

# COMS30017

## *Computational Neuroscience*

Week 7 / Video 1 / Supervised learning using the delta rule

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# Intended Learning Outcomes

- Definition and intuition behind delta-rule
- Formal derivation as error-minimization

# The delta rule: definitions

- inputs:  $x_i$
- (synaptic) weights:  $w_i$
- output:  $y = \sum_i w_i x_i$
- "target" or optimal output:  $y^*$
- delta, or error  $\delta = y^* - y$
- learning rate,  $\eta$
- weight update:

$$\Delta w_\alpha = \eta \delta x_\alpha$$

# The delta rule: intuitions

- $y = \sum_i w_i x_i$
- $\delta = y^* - y$
- $\Delta w_i = \eta \delta x_i$
- If output is too low,  $y < y^*$ , then  $0 < \delta$  and (assuming inputs,  $x_i$ , are positive),  $0 < \Delta w_i$ , so next time output,  $y$ , is higher.
- Note that we only update the weights corresponding to inputs that were on. If the inputs were off,  $x_i = 0$ , then  $\Delta w_i = 0$

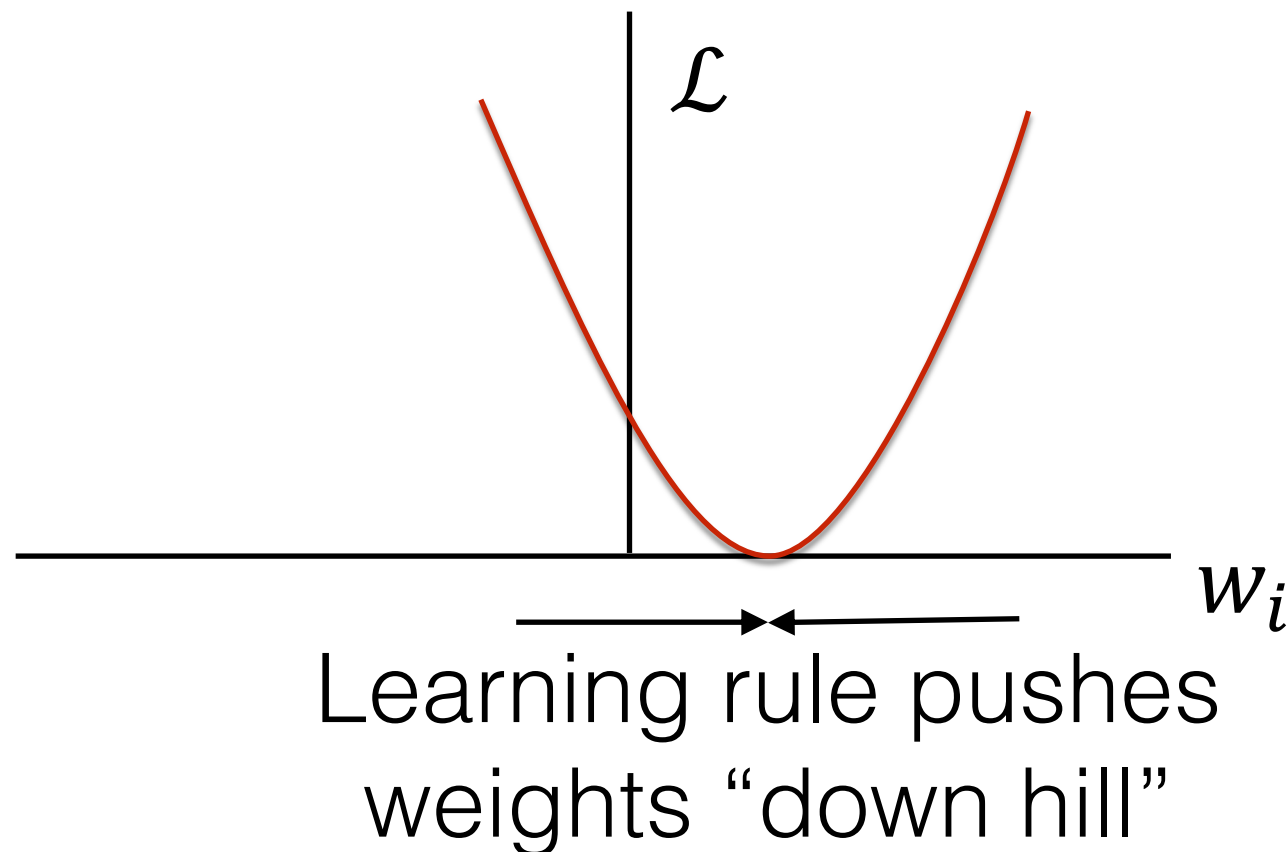
# The delta rule: example

- two inputs,  $x_1 = 0, x_2 = 1$ .
- initialize weights to one,  $w_1 = 1, w_2 = 1$
- output  $y = w_1 \times x_1 + w_2 \times x_2 = 1$
- target,  $y^* = 3$
- delta,  $\delta = y^* - y = 3 - 1 = 2$
- learning rate,  $\eta = 0.1$
- weight updates:
$$\Delta w_1 = \eta \delta x_1 = 0.1 \times 2 \times 0 = 0$$
$$\Delta w_2 = \eta \delta x_2 = 0.1 \times 2 \times 1 = 0.2$$
- final weights,  $w_1 = 1, w_2 = 1.2$
- so next time,  $y = w_1 \times x_1 + w_2 \times x_2 = 1.2$  is closer to the target

# The delta rule: derivation (1/3)

- define a "loss" function, the squared error between the target and output,

$$\mathcal{L} = \frac{1}{2}(y^* - y)^2 = \frac{1}{2} \left( y^* - \sum_i w_i x_i \right)^2 .$$



# The delta rule: derivation (2/3)

- By the definition of the loss,

$$\frac{\partial \mathcal{L}}{\partial w_\alpha} = \frac{1}{2} \frac{\partial}{\partial w_\alpha} \left( y^* - \sum_i w_i x_i \right)^2$$

- Applying the chain rule,

$$\frac{\partial \mathcal{L}}{\partial w_\alpha} = \left( y^* - \sum_i w_i x_i \right) \frac{\partial}{\partial w_\alpha} \left( y^* - \sum_i w_i x_i \right)$$

Noting that the gradient of  $y$ ,  $x_i$  and  $w_{\{i \neq \alpha\}}$  are all zero,

$$\frac{\partial \mathcal{L}}{\partial w_\alpha} = \left( y^* - \sum_i w_i x_i \right) \frac{\partial}{\partial w_\alpha} (-w_\alpha x_\alpha)$$

$$\frac{\partial \mathcal{L}}{\partial w_\alpha} = \left( y^* - \sum_i w_i x_i \right) (-x_\alpha)$$

$$\frac{\partial \mathcal{L}}{\partial w_\alpha} = -\delta x_\alpha$$

# The delta rule: derivation (3/3)

To go downhill a bit, we need:

$$\Delta w_{\alpha} = -\eta \frac{\partial \mathcal{L}}{\partial w_{\alpha}}$$

(note the gradient points up hill, so we use minus the gradient to go downhill).

Substituting the gradient from the previous slide, we get back the delta rule,

$$\Delta w_{\alpha} = \eta \delta x_{\alpha}$$



End