

Bayesian inference and prediction with finite regression models

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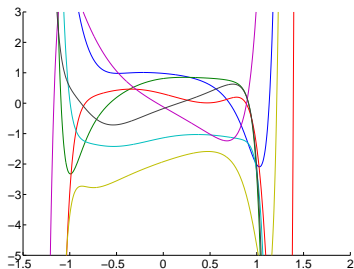
Key concepts

Posterior probability of a function

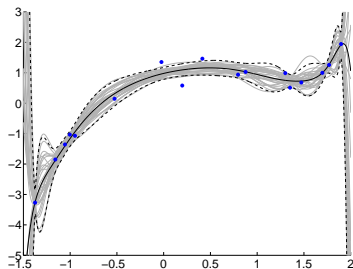
Given the **prior** functions $p(f)$ how can we make predictions?

- Of all functions generated from the prior, keep those that fit the data.
- The notion of closeness to the data is given by the **likelihood** $p(y|f)$.
- We are really interested in the posterior distribution over functions:

$$p(f|y) = \frac{p(y|f) p(f)}{p(y)} \quad \text{Bayes Rule}$$



Some samples from the prior



Samples from the posterior

Priors on parameters induce priors on functions

A model \mathcal{M} is the choice of a **model structure** and of **parameter values**.

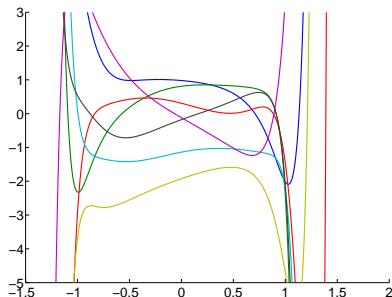
$$f_{\mathbf{w}}(\mathbf{x}) = \sum_{m=0}^M \mathbf{w}_m \phi_m(\mathbf{x})$$

The prior $p(\mathbf{w}|\mathcal{M})$ determines what **functions** this model can generate. Example:

- Imagine we choose $M = 17$, and $p(\mathbf{w}_m) = \mathcal{N}(\mathbf{w}_m; 0, \sigma_{\mathbf{w}}^2)$.
- We have actually defined a **prior distribution over functions** $p(f|\mathcal{M})$.

This figure is generated as follows:

- Use polynomial basis functions, $\phi_m(\mathbf{x}) = \mathbf{x}^m$.
- Define a uniform grid of $n = 100$ values in \mathbf{x} from $[-1.5, 2]$.
- Generate matrix Φ for $M = 17$.
- Draw $\mathbf{w}_m \sim \mathcal{N}(0, 1)$.
- Compute and plot $\mathbf{f} = \Phi_{n \times 18} \mathbf{w}$.



Maximum likelihood, parametric model

Supervised parametric learning:

- data: \mathbf{x}, \mathbf{y}
- model \mathcal{M} : $y = f_{\mathbf{w}}(\mathbf{x}) + \varepsilon$

Gaussian likelihood:

$$p(\mathbf{y}|\mathbf{x}, \mathbf{w}, \mathcal{M}) \propto \prod_{n=1}^N \exp(-\frac{1}{2}(y_n - f_{\mathbf{w}}(\mathbf{x}_n))^2 / \sigma_{\text{noise}}^2).$$

Maximize the likelihood:

$$\mathbf{w}_{\text{ML}} = \underset{\mathbf{w}}{\operatorname{argmax}} p(\mathbf{y}|\mathbf{x}, \mathbf{w}, \mathcal{M}).$$

Make predictions, by plugging in the ML estimate:

$$p(y_*|\mathbf{x}_*, \mathbf{w}_{\text{ML}}, \mathcal{M})$$

Bayesian inference, parametric model, cont.

Posterior parameter distribution by Bayes rule ($p(\mathbf{a}|\mathbf{b}) = p(\mathbf{a})p(\mathbf{b}|\mathbf{a})/p(\mathbf{b})$):

$$p(\mathbf{w}|\mathbf{x}, \mathbf{y}, \mathcal{M}) = \frac{p(\mathbf{w}|\mathcal{M})p(\mathbf{y}|\mathbf{x}, \mathbf{w}, \mathcal{M})}{p(\mathbf{y}|\mathbf{x}, \mathcal{M})}$$

Making predictions (marginalizing out the parameters):

$$\begin{aligned} p(y_*|\mathbf{x}_*, \mathbf{x}, \mathbf{y}, \mathcal{M}) &= \int p(y_*, \mathbf{w}|\mathbf{x}, \mathbf{y}, \mathbf{x}_*, \mathcal{M}) d\mathbf{w} \\ &= \int p(y_*|\mathbf{w}, \mathbf{x}_*, \mathcal{M})p(\mathbf{w}|\mathbf{x}, \mathbf{y}, \mathcal{M}) d\mathbf{w}. \end{aligned}$$

Posterior and predictive distribution in detail

For a linear-in-the-parameters model with Gaussian priors and Gaussian noise:

- Gaussian *prior* on the weights: $p(\mathbf{w}|\mathcal{M}) = \mathcal{N}(\mathbf{w}; \mathbf{0}, \sigma_w^2 \mathbf{I})$
- Gaussian *likelihood* of the weights: $p(\mathbf{y}|\mathbf{x}, \mathbf{w}, \mathcal{M}) = \mathcal{N}(\mathbf{y}; \mathbf{\Phi} \mathbf{w}, \sigma_{\text{noise}}^2 \mathbf{I})$

Posterior parameter distribution by Bayes rule $p(\mathbf{a}|\mathbf{b}) = p(\mathbf{a})p(\mathbf{b}|\mathbf{a})/p(\mathbf{b})$:

$$p(\mathbf{w}|\mathbf{x}, \mathbf{y}, \mathcal{M}) = \frac{p(\mathbf{w}|\mathcal{M})p(\mathbf{y}|\mathbf{x}, \mathbf{w}, \mathcal{M})}{p(\mathbf{y}|\mathbf{x}, \mathcal{M})} = \mathcal{N}(\mathbf{w}; \boldsymbol{\mu}, \boldsymbol{\Sigma})$$

$$\boldsymbol{\Sigma} = (\sigma_{\text{noise}}^{-2} \mathbf{\Phi}^\top \mathbf{\Phi} + \sigma_w^{-2} \mathbf{I})^{-1} \quad \text{and} \quad \boldsymbol{\mu} = \left(\mathbf{\Phi}^\top \mathbf{\Phi} + \frac{\sigma_{\text{noise}}^2}{\sigma_w^2} \mathbf{I} \right)^{-1} \mathbf{\Phi}^\top \mathbf{y}$$

The predictive distribution is given by:

$$p(y_*|\mathbf{x}_*, \mathbf{x}, \mathbf{y}, \mathcal{M}) = \mathcal{N}(y_*; \mathbf{\Phi}(\mathbf{x}_*)^\top \boldsymbol{\mu}, \mathbf{\Phi}(\mathbf{x}_*)^\top \boldsymbol{\Sigma} \mathbf{\Phi}(\mathbf{x}_*) + \sigma_{\text{noise}}^2)$$