Notes on GBStools algorithms

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1 Notations

Suppose there are N sites for n diploid individuals, and each site is composed of a restriction site with alleles $\{+, -\}$, and a SNP with alleles $\{A, a\}$. SNP alleles on the same haplotype as the '+' allele are sampled by GBS, but alleles on the same haplotype as the '-' allele are not. The '-' allele (and any 'A' or 'a' allele associated with it) cannot be observed directly, but can be observed indirectly because reduced sampling causes reduced sequencing coverage. Therefore let $\{A, a, -\}$ be the set of observable alleles, and let $\{AA, Aa, aa, A-, a-, --\}$ be the set of observable genotypes.

Let $\mathbf{G} = (\vec{G}_1, ..., \vec{G}_N)^{\mathsf{T}}$ be the observable genotypes with vector $\vec{G}_s = (\vec{G}_{s,1}, ..., \vec{G}_{s,n})$ representing the observable genotypes at site s, and $G_{s,i,1}, G_{s,i,2}, G_{s,i,3}$ representing the number of 'A', 'a', and '-' alleles for individual i. For convenience, we may drop the position subscript s when we are looking at only one locus. Let $\vec{\phi} = (\phi_1, \phi_2, \phi_3)$ be the site allele frequencies for the observable alleles.

Let $\mathbf{D} = (\vec{D_1},...,\vec{D_N})^{\intercal}$ be the data matrix with vector $\vec{D_s} = (\vec{D_{s,1}},...,\vec{D_{s,n}})$ representing the read data at site s. Let $\vec{d_s} = (|\vec{D_{s,1}}|,...,|\vec{D_{s,n}}|)$ be a vector of the number of reads for each sample. Let λ be the site mean coverage for samples with genotypes $\{(2,0,0),(1,1,0),(0,2,0)\}$ (i.e. for '++' samples).

Let $\mathbf{Z} = (\vec{Z}_1, ..., \vec{Z}_N)^{\intercal}$ be a matrix of variables indicating success (1) or failure (0) of the restriction digest, where $\vec{Z}_s = (Z_{s,1}, ..., Z_{s,n})$. If $Z_{s,i} = 0$, then $d_{s,i} = 0$ regardless of the genotype of the i-th sample. Let δ be the site failure rate.

2 Estimating the site allele frequency

We aim to find $\vec{\phi}$, λ , and δ that maximize $\Pr{\{\vec{D}|\vec{\phi},\lambda,\delta\}}$. We have:

$$\begin{split} \log \Pr\{\vec{D}, \vec{g}, \vec{z} | \vec{\phi}, \lambda, \delta\} &= \log \prod_{i=i}^n \Pr\{\vec{D}_i | g_i, d_i\} \Pr\{d_i | g_i, z_i, \lambda\} \Pr\{g_i | \vec{\phi}\} \Pr\{z_i | \delta\} \\ &= \log \prod_{i=i}^n \prod_{j=1}^{d_i} \Pr\{D_{i,j} | g_i\} \Pr\{d_i | g_i, z_i, \lambda\} \Pr\{g_i | \vec{\phi}\} \Pr\{z_i | \delta\} \end{split}$$

$$= C + \sum_{i=i}^{n} \log \Pr\{d_i|g_i, z_i, \lambda\} \Pr\{g_i|\vec{\phi}\} \Pr\{z_i|\delta\}$$

Let $m_i = 2 - g_{i,3}$ be the observable ploidy for the i-th individual (i.e. the number of '+' alleles it carries), and let $\vec{r} = (r_1, ..., r_n)$ be a vector of read count normalization factors, where

$$r_i = \frac{\sum_{s=1}^{N} d_{s,i}}{\frac{1}{n} \sum_{j=1}^{n} \sum_{s=1}^{N} d_{s,j}}$$

We assume that the sample read count, d_i follows a negative binomial distribution with mean $\mu = \lambda z_i r_i \frac{m_i}{2}$ and size parameter ψ :

$$\Pr\{d_i|g_i, z_i, \lambda\} = \frac{\Gamma(d_i + \psi)}{\Gamma(d_i + 1)\Gamma(\psi)} \left(\frac{\psi}{\lambda z_i r_i \frac{m_i}{2} + \psi}\right)^{\psi} \left(\frac{\lambda z_i r_i \frac{m_i}{2}}{\lambda z_i r_i \frac{m_i}{2} + \psi}\right)^{d_i}$$

Let $disp(\mu) = a\mu + 1$ be a function chosen to model the dispersion in the normalized read counts, $\vec{d} \circ \vec{r}$. The negative binomial variance is $\mu + \frac{\mu^2}{\psi}$. Therefore ψ is constant across all N sites and $\psi = \frac{1}{a}$.

We assume Hardy-Weinberg equilibrium for the observable genotypes:

$$\Pr\{G_i = g_i | \phi\} = {2 \choose g_{i,1}, g_{i,2}, g_{i,3}} \phi_1^{g_{i,1}} \phi_2^{g_{i,2}} \phi_3^{g_{i,3}}$$

And the probability of the digest success/failure state for the i-th individual is:

$$\Pr\{Z_i = z_i | \delta\} = (1 - \delta)^{z_i} \delta^{1 - z_i}$$

Given estimates $\vec{\phi_t}$, λ_t , δ_t at the t-th iteration, the $Q(\vec{\phi}, \lambda, \delta | \vec{\phi_t}, \lambda_t, \delta_t)$ function of EM is:

$$\begin{split} &Q(\vec{\phi},\lambda,\delta|\vec{\phi_t},\lambda_t,\delta_t) = \sum_{\vec{z}} \sum_{\vec{g}} \Pr\{\vec{g},\vec{z}|\vec{D},\vec{\phi_t},\lambda_t,\delta_t\} \log \Pr\{\vec{D},\vec{g},\vec{z}|\vec{\phi},\lambda,\delta\} \\ &= C + \sum_{\vec{z}} \sum_{\vec{g}} \prod_{i=1}^n \Pr\{g_i,z_i|\vec{D_i},\vec{\phi_t},\lambda_t,\delta_t\} \sum_{j} \log \Pr\{d_j|g_j,z_j,\lambda\} \Pr\{g_j|\vec{\phi}\} \Pr\{z_j|\delta\} \\ &= C + \sum_{i=1}^n \sum_{z_i=0}^1 \sum_{g_i} \Pr\{g_i,z_i|\vec{D_i},\vec{\phi_t},\lambda_t,\delta_t\} \log \Pr\{d_i|g_i,z_i,\lambda\} \Pr\{g_i|\vec{\phi}\} \Pr\{z_i|\delta\} \\ &= C' + \sum_{i=1}^n \sum_{z_i=0}^1 \sum_{g_i} \Pr\{g_i,z_i|\vec{D_i},\vec{\phi_t},\lambda_t,\delta_t\} \left[d_i\log(\lambda) - (d_i+\psi)\log(\lambda z_ir_i\frac{m_i}{2}+\psi) + g_{i,1}\log(\phi_1) + g_{i,2}\log(\phi_2) + g_{i,3}\log(\phi_3) + z_i\log(1-\delta) + (1-z_i)\log(\delta)\right] \end{split}$$

Thus

$$\begin{split} \frac{\partial Q}{\partial \phi_1} &= \sum_{i=1}^n \sum_{z_i=0}^1 \sum_{g_i} \Pr\{g_i, z_i | \vec{D}_i, \vec{\phi}_t, \lambda_t, \delta_t\} \frac{g_{i,1}}{\phi_1} \\ \frac{\partial Q}{\partial \phi_2} &= \sum_{i=1}^n \sum_{z_i=0}^1 \sum_{g_i} \Pr\{g_i, z_i | \vec{D}_i, \vec{\phi}_t, \lambda_t, \delta_t\} \frac{g_{i,2}}{\phi_2} \\ \frac{\partial Q}{\partial \phi_3} &= \sum_{i=1}^n \sum_{z_i=0}^1 \sum_{g_i} \Pr\{g_i, z_i | \vec{D}_i, \vec{\phi}_t, \lambda_t, \delta_t\} \frac{g_{i,3}}{\phi_3} \\ \frac{\partial Q}{\partial \delta} &= \sum_{i=1}^n \sum_{z_i=0}^1 \sum_{g_i} \Pr\{g_i, z_i | \vec{D}_i, \vec{\phi}_t, \lambda_t, \delta_t\} \left[\frac{1-z_i}{\delta} - \frac{z_i}{1-\delta} \right] \\ \frac{\partial Q}{\partial \lambda} &= \sum_{i=1}^n \sum_{z_i=0}^1 \sum_{g_i} \Pr\{g_i, z_i | \vec{D}_i, \vec{\phi}_t, \lambda_t, \delta_t\} \left[\frac{d_i}{\lambda} - \frac{z_i r_i \frac{m_i}{2} (d_i + \psi)}{\lambda z_i r_i \frac{m_i}{2} + \psi} \right] \end{split}$$

and using a first-order Taylor expansion about the point $\lambda = \lambda_t$

$$\frac{\partial Q}{\partial \lambda} \approx \sum_{i=1}^{n} \sum_{z_{i}=0}^{1} \sum_{g_{i}} \Pr\{g_{i}, z_{i} | \vec{D_{i}}, \vec{\phi_{t}}, \lambda_{t}, \delta_{t}\} \left[\frac{d_{i}}{\lambda_{t}} - \frac{z_{i} r_{i} \frac{m_{i}}{2} (d_{i} + \psi)}{\lambda_{t} z_{i} r_{i} \frac{m_{i}}{2} + \psi} \right] + (\lambda - \lambda_{t}) \sum_{i=1}^{n} \sum_{z_{i}=0}^{1} \sum_{g_{i}} \Pr\{g_{i}, z_{i} | \vec{D_{i}}, \vec{\phi_{t}}, \lambda_{t}, \delta_{t}\} \left[\frac{(z_{i} r_{i} \frac{m_{i}}{2})^{2} (d_{i} + \psi)}{(\lambda_{t} z_{i} r_{i} \frac{m_{i}}{2} + \psi)^{2}} - \frac{d_{i}}{\lambda_{t}^{2}} \right]$$

To calculate the updated parameter estimates we set each partial derivative equal to 0 and solve for ϕ_1 , ϕ_2 , ϕ_3 , λ , and δ . Because of the constraint $\phi_1 + \phi_2 + \phi_3 = 1$ we introduce a Lagrange multiplier:

$$\rho = \sum_{i=1}^{n} \sum_{z_i=0}^{1} \sum_{g_i} \Pr\{g_i, z_i | \vec{D}_i, \vec{\phi_t}, \lambda_t, \delta_t\} (g_{i,1} + g_{i,2} + g_{i,3}) = 2n$$

Thus

$$\phi_{1(t+1)} = \frac{1}{2n} \sum_{i=1}^{n} \sum_{z_i=0}^{1} \sum_{g_i} \Pr\{g_i, z_i | \vec{D_i}, \vec{\phi_t}, \lambda_t, \delta_t\} g_{i,1}$$

$$\phi_{2(t+1)} = \frac{1}{2n} \sum_{i=1}^{n} \sum_{z_i=0}^{1} \sum_{g_i} \Pr\{g_i, z_i | \vec{D_i}, \vec{\phi_t}, \lambda_t, \delta_t\} g_{i,2}$$

$$\phi_{3(t+1)} = \frac{1}{2n} \sum_{i=1}^{n} \sum_{z_i=0}^{1} \sum_{g_i} \Pr\{g_i, z_i | \vec{D_i}, \vec{\phi_t}, \lambda_t, \delta_t\} g_{i,3}$$

and

$$\delta_{t+1} = \frac{1}{n} \sum_{i=1}^{n} \sum_{z_{i}=0}^{1} \sum_{g_{i}} \Pr\{g_{i}, z_{i} | \vec{D_{i}}, \vec{\phi_{t}}, \lambda_{t}, \delta_{t}\} (1 - z_{i})$$

$$\lambda_{t+1} = \lambda_{t} - \frac{\sum_{i=1}^{n} \sum_{z_{i}=0}^{1} \sum_{g_{i}} \left[\frac{d_{i}}{\lambda_{t}} - \frac{z_{i} r_{i} \frac{m_{i}}{2} (d_{i} + \psi)}{z_{i} r_{i} \frac{m_{i}}{2} \lambda_{t} + \psi} \right] \Pr\{g_{i}, z_{i} | \vec{D_{i}}, \vec{\phi_{t}}, \lambda_{t}, \delta_{t}\}}{\sum_{i=1}^{n} \sum_{z_{i}=0}^{1} \sum_{g_{i}} \left[\frac{(z_{i} r_{i} \frac{m_{i}}{2})^{2} (d_{i} + \psi)}{(z_{i} r_{i} \frac{m_{i}}{2} \lambda_{t} + \psi)^{2}} - \frac{d_{i}}{\lambda_{t}^{2}} \right] \Pr\{g_{i}, z_{i} | \vec{D_{i}}, \vec{\phi_{t}}, \lambda_{t}, \delta_{t}\}}$$

thus

$$\phi_{1(t+1)} = \frac{1}{2n} \sum_{i=1}^{n} \frac{1}{C_i} \sum_{z_i=0}^{1} \sum_{g_i} g_{i,1} \Pr\{\vec{D}_i, g_i, z_i | \vec{\phi_t}, \lambda_t, \delta_t\}$$
(1)

$$\phi_{2(t+1)} = \frac{1}{2n} \sum_{i=1}^{n} \frac{1}{C_i} \sum_{z_i=0}^{1} \sum_{q_i} g_{i,2} \Pr\{\vec{D}_i, g_i, z_i | \vec{\phi_t}, \lambda_t, \delta_t\}$$
 (2)

$$\phi_{3(t+1)} = \frac{1}{2n} \sum_{i=1}^{n} \frac{1}{C_i} \sum_{z_i=0}^{1} \sum_{g_i} g_{i,3} \Pr\{\vec{D}_i, g_i, z_i | \vec{\phi}_t, \lambda_t, \delta_t\}$$
(3)

$$\delta_{t+1} = \frac{1}{n} \sum_{i=1}^{n} \frac{1}{C_i} \sum_{z_i=0}^{1} \sum_{g_i} (1 - z_i) \Pr\{\vec{D_i}, g_i, z_i | \vec{\phi_t}, \lambda_t, \delta_t\}$$
(4)

$$\lambda_{t+1} = \lambda_t - \frac{\sum_{i=1}^n \frac{1}{C_i} \sum_{z_i=0}^1 \sum_{g_i} \left[\frac{d_i}{\lambda_t} - \frac{z_i r_i \frac{m_i}{2} (d_i + \psi)}{z_i r_i \frac{m_i}{2} \lambda_t + \psi} \right] \Pr\{\vec{D}_i, g_i, z_i | \vec{\phi_t}, \lambda_t, \delta_t\}}{\sum_{i=1}^n \frac{1}{C_i} \sum_{z_i=0}^1 \sum_{g_i} \left[\frac{(z_i r_i \frac{m_i}{2})^2 (d_i + \psi)}{(z_i r_i \frac{m_i}{2} \lambda_t + \psi)^2} - \frac{d_i}{\lambda_t^2} \right] \Pr\{\vec{D}_i, g_i, z_i | \vec{\phi_t}, \lambda_t, \delta_t\}}$$
(5)

where

$$\Pr{\{\vec{D}_i, g_i, z_i | \vec{\phi_t}, \lambda_t, \delta_t\}} = \Pr{\{\vec{D}_i | g_i, d_i\}} \Pr{\{d_i | g_i, z_i, \lambda_t\}} \Pr{\{g_i | \vec{\phi_t}\}} \Pr{\{z_i | \delta_t\}}$$

and

$$C_i = \sum_{z_i=0}^{1} \sum_{q_i} \Pr{\{\vec{D}_i, g_i, z_i | \vec{\phi_t}, \lambda_t, \delta_t\}}$$

3 The distribution of site '-' allele count

At site a let \vec{X} be a vector of allele counts, where $X_1 = \sum_i G_{i,1}$ is the number of 'A' alleles, $X_2 = \sum_i G_{i,2}$ is the number of 'a' alleles, and $X_3 = \sum_i G_{i,3}$ is the number of '-' alleles. Define $Y = \sum_i 1 - Z_i$ to be the number of restriction digest failures. The probability that there are no '-' alleles segregating at the site will be our measure of GBS site quality. We aim to calculate

$$\Pr\{X_3 = 0 | \vec{D}, \Phi, \Delta\} = \frac{\sum_y \sum_{j,k} \Pr\{\vec{D} | \vec{X} = (j,k,0), y\} \Pr\{\vec{x} | \Phi\} \Pr\{y | \Delta\}}{\sum_y \sum_{j,k,l} \Pr\{\vec{D} | \vec{X} = (j,k,l), y\} \Pr\{\vec{x} | \Phi\} \Pr\{y | \Delta\}}$$
(6)

where Φ is the tri-allelic site frequency spectrum, Δ is the site digest failure spectrum. The likelihood can be re-written as

$$\Pr\{\vec{D}|\vec{x},y\} = \sum_{\vec{z}} \sum_{\vec{q}} \Pr\{\vec{D}|\vec{g},\vec{d}\} \Pr\{\vec{d}|\vec{g},\vec{z},\lambda(\vec{g},\vec{z})\} \Pr\{\vec{g}|\vec{x}\} \Pr\{\vec{z}|y\} I(\vec{x})$$

where λ depends on \vec{g} and \vec{z}

$$\lambda(\vec{g}, \vec{z}) = \frac{\sum_{i} d_{i} 2^{\mathbb{1}_{1}(g_{i,3})} / r_{i}}{n - \sum_{i} \mathbb{1}_{0}((2 - g_{i,3})(1 - z_{i}))}$$
(7)

and the indicator function $I(\vec{X})$ equals 1 if $\vec{X} = (j, k, l)$, and 0 otherwise. Assume that each of the possible configurations (\vec{g}, \vec{z}) is equally likely when \vec{x} and y are given (c.f. section 4.2.2 in [?]). Thus

$$\Pr{\{\vec{D}|\vec{x},y\}} = \sum_{\vec{z}} \sum_{\vec{g}} \prod_{i} \Pr{\{\vec{D}_{i}|g_{i},d_{i}\}} \Pr{\{d_{i}|g_{i},z_{i},\lambda(\vec{g},\vec{z})\}} \frac{\prod_{j} \binom{2}{g_{j,1},g_{j,2},g_{j,3}}}{\binom{2n}{k+l} \binom{n}{y}} I(\vec{x})$$

$$= \frac{1}{\binom{2n}{k+l}\binom{n}{y}} \sum_{\vec{z}} \sum_{\vec{g}} \prod_{i}^{n} \Pr\{\vec{D}_{i}|g_{i}, d_{i}\} \Pr\{d_{i}|g_{i}, z_{i}, \lambda(\vec{g}, \vec{z})\} \binom{2}{g_{j,1}, g_{j,2}, g_{j,3}} I(\vec{x})$$
(8)

Direct evaluation of Eq. (??) is made difficult by the dependence of λ on \vec{g} and \vec{z} , and because there are potentially 12^n combinations of genotypes and digest failure states (\vec{g}, \vec{z}) . The numerator in Eq. (??) can be approximated, however, by the probability of the most likely configuration of \vec{x} , y, \vec{z} and \vec{g} , given $x_3 = 0$. The denominator in Eq. (??) can likewise be approximated by a sum over l of the probability of the most likely configuration given $x_3 = l$. We use a best-first search algorithm to find these configurations [?]. We define the initial configuration in the search to be $\vec{g} = ((2,0,0),...,(2,0,0))$ and $\vec{z} = (1,...,1)$.

Algorithm 1 Best-first search for most likely (\vec{z}, \vec{q})

- 1: **function** Selectronfig (C_{x_3}, l)
- 2: If l is unspecified, choose one individual, i, and add 1 to $g_{i,2}$, $g_{i,3}$ or z_i , and return the new configuration (\vec{g}, \vec{z}) . To choose the best individual and configuration calculate the new likelihood after each possible increment according to Eq. $(\ref{eq:configuration})$, multiply by the priors for \vec{x} and y, and select the most probable one. If l is specified, perform the same function, but do not increment $g_{i,3}$ (i.e. do not change the number of '-' alleles).
- 3: end function

end while

24: end procedure

23:

```
4: procedure BestFirstSearch((\vec{q}, \vec{z}), l)
              \vec{x} \leftarrow (\sum_{i=1}^{n} g_{i,1}, \sum_{i=1}^{n} g_{i,2}, \sum_{i=1}^{n} g_{i,3})
                                                                                                                                        ▶ Allele counts
              y \leftarrow \sum_{i=1}^{n} z_i
  6:
                                                                                                                       ▷ Digest failure counts
               \lambda \leftarrow \lambda(\vec{q}, \vec{z})
                                                                                                                                          See Eq (??)
  7:
              C_{x_3} \leftarrow (\vec{g}, \vec{z})
                                                                                                       \triangleright Best configuration, given x_3
  8:
              M_{x_3} \leftarrow \sum_{i=1}^n \ell(\vec{D}_i, g_i, z_i | \vec{x}, y; \lambda) + \log \Pr{\{\vec{x} | \Phi\}} \Pr{\{y | \Delta\}}
                                                                                                                                                       ⊳ log of
       likelihood times prior for configuration C_{x_3}
               while x_1 > 0 do
10:
                      (\vec{g}, \vec{z}) \leftarrow \text{Selectconfig}(C_{x_3}, l)
11:
                      \lambda \leftarrow \lambda(\vec{g}, \vec{z})
                                                                                                                                                \triangleright update \lambda
12:
                     \begin{split} y &\leftarrow \sum_{i=1}^{n} z_{i} \\ \vec{x'} &\leftarrow (\sum_{i=1}^{n} g_{i,1}, \sum_{i=1}^{n} g_{i,2}, \sum_{i=1}^{n} g_{i,3}) \\ M' &\leftarrow \sum_{i=1}^{n} \ell(\vec{D}_{i}, g_{i}, z_{i} | \vec{x'}, y; \lambda) + \log \Pr\{\vec{x'} | \Phi\} \Pr\{y | \Delta\} \end{split}
13:
14:
15:
                      if M' > M_{x_3} then
16:
                             \vec{x} \leftarrow \vec{x'}
17:
                             C_{x_3} \leftarrow (\vec{g}, \vec{z})
18:
                             M_{x_3} \leftarrow M'
19:
20:
                      else
                             return (C_{x_3}, M_{x_3})
21:
                      end if
22:
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References

- [1] Li H. Mathematical notes on SAMtools algorithms. www.broadinstitute.org/gatk/media/docs/Samtools.pdf
- [2] DePristo M.A. *et al.* A framework for variation discovery and genotyping using next-generation DNA sequence data. *Nature Genetics* 43, 491-498 (2011).