

Opencv简单操作

```
In [5]: #我们会用4.4版本的opencv  
import cv2  
print(cv2.__version__)
```

4.4.0

```
In [6]: # 读取image
image = cv2.imread('test.jpg')

#python中的image数据为三维数组, 为长, 宽, channel, 一般情况下第三维度的3是rgb value
display(image.shape)
image
```

```
(253, 199, 3)
```

```
Out[6]: array([[ [ 10, 11, 0],
                  [ 79, 72, 55],
                  [172, 147, 167],
                  ...,
                  [ 59, 102, 123],
                  [ 57, 100, 121],
                  [ 66, 107, 129]],

                [ [ 12, 11, 0],
                  [ 30, 21, 12],
                  [123, 96, 122],
                  ...,
                  [ 58, 101, 122],
                  [ 57, 100, 121],
                  [ 66, 107, 129]],

                [ [ 21, 15, 4],
                  [ 11, 0, 3],
                  [ 77, 45, 86],
                  ...,
                  [ 58, 101, 122],
                  [ 57, 100, 121],
                  [ 66, 107, 129]],

                ...,

                [ [ 4, 2, 2],
                  [ 4, 2, 2],
                  [ 3, 1, 1],
                  ...,
                  [ 10, 8, 8],
                  [ 10, 8, 8],
                  [ 11, 9, 9]],

                [ [ 4, 2, 2],
                  [ 4, 2, 2],
                  [ 3, 1, 1],
                  ...,
                  [ 10, 8, 8],
                  [ 10, 8, 8],
                  [ 11, 9, 9]],

                [ [ 4, 2, 2],
                  [ 4, 2, 2],
                  [ 3, 1, 1],
                  ...,
                  [ 10, 8, 8],
```

```
[ 10,  8,  8],  
[ 11,  9,  9]], dtype=uint8)
```

```
In [7]: # 读取后默认储存是bgr 不是rgb, which只是rgb的reverse反过来了, 所以如果查看这个image会  
import matplotlib.pyplot as plt  
plt.imshow(image)
```

```
Out[7]: <matplotlib.image.AxesImage at 0x1ac7bcff470>
```

```
In [8]: # 解决方式很简单, 把dimension 3 reverse一下就好了  
plt.imshow(image[:, :, ::-1])  
  
plt.axis('off') # 撤销坐标轴
```

```
Out[8]: (-0.5, 198.5, 252.5, -0.5)
```



```
In [9]: # 图像的灰度转化  
gray = cv2.cvtColor(image, cv2.COLOR_BGR2GRAY)  
plt.imshow(gray, cmap='gray') # 这里cmap需要标注gray, 不然会出现很奇怪的图像, 具体原  
#的颜色不是黑白灰, 所以需要标注cmap, 不是很重要的细节, 但是有兴趣的可以自己探索, 试试其  
plt.axis('off')
```

```
Out[9]: (-0.5, 198.5, 252.5, -0.5)
```



人脸特征点提取

```
In [16]: # 虽然听上去很高大上, 但是opencv已有自带的人脸特征点提取函数, 运用起来十分方便简单
# 算法原理和源码感兴趣的可以私聊, 或者看这两个链接https://docs.opencv.org/3.4/db/d28/
# https://medium.com/@soumyapatilblogs/face-and-eyes-detection-using-opencv-9fca

# 各个detection的xml file可以从https://github.com/anaustinbeing/haar-cascade-files

face_cascade = cv2.CascadeClassifier('haar/haarcascade_frontalface_default.xml')
faces = face_cascade.detectMultiScale(gray, 1.1, 4)
# 用classifier识别, documentation: https://www.bogotobogo.com/python/OpenCV_Pyth
# documentation https://docs.opencv.org/3.4/d1/de5/classcv_1_1CascadeClassifier.html
# return一个正方形的左上放的点, 和宽和长

#根据数据画出检测到的人脸
for (x, y, w, h) in faces:
    cv2.rectangle(image, (x, y), (x+w, y+h), (255, 0, 0), 2)
plt.imshow(image)
plt.axis('off')
```

Out[16]: (-0.5, 198.5, 252.5, -0.5)



人脸特征点提取

我们将会用两种library实现特征点提取

1.opencv <https://medium.com/analytics-vidhya/facial-landmarks-and-face-detection-in-python-with-opencv-73979391f30e> (<https://medium.com/analytics-vidhya/facial-landmarks-and-face-detection-in-python-with-opencv-73979391f30e>)

如果是用4.4.2的opencv会提示cv2.cv2.face不存在, 如果想要使用这个教程里的方法, 需要把opencv降回4.1.2并且安装opencv-contrib-python

2.dlib <https://towardsdatascience.com/detecting-face-features-with-python-30385aee4a8e> (<https://towardsdatascience.com/detecting-face-features-with-python-30385aee4a8e>)

这个notebook只会演示dlib的码

```
In [ ]: #!conda install -c conda-forge
```

模型文件可以从这里下载<https://github.com/italojs/facial-landmarks-recognition>
(<https://github.com/italojs/facial-landmarks-recognition>)

演示中用的shape_predictor_68_face_landmarks.dat已在当前dir中

```
In [3]: import dlib
detector = dlib.get_frontal_face_detector() #跟opencv的haar作用一样, 用来检测人脸
predictor = dlib.shape_predictor("shape_predictor_68_face_landmarks.dat") # 创立p
# documentation http://dlib.net/python/index.html#dlib.shape_predictor
```

```
In [24]: image = cv2.imread('test.jpg') #读取图像
gray = cv2.cvtColor(image, cv2.COLOR_BGR2GRAY) #转成灰度文件
faces = detector(gray) #这里之所以用dlib的而不是opencv之前的haar是因为predictor需要
#为了方便所以用dlib的face detection函数, 不过我们也是可以用opencv的, 然后在转化
landmarks = predictor(image=gray, box=faces[0]) #传入模型得到结果
x = landmarks.part(27).x
y = landmarks.part(27).y
# 画出所有特征点
for n in range(0, 68):
    x = landmarks.part(n).x
    y = landmarks.part(n).y
    cv2.circle(img=image, center=(x, y), radius=1, color=(0, 255, 0), thickness=
plt.axis('off')
plt.imshow(image)
```

```
Out[24]: <matplotlib.image.AxesImage at 0x1ac0c273908>
```



在我们这次的proj中, 我们关注的是这68个特征点中的眼睛的特征点, 模型思路大概是实时计算上下眼睑的pixel距离, 设立阈值来监控疲劳值

```
In [ ]:
```

