the IGG needs to be larger than the minimal required one in order to correctly capture certain quantum phases. The double-semion PEPS mentioned above may be viewed as such an example.

A more conventional example in which this is expected to happen is the collinear Neel ordered phase on the square lattice, for which we expect $\text{IGG} = \text{U}(1)$ in our PEPS construction. In fact, the noncompact CP^1 (NCCP¹) description [95] for the Neel state signals that the natural gauge dynamics in this state, although Higgs'ed out in the long range, should be $\text{U}(1)$.

One can ask the following question: For instance, suppose we have one parent crude class of symmetric PEPS with a large IGG_1 , what are the possible descendant crude classes with a smaller $\text{IGG}_2 \subset \text{IGG}_1$? Similar questions were investigated in the context of parton constructions [26,96]. Generally, one expects that there could exist multiple descendant crude classes with IGG_2 , which eventually gives a hierarchical structure of the crude classes with different IGG's. This hierarchical structure may be useful to understand certain exotic quantum criticalities. For example, two member phases belonging to distinct crude classes could be smoothly connected via a critical point described by their parent crude class.¹¹

As one can see from the above discussions, this work, which is based on the point of view of diagnosing ground-state wave functions using symmetric PEPS, brings up many open questions and needs future investigations to clarify. In addition, the algorithms proposed here for simulating strongly interacting models need benchmark tests to have an understanding of its practical performance. Nevertheless, we believe that separating the short-range part of the physics from the long-range part is a useful idea in investigating quantum phase diagrams of strongly correlated systems. While generally the long-range part is still a difficult task, we expect that the method introduced here can be used to provide sharp information for the short-range physics efficiently.

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APPENDIX A: SYMMETRY GROUP OF THE KAGOME LATTICE

As shown in Fig. 4, we label the three lattice sites in each unit cell with sublattice index $\{s = u, v, w\}$. Further, we specify

¹¹In addition, for the deconfined criticality on the square lattice [95], we expect that the Neel ordered state is described by a class with $\text{IGG} = \text{U}(1)$, while the VBS ordered state is described by a class with $\text{IGG} = Z_2$.

the virtual index $\{i = a, b, c, d\}$ of a given site. We choose Bravais unit vector as $\vec{a}_1 = \hat{x}$ and $\vec{a}_2 = \frac{1}{2}(\hat{x} + \sqrt{3}\hat{y})$. Thus, we are able to specify the virtual degrees of freedom of site tensors as (x, y, s, i) . The symmetry group of such a two-dimensional kagome lattice is generated by the following operations:

$$\begin{aligned} T_1 : (x, y, s, i) &\rightarrow (x + 1, y, s, i), \\ T_2 : (x, y, s, i) &\rightarrow (x, y + 1, s, i), \\ \sigma : (x, y, u, i) &\rightarrow (y, x, u, i_{\sigma 1}), \\ &(x, y, v, i) \rightarrow (y, x, w, i_{\sigma 2}), \\ &(x, y, w, i) \rightarrow (y, x, v, i_{\sigma 2}), \\ C_6 : (x, y, u, i) &\rightarrow (-y + 1, x + y - 1, v, i), \\ &(x, y, v, i) \rightarrow (-y, x + y, w, i), \\ &(x, y, w, i) \rightarrow (-y + 1, x + y, u, i_{C_6}), \end{aligned} \quad (A1)$$

together with time reversal \mathcal{T} . Here,

$$\begin{aligned} \{a_{\sigma 1}, b_{\sigma 1}, c_{\sigma 1}, d_{\sigma 1}\} &= \{d, c, b, a\}, \\ \{a_{\sigma 2}, b_{\sigma 2}, c_{\sigma 2}, d_{\sigma 2}\} &= \{c, d, a, b\}, \\ \{a_{C_6}, b_{C_6}, c_{C_6}, d_{C_6}\} &= \{b, a, d, c\}. \end{aligned} \quad (A2)$$

The symmetry group of a kagome lattice is defined by the following algebraic relations between its generators:

$$\begin{aligned} T_2^{-1} T_1^{-1} T_2 T_1 &= e, \\ \sigma^{-1} T_1^{-1} \sigma T_2 &= e, \\ \sigma^{-1} T_2^{-1} \sigma T_1 &= e, \\ C_6^{-1} T_2^{-1} C_6 T_1 &= e, \\ C_6^{-1} T_2^{-1} T_1 C_6 T_2 &= e, \\ \sigma^{-1} C_6 \sigma C_6 &= e, \\ C_6^6 &= \sigma^2 = \mathcal{T}^2 = e, \\ g^{-1} \mathcal{T}^{-1} g \mathcal{T} &= e, \forall g = T_{1,2}, \sigma, C_6, \end{aligned} \quad (A3)$$

where e stands for the identity element in the symmetry group.

Further, consider the system with spin-rotation symmetry operator $R_{\theta \vec{n}}$, which means spin rotation about axis \vec{n} through angle θ . We mainly consider half-integer spins [SU(2) symmetry] in this paper. The spin-rotation symmetry commutes with all lattice symmetries as well as time-reversal symmetry:

$$g^{-1} R_{\theta \vec{n}}^{-1} g R_{\theta \vec{n}} = e, \quad \forall g = T_{1,2}, \sigma, C_6, \mathcal{T}. \quad (A4)$$

APPENDIX B: CLASSIFICATION OF PEPS WAVE FUNCTION WITH Z_2 IGG ON KAGOME LATTICE

In this appendix, we will classify symmetric PEPS wave functions defined on kagome lattice with a half-integer spin per site. We first obtain the symmetry transformation rules for all different classes. Then, using the symmetry transformation rules, we can solve the constraint Hilbert space for all classes.

1. Solving symmetry operation on PEPS

In this section, we will work out symmetry transformation rules for PEPS defined on a infinite kagome lattice with a half-integer spin per site. We will focus on the case with minimal

required IGG, which equals Z_2 , as shown in the main text. Further, every site tensor is a Z_2 odd tensor as we will see later.

As shown in Sec. III B, the representation of Z_2 IGG on virtual legs can be set as the same form $\{I, J\}$, where $J \equiv I_{D_1} \oplus (-I_{D_2})$ with a ± 1 ambiguity. The remaining V ambiguity $V(x, y, s, i)$ commutes with J . Namely, $V(x, y, s, i)$ is block diagonal with two blocks with blocks' size to be D_1 and D_2 , respectively. Further, for any symmetry R , we have proved the associated W_R transformation should also commute with J .

a. Implementation of lattice symmetry on PEPS

For completeness, we copy the calculation for translation symmetry transformation rules done in Sec. III B. According to the definition of symmetric PEPS, for T_i ($i = 1, 2$) transformation, site tensors and bond tensors satisfy the following condition:

$$\begin{aligned} T^{(x, y, s)} &= \Theta_{T_i} W_{T_i} T_i \circ T^{(x, y, s)}, \\ B_{(xys i | x' y' s' i')} &= W_{T_i} T_i \circ B_{(xys i | x' y' s' i')}. \end{aligned} \quad (B1)$$

From group relation $T_2^{-1} T_1^{-1} T_2 T_1 = e$, we have

$$\begin{aligned} W_{T_2}^{-1} [T_2(x, y, s, i)] W_{T_1}^{-1} [T_1 T_2(x, y, s, i)] W_{T_2} [T_1 T_2(x, y, s, i)] \\ \times W_{T_1} [T_2^{-1} T_1 T_2(x, y, s, i)] = \eta_{12} \chi_{12}(x, y, s, i) \end{aligned} \quad (B2)$$

as well as

$$\begin{aligned} \Theta_{T_2}^* [T_2(x, y, s)] \Theta_{T_1}^* [T_1 T_2(x, y, s)] \Theta_{T_2} [T_1 T_2(x, y, s)] \\ \Theta_{T_1} [T_2^{-1} T_1 T_2(x, y, s)] = \mu_{12} \prod_i \chi_{12}^*(x, y, s, i), \end{aligned} \quad (B3)$$

where $\eta_{12} \in \{I, J\}$, and $\chi_{12}(x, y, s, i)$ is a bond-dependent phase. Under ε_{T_i} ambiguity $W_{T_i} \rightarrow \varepsilon_{T_i} W_{T_i}$, $\Theta_{T_i} \rightarrow \varepsilon_{T_i} \Theta_{T_i}$, we get

$$\begin{aligned} \chi_{12} &\rightarrow \varepsilon_{T_2}(x, y + 1, s, i) \varepsilon_{T_1}^*(x + 1, y + 1, s, i) \\ &\times \varepsilon_{T_2}(x + 1, y + 1, s, i) \varepsilon_{T_1}(x + 1, y, s, i) \chi_{12}(x, y, s, i). \end{aligned} \quad (B4)$$

Thus, we are able to set $\chi_{12}(x, y, s, i) = 1, \forall (x, y, s, i)$.

According to Eqs. (32) and (34), using gauge transformation $V(x, y, s, i)$ and phase factor ambiguity $\Phi(x, y, s)$, we get

$$\begin{aligned} W_{T_2}(x, y, s, i) &\rightarrow V(x, y, s, i) W_{T_2}(x, y, s, i) V^{-1}(x, y - 1, s, i), \\ \Theta_{T_2}(x, y, s) &\rightarrow \Theta_{T_2}(x, y, s) \Phi(x, y, s) \Phi^*(x, y - 1, s). \end{aligned} \quad (B5)$$

Then, we are able to set $W_{T_2}(x, y, s, i) = I$ as well as $\Theta_{T_2}(x, y, s, i) = 1$, and we get $T^{(x, y, s)} = T^{(0, y, s)}$. The remaining ambiguity which leaves W_{T_2} and Θ_{T_2} invariant should satisfy the conditions $V(x, y, s, i) = V(x, 0, s, i)$ and $\Phi(x, y, s) = \Phi(x, 0, s)$. Any ε_{T_2} transformation will change W_{T_2} , so ε_{T_2} is fixed to 1.

Similarly, for T_1 transformation, using remaining gauge transformation, we have

$$\begin{aligned} W_{T_1}(x, y, s, i) &\rightarrow V(x, 0, s, i) W_{T_1}(x, y, s, i) V^{-1}(x - 1, 0, s, i), \\ \Theta_{T_1}(x, y, s) &\rightarrow \Theta_{T_1}(x, y, s) \Phi(x, 0, s) \Phi^*(x - 1, 0, s). \end{aligned} \quad (B6)$$

Thus, we can set $W_{T_1}(x, 0, s, i) = I$ and $\Theta_{T_1}(x, 0, s) = 0$. Then, $\varepsilon_{T_1}(x, y, s, i) = \varepsilon_{T_1}(x, 0, s, i) = 1$. Further, according to

Eq. (B1), site tensors are translational invariant under this gauge:

$$T^{(x,y,s)} = T^{(x,0,s)} = T^s \doteq T^{(0,0,s)}. \quad (\text{B7})$$

To keep this property, the allowed transformations are only sublattice dependent: $V(x,y,s,i) = V(s,i)$ and $\Phi(x,y,s) = \Phi(s)$.

In the gauge we choose above, we can solve Eq. (B2) as

$$\begin{aligned} W_{T_1}(x,y,s,i) &= \eta_{12}^y, \\ W_{T_2}(x,y,s,i) &= \text{I}, \\ \Theta_{T_1}(x,y,s) &= \mu_{12}^y, \\ \Theta_{T_2}(x,y,s) &= 1. \end{aligned} \quad (\text{B8})$$

Now, let us add C_6 rotation symmetry. Under C_6 symmetry, tensors will transform as

$$\begin{aligned} T^{(x,y,s)} &= \Theta_{C_6} W_{C_6} C_6 \circ T^{(x,y,s)}, \\ B_{(xysi|x'y's'i')} &= W_{C_6} C_6 \circ B_{(xysi|x'y's'i')}, \end{aligned} \quad (\text{B9})$$

where

$$\begin{aligned} C_6 \circ (T^{(x,y,u)})_{\alpha\beta\gamma\delta}^i &= (T^{(x+y-1, -x+1, u)})_{\beta\alpha\delta\gamma}^i, \\ C_6 \circ (T^{(x,y,v)})_{\alpha\beta\gamma\delta}^i &= (T^{(x+y, -x+1, u)})_{\alpha\beta\gamma\delta}^i, \\ C_6 \circ (T^{(x,y,w)})_{\alpha\beta\gamma\delta}^i &= (T^{(x+y, -x, v)})_{\alpha\beta\gamma\delta}^i. \end{aligned} \quad (\text{B10})$$

From group relation $C_6^{-1} T_2^{-1} C_6 T_1 = C_6^{-1} T_2^{-1} T_1 C_6 T_2 = \text{e}$, we get

$$\begin{aligned} W_{C_6}^{-1} [C_6(x,y,s,i)] W_{T_2}^{-1} [T_2 C_6(x,y,s,i)] W_{C_6} [T_2 C_6(x,y,s,i)] \\ \times W_{T_1} [C_6^{-1} T_2 C_6(x,y,s,i)] &= \eta_{T_1 C_6} \chi_{T_1 C_6}(x,y,s,i), \\ W_{C_6}^{-1} [C_6(x,y,s,i)] W_{T_2}^{-1} [T_2 C_6(x,y,s,i)] W_{T_1} [T_2 C_6(x,y,s,i)] \\ \times W_{C_6} [C_6 T_2(x,y,s,i)] W_{T_2} [T_2(x,y,s,i)] \\ &= \eta_{T_2 C_6} \chi_{T_2 C_6}(x,y,s,i), \end{aligned} \quad (\text{B11})$$

as well as

$$\begin{aligned} \Theta_{C_6}^* [C_6(x,y,s)] \Theta_{T_2}^* [T_2 C_6(x,y,s)] \Theta_{C_6} [T_2 C_6(x,y,s)] \\ \Theta_{T_1} [C_6^{-1} T_2 C_6(x,y,s)] &= \mu_{T_1 C_6} \prod_i \chi_{T_1 C_6}^*(x,y,s,i), \\ \Theta_{C_6}^* [C_6(x,y,s)] \Theta_{T_2}^* [T_2 C_6(x,y,s)] \Theta_{T_1} [T_2 C_6(x,y,s)] \\ \Theta_{C_6} [C_6 T_2(x,y,s)] \Theta_{T_2} [T_2(x,y,s)] \\ &= \mu_{T_2 C_6} \prod_i \chi_{T_2 C_6}^*(x,y,s,i). \end{aligned} \quad (\text{B12})$$

Due to the η ambiguity, we can always redefine $W_R \rightarrow \eta W_R$ and $\Theta_R \rightarrow \mu \Theta_R$, which has no physics consequence. Thus, by redefining

$$\begin{aligned} W_{T_1} &\rightarrow \eta_{T_2 C_6} W_{T_1}, \quad W_{T_2} \rightarrow \eta_{T_1 C_6} \eta_{T_2 C_6} W_{T_2}, \\ \Theta_{T_1} &\rightarrow \mu_{T_2 C_6} \Theta_{T_1}, \quad \Theta_{T_2} \rightarrow \mu_{T_1 C_6} \mu_{T_2 C_6}, \end{aligned} \quad (\text{B13})$$

we set the right side of Eqs. (B11) and (B12) to be I and 1. Then, by performing transformation

$$\begin{aligned} V(x,y,s,i) &= \eta_{T_1 C_6}^y \eta_{T_2 C_6}^{(x+y)}, \\ \Phi(x,y,s) &= \mu_{T_1 C_6}^y \mu_{T_2 C_6}^{(x+y)}. \end{aligned} \quad (\text{B14})$$

W_{T_i} and Θ_{T_i} are changed back to its original value in Eq. (B8).

Using ε_{C_6} ambiguity, we are able to set $\chi_{T_1 C_6}(x,y,s,i) = 1$ and $\chi_{T_2 C_6}(0,y,s,a/b) = 1$. The remaining ε_{C_6} is independent of unit-cell coordinate, namely, $\varepsilon_{C_6}(x,y,s,i) = \varepsilon_{C_6}(s,i)$. Then, by solving Eqs. (B11) and (B12), we get

$$\begin{aligned} W_{C_6}(x,y,u,i) &= [\eta_{12}(i)]^{xy+\frac{1}{2}x(x+1)+x+y} w_{C_6}(u,i), \\ W_{C_6}(x,y,v,i) &= [\eta_{12}(i)]^{xy+\frac{1}{2}x(x+1)+x+y} w_{C_6}(v,i), \\ W_{C_6}(x,y,w,i) &= [\eta_{12}(i)]^{xy+\frac{1}{2}x(x+1)} w_{C_6}(w,i), \end{aligned} \quad (\text{B15})$$

as well as

$$\begin{aligned} \Theta_{C_6}(x,y,u) &= \mu_{12}^{xy+\frac{1}{2}x(x+1)+x+y} \Theta_{C_6}(u), \\ \Theta_{C_6}(x,y,v) &= \mu_{12}^{xy+\frac{1}{2}x(x+1)+x+y} \Theta_{C_6}(v), \\ \Theta_{C_6}(x,y,w) &= \mu_{12}^{xy+\frac{1}{2}x(x+1)} \Theta_{C_6}(w), \end{aligned} \quad (\text{B16})$$

where we define $w_R(s,i) \equiv W_R(0,0,s,i)$ and $\Theta_R(s) \equiv \Theta_R(0,0,s)$. Inserting the above result back to Eqs. (B11) and (B12), we conclude that all $\chi_{T_2 C_6} = 1$.

Further, since $C_6^6 = \text{e}$, we get

$$\begin{aligned} W_{C_6}(x,y,s,i) W_{C_6} [C_6^{-1}(x,y,s,i)] W_{C_6} [C_6^{-2}(x,y,s,i)] \\ \times W_{C_6} [C_6^{-3}(x,y,s,i)] W_{C_6} [C_6^{-4}(x,y,s,i)] W_{C_6} \\ \times [C_6^{-5}(x,y,s,i)] &= \eta_{C_6} \chi_{C_6}(x,y,s,i). \end{aligned} \quad (\text{B17})$$

Using Eqs. (B15) and (B17), we can simplify the above equation as

$$\begin{aligned} w_{C_6}(w,i) w_{C_6}(v,i) w_{C_6}(u,i) w_{C_6}(w,i_{C_6}) \\ \times w_{C_6}(v,i_{C_6}) w_{C_6}(u,i_{C_6}) &= \eta_{12} \eta_{C_6} \chi_{C_6}(x,y,s,i). \end{aligned} \quad (\text{B18})$$

So, we conclude that $\chi_{C_6}(i) \equiv \chi_{C_6}(0,0,u,i) = \chi_{C_6}(x,y,s,i)$ and $\chi_{C_6}(i) = \chi_{C_6}(i_{C_6})$. Under remaining $\varepsilon_{C_6}(s,i)$, $\chi_{C_6}(i)$ changes as

$$\chi_{C_6}(i) \rightarrow \chi_{C_6}(i) \prod_s \varepsilon_{C_6}(s,i) \varepsilon_{C_6}(s,i_{C_6}). \quad (\text{B19})$$

By choosing the proper ε_{C_6} , we can set $\chi_{C_6} = 1$.

Then, by performing unit-cell independent gauge transformation $V(s,i)$, W_{C_6} transforms as

$$\begin{aligned} W_{C_6}(x,y,u,i) &\rightarrow V(u,i) W_{C_6}(x,y,u,i) V^{-1}(w,i_{C_6}), \\ W_{C_6}(x,y,v,i) &\rightarrow V(v,i) W_{C_6}(x,y,v,i) V^{-1}(u,i), \\ W_{C_6}(x,y,w,i) &\rightarrow V(w,i) W_{C_6}(x,y,w,i) V^{-1}(v,i). \end{aligned} \quad (\text{B20})$$

Thus, we can set $w_{C_6}(v,i) = w_{C_6}(w,i) = w_{C_6}(u,a) = w_{C_6}(u,c) = \text{I}$ by choosing proper gauge. Now, ε_{C_6} is fixed to 1. The remaining V ambiguity satisfies $V(s,i) = V(i) = V(i_{C_6})$. We solve Eq. (B18) under this gauge as

$$w_{C_6}(u,b) = w_{C_6}(u,d) = \eta_{12} \eta_{C_6}. \quad (\text{B21})$$

Similarly, for phase factor, the corresponding equation reads as

$$\begin{aligned} & \Theta_{C_6}(x, y, s) \Theta_{C_6}[C_6^{-1}(x, y, s)] \Theta_{C_6}[C_6^{-2}(x, y, s)] \\ & \Theta_{C_6}[C_6^{-3}(x, y, s)] \Theta_{C_6}[C_6^{-4}(x, y, s)] \Theta_{C_6}[C_6^{-5}(x, y, s)] \\ & = \mu_{C_6}. \end{aligned} \quad (\text{B22})$$

From Eq. (B16), we conclude

$$\Theta_{C_6}(u) \Theta_{C_6}(v) \Theta_{C_6}(w) = \pm(\mu_{12} \mu_{C_6})^{\frac{1}{2}}. \quad (\text{B23})$$

Due to η ambiguity for C_6 , we can always redefine symmetry transformation rules as

$$W_{C_6} \rightarrow JW_{C_6}, \quad \Theta_{C_6} \rightarrow -\Theta_{C_6} \quad (\text{B24})$$

to absorb the minus sign in Eq. (B23). Further, W_{C_6} can be transformed back to the original form by performing gauge transformation

$$\begin{aligned} V(u/w, a/c) &= V(v, b/d) = I, \\ V(u/w, b/d) &= V(v, a/c) = \eta. \end{aligned} \quad (\text{B25})$$

The remaining V ambiguity satisfies $V(x, y, s, i) = V(i) = V(i_{C_6})$.

Under phase transformation $\Phi(s)$, we get

$$\Theta(s) \rightarrow \Theta(s) \Phi(s) \Phi[C_6^{-1}(s)]. \quad (\text{B26})$$

So, we can set $\Theta(v) = \Theta(w) = 1$. Now, Φ ambiguity is only left with an overall phase factor. Further, according to Eq. (B23) (without minus sign), we have

$$\Theta_{C_6}(u) = (\mu_{12} \mu_{C_6})^{\frac{1}{2}}. \quad (\text{B27})$$

Notice that in the above gauge, according to Eq. (B9), all site tensors are equal, namely,

$$T^u = T^v = T^w. \quad (\text{B28})$$

Now, let us add reflection. For reflection symmetry σ , we have

$$\begin{aligned} T^{(x, y, s)} &= \Theta_\sigma W_\sigma \sigma \circ T^{(x, y, s)}, \\ B_{(xys i | x' y' s' i')} &= W_\sigma \sigma \circ B_{(xys i | x' y' s' i')}, \end{aligned} \quad (\text{B29})$$

where

$$\begin{aligned} \sigma \circ (T^{(x, y, u)})_{\alpha\beta\gamma\delta}^i &= (T^{(y, x, u)})_{\delta\gamma\beta\alpha}^i, \\ \sigma \circ (T^{(x, y, v)})_{\alpha\beta\gamma\delta}^i &= (T^{(y, x, w)})_{\gamma\delta\alpha\beta}^i, \\ \sigma \circ (T^{(x, y, w)})_{\alpha\beta\gamma\delta}^i &= (T^{(y, x, v)})_{\gamma\delta\alpha\beta}^i. \end{aligned} \quad (\text{B30})$$

From group relation $\sigma^{-1} T_1^{-1} \sigma T_2 = e$ and $\sigma^{-1} T_2^{-1} \sigma T_1 = e$, we can list the corresponding equations as

$$\begin{aligned} & W_\sigma^{-1}[\sigma(x, y, s, i)] W_{T_2}^{-1}[T_2 \sigma(x, y, s, i)] W_\sigma[T_2 \sigma(x, y, s, i)] \\ & \times W_{T_1}[\sigma^{-1} T_2 \sigma(x, y, s, i)] = \eta_{\sigma T_1} \chi_{\sigma T_1}(x, y, s, i), \\ & W_\sigma^{-1}[\sigma(x, y, s, i)] W_{T_1}^{-1}[T_1 \sigma(x, y, s, i)] W_\sigma[T_1 \sigma(x, y, s, i)] \\ & \times W_{T_2}[\sigma^{-1} T_1 \sigma(x, y, s, i)] = \eta_{\sigma T_2} \chi_{\sigma T_2}(x, y, s, i). \end{aligned} \quad (\text{B31})$$

Using ε_σ ambiguity, we are able to set $\chi_{\sigma T_1}(x, y, s, i) = 1$ and $\chi_{\sigma T_2}(0, y, s, c/d) = 1$, with remaining $\varepsilon_\sigma(x, y, s, i) = \varepsilon_\sigma(s, i)$.

Then, we can solve the above equation as

$$W_\sigma(x, y, s, i) = \eta_{\sigma T_1}^y \eta_{\sigma T_2}^x \eta_{12}^{xy} w_\sigma(s, i). \quad (\text{B32})$$

Inserting the solution back to Eq. (B31), we get all $\chi_{\sigma T_2}(x, y, s, i) = 1$.

Similarly, the equations for phase factor read as

$$\begin{aligned} & \Theta_\sigma^*[\sigma(x, y, s)] \Theta_{T_2}^*[T_2 \sigma(x, y, s)] \Theta_\sigma[T_2 \sigma(x, y, s)] \\ & \Theta_{T_1}[\sigma^{-1} T_2 \sigma(x, y, s)] = \mu_{\sigma T_1}, \\ & \Theta_\sigma^*[\sigma(x, y, s)] \Theta_{T_1}^*[T_1 \sigma(x, y, s)] \Theta_\sigma[T_1 \sigma(x, y, s)] \\ & \Theta_{T_2}[\sigma^{-1} T_1 \sigma(x, y, s)] = \mu_{\sigma T_2}. \end{aligned} \quad (\text{B33})$$

By solving the above equations, we get

$$\Theta_\sigma(x, y, s) = \mu_{\sigma T_1}^y \mu_{\sigma T_2}^x \mu_{12}^{xy} \Theta_\sigma(s). \quad (\text{B34})$$

The equation corresponding to $\sigma^2 = e$ reads as

$$W_\sigma(x, y, s, i) W_\sigma[\sigma(x, y, s, i)] = \eta_\sigma \chi_\sigma(x, y, s, i). \quad (\text{B35})$$

Combining Eqs. (B32) and (B35), we have

$$(\eta_{\sigma T_1} \eta_{\sigma T_2})^{x+y} w_\sigma(s, i) w_\sigma[\sigma(s, i)] = \eta_\sigma \chi_\sigma(x, y, s, i). \quad (\text{B36})$$

So, we conclude that $\eta_{\sigma T_1} = \eta_{\sigma T_2}$, and $\chi_\sigma(x, y, s, i) = \chi_\sigma(s, i)$. By applying σ on both sides of Eq. (B36), we get

$$w_\sigma[\sigma(s, i)] w_\sigma(s, i) = \eta_\sigma \chi_\sigma[\sigma(s, i)]. \quad (\text{B37})$$

Since the left sides of Eqs. (B36) and (B37) are equal, we have $\chi_\sigma(s, i) = \chi_\sigma[\sigma(s, i)]$. In particular, we have

$$\chi_\sigma(w, a/b) = \chi_\sigma(v, c/d) = \chi_\sigma^*(w, a/b), \quad (\text{B38})$$

which means

$$\chi_\sigma(w, a/b) = \pm 1. \quad (\text{B39})$$

Using the remaining $\varepsilon_\sigma(s, i)$, we can set $\chi_\sigma(u, a/b) = \chi_\sigma(v, a/b) = 1$. Then, we are left with $\varepsilon_\sigma(s, i)$ satisfying the following relations:

$$\varepsilon_\sigma(u, a) = \varepsilon_\sigma(v, b), \quad \varepsilon_\sigma(u, b) = \varepsilon_\sigma(v, a). \quad (\text{B40})$$

For group relation $\sigma^{-1} C_6 \sigma C_6 = e$, the corresponding equation is

$$\begin{aligned} & W_\sigma^{-1}[\sigma(x, y, s, i)] W_{C_6}[\sigma(x, y, s, i)] W_\sigma[C_6^{-1} \sigma(x, y, s, i)] \\ & \times W_{C_6}[C_6(x, y, s, i)] = \eta_{\sigma C_6} \chi_{\sigma C_6}(x, y, s, i). \end{aligned} \quad (\text{B41})$$

By simplifying the above equation, we have $\eta_{\sigma T_1} = \eta_{12}$ and $\chi_{\sigma C_6}(x, y, s, i) = \chi_{\sigma C_6}(s, i)$, with

$$\begin{aligned} & w_\sigma(v, i) w_\sigma(v, i_{\sigma 2}) = \eta_\sigma \eta_{\sigma C_6} \chi_{\sigma C_6}(v, i) \chi_{\sigma C_6}(v, i), \\ & w_\sigma(u, i) w_{C_6}(u, i_{\sigma 1}) w_\sigma(w, i_{\sigma 2}) = \eta_\sigma \eta_{\sigma C_6} \eta_{12} \chi_{\sigma C_6}(u, i) \\ & = \eta_\sigma \eta_{\sigma C_6} \eta_{12} \chi_\sigma(w, i_{\sigma 2}) \chi_{\sigma C_6}(w, i_{\sigma 2}). \end{aligned} \quad (\text{B42})$$

Using the remaining ε_σ transformation, we are able to set

$$\begin{aligned}\chi_{\sigma C_6}(u/v, a/b) &= 1, \\ \chi_{\sigma C_6}(w, a) &= \chi_\sigma(w, a) = \pm 1, \\ \chi_{\sigma C_6}(w, b) &= \chi_\sigma(w, b) = \pm 1.\end{aligned}\quad (\text{B43})$$

Further, by performing the remaining gauge transformation $V(x, y, s, i) = V(i) = V(i_{C_6})$, W_σ transforms as

$$\begin{aligned}W_\sigma(x, y, u, i) &\rightarrow V(i)W_\sigma(x, y, u, i)V^{-1}(i_{\sigma 1}), \\ W_\sigma(x, y, v/w, i) &\rightarrow V(i)W_\sigma(x, y, v/w, i)V^{-1}(i_{\sigma 2}).\end{aligned}\quad (\text{B44})$$

Then, we can set $w(u, a) = \text{I}$. The only V ambiguity left is a block diagonal independent of sites and legs matrix $V(x, y, s, i) = V$.

According to Eqs. (B36) and (B42), we can solve the transformation rules for reflection as

$$\begin{aligned}w_\sigma(u, a) &= \text{I}, \quad w_\sigma(u, b) = \chi_\sigma \eta_{\sigma C_6}, \\ w_\sigma(u, c) &= \chi_\sigma \eta_\sigma \eta_{\sigma C_6}, \quad w_\sigma(u, d) = \eta_\sigma; \\ w_\sigma(v, a) &= \eta_{C_6} \eta_{\sigma C_6}, \quad w_\sigma(v, b) = \chi_\sigma \eta_{12}, \\ w_\sigma(v, c) &= \eta_\sigma \eta_{C_6}, \quad w_\sigma(v, d) = \chi_\sigma \eta_{12} \eta_\sigma \eta_{\sigma C_6}; \\ w_\sigma(w, a) &= \chi_\sigma \eta_{C_6}, \quad w_\sigma(w, b) = \eta_{12} \eta_{\sigma C_6}, \\ w_\sigma(w, c) &= \eta_\sigma \eta_{C_6} \eta_{\sigma C_6}, \quad w_\sigma(w, d) = \chi_\sigma \eta_{12} \eta_\sigma,\end{aligned}\quad (\text{B45})$$

where $\chi_\sigma \equiv \chi_\sigma(w, a) = \chi_\sigma(w, b)$.

For the phase factor, the equations read as

$$[\Theta_\sigma(u)]^2 = \Theta_\sigma(v)\Theta_\sigma(w) = \mu_\sigma \quad (\text{B46})$$

as well as

$$\begin{aligned}[\Theta_\sigma(v)]^2 &= \mu_\sigma \mu_{\sigma C_6}, \\ \Theta_\sigma(u)\Theta_\sigma(w)\Theta_{C_6}(u) &= \mu_{12}\mu_\sigma \mu_{\sigma C_6},\end{aligned}\quad (\text{B47})$$

where we have used the fact $\prod_i \chi_\sigma(s, i) = \prod_i \chi_{\sigma C_6} = 1$.

According to Eqs. (B27), (B46), and (B47), we have

$$\begin{aligned}[\Theta_\sigma(u)\Theta_\sigma(w)\Theta_{C_6}(u)]^2 &= (\mu_{12}\mu_\sigma \mu_{\sigma C_6})^2 = 1 \\ &= \mu_\sigma \mu_\sigma \mu_{\sigma C_6} \mu_{12} \mu_{C_6} = \mu_{12} \mu_{C_6} \mu_{\sigma C_6}.\end{aligned}\quad (\text{B48})$$

So, we get $\mu_{\sigma C_6} = \mu_{12} \mu_{C_6}$. In our case, site tensors are \mathbb{Z}_2 odd, then the relation for μ causes additional constraint for η :

$$\eta_{\sigma C_6} = \eta_{12} \eta_{C_6}. \quad (\text{B49})$$

From Eq. (B46), we get

$$\Theta_\sigma(u) = \pm(\mu_\sigma)^{\frac{1}{2}}. \quad (\text{B50})$$

However, using the η ambiguity for σ , we can absorb the minus sign in the above equations by redefining $W_\sigma \rightarrow \eta W_\sigma$ and $\Theta_\sigma \rightarrow \mu \Theta_\sigma$. Further, by performing gauge transformation $V(a/b) = \text{I}$, $V(c/d) = \text{J}$, we can transform W_σ to their original forms.

Then, we get solutions for $\Theta_\sigma(s)$ as

$$\begin{aligned}\Theta_\sigma(u) &= (\mu_\sigma)^{\frac{1}{2}}; \\ \Theta_\sigma(v) &= \mu_{C_6} \Theta_{C_6}(u) \Theta_\sigma(u); \\ \Theta_\sigma(w) &= \mu_\sigma \mu_{C_6} [\Theta_{C_6}(u) \Theta_\sigma(u)]^{-1}.\end{aligned}\quad (\text{B51})$$

Let us summarize the result for lattice symmetry:

$$\begin{aligned}W_{T_1}(x, y, s, i) &= \eta_{12}^y, \\ W_{T_2}(x, y, s, i) &= \text{I}, \\ W_{C_6}(x, y, u, i) &= \eta_{12}^{xy + \frac{1}{2}x(x+1) + x+y} w_{C_6}(u, i), \\ W_{C_6}(x, y, v, i) &= \eta_{12}^{xy + \frac{1}{2}x(x+1) + x+y}, \\ W_{C_6}(x, y, w, i) &= \eta_{12}^{xy + \frac{1}{2}x(x+1)}, \\ W_\sigma(x, y, s, i) &= \eta_{12}^{x+y+xy} w_\sigma(s, i),\end{aligned}\quad (\text{B52})$$

where

$$\begin{aligned}w_{C_6}(u, a) &= w_{C_6}(u, c) = \text{I}, \\ w_{C_6}(u, b) &= w_{C_6}(u, d) = \eta_{12} \eta_{C_6},\end{aligned}\quad (\text{B53})$$

and $w_\sigma(s, i)$ are given in Eq. (B45) with additional condition $\eta_{\sigma C_6} = \eta_{12} \eta_{C_6}$.

For phase factor Θ_R , we get

$$\begin{aligned}\Theta_{T_1}(x, y, s) &= \mu_{12}^y, \\ \Theta_{T_2}(x, y, s) &= 1, \\ \Theta_{C_6}(x, y, u) &= \mu_{12}^{xy + \frac{1}{2}x(x+1) + x+y} \Theta_{C_6}(u), \\ \Theta_{C_6}(x, y, v) &= \mu_{12}^{xy + \frac{1}{2}x(x+1) + x+y}, \\ \Theta_{C_6}(x, y, w) &= \mu_{12}^{xy + \frac{1}{2}x(x+1)}, \\ \Theta_\sigma(x, y, s) &= \mu_{12}^{x+y+xy} \Theta_\sigma(s),\end{aligned}\quad (\text{B54})$$

where $\Theta_{C_6}(u)$ and $\Theta_\sigma(s)$ are given in Eqs. (B27) and (B51).

b. Adding time-reversal symmetry

Now, let us consider time-reversal symmetry \mathcal{T} . The transformation rule for time-reversal symmetry is defined in Eq. (10). We should keep in mind that time reversal is antiunitary, so for symmetry operation W_R , we have $\mathcal{T} W_R \mathcal{T}^{-1} = W_R^*$.

From group relation $T_1^{-1} \mathcal{T}^{-1} T_1 \mathcal{T} = T_2^{-1} \mathcal{T}^{-1} T_2 \mathcal{T} = \text{e}$, we get

$$\begin{aligned}W_{T_1}(x, y, s, i) [W_{\mathcal{T}}^{-1}(x, y, s, i)]^* W_{T_1}^*(x, y, s, i) \\ \times W_{\mathcal{T}}^*[T_1^{-1}(x, y, s, i)] = \eta_{T_1 \mathcal{T}} \chi_{T_1 \mathcal{T}} [T_1^{-1}(x, y, s, i)], \\ W_{T_2}(x, y, s, i) [W_{\mathcal{T}}^{-1}(x, y, s, i)]^* W_{T_2}^*(x, y, s, i) \\ \times W_{\mathcal{T}}^*[T_2^{-1}(x, y, s, i)] = \eta_{T_2 \mathcal{T}} \chi_{T_2 \mathcal{T}} [T_2^{-1}(x, y, s, i)].\end{aligned}\quad (\text{B55})$$

Similar to the previous case, by using $\varepsilon_{\mathcal{T}}$ transformation, we are able to set $\chi_{T_1 \mathcal{T}}$ and $\chi_{T_2 \mathcal{T}}$ to be identity. The solution for the above equation is

$$W_{\mathcal{T}}(x, y, s, i) = \eta_{T_1 \mathcal{T}}^x \eta_{T_2 \mathcal{T}}^y w_{\mathcal{T}}(s, i). \quad (\text{B56})$$

The remaining $\varepsilon_{\mathcal{T}}$ is independent of unit-cell coordinate (x, y) .

For group relation $\sigma^{-1} \mathcal{T}^{-1} \sigma \mathcal{T} = \text{e}$, we have

$$\begin{aligned}(\eta_{T_1 \mathcal{T}} \eta_{T_2 \mathcal{T}})^{x+y} w_\sigma^{-1}(s, i) [w_{\mathcal{T}}^{-1}(s, i)]^* \\ \times w_\sigma^*(s, i) w_{\mathcal{T}}^*[\sigma(s, i)] = \eta_{\sigma \mathcal{T}} \chi_{\sigma \mathcal{T}} [\sigma(s, i)].\end{aligned}\quad (\text{B57})$$

So, we conclude $\chi_{\sigma \mathcal{T}}(x, y, s, i) = \chi_{\sigma \mathcal{T}}(s, i)$ and $\eta_{T_1 \mathcal{T}} = \eta_{T_2 \mathcal{T}}$. Inserting the solution for $w_\sigma(s, i)$ into the above equation, we

get

$$w_T^{-1}(s,i)w_T[\sigma(s,i)] = \eta_{\sigma T}\chi_{\sigma T}^*[\sigma(s,i)]. \quad (\text{B58})$$

Acting σ on both sides of the above equation, we get

$$w_T^{-1}[\sigma(s,i)]w_T(s,i) = \eta_{\sigma T}\chi_{\sigma T}^*(s,i). \quad (\text{B59})$$

Since the left sides of the above two equations are Hermitian conjugate to each other, we conclude that $\chi_{\sigma T}(s,i) = \chi_{\sigma T}^*[\sigma(s,i)]$.

Let us consider $C_6^{-1}T^{-1}C_6T = e$. The corresponding equation is

$$W_{C_6}(x,y,s,i)[W_T^{-1}(x,y,s,i)]^*W_{C_6}^*(x,y,s,i) \times W_T^*[C_6^{-1}(x,y,s,i)] = \eta_{C_6T}\chi_{C_6T}[C_6^{-1}(x,y,s,i)]. \quad (\text{B60})$$

Then, we get $\eta_{T_1T} = \eta_{T_2T} = 1$ and $\chi_{C_6T}(x,y,s,i) = \chi_{C_6T}(s,i)$. Inserting values of W_{C_6} , we have

$$w_T^{-1}(s,i)w_T[C_6^{-1}(s,i)] = \eta_{C_6T}\chi_{C_6T}^*[C_6^{-1}(s,i)]. \quad (\text{B61})$$

Under transformation $W_T \rightarrow \varepsilon_T W_T$, χ_{C_6T} changes as

$$\chi_{C_6T}(s,i) \rightarrow \chi_{C_6T}(s,i)\varepsilon_T[C_6(s,i)]\varepsilon_T^*(s,i). \quad (\text{B62})$$

So, we can set all $\chi_{C_6T}(s,i) = 1$, with remaining $\varepsilon_T \equiv \varepsilon_T(s,a/b) = \varepsilon_T^*(s,c/d)$. The above equation is simplified as

$$w_T^{-1}(s,i)w_T[C_6^{-1}(s,i)] = \eta_{C_6T}. \quad (\text{B63})$$

Let us try to fix $\chi_{\sigma T}(s,i)$ by remaining ε_T . We observe that $\chi_{\sigma T}(s,a/b) \rightarrow \chi_{\sigma T}(s,a/b)(\varepsilon_T^*)^2$. So, we can set $\chi_{\sigma T}(u,a) = 1$. Further, we get

$$\chi_{\sigma T}(v,b) = \chi_{\sigma T}^*(u,d) = \chi_{\sigma T}(u,a) \quad (\text{B64})$$

due to the relation $\chi_{\sigma T}(s,i) = \chi_{\sigma T}^*[\sigma(s,i)]$. So, we have

$$w_T^{-1}(u,a)w_T(u,d) = \eta_{\sigma T}. \quad (\text{B65})$$

From Eqs. (B63) and (B65), we conclude

$$w_T^{-1}(s,i)w_T[\sigma(s,i)] = \eta_{\sigma T}, \quad (\text{B66})$$

namely, we have $\chi_{\sigma T}(s,i) = 1$.

So, once we can determine the value of $w_T \equiv w_T(u,a)$, we get the complete the solution of time-reversal symmetry W_T with $W_T(x,y,s,i) = w_T(s,i)$. And, $w_T(s,i)$ can be expressed by w_T as follows:

$$\begin{aligned} w_T(u,a) &= w_T, & w_T(u,b) &= \eta_{C_6T}w_T, \\ w_T(u,c) &= \eta_{\sigma T}\eta_{C_6T}w_T, & w_T(u,d) &= \eta_{\sigma T}w_T; \\ w_T(v,a) &= \eta_{C_6T}w_T, & w_T(v,b) &= w_T, \\ w_T(v,c) &= \eta_{\sigma T}w_T, & w_T(v,d) &= \eta_{\sigma T}\eta_{C_6T}w_T; \\ w_T(w,a) &= w_T, & w_T(w,b) &= \eta_{C_6T}w_T, \\ w_T(w,c) &= \eta_{\sigma T}\eta_{C_6T}w_T, & w_T(w,d) &= \eta_{\sigma T}w_T. \end{aligned} \quad (\text{B67})$$

Now, let us determine Θ_T . The equations for Θ_T read as

$$\Theta_g^*(x,y,s)\Theta_T(x,y,s)\Theta_g^*(x,y,s)\Theta_T^*[g^{-1}(x,y,s)] = \mu_{gT}, \quad (\text{B68})$$

where g labels lattice symmetry generators T_1, T_2, C_6, σ . Further, under action of global phase factor Φ , Θ_T changes as

$$\Theta_T(x,y,s) \rightarrow \Theta_T(x,y,s)\Phi^2. \quad (\text{B69})$$

Therefore, by choosing the proper phase, we can always set $\Theta_T(u) = 1$. Combined with Eq. (B54), we are able to solve Eq. (B68). The solution is $\Theta_T(x,y,s) = \Theta_T(s)$, where

$$\begin{aligned} \Theta_T(u) &= 1, \\ \Theta_T(v) &= \mu_{12}\mu_{C_6}, \\ \Theta_T(w) &= 1. \end{aligned} \quad (\text{B70})$$

The constraint on μ_{gT} is

$$\mu_{\sigma T} = \mu_{\sigma}, \quad \mu_{C_6T} = \mu_{12}\mu_{C_6}. \quad (\text{B71})$$

Since site tensors are Z_2 odd, we also have constraint on η_{gT} as

$$\eta_{\sigma T} = \eta_{\sigma}, \quad \eta_{C_6T} = \eta_{12}\eta_{C_6}. \quad (\text{B72})$$

Finally, let us consider group relation $T^2 = e$. For W_T , we get

$$w_T(s,i)w_T^*(s,i) = \eta_T\chi_T(x,y,s,i), \quad (\text{B73})$$

where we use the fact that $W_T(x,y,s,i) = w_T(s,i)$. Inserting Eq. (B67) back to the above equation, we conclude that $\chi_T \equiv \chi_T(x,y,s,i) = \pm 1$. So, we have

$$w_T(s,i)w_T^*(s,i) = \eta_T\chi_T. \quad (\text{B74})$$

Similarly, for phase factor Θ_T , we have

$$\Theta_T(s,i)\Theta_T^*(s,i) = \mu_T. \quad (\text{B75})$$

We conclude that $\mu_T = 1$.

In our case, a physical leg supports Kramer doublets. Namely, we have $U_T^2 = -1$, where $T = U_T K$ is the action of time-reversal operator on a physical leg, and K is the complex conjugation. In the following, we will prove that η_T cannot be trivial, and site tensor must be Z_2 odd tensor.

To see this, we can act time reversal twice on site tensor T^s . Then, we get

$$\begin{aligned} T^s &= \Theta_T W_T T \Theta_T W_T T \circ T^s \\ &= \prod_i \chi_T(s,i) \mu_T \eta_T T^2 \circ T^s \\ &= -\eta_T \circ T^s, \end{aligned} \quad (\text{B76})$$

where we use Eqs. (B73) and (B75) to get the second line. In the third line, we use the fact that $\mu_T = 1$, $\chi_T(s,i) = \chi_T = \pm 1$, while $T^2 \circ T^s = -T^s$. So, we conclude $\eta_T \circ T^s = -T^s$, namely, η_T must be nontrivial, and T^s is Z_2 odd.

Let us try to understand the physical meaning of the above statement. We want to construct a PEPS wave function on the kagome lattice with every site as a Kramer doublet, and preserving all lattice symmetries as well as time-reversal symmetry. However, the above proof tells us that we are forced to introduce Z_2 gauge structure due to the nontrivialness of η_T . The Z_2 gauge structure leads to either a spin-liquid phase or a symmetry-breaking phase in the long-range physics. In other words, we can never be able to write a trivial symmetric wave function with Kramer doublets on physical sites with no ground-state degeneracy in this formulation! The above argument can be viewed as manifestation of the Hastings-Oshikawa-Lieb-Schultz-Mattis theorem on PEPS.

c. Adding spin-rotation symmetry

At last, let us consider the spin-rotation symmetry. The action of a group element of the spin-rotation symmetry on site tensors is defined as

$$U_{\theta\vec{n}} \circ T^s \doteq (e^{i\theta\vec{n}\cdot\vec{S}})_{ij} (T^s)^j_{\alpha\beta\gamma\delta}, \quad (\text{B77})$$

where \vec{S} labels physical spins. In our case, the system is formed by half-integer spins. For PEPS invariant under spin-rotation symmetry, we have

$$\begin{aligned} T^s &= \Theta_{\theta\vec{n}} W_{\theta\vec{n}} U_{\theta\vec{n}} \circ T^s, \\ B_b &= W_{\theta\vec{n}} \circ B_b. \end{aligned} \quad (\text{B78})$$

Here, $W_{\theta\vec{n}}$ and $\Theta_{\theta\vec{n}}$ are projective representations of spin-rotation symmetry. To see this, let us consider the group multiplication relation

$$U_{\theta_1\vec{n}_1} \cdot U_{\theta_2\vec{n}_2} = U_{\theta_3\vec{n}_3}. \quad (\text{B79})$$

The corresponding equation on virtual legs reads as

$$\begin{aligned} W_{\theta_1\vec{n}_1}(x, y, s, i) \cdot W_{\theta_2\vec{n}_2}(x, y, s, i) \\ = \chi_{\theta_1\vec{n}_1, \theta_2\vec{n}_2} \eta_{\theta_1\vec{n}_1, \theta_2\vec{n}_2} \cdot W_{\theta_3\vec{n}_3}(x, y, s, i). \end{aligned} \quad (\text{B80})$$

The above equation implies $W_{\theta\vec{n}}(x, y, s, i)$ forms a projective representation of SU(2) symmetry, with coefficient $U(1) \times Z_2$. However, it is well known that SU(2) group has no nontrivial projective symmetry. Thus, we can always set χ 's and η 's to be trivial ones by group extension ambiguities. Further, we have $\Theta_{\theta\vec{n}}$ always equal to 1 since SU(2) has no nontrivial 1D representation.

The onsite spin-rotation symmetry commutes with all lattice symmetry. Namely, we have $g^{-1} U_{\theta\vec{n}}^{-1} g U_{\theta\vec{n}} = \text{e}$, where $g = T_1, T_2, C_6, \sigma$. So, for W_g and $W_{\theta\vec{n}}$, the corresponding equations are:

$$\begin{aligned} W_g^{-1}(x, y, s, i) W_{\theta\vec{n}}^{-1}(x, y, s, i) W_g(x, y, s, i) \\ \times W_{\theta\vec{n}}[g^{-1}(x, y, s, i)] = \eta_{g, \theta\vec{n}} \chi_{g, \theta\vec{n}}(x, y, s, i). \end{aligned} \quad (\text{B81})$$

According to the above solution, we have $W_g(x, y, s, i) = \text{I}/\text{J}$, which always commutes with $W_{\theta\vec{n}}$. So, we get

$$W_{\theta\vec{n}}^{-1}(x, y, s, i) W_{\theta\vec{n}}[g^{-1}(x, y, s, i)] = \eta_{g, \theta\vec{n}} \chi_{g, \theta\vec{n}}(x, y, s, i). \quad (\text{B82})$$

One can prove that $W_{\theta\vec{n}}^{-1}(x, y, s, i) W_{\theta\vec{n}}[g^{-1}(x, y, s, i)]$ forms a 1D representation of SU(2) symmetry. Thus, $\eta_{g, \theta\vec{n}}$ and $\chi_{g, \theta\vec{n}}$ can be set to trivial. We have

$$W_{\theta\vec{n}}(x, y, s, i) = w_{\theta\vec{n}}. \quad (\text{B83})$$

Namely, the representation of spin-rotation symmetry shares the same form on virtual legs.

Now, we consider the relation

$$W_{\theta=2\pi}(x, y, s, i) = \eta_{\theta=2\pi} \chi_{\theta=2\pi}(x, y, s, i). \quad (\text{B84})$$

Using the fact that $W_{\theta=2\pi}(x, y, s, i) = w_{\theta=2\pi}$, which is independent of sites and virtual legs, we conclude that $\chi_{\theta=2\pi}(x, y, s, i) = \chi_{\theta=2\pi} = \pm 1$.

At last, we have the relation $U_{\theta\vec{n}}^{-1} T^{-1} U_{\theta\vec{n}} T = \text{e}$, which is the equivalent way to say that a spin reverses its direction

under time-reversal symmetry. Then, for transformation rules on virtual legs, we get

$$\begin{aligned} W_{\theta\vec{n}}^{-1}(x, y, s, i) [W_T^{-1}(x, y, s, i)]^* W_{\theta\vec{n}}^*(x, y, s, i) \\ \times W_T^*(x, y, s, i) = \eta_{T, \theta\vec{n}} \chi_{T, \theta\vec{n}}(x, y, s, i). \end{aligned} \quad (\text{B85})$$

We can easily conclude that $\eta_{T, \theta\vec{n}} = \text{I}$ and $\chi_{T, \theta\vec{n}}(x, y, s, i) = 1$. The result is reasonable since we also expect spins living on virtual legs reverse direction under time-reversal action. Then, we have

$$w_{\theta\vec{n}}^{-1} [w_T^{-1}(s, i)]^* w_{\theta\vec{n}}^* w_T^*(s, i) = \text{I}. \quad (\text{B86})$$

In our case, physical legs are spin doublets, so $U_{\theta=2\pi} = -\text{I}$. Using similar proof as in the Kramer doublet case, we are able to show that $\eta_{\theta=2\pi}$ must be nontrivial and site tensors must be Z_2 odd. So, we conclude $\eta_{\theta=2\pi} = \eta_T = \text{J}$. Further, it is straightforward to see that one can always redefine J such that $\chi_{\theta=2\pi} = 1$. WLOG, we assume $\text{J} = \text{I}_{D_1} \oplus (-\text{I}_{D_2})$, where $D_1 + D_2 = D$ is dimension of a virtual leg.

Now, let us fix the form of $w_{\theta\vec{n}}$ and w_T using the remaining V ambiguity, which is a leg-independent block diagonal matrix. Under gauge transformation V, we have

$$\begin{aligned} w_{\theta\vec{n}} &\rightarrow V w_{\theta\vec{n}} V^{-1}, \\ w_T &\rightarrow V w_T [V^{-1}]^*. \end{aligned} \quad (\text{B87})$$

So, first, we are able to set the (reducible) representation of spin-rotation symmetry on virtual legs as

$$w_{\theta\vec{n}} = \bigoplus_{i=1}^M (\text{I}_{n_i} \otimes e^{i\theta\vec{n}\cdot\vec{S}_i}), \quad (\text{B88})$$

where \vec{S}_i labels spin quantum number while n_i is the extra degeneracy associated with spin \vec{S}_i . In other words, a virtual leg is formed by n_i number of spin S_i , where $i = 1, 2, \dots, M$. The dimension for spin S_i is $n_i(2S_i + 1)$, and we get the total dimension of a virtual leg $D = \sum_{i=1}^M n_i(2S_i + 1)$. Further, we can arrange the order of S_i , such that S_i is integer (half-integer) for $i \leq m_1$ ($i > m_1$), and we have $S_1 < \dots < S_{m_1}$ as well as $S_{m_1+1} < \dots < S_M$. Apparently, $D_1 = \sum_{i=1}^{m_1} n_i(2S_i + 1)$ and $D_2 = \sum_{i=m_1+1}^M n_i(2S_i + 1)$.

After fixing the form of $w_{\theta\vec{n}}$, we are still left with overall gauge transformation $V = \bigoplus_i (\tilde{V}_{S_i} \otimes \text{I}_{2S_i+1})$, where \tilde{V}_{S_i} is an arbitrary n_i -dimensional invertible matrix. We will use the remaining gauge degree of freedom to fix the representation of time-reversal symmetry on virtual legs $w_T(s, i)$. Particularly, let us focus on $w_T \equiv w_T(u, a)$ since representations on other legs can be generated using Eq. (B67).

According to Eqs. (B86) and (B88), time reversal reverses spin direction. So, the most general form of w_T reads as

$$w_T = \bigoplus_{i=1}^M (\tilde{w}_T^{S_i} \otimes e^{i\pi S_i^y}). \quad (\text{B89})$$

Here, $\tilde{w}_T^{S_i}$ is n_i -dimensional invertible matrix. Further, according to Eq. (B74), we have

$$\bigoplus_{i=1}^M ([\tilde{w}_T^{S_i} (\tilde{w}_T^{S_i})^*] \otimes [e^{i\pi S_i^y} e^{-i\pi (S_i^y)^*}]) = \eta_T \chi_T, \quad (\text{B90})$$

where $e^{i\pi S_i^y} e^{-i\pi(S_i^y)^*} = \mathbf{I} (-\mathbf{I})$ for integer (half-integer) spin. Note that we focus on the case where $\eta_T = \mathbf{J}$, so we have

$$\tilde{w}_T^{S_i} (\tilde{w}_T^{S_i})^* = \chi_T. \quad (\text{B91})$$

Then, under gauge transformation $V = \bigoplus_i (\tilde{V}_{S_i} \otimes \mathbf{I}_{2S_i+1})$,

$$\tilde{w}_T^{S_i} \rightarrow \tilde{V}_{S_i} \tilde{w}_T^{S_i} [\tilde{V}_{S_i}^{-1}]^*. \quad (\text{B92})$$

If two matrices are related by the above transformation, then they are consimilar to each other. The canonical form for matrix under consimilarity has already been studied in the mathematical literature [97]. In the following, we will give results for the two cases $\chi_T = \pm 1$.

First, consider $\chi_T = 1$. Then, the n_i -dimensional extra degeneracy space should accommodate representation of Kramer singlet. By choosing proper basis, we are able to obtain

$$\tilde{w}_T^{S_i} = \mathbf{I}_{n_i}. \quad (\text{B93})$$

Then, the remaining gauge transformation must satisfy

$$\tilde{V}_{S_i} = \tilde{V}_{S_i}^*. \quad (\text{B94})$$

Namely, \tilde{V}_{S_i} is real matrix.

Then, we consider the case where $\chi_T = -1$. Then, the n_i -dimensional space is Kramer doublet, so n_i should be even number in this case. By choosing the proper basis, the canonical form for $\tilde{w}_T^{S_i}$ is

$$\tilde{w}_T^{S_i} = \Omega_{n_i}, \quad (\text{B95})$$

where $\Omega_{n_i} = i\sigma_y \otimes \mathbf{I}_{n_i/2}$. After choosing the basis for canonical $\tilde{w}_T^{S_i}$, we are left with gauge transformation $V = \bigoplus_i (\tilde{V}_{S_i} \otimes \mathbf{I}_{S_i(S_i+1)})$ that satisfies

$$\tilde{V}_{S_i} \Omega_{n_i} = \Omega_{n_i} \tilde{V}_{S_i}^*. \quad (\text{B96})$$

Now, let us summarize the result. For a fully symmetric wave function on kagome lattice with a half-integer spin per site, there are at most $2^3 \times 2^2 = 32$ classes in the above framework. The different classes are distinguished by parameter η 's and χ 's. Here, $\eta_{12}, \eta_{C_6}, \eta_\sigma \in \{\mathbf{I}, \mathbf{J}\}$, while other η 's are fixed. $\chi_\sigma, \chi_T = \pm 1$.

2. Construction of PEPS state for different classes

In this section, we will use the symmetry transformation rules obtained above as a constraint to determine the Hilbert space for a symmetric PEPS state for all classes. We will present the general framework first, and then work out possible forms of bond tensors and site tensors separately.

a. General framework

In the following, we will set up the framework to get the constraint Hilbert space for symmetric PEPS. Let us start by reviewing Hilbert space of PEPS without any symmetry. We require every virtual leg of site tensors is isomorphism to a D -dimensional Hilbert space \mathbb{V} . Virtual legs of bond tensors are all isomorphism to $\bar{\mathbb{V}}$, which is the dual space of \mathbb{V} . Further, every physical leg is isomorphism to a d -dimensional Hilbert space \mathbb{U} .

The Hilbert space of a single bond tensor \mathbb{V}_B and a site tensor \mathbb{V}_T have the following tensor product structure:

$$\begin{aligned} \mathbb{V}_B &\cong \bar{\mathbb{V}} \otimes \bar{\mathbb{V}}, \\ \mathbb{V}_T &\cong \mathbb{U} \otimes \mathbb{V} \otimes \mathbb{V} \otimes \mathbb{V} \otimes \mathbb{V}. \end{aligned} \quad (\text{B97})$$

Then, let us add the spin-rotation symmetry. For a physical leg, there lives a half-integer spin S_0 , so we have

$$\mathbb{U} \cong \mathbb{V}_{S_0}, \quad (\text{B98})$$

where \mathbb{V}_{S_0} accommodates an irreducible representation of $\text{SU}(2)$ with dimension $2S_0 + 1$.

Let us consider virtual legs of site tensors. Notice that all virtual legs of site tensors are related by lattice group transformations. So, in the presence of lattice symmetries, all virtual legs of site tensors share the same representation (can be reducible) for spin rotation up to isomorphism. In particular, as we show in the previous subsection, we can always choose a proper basis, such that the spin operators have the same form on all virtual legs of site tensors, as in Eq. (B83). Further, we can decompose $\mathbb{V} = \mathbb{V}_1 \oplus \mathbb{V}_2$, where \mathbb{V}_1 with dimension D_1 denotes integer spin representations, and \mathbb{V}_2 ($\bar{\mathbb{V}}_2$) with dimension D_2 accommodates half-integer spin representations.

We can further decompose \mathbb{V} to $\text{SU}(2)$ irreducible representations as

$$\mathbb{V} \cong \bigoplus_{i=1}^M (\mathbb{D}_{S_i} \otimes \mathbb{V}_{S_i}). \quad (\text{B99})$$

Here, \mathbb{D}_{S_i} is an n_i -dimensional space that labels the extra degeneracy for spin S_i . According to the decomposition, the orthonormal basis of \mathbb{V} can be chosen as

$$|S_i, t_\alpha, m_\beta\rangle \equiv |S_i, t_\alpha\rangle \otimes |S_i, m_\beta\rangle, \quad (\text{B100})$$

where $|S_i, m_\beta\rangle \in \mathbb{V}_{S_i}$ labels an eigenstate of \vec{S}^2 and S_z , while $|S_i, t_\alpha\rangle \in \mathbb{D}_{S_i}$ labels basis in the extra degenerate space. Under this basis, the spin-rotation operator shares the form as in Eq. (B88).

Similarly, virtual legs of bond tensors can be decomposed as

$$\bar{\mathbb{V}} \cong \bigoplus_{i=1}^M (\bar{\mathbb{D}}_{S_i} \otimes \bar{\mathbb{V}}_{S_i}) \quad (\text{B101})$$

with basis as

$$\langle S_i, t_\alpha, m_\beta | \equiv \langle S_i, t_\alpha | \otimes \langle S_i, m_\beta |. \quad (\text{B102})$$

We point out that the nontrivial Z_2 IGG element is in fact 2π spin rotation on all virtual legs. In other words, we get Z_2 group $\{\mathbf{I}, g\}$ with a trivial representation on \mathbb{V}_1 ($\bar{\mathbb{V}}_1$) and a nontrivial representation on \mathbb{V}_2 ($\bar{\mathbb{V}}_2$).

After establishing the structure of a single virtual leg as in Eq. (B99), we are able to get the structure of \mathbb{V}_B and \mathbb{V}_T according to Eq. (B97). \mathbb{V}_B and \mathbb{V}_T are formed by tensor product of $\text{SU}(2)$ representation, which can be decomposed to direct sums of irreps of $\text{SU}(2)$ by Clebsch-Gordan coefficients. Further, we require bond states and site states to be spin singlets, which gives extra constraint to the possible Hilbert space.

Now, let us add lattice symmetries. There are two kinds of constraint caused by lattice symmetries. First, a lattice symmetry may act as a linear mapping between the Hilbert space of different bonds and sites. In other words, if a single bond/site tensor is fixed, one can use transformation rules of lattice symmetries to generate other symmetry-related tensors. Second, a lattice symmetry may also be a self-mapping (automorphism) on the Hilbert space of a single bond/site. In this case, the possible Hilbert space of a single bond/site tensor will be further constrained by lattice symmetry transformation rules.

At last, due to time-reversal symmetry, we require all tensors to be Kramer singlets. In the following, we will apply the method developed above to solve the possible Hilbert space for the symmetric PEPS wave function of all classes.

b. Constraint on bond tensors

Let us consider bond tensors first. A bond tensor can be viewed as a matrix with dimension $D \times D$. Let us define $B_b = B_{(xys i | x' y' s' i')}$ as the bond tensor connecting two virtual legs (x, y, s, i) and (x', y', s', i') . It is obvious that $B_{(xys i | x' y' s' i')} = B_{(x' y' s' i' | xys i)}^t$.

Under the action of spin-rotation symmetry $w_{\theta \vec{n}} = \bigoplus_{i=1}^M (\mathbb{I}_{n_i} \otimes e^{i\theta \vec{n} \cdot \vec{S}_i})$, the bond tensor is a spin singlet in the sense

$$B_b = w_{\theta \vec{n}}^* \cdot B_b \cdot w_{\theta \vec{n}}^{-1}. \quad (\text{B103})$$

Then, we can explicitly write bond tensor B_b as a block diagonal matrix according to the spin quantum number of virtual legs as

$$B_b = \bigoplus_{i=1}^M (\tilde{B}_b^{S_i} \otimes K_{S_i}), \quad (\text{B104})$$

where $\tilde{B}_b^{S_i}$ is an n_i -dimensional matrix, and K_{S_i} is a $(2S_i + 1)$ -dimensional matrix labeling singlet state. More precisely, the quantum state $\hat{K}_{S_i} \equiv \langle S_i, m_\alpha, S_i, m_\beta | (K_{S_i})_{\alpha\beta} \rangle$ is a singlet state under $S_{\text{tot}} = S \otimes \mathbb{I} + \mathbb{I} \otimes S$. Here, $m_\alpha = -S_i + \alpha - 1$ labels the quantum number of S_i^z . Namely, we have

$$\langle S, m_\alpha, S, m_\beta | (K_S)_{\alpha\beta} S_{\text{tot}}^2 = 0. \quad (\text{B105})$$

Using Clebsch-Gordan(CG) coefficients, we get

$$(K_S)_{\alpha\beta} = e^{i\phi_S} (-1)^{S-m_\alpha} \delta_{m_\alpha, -m_\beta}, \quad (\text{B106})$$

where ϕ_S is an indefinite phase. We can absorb the phase factor to \tilde{B}_b^S , thus K_S is always real. For example, we have $K_{S=0} = 1$, $K_{S=\frac{1}{2}} = i\sigma_y$.

From another point of view, the Hilbert space of a bond tensor \mathbb{V}_B is the tensor product of two virtual legs \mathbb{V} , where \mathbb{V} is decomposed as Eq. (B101). So, we can decompose \mathbb{V}_B as

$$\begin{aligned} \mathbb{V}_B &\cong \bigoplus_{i,j} [(\tilde{\mathbb{D}}_{S_i} \otimes \tilde{\mathbb{D}}_{S_j}) \otimes (\tilde{\mathbb{V}}_{S_i} \otimes \tilde{\mathbb{V}}_{S_j})] \\ &\cong \bigoplus_{i,j,k} (\tilde{\mathbb{D}}_{S_i} \otimes \tilde{\mathbb{D}}_{S_j} \otimes \tilde{\mathbb{V}}_{S_i S_j}^{S_k} \otimes \tilde{\mathbb{V}}_{S_k}), \end{aligned} \quad (\text{B107})$$

where $\tilde{\mathbb{V}}_{S_i S_j}^{S_k}$ is the “fusion space,” which means different ways to fuse spin S_i and S_j to spin S_k . According to representation

theory of $\text{SU}(2)$, $\tilde{\mathbb{V}}_{S_i S_j}^{S_k}$ is isomorphic to \mathbb{C} if $|S_i - S_j| \leq S_k \leq S_i + S_j$. Otherwise, $\tilde{\mathbb{V}}_{S_i S_j}^{S_k}$ vanishes. Since we only focus on spin-singlet bond states $S_k = 0$, so we conclude the possible Hilbert space of a bond tensor should be

$$\mathbb{V}_B^{S=0} \cong \bigoplus_i (\tilde{\mathbb{D}}_{S_i} \otimes \tilde{\mathbb{D}}_{S_i} \otimes \tilde{\mathbb{V}}_{S_i S_i}^{S=0} \otimes \tilde{\mathbb{V}}_{S=0}), \quad (\text{B108})$$

where we use the fact $\tilde{\mathbb{V}}_{S_i S_j}^{S=0}$ vanishes if $S_i \neq S_j$. Then, $\hat{B}_b \in \mathbb{V}_B^{S=0}$ can be decomposed to $\hat{B}_b \in \tilde{\mathbb{D}}_{S_i} \otimes \tilde{\mathbb{D}}_{S_i}$ and $\hat{K}_{S_i} \in \tilde{\mathbb{V}}_{S_i S_i}^{S=0} \otimes \tilde{\mathbb{V}}_{S=0}$. Namely, we have

$$\hat{B}_b = \sum_{i; \alpha_1, \alpha_2; \beta_1, \beta_2} \langle S_i, t_{\alpha_1}, m_{\alpha_2}; S_i, t_{\beta_1}, m_{\beta_2} | (\tilde{B}_b^{S_i})_{\alpha_1 \beta_1} (K_{S_i})_{\alpha_2 \beta_2} \rangle. \quad (\text{B109})$$

The above equation is just another way to express Eq. (B104). Notice that we use \hat{B}_b to denote the quantum state associated with matrix (tensor) B_b .

Let us add the lattice symmetry. Given a single bond tensor B_{b_0} , we can generate all other bond tensors by using the relation $R^{-1} B_{b_0} = R^{-1} W_R R \circ B_{b_0}$, where R is some lattice symmetry here. The explicit expression is

$$\begin{aligned} B_{[R(xys i) | R(x' y' s' i')]} &= W_R^* [R(x, y, s, i)] B_{(xys i | x' y' s' i')} W_R^{-1} [R(x', y', s', i')]. \end{aligned} \quad (\text{B110})$$

It is obvious that we can generate all bond tensors if we consider the group generated by T_1 , T_2 , and C_6 .

Further, reflection σ will provide extra constraint on the Hilbert space of a single bond tensor. Let us consider $B_{(vd|wb)} \equiv B_{(00vd|00wb)}$. It is straightforward to see that

$$B_{(vd|wb)} = w_\sigma^*(v, d) B_{(vd|wb)}^t w_\sigma^{-1}(w, b). \quad (\text{B111})$$

According to Eq. (B45), we have $w_\sigma(v, d) = \chi_\sigma \eta_{12} \eta_\sigma \eta_{\sigma C_6}$ and $w_\sigma(w, b) = \eta_{12} \eta_\sigma \eta_{\sigma C_6}$. Then, we get

$$B_{(vd|wb)} = \chi_\sigma \eta_\sigma B_{(vd|wb)}^t. \quad (\text{B112})$$

Namely, for any block of $B_{(vd|wb)}$, it is either symmetric or antisymmetric, depending on values of χ_σ and η_σ . One can easily verify that the above result is not limited to bond $B_{(vd|wb)}$. In fact, it is true for all bond tensors.

Note that for integer (half-integer) spin S , K_S is symmetric (antisymmetric). So, we conclude matrix $\tilde{B}_b^{S_i}$ must be either symmetric or antisymmetric depending on values of χ_σ and η_σ . In particular, we can write

$$\eta_R = \bigoplus_i (\mu_R)^{2S_i} \mathbb{I}_{n_i(2S_i+1)}, \quad (\text{B113})$$

where $\mu_R = 1$ (-1) for $\eta_R = \mathbb{I}$ (J). Since we also have $K_{S_i}^t = (-1)^{2S_i} K_{S_i}$, we conclude

$$\tilde{B}_b^{S_i} = (-\mu_\sigma)^{2S_i} \chi_\sigma (\tilde{B}_b^{S_i})^t. \quad (\text{B114})$$

Finally, let us consider time-reversal symmetry. The bond tensor should be a Kramer singlet in the sense

$$B_{(s_1 i_1 | s_2 i_2)}^* = W_T(s_1, i_1) B_{(s_1 i_1 | s_2 i_2)} W_T^t(s_2, i_2). \quad (\text{B115})$$

By inserting Eq. (B67), we conclude, for any bond B_b ,

$$B_b^* = \eta_\sigma w_T B_b w_T^\dagger. \quad (\text{B116})$$

Further, using Eqs. (B89) and (B104), we get

$$(\tilde{B}_b^{S_i})^* = (\mu_\sigma)^{2S_i} \tilde{w}_T^{S_i} \tilde{B}_b^{S_i} (\tilde{w}_T^{S_i})^\dagger, \quad (\text{B117})$$

where we use the fact that K_S is invariant under time-reversal symmetry:

$$e^{i\pi S_y} K_S (e^{i\pi S_y})^\dagger = K_S^*. \quad (\text{B118})$$

Here, we have $\tilde{w}_T^{S_i} = \mathbb{I}_{n_i}$ for $\chi_T = 1$ while $\tilde{w}_T^{S_i} = \Omega_{n_i}$ for $\chi_T = -1$.

So, to summarize, the constraints on the Hilbert space of a single bond tensor are determined by parameters χ_σ , η_σ , and χ_T . We will list the constraints case by case.

(1) $\chi_T = 1$. In this case, time-reversal symmetry reads as

$$w_T = \bigoplus_{i=1}^M (\mathbb{I}_{n_i} \otimes e^{i\pi S_i^y}). \quad (\text{B119})$$

So, according to Eq. (B117),

$$(\tilde{B}_b^{S_i})^* = (\mu_\sigma)^{2S_i} \tilde{B}_b^{S_i}. \quad (\text{B120})$$

Further, we are left with remaining global gauge transformation

$$V = \bigoplus_i (\tilde{V}_{S_i} \otimes \mathbb{I}_{2S_i+1}), \quad (\text{B121})$$

where \tilde{V}_{S_i} is matrix defined on \mathbb{R} . Under gauge transformation V , we get

$$\tilde{B}_b^{S_i} \rightarrow \tilde{V}_{n_i} \tilde{B}_b^{S_i} \tilde{V}_{n_i}^\dagger. \quad (\text{B122})$$

(a) $\eta_\sigma = \mathbb{I}$, $\chi_\sigma = 1$. In this case, we get $\tilde{B}_b^{S_i}$ is real symmetric for integer S_i , while real antisymmetric for half-integer S_i .

(b) $\eta_\sigma = \mathbb{I}$, $\chi_\sigma = -1$. In this case, we get $\tilde{B}_b^{S_i}$ is real antisymmetric for integer S_i , while real symmetric for half-integer S_i .

(c) $\eta_\sigma = \mathbb{J}$, $\chi_\sigma = 1$. In this case, we get $\tilde{B}_b^{S_i}$ is real symmetric for integer S_i , while imaginary symmetric for half-integer S_i .

(d) $\eta_\sigma = \mathbb{J}$, $\chi_\sigma = -1$. In this case, we get $\tilde{B}_b^{S_i}$ is real antisymmetric for integer S_i , while imaginary antisymmetric for half-integer S_i .

By using the remaining gauge transformation V , we can set the bond tensor to maximal entangled states. Namely, if $\tilde{B}_b^{S_i}$ is real symmetric, the canonical form is

$$\tilde{B}_b^{S_i} = \text{Diag}(1, \dots, 1, -1, \dots, -1), \quad (\text{B123})$$

where the number of \pm sign $n_{i\pm}$ is not fixed. After doing this, we are still left with gauge transformation $\tilde{V}_{n_i} \in \text{O}(n_{i+}) \otimes \text{O}(n_{i-})$. Here, we point out that different $n_{i\pm}$ does not lead to new classes. If we do not require bond tensors to be maximal entangled, different $n_{i\pm}$ can be connected adiabatically by continuously tuning the entries of bond tensors. If $\tilde{B}_b^{S_i}$ is real antisymmetric, the canonical form is

$$\tilde{B}_b^{S_i} = \Omega_{n_i/2}, \quad (\text{B124})$$

where $\Omega \equiv i\sigma_y \otimes \mathbb{I}_{n_i/2}$. The remaining gauge transformation satisfies $\Omega_{n_i/2} = \tilde{V}_{n_i} \Omega_{n_i/2} \tilde{V}_{n_i}^\dagger$. If $\tilde{B}_b^{S_i}$ is imaginary, the canonical form is similar as the real case, except that all entries are replaced by $\pm i$.

(2) $\chi_T = -1$. In this case, the time-reversal symmetry reads as

$$w_T = \bigoplus_{i=1}^M (\Omega_{n_i} \otimes e^{i\pi S_i^y}). \quad (\text{B125})$$

So, we get the constraint on the bond tensor to be

$$(\tilde{B}_b^{S_i})^* = (\mu_\sigma)^{2S_i} \Omega_{n_i} \tilde{B}_b^{S_i} \Omega_{n_i}^{-1}. \quad (\text{B126})$$

Then, depending on values of μ_σ and S_i , either $\tilde{B}_b^{S_i}$ or $i\tilde{B}_b^{S_i}$ is a quaternion matrix. In this case, the remaining gauge transformation is block diagonal matrix V , which reads

$$V = \bigoplus_i (\tilde{V}_{S_i} \otimes \mathbb{I}_{2S_i+1}), \quad (\text{B127})$$

where \tilde{V}_{S_i} satisfies

$$\tilde{V}_{S_i} \Omega_{n_i} = \Omega_{n_i} \tilde{V}_{S_i}^*. \quad (\text{B128})$$

Under the gauge transformation V , we have

$$\tilde{B}_b^{S_i} \rightarrow \tilde{V}_{n_i} \tilde{B}_b^{S_i} \tilde{V}_{n_i}^\dagger. \quad (\text{B129})$$

(a) $\eta_\sigma = \mathbb{I}$, $\chi_\sigma = 1$. In this case, we get $\tilde{B}_b^{S_i}$ is quaternion symmetric for integer S_i , while quaternion antisymmetric for half-integer S_i .

(b) $\eta_\sigma = \mathbb{I}$, $\chi_\sigma = -1$. In this case, we get $\tilde{B}_b^{S_i}$ is quaternion antisymmetric for integer S_i , while quaternion symmetric for half-integer S_i .

(c) $\eta_\sigma = \mathbb{J}$, $\chi_\sigma = 1$. In this case, we get $\tilde{B}_b^{S_i}$ is quaternion symmetric for integer S_i , while $i\tilde{B}_b^{S_i}$ is quaternion symmetric for half-integer S_i .

(d) $\eta_\sigma = \mathbb{J}$, $\chi_\sigma = -1$. In this case, we get $\tilde{B}_b^{S_i}$ is quaternion antisymmetric for integer S_i , while $i\tilde{B}_b^{S_i}$ is quaternion antisymmetric for half-integer S_i .

c. Constraint on site tensors

The Hilbert space of a site tensor \mathbb{V}_T is defined in Eq. (B97). In the presence of $\text{SU}(2)$ symmetry, \mathbb{V}_T can be decomposed as

$$\begin{aligned} \mathbb{V}_T &\cong \mathbb{U} \otimes \mathbb{V} \otimes \mathbb{V} \otimes \mathbb{V} \otimes \mathbb{V} \\ &\cong \bigoplus_{i_a, i_b, i_c, i_d} (\mathbb{D}_{S_{i_a} S_{i_b} S_{i_c} S_{i_d}} \otimes \mathbb{V}_{S_0} \otimes \mathbb{V}_{S_{i_a}} \otimes \mathbb{V}_{S_{i_b}} \otimes \mathbb{V}_{S_{i_c}} \otimes \mathbb{V}_{S_{i_d}}) \\ &\cong \bigoplus_{i_a, i_b, i_c, i_d, k} (\mathbb{D}_{S_{i_a} S_{i_b} S_{i_c} S_{i_d}} \otimes \mathbb{V}_{S_0 S_{i_a} S_{i_b} S_{i_c} S_{i_d}}^{S_k} \otimes \mathbb{V}_{S_k}), \end{aligned} \quad (\text{B130})$$

where

$$\mathbb{D}_{S_{i_a} S_{i_b} S_{i_c} S_{i_d}} \equiv \mathbb{D}_{S_{i_a}} \otimes \mathbb{D}_{S_{i_b}} \otimes \mathbb{D}_{S_{i_c}} \otimes \mathbb{D}_{S_{i_d}} \quad (\text{B131})$$

labels the extra degenerate space associated with spins $S_{i_a}, S_{i_b}, S_{i_c}, S_{i_d}$ on four virtual legs. The basis of $\mathbb{D}_{S_{i_a} S_{i_b} S_{i_c} S_{i_d}}$ is labeled as

$$|S_{i_a}, t_\alpha\rangle \otimes |S_{i_b}, t_\beta\rangle \otimes |S_{i_c}, t_\gamma\rangle \otimes |S_{i_d}, t_\delta\rangle. \quad (\text{B132})$$

$V_{S_0 S_{i_a} S_{i_b} S_{i_c} S_{i_d}}^{S_k}$ is the fusion space, which denotes different ways to fuse spin $S_0, S_{i_a}, S_{i_b}, S_{i_c}, S_{i_d}$ to spin S_k . The complicated fusion rules with six spins can be obtained by the fusion rules with only three spins as

$$V_{S_0 S_{i_a} S_{i_b} S_{i_c} S_{i_d}}^{S_k} \cong \bigoplus_{\alpha, \beta, \gamma} V_{S_0 S_{i_a}}^{\alpha} \otimes V_{S_{i_a} S_{i_b}}^{\beta} \otimes V_{S_{i_b} S_{i_c}}^{\gamma} \otimes V_{S_{i_c} S_{i_d}}^{S_k}. \quad (\text{B133})$$

Since site tensors are SU(2) singlet, we should focus on the Hilbert space with $S = 0$:

$$V_T^{S=0} \cong \bigoplus_{i_a, i_b, i_c, i_d} (\mathbb{D}_{S_{i_a} S_{i_b} S_{i_c} S_{i_d}} \otimes V_{S_0 S_{i_a} S_{i_b} S_{i_c} S_{i_d}}^{S=0} \otimes V_{S=0}). \quad (\text{B134})$$

The basis for space $V_{S_0 S_{i_a} S_{i_b} S_{i_c} S_{i_d}}^{S=0} \otimes V_{S=0}$ can be expressed as

$$\hat{K}_{S_0 S_{i_a} S_{i_b} S_{i_c} S_{i_d}}^l \equiv (K_{S_0 S_{i_a} S_{i_b} S_{i_c} S_{i_d}}^l)_{\alpha\beta\gamma\delta}^j |S_0, m_j\rangle \otimes |S_{i_a}, m_\alpha\rangle \otimes |S_{i_b}, m_\beta\rangle \otimes |S_{i_c}, m_\gamma\rangle \otimes |S_{i_d}, m_\delta\rangle, \quad (\text{B135})$$

where $\hat{K}_{S_0 S_{i_a} S_{i_b} S_{i_c} S_{i_d}}^l$ labels orthogonal singlet states for different l .

Then, in terms of the tensor representation, we decompose the site tensor T^S as

$$T^S = \bigoplus_{i_a, i_b, i_c, i_d, l} (\tilde{T}_{S_{i_a} S_{i_b} S_{i_c} S_{i_d}}^l \otimes K_{S_0 S_{i_a} S_{i_b} S_{i_c} S_{i_d}}^l), \quad (\text{B136})$$

where the state

$$\sum_{\alpha, \beta, \gamma, \delta} (\tilde{T}_{S_{i_a} S_{i_b} S_{i_c} S_{i_d}}^l)_{\alpha\beta\gamma\delta} |S_{i_a}, t_\alpha\rangle \otimes |S_{i_b}, t_\beta\rangle \otimes |S_{i_c}, t_\gamma\rangle \otimes |S_{i_d}, t_\delta\rangle \quad (\text{B137})$$

is an arbitrary state that lives in the extra degenerate space $\mathbb{D}_{S_{i_a} S_{i_b} S_{i_c} S_{i_d}}$.

Due to the representation theory of SU(2), $K_{S_0 S_{i_a} S_{i_b} S_{i_c} S_{i_d}}$ does not vanish only if there are even number of half-integer spins for S_0, \dots, S_{i_d} . Since S_0 is a half-integer spin, we conclude that there should always be odd number of half-integer spins living on virtual legs. For a site tensor, there are four virtual legs, so we get two different cases:

(1) Only one virtual leg is a half-integer spin, while the other three are integer spins.

(2) Three virtual legs are half-integer spins, while the remaining one is an integer spin.

We now consider the constraint from lattice symmetry. Remember that in the presence of translation and rotation, we can always choose a gauge such that all site tensors share the same form, as shown in Eqs. (B7) and (B28). Then, in the following, we only need to focus on a single site tensor.

We figure out lattice symmetries that map site tensor T^u to itself as follows:

$$\sigma \circ (T^u)_{\alpha\beta\gamma\delta}^i = (T^u)_{\delta\gamma\beta\alpha}^i, \quad T_1 T_2 C_6^3 \circ (T^u)_{\alpha\beta\gamma\delta}^i = C_6 \circ (T^u)_{\alpha\beta\gamma\delta}^i = (T^u)_{\beta\alpha\delta\gamma}^i. \quad (\text{B138})$$

Besides, combining reflection σ and rotation C_6 , we get

$$\sigma C_6 \circ (T^u)_{\alpha\beta\gamma\delta}^i = (T^u)_{\gamma\delta\alpha\beta}^i. \quad (\text{B139})$$

In the following, we will solve the constraint from the above symmetry operations. Further, we can prove that the whole

site tensor can be generated by lattice symmetries once we fix quantum states in the Hilbert space satisfying the two situations following:

(1) S_{i_a} is a half-integer spin, while the other three are integer spins.

(2) S_{i_a} is an integer spin, while the other three are half-integer spins.

To see this, let us first consider reflection symmetry σ . Under the action of σ , for the decomposed parts of the site tensor, we have

$$\sigma \circ (\tilde{T}_{S_{i_a} S_{i_b} S_{i_c} S_{i_d}}^l)_{\alpha\beta\gamma\delta} = (\tilde{T}_{S_{i_d} S_{i_c} S_{i_b} S_{i_a}}^l)_{\delta\gamma\beta\alpha}, \quad \sigma \circ (K_{S_0 S_{i_a} S_{i_b} S_{i_c} S_{i_d}}^l)_{\alpha\beta\gamma\delta}^j = (K_{S_0 S_{i_d} S_{i_c} S_{i_b} S_{i_a}}^l)_{\delta\gamma\beta\alpha}^j. \quad (\text{B140})$$

It is obvious that we can choose $K_{S_0 S_{i_a} S_{i_b} S_{i_c} S_{i_d}}$ to be either symmetric or antisymmetric under the permutation of $\{S_{i_a}, S_{i_b}, S_{i_c}, S_{i_d}\}$:

$$(K_{S_0 \mathbf{P}(S_{i_a} S_{i_b} S_{i_c} S_{i_d})})_{\mathbf{P}(\alpha\beta\gamma\delta)}^j = \pm (K_{S_0 S_{i_a} S_{i_b} S_{i_c} S_{i_d}})_{\alpha\beta\gamma\delta}^j, \quad (\text{B141})$$

where \mathbf{P} is any permutation. The \pm sign depends on the definition of K . Particularly, we have

$$\sigma \circ (K_{S_0 S_{i_a} S_{i_b} S_{i_c} S_{i_d}})_{\alpha\beta\gamma\delta}^j = \pm (K_{S_0 S_{i_d} S_{i_c} S_{i_b} S_{i_a}})_{\delta\gamma\beta\alpha}^j. \quad (\text{B142})$$

For the two cases we consider here, S_{i_a} is always different from spins of other three virtual legs. So, $K_{S_0 S_{i_a} S_{i_b} S_{i_c} S_{i_d}}$ and $K_{S_0 S_{i_d} S_{i_c} S_{i_b} S_{i_a}}$ are always independent tensors. Thus, we can absorb minus sign in the above equation by redefining $K_{S_0 S_{i_d} S_{i_c} S_{i_b} S_{i_a}}$. Then, we get

$$\sigma \circ T^l = \bigoplus_{i_a, i_b, i_c, i_d, l} (\sigma \circ \tilde{T}_{S_{i_a} S_{i_b} S_{i_c} S_{i_d}}^l \otimes K_{S_0 S_{i_a} S_{i_b} S_{i_c} S_{i_d}}^l). \quad (\text{B143})$$

Remember that the site tensor is symmetric under σ , so we have

$$T^u = \Theta_\sigma W_\sigma \sigma \circ T^u = \Theta_\sigma W_\sigma \bigoplus_{i_a, i_b, i_c, i_d, l} (\sigma \circ \tilde{T}_{S_{i_a} S_{i_b} S_{i_c} S_{i_d}}^l \otimes K_{S_0 S_{i_a} S_{i_b} S_{i_c} S_{i_d}}^l). \quad (\text{B144})$$

As shown in the last subsection, we always choose the basis such that $W_R(x, y, s) \in \{I, J\}$ for any lattice symmetry R . So, we can always define the action of W_σ trivially on $K_{S_0 S_{i_a} S_{i_b} S_{i_c} S_{i_d}}^l$. Namely, we can decompose $W_R(x, y, s, i)$ as

$$W_R(x, y, s, i) = \bigoplus_i (\tilde{W}_R^{S_i}(x, y, s, i) \otimes I_{2S_i+1}). \quad (\text{B145})$$

Then, from the above analysis, we conclude

$$\tilde{T}_{S_{i_a} S_{i_b} S_{i_c} S_{i_d}}^l = \Theta_\sigma \tilde{W}_\sigma \sigma \circ \tilde{T}_{S_{i_a} S_{i_b} S_{i_c} S_{i_d}}^l. \quad (\text{B146})$$

Writing the above equation explicitly, we get

$$[\tilde{T}_{S_{i_a} S_{i_b} S_{i_c} S_{i_d}}^l]_{\alpha\beta\gamma\delta} = \Theta_\sigma(u) [\tilde{w}_\sigma^{S_{i_a}}]_{\alpha\alpha'} [\tilde{w}_\sigma^{S_{i_b}}]_{\beta\beta'} [\tilde{w}_\sigma^{S_{i_c}}]_{\gamma\gamma'} \times [\tilde{w}_\sigma^{S_{i_d}}]_{\delta\delta'} [\tilde{T}_{S_{i_d} S_{i_c} S_{i_b} S_{i_a}}^l]_{\delta'\gamma'\beta'\alpha'}. \quad (\text{B147})$$

According to Eq. (B45), we have

$$\tilde{w}_\sigma^S(u, a) = I, \quad \tilde{w}_\sigma^S(u, b) = \chi_\sigma(\mu_{12} \mu_{C_6})^{2S}, \quad \tilde{w}_\sigma^S(u, c) = \chi_\sigma(\mu_{12} \mu_{C_6} \mu_\sigma)^{2S}, \quad \tilde{w}_\sigma^S(u, d) = (\mu_\sigma)^{2S}. \quad (\text{B148})$$

Then, we can simplify the constraint as

$$\begin{aligned} [\tilde{T}_{S_{ia} S_{ib} S_{ic} S_{id}}^l]_{\alpha\beta\gamma\delta} &= \Theta_\sigma(u) (\mu_\sigma)^{2S_{ic}+2S_{id}} (\mu_{12}\mu_{C_6})^{2S_{ib}+2S_{id}} \\ &\times [\tilde{T}_{S_{id} S_{ic} S_{ib} S_{ia}}^l]_{\delta\gamma\beta\alpha}. \end{aligned} \quad (\text{B149})$$

Since S_{ib} , S_{ic} , and S_{id} are all integer spins or all half-integer spins, the above equation reads as

$$[\tilde{T}_{S_{ia} S_{ib} S_{ic} S_{id}}^l]_{\alpha\beta\gamma\delta} = \Theta_\sigma(u) [\tilde{T}_{S_{id} S_{ic} S_{ib} S_{ia}}^l]_{\delta\gamma\beta\alpha}, \quad (\text{B150})$$

where $\Theta_\sigma(u) = (\mu_\sigma)^{\frac{1}{2}}$.

We consider the constraint by the rotation symmetry now. Similarly, $\tilde{T}_{S_{ib} S_{ic} S_{id} S_{ia}}^l$ and $\tilde{T}_{S_{ic} S_{id} S_{ib} S_{ia}}^l$ can be obtained from $\tilde{T}_{S_{ia} S_{ib} S_{ic} S_{id}}^l$ and $\tilde{T}_{S_{id} S_{ic} S_{ib} S_{ia}}^l$ by rotation symmetry:

$$\begin{aligned} \tilde{T}_{S_{ia} S_{ib} S_{ic} S_{id}}^l &= \Theta_{C_6} \tilde{W}_{C_6} C_6 \circ \tilde{T}_{S_{ib} S_{ic} S_{id} S_{ia}}^l, \\ \tilde{T}_{S_{id} S_{ic} S_{ib} S_{ia}}^l &= \Theta_{C_6} \tilde{W}_{C_6} C_6 \circ \tilde{T}_{S_{ia} S_{ib} S_{ic} S_{id}}^l. \end{aligned} \quad (\text{B151})$$

By inserting $w_{C_6}(u, i)$ defined in Eq. (B53), we get

$$\begin{aligned} [\tilde{T}_{S_{ia} S_{ib} S_{ic} S_{id}}^l]_{\alpha\beta\gamma\delta} &= \Theta_{C_6}(u) [\tilde{T}_{S_{ib} S_{ic} S_{id} S_{ia}}^l]_{\beta\alpha\delta\gamma}, \\ [\tilde{T}_{S_{ia} S_{ib} S_{ic} S_{id}}^l]_{\alpha\beta\gamma\delta} &= \mu_{12}\mu_{C_6} \Theta_{C_6}(u) \Theta_\sigma(u) [\tilde{T}_{S_{ic} S_{id} S_{ib} S_{ia}}^l]_{\gamma\delta\alpha\beta}, \end{aligned} \quad (\text{B152})$$

where $\Theta_{C_6}(u) = (\mu_{12}\mu_{C_6})^{\frac{1}{2}}$.

Thus, once we know tensors $\tilde{T}_{S_{ia} S_{ib} S_{ic} S_{id}}^l$ with S_{ia} to be a half-integer/integer spin and S_{ib}, S_{ic}, S_{id} to be integer/half-integer spins, by the above lattice symmetries, we are able to generate tensors $\tilde{T}_{S_{ia} S_{ib} S_{ic} S_{id}}^l$ which satisfy one virtual leg to be a half-integer/integer spin and other three virtual legs to be integer/half-integer spins.

At last, we add time-reversal symmetry. The constraint of time-reversal symmetry reads as $T^s = \Theta_T W_T T^s$. Since $K_{S_0 S_{ia} S_{ib} S_{ic} S_{id}}^l$ is a Kramer singlet state and real, we have

$$\begin{aligned} [K_{S_0 S_{ia} S_{ib} S_{ic} S_{id}}^l]_{\alpha\beta\gamma\delta}^j &= [e^{i\pi S_0^y}]_{jj'} [e^{i\pi S_{ia}^y}]_{\alpha\alpha'} [e^{i\pi S_{ib}^y}]_{\beta\beta'} [e^{i\pi S_{ic}^y}]_{\gamma\gamma'} \\ &\times [e^{i\pi S_{id}^y}]_{\delta\delta'} [K_{S_0 S_{ia} S_{ib} S_{ic} S_{id}}^l]_{\alpha'\beta'\gamma'\delta'}^{j'}. \end{aligned} \quad (\text{B153})$$

Then, according to Eq. (B89), the constraint on $\tilde{T}_{S_{ia} S_{ib} S_{ic} S_{id}}^l$ reads as

$$\begin{aligned} [\tilde{T}_{S_{ia} S_{ib} S_{ic} S_{id}}^l]_{\alpha\beta\gamma\delta} &= [\tilde{w}_T^{S_{ia}}(u, a)]_{\alpha\alpha'} [\tilde{w}_T^{S_{ib}}(u, b)]_{\beta\beta'} [\tilde{w}_T^{S_{ic}}(u, c)]_{\gamma\gamma'} \\ &\times [\tilde{w}_T^{S_{id}}(u, d)]_{\delta\delta'} [\tilde{T}_{S_{ia} S_{ib} S_{ic} S_{id}}^{l*}]_{\alpha'\beta'\gamma'\delta'}, \end{aligned} \quad (\text{B154})$$

where according to Eq. (B67), we obtain $\tilde{w}_T^S(u, i)$ as

$$\begin{aligned} \tilde{w}_T^S(u, a) &= \tilde{w}_T^S, \quad \tilde{w}_T^S(u, b) = (\mu_{12}\mu_{C_6})^{2S} \tilde{w}_T^S, \\ \tilde{w}_T^S(u, c) &= (\mu_{12}\mu_{C_6}\mu_\sigma)^{2S} \tilde{w}_T^S, \quad \tilde{w}_T^S(u, d) = (\mu_\sigma)^{2S} \tilde{w}_T^S. \end{aligned} \quad (\text{B155})$$

\tilde{w}_T^S depends on χ_T . Remember that we will focus on the case where S_{ib} , S_{ic} , and S_{id} must be all integer or half-integer spins.

Then, by inserting Eq. (B155) back to Eq. (B154), we get

$$\begin{aligned} [\tilde{T}_{S_{ia} S_{ib} S_{ic} S_{id}}^l]_{\alpha\beta\gamma\delta} &= [\tilde{w}_T^{S_{ia}}]_{\alpha\alpha'} [\tilde{w}_T^{S_{ib}}]_{\beta\beta'} [\tilde{w}_T^{S_{ic}}]_{\gamma\gamma'} \\ &\times [\tilde{w}_T^{S_{id}}]_{\delta\delta'} [\tilde{T}_{S_{ia} S_{ib} S_{ic} S_{id}}^{l*}]_{\alpha'\beta'\gamma'\delta'}. \end{aligned} \quad (\text{B156})$$

When $\chi_T = 1$, we have $\tilde{w}_T^{S_i} = \mathbb{I}_{n_i}$, then Eq. (B156) is simplified as

$$\tilde{T}_{S_{ia} S_{ib} S_{ic} S_{id}}^l = \tilde{T}_{S_{ia} S_{ib} S_{ic} S_{id}}^{l*}. \quad (\text{B157})$$

So, $\tilde{T}_{S_{ia} S_{ib} S_{ic} S_{id}}^l$ is real tensor.

When $\chi_T = -1$, we have $\tilde{w}_T^{S_i} = \Omega_{n_i}$, then Eq. (B156) becomes

$$\begin{aligned} [\tilde{T}_{S_{ia} S_{ib} S_{ic} S_{id}}^l]_{\alpha\beta\gamma\delta} &= [\Omega_{n_{ia}}]_{\alpha\alpha'} [\Omega_{n_{ib}}]_{\beta\beta'} [\Omega_{n_{ic}}]_{\gamma\gamma'} \\ &\times [\Omega_{n_{id}}]_{\delta\delta'} [\tilde{T}_{S_{ia} S_{ib} S_{ic} S_{id}}^{l*}]_{\alpha'\beta'\gamma'\delta'}. \end{aligned} \quad (\text{B158})$$

d. Examples

Now, let us focus on a special case where the physical spin $S_0 = \frac{1}{2}$ and there are only spin-0 and spin- $\frac{1}{2}$ living on virtual legs. Then, to obtain site tensors, according to the above analysis, we restrict ourselves to two subspaces of $\mathbb{V}_T^{S=0}$:

(1) $S_{ia} = \frac{1}{2}$ and $S_{ib} = S_{ic} = S_{id} = 0$. Then, the corresponding Hilbert space \mathbb{H}_0 is

$$\mathbb{H}_0 = \mathbb{D}_{\frac{1}{2}} \otimes (\mathbb{D}_0)^3 \otimes \mathbb{V}_{\frac{1}{2} \frac{1}{2} \frac{1}{2} \frac{1}{2}}^0 \otimes \mathbb{V}_0, \quad (\text{B159})$$

where fusion space $\mathbb{V}_{\frac{1}{2} \frac{1}{2} \frac{1}{2} \frac{1}{2}}^0 \cong \mathbb{V}_{\frac{1}{2} \frac{1}{2}}^0$ with dimension one. The singlet state $K_0 \doteq K_{\frac{1}{2} \frac{1}{2} \frac{1}{2} \frac{1}{2}}^0$ is

$$(K_0)_{\alpha\beta\gamma\delta}^j = (i\sigma^y)_{j\alpha} \quad (\text{B160})$$

since $\beta = \gamma = \delta \equiv 1$ in this case. One can easily verify that K_0 is invariant under time-reversal operator:

$$(K_0^*)_{\alpha\beta\gamma\delta}^j = (i\sigma^y)_{jj'} (i\sigma^y)_{\alpha\alpha'} (K_0^*)_{\alpha'\beta'\gamma'\delta'}^{j'}. \quad (\text{B161})$$

Then, quantum state in \mathbb{H}_0 can be expressed by the tensor form as

$$\tilde{T}_0 \otimes K_0, \quad (\text{B162})$$

where \tilde{T}_0 denotes an arbitrary quantum state in $\mathbb{D}_{\frac{1}{2}} \otimes (\mathbb{D}_0)^3$.

(2) $S_{ia} = 0$ and $S_{ib} = S_{ic} = S_{id} = \frac{1}{2}$. The corresponding Hilbert space \mathbb{H}_1 is

$$\mathbb{H}_1 = \mathbb{D}_0 \otimes (\mathbb{D}_{\frac{1}{2}})^3 \otimes \mathbb{V}_{0 \frac{1}{2} \frac{1}{2} \frac{1}{2} \frac{1}{2}}^0 \otimes \mathbb{V}_0. \quad (\text{B163})$$

Using representation theory of SU(2), we get

$$\mathbb{V}_{0 \frac{1}{2} \frac{1}{2} \frac{1}{2} \frac{1}{2}}^0 \cong (\mathbb{V}_{\frac{1}{2} \frac{1}{2}}^0 \otimes \mathbb{V}_{\frac{1}{2} \frac{1}{2}}^0 \otimes \mathbb{V}_{\frac{1}{2} \frac{1}{2}}^0) \oplus (\mathbb{V}_{\frac{1}{2} \frac{1}{2}}^0 \otimes \mathbb{V}_{\frac{1}{2} \frac{1}{2}}^0 \otimes \mathbb{V}_{\frac{1}{2} \frac{1}{2}}^1). \quad (\text{B164})$$

So, $\mathbb{V}_{0 \frac{1}{2} \frac{1}{2} \frac{1}{2} \frac{1}{2}}^0$ has dimension 2. We choose the two bases in $\mathbb{V}_{0 \frac{1}{2} \frac{1}{2} \frac{1}{2} \frac{1}{2}}^0 \otimes \mathbb{V}_0$ as

$$\begin{aligned} (K_1)_{\alpha\beta\gamma\delta}^j &= (i\sigma^y)_{j\beta} (i\sigma^y)_{\gamma\delta}, \\ (K_2)_{\alpha\beta\gamma\delta}^j &= \sum_{\mu\nu} (i\sigma^y)_{j\nu} C_{\frac{1}{2} m_\beta \frac{1}{2} m_\mu}^{\frac{1}{2} m_\nu} C_{\frac{1}{2} m_\gamma \frac{1}{2} m_\delta}^{\frac{1}{2} m_\nu}, \end{aligned} \quad (\text{B165})$$

where $\alpha \equiv 1$ in this case. Here, $C_{S_1 m_1 S_2 m_2}^{J m_J} \doteq \langle S_1 m_1 S_2 m_2 | J m_J \rangle$ is the CG coefficient and $m_i = -S - 1 + i$ is the S_z quantum number. Similar as in the previous case, K_1 and K_2 are also chosen to be invariant under time-reversal operator:

$$(K_{1(2)})_{\alpha\beta\gamma\delta}^j = (i\sigma^y)_{jj'}(i\sigma^y)_{\beta\beta'}(i\sigma^y)_{\gamma\gamma'}(i\sigma^y)_{\delta\delta'}(K_{1(2)}^*)_{\alpha\beta'\gamma'\delta'}^{j'}. \quad (\text{B166})$$

Then, the quantum state in \mathbb{H}_1 can be expressed by the tensor form as

$$\tilde{T}_1 \otimes K_1 \oplus \tilde{T}_2 \otimes K_2, \quad (\text{B167})$$

where \tilde{T}_1, \tilde{T}_2 are tensor representation of arbitrary states in $\mathbb{D}_0 \otimes (\mathbb{D}_{\frac{1}{2}})^3$.

We can explicitly write K_i as a quantum state by introducing basis $|0\rangle$ for spin-0 and $|\uparrow\rangle, |\downarrow\rangle$ for spin- $\frac{1}{2}$:

$$\begin{aligned} \hat{K}_0 &= |\uparrow\rangle \otimes |\downarrow 000\rangle - |\downarrow\rangle \otimes |\uparrow 000\rangle, \\ \hat{K}_1 &= |\uparrow\rangle \otimes (|0\downarrow\uparrow\downarrow\rangle - |0\downarrow\downarrow\uparrow\rangle) \\ &\quad - |\downarrow\rangle \otimes (|0\uparrow\uparrow\downarrow\rangle - |0\uparrow\downarrow\uparrow\rangle), \\ \hat{K}_2 &= |\uparrow\rangle \otimes (2|0\uparrow\downarrow\downarrow\rangle - |0\downarrow\uparrow\downarrow\rangle - |0\downarrow\downarrow\uparrow\rangle) \\ &\quad + |\downarrow\rangle \otimes (2|0\downarrow\uparrow\uparrow\rangle - |0\uparrow\uparrow\downarrow\rangle - |0\uparrow\downarrow\uparrow\rangle), \end{aligned} \quad (\text{B168})$$

where we define $\hat{K}_i = (K_i)_{\alpha\beta\gamma\delta}^j |m_j\rangle \otimes |m_\alpha m_\beta m_\gamma m_\delta\rangle$.

Now, let us consider case $D = 3$ virtual legs $\mathbb{V} \cong 0 \oplus \frac{1}{2}$. Then, there is no extra degeneracy of spins. So, according to constraints from bond tensors, only classes with $\eta_\sigma = J$, $\chi_\sigma = 1$, and $\chi_T = 1$ can be realized. Other classes require even dimensional extra degenerate spaces since bond tensors of those classes are either antisymmetric or symplectic in the extra degenerate spaces. Thus, when $D = 3$, we are only left with η_{12} , η_{C_6} , and the number of classes can be realized is $2^2 = 4$.

Given a bond tensor B_{b_0} , we can fix it as a maximal entangled state with the following form:

$$B_{b_0} = \begin{pmatrix} \pm 1 & 0 & 0 \\ 0 & 0 & -i \\ 0 & i & 0 \end{pmatrix}. \quad (\text{B169})$$

Other bonds are all related to B_{b_0} by translation and rotation symmetry, and can be generated as

$$B_{R(b)} = R^{-1} W_R R \circ B_{b_0}, \quad (\text{B170})$$

where $R = T_1^{n_1} T_2^{n_2} C_6^{n_{C_6}}$ with $n_1, n_2, n_{C_6} \in \mathbb{Z}$.

For site tensors, they all share the same form. The spin-singlet state $\hat{K}_{S_0 S_{i_a} S_{i_b} S_{i_c} S_{i_d}}$ is fixed as Eq. (B168). So, we can express the site tensor using the quantum state representation as

$$\begin{aligned} \hat{T}^s &= \{\hat{K}_0 + \hat{K}_{12}(p_1, p_2)\} + \Theta_{C_6}^{-1}(u) \{a \leftrightarrow b, c \leftrightarrow d\} + \Theta_\sigma^{-1}(u) \\ &\quad \times \{a \leftrightarrow d, b \leftrightarrow c\} + \mu_{12} \mu_{C_6} [\Theta_{C_6}(u) \Theta_\sigma(u)]^{-1} \\ &\quad \times \{a \leftrightarrow c, b \leftrightarrow d\}, \end{aligned} \quad (\text{B171})$$

where we have

$$\begin{aligned} \hat{K}_{12} &= a_1 \hat{K}_1 + a_2 \hat{K}_2 \\ &= p_1 (|\uparrow\rangle \otimes |0\downarrow\uparrow\downarrow\rangle + |\downarrow\rangle \otimes |0\uparrow\downarrow\uparrow\rangle) \\ &\quad + p_2 \frac{a}{b} (|\uparrow\rangle \otimes |0\downarrow\downarrow\uparrow\rangle + |\downarrow\rangle \otimes |0\uparrow\uparrow\downarrow\rangle) \\ &\quad - (p_1 + p_2) (|\uparrow\rangle \otimes |0\uparrow\downarrow\downarrow\rangle + |\downarrow\rangle \otimes |0\downarrow\uparrow\uparrow\rangle), \end{aligned} \quad (\text{B172})$$

where we define $p_1 \equiv a_1 - a_2$ and $p_2 \equiv -a_1 - a_2$ as the two tunable parameters.

Now, let us consider virtual legs $\mathbb{V} \cong 0 \oplus 0 \oplus \frac{1}{2} \oplus \frac{1}{2}$ with $D = 6$. In this case, there are extra two-dimensional degeneracy spaces for both spin-0 and spin- $\frac{1}{2}$. We believe all 32 classes can be realized in this case. However, here we will focus on the four classes realized in the $D = 3$ case.

Fixing $\eta_\sigma = J$, $\chi_\sigma = 1$, and $\chi_T = 1$, the bond tensor B_{b_0} now reads as

$$B_{b_0} = \begin{pmatrix} \pm 1 & 0 \\ 0 & \pm 1 \end{pmatrix} \oplus \begin{pmatrix} \pm 1 & 0 \\ 0 & \pm 1 \end{pmatrix} \otimes \begin{pmatrix} 0 & i \\ -i & 0 \end{pmatrix}. \quad (\text{B173})$$

Other bonds can be generated by translation and reflection symmetry as discussed above.

For the site tensor, we have

$$\begin{aligned} \hat{T}^s &= \{\hat{T}_0 \otimes \hat{K}_0 + \hat{T}_1 \otimes \hat{K}_1 + \hat{T}_2 \otimes \hat{K}_2\} \\ &\quad + \Theta_{C_6}^{-1}(u) \{a \leftrightarrow b, c \leftrightarrow d\} + \Theta_\sigma^{-1}(u) \{a \leftrightarrow d, b \leftrightarrow c\} \\ &\quad + \mu_{12} \mu_{C_6} [\Theta_{C_6}(u) \Theta_\sigma(u)]^{-1} \{a \leftrightarrow c, b \leftrightarrow d\}, \end{aligned} \quad (\text{B174})$$

where \hat{T}_i labels a quantum state in extra degenerate space, which has dimension $2^4 = 16$. Further, the transformation rules of \hat{T} 's are given in Eqs. (B150) and (B152). So, there are three \hat{T} 's (\hat{T}_0, \hat{T}_1 , and \hat{T}_2) serving as tunable parameters. Then, the tunable parameters in the $D = 6$ case should be $16 \times 3 - 1 = 47$, where the additional -1 comes from the fact that the norm of the wave function has no physical consequence.

APPENDIX C: PROJECTIVE REPRESENTATION, GROUP EXTENSION, AND SECOND COHOMOLOGY

In this appendix, we will introduce mathematical tools for symmetry fractionalization, including projective representation, group extension, as well as the second cohomology. Readers may refer to Ref. [35] for more details.

Consider a group G with elements $g \in G$. We call $\Gamma(g)$ a projective representation of G with coefficient A , where A is an Abelian group, if

$$\Gamma(g_1) \Gamma(g_2) = \omega(g_1, g_2) \Gamma(g_1 g_2). \quad (\text{C1})$$

Here, ω is a map, which is defined as $\omega : G \times G \rightarrow A$. According to associativity of matrix product, we get

$$\begin{aligned} \Gamma(g_1) \Gamma(g_2) \Gamma(g_3) &= \omega(g_1, g_2) \omega(g_1 g_2, g_3) \Gamma(g_1 g_2 g_3) \\ &= \omega(g_1, g_2 g_3) {}^g \omega(g_2, g_3) \Gamma(g_1 g_2 g_3), \end{aligned} \quad (\text{C2})$$

where appearance of ${}^g \omega(g_2, g_3)$ comes from commutation of g_1 and $\omega(g_2, g_3)$, which indicates action of G on coefficient A may be nontrivial. Further, we require the action of $\forall g \in G$

on Abelian group A should be an automorphism of A . Then, the associativity constraint for ω is

$$\omega(g_1, g_2)\omega(g_1 g_2, g_3) = \omega(g_1, g_2 g_3) {}^g \omega(g_2, g_3). \quad (\text{C3})$$

Any function ω satisfying the associativity constraint is called a factor set.

If ω_a and ω_b are both factor sets, then $\omega_{ab} = \omega_a \omega_b$ is also a factor set, where $(\omega_a \omega_b)(g_1, g_2) \equiv \omega_a(g_1, g_2)\omega_b(g_1, g_2)$. The product of factor sets is associated with tensor product of projective representations: if ω_a, ω_b are factor sets of Γ_a, Γ_b , respectively, then ω_{ab} is factor set of the tensor product representation $\Gamma_a \otimes \Gamma_b$.

Now, let us define the equivalent class for factor sets. Suppose we allow a redefinition of the Γ 's by

$$\Gamma'(g) = \lambda(g)\Gamma(g), \quad (\text{C4})$$

where λ is defined as $\lambda : G \rightarrow A$. This induces transformation of the factor set

$$\omega'(g_1, g_2) = \lambda(g_1) {}^g \lambda(g_2) \lambda(g_1 g_2)^{-1} \omega(g_1, g_2), \quad (\text{C5})$$

where ω' is also a factor set. Two factor sets ω and ω' are said to be equivalent if they are related by the above equation for some λ , and we write as $\omega \sim \omega'$. We group all equivalent ω as a class, and define the equivalence class by $c(\omega)$. Then, one can easily verify that the equivalent classes form an Abelian group with product defined by

$$c(\omega_1)c(\omega_2) = c(\omega_1 \omega_2). \quad (\text{C6})$$

The Abelian group of factor set equivalence classes is isomorphic to the cohomology group $H^2(G, A)$. We can view it as definition of the second group cohomology. Any factor set ω is named as cocycle, which is classified by $Z^2(G, A)$, while λ is called coboundary, classified by $B^2(G, A)$. Then, we have

$$H^2(G, A) = Z^2(G, A)/B^2(G, A). \quad (\text{C7})$$

We point out here the definition of $H^2(G, A)$ depends on the action of G on A . In mathematics language, A is a G module, which is equivalent to say that $\forall g \in G$ may have nontrivial action on A with the action to be automorphism of A , rather than just an Abelian group. For example, a trivial module just means A is invariant under G :

$${}^g a = a, \quad \forall g \in G, a \in A. \quad (\text{C8})$$

One should always fix a G module A , and then classify projective representation with coefficient A . However, in our case, $\text{IGG} = Z_2$, the automorphism of Z_2 only contains trivial one.

We now put projective representation aside and turn to discussion about group extension. Assume group E has a normal subgroup A . Then, we can define G as quotient group

$$G = E/A \quad (\text{C9})$$

with associated homomorphism $\pi : E \rightarrow G$. Then, it is natural to define G module A : given $g \in G$, the action of g on A is characterized by

$${}^g a = \tilde{g} a \tilde{g}^{-1}, \quad (\text{C10})$$

where we choose \tilde{g} so that $\pi(\tilde{g}) = g$. E is called an extension of a group G by G module A . In particular, A is central in E

if and only if the G action is trivial. In this case, the extension is called a central extension.

Now, let us discuss about the relation between group extension and projective representation. Roughly speaking, the equivalent class of projective representation has one-to-one correspondence with group extension of G by G module A . Namely, group extension E is also classified by 2-cohomology $H^2(G, A)$. Projective representation Γ can be viewed as a map $\Gamma : G \rightarrow E$ such that $\pi \circ \Gamma = \text{id}_G$. Then, factor set ω is naturally induced by Γ , and automatically satisfies associativity constraint (C5). Notice that the choice of Γ is far from unique, and we can always redefine Γ as shown in Eq. (C4).

In the following, we will develop a general method to solve the inequivalent projective representations for discrete group G with G module A , and the corresponding extended group is E . Particularly, we will focus on G as the symmetry group of kagome PEPS defined in Appendix A, while $A = \text{IGG} = Z_2$ is a trivial G module. Spin-rotation symmetry will also be discussed.

Let us first set up the general framework. G is defined by generators $\{T_1, T_2, C_6, \sigma, \mathcal{T}\}$ as well as the relation between these generators, as shown in Eq. (A3). In other words, $\forall g \in G$, there is one integer set $\{n_1, n_2, n_{C_6}, n_\sigma\}$ such that

$$g = T_1^{n_1} T_2^{n_2} C_6^{n_{C_6}} \sigma^{n_\sigma}. \quad (\text{C11})$$

As discussed before, projective representation can be constructed from E by map Γ . Let us first choose the gauge such that $\Gamma(1) = 1$. Then, this implies $\omega(1, 1) = \omega(g, 1) = \omega(1, g) = 1, \forall g \in G$. Let us consider a particular relation between generators as

$$T_2^{-1} T_1^{-1} T_2 T_1 = e. \quad (\text{C12})$$

Lifting this relation to E by Γ , we have

$$\Gamma(T_2)^{-1} \Gamma(T_1)^{-1} \Gamma(T_2) \Gamma(T_1) = \eta_{12}, \quad (\text{C13})$$

where $\eta_{12} \in Z_2$. Similarly, for all relations, we obtain a set of η 's.

These η 's are closely related to classification of projective representation. However, there are some issues that arise. First, the η 's are not, in general, in one-to-one correspondence with cohomology classes. There may be some redundancy in this description. Second, some choices of η 's may be inconsistent and not give a legitimate factor set. To see this, let us solve the classification of projective representations for the kagome lattice symmetry group completely. Conditions for group relations are as follows:

$$\begin{aligned} \Gamma(T_2)^{-1} \Gamma(T_1)^{-1} \Gamma(T_2) \Gamma(T_1) &= \eta_{12}, \\ \Gamma(\sigma)^{-1} \Gamma(T_1)^{-1} \Gamma(\sigma) \Gamma(T_2) &= \eta_{\sigma T_2}, \\ \Gamma(\sigma)^{-1} \Gamma(T_2)^{-1} \Gamma(\sigma) \Gamma(T_1) &= \eta_{\sigma T_1}, \\ \Gamma(C_6)^{-1} \Gamma(T_2)^{-1} \Gamma(C_6) \Gamma(T_1) &= \eta_{C_6 T_1}, \\ \Gamma(C_6)^{-1} \Gamma(T_2)^{-1} \Gamma(T_1) \Gamma(C_6) \Gamma(T_2) &= \eta_{C_6 T_2}, \\ \Gamma(\sigma)^{-1} \Gamma(C_6) \Gamma(\sigma) \Gamma(C_6) &= \eta_{\sigma C_6}, \\ \Gamma(C_6)^6 &= \eta_{C_6}, \\ \Gamma(\sigma)^2 &= \eta_\sigma, \\ \Gamma(\mathcal{T})^2 &= \eta_\mathcal{T}, \\ \Gamma(g)^{-1} \Gamma(\mathcal{T})^{-1} \Gamma(g) \Gamma(\mathcal{T}) &= \eta_{g\mathcal{T}}, \forall g = T_{1,2}, \sigma, C_6 \end{aligned} \quad (\text{C14})$$

where we get 13 η 's. One may expect the number of cohomology classes should be 2^{13} , however, as we will see later, there is a lot of redundancy.

Now, let us try to eliminate those redundant parameters by choosing gauge of $\Gamma(g)$. By doing gauge transformation $\Gamma(T_1) \rightarrow \eta_{C_6 T_2} \Gamma(T_1)$ and $T_2 \rightarrow \eta_{C_6 T_2} \eta_{\sigma T_1} T_2$, we are able to set $\eta_{C_6 T_2} = \eta_{\sigma T_1} = I$. Notice, other η 's may also change, however, we can always absorb the change by redefining other η 's.

Then, we have

$$\Gamma(T_2) = \Gamma(\sigma) \Gamma(T_1) \Gamma(\sigma)^{-1}. \quad (C15)$$

By applying the above equation, we get

$$\begin{aligned} \eta_{\sigma T_2} &= \Gamma(\sigma)^{-1} \Gamma(T_1)^{-1} \Gamma(\sigma) \Gamma(T_2) \\ &= \Gamma(\sigma)^{-1} \Gamma(T_1)^{-1} \Gamma(\sigma) \Gamma(\sigma) \Gamma(T_1) \Gamma(\sigma)^{-1} = I \end{aligned} \quad (C16)$$

as well as

$$\begin{aligned} \eta_{\sigma T} &= \Gamma(T_2)^{-1} \Gamma(T)^{-1} \Gamma(T_2) \Gamma(T) \\ &= \Gamma(\sigma) \Gamma(T_1)^{-1} \Gamma(\sigma)^{-1} \Gamma(T)^{-1} \Gamma(\sigma) \Gamma(T_1) \Gamma(\sigma)^{-1} \Gamma(T) \\ &= \eta_{\sigma T} \Gamma(\sigma) \Gamma(T_1) \Gamma(T)^{-1} \Gamma(T_1) \Gamma(\sigma)^{-1} \Gamma(T) \\ &= (\eta_{\sigma T})^2 \Gamma(T) \Gamma(T_1)^{-1} \Gamma(T)^{-1} \Gamma(T_1) = \eta_{T_1 T}. \end{aligned} \quad (C17)$$

After the above calculation, we are left with nine free tunable Z_2 parameters

$$\{\eta_{12}, \eta_{C_6 T_1}, \eta_{\sigma C_6}, \eta_{\sigma}, \eta_{C_6}, \eta_{\sigma T}, \eta_{T_1 T}, \eta_{\sigma T}, \eta_{C_6 T}\}, \quad (C18)$$

so, we expect $H^2(G, Z_2) = 2^9$.

Now, let us add spin-rotation symmetry $R_s(\theta \vec{n})$. We have

$$\begin{aligned} \Gamma[R_s(2\pi)] &= \eta_{\theta=2\pi}, \\ \Gamma[R_s(\theta \vec{n})] \Gamma(g) &= \eta_{g, \theta \vec{n}} \Gamma(g) \Gamma[R_s(\theta \vec{n})], \end{aligned} \quad (C19)$$

where $g \in T_1, T_2, C_6, \sigma, T$. As argued in Ref. [35], one can always set $\eta_{g, \theta \vec{n}} = I$. Thus, by including spin-rotation symmetry, we get an extra parameter $\eta_{\theta=2\pi}$. So, the number of cohomology classes becomes 2^{10} .

APPENDIX D: DISTINGUISHING DIFFERENT CLASSES BY LATTICE QUANTUM NUMBERS

It has been shown that for a system defined on a torus, lattice quantum numbers can be served as useful tools to distinguish different phases [23, 41, 42, 98]. Here, we will show lattice quantum numbers are also very useful to distinguish different classes.

First, let us set the framework to extract quantum numbers of symmetric PEPS wave function $|\Psi\rangle$ defined on a torus. Similar to the PEPS on a infinite plane, tensors of the torus PEPS wave function $|\Psi\rangle$ satisfy

$$\begin{aligned} T^{(x,y,s)} &= \Theta_R W_R R \circ T^{(x,y,s)}, \\ B_{(x,y,b)} &= W_R R \circ B_{(x,y,b)}, \end{aligned} \quad (D1)$$

where R is the global symmetry operator, while W_R acts on virtual legs as a gauge transformation. Then, the global quantum number of R is simply a product of all Θ_R . Namely, we get

$$R|\Psi\rangle = \prod_{x,y,s} \Theta_R(x,y,s) |\Psi\rangle. \quad (D2)$$

Let us focus on two particular classes:

- (1) Class I is labeled by $\eta_{12} = \eta_{C_6} = I$, $\eta_{\sigma} = J$, and $\chi_{\sigma} = \chi_T = 1$. $Q_1 = Q_2$ spin-liquid phase [24] belongs to this class.
- (2) Class II is labeled by $\eta_{12} = I$, $\eta_{C_6} = \eta_{\sigma} = J$, and $\chi_{\sigma} = \chi_T = 1$. $Q_1 = -Q_2$ spin-liquid phase [24] belongs to this class.

To distinguish quantum numbers of these two classes, let us consider systems on a torus with $(4n+2)$ unit cells with even number of unit cells in T_1 direction and odd number of unit cells in T_2 direction. Notice that wave functions defined on this system explicitly break C_6 rotation symmetry. However, it still preserves inversion symmetry $R_{\pi} = C_6^3$. In the following, we will show that the ground-state manifold of these two classes defined on systems with $(4n+2)$ unit cells forms distinct representations of symmetry group generated by translation T_1, T_2 and inversion R_{π} .

Let us first list symmetry transformation rules for infinite PEPS. For translation, we can choose a proper gauge such that $W_{T_1}(x, y, s, i) = W_{T_2}(x, y, s, i) = I$ as well as $\Theta_{T_1}(x, y, s) = \Theta_{T_2}(x, y, s) = 1$ for both two classes. The symmetry transformation rule of reflection R_{π} can be generated by C_6 rotation as

$$\begin{aligned} W_{R_{\pi}}(x, y, s, i) &= W_{C_6}(x, y, s, i) W_{C_6}[C_6^{-1}(x, y, s, i)] \\ &\quad \times W_{C_6}[C_6^{-2}(x, y, s, i)], \\ \Theta_{R_{\pi}}(x, y, s) &= \Theta_{C_6}(x, y, s) \Theta_{C_6}[C_6^{-1}(x, y, s)] \\ &\quad \Theta_{C_6}[C_6^{-2}(x, y, s)]. \end{aligned} \quad (D3)$$

Thus, for infinite PEPS in Class I, we have

$$\begin{aligned} W_{R_{\pi}}(x, y, s, i) &= I, \\ \Theta_{R_{\pi}}(x, y, s) &= 1. \end{aligned} \quad (D4)$$

For Class II, we have

$$\begin{aligned} W_{R_{\pi}}(x, y, s, a/c) &= I, \\ W_{R_{\pi}}(x, y, s, b/d) &= J, \\ \Theta_{R_{\pi}}(x, y, s) &= i. \end{aligned} \quad (D5)$$

Now, let us turn to PEPS on a torus with $(4n+2)$ unit cells. For these two classes, one can construct a symmetric wave function $|\Psi_{0,0}\rangle$ with the symmetry transformation rules defined the same as infinite PEPS since the transformation rules of T_1, T_2 , and R_{π} on virtual legs of both classes are compatible with the system size. Symmetry quantum numbers of these states can be calculated using Eq. (D2), where the result is listed in the first columns in Table I.

As discussed in Sec. V, other bases of ground-state manifold are obtained by inserting noncontractible flux loops, labeled by $|\Psi_{\pi,0}\rangle$, $|\Psi_{0,\pi}\rangle$, and $|\Psi_{\pi,\pi}\rangle$. W_R and Θ_R change their values after the loop insertion, but it is easy to extract the quantum numbers of these states. For example, let us consider T_1 quantum number of $|\Psi_{\pi,0}\rangle$. T_1 will move the noncontractible g loop with one lattice spacing, leading to a new wave function $|\Psi'_{\pi,0}\rangle$. One can easily figure out that the PEPS wave function $|\Psi'_{\pi,0}\rangle$ is related to $|\Psi_{0,\pi}\rangle$ by a Z_2 gauge transformation on the column sandwiched by g loops of $|\Psi_{0,\pi}\rangle$ and $|\Psi'_{\pi,0}\rangle$, plus the T_1 symmetry transformation rule of $|\Psi_{0,0}\rangle$. Since there are odd number of sites per column, and site tensors are Z_2 odd, the single column Z_2 gauge transformation contributes an extra -1 to T_1 quantum number. Following similar strategy, one

TABLE I. Translation and inversion quantum numbers for topological degenerate ground states on $(4n + 2)$ unit-cell lattice (even by odd) samples.

(a) Quantum number for Class I				
Sym.	$ \Psi_{0,0}\rangle$	$ \Psi_{\pi,0}\rangle$	$ \Psi_{0,\pi}\rangle$	$ \Psi_{\pi,\pi}\rangle$
T_1	1	-1	1	-1
T_2	1	1	1	1
R_π	1	-1	1	-1

(b) Quantum number for Class II				
Sym.	$ \Psi_{0,0}\rangle$	$ \Psi_{\pi,0}\rangle$	$ \Psi_{0,\pi}\rangle$	$ \Psi_{\pi,\pi}\rangle$
T_1	1	-1	1	-1
T_2	1	1	1	1
R_π	-1	1	-1	1

can obtain the representation of symmetry group on the whole ground-state manifold for both classes. We list the result in Table I.

As seen in Table I, ground-state manifolds of the two classes have distinct representations. So, these two classes can be distinguished by lattice quantum numbers.

APPENDIX E: VALENCE BOND SOLID PHASE

As we mentioned before, a single class includes many different phases, which can only be distinguished by finite-size scaling. One may ask, is it possible that some particular phase can be described by different classes? We think that the answer is yes, and we will give an example in the following.

Let us focus on Class I and Class II discussed in Appendix D. As we argued before, the ground-state spaces of these two corresponding QSL have different lattice quantum numbers on systems with $(4n + 2)$ unit cells.

Now, let us consider the valence bond solid (VBS) phases. The VBS pattern can be obtained by Landau-Ginzburg theory of visons. The effective Lagrangian of visons is constrained by visons' transformation rules under symmetries, which are calculated in Sec. V. It turns out that the transformation rules only depend on spinon distributions, which are the same for all classes. Thus, we expect both Class I and Class II give the same VBS order pattern after vison condensation. This seems to contradict the quantum number discrepancy mentioned before.

The first observation is that for those samples where two classes have different lattice quantum numbers, it is impossible to write a compatible VBS order with the lattice size. In other words, there are always domain-wall configurations on those samples.

To see this, let us consider a particular 12-site VBS order pattern shown in Fig. 15 which is compatible with vison symmetry transformation rules [44]. As shown in Appendix D, Class I and Class II have different lattice quantum numbers on a torus with $(4n + 2)$ unit cells with even number of unit cells in the T_1 direction and odd in the T_2 direction. It is straightforward to see that on those samples, one can never avoid domain walls. In the following, we will show the different lattice quantum numbers are actually caused by different quantum fluctuations along the domain wall.

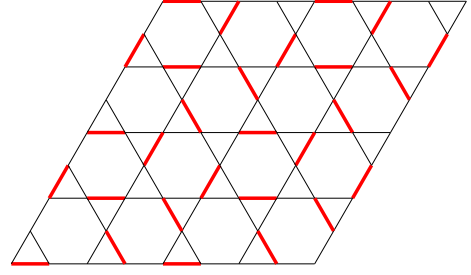


FIG. 15. (Color online) Visualization of the 12-site valence bond solid state as coverings of spin singlets (red thick bonds) on the kagome lattice.

Let us focus on the simplest case where the sample is a chain along the T_1 direction with even number of unit cells, but with only one unit cell along the T_2 direction, as shown in Fig. 16. Notice that the periodic boundary condition is imposed. Then, every site is connected with four bonds. Arrows on Figs. 16(a) and 16(b) denote the direction of singlet bonds of Class I and Class II, respectively. The direction of single bonds (red ones) on Figs. 16(c)–16(f) follows the convention in Fig. 16. We label these four domain-wall states as $|\phi_1\rangle$, $|\phi_2\rangle$, $|\phi_3\rangle$, and $|\phi_4\rangle$, respectively. In the following, we will show how these four simple VBS configurations give states with different quantum numbers.

On the Hilbert space spanned by these four bases, the representation of T_1 , T_2 , and R_π reads as

$$T_1 = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 \end{pmatrix}, \quad T_2 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix},$$

$$R_\pi = \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix}. \quad (E1)$$

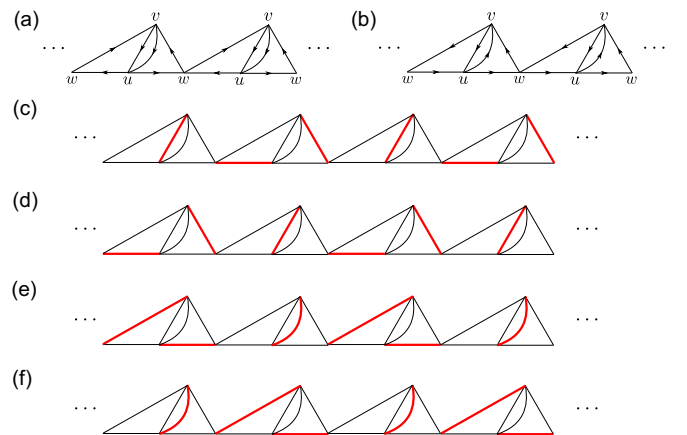


FIG. 16. (Color online) (a), (b) 1D chain in the T_1 direction. The periodic boundary condition is imposed, so every site shares four bonds. If two sites connected by a bond form a spin singlet, then we require the direction of the singlet is along the arrow on the bond. Arrows on (a) are consistent with Class I, while arrows on (b) are consistent with Class II. (c)–(f) Four possible domain-wall configurations connected by symmetry T_2 and R_π . The direction of spin singlets (red thick bonds) follows arrows in (a).

Then, eigenstates and eigenvalues for these three matrices are as following:

Eigenstates	T_1	T_2	R_π
$ \phi_1\rangle + \phi_2\rangle + \phi_3\rangle + \phi_4\rangle$	1	1	1
$ \phi_1\rangle + \phi_2\rangle - \phi_3\rangle - \phi_4\rangle$	1	1	-1
$ \phi_1\rangle - \phi_2\rangle + \phi_3\rangle - \phi_4\rangle$	-1	1	1
$ \phi_1\rangle - \phi_2\rangle - \phi_3\rangle + \phi_4\rangle$	-1	1	-1

So, different superpositions of VBS configurations give different quantum numbers. The above picture is similar to spin-liquid phases (RVB states). Different spin-liquid phases are distinguished by relative phases of different configurations of bond coverings. These relative phase factors may result in different quantum numbers on some finite-size sample. However, unlike spin-liquid phases, fluctuation along the VBS domain wall is essentially 1D physics. This remains true after considering samples with more unit cells along the T_2 direction. In one dimension, in the thermodynamic limit, the system will be pinned to a particular VBS configuration, and the information of phase factors is lost. So, we believe different ways of fluctuations along the VBS domain wall will not give new phases.

Now, let us check the correctness of the fluctuation-along-domain-wall picture by studying the possible superposition of these four states in Classes I and II, respectively. By comparing directions of singlet bonds, We conclude that for Class I, the possible superposition of these four states is $(|\phi_1\rangle + |\phi_2\rangle + |\phi_3\rangle + |\phi_4\rangle)$. Further, we observe $|\phi_1\rangle - |\phi_2\rangle - |\phi_3\rangle - |\phi_4\rangle$ is also consistent with Class I with noncontractible flux loops in the T_2 direction. While for Class II, there are two cases. For chains with $(4n + 2)$ unit cells, the possible superposition of these four states is $(-|\phi_1\rangle - |\phi_2\rangle + |\phi_3\rangle + |\phi_4\rangle)$ as well as $|\phi_1\rangle - |\phi_2\rangle + |\phi_3\rangle - |\phi_4\rangle$ (with noncontractible flux loop in the T_2 direction). For chains with $4n$ unit cells, we get the same result as Class I. Thus, for systems with $(4n + 2)$ sites, the two classes always have different quantum numbers. The above observation is consistent with the quantum numbers of Classes I and II obtained in the previous appendix.

APPENDIX F: AN EXAMPLE ON THE SQUARE LATTICE

As a pedagogical example, here we present the classification of symmetric PEPS with $\text{IGG} = Z_2$ for systems on the square lattice with a half-integer spin per site, in the presence of lattice translation, lattice C_4 rotation, and spin $\text{SU}(2)$ rotation symmetries.

The lattice symmetry group is generated by T_1, T_2, C_4 , which transform the virtual leg labeled by (x, y, i) as

$$\begin{aligned} T_1(x, y, i) &= (x + 1, y, i), \\ T_2(x, y, i) &= (x, y + 1, i), \\ C_4(x, y, i) &= [-y, x, C_4(i)], \end{aligned} \quad (\text{F1})$$

where $i = a, b, c, d$ labels the four virtual legs on a site tensor at (x, y) in a counterclockwise fashion, as shown in Fig. 17. The counterclockwise C_4 rotates the legs as

$$C_4(a) = b, \quad C_4(b) = c, \quad C_4(c) = d, \quad C_4(d) = a. \quad (\text{F2})$$

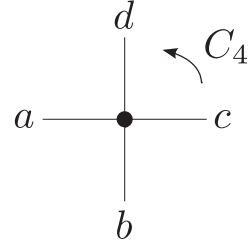


FIG. 17. A site on the square lattice with four virtual legs labeled as a, b, c, d .

These generators satisfy the following identities which define the space group:

$$\begin{aligned} [1]: \quad & T_1 T_2 T_1^{-1} T_2^{-1} = e, \\ [2]: \quad & C_4^{-1} T_1 C_4 T_2 = e, \\ [3]: \quad & C_4^{-1} T_2 C_4 T_1^{-1} = e, \\ [4]: \quad & C_4^4 = e. \end{aligned}$$

The onsite physical spin rotation by an angle θ around the spin axis \vec{n} : $U_{\theta\vec{n}}$, which forms a half-integer spin irrep of the $\text{SU}(2)$, commutes with all lattice symmetries:

$$g^{-1} \cdot U_{\theta\vec{n}} \cdot g \cdot U_{\theta\vec{n}}^{-1} = e, \quad \forall g = T_1, T_2, C_4. \quad (\text{F3})$$

Following, we solve the implementations of these symmetries on PEPS with $\text{IGG} = Z_2 = \{I, J\}$, step by step. As discussed in Sec. III A, each symmetry element R is associated with its own η ambiguity and ϵ ambiguity. And the PEPS itself has a Φ ambiguity and a V ambiguity, a statement unrelated to specific symmetry elements.

(1) Choose the virtual basis such that $J(x, y, i) = J = I_{D_1} \oplus (-I_{D_2})$ is a site- and leg-independent diagonal matrix, according to the discussion in Sec. III B. This determines J up to an overall ± 1 sign, which we will use in step 10. (Note that we have not attached any physical meanings for the D_1 and D_2 sectors yet.) All the remaining V -ambiguity matrices (could be site and leg dependent) as well as all the W_R matrices (could be site and leg dependent) commute with J , so they are block diagonal and act within the D_1 and D_2 subspaces.

(2) Consider identity [2]. Applying Eq. (28) to this identity,

$$\begin{aligned} W_{C_4}^{-1}[-y, x, C_4(i)] W_{T_1}[-y, x, C_4(i)] W_{C_4}[-y - 1, x, C_4(i)] \\ \times W_{T_2}(x, y + 1, i) = \eta_{[2]} \chi_{[2]}(x, y, i). \end{aligned} \quad (\text{F4})$$

Since W_{T_1} appears in this equation only once, we can always use the η_{T_1} ambiguity: $W_{T_1} \rightarrow J W_{T_1}$ to tune $\eta_{[2]} = I$. This fixes the relative η ambiguity for W_{T_1} , W_{T_2} , and still leaves an overall η ambiguity $W_{T_1}, W_{T_2} \rightarrow J W_{T_1} J W_{T_2}$.

(3) Using the remaining V ambiguity to transform W_{T_2} , according to Eq. (32),

$$W_{T_2}(x, y, i) \rightarrow V(x, y, i) W_{T_2}(x, y, i) V^{-1}(x, y - 1, i). \quad (\text{F5})$$

So, we can set $W_{T_2}(x, y, i) = I$. There is no ϵ_{T_2} ambiguity left. The remaining V ambiguity satisfies $V(x, y, i) = V(x, 0, i)$. Next, we use this remaining V ambiguity to transform W_{T_1} along the row of sites at $y = 0$:

$$W_{T_1}(x, 0, i) \rightarrow V(x, 0, i) W_{T_1}(x, 0, i) V^{-1}(x - 1, 0, i), \quad (\text{F6})$$

so that $W_{T_1}(x, 0, i) = I$. Now, the remaining V ambiguity is site independent but could be leg dependent: $V(x, y, i) = V(i)$. The remaining ϵ_{T_1} ambiguity satisfies $\epsilon_{T_1}(x, 0, i) = 1$. Consider identity [1]. Applying Eq. (28) to this identity,

$$W_{T_1}(x, y, i) W_{T_2}(x - 1, y, i) W_{T_1}^{-1}(x, y - 1, i) \times W_{T_2}^{-1}(x, y, i) = \eta_{12} \chi_{12}(x, y, i). \quad (\text{F7})$$

The remaining η ambiguity for W_{T_1}, W_{T_2} cannot tune away η_{12} . Using results obtained previously in the step, we have

$$W_{T_1}(x, y, i) W_{T_1}^{-1}(x, y - 1, i) = \eta_{12} \chi_{12}(x, y, i). \quad (\text{F8})$$

We then use the remaining ϵ_{T_1} ambiguity to transform χ_{12} , according to Eq. (36):

$$\chi_{12}(x, y, i) \rightarrow \chi_{12}(x, y, i) \epsilon_{T_1}(x, y, i) \epsilon_{T_1}^*(x, y - 1, i). \quad (\text{F9})$$

So, we can set $\chi_{12}(x, y, i) = 1$. After this, Eq. (F8) leads to $W_{T_1}(x, y, i) = \eta_{12}^y W_{T_1}(x, 0, i) = \eta_{12}^y$, and there is no ϵ_{T_1} ambiguity left. In this gauge all site tensors are the same: $T^{(x, y)} = T^{(0, 0)} \equiv T$, while bond tensors are spatial dependent if the η_{12} index is nontrivial.

Next, we study Θ_{T_1} and Θ_{T_2} . First, we use the Φ ambiguity, which we have not used before, to transform Θ_{T_2} . According to Eq. (34),

$$\Theta_{T_2}(x, y) \rightarrow \Theta_{T_2}(x, y) \Phi(x, y) \Phi^*(x, y - 1), \quad (\text{F10})$$

so we can set $\Theta_{T_2}(x, y) = 1$, and the remaining Φ ambiguity satisfies $\Phi(x, y) = \Phi(x, 0)$. We then use the remaining Φ ambiguity to transform Θ_{T_1} along the row of sites at $y = 0$:

$$\Theta_{T_1}(x, 0) \rightarrow \Theta_{T_1}(x, 0) \Phi(x, 0) \Phi^*(x - 1, 0), \quad (\text{F11})$$

so we can set $\Theta_{T_1}(x, 0) = 1$. The remaining Φ ambiguity is only a site-independent overall phase: $\Phi(x, y) = \Phi(0, 0) \equiv \Phi$. Since we will not study time-reversal symmetry here, it turns out that this overall phase ambiguity is not useful. Applying Eq. (29) to the identity [1], we have

$$\Theta_{T_1}(x, y) \Theta_{T_2}(x - 1, y) \Theta_{T_1}^*(x, y - 1) \Theta_{T_2}^*(x, y) = \mu_{12} \prod_i \chi_{12}^*(x, y, i), \quad (\text{F12})$$

where μ_{12} is the site-independent phase factor obtained when applying η_{12} on a site tensor, as mentioned in Sec. III B. Using the results obtained so far, we find $\Theta_{T_1}(x, y) = \mu_{12}^y \Theta_{T_1}(x, 0) = \mu_{12}^y$.

We can summarize the results obtained in step 3:

$$\begin{aligned} W_{T_1}(x, y, i) &= \eta_{12}^y, \\ W_{T_2}(x, y, i) &= I, \\ \Theta_{T_1}(x, y) &= \mu_{12}^y, \\ \Theta_{T_2}(x, y) &= 1. \end{aligned} \quad (\text{F13})$$

The remaining Φ ambiguity is an overall phase. The remaining $V(x, y, i) = V(i)$. There are no remaining $\epsilon_{T_1}, \epsilon_{T_2}$ ambiguities left. There is a remaining overall η ambiguity for W_{T_1}, W_{T_2} .

(4) Consider identity [2] again. Based on the discussion in step 2, we have

$$W_{C_4}^{-1}[-y, x, C_4(i)] W_{T_1}[-y, x, C_4(i)] W_{C_4}[-y - 1, x, C_4(i)] \times W_{T_2}(x, y + 1, i) = \chi_{[2]}(x, y, i). \quad (\text{F14})$$

Plugging in the results in step 3, we obtain

$$W_{C_4}^{-1}[-y, x, C_4(i)] W_{C_4}[-y - 1, x, C_4(i)] = \eta_{12}^x \chi_{[2]}(x, y, i). \quad (\text{F15})$$

Now, we use the ϵ_{C_4} ambiguity. Applying Eq. (36), this transforms $\chi_{[2]}$ as

$$\begin{aligned} \chi_{[2]}(x, y, i) \\ \rightarrow \chi_{[2]}(x, y, i) \epsilon_{C_4}[-y - 1, x, C_4(i)] \epsilon_{C_4}^*[-y, x, C_4(i)]. \end{aligned} \quad (\text{F16})$$

So, we can set $\chi_{[2]}(x, y, i) = 1$, and the remaining ϵ_{C_4} ambiguity satisfies $\epsilon_{C_4}(x, y, i) = \epsilon_{C_4}(0, y, i)$. After this, Eq. (F15) leads to $W_{C_4}(x, y, i) = \eta_{12}^{xy} W_{C_4}(0, y, i)$.

(5) Consider identity [3]. Applying Eq. (28),

$$\begin{aligned} W_{C_4}^{-1}[-y, x, C_4(i)] I W_{C_4}[-y, x - 1, C_4(i)] W_{T_1}^{-1}(x, y, i) \\ = \eta_{C_4 T} \chi_{C_4 T}(x, y, i). \end{aligned} \quad (\text{F17})$$

Using results in steps 3 and 4, we have

$$W_{C_4}^{-1}[0, x, C_4(i)] W_{C_4}[0, x - 1, C_4(i)] = \eta_{C_4 T} \chi_{C_4 T}(x, y, i), \quad (\text{F18})$$

so we know $\chi_{C_4 T}(x, y, i) = \chi_{C_4 T}(x, 0, i)$, independent of y .

We then can use the remaining ϵ_{C_4} ambiguity from step 4 to transform $\chi_{C_4 T}$:

$$\chi_{C_4 T}(x, 0, i) \rightarrow \chi_{C_4 T}(x, 0, i) \epsilon_{C_4}^*[0, x, C_4(i)] \epsilon_{C_4}[0, x - 1, C_4(i)]. \quad (\text{F19})$$

So, we can set $\chi_{C_4 T}(x, 0, i) = 1$ and the remaining ϵ_{C_4} ambiguity is site independent: $\epsilon_{C_4}(x, y, i) = \epsilon_{C_4}(i)$.

After this, the site dependence of W_{C_4} is solved: $W_{C_4}(0, y, i) = \eta_{C_4 T}^y W_{C_4}(0, 0, i)$. Together with results in step 4,

$$W_{C_4}(x, y, i) = \eta_{12}^{xy} \eta_{C_4 T}^y W_{C_4}(i), \quad (\text{F20})$$

where we defined $W_{C_4}(i) \equiv W_{C_4}(0, 0, i)$.

So far, we have not used the η ambiguity for W_{C_4} . The remaining $\epsilon_{C_4}(x, y, i) = \epsilon_{C_4}(i)$, and there is still a remaining $V(x, y, i) = V(i)$ ambiguity.

(6) Consider Θ_{C_4} . Applying Eq. (29) to identity [2], together with results in steps 2 and 4,

$$\Theta_{C_4}^*(-y, x) \Theta_{T_1}(-y, x) \Theta_{C_4}(-y - 1, x) \Theta_{T_2}(x, y) = 1. \quad (\text{F21})$$

Plugging in results in step 3, this leads to

$$\Theta_{C_4}(x, y) = \mu_{12}^{xy} \Theta_{C_4}(0, y). \quad (\text{F22})$$

Similarly, we apply Eq. (29) to identity [3]:

$$\Theta_{C_4}^*(-y, x) \Theta_{C_4}(-y, x - 1) \mu_{12}^y = \mu_{C_4 T} \prod_i \chi_{C_4 T}^*(x, y, i), \quad (\text{F23})$$

where we used results in step 3. Plugging in $\chi_{C_4 T} = 1$, which has been obtained in step 5, and using Eq. (F22), the site dependence of Θ_{C_4} is solved:

$$\Theta_{C_4}(x, y) = \mu_{C_4 T}^y \mu_{12}^{xy} \Theta_{C_4}, \quad (\text{F24})$$

where we introduced $\Theta_{C_4} \equiv \Theta_{C_4}(0, 0)$.

(7) Consider identity [4]. Applying Eq. (28) and the site dependence of W_{C_4} obtained in step 5, we have

$$\begin{aligned} W_{C_4}(i)W_{C_4}[C_4^3(i)]W_{C_4}[C_4^2(i)]W_{C_4}[C_4(i)] \\ = \eta_{C_4}\chi_{C_4}(i), \end{aligned} \quad (\text{F25})$$

where $\chi_{C_4}(i) \equiv \chi_{C_4}(x, y, i)$ since the above relation dictates χ_{C_4} to be site independent.

Applying Eq. (29) and the site dependence of Θ_{C_4} obtained in step 6, we find

$$\Theta_{C_4}^4 = \mu_{C_4} \prod_i \chi_{C_4}^*(i). \quad (\text{F26})$$

But, due to the definition of the χ group, we know that $\chi_{C_4}(a) = \chi_{C_4}^*(c)$ and $\chi_{C_4}(b) = \chi_{C_4}^*(d)$, so $\prod_i \chi_{C_4}^*(i) = 1$.

Consequently, $\Theta_{C_4} = (\mu_{C_4})^{\frac{1}{4}}$. Naively, there would be four allowed roots for a given choice of η_{C_4} . However, we have not used the η ambiguity for W_{C_4} . Under the η -ambiguity transformation, $W_{C_4} \rightarrow JW_{C_4}$, clearly Θ_{C_4} transforms as $\Theta_{C_4} \rightarrow \mu_J \Theta_{C_4}$. We will prove that $\mu_J = -1$ in step 10; i.e., every site tensor is Z_2 odd. Thus, we can use the η ambiguity for W_{C_4} to tune away the sign in Θ_{C_4} , and there are only two independent values for the root. We made the following choice:

$$\begin{aligned} \Theta_{C_4} &= 1 \text{ or } i, \quad \text{if } \eta_{C_4} = \text{I}; \\ \Theta_{C_4} &= e^{i\frac{\pi}{4}} \text{ or } e^{-i\frac{\pi}{4}}, \quad \text{if } \eta_{C_4} = \text{J}. \end{aligned} \quad (\text{F27})$$

After this, there is no remaining η ambiguity for W_{C_4} .

Next, we can use the remaining $V(i)$ ambiguity to transform $W_{C_4}(i)$:

$$W_{C_4}(i) \rightarrow V(i)W_{C_4}(i)V^{-1}[C_4^{-1}(i)]. \quad (\text{F28})$$

So, we can set $W_{C_4}(b) = W_{C_4}(c) = W_{C_4}(d) = \text{I}$. This leaves no remaining ϵ_{C_4} ambiguity because $\epsilon_{C_4}(a) = \epsilon_{C_4}^*(c)$ as required in the definition of the χ group. The remaining V ambiguity is site and leg independent: $V(x, y, i) = V$.

Coming back to Eq. (F25), in the current gauge we have

$$W_{C_4}(a) = \eta_{C_4}\chi_{C_4}(i), \quad \forall i = a, b, c, d. \quad (\text{F29})$$

Consequently, $\chi_{C_4}(i) \equiv \chi_{C_4}$ is leg independent, and $\chi_{C_4} = \pm 1$ since, e.g., $\chi_{C_4}(a) = \chi_{C_4}^*(c)$.

One may worry that if $\eta_{C_4} = \text{J}$, we simply have $W_{C_4}(a) = \chi_{C_4}\text{J}$, and the ± 1 sign here may be tuned away by redefining the J element (recall that there is such sign freedom as mentioned in step 1). But, for the moment let us not use this sign freedom in the definition of J because it will be used later in step 10. Consequently, after step 10, the χ_{C_4} index here cannot be tuned away.

(8) Consider the onsite $\text{SU}(2)$ symmetry. We can apply Eq. (28) for a group identity in the multiplication table of $\text{SU}(2)$:

$$[\theta_2 \vec{n}_2] \cdot [\theta_1 \vec{n}_1] = [\theta_3 \vec{n}_3], \quad (\text{F30})$$

and obtain

$$\begin{aligned} W_{\theta_3 \vec{n}_3}^{-1}(x, y, i)W_{\theta_2 \vec{n}_2}(x, y, i)W_{\theta_1 \vec{n}_1}(x, y, i) \\ = \eta_{[\theta_2 \vec{n}_2], [\theta_1 \vec{n}_1]} \chi_{[\theta_2 \vec{n}_2], [\theta_1 \vec{n}_1]}(x, y, i). \end{aligned} \quad (\text{F31})$$

Let us focus on a single virtual leg (x, y, i) , and consider all the possible $[\theta_2 \vec{n}_2], [\theta_1 \vec{n}_1]$. One can then immediately see that both $\eta_{[\theta_2 \vec{n}_2], [\theta_1 \vec{n}_1]}$ and $\chi_{[\theta_2 \vec{n}_2], [\theta_1 \vec{n}_1]}(x, y, i)$ must satisfy 2-cocycle

conditions as a function of $[\theta_2 \vec{n}_2]$ and $[\theta_1 \vec{n}_1]$ (see Appendix C for detailed discussions). Namely, for a fixed (x, y, i) ,

$$\eta_{[\theta_2 \vec{n}_2], [\theta_1 \vec{n}_1]} \in H^2[\text{SU}(2), Z_2] = Z_1,$$

$$\chi_{[\theta_2 \vec{n}_2], [\theta_1 \vec{n}_1]}(x, y, i) \in H^2[\text{SU}(2), U(1)] = Z_1. \quad (\text{F32})$$

Because both 2-cohomology groups are trivial, we find both $\eta_{[\theta_2 \vec{n}_2], [\theta_1 \vec{n}_1]}$ and $\chi_{[\theta_2 \vec{n}_2], [\theta_1 \vec{n}_1]}(x, y, i)$ are 2-coboundaries. Consequently, one can use the η ambiguities for $W_{\theta \vec{n}}$ and the $\epsilon_{\theta \vec{n}}(x, y, i)$ ambiguities to set $\eta_{[\theta_2 \vec{n}_2], [\theta_1 \vec{n}_1]} = \text{I}$ and $\chi_{[\theta_2 \vec{n}_2], [\theta_1 \vec{n}_1]}(x, y, i) = 1$. After this, Eq. (F31) simply means that $W_{\theta \vec{n}}(x, y, i)$ forms a representation of $\text{SU}(2)$, $\forall (x, y, i)$:

$$W_{\theta_3 \vec{n}_3}^{-1}(x, y, i)W_{\theta_2 \vec{n}_2}(x, y, i)W_{\theta_1 \vec{n}_1}(x, y, i) = \text{I}. \quad (\text{F33})$$

(9) Study the site and leg dependence of $W_{\theta \vec{n}}(x, y, i)$. For any space-group symmetry element g , we have the group identity

$$g^{-1} \cdot [\theta \vec{n}] \cdot g \cdot [\theta \vec{n}]^{-1} = e. \quad (\text{F34})$$

Applying Eq. (28) to this identity, we find

$$\begin{aligned} W_g^{-1}[g(x, y, i)]W_{\theta \vec{n}}[g(x, y, i)]W_g[g(x, y, i)]W_{\theta \vec{n}}^{-1}(x, y, i) \\ = \eta_{g, [\theta \vec{n}]} \chi_{g, [\theta \vec{n}]}(x, y, i). \end{aligned} \quad (\text{F35})$$

Because we have already determined the form of $W_g(x, y, i)$ in steps 3, 5, and 7, and $W_g(x, y, i)$ can only be a power of J up to a factor, we conclude that $W_g(x, y, i)$ commutes with $W_{\theta \vec{n}}(x, y, i)$. So, the above equation reduces to

$$W_{\theta \vec{n}}[g(x, y, i)]W_{\theta \vec{n}}^{-1}(x, y, i) = \eta_{g, [\theta \vec{n}]} \chi_{g, [\theta \vec{n}]}(x, y, i). \quad (\text{F36})$$

Next, one can plug in $[\theta_2 \vec{n}_2] \cdot [\theta_1 \vec{n}_1] = [\theta_3 \vec{n}_3]$ on the right-hand side of this equation and apply Eq. (F33). One then concludes that, for any fixed (x, y, i) , $\eta_{g, [\theta \vec{n}]} [\chi_{g, [\theta \vec{n}]}(x, y, i)]$ must be a representation of $\text{SU}(2)$ in $Z_2[U(1)]$. But, such representations must be trivial. Therefore, $\eta_{g, [\theta \vec{n}]} = \text{I}$ and $\chi_{g, [\theta \vec{n}]}(x, y, i) = 1$, $\forall (x, y, i)$. Equation (F36) dictates that $W_{\theta \vec{n}}$ must be site and leg independent:

$$W_{\theta \vec{n}}(x, y, i) = W_{\theta \vec{n}}, \quad \forall (x, y, i). \quad (\text{F37})$$

In addition, we can consider $\Theta_{\theta \vec{n}}(x, y)$. Due to the definition of Θ , the following is true for any site tensor $T^{(x, y)}$:

$$T^{(x, y)} = \Theta_{\theta \vec{n}} W_{\theta \vec{n}} U_{\theta \vec{n}} \circ T^{(x, y)}. \quad (\text{F38})$$

However, since $U_{\theta \vec{n}}$ is the $\text{SU}(2)$ representation on the physical leg and we already showed that $W_{\theta \vec{n}}$ also form a representation of $\text{SU}(2)$, $\Theta_{\theta \vec{n}}$ must be a representation of $\text{SU}(2)$ in $U(1)$, which again must be trivial. So, $\Theta_{\theta \vec{n}}(x, y) = 1$.

(10) Finally, consider the $\theta = 2\pi$ $\text{SU}(2)$ rotation. Equation (F38) for this particular case becomes

$$T^{(x, y)} = -W_{\theta=2\pi} \circ T^{(x, y)}, \quad (\text{F39})$$

where we use the fact that the physical spin is half-integer and $\Theta_{\theta=2\pi} = 1$ obtained in step 9. This means that $W_{\theta=2\pi}$, a site- and leg-independent transformation, must be an element in $\overline{\text{IGG}}$ and thus can be written as

$$W_{\theta=2\pi} = \eta_{\theta=2\pi} \chi_{\theta=2\pi}(x, y, i), \quad (\text{F40})$$

we see that $\chi_{\theta=2\pi}(x, y, i) \equiv \chi_{\theta=2\pi}$ is site and leg independent. Due to the definition of the χ group, this limits $\chi_{\theta=2\pi} = \pm 1$.

Plugging the above equation back in Eq. (F39), one has

$$-\mu_{\theta=2\pi} \prod_i \chi_{\theta=2\pi} = -\mu_{\theta=2\pi} = 1. \quad (\text{F41})$$

So, $\mu_{\theta=2\pi} = -1$. This dictates that $\eta_{\theta=2\pi} = J$ and every site tensor must be Z_2 odd: $\mu_J = -1$.

We then have

$$W_{\theta=2\pi} = \chi_{\theta=2\pi} J. \quad (\text{F42})$$

Note that we still have a sign ambiguity in the definition of J , as mentioned in step 1. We now use this sign ambiguity to set $\chi_{\theta=2\pi} = 1$ and $W_{\theta=2\pi} = J$.

(11) We still have the remaining $V(x, y, i) = V$ ambiguity. Now, we use this ambiguity to transform the site and leg independent $W_{\theta\vec{n}}$ to the standard form

$$W_{\theta\vec{n}} = \oplus_{i=1}^M (\mathbf{I}_{n_i} \otimes e^{i\theta\vec{n} \cdot \vec{S}_i}); \quad (\text{F43})$$

namely, each virtual leg is a direct sum of n_i number of \vec{S}_i with different spin representation \vec{S}_i . Here, we are only left with the V ambiguity that is a direct sum of the similarity transformations acting in the \mathbf{I}_{n_i} spaces.

Summary. We find in the presence of translational symmetry, C_4 symmetry, spin-rotational symmetry, the IGG = Z_2 symmetric PEPS for a half-integer spin system on the square lattice is classified by the following three sets of algebraic data:

- (a) $\eta_{12}, \eta_{C_4 T}, \eta_{C_4} \in \text{IGG} = \{1, J\}$,
- (b) χ_{C_4} which can be ± 1 ,

(c) Θ_{C_4} which can choose values as defined in Eq. (F27). Since each index can choose two values, there are $2^5 = 32$ classes. These indices completely determine the transformation rules of the site and bond tensors as

$$W_{\theta\vec{n}}(x, y, i) = W_{\theta\vec{n}} = \oplus_{i=1}^M (\mathbf{I}_{n_i} \otimes e^{i\theta\vec{n} \cdot \vec{S}_i}),$$

$$J = W_{\theta=2\pi},$$

$$W_{T_1}(x, y, i) = \eta_{12}^y,$$

$$W_{T_2}(x, y, i) = I,$$

$$W_{C_4}(x, y, a) = \chi_{C_4} \eta_{12}^{xy} \eta_{C_4 T}^y \eta_{C_4},$$

$$W_{C_4}(x, y, b/c/d) = \eta_{12}^{xy} \eta_{C_4 T}^y, \quad (\text{F44})$$

and

$$\Theta_{\theta\vec{n}}(x, y) = 1,$$

$$\Theta_{T_1}(x, y) = \mu_{12}^y,$$

$$\Theta_{T_2}(x, y) = 1,$$

$$\Theta_{C_4}(x, y) = \mu_{C_4 T}^y \mu_{12}^{xy} \Theta_{C_4}. \quad (\text{F45})$$

Here, $\mu_{12} = 1 (-1)$ if $\eta_{12} = I (J)$, and similarly $\mu_{C_4 T} = 1 (-1)$ if $\eta_{C_4 T} = I (J)$. $\Theta_{C_4} = 1$ or i ($\Theta_{C_4} = e^{i\pi/4}$ or $e^{-i\pi/4}$) if $\eta_{C_4} = I$ (J).

After the physical half-integer spin is specified, e.g. $S = \frac{1}{2}$ or $\frac{3}{2}$, we know the transformation rules for both physical and virtual legs. One can thus determine the generic form of the symmetric tensor network for each class and use it for numerical simulation as discussed in Sec. III C.

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