

6 Design of Algorithms: By Dynamic Programming

6.1 Introduction

Reading: CLRS 15.3

- Divide-and-conquer algorithms are implemented by recursion. Its design is top-down, and it is efficient when the subproblems don't overlap. However, when subproblems do overlap (share sub-subproblems), recursion does redundant work. In this case, a tabular method is often used. It is nonrecursive and bottom-up. It is called dynamic programming.
- An example: Fibonacci numbers:

```
fib1(n)
    if n < 2 return n
    else return fib1(n-1) + fib1(n-2)
```

We can see that this recursive (divide-and-conquer) algorithm is not efficient. To compute $fib1(n)$, the algorithm computes $fib1(n-1)$ and $fib1(n-2)$ separately. To compute $fib1(n-1)$, the values of $fib1(n-2)$ and $fib1(n-3)$ are needed. To compute $fib1(n-2)$, the values of $fib1(n-3)$ and $fib1(n-4)$ are needed. We observe that subproblems $fib1(n-1)$ and $fib1(n-2)$ share sub-subproblem.

The time complexity $T(n) \geq T(n-1) + T(n-2)$. So $T(n)$ is larger than the n th Fibonacci number. So $T(n) \geq \frac{1}{\sqrt{5}}((\frac{1+\sqrt{5}}{2})^n - (-\frac{1+\sqrt{5}}{2})^{-n}) = \Theta(1.618^n)$.

We can use the dynamic programming method by building a 1-D table as below and returning the n th entry of the table.

k	0	1	2	3	4	...	n
f_k	0	1	1	2	3	...	f_n

```
fib2(n)
    if n < 2 return n
    else i ← 0
        j ← 1
        for k ← 2 to n
            f ← i + j
            i ← j
            j ← f
        return f
```

The time complexity is obviously $O(n)$.

To summarize how to use dynamic programming, first define a function F recursively (so that the solution information is embedded in $F(n)$): $F(n) = G(F(n_1), F(n_2), \dots, F(n_k))$ for $n_1, n_2, \dots, n_k < n$. Construct a table to compute nonrecursively $F(n_1), F(n_2), \dots, F(n_k)$, hence $F(n)$.

6.2 Making change

- Let n , a positive integer, be the number of different types of coin in a country. Let $coin[1..n]$, an array of positive integers, be the values of these n types of coin. Let m , a positive integer, be the amount of change that one wishes to make. Design a dynamic programming algorithm that determines whether m can be made with the coins, and if so, computes the minimum number of coins needed.
- Define $count(i)$ to be the minimum number of coins to make i (> 0). That $count(i) = \infty$ implies that no solution exists. The recursive definition of $count(i)$ is as follows.

```
count(1) = ∞ if 1 ∉ coin[ ].
count(coin[j]) = 1 for j = 1, ..., n.
count(i) = 1 + min_{1 ≤ j ≤ n, coin[j] < i} {count(i - coin[j])}
```

- The table is a 1-D table and its entries are filled from left to right until $count[m]$ is reached.

i	1	2	...	m
$count[i]$	\rightarrow	\rightarrow	...	*

- Algorithm:

```

for  $i \leftarrow 1$  to  $m$   $count[i] \leftarrow -1$ 
 $count[1] \leftarrow \infty$ 
for  $j \leftarrow 1$  to  $n$ 
   $count[coin[j]] \leftarrow 1$ 
for  $i \leftarrow 1$  to  $m$ 
  if  $count[i] = -1$ 
     $min \leftarrow \infty$ 
    for  $j \leftarrow 1$  to  $n$ 
      if  $coin[j] < i$ 
        if  $min > count[i - coin[j]]$ 
           $min \leftarrow count[i - coin[j]]$ 
     $count[i] \leftarrow 1 + min$ 

```

- Time complexity: $\Theta(mn)$. (pseudo-polynomial)

6.3 Chained matrix multiplication

Reading: CLRS 15.2

- We wish to compute $A_1 \times A_2 \times \cdots \times A_n$, where A_i is a $p_{i-1} \times p_i$ matrix. Which order of computation should we use to achieve the highest efficiency of the algorithm?
- The number of basic operations needed to compute $A_i \times A_{i+1}$ is $p_{i-1}p_i p_{i+1}$.
- Order of computation determines the time efficiency. For example, $A_1 : 10 \times 20$, $A_2 : 20 \times 50$, $A_3 : 50 \times 1$, and $A_4 : 1 \times 100$. If we use the order in $A_1 \times (A_2 \times (A_3 \times A_4))$, the number of basic operations is $(50 \times 1 \times 100) + (20 \times 50 \times 100) + (10 \times 20 \times 100) = 125,000$. However, if we use the order in $((A_1 \times A_2) \times A_3) \times A_4$, the number of basic operations is $(10 \times 20 \times 50) + (10 \times 50 \times 1) + (10 \times 1 \times 100) = 11,500$.
- Question: What is the minimum number of basic operations in computing $A_1 \times A_2 \times \cdots \times A_n$?
- Let $m(i, j)$ be the minimum number of basic operations in computing $A_i \times A_{i+1} \times \cdots \times A_j$ for $1 \leq i \leq j \leq n$. Assume in general that k is used to indicate the position of the last multiplication to be performed among all: $(A_i \times \cdots \times A_k) \times (A_{k+1} \times \cdots \times A_j)$. Then

$$m(i, j) = 0 \text{ if } i = j.$$

$$m(i, j) = \min_{i \leq k \leq j-1} \{m(i, k) + m(k+1, j) + p_{i-1}p_k p_j\} \text{ if } i \neq j.$$
- We can use a dynamic programming algorithm to compute $m(1, n)$, the minimum number of basic operations in computing $A_1 \times A_2 \times \cdots \times A_n$. Entries are filled left to right and bottom to top. Note that those in the lower left triangle are undefined.

$i \backslash j$	1	2	...	n
1	0	\uparrow	...	*
2	--	0	...	\uparrow
...
n	--	--	...	0

- The algorithm:


```

      for  $i \leftarrow 1$  to  $n$ 
         $m[i, i] \leftarrow 0$ 
      for  $j \leftarrow 2$  to  $n$ 
        for  $i \leftarrow j - 1$  to  $1$ 
           $m[i, j] \leftarrow \min_{i \leq k \leq j-1} \{m[i, k] + m[k + 1, j] + p_{i-1}p_kp_j\}$ 
      
```
- Time complexity: $O(n^3)$.

6.4 Longest common subsequence

Reading: CLRS 15.4

- Subsequence: If $X = \langle A, B, C, B, D, A, B \rangle$ and $Z = \langle B, C, D, B \rangle$, then Z is a subsequence of X .
Common subsequence: Let $Y = \langle B, D, C, A, B, A \rangle$. Then $\langle B, C, A \rangle$ is a common subsequence of X and Y .
Longest common subsequence (LCS): For X and Y , there is no common subsequence with length longer than 4. $\langle B, C, B, A \rangle$ and $\langle B, D, A, B \rangle$ are both LCS's of X and Y .
Question: Given two sequences, what is the length of their LCS? (What is the LCS of the sequences?)
- A brute-force method:
Assume $X = \langle x_1, \dots, x_m \rangle$ and $Y = \langle y_1, \dots, y_n \rangle$. For each subsequence of X , check if it is also a subsequence of Y , keeping track of the longest found.
How many possible subsequences are there for X ? $\binom{m}{0} + \binom{m}{1} + \binom{m}{2} + \dots + \binom{m}{m} = 2^m$.
- A recursive approach:
Define $X_i = \langle x_1, \dots, x_i \rangle$ and $Y_j = \langle y_1, \dots, y_j \rangle$. Define $C(i, j)$ to be the length of the LCS of X_i and Y_j .
 $C(i, j) = 0$ if $i = 0$ or $j = 0$;
 $C(i, j) = C(i - 1, j - 1) + 1$ if $i, j > 0$ and $x_i = y_j$;
 $C(i, j) = \max\{C(i, j - 1), C(i - 1, j)\}$ if $i, j > 0$ and $x_i \neq y_j$.
When $x_i = y_j$, $X_i = X_{i-1} \langle x_i \rangle$ and $Y_j = Y_{j-1} \langle y_j \rangle$. So $LCS(X_i, Y_j) = LCS(X_{i-1}, Y_{j-1}) \langle x_i \rangle$. Hence, $C(i, j) = C(i - 1, j - 1) + 1$.
When $x_i \neq y_j$, x_i and y_j cannot both appear in $LCS(X_i, Y_j)$. So $LCS(X_i, Y_j) = LCS(X_i, Y_{j-1})$ or $LCS(X_{i-1}, Y_j)$. Hence, $C[i, j] = \max\{C(i, j - 1), C(i - 1, j)\}$.
- A nonrecursive implementation: Dynamic programming:
A 2-D table is constructed where each entry is filled left to right and top to bottom. The initialization handles the first row and the first column of the table. Entry $C[m, n]$ is the length of the LCS of X and Y .

$i \backslash j$	0	1	2	\dots	n
0	0	0	0	\dots	0
1	0	\rightarrow	\rightarrow	\dots	\rightarrow
2	0	\rightarrow	\rightarrow	\dots	\rightarrow
\dots	\dots	\dots	\dots	\dots	\dots
m	0	\rightarrow	\rightarrow	\dots	*

- The algorithm:


```

      for  $i \leftarrow 0$  to  $m$   $C[i, 0] \leftarrow 0$ 
      for  $j \leftarrow 0$  to  $n$   $C[0, j] \leftarrow 0$ 
      for  $i \leftarrow 1$  to  $m$ 
        for  $j \leftarrow 1$  to  $n$ 
          if  $x_i = y_j$   $C[i, j] \leftarrow C[i - 1, j - 1] + 1$ 
          else  $C[i, j] = \max\{C[i, j - 1], C[i - 1, j]\}$ 
      
```

- Time complexity: $\Theta(mn)$.
- How to compute the LCS in addition to the length of the LCS: Maintain an array $S[i, j]$ of special characters. Set $S[i, 0] = S[0, j] = \sqcup$ (single space) for $0 \leq i \leq m$ and $0 \leq j \leq n$. In the nested for loop, if $x_i = y_j$, set $S[i, j]$ to be \nwarrow , else if $C[i, j-1] \geq C[i-1, j]$, set $S[i, j]$ to be \leftarrow , and if $C[i, j-1] < C[i-1, j]$, set $S[i, j]$ to be \uparrow . The following additional code generates the LCS of two sequences.

```

i ← m
j ← n
while S[i, j] ≠ ⊔
    if S[i, j] = ← j ← j - 1
    else if S[i, j] = ↑ i ← i - 1
    else push  $x_i$  to a stack
        i ← i - 1
        j ← j - 1
output the content in the stack

```

6.5 Optimal binary search tree

Reading: CLRS 15.5

- Given a set of keys (numbers) and the probability that each key is located. How can one organize the set in a binary search tree so that the average time to locate a key in the tree is minimized?
- For each node (key) in a binary search tree, the time needed to locate the node is its level number.
- Let the keys be a_1, a_2, \dots, a_n (in increasing order). Let l_i be the level number of the node corresponding to key a_i in a given binary search tree. Let p_i be the probability that a_i is to be located. Then the average search time for that tree is $\sum_{i=1}^n p_i l_i$. We wish to build an optimal binary search tree, where this cost is minimized.
- An example: $n = 3$ and $p_1 = 0.7$, $p_2 = 0.2$ and $p_3 = 0.1$. The following figure contains all five possible binary search trees for $n = 3$.

1. $3(0.7) + 2(0.2) + 1(0.1) = 2.6$
2. $2(0.7) + 3(0.2) + 1(0.1) = 2.1$
3. $2(0.7) + 1(0.2) + 2(0.1) = 1.8$
4. $1(0.7) + 3(0.2) + 2(0.1) = 1.5$
5. $1(0.7) + 2(0.2) + 3(0.1) = 1.4 \Leftarrow$ optimal!

- A recursive approach: Let $c(i, j)$ be the average search time in a tree with only a_i, \dots, a_j , where $1 \leq i \leq j \leq n$. If a_k happens to be the root of the tree containing a_i, \dots, a_j , then in the left subtree are a_i, \dots, a_{k-1} and in the right subtree are a_{k+1}, \dots, a_j .

$$c(i, i) = p_i \text{ for } 1 \leq i \leq n$$

$$c(i, j) = \min_{i \leq k \leq j} \{c(i, k-1) + c(k+1, j) + \sum_{l=i}^j p_l\} \text{ for } i < j$$

$$c(i, j) = 0 \text{ for } i = j + 1 \text{ (Why needed?)}$$

- A dynamic programming algorithm with $O(n^3)$:

$i \backslash j$	1	2	...	$n-1$	n
1	p_1	\uparrow	...	\uparrow	*
2	0	p_2	...	\uparrow	\uparrow
...
n	--	--	...	0	p_n

6.6 Comparing Two Sequences

- Interested in finding the best alignment of two sequences for the purpose of comparison.
- Given two sequences, s and t , over the same alphabet. For any alignment A of the two sequences, define its score $score_A(s, t)$ to be the sum of the scores of all columns in the alignment, where the score of a column containing characters a and b , denoted as $p(a, b)$, may be defined to be, for example
 - -1 if a and b are nonspaces and $a = b$ (a match)
 - 1 if a and b are nonspaces $a \neq b$ (a mismatch)
 - 2 if one of a and b is a space (one space)
- Problem: Given two sequences, s and t , over the same alphabet, determine the optimal alignment with the minimum score, i.e., $score^*(s, t) = \min_{\forall A} \{score_A(s, t)\}$.
- Example: $s = \text{GACGGATTAG}$ and $t = \text{GATCGGAATAG}$ are two DNA sequences. For the following (optimal) alignment,

G	A	-	C	G	G	A	T	T	A	G
G	A	T	C	G	G	A	A	T	A	G

its score is $-9 + 1 + 2 = -6$.

- Let $score^*(s[1..i], t[1..j])$ be the minimum score of any alignment for sequences $s[1..i]$ and $t[1..j]$. Note $i = 0, \dots, |s|$ and $j = 0, \dots, |t|$. If $i = 0$ (or $j = 0$) then $s[1..i]$ (or $t[1..j]$) becomes the empty string.
- Three possibilities to align $s[1..i]$ and $t[1..j]$:
 - Align $s[1..i]$ with $t[1..j-1]$ and match a space with $t[j]$, or
 - Align $s[1..i-1]$ with $t[1..j-1]$ and match $s[i]$ with $t[j]$, or
 - Align $s[1..i-1]$ with $t[1..j]$ and match $s[i]$ with a space.
- A recursive definition of $score^*(s[1..i], t[1..j])$:
 - $score^*(\epsilon, \epsilon) = 0$
 - $score^*(s[1..i], \epsilon) = sspace * i$ for $i = 1, \dots, |s|$
 - $score^*(\epsilon, t[1..j]) = sspace * j$ for $j = 1, \dots, |t|$
 - $score^*(s[1..i], t[1..j]) = \min\{score^*(s[1..i], t[1..j-1]) + sspace, score^*(s[1..i-1], t[1..j-1]) + cij, score^*(s[1..i-1], t[1..j]) + sspace\}$

where $sspace$ is the score of a space opposite a nonspace, $smatch$ is the score of a match, and $smiss$ is the score of a mismatch. cij is $smatch$ if $s[i] = t[j]$ and is $smiss$ if $s[i] \neq t[j]$. Note that a space is never aligned against another space in the alignment of two sequences.

- A dynamic programming algorithm:

Algorithm: Optimal Pairwise Alignment

```

input: sequence s and t
output: score*(s, t) //Use table cell a[i, j] for score*(s[1..i], t[1..j])
m <- |s|
n <- |t|
a[0, 0] <- 0
for i <- 1 to m do
  a[i, 0] <- sspace * i
for j <- 1 to n do
  a[0, j] <- sspace * j
for i <- 1 to m do
  for j <- 1 to n do
    if s[i] = t[j] then cij <- smatch
    else cij <- smiss
    a[i, j] <- min {a[i, j-1] + sspace, a[i-1, j-1] + cij, a[i-1, j] + sspace}
return a[m, n]
```

- Example: $s = \text{AAAC}$ and $t = \text{AGC}$. Let $sspace = 2$, $smatch = -1$, and $smis = 1$. What is $score^*(s, t)$ and what is the optimal alignment for s and t (maybe more than one)?
- Time complexity: Computing $score^*(s, t)$ (constructing the table) takes $O(|s||t|)$ and constructing the optimal alignment once the table is given takes $O(|s| + |t|)$.
- A similar dynamic programming algorithm exists for aligning three or more DNA sequences.

6.7 Memory functions

Reading: CLRS 15.3

- Divide and conquer: Only needed entries are computed but some entries are computed more than once. Dynamic programming: All entries in the table are computed once, whether needed or not.
- A compromise: Only compute needed entries exactly once. To do so, we combine the recursive implementation with a table. Before we enter a recursion, we check the table to see whether the entry has been computed before. This method is called the memory function method.
- Example: Chained matrix multiplication revisited.

We first initialize all entries in table $m[1..n, 1..n]$ to be -1 , and then call $mf(1, n)$.

```

mf(i, j)
    if i = j return 0
    if m[i, j] ≠ -1 return m[i, j]
    c ← ∞
    for k ← i to j - 1
        c ← min{c, mf(i, k) + mf(k + 1, j) + pi-1pkpj}
    m[i, j] ← c
    return c

```

- The time complexity is no larger than that in the corresponding dynamic programming algorithm, but the space complexity will be more since recursion requires more space to implement.