

What is Capsule net?

Dr. Narisu Tao

Data Scientist@Advanced Analytics and Data Lab, E.ON

2018-03-29

Munich, Germany

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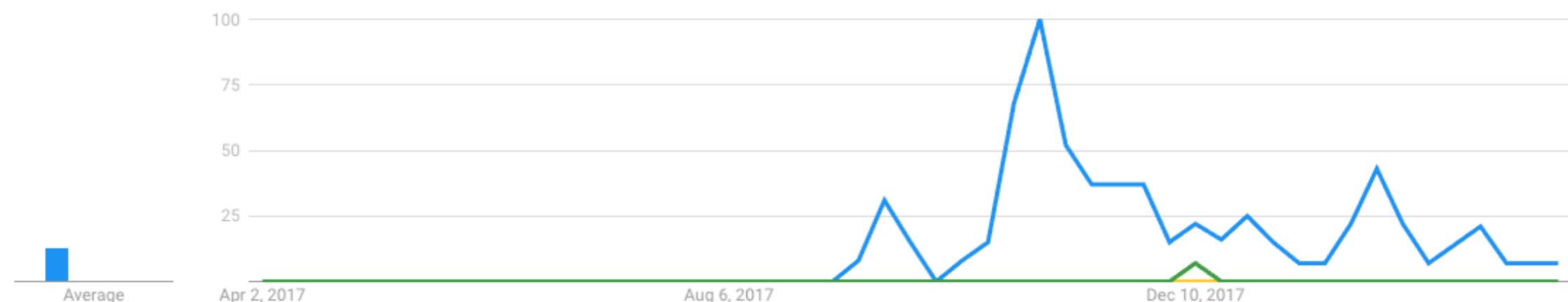
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Interest over time ?



Interest by region ?



**Why people are so
interested?**

A portrait of Geoffrey Hinton, a middle-aged man with light brown hair, wearing a dark sweater over a light-colored collared shirt. He is looking directly at the camera with a neutral expression. The background is a bright, outdoor setting with green trees and a blue sky.

Do you know who is this man?

Dynamic Routing Between Capsules

Sara Sabour

Nicholas Frosst

Geoffrey E. Hinton

Google Brain

Toronto

{sasabour, frosst, geoffhinton}@google.com

Abstract

A capsule is a group of neurons whose activity vector represents the instantiation parameters of a specific type of entity such as an object or an object part. We use the length of the activity vector to represent the probability that the entity exists and its orientation to represent the instantiation parameters. Active capsules at one level make predictions, via transformation matrices, for the instantiation parameters of higher-level capsules. When multiple predictions agree, a higher level capsule becomes active. We show that a discriminatively trained, multi-layer capsule system achieves state-of-the-art performance on MNIST and is considerably better than a convolutional net at recognizing highly overlapping digits. To achieve these results we use an iterative routing-by-agreement mechanism: A lower-level capsule prefers to send its output to higher level capsules whose activity vectors have a big scalar product with the prediction coming from the lower-level capsule.

The image shows a YouTube video player interface. The video is titled "What is wrong with “standard” neural nets?". The content of the video is a slide with the following text:

- They have too few levels of structure:
 - Neurons, Layers, Whole Nets
- We need to group the neurons in each layer into “capsules” that do a lot of internal computation and then output a compact result.
 - A capsule is inspired by a mini-column.

Below the video player, there is a caption: "Geoffrey Hinton talk 'What is wrong with convolutional neural nets ?'" and a view count of "115,844 views".



Prof. Dr. Geoffrey E. Hinton
God father of Deep Learning

The limitation of CNNs

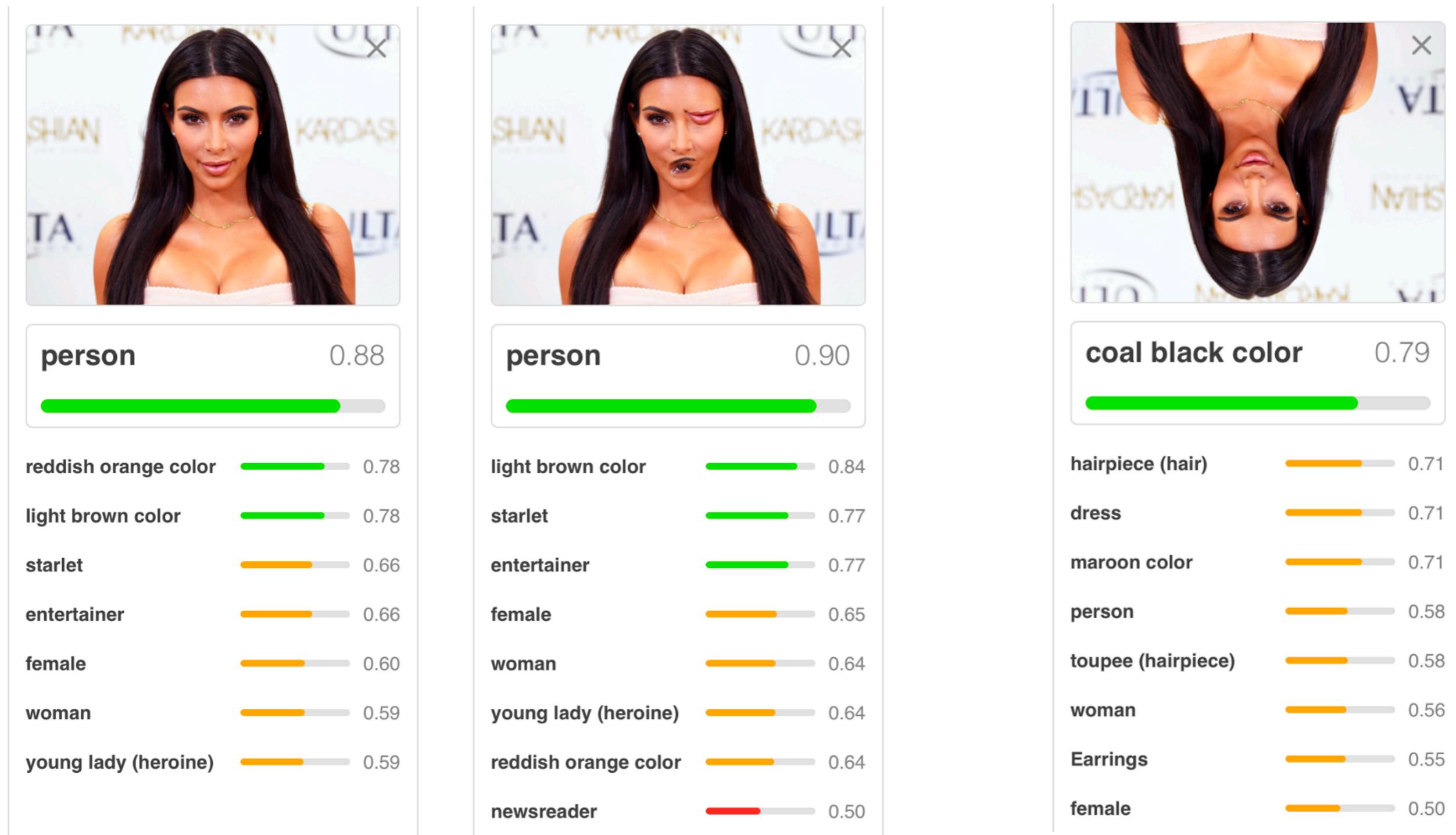


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“For thirty years, the state-of-the-art in speech recognition used hidden Markov models These models ... had a **representational limitation** that was ultimately fatal: The one-of-n representations they use are **exponentially inefficient** compared with, say, a recurrent neural network that uses **distributed representations**. To double the amount of information that an HMM can remember ..., we need to square the number of hidden nodes. For a recurrent net we only need to double the number of hidden neurons.

Now that convolutional neural networks have become the dominant approach to object recognition, it makes sense to ask whether there are any exponential inefficiencies that may lead to their demise.

A good candidate is the difficulty that convolutional nets have in generalizing to novel viewpoints. The ability to deal with translation is built in, but for the other dimensions of an affine transformation we have to chose between replicating feature detectors on a grid that grows exponentially with the number of dimensions, or increasing the size of the labelled training set in a similarly exponential way. **Capsules (Hinton et al. [2011]) avoid these exponential inefficiencies ...**

Capsules make a very strong representational assumption: ..., which ..., eliminates the binding problem (Hinton [1981a]) and allows a capsule to use a distributed representation This distributed representation is **exponentially more efficient** than encoding the instantiation parameters by activating a point on a high-dimensional grid and with the right distributed representation, capsules can then take full advantage of the fact that spatial relationships can be modelled by matrix multiplies.

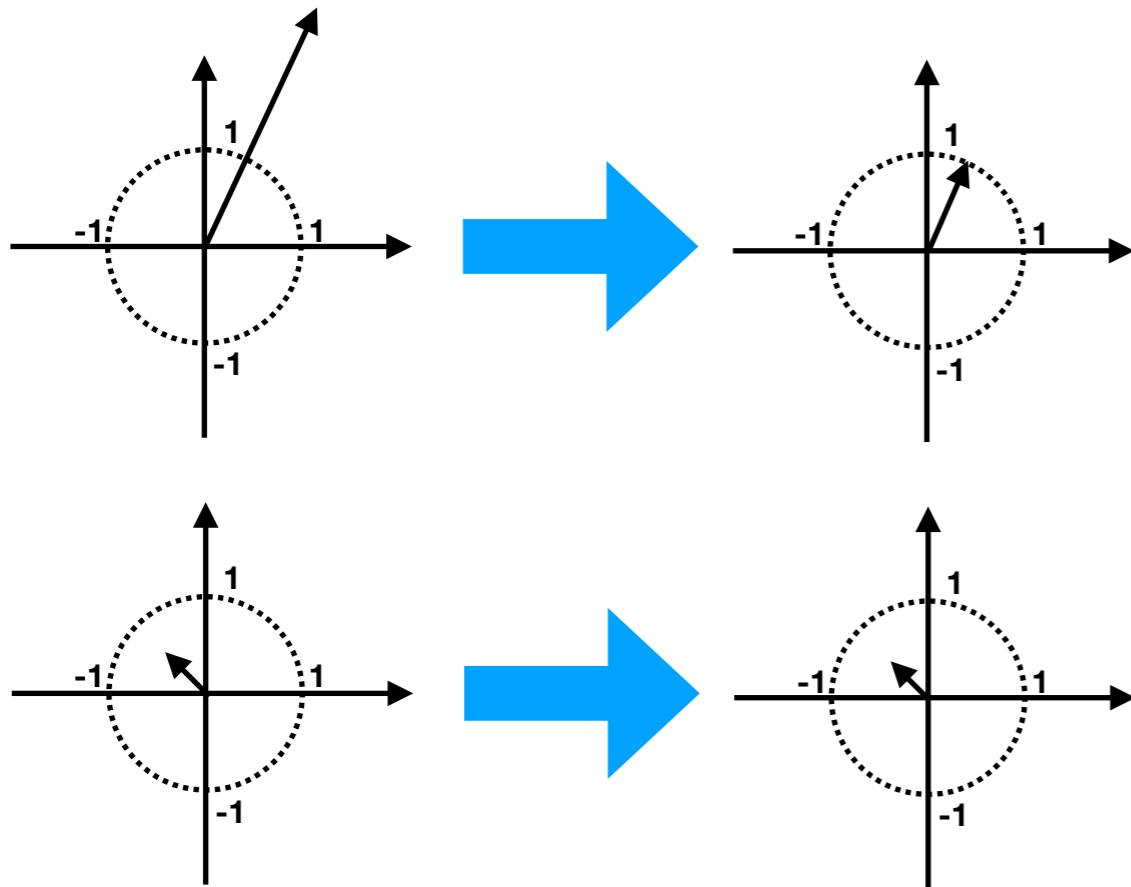
Research on capsules is now at a similar stage to research on recurrent neural networks for speech recognition at the beginning of this century. ...”

— *Discussion and previous work* section
from the paper *Dynamic Routing Between Capsules*

How it actually works?

Squash function versus sigmoid activation function

$$\mathbf{v}_j = \frac{\|\mathbf{s}_j\|^2}{1 + \|\mathbf{s}_j\|^2} \frac{\mathbf{s}_j}{\|\mathbf{s}_j\|}$$



$$f(x) = \frac{1}{1 + e^{-x}}$$

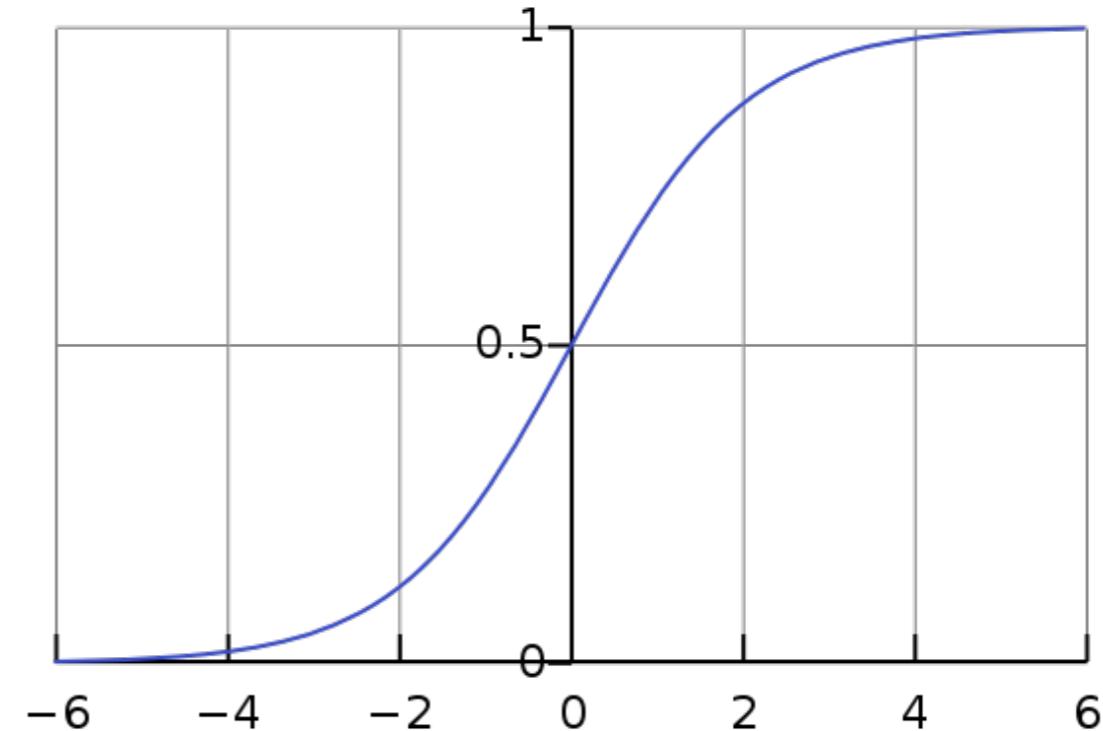


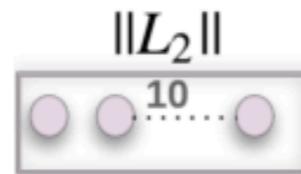
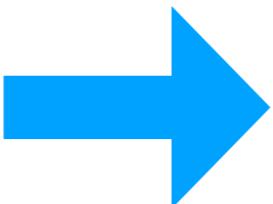
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Inference

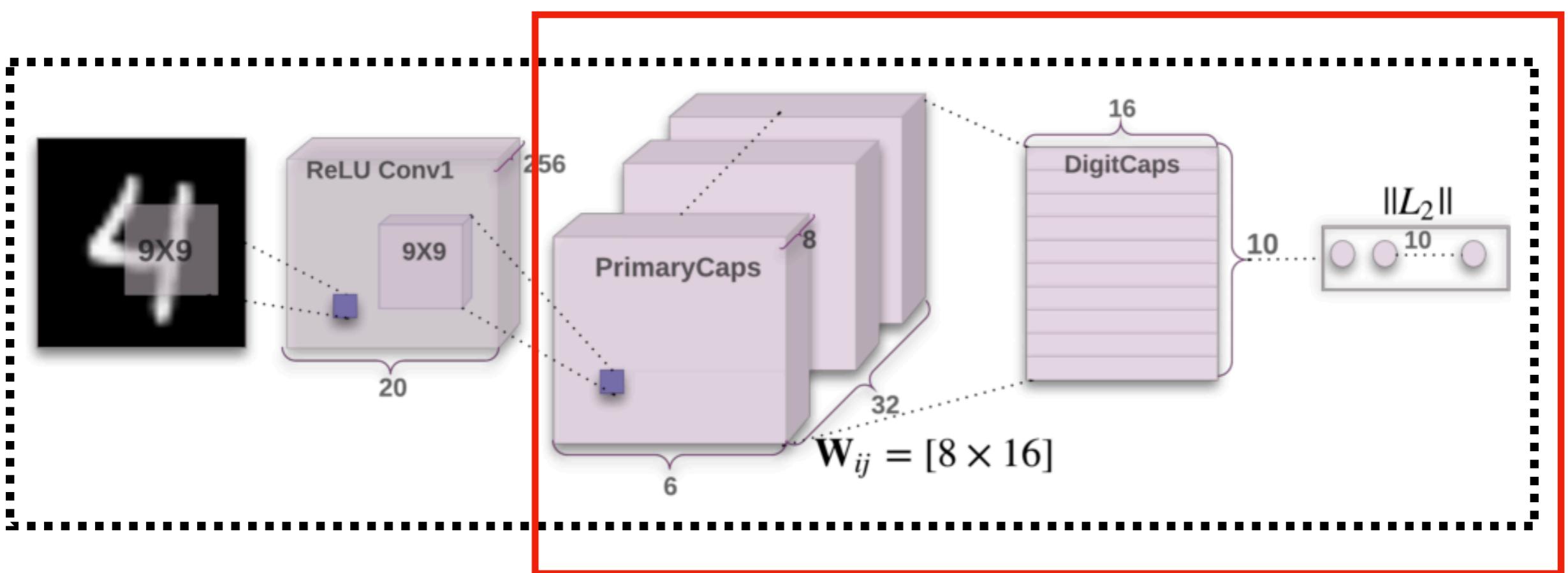


Input

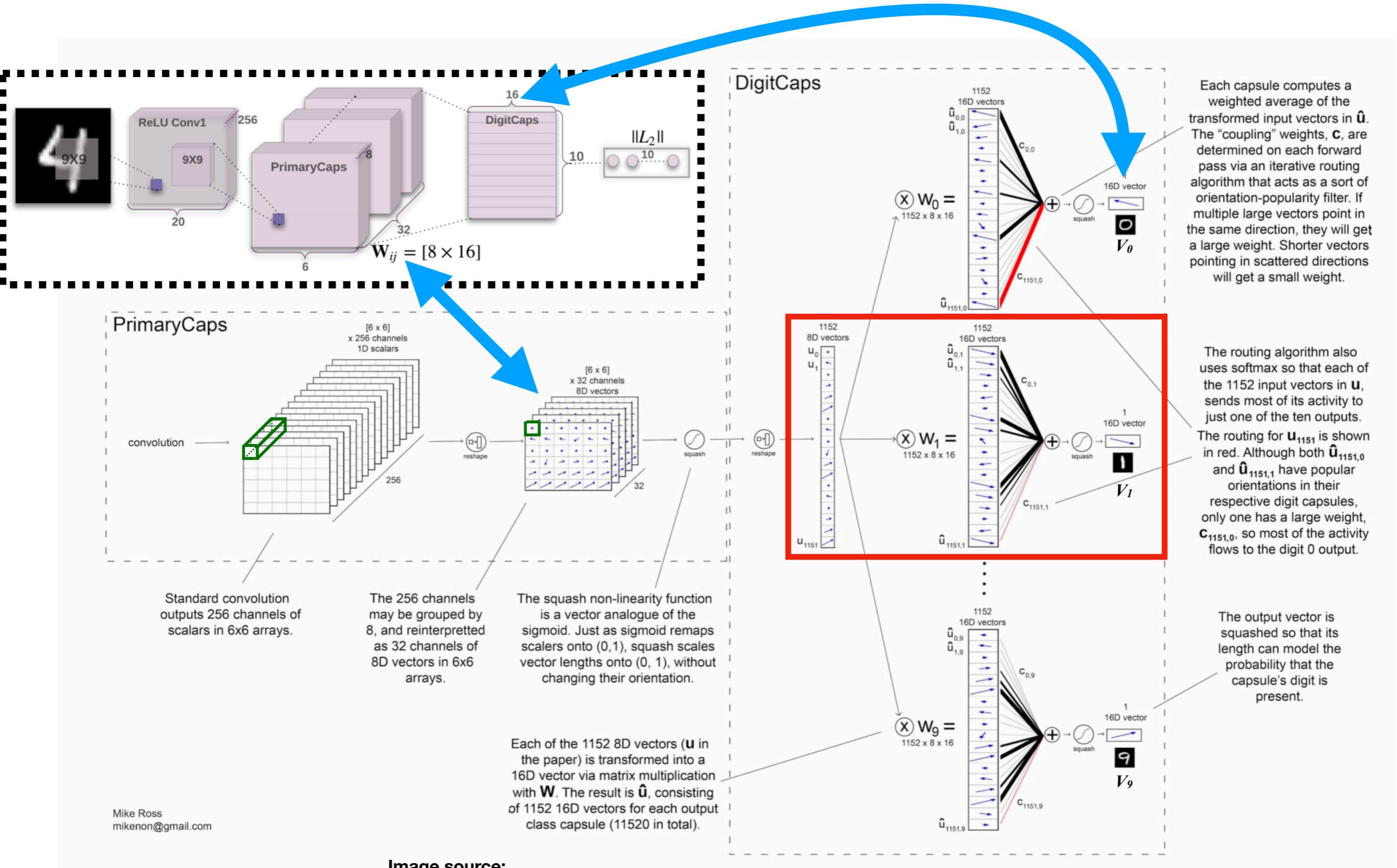


Output

Inference



Inference



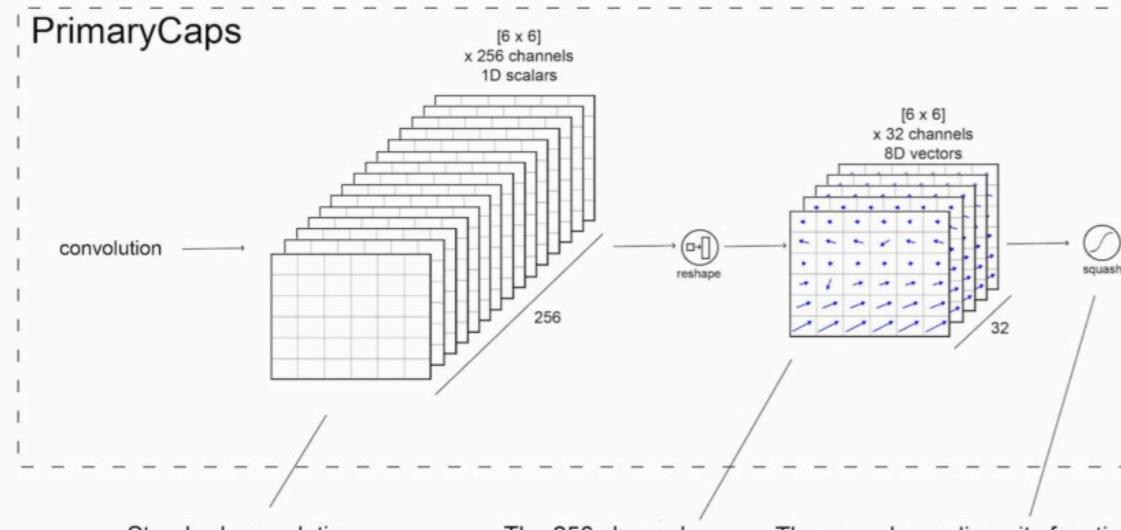
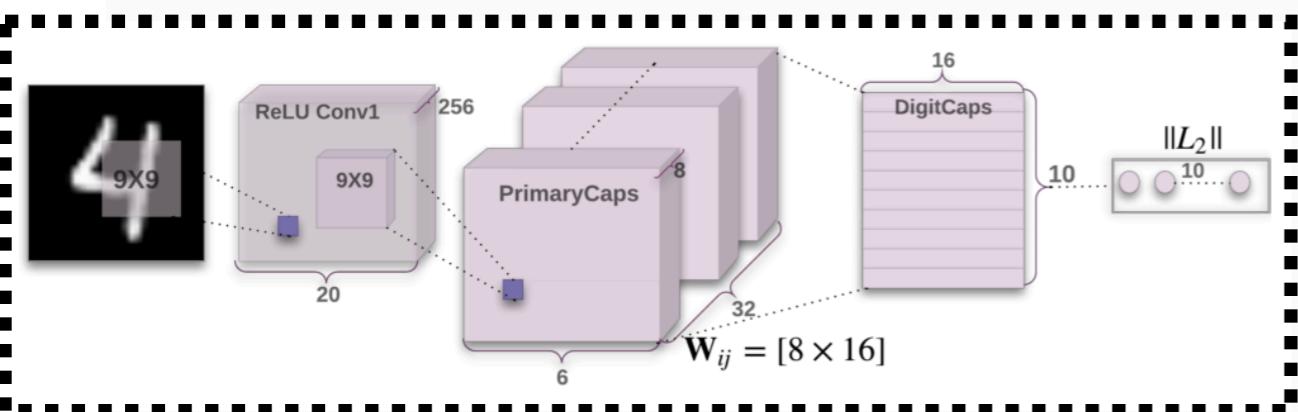
Inference

capsule		VS.	traditional neuron
Input from low-level neurons/capsules	$\mathbf{vector}(u_i)$		$\mathbf{scalar}(x_i)$
Operations	Linear/Affine Transformation	$\hat{u}_{j i} = W_{ij} u_i \quad (\text{Eq. 2})$	$a_{j i} = w_{ij} x_i + b_j$
	Weighting	$s_j = \sum_i c_{ij} \hat{u}_{j i} \quad (\text{Eq. 2})$	$z_j = \sum_{i=1}^3 1 \cdot a_{j i}$
	Summation		
	Non-linearity activation	$v_j = \text{squash}(s_j) \quad (\text{Eq. 1})$	$h_{w,b}(x) = f(z_j)$
output	$\mathbf{vector}(v_j)$		$\mathbf{scalar}(h)$

Capsule = New Version Neuron!
vector in, vector out VS. scalar in, scalar out

Dynamic Routing Between Capsules

Dynamic Routing



Mike Ross
mikenon@gmail.com

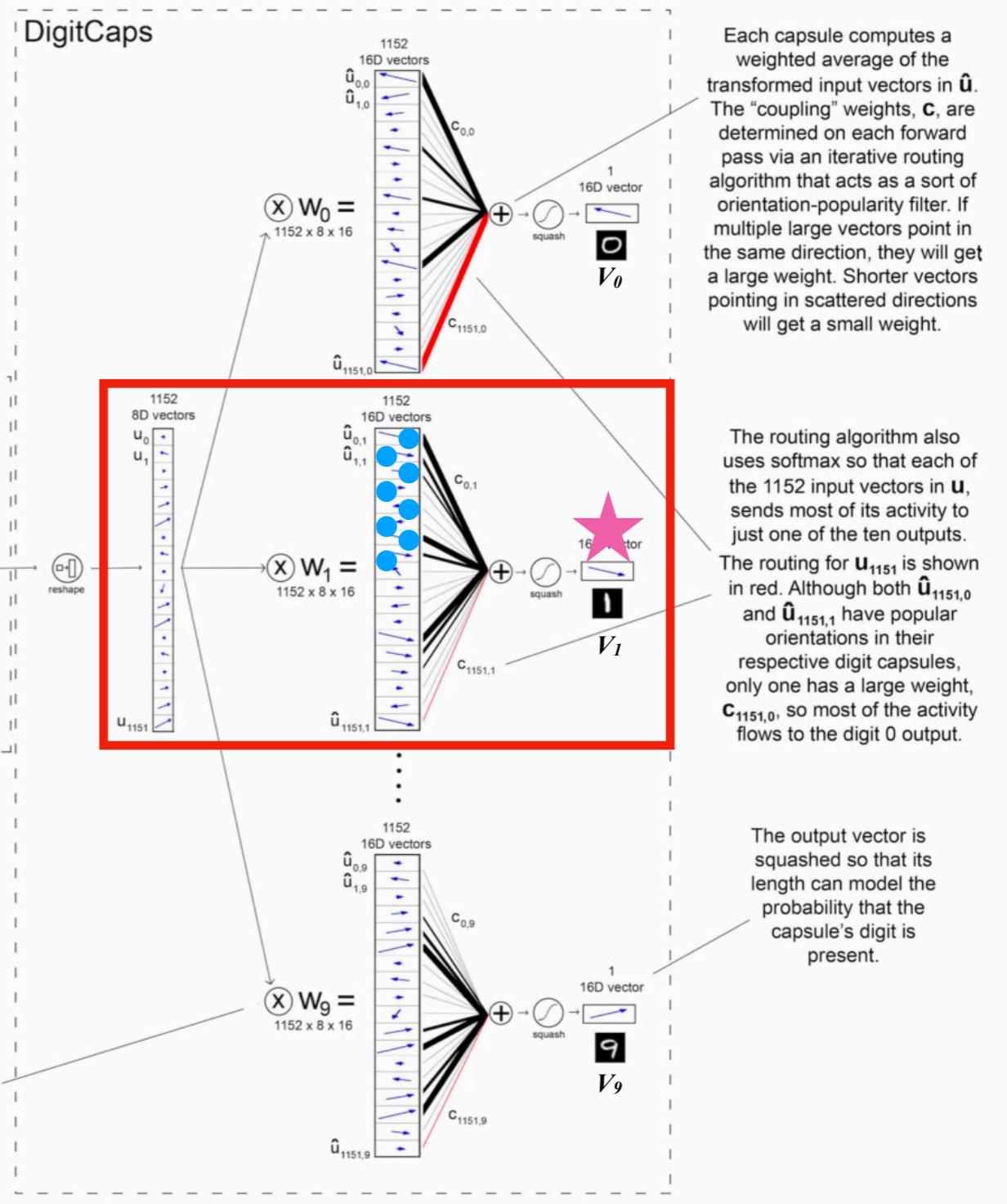


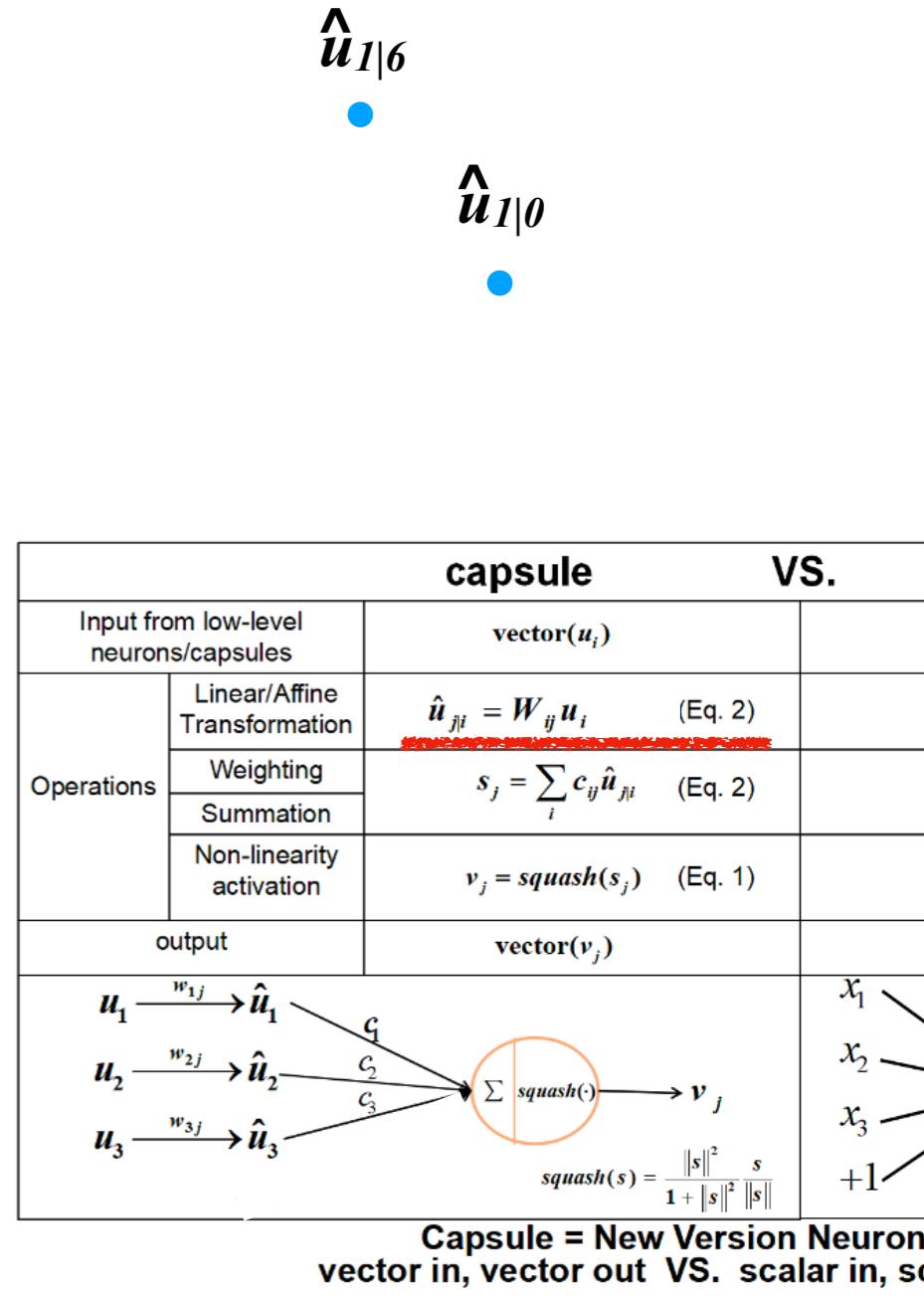
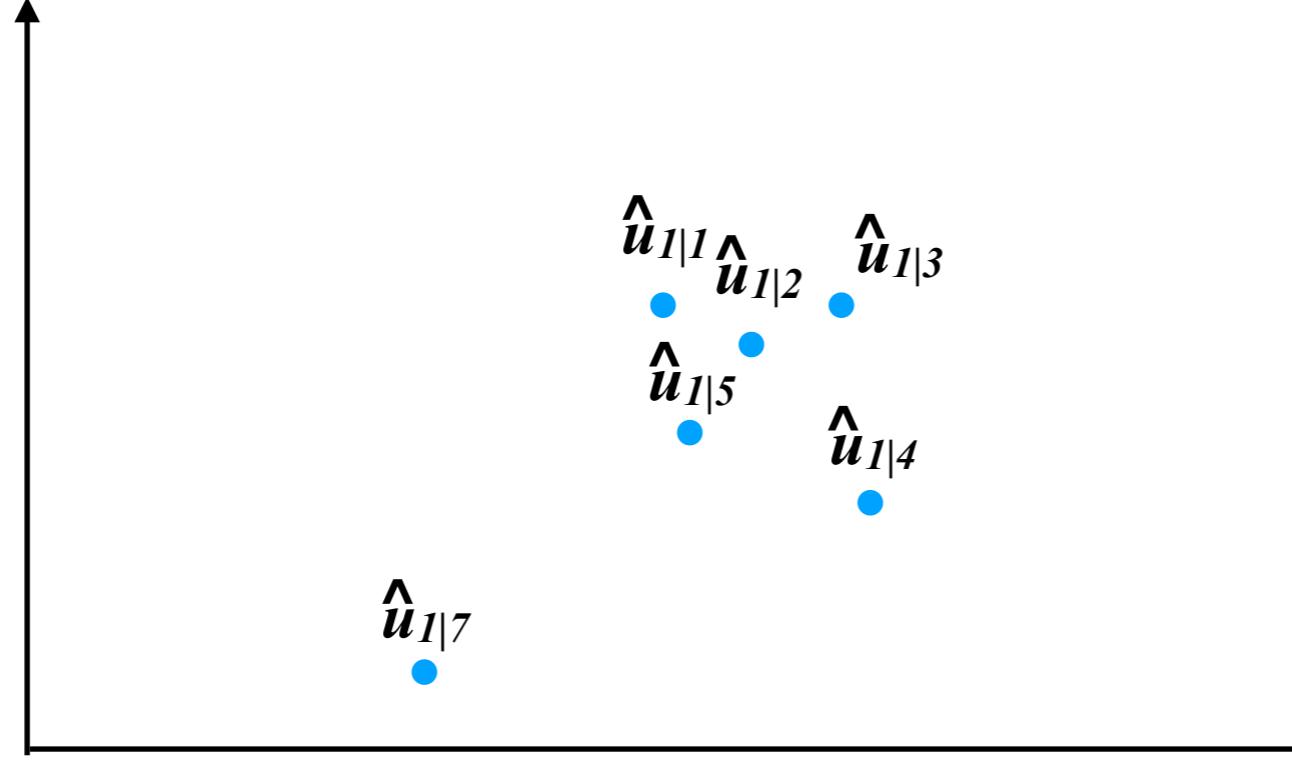
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Dynamic Routing

Assuming that the digits capsule is 2-D vector rather than 16-D vector.



Procedure 1 Routing algorithm.

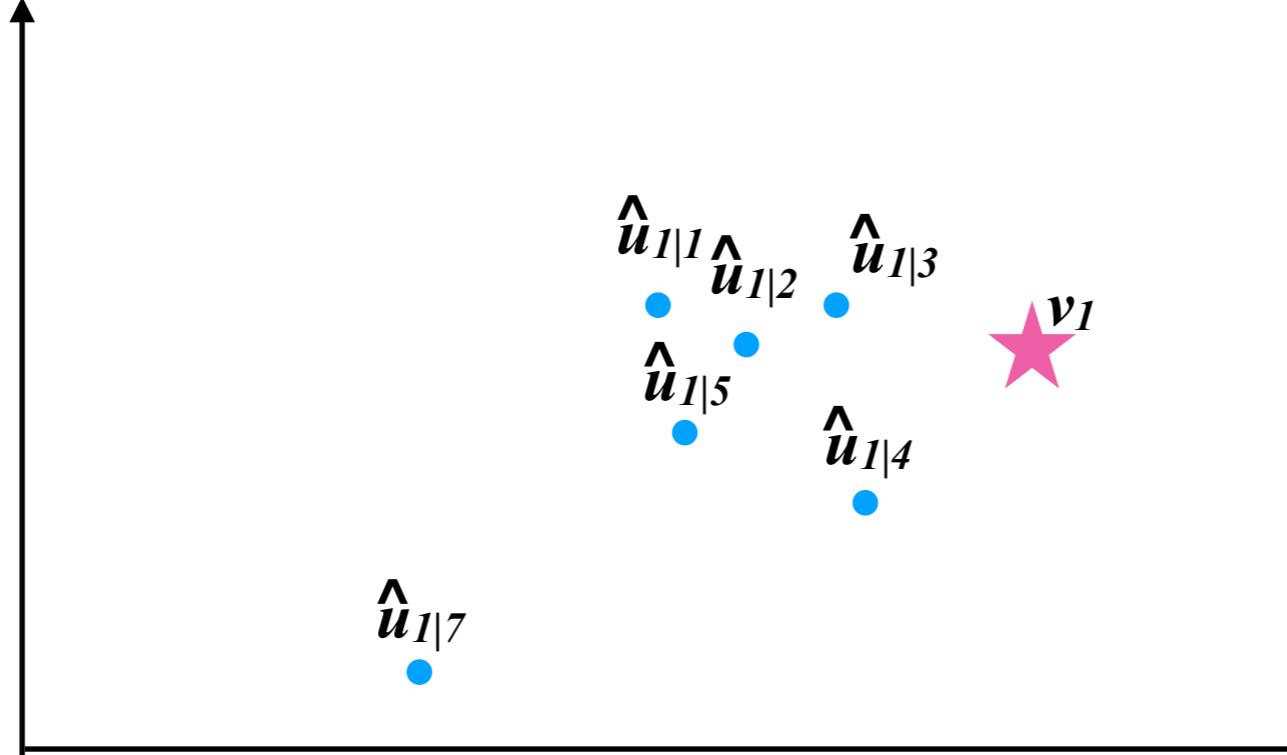
```

1: procedure ROUTING( $\hat{u}_{j|i}$ ,  $r$ ,  $l$ )
2:   for all capsule  $i$  in layer  $l$  and capsule  $j$  in layer  $(l + 1)$ :  $b_{ij} \leftarrow 0$ .
3:   for  $r$  iterations do
4:     for all capsule  $i$  in layer  $l$ :  $c_i \leftarrow \text{softmax}(b_i)$             $\triangleright$  softmax computes Eq. 3
5:     for all capsule  $j$  in layer  $(l + 1)$ :  $s_j \leftarrow \sum_i c_{ij} \hat{u}_{j|i}$ 
6:     for all capsule  $j$  in layer  $(l + 1)$ :  $v_j \leftarrow \text{squash}(s_j)$             $\triangleright$  squash computes Eq. 1
7:     for all capsule  $i$  in layer  $l$  and capsule  $j$  in layer  $(l + 1)$ :  $b_{ij} \leftarrow b_{ij} + \hat{u}_{j|i} \cdot v_j$ 
return  $v_j$ 

```

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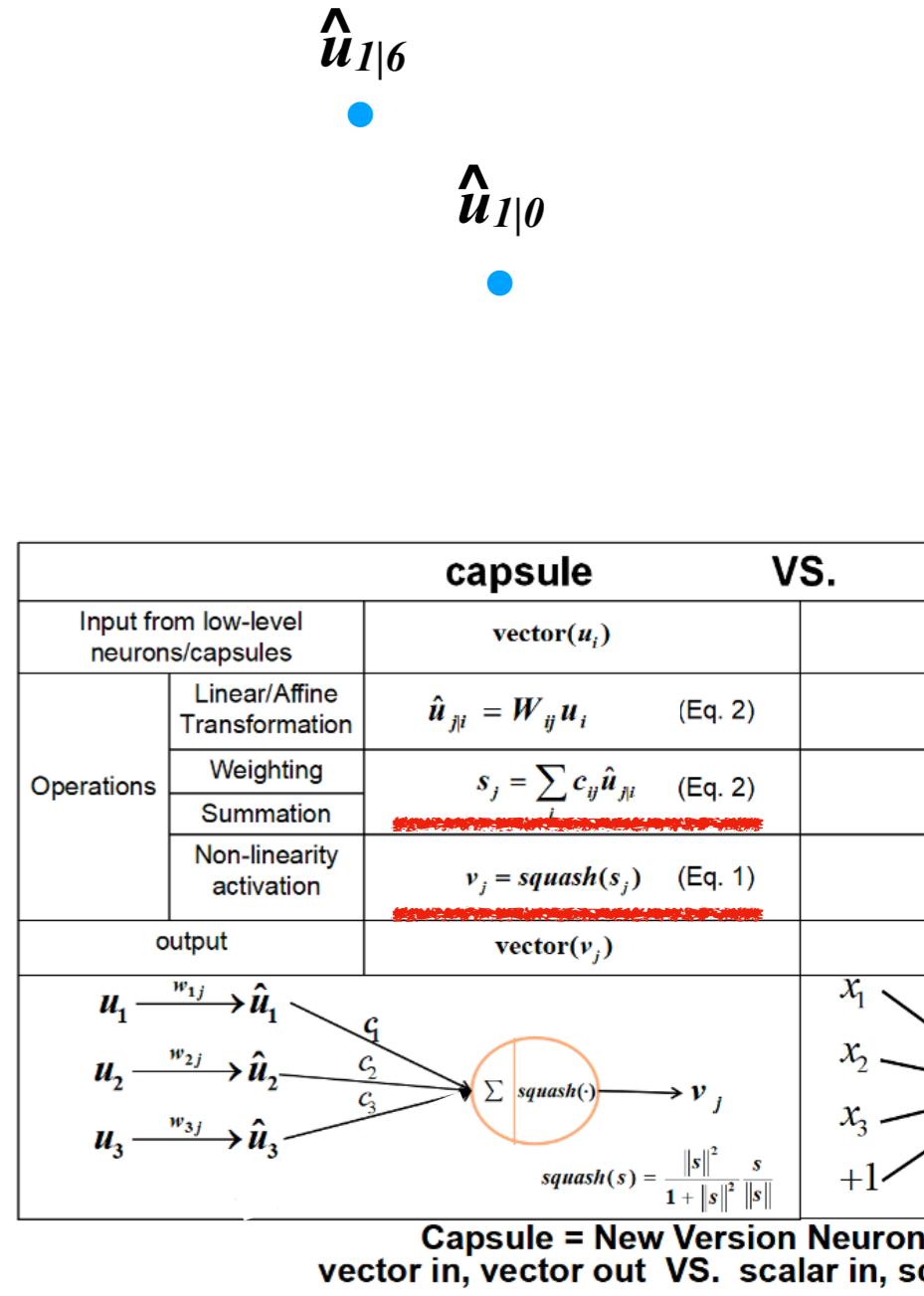


Procedure 1 Routing algorithm.

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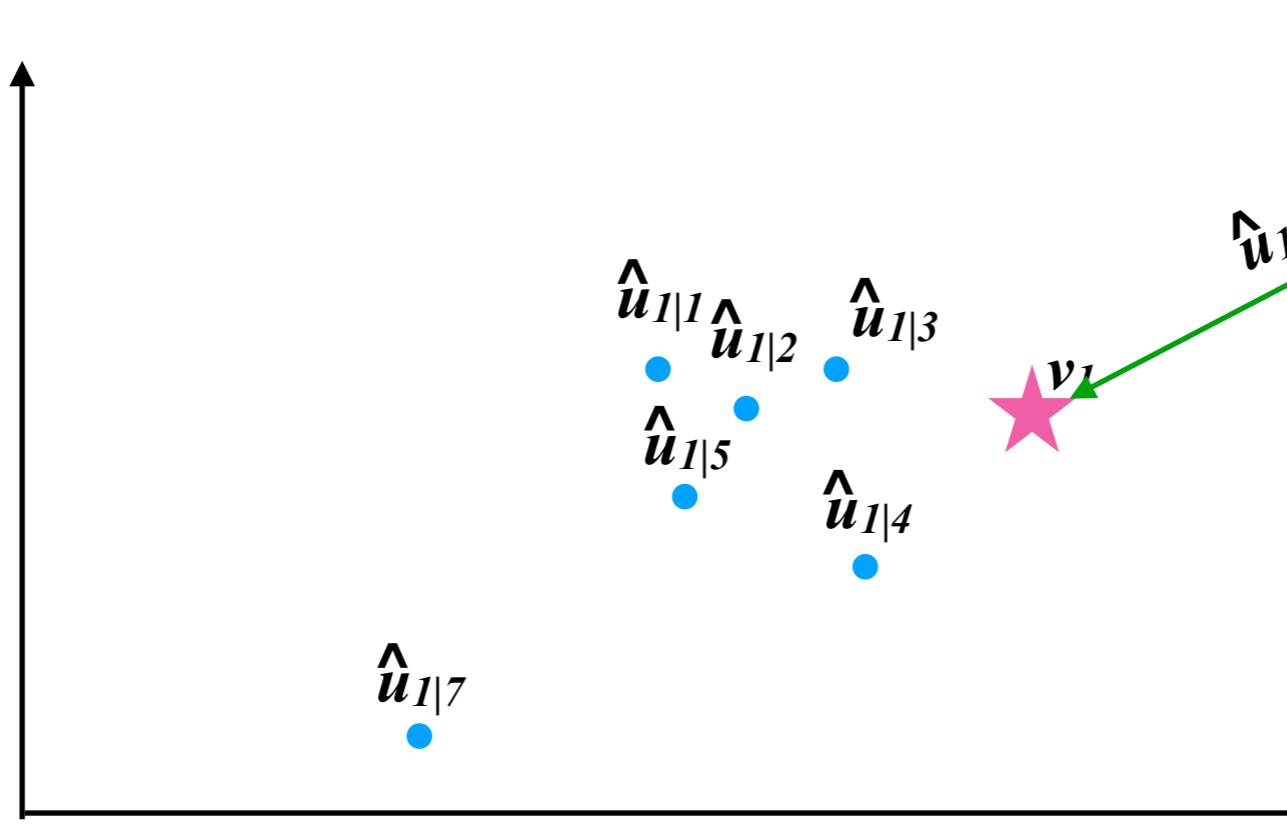
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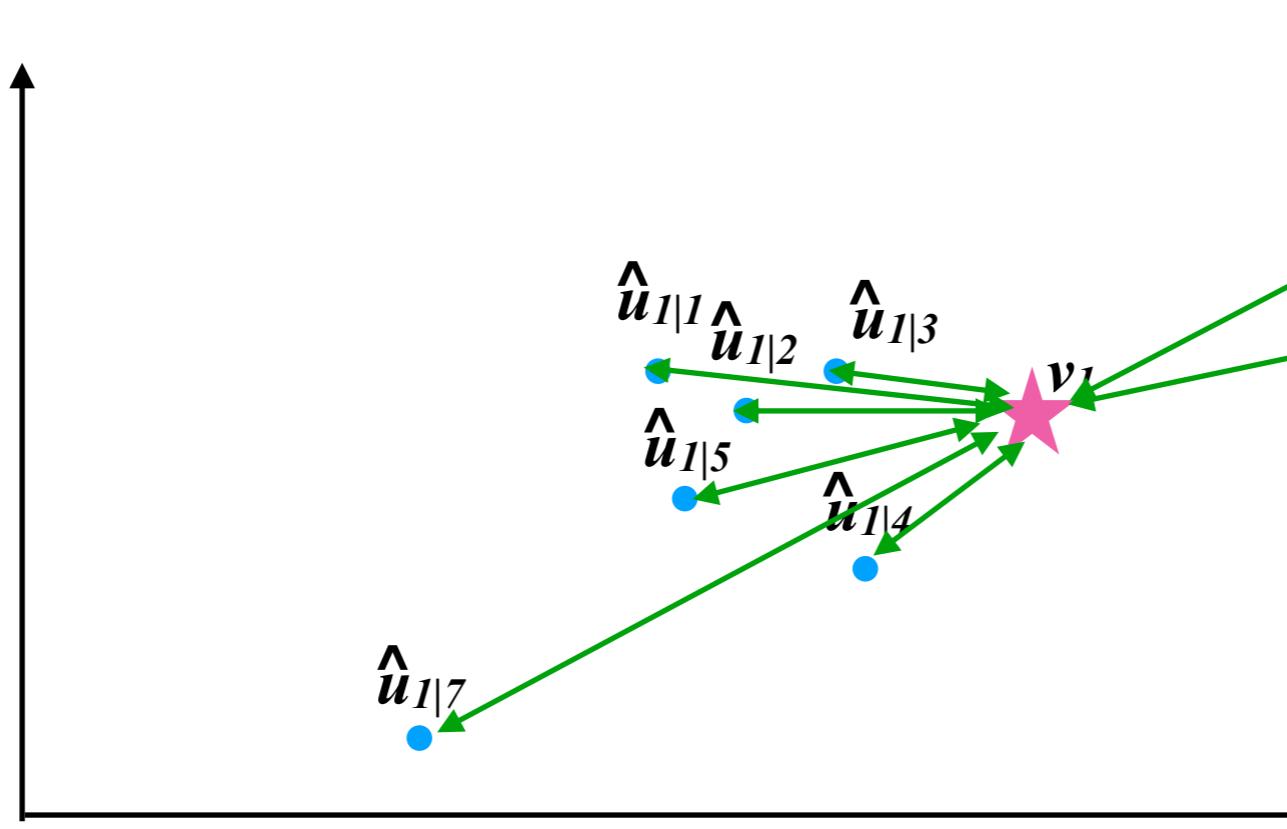
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```

		capsule	VS.
		Input from low-level neurons/capsules	vector(u_i)
Operations	Linear/Affine Transformation	$\hat{u}_{j i} = W_{ij} u_i$	(Eq. 2)
	Weighting	$s_j = \sum_i c_{ij} \hat{u}_{j i}$	(Eq. 2)
	Summation		
	Non-linearity activation	$v_j = \text{squash}(s_j)$	(Eq. 1)
	output	vector(v_j)	
$\text{squash}(s) = \frac{\ s\ ^2}{1 + \ s\ ^2} \frac{s}{\ s\ }$			
Capsule = New Version Neuron vector in, vector out VS. scalar in, scalar out			

Dynamic Routing

Assuming that the digits capsule is 2-D vector rather than 16-D vector.



Procedure 1 Routing algorithm.

```

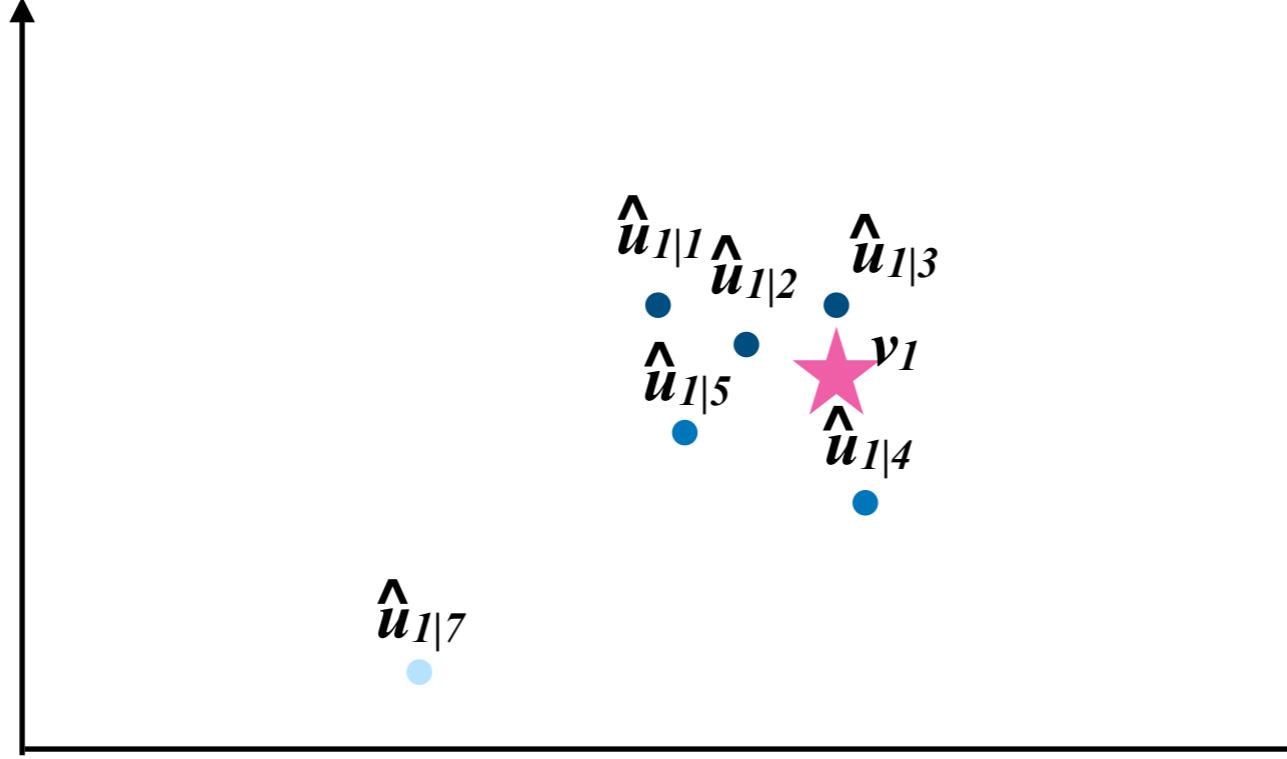
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return  $\mathbf{v}_j$ 

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capsule		VS.
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Operations	Linear/Affine Transformation	$\hat{u}_{j i} = \mathbf{W}_{ij} \mathbf{u}_i$ (Eq. 2)
	Weighting	$s_j = \sum_i c_{ij} \hat{u}_{j i}$ (Eq. 2)
	Summation	
	Non-linearity activation	$\mathbf{v}_j = \text{squash}(s_j)$ (Eq. 1)
output	vector(\mathbf{v}_j)	
$\mathbf{u}_1 \xrightarrow{w_{1j}} \hat{u}_1$	\hat{u}_1	x_1
$\mathbf{u}_2 \xrightarrow{w_{2j}} \hat{u}_2$	\hat{u}_2	x_2
$\mathbf{u}_3 \xrightarrow{w_{3j}} \hat{u}_3$	\hat{u}_3	x_3
	$\Sigma \text{ squash}(\cdot) \rightarrow \mathbf{v}_j$	+1
	$\text{squash}(s) = \frac{\ s\ ^2}{1 + \ s\ ^2} \frac{s}{\ s\ }$	
Capsule = New Version Neuron vector in, vector out VS. scalar in, s		

Dynamic Routing

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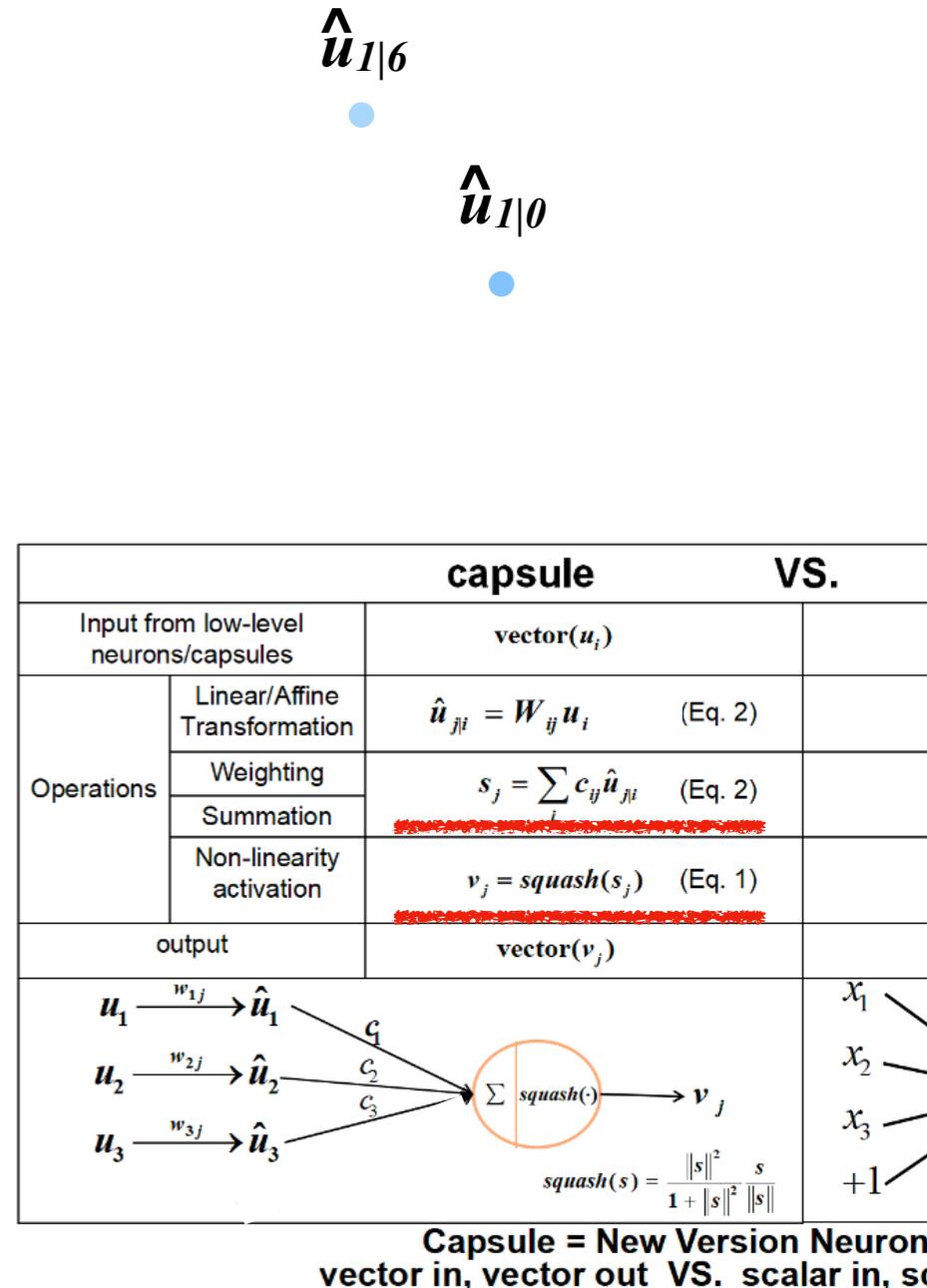


Procedure 1 Routing algorithm.

```

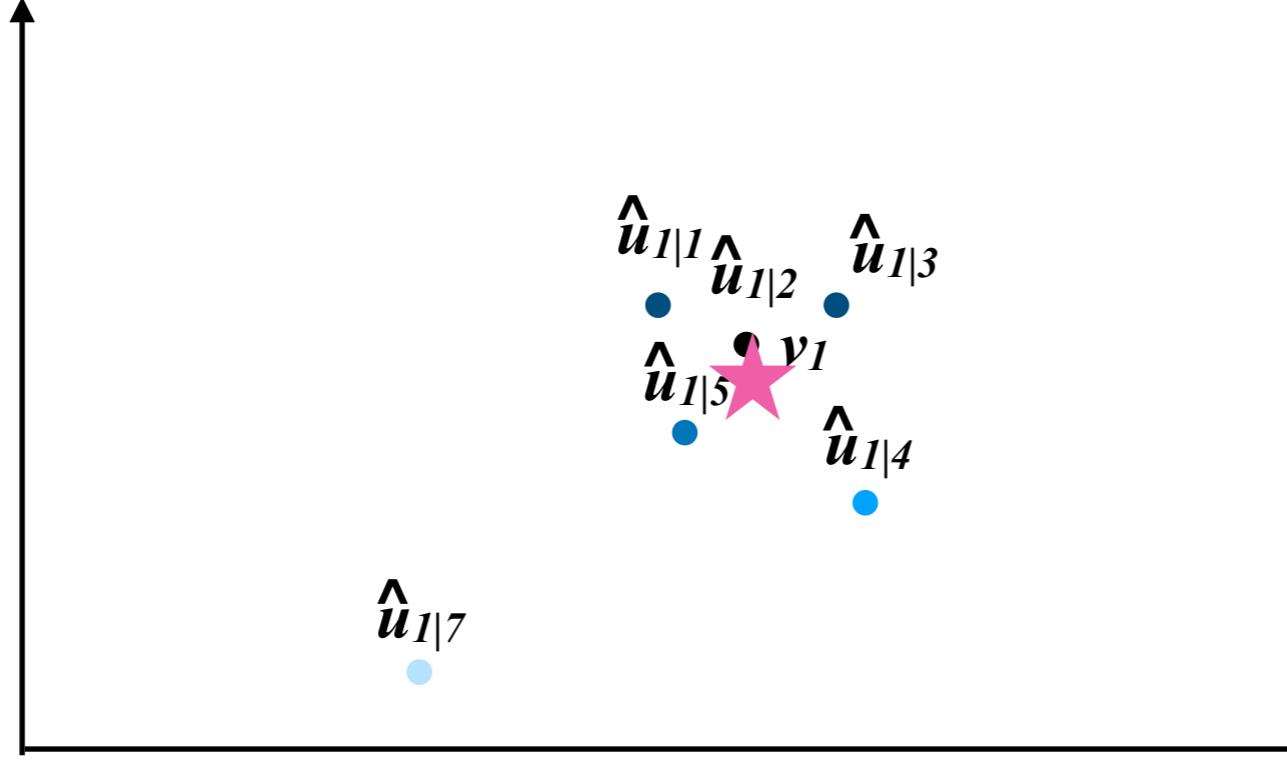
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Dynamic Routing

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Procedure 1 Routing algorithm.

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	Summation		
	Non-linearity activation	$v_j = \text{squash}(s_j)$	(Eq. 1)
		output	vector(v_j)
		$u_1 \xrightarrow{w_{1j}} \hat{u}_1$	x_1
		$u_2 \xrightarrow{w_{2j}} \hat{u}_2$	x_2
		$u_3 \xrightarrow{w_{3j}} \hat{u}_3$	x_3
		$\Sigma \text{ squash}(\cdot) \rightarrow v_j$	+1
		$\text{squash}(s) = \frac{\ s\ ^2}{1 + \ s\ ^2} \frac{s}{\ s\ }$	
Capsule = New Version Neuron vector in, vector out VS. scalar in, scalar out			

Learning

Learning: loss function

$$m^+ = 0.9$$

$$m^- = 0.1$$

Margin loss function

$T_k = 1$ if digit of class k is present

$$\lambda = 0.5$$

$$L_k = T_k \max(0, m^+ - \|\mathbf{v}_k\|)^2 + \lambda (1 - T_k) \max(0, \|\mathbf{v}_k\| - m^-)^2$$

Translation to English:

“For digit capsule k,

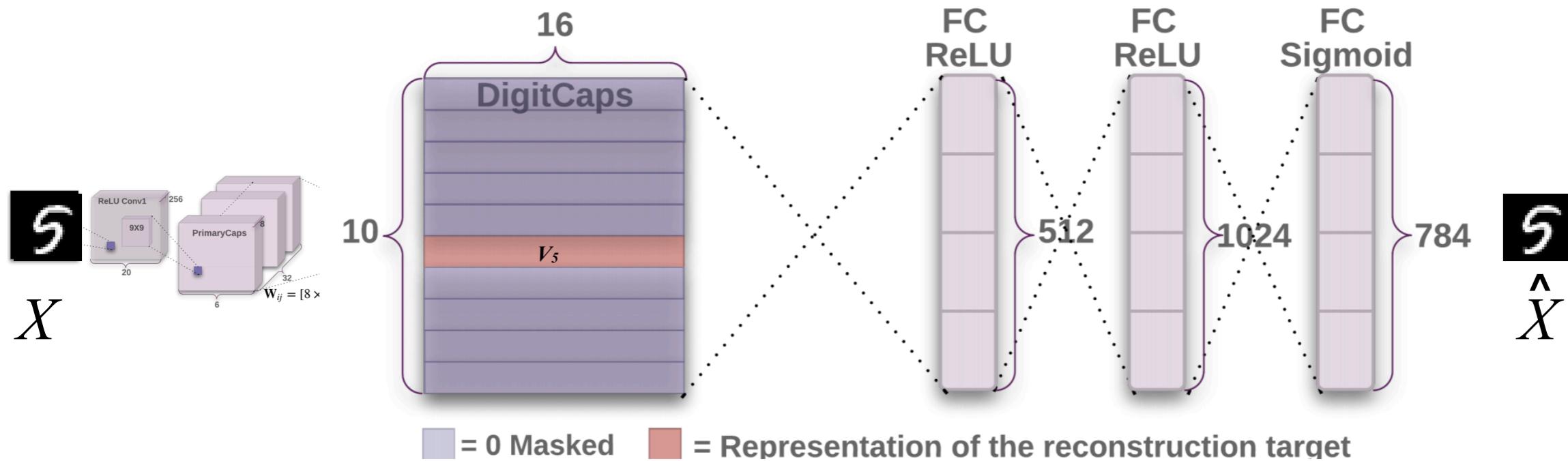
If an input image is digit k, then $\|V_k\|^2$ should be no less than 0.9.

If not, then $\|V_k\|^2$ should be no more than 0.1.”

Learning: loss function

Reconstruction loss function

$$L_{re} = ||X - \hat{X}||$$



Learning: loss function

Loss function

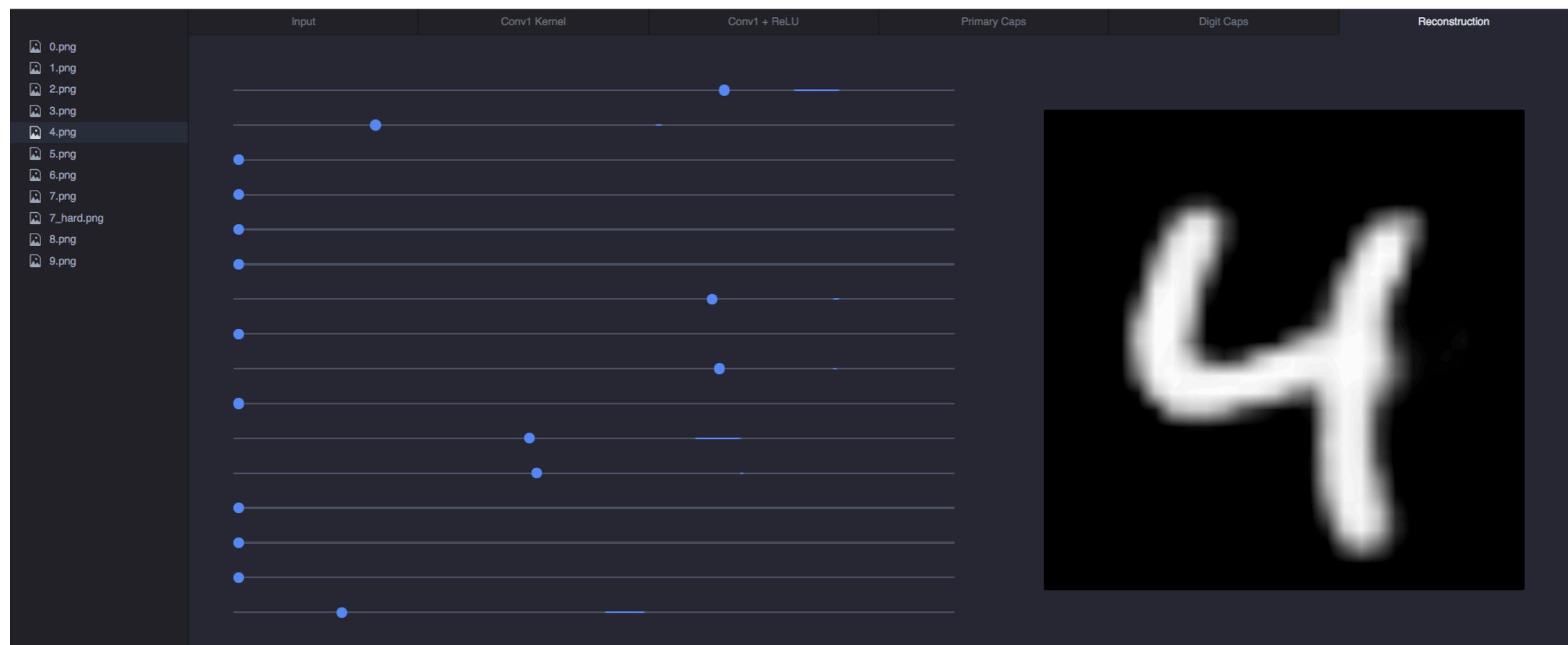
$$L = \sum L_k + 0.0005 \cdot L_{re}$$

Updated weights:

All the weights expect C_{ij} , because C_{ij} is not weights of the model.

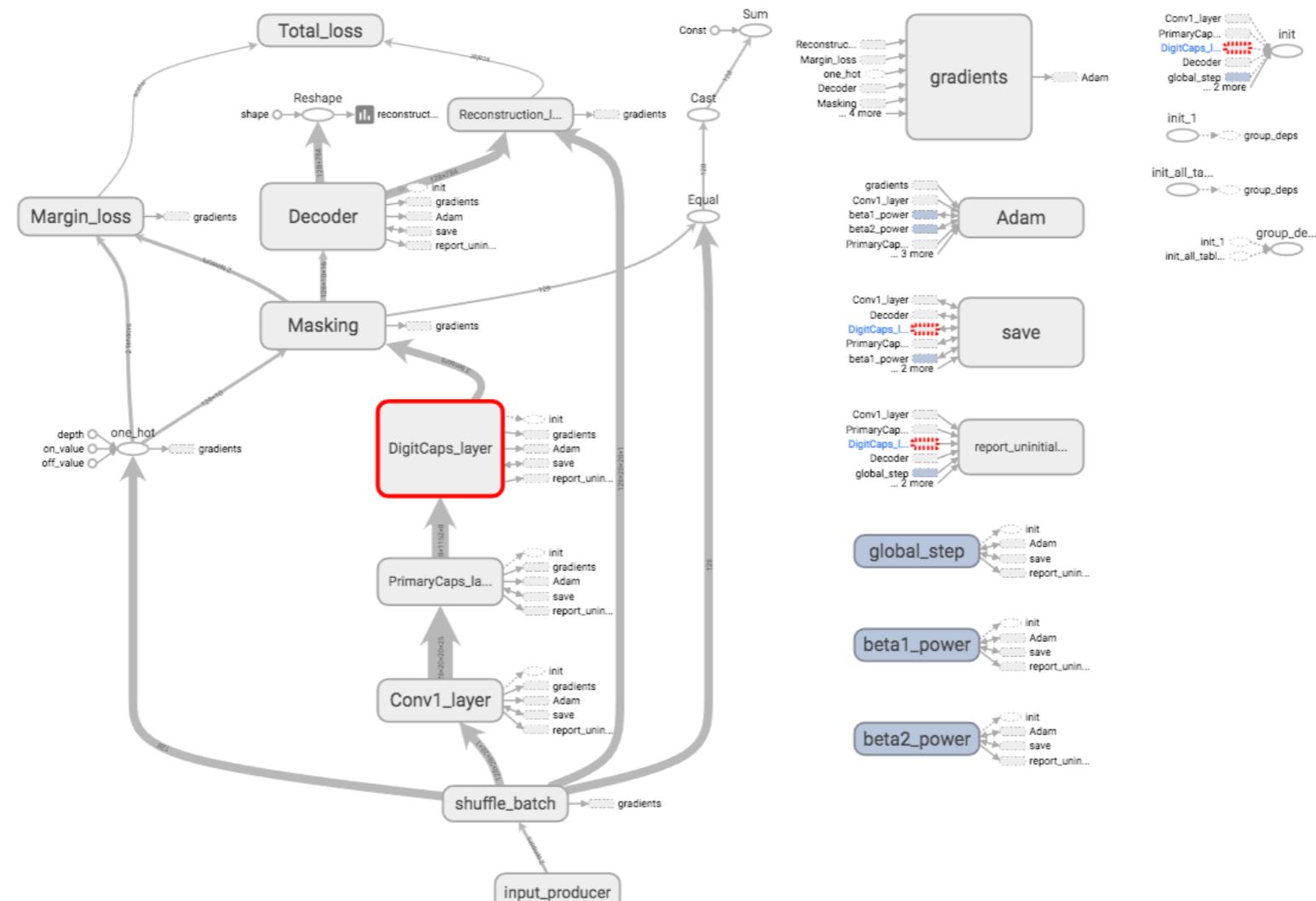
Demo on the reconstruction from digit capsules

Credit goes to
[https://github.com/bourdakos1/CapsNet-
Visualization](https://github.com/bourdakos1/CapsNet-Visualization)



Computation graph of capsule net in TensorBoard

Credit goes to
<https://github.com/naturomics/CapsNet-Tensorflow>



More Resource

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A curated list of awesome resources related to capsule networks

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aisummary Added the missing link to the Keras subsection in the table of contents Latest commit de8594a 11 days ago

README.md Added the missing link to the Keras subsection in the table of contents 11 days ago

diagram.png Added figure 1 from Sabour et al. (2017) 2 months ago

README.md

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A curated list of awesome resources related to capsule networks maintained by AI Summary.

Contributing

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<https://github.com/aisummary/awesome-capsule-networks>

Capsule net should say it's not a person





Thank you!

