

OpenModelica Course Intermediate Modelica.Fluid library description

Appendix 1. Pipe pressure loss and mass flow

Appendix 2. Partial Vessel pressure calculation formula

December 7, 2017 Shu Tanaka (Amane Ryuken Co., Ltd.)

Appendix 1. Pipe pressure loss and mass flow

(1) Overview

(2) Parameters that classify the calculation method

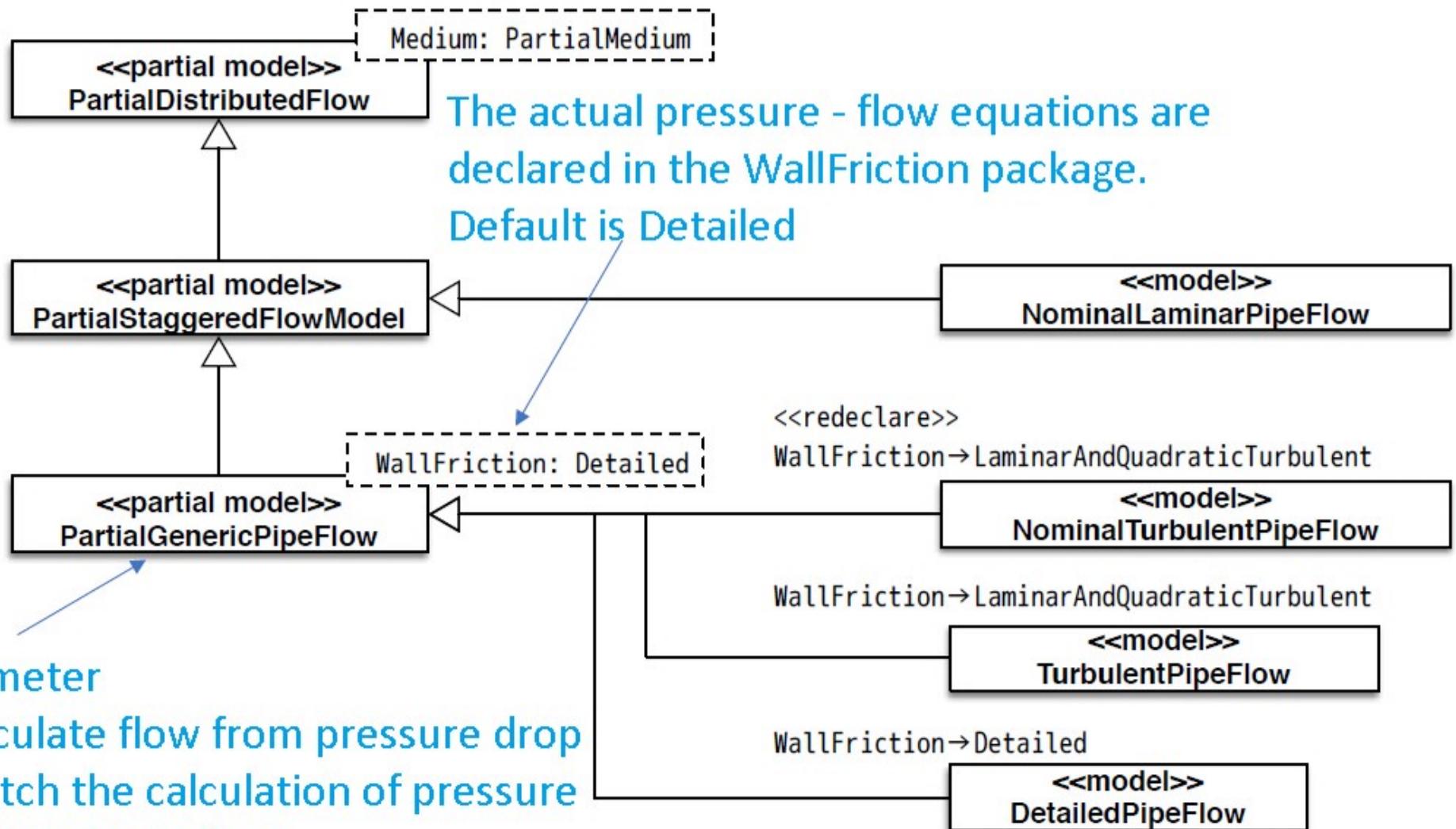
(3) homotopy method and homotopy operator

(4) WallFriction.Detailed

- massFlowRate_dp
- pressureLoss_m_flow

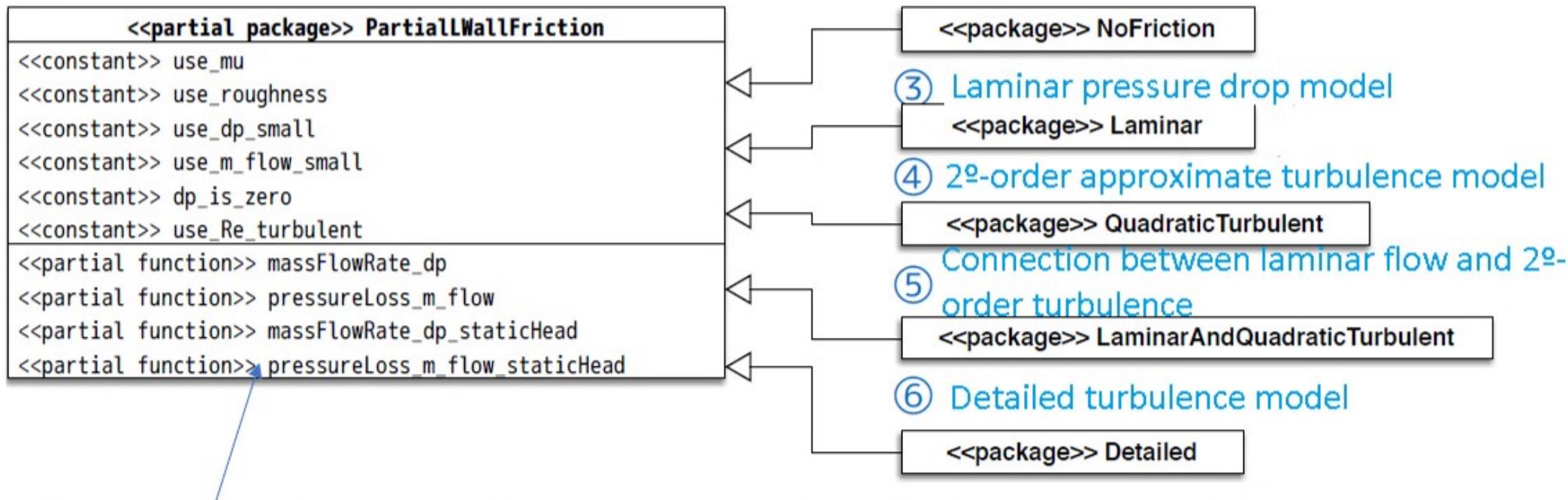
(1) Overview

The relationship between the pressure loss of the pipe and the mass flow rate is calculated by the model that inherits PartialGenericFlow.



WallFriction Package

① Interface



The pressure changes continuously when changing from forward to reverse flow

- `massFlowRate_dp`: Calculate mass flow from pressure loss
- `pressureLoss_m_flow`: Calculate the pressure loss from the mass flow rate

If it changes discontinuously or if there is a height difference

- `massFlowRate_dp_staticHead`: Calculate mass flow from pressure loss
- `pressureLoss_m_flow_staticHead`: Calculate pressure loss from mass flow

Part of Mass Flow or Pressure Drop Calculation in PartialGenericPipeFlow

```
if continuousFlowReversal then
    // simple regularization
    if from_dp and not WallFriction.dp_is_zero then
        m_flows = homotopy(
            actual= WallFriction.massFlowRate_dp(
                dps_fg - {g*dheights[i]*rhos_act[i] for i in 1:n-1},
                rhos_act,
                rhos_act,
                mus_act,
                mus_act,
                pathLengths_internal,
                diameters,
                (crossAreas[1:n-1]+crossAreas[2:n])/2,
                (roughnesses[1:n-1]+roughnesses[2:n])/2,
                dp_small/(n-1),
                Res_turbulent_internal)*nParallel,
            simplified= m_flow_nominal/dp_nominal*(dps_fg - g*dheights*rho_nominal));
    else
        dps_fg = homotopy(
            actual= WallFriction.pressureLoss_m_flow(
                m_flows/nParallel,
                rhos_act,
                rhos_act,
                mus_act,
                mus_act,
                pathLengths_internal,
                diameters,
                (crossAreas[1:n-1]+crossAreas[2:n])/2,
                (roughnesses[1:n-1]+roughnesses[2:n])/2,
                m_flow_small/nParallel,
                Res_turbulent_internal) + {g*dheights[i]*rhos_act[i] for i in 1:n-1},
            simplified= dp_nominal/m_flow_nominal*m_flows + g*dheights*rho_nominal);
    end if;
```

(2) Classification of calculation method using parameters

(3) Homotopy method

```

else
    // regularization for discontinuous flow reversal and static head
    if from_dp and not WallFriction.dp_is_zero then
        m_flows = homotopy(
            actual= WallFriction.massFlowRate_dp_staticHead(
                dps_fg,
                rhos[1:n-1],
                rhos[2:n],
                mus[1:n-1],
                mus[2:n],
                pathLengths_internal,
                diameters,
                g*dheights,
                (crossAreas[1:n-1]+crossAreas[2:n])/2,
                (roughnesses[1:n-1]+roughnesses[2:n])/2,
                dp_small/(n-1),
                Res_turbulent_internal)*nParallel,
            simplified= m_flow_nominal/dp_nominal*(dps_fg - g*dheights*rho_nominal));
    else
        dps_fg = homotopy(
            actual= WallFriction.pressureLoss_m_flow_staticHead(
                m_flows/nParallel,
                rhos[1:n-1],
                rhos[2:n],
                mus[1:n-1],
                mus[2:n],
                pathLengths_internal,
                diameters,
                g*dheights,
                (crossAreas[1:n-1]+crossAreas[2:n])/2,
                (roughnesses[1:n-1]+roughnesses[2:n])/2,
                m_flow_small/nParallel,
                Res_turbulent_internal),
            simplified= dp_nominal/m_flow_nominal*m_flows + g*dheights*rho_nominal);
    end if;
end if;

```

(2) Parameters for calculation method

① from_dp

If true, calculate mass flow from pressure difference
if false, calculate pressure difference from mass flow

Connected by momentumDynamics

Declaration part of PartialGenericPipeFlow

```
parameter Boolean from_dp = momentumDynamics >= Types.Dynamics.SteadyStateInitial  
"= true, use m_flow = f(dp), otherwise dp = f(m_flow)" annotation( ...);
```

momentumDynamics	from_dp	initial condition
DynamicFreeInitial	false	
FixedInitial	false	m_flow_start
SteadyStateInitial	true	d(m_flow)/dt = 0
SteadyState	true	

② WallFriction.dp_is_zero

True if there is no viscous pressure loss

③ continuousFlowReversal

True if the pressure changes continuously when changing from forward to reverse

Declaration part of PartialGenericPipeFlow

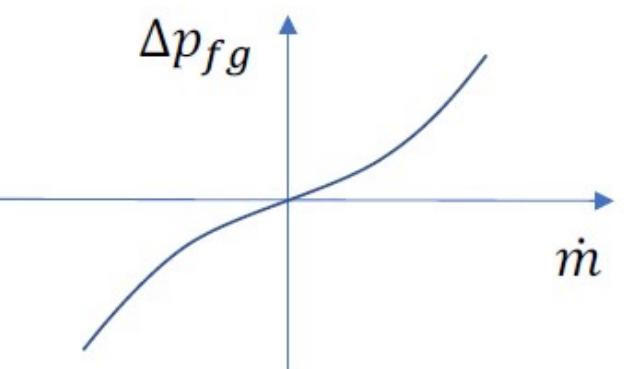
```
final parameter Boolean continuousFlowReversal=  
  (not useUpstreamScheme)  
  or constantPressureLossCoefficient  
  or not allowFlowReversal
```

In addition, the value is true when the pressure loss coefficient is not a wind-up difference scheme

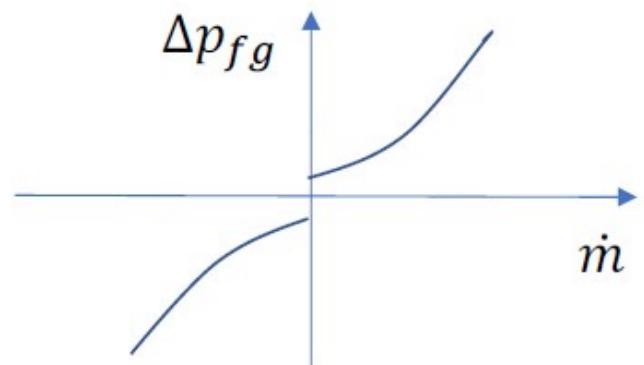
or the pressure loss coefficient is constant or does not consider backflow.

For false, separate cases because a special regularization is required.

true



false



(3) Homotopy method and homotopy operator

Overview

- In the initialization phase of dynamic simulation, you may need to solve a large non-linear equation system with repeated calculations.
- The homotopy method is a method for solving a non-linear equation system by solving a model that simply converges, and continuously deforming the model from the model to the actual model to track the solution.

Homotopy transformation The following expression continuously changes λ from 0 to 1.

$$\lambda * \text{actual} + (1 - \lambda) * \text{simplified}$$

Modelica homotopy operator

The homotopy operator is used for a variable to be input into a non-linear equation.

Homotopy operator

m_flows = homotpy(actual, simplified)

(4) Wall Friction.Detailed

Darcy-Weisbach Equation

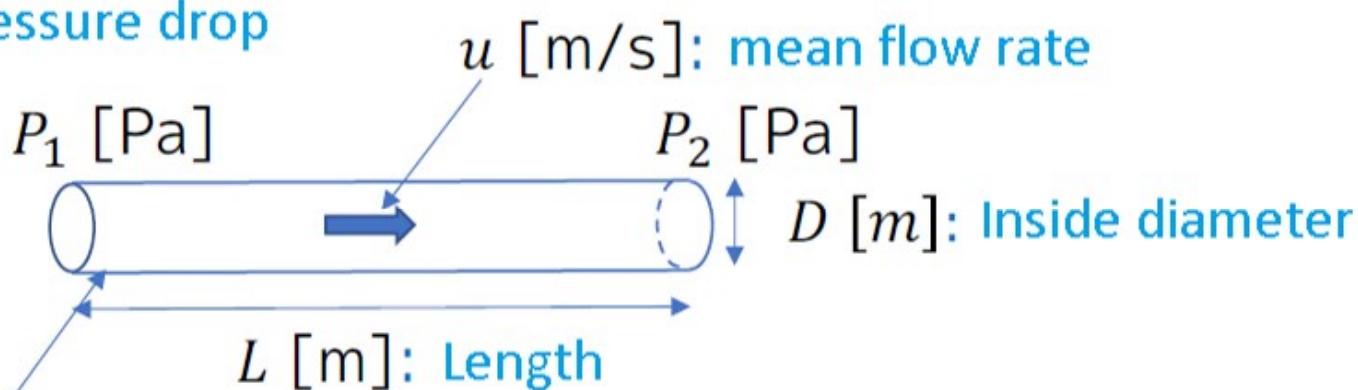
$$\Delta P = \lambda \frac{L}{D} \frac{\rho u^2}{2}$$

λ : Pipe friction coefficient (Darcy's friction factor)

ρ [kg/m³]: Density

μ [Pa.s]: Viscosity

$\Delta P = P_1 - P_2$: Pressure drop



ε [m]: Surface roughness

$$\Delta = \frac{\varepsilon}{D} : \text{Relative roughness}$$

$$Re = \frac{\rho u D}{\mu} : \text{Reynolds number}$$

λ : Darcy's friction factor

$Re < Re_1$ Laminar flow

$$\lambda = \frac{64}{Re} \quad u = \frac{\Delta P}{L} \frac{r^2}{8\mu}$$

Hagen-Poiseuille flow

$Re > Re_2$ Turbulent flow

Colebrook–White Equation

$$\frac{1}{\sqrt{\lambda}} = -2 \log_{10} \left(\frac{2.51}{Re\sqrt{\lambda}} + \frac{\varepsilon/D}{3.7} \right) = -2 \log_{10} \left(\frac{2.51}{Re\sqrt{\lambda}} + 0.27\Delta \right)$$

$Re_1 < Re < Re_2$

The range of transition regions between turbulent and laminar flow

$$Re_1 = 745 \exp \left(\text{if } \Delta < 0.0065 \text{ then } 1 \text{ else } \frac{0.0065}{\Delta} \right)$$

[Samoilenko 1968; Idelchik 1994, p. 81, sect. 2.1.21]

$$Re_2 = Re_{turbulent} = 4000$$

$$\lambda_2 \equiv \lambda Re^2$$

Introduction
For laminar flow

$$\lambda = \frac{64}{Re} \Leftrightarrow Re = \frac{\lambda_2}{64} \quad \text{or} \quad \lambda_2 = 64 Re$$

$Re \rightarrow 0$ So λ is diverging, but λ_2 is not

In the case of turbulence

$$\frac{1}{\sqrt{\lambda}} = -2 \log_{10} \left(\frac{2.51}{Re\sqrt{\lambda}} + 0.27\Delta \right) \Leftrightarrow Re = -2\sqrt{\lambda_2} \log_{10} \left(\frac{2.51}{\sqrt{\lambda_2}} + 0.27\Delta \right)$$

The Colebrook-White expression is no longer a implicit function.

Relation between pressure and lambda

$$\Delta P = \lambda \frac{L}{D} \frac{\rho u^2}{2}, \quad Re = \frac{\rho u D}{\mu} \Leftrightarrow \lambda_2 = |\Delta p| \frac{2D^3 \rho}{L \mu^2} \quad \text{または} \quad \Delta p = \pm \frac{L \mu^2}{2D^3 \rho} \lambda_2$$

Relationship between Mass flow rate and Reynolds number

$$Re = \frac{\rho u D}{\mu}, \quad \dot{m} = \rho u A \Leftrightarrow \dot{m} = \frac{\mu A}{D} Re \quad \text{or} \quad Re = \frac{D}{\mu A} |\dot{m}|$$

massFlowRate_dp Determine mass flow from pressure difference

$$\textcircled{1} \quad \lambda_2 = |\Delta p| \frac{2D^3 \rho}{L \mu^2}$$

\textcircled{2} $Re = \frac{\lambda_2}{64}$ First, the Reynolds number is obtained by assuming the laminar flow.

if $Re > Re_1$

$$Re = -2\sqrt{\lambda_2} \log_{10} \left(\frac{2.51}{\sqrt{\lambda_2}} + 0.27\Delta \right)$$

If it is outside the range of laminar flow, the Reynolds number is calculated assuming turbulent flow.

if $Re < Re_2$

In the transition region, the Reynolds number is calculated by an interpolation function.

$$Re = \text{interpolateRegion2}(Re, Re_1, Re_2, \Delta, \lambda_2)$$

$$\textcircled{3} \quad \dot{m} = \pm \frac{\mu A}{D} Re$$

A mass flow rate is calculated from the Reynolds number.
The sign matches $\Delta\%$.

pressureLoss_m_flow Calculate pressure difference from mass flow rate

$$\textcircled{1} \quad Re = \frac{D}{\mu A} |\dot{m}|$$

$$\textcircled{2} \quad \text{if } Re \leq Re_1$$

$$\lambda_2 = 64 Re$$

(Swamee-Jain equation)

(Approximate formula of Colebrook-White's formula)

$$\lambda = 0.25 \left[\log \left\{ \frac{\Delta}{3.7} + \frac{5.74}{Re^{0.9}} \right\} \right]^{-2}$$

$$\text{if } Re \geq Re_2$$

$$\lambda_2 = 0.25 \left(\frac{Re}{\log \left\{ \frac{\Delta}{3.7} + \frac{5.74}{Re^{0.9}} \right\}} \right)^2$$

$Re_1 < Re < Re_2$ Interpolation function for transition region

$$\lambda_2 = \text{interpolateInRegion2}(Re, Re1, Re2, \Delta)$$

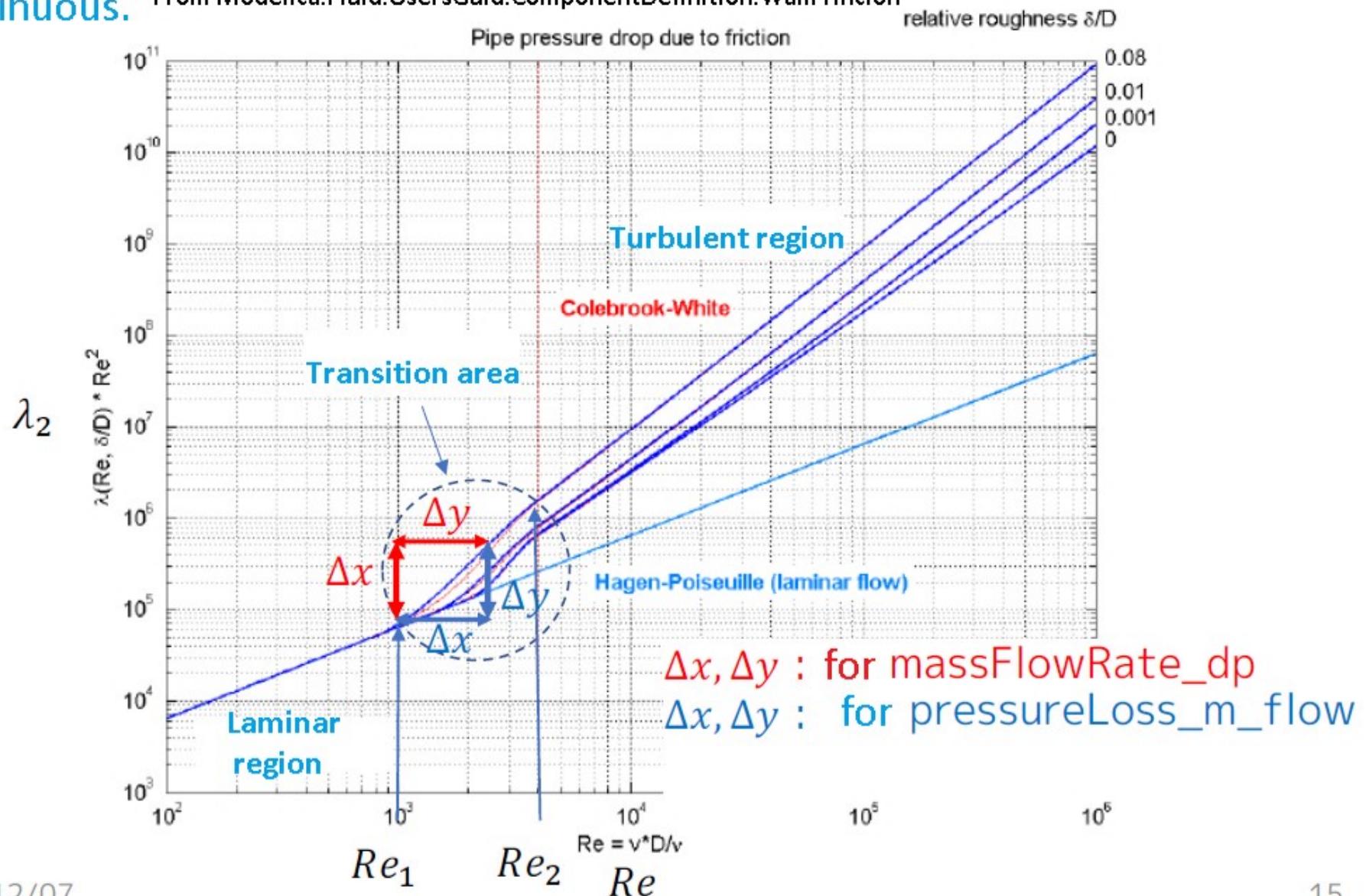
$$\textcircled{3} \quad \Delta p = \pm \frac{L \mu^2}{2 D^3 \rho} \lambda_2 \quad \text{Calculate the pressure difference from } \lambda_2$$

The sign matches \dot{m}

Concept of interpolation method for transition region

Approximate Δy with a cubic polynomial of Δx using the distances Δx and Δy on the logarithmic graph, and connect to the curves of the laminar flow region and the turbulent flow region with Re_1 and Re_2 , respectively, until the 1st derivative is continuous.

From Modelica.Fluid.UsersGuid.ComponentDefinition.WallFriction



Appendix 2. PartialLumpedVessel pressure equation

- (1) General pressure loss coefficient and pressure flow rate relational expression
- (2) Effect of correction penetration when the liquid level is close to the port height
- (3) Regularization when flow rate is small (Proper flow)
- (4) Calculation of nonlinear equations by homotopy method

(1) General pressure loss coefficient and pressure flow rate relational expression

Inflow

$$p_{in} + \frac{\dot{m}^2}{2\rho_{in}A_{in}^2} - \zeta_{in} \cdot \frac{\dot{m}^2}{2\rho_{in}A_{in}^2} = p_{vessel} + \frac{\dot{m}^2}{2\rho_{vessel}A_{vessel}^2}$$

Static
pressure

Dynamic
pressure

Pressure
loss

Static
pressure

Dynamic
pressure



$$\Rightarrow p_{in} = p_{vessel} + \left(\zeta_{in} - 1 + \frac{A_{in}^2}{A_{vessel}^2} \right) \frac{1}{2\rho_{in}A_{in}^2} \cdot \dot{m}^2$$

Outflow

$$p_{vessel} + \frac{\dot{m}^2}{2\rho_{vessel}A_{vessel}^2} - \zeta_{out} \cdot \frac{\dot{m}^2}{2\rho_{out}A_{out}^2} = p_{out} + \frac{\dot{m}^2}{2\rho_{out}A_{out}^2}$$

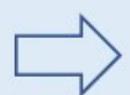
Static
pressure

Dynamic
pressure

Pressure
loss

Static
pressure

Dynamic
pressure



$$\Rightarrow p_{out} = p_{vessel} - \left(\zeta_{out} + 1 - \frac{A_{out}^2}{A_{vessel}^2} \right) \frac{1}{2\rho_{vessel}A_{out}^2} \dot{m}^2$$

Dynamic
pressure

$$\frac{1}{2}\rho u^2 = \frac{(\rho u A)^2}{2\rho A^2} = \frac{\dot{m}^2}{2\rho A^2}$$

(Kinetic energy per unit volume)

(2) Correction when the liquid level is close to the port height

When entering the container ($\dot{m}_{port} > \dot{m}_{turbulent}$) Port static pressure

$$p_{in} = p_{vessel_i} + \frac{1}{2A_i^2} \left(\zeta_{in_i} - 1 + \frac{A_i^2}{A_{vessel}^2} \right) \frac{1}{\rho_{in_i}} \text{penetration}_i \cdot \dot{m}_i^2$$

k_1

When spilling from the container ($\dot{m}_{port} < -\dot{m}_{turbulent}$) Port static pressure

$$p_{out} = p_{vessel_i} - \frac{1}{2A_i^2} \left(\zeta_{out_i} + 1 - \frac{A_i^2}{A_{vessel}^2} \right) \frac{1}{\rho_{vessel}} \frac{1}{\text{penetration}_i} \cdot \dot{m}_i^2$$

k_2

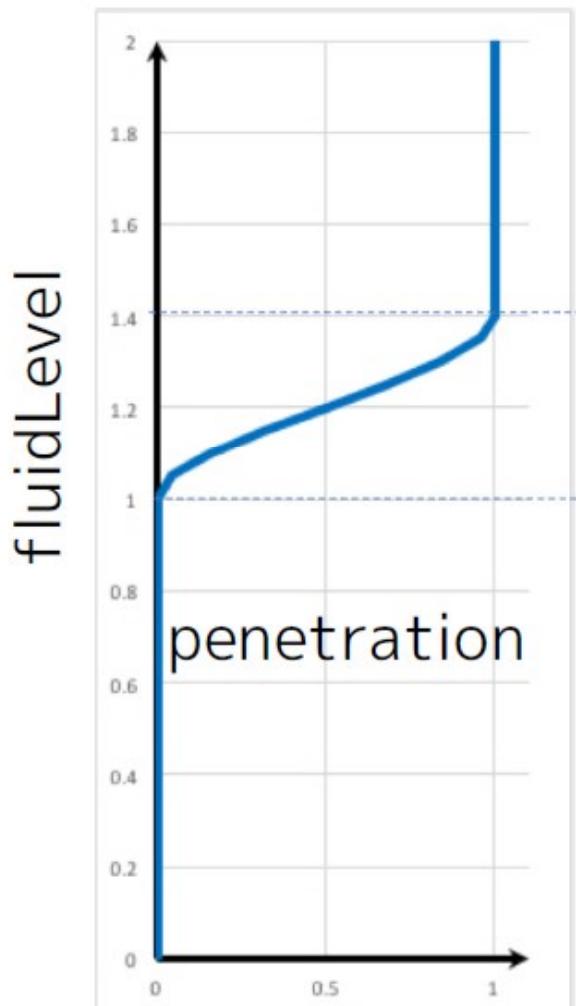
When the liquid level is below the port height + 0.2D, $\text{penetration}_i < 1$
The pressure loss at the time of inflow is small, and the pressure loss at the time of outflow is large.

Formula for penetration

$$penetration_i = \text{regStep}(fluidLevel - height_i - 0.1D_i, 1, 1 \times 10^{-3}, 0.1D_i)$$

```
ports_penetration[i]
```

```
= Utilities.regStep(fluidLevel - portsData_height[i] - 0.1*portsData_diameter[i],  
1, 1e-3, 0.1*portsData_diameter[i]);
```



penetration=1.0

Port height + 0.2D

Port height

penetration=0.001

$penetration_i = 1$ when `use_portsData = false`

Modelica.Fluid.Utilities.regStep

A function that approximates a step function in a continuous differentiable line

$$y = \begin{cases} y_1, & x > 0 \\ y_2, & x \leq 0 \end{cases} \quad \xrightarrow{\hspace{1cm}} \quad y = \begin{cases} y_1, & x > x_{small} \\ y_2, & x < -x_{small} \\ f(y_1, y_2) & -x_{small} \leq x \leq x_{small} \end{cases}$$

The area of $-x_{small} < x < x_{small}$ is a quadratic that changes from y_1 to y_2 . Approximate with polynomial $f(x)$

```
y := smooth(1, if x > x_small then y1 else
               if x < -x_small then y2 else
               if x_small > 0 then
                   (x/x_small)*((x/x_small)^2 - 3)*(y2-y1)/4 + (y1+y2)/2
               else
                   (y1+y2)/2);
```

(3) Regularization when flow rate is small

$$p_{port} = p_{vessel_i} + \frac{1}{2A_i} \text{regSquare2}(\dot{m}_i, \dot{m}_{turbulent}, k_1, k_2)$$

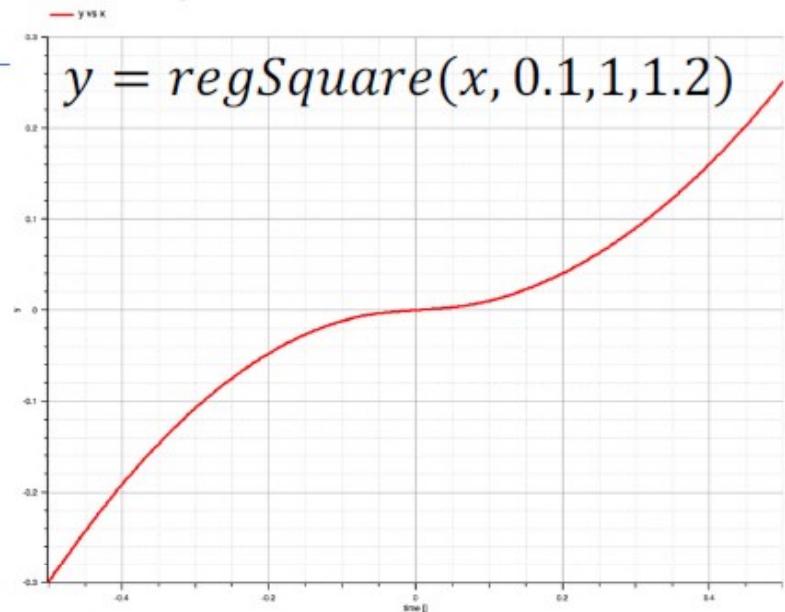
Connect p_{in} and p_{out} smoothly when $|\dot{m}_i| < \dot{m}_{turbulent_i}$

Modelica.Fluid.Utilities.regSquare2

$$y = \text{regSquare}(x, x_{small}, k_1, k_2, \text{use_yd0}, yd0)$$

$$y = \begin{cases} k_1 x^2, & x \geq 0, k_1 > 0 \\ -k_2 x^2, & x < 0, k_2 > 0 \end{cases}$$

Smoothly connect with $-x_{small} \leq x \leq x_{small}$



- Approximate $-x_{small} \leq x \leq 0$ and $0 \leq x \leq x_{small}$ with separate cubic polynomials.
- The derivative is not zero at $x = 0$. (The reciprocal does not become infinity.)
- The first derivative is continuous in all areas.
- If $\text{use_yd0} = \text{false}$ (default), the second derivative of two cubic polynomials will match at $x = 0$.
- If $\text{use_yd0} = \text{true}$, specify the first-order fine $yd0$ at $x = 0$ as an argument.

(4) Computation of nonlinear equations by homotopy

The homotopy operator is used because the relationship between flow rate and pressure loss is non-linear.

actual model

$$p_{port} = p_{vessel} + \frac{1}{2A^2} \text{regSqure2}(\dot{m}, \dot{m}_{turbulent}, k_1, k_2)$$

simplified model

$$p_{port} = p_{vessel}$$

homotopy model

Homotopy operator

$$p_{port} = \text{homotpy}\left(p_{vessel} + \frac{1}{2A^2} \text{regSqure2}(\dot{m}, \dot{m}_{turbulent}, k_1, k_2), p_{vessel}\right)$$

Partial Vessel pressure calculation formula

```
// fluid flow through ports
regularFlow[i] = fluidLevel >= portsData_height[i];
inFlow[i]      = not regularFlow[i] and (s[i] > 0 or portsData_height[i] >= fluidLevel_max);
if regularFlow[i] then
    // regular operation: fluidLevel is above ports[i]
    // Note: >= covers default values of zero as well
    if use_portsData then
        /* Without regularization
        ports[i].p = vessel_ps_static[i] + 0.5*ports[i].m_flow^2/portAreas[i]^2
            * noEvent(if ports[i].m_flow>0 then zeta_in[i]/portInDensities[i] else -zeta_out[i]/medium.d);
        */
        ports[i].p = homotopy(vessel_ps_static[i] + (0.5/portAreas[i]^2*Utilities.regSquare2(ports[i].m_flow, m_flow_turbulent[i],
            (portsData_zeta_in[i] - 1 + portAreas[i]^2/vesselArea^2)/portInDensities[i]*ports_penetration[i],
            k1
            (portsData_zeta_out[i] + 1 - portAreas[i]^2/vesselArea^2)/medium.d/ports_penetration[i]),
            k2
            vessel_ps_static[i]));
        /*
        // alternative formulation m_flow=f(dp); not allowing the ideal portsData_zeta_in[i]=1 though
        ports[i].m_flow = smooth(2, portAreas[i]*Utilities.regRoot2(ports[i].p - vessel_ps_static[i], dp_small,
            2*portInDensities[i]/portsData_zeta_in[i],
            2*medium.d/portsData_zeta_out[i]));
        */
    else
        ports[i].p = vessel_ps_static[i];
    end if;
    s[i] = fluidLevel - portsData_height[i];
```

Homotopy operator **regularization**

k_1 k_2

penetration

- The purpose of this document is introducing Media and Fluid Libraries in the Modelica Standard Library (MSL). This document uses libraries, software, figures, and documents included in MSL and those modifications. Licenses and copyrights of those are written in next page.
- Copyright and License of this document are written in the last page.

Modelica Standard Library License

<https://github.com/modelica/ModelicaStandardLibrary/blob/master/LICENSE>

BSD 3-Clause License

Copyright (c) 1998-2018, ABB, Austrian Institute of Technology, T. Bödrich, DLR, Dassault Systèmes AB, ESI ITI, Fraunhofer, A. Haumer, C. Kral, Modelon, TU Hamburg-Harburg, Politecnico di Milano, and XRG Simulation
All rights reserved.

Redistribution and use in source and binary forms, with or without modification, are permitted provided that the following conditions are met:

- * Redistributions of source code must retain the above copyright notice, this list of conditions and the following disclaimer.
- * Redistributions in binary form must reproduce the above copyright notice, this list of conditions and the following disclaimer in the documentation and/or other materials provided with the distribution.
- * Neither the name of the copyright holder nor the names of its contributors may be used to endorse or promote products derived from this software without specific prior written permission.

THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES; LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.



Copyright © 2017 The Open CAE Society of Japan

This work is licensed under a Creative Commons
Attribution-NonCommercial 4.0 International License.

<http://creativecommons.org/licenses/by-nc/4.0/>

