Predicting Automobile Fuel Efficiency: A Bayesian Inference Approach

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The Problem

- Build a model to predict fuel efficiency of a vehicle using Bayesian inference
- Why is this useful?
 - Allows for less manual analysis of vehicle design (and thus less prototyping and testing)
 - Allows for easier business expense analysis



The Model

- MPG is a count per unit (i.e miles per gallon)
- Poisson distributions model these types of variables well
- Assumptions:
 - The predicted variable is a count per unit of time or space described by a Poisson distribution
 - The observations must be independent of each other
 - The mean and variance of a Poisson random variable must be equal
 - The log of the mean rate, $\log(\lambda)$, must be linear with respect to our feature variables x_i

$$f(k; \lambda) = \Pr(X = k) = \frac{\lambda^k e^{-\lambda}}{k!}$$

The Data

- Seven usable fields
 - Number of engine cylinders (discrete)
 - Displacement (summative volume of vehicle's cylinders; continuous)
 - Engine horsepower (continuous)
 - Vehicle weight (continuous)
 - Acceleration (continuous)
 - Model year (discrete)
 - Origin of the car (US, Europe, Japan; label-encoded, discrete)
- Predicting MPG rating (discrete, necessary for Poisson distribution)

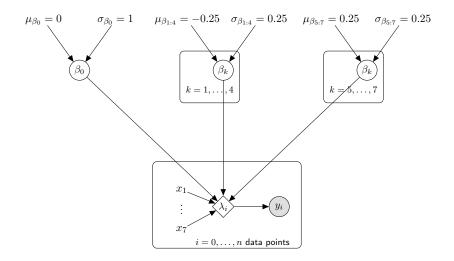
Poisson Regression

$$\log(\lambda_i) = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \dots + \beta_7 x_7$$

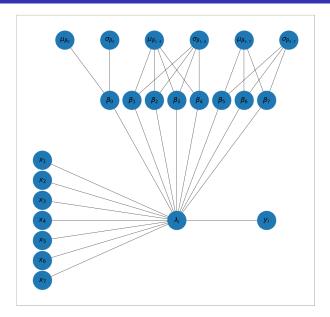
$$y_i \sim \mathsf{Poisson}(\lambda = \lambda_i)$$

$$\beta_k \sim \mathcal{N}(\mu_{\beta_k}, \sigma_{\beta_k}^2) \quad \text{for } k = 0, ..., 7$$

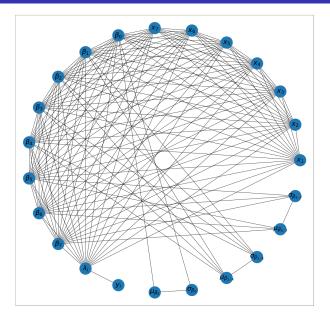
Belief Network (Plate Diagram)



Markov Network and Skeleton



Moralized and Triangulated Network



Joint Prior and Likelihood

Joint Prior:

$$\pi_0(\beta_k) \propto \frac{1}{\sigma_{\beta_k}^2 \sqrt{2\pi}} e^{-\frac{1}{2} \left(\frac{\beta_k - \mu_{\beta_k}}{\sigma_{\beta_k}^2}\right)^2}$$
$$\pi_0(\beta) \propto \prod_{k=0}^7 \pi_0(\beta_k)$$

Likelihood:

$$\pi(y \mid \beta) \propto \prod_{i=0}^{n} \frac{\lambda_{i}^{y_{i}} e^{-\lambda_{i}}}{y_{i}!}$$

$$\lambda_{i} = \exp(\beta_{0} + \beta_{1} x_{1}^{i} + \beta_{2} x_{2}^{i} + \dots + \beta_{7} x_{7}^{i})$$

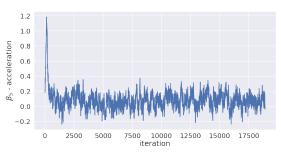
$$\pi(y \mid \beta) \propto \prod_{i=0}^{n} \frac{\exp(\beta_{0} + \beta_{1} x_{1}^{i} + \dots + \beta_{7} x_{7}^{i})^{y_{i}}}{\exp(\exp(\beta_{0} + \beta_{1} x_{1}^{i} + \dots + \beta_{7} x_{7}^{i}))y_{i}!}$$

Metropolis-Hastings Algorithm (MCMC)

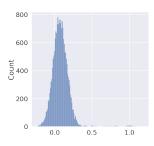
- This algorithm depends on the posterior being correctly proportional to the real posterior
- The assumptions we made earlier may be satisfied given that MPG is truly a Poisson distribution
 - mean = variance
- Possible improvements:
 - Negative binomial likelihood in place of the Poisson to capture dispersion
 - Quasi-likelihood

Metropolis-Hastings Algorithm (MCMC)

- 20/80 test-train split
- Ran for 100,000 iterations with a burn in of 25,000.
- Acceptance ratio of 23.317%

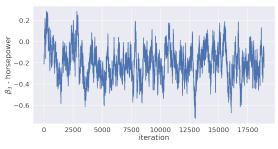


(a) Trace of acceleration parameter β_5 .

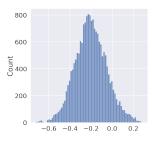


(b) Marginalization of acceleration parameter β_5 .

Metropolis-Hastings Algorithm (MCMC)



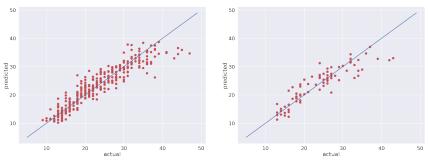
(a) Trace of horsepower parameter β_3 .



(b) Marginalization of horsepower parameter β_3 .

Results

- Train: $R^2 = 0.86758$, MSE = 8.327
- Test: $R^2 = 0.806$, MSE = 10.34



(a) Error in train set predictions.

(b) Error in test set predictions.

Figure 3: The error in both the train and test sets, points closer the x=y line are more accurate.