

VE281

Data Structures and Algorithms

AVL Trees and Midterm Review

Review

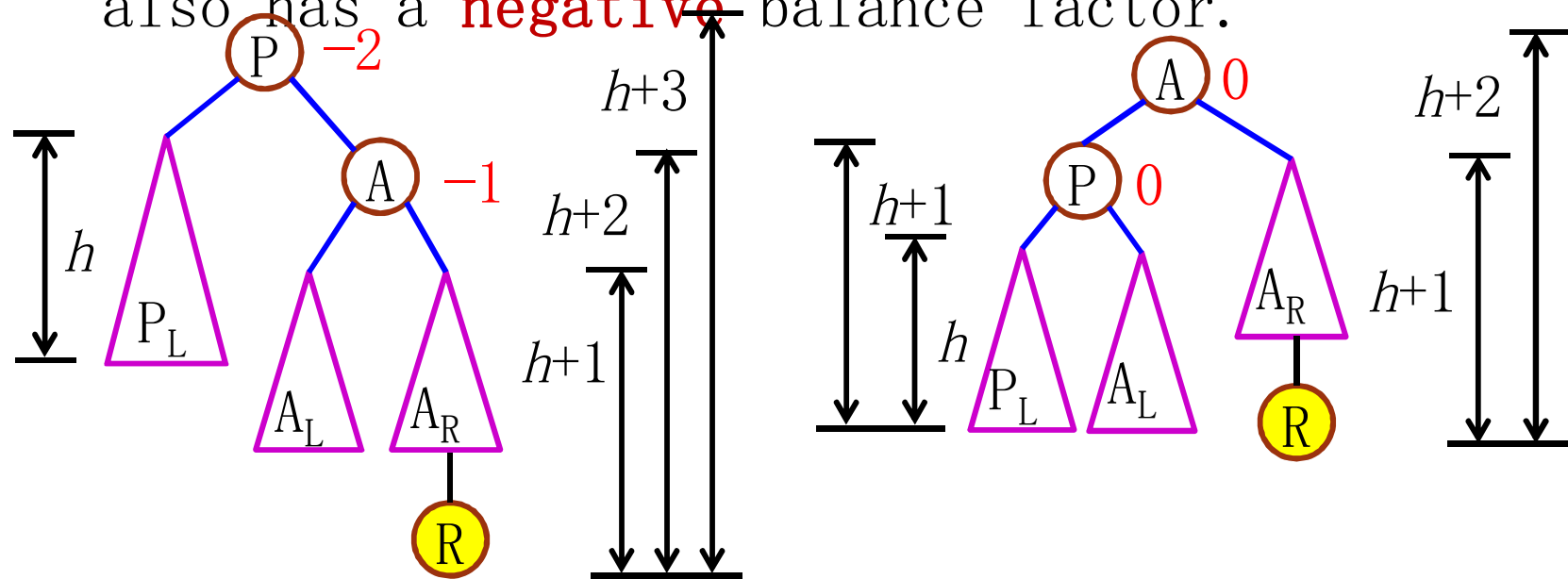
- Binary Search Trees
 - Binary search tree with **leftSize**
 - Rank search
 - Range search
- AVL Trees
 - Balance condition
 - Rotation
 - Balance factor
 - Left-left Insertion and left-left rotation

Outline

- AVL Trees
- Midterm Review

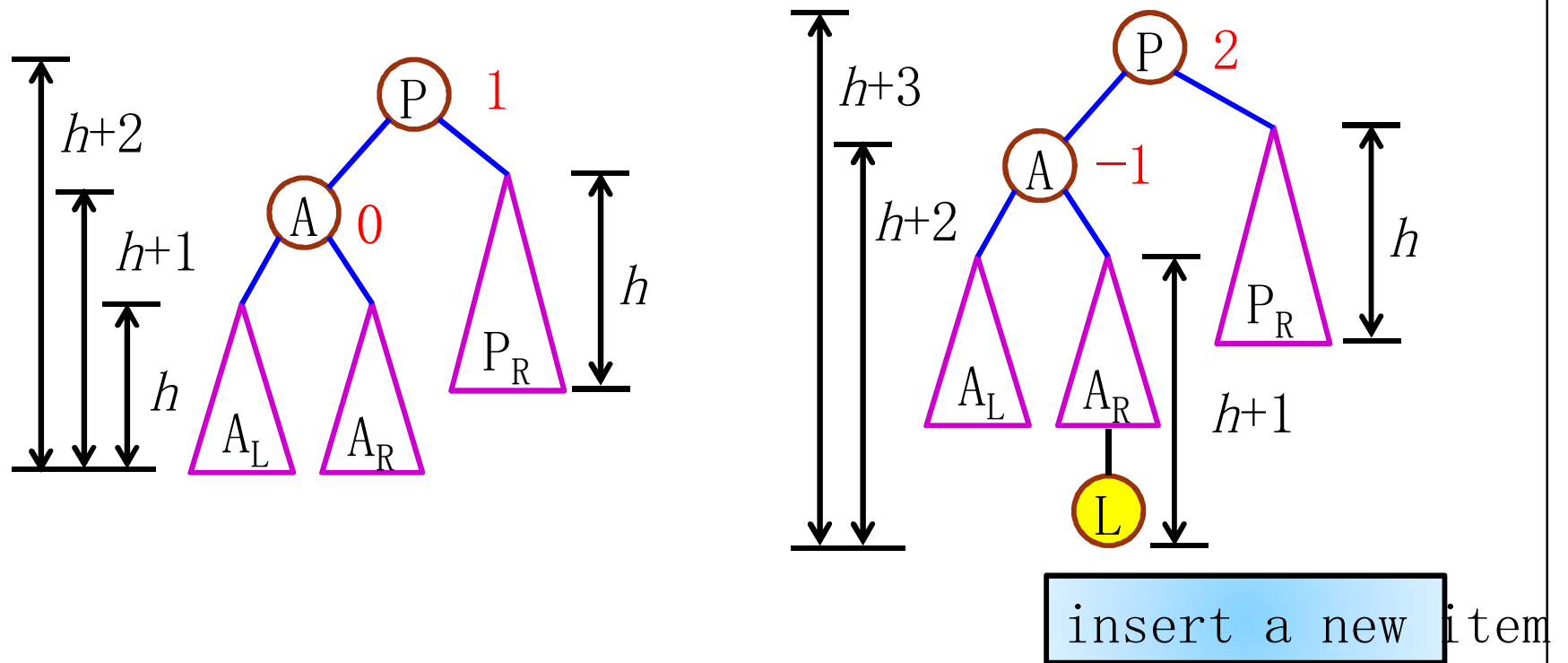
Right-Right (RR) Rotation

- Symmetric to left-left rotation.
- An RR rotation is called for when the node becomes unbalanced with a **negative** balance factor and the right subtree of the node also has a **negative** balance factor.



Breaking AVL Balance Condition

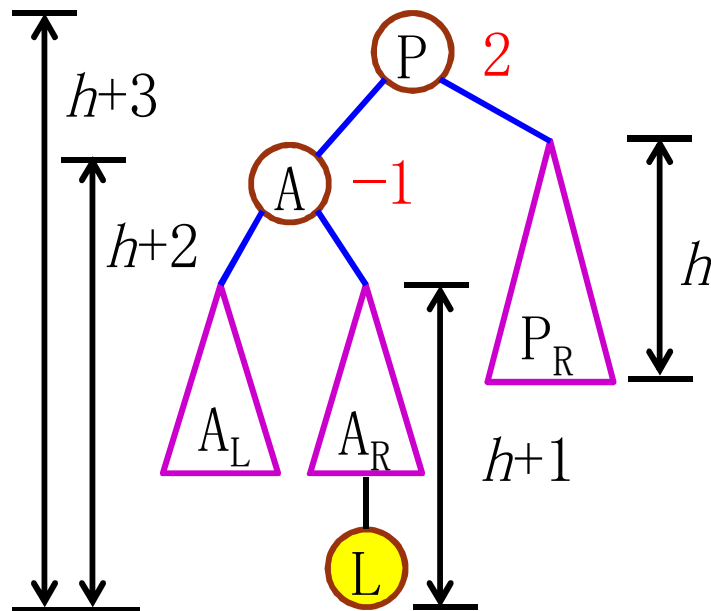
Left-Right Insertion



Left-right insertion: the first edge in the insertion path goes to the left and the second edge goes to the right.

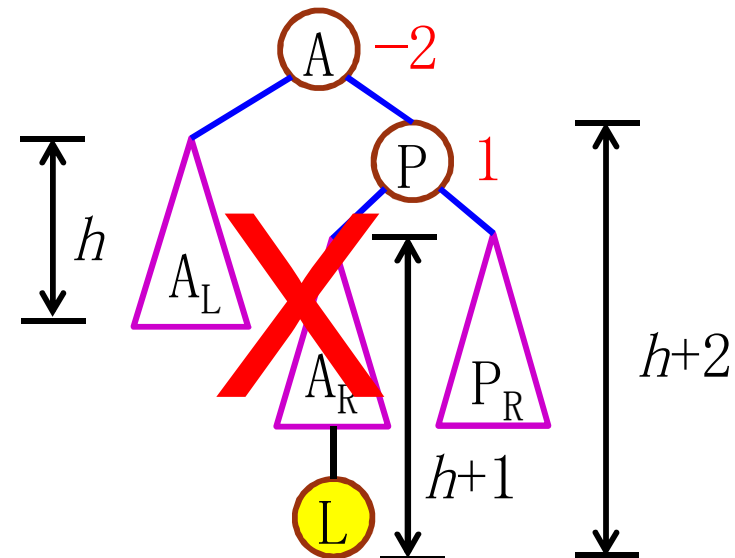
Restoring AVL Balance Condition

Left-Right Insertion

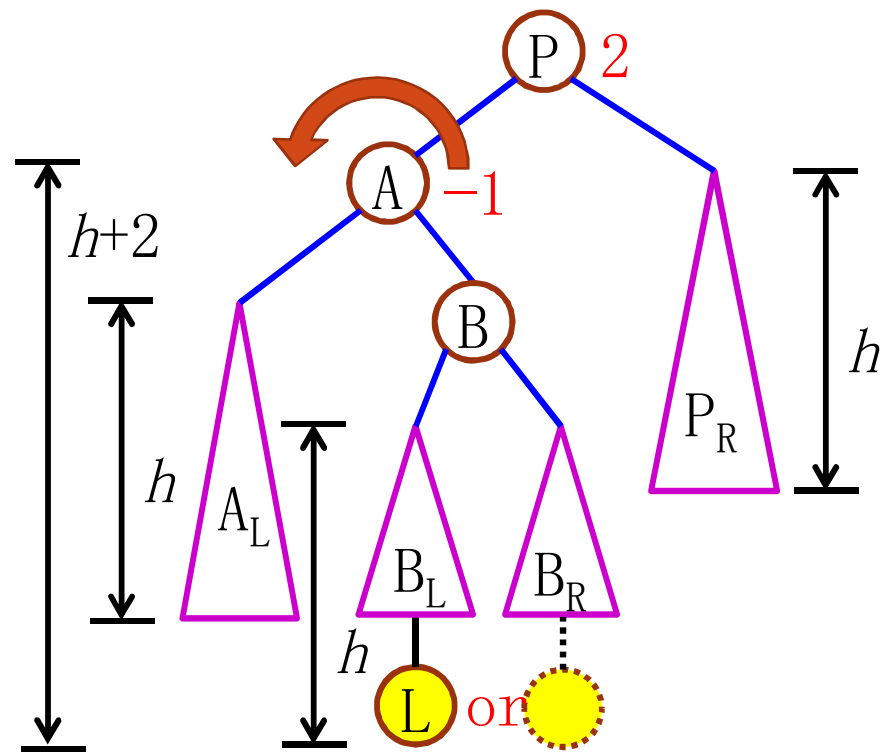


How to restore AVL balance?

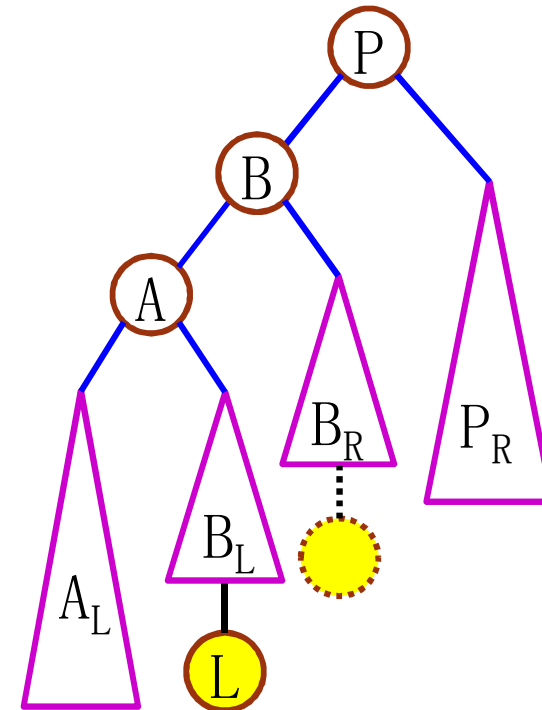
A right rotation at node P does not work!



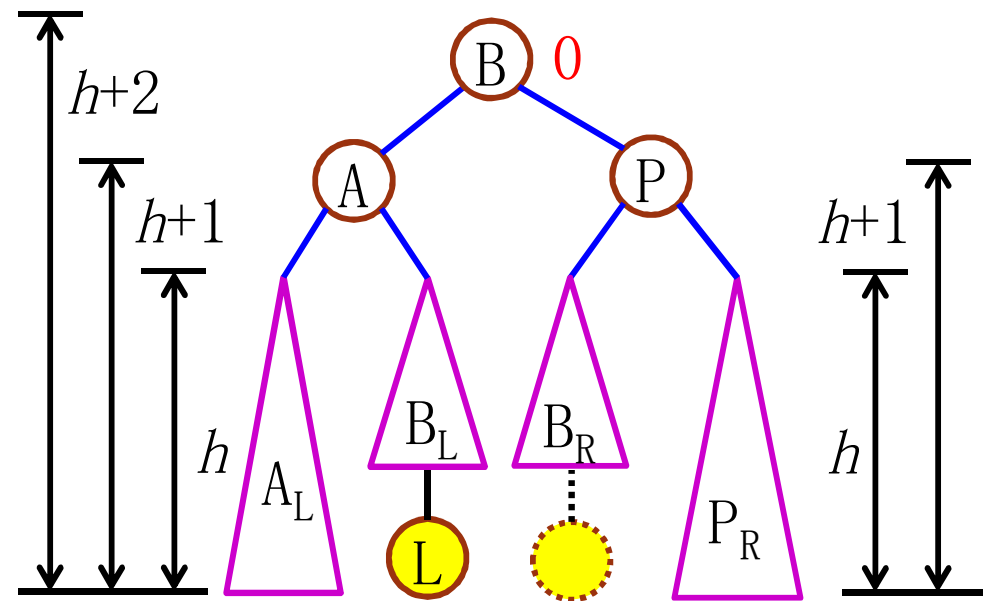
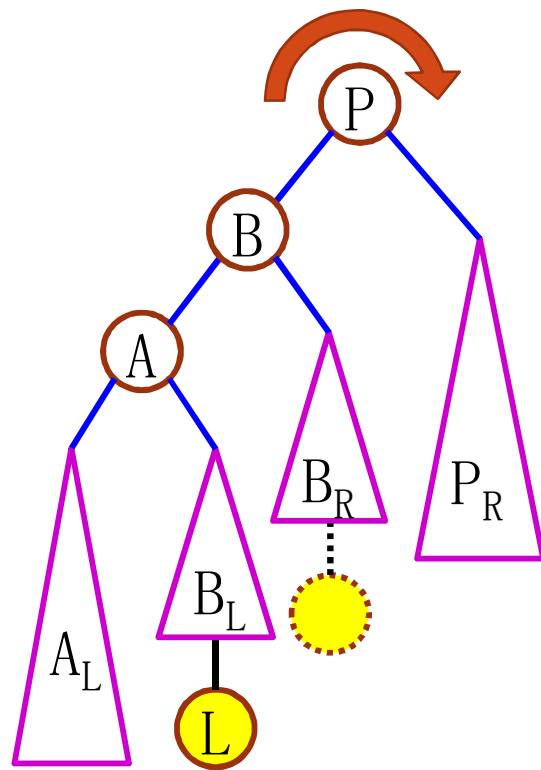
Left-Right (LR) Rotation



A **double rotation** to re-balance:
 Do a **left** rotation on node A
 then a **right** rotation on node P
 (next slide).

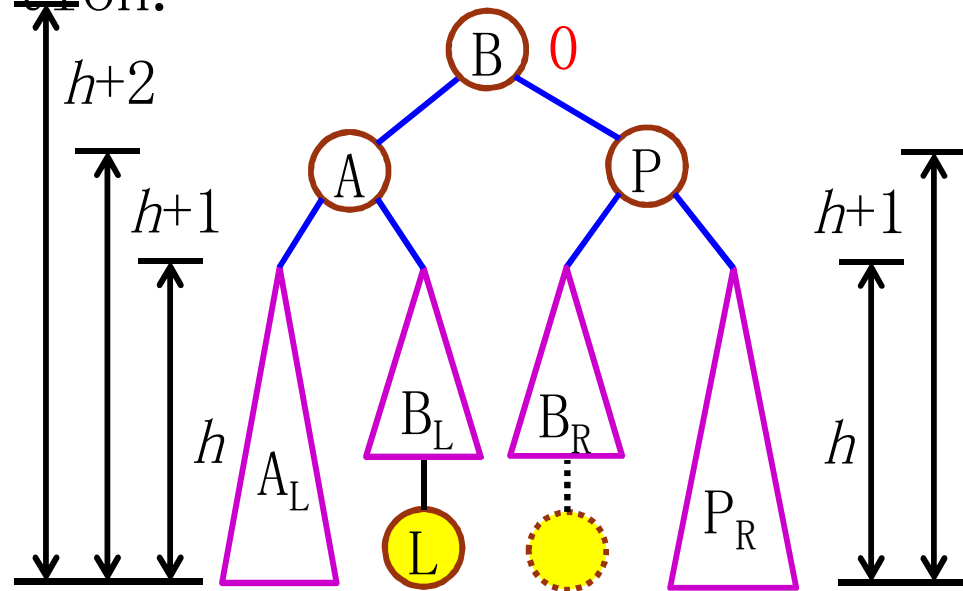


Left-Right (LR) Rotation



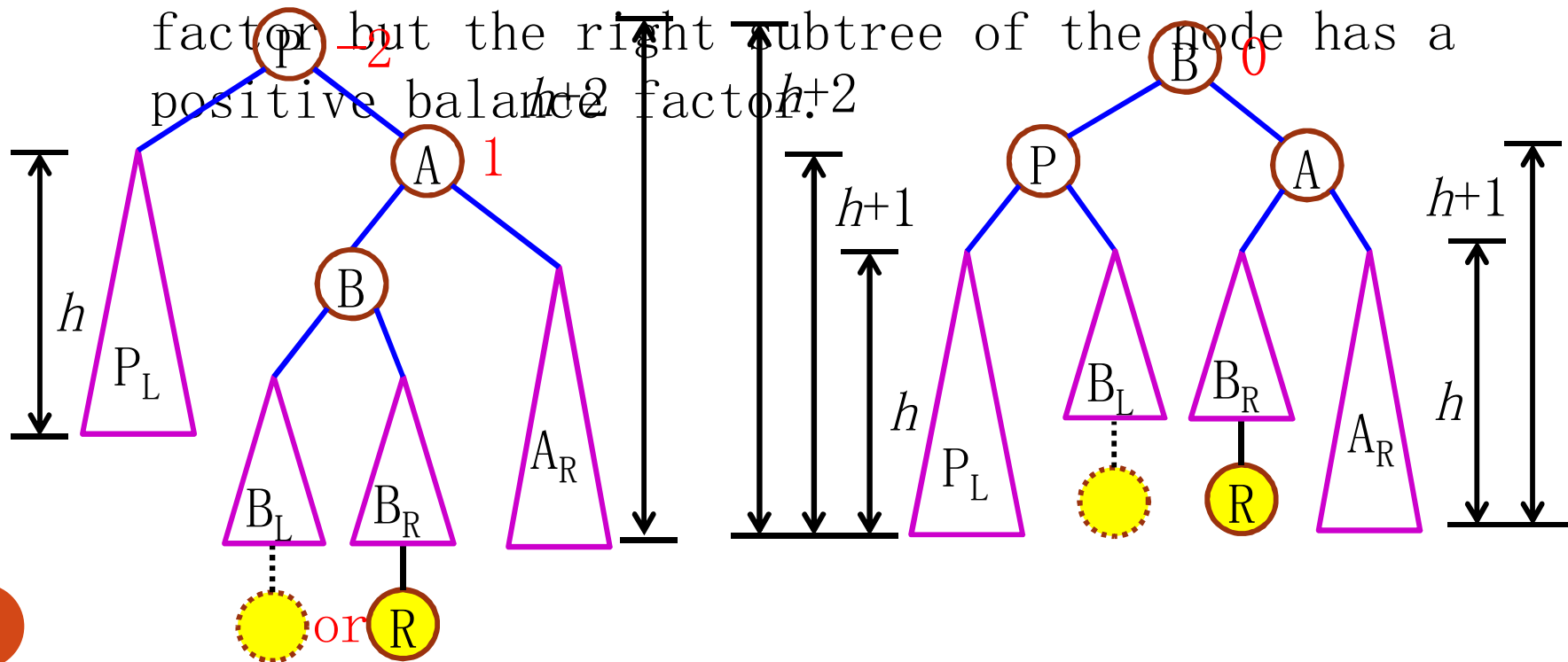
Properties of Left-Right Rotation

- The ordering property of BST is kept.
- Node B has a balance factor of 0.
- The height of the tree **after the rotation** is the same as the height of the tree before insertion.



Right-Left (RL) Rotation

- Symmetric to left-right rotation; also a double rotation.
- An RL rotation is called for when the node becomes unbalanced with a negative balance factor -2 but the right subtree of the node has a positive balance factor $+2$.

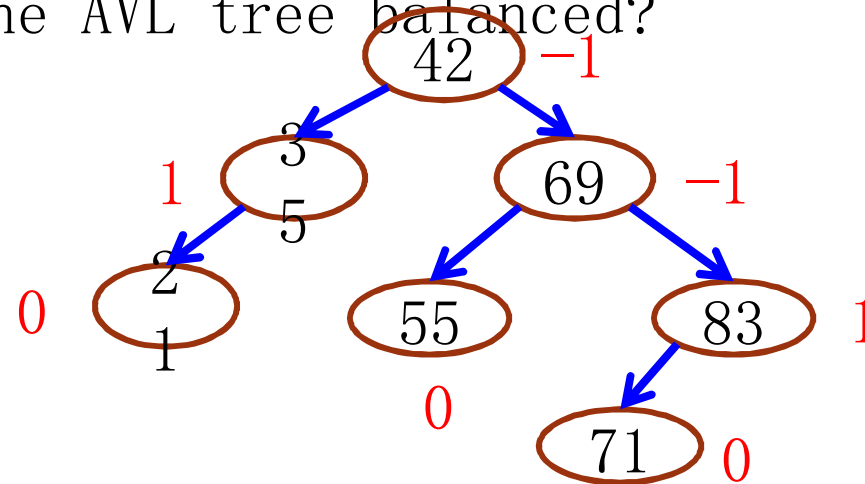


Rotation Summary

- When an AVL tree becomes unbalanced, there are four cases to consider depending on the **direction** of the first two edges on the insertion path. From the **unbalanced node**:
 - Left-left RR Rotation } single rotation
 - Right-right LR Rotation }
 - Left-right RL Rotation } double rotation
 - Right-left

Exercises

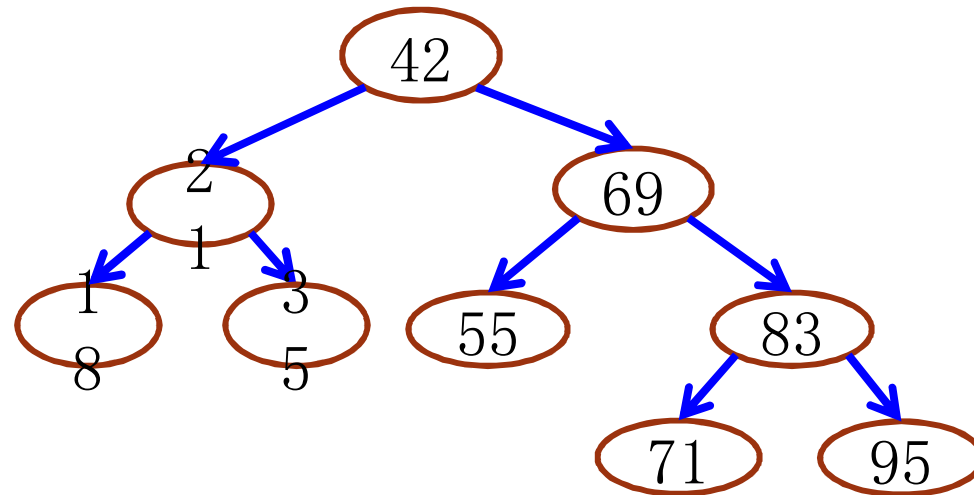
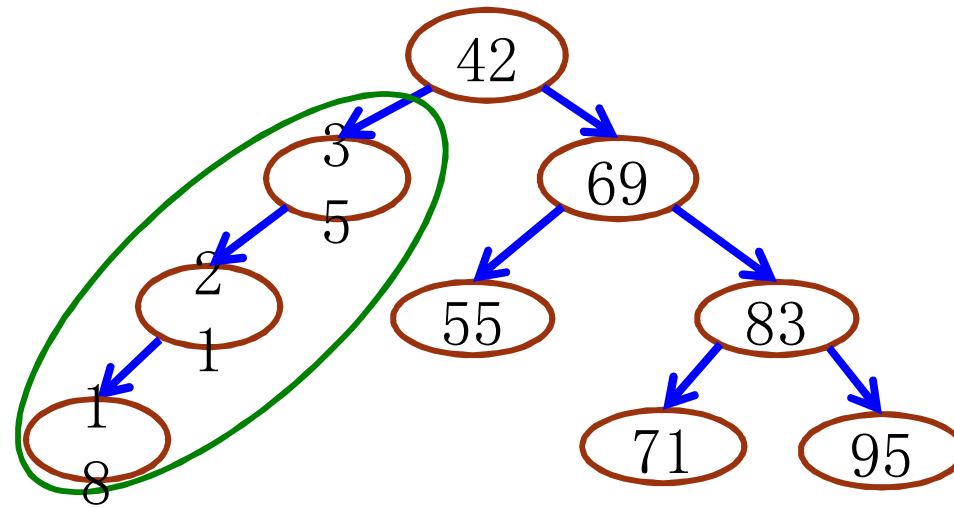
- Insert into an empty AVL tree: 42, 35, 69, 21, 55, 83, 71.
 - Compute the balance factors.
 - Is the AVL tree balanced?



- Insert 95, 18, 75?

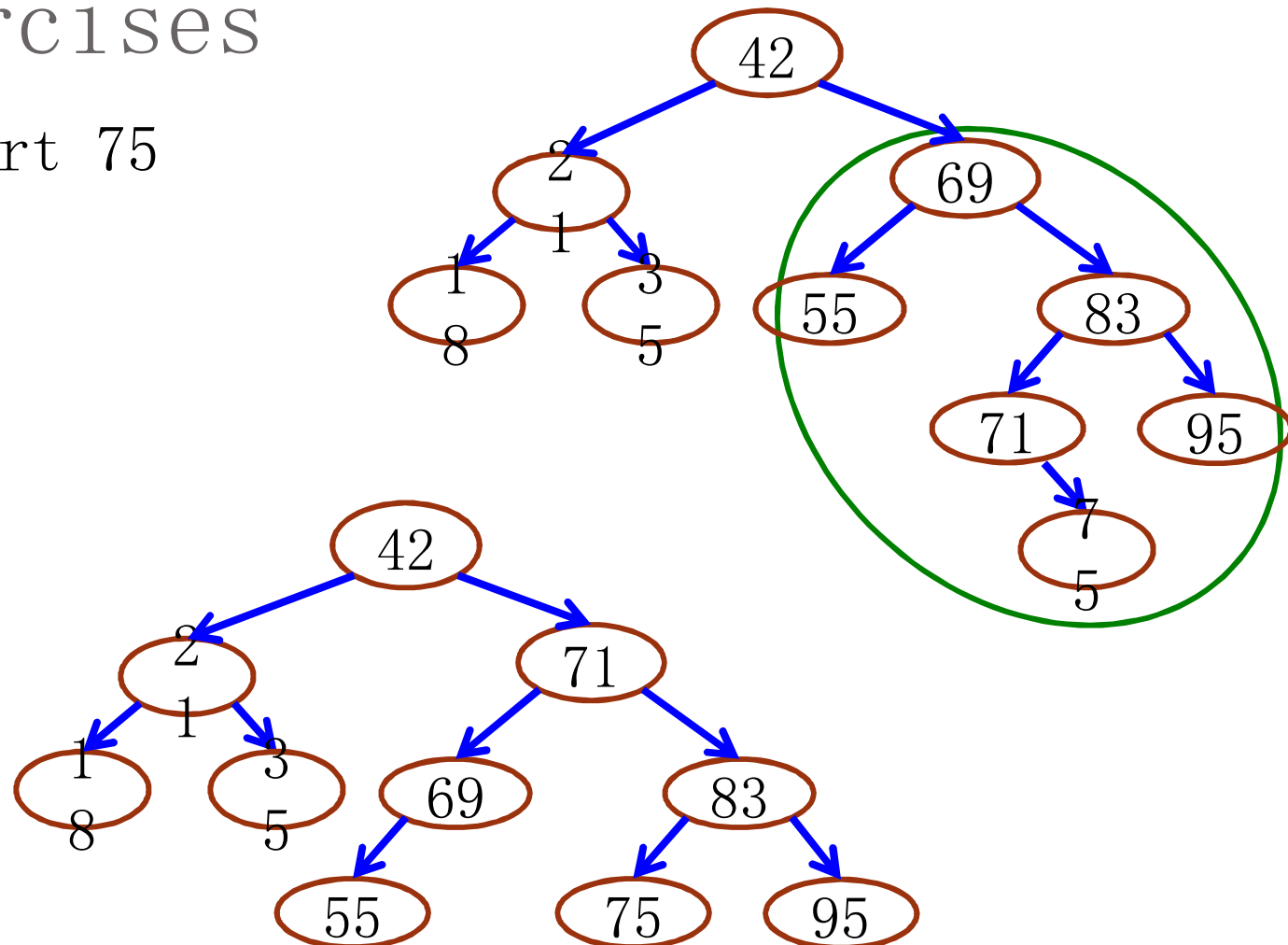
Exercises

- Insert 95, 18



Exercises

- Insert 75



The Number of Rotations Required

- When an AVL tree **becomes unbalanced after an insertion**, **exactly one** single or double rotation is required to balance the tree.
 - Before the insertion, the tree is balanced.
 - Only nodes on the access path of the insertion can be unbalanced. All other nodes are balanced.
 - We rotate at the first unbalanced node from the leaf.
 - By the properties of rotation, the height of the node after rotation is the same as that before insertion.
 - All ancestors of that node on the access path ~~should now be balanced~~

AVL Trees

Supporting Data Members and Functions

```
struct node {  
    Item item;  
    int height;  
    node *left;  
    node *right;  
};
```

```
int Height(node *n) {  
    if(!n) return -1;  
    return n->height;  
}
```

```
void AdjustHeight(node *n) {  
    if(!n) return;  
    n->height = max( Height(n->left),  
                    Height(n->right) ) + 1;  
}
```

```
int BalFactor(node *n) {  
    if(!n) return 0;  
    return (Height(n->left) -  
            Height(n->right));  
}
```


AVL Trees

Supporting Functions

```
void LLRotation(node *&n) ;
void RRRotation(node *&n) ;
void LRRotation(node *&n) ;
void RLRotation(node *&n) ;

void Balance(node *&n) {
    if(BalFactor(n) > 1) {
        if(BalFactor(n->left) > 0) LLRotation(n) ;
        else LRRotation(n) ;
    }
    else if(BalFactor(n) < -1) {
        if(BalFactor(n->right) < 0) RRRotation(n) ;
        else RLRotation(n) ;
    }
}
```

AVL Trees

Changes to Insertion

```
void insert(node *&root, Item item)
{
    if(root == NULL) {
        root = new node(item);
        return;
    }
    if(item.key < root->item.key)
        insert(root->left, item);
    else if(item.key > root->item.key)
        insert(root->right, item);

    AdjustHeight(root);
    Balance(root);
}
```

Removal

- First remove node as with BST
- Then update the balance factors of those ancestors in the access path and rebalance as needed.

Midterm Review

Logistics of Midterm Exam

- 10:00 am - 11:40 am, Thursday, November 8th, 2012
- Location: Dong Xia Yuan 200
- Written exam with 8 questions in total.
- Closed book and closed notes.
- No electronic devices are allowed.
 - These include laptops and cell phones.
 - We will show a clock on the screen.
- Abide by the **Honor Code**!

Topics in Midterm Exam

- Asymptotic Algorithm Analysis
- Linked lists
- Stacks and queues
- Hashing and hash tables
- Trees and binary trees
- Binary tree traversal
- Binary search trees
- AVL trees

Asymptotic Algorithm Analysis

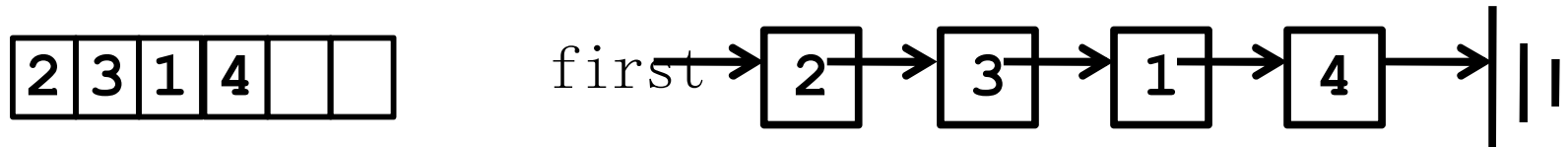
- Best, worst, and average cases
- Big-Oh, Big-Omega, and theta notations
 - Big-Oh: upper-bound
 - Big-Omega: lower-bound
- Common functions and their growth rates
 - $\log n, n, n \log n, n^k, 2^n, n!$
- Analyzing the time complexity of programs
 - Loop statement

Linked Lists

- Basic methods:
insertFirst()
removeFirst()
- Methods requiring **linked list traversal**:
getSize()
appendNode()
removeNode()

Arrays versus Linked Lists

Worst Case Time Complexity



	Array	Linked List
Random access	$O(1)$ time	$O(n)$ time
insertFirst	$O(n)$ time	$O(1)$ time
removeFirst	$O(n)$ time	$O(1)$ time
appendNode	$O(1)$ time	$O(n)$ time
removeNode	$O(n)$ time	$O(n)$ time

Linked List Optimization

• **appendNode ()**

- Double-ended singly-linked list

• **removeNode ()**

- Double-ended doubly-linked list
- How to reduce the time complexity to $O(1)$ with a singly-linked list?

- Reverse a linked list

Stacks

- A “pile” of objects where new object is put on **top** of the pile and the top object is removed first.
 - **LIFO** access: last in, first out.
- Methods: **push**, **pop**, **size**, etc.
- Implementations: arrays versus linked lists
- Applications
 - Web browser’ s “back” feature
 - Parentheses matching

Queues

- A “line” of items in which the **first** item inserted into the queue is the **first** one out.

- **FIFO** access: first in, first out

- Methods: **enqueue**, **dequeue**, **size**, etc.

- Implementations by linked lists

- Double-ended singly-linked list



- Implementations by arrays: circular array

- “circular” increment

- $$\text{front} = (\text{front} + 1) \% \text{MAXSIZE};$$

- Distinguish between an empty queue and a full queue



Queues

- Application: wire routing - lee' s algorithm
- Deque: combination of stack and queue

Dictionary

- A collection of pairs, each containing a **key** and an **element**

(key, element)

- Different pairs have different keys.
- Operations: search, insertion, and removal by keys.
- Implementations using arrays or linked lists.

Hashing and Hash Table

- Access table items by their keys in time that is relatively **constant** **regardless of their locations**.
- Main idea: use arithmetic operations, known as **hash function**, to transform keys into table locations.
 - The same key is always hashed to the **same** location.
 - Thus, **insert()** and **find()** are both directed to the same location in $O(1)$ time.
- **Hash table**: An array of **buckets**, where each bucket contains items as assigned by a hash

Hash Table Issues

- Choice of the hash function.
- Collision resolution scheme.
- Size of the hash table and rehashing.

Hash Functions

- Hash function (**$h(\text{key})$**) maps key to buckets in two steps:
 1. Convert key into an integer in case the key is not an integer.
 - A function **$t(\text{key})$** which returns an integer value, known as **hash code**.
 - How to map strings to integers?
 2. **Compression map**: Map an integer (hash code) into a home bucket.
 - A function **$c(\text{hashcode})$** which gives an integer in the range $[0, M-1]$, where M is the number of buckets in the table.
 - Compression mapping by modulo arithmetic: How to choose the divisor M ?

Collision and Collision Resolution

- Collision occurs when the hash function maps two or more items—all having **different** search keys—into the **same** bucket.
- **Collision-resolution scheme**: assigns distinct locations in the hash table to items involved in a collision.
- Two major schemes:
 - Separate chaining: Each bucket keeps a **linked list** of all items whose home buckets are that bucket.
 - Open addressing: Probe with a sequence of hash functions h_0, h_1, h_2, \dots

Open Addressing

- Linear probing:

$$h_i(\mathbf{x}) = (h(\mathbf{x}) + i) \% M$$

- **insert, find, remove**
- The problem of clustering

- Quadratic probing:

$$h_i(\mathbf{x}) = (h(\mathbf{x}) + i^2) \% M$$

- Double hashing:

$$h_i(\mathbf{x}) = (h(\mathbf{x}) + i * g(\mathbf{x})) \% M$$

Average Number of Comparisons

- Depends on the **load factor** $L = N/M$, where N is the number of items in the hash table and M is the size of the hash table.
- We analyze both the case of unsuccessful search ($U(L)$) and the case of successful search ($S(L)$).

Hash Table Size and Rehashing

- **Rehashing**: Create a larger table, scan the current table, and then insert items into new table using the new hash function.
 - We can approximately double the size of the current table.
 - The single operation of rehashing is time-consuming. However, it does not occur frequently.
- **Amortized analysis**: A method of analyzing algorithms that considers the entire sequence of operations of the program.
 - The cost is **averaged** over a sequence of operations.
 - Amortized analysis of rehashing: the average cost to insert $M + 1$ items is $O(1)$.

Trees

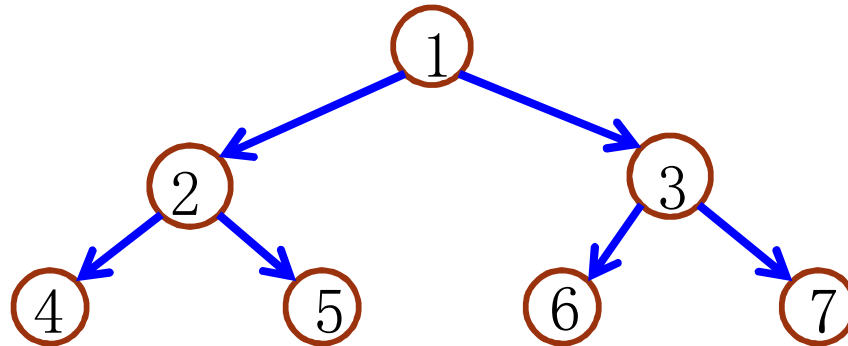
- Root, leaf, subtree, parent, child, sibling, path, ancestors, and descendants.
- Depth, height, level, degree of a node/tree

Binary Trees

- The relation between the number of nodes and the height

$$h + 1 \leq n \leq 2^{h+1} - 1$$

- **Proper**, **complete**, and **perfect** binary trees.
- Numbering nodes in a perfect binary tree.



- Representing a binary tree using linked structure.

```
struct node {  
    Item item;  
    node *left;  
    node *right;  
};
```

Binary Tree Traversal

- Depth-first traversal
 - Pre-order
 - Post-order
 - In-order
 - Implemented with recursion
 - Implemented with a stack
- Level order traversal
 - Implemented with a queue

Binary Search Trees

- A binary search tree (BST) is a binary tree with the following properties:
 - Each node is associated with a **key**. A key is a value that can be compared.
 - The key of any node is greater than the keys of all nodes in its left subtree and smaller than the keys of all nodes in its right tree.
- Operations
 - Search, insertion, and removal by keys.
 - Rank search
 - Range search

Binary Search Trees

Insertion and Removal

- Insertion
 - Insertion inserts the item **as a leaf** of the BST.
 - It inserts at a proper location in the BST, maintaining the BST properties.
- Removal
 - Node to be removed is a leaf: delete the node.
 - Node to be removed is a degree-one node:
“bypass” the node from its parent to its child.
 - Node to be removed is a degree-two node:
replace the node key with the largest key in the left subtree.

Average Case Time Complexity

- The average case time complexity for a **successful/unsuccessful** search with BST is $\Theta(\log n)$.

	Search	Insert/Remove
Linked List	$O(n)$	$O(n)$
Sorted Array	$O(\log n)$	$O(n)$
Hash Table (Separate Chaining)	$O(L)$	$O(L)$
BST	$O(\log n)$	$O(\log n)$

AVL Trees

- Motivation: the worst case time complexity for search/insertion/removal is still $O(\log n)$.
- Balance condition of AVL trees
 - A non-empty binary tree is **AVL balanced** if
 1. Both its left and right subtrees are AVL balanced, and
 2. The height of left and right subtrees differ by **at most 1**.
- Balance factor: $B_T = h_l - h_r$

Balance AVL Trees: Rotation

- When an AVL tree becomes unbalanced, there are four cases to consider depending on the **direction** of the first two edges on the insertion path. From the **unbalanced node**:
 - Left-left RR Rotation } single rotation
 - Right-right LR Rotation }
 - Left-right RL Rotation } double rotation
 - Right-left

Good Luck to Everyone

Questions?