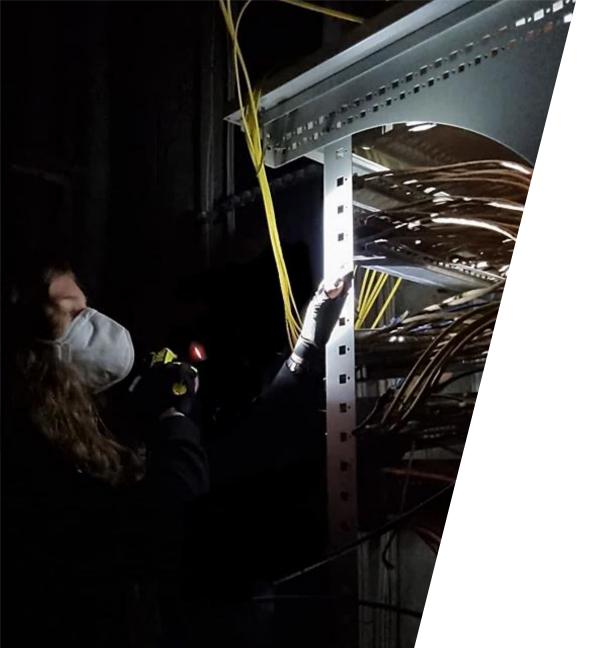
Networks on Wheels An Introduction to Automotive Networks

Lara Hallaczek :: DENOG15 :: 2023-11-21





whoami

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- System Security Engineer at Robert Bosch GmbH
- Practical Computer Science (M.Sc.)
 Student at FernUniversität in Hagen
- Volunteer at Selfnet e.V.



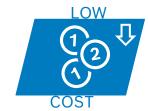
Use Cases



Requirements







Examples







Use Cases



Requirements







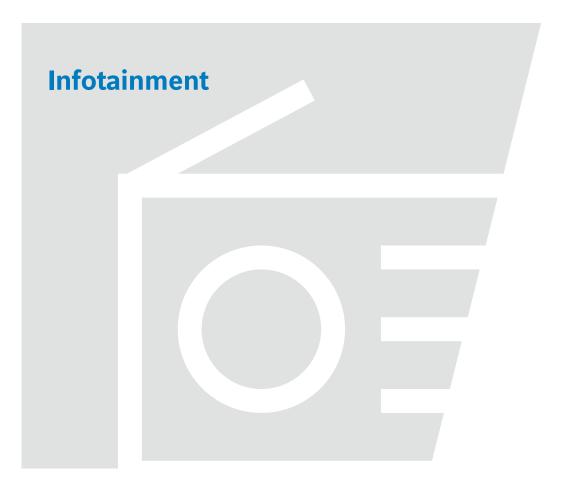
Examples







Use Cases



Requirements







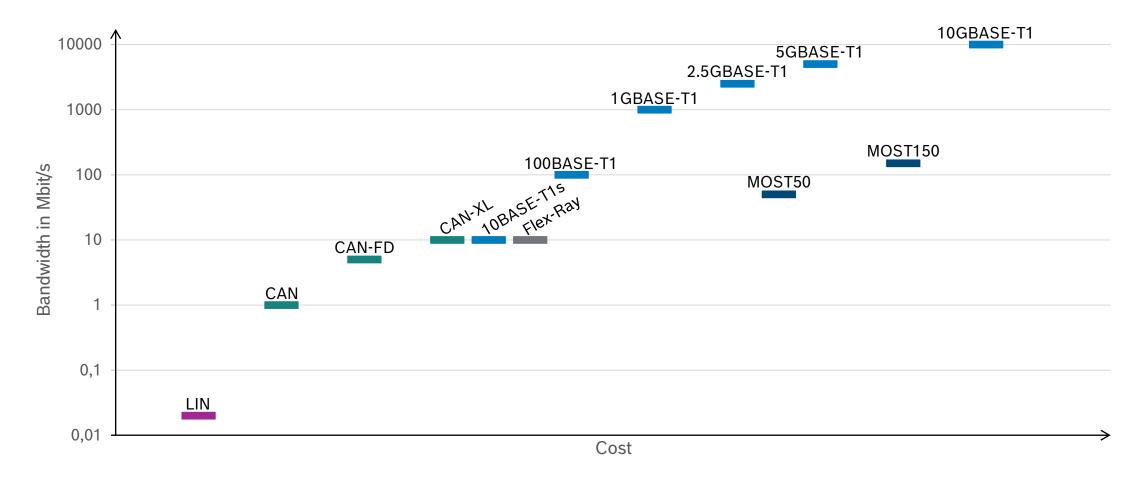
Examples





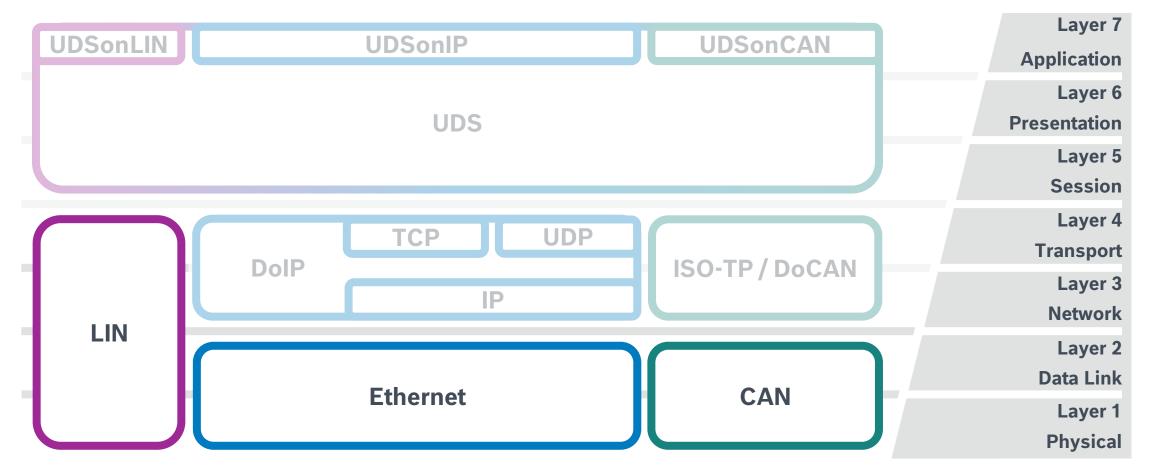


Bus Systems



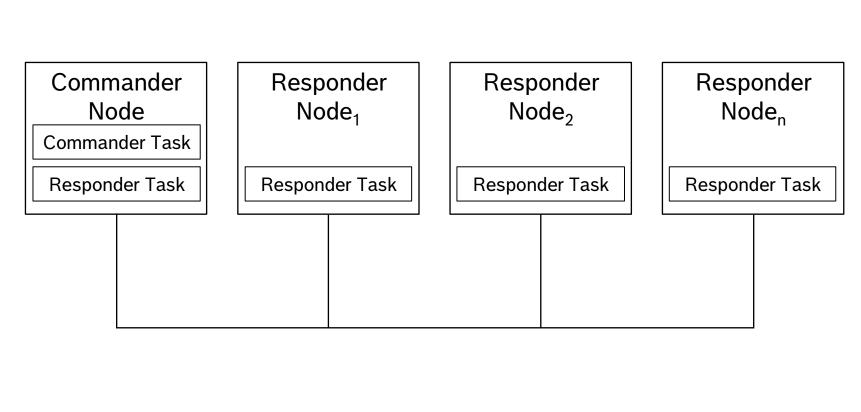


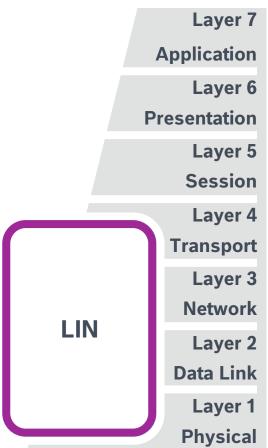
Automotive Networks Protocol Stack



Local Interconnect Network (LIN)

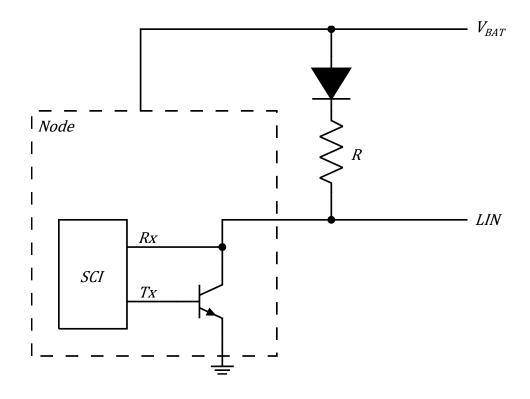
Overview





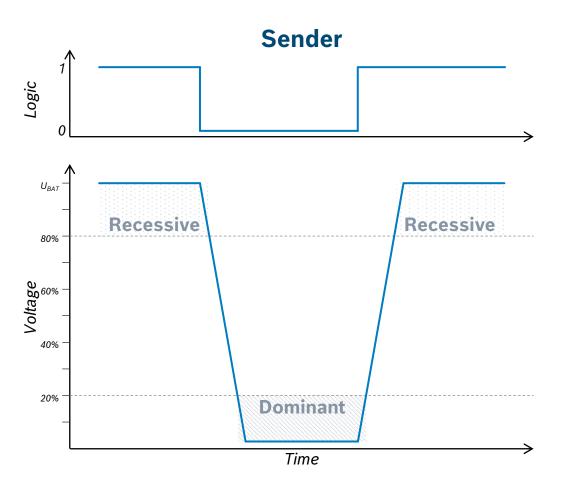


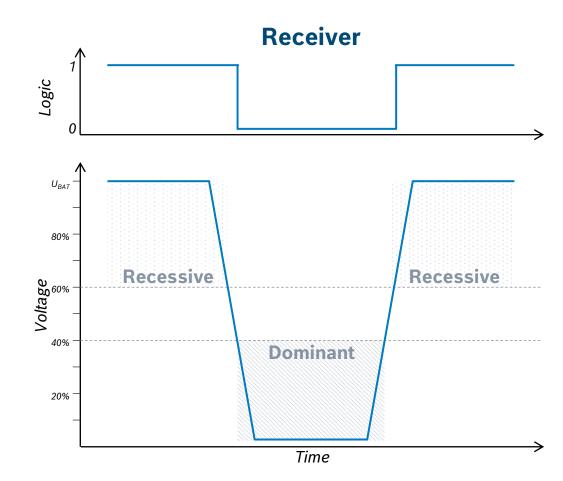
Local Interconnect Network (LIN) Driver Schematic





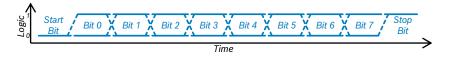
Local Interconnect Network (LIN) Encoding

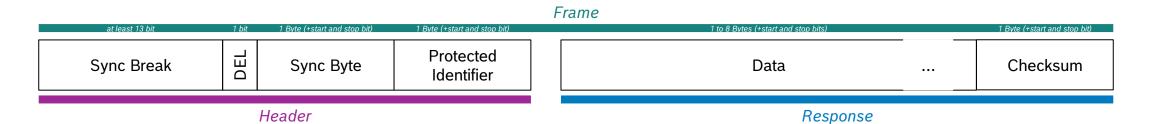






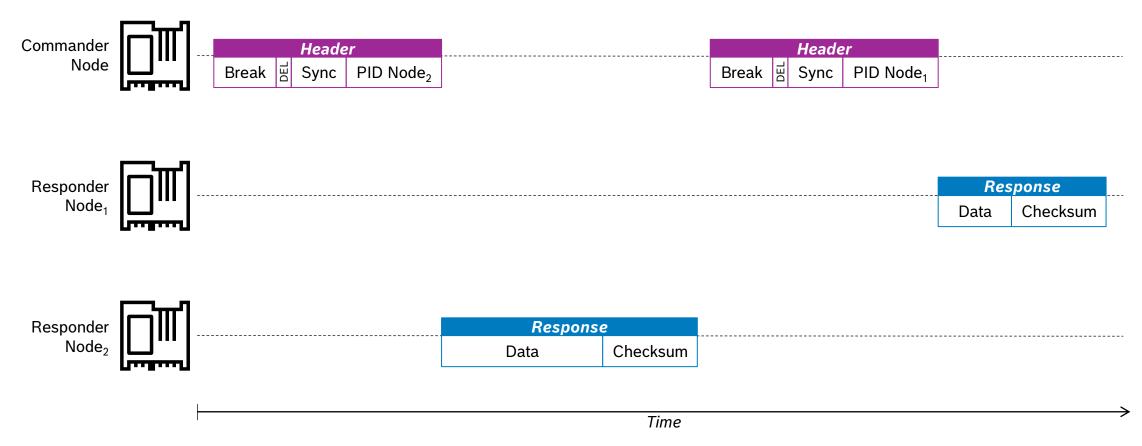
Local Interconnect Network (LIN) Frame Format





Local Interconnect Network (LIN)

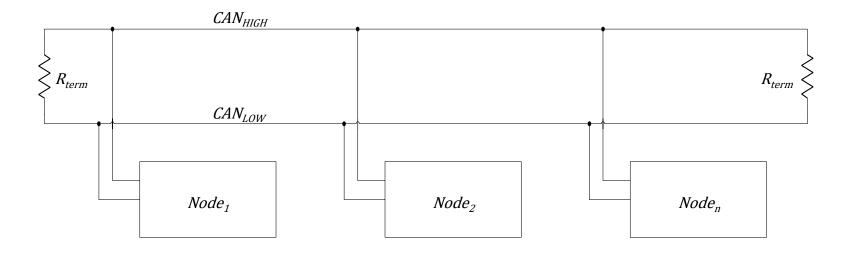
Commander - Responder Communication





Controller Area Network (CAN)

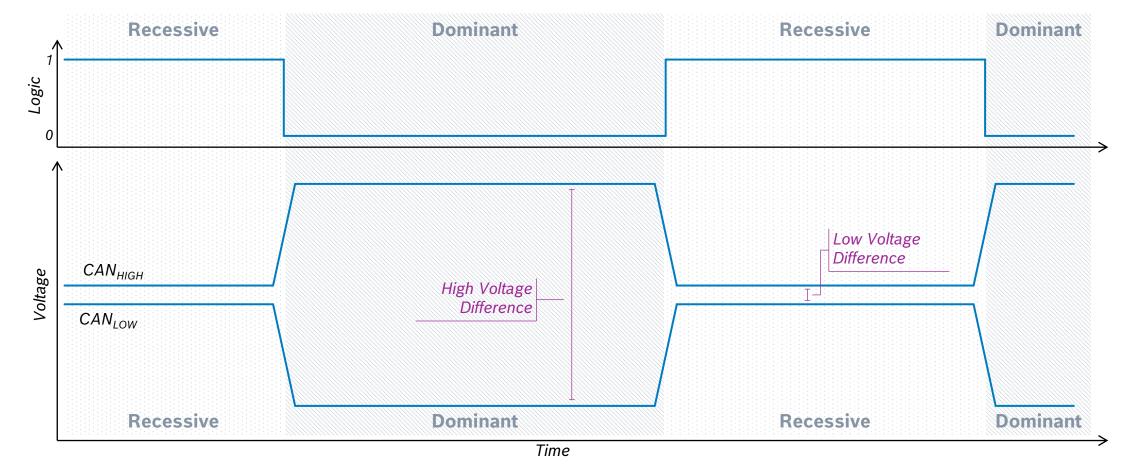
Overview



Layer 7 **Application** Layer 6 **Presentation** Layer 5 **Session** Layer 4 **Transport** Layer 3 **Network** Layer 2 **Data Link CAN** Layer 1 **Physical**



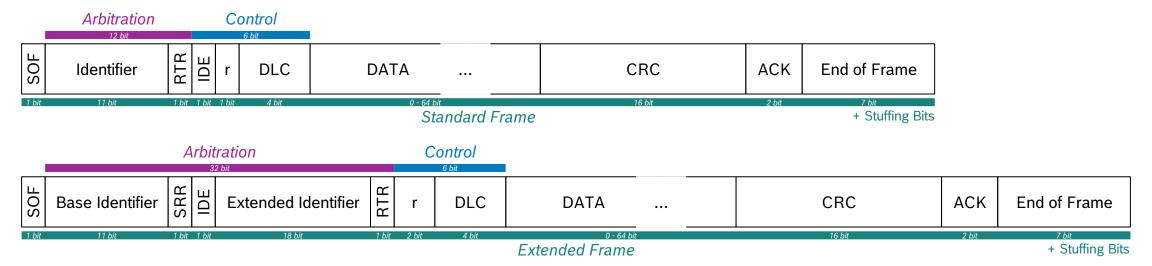
Controller Area Network (CAN) **Encoding**



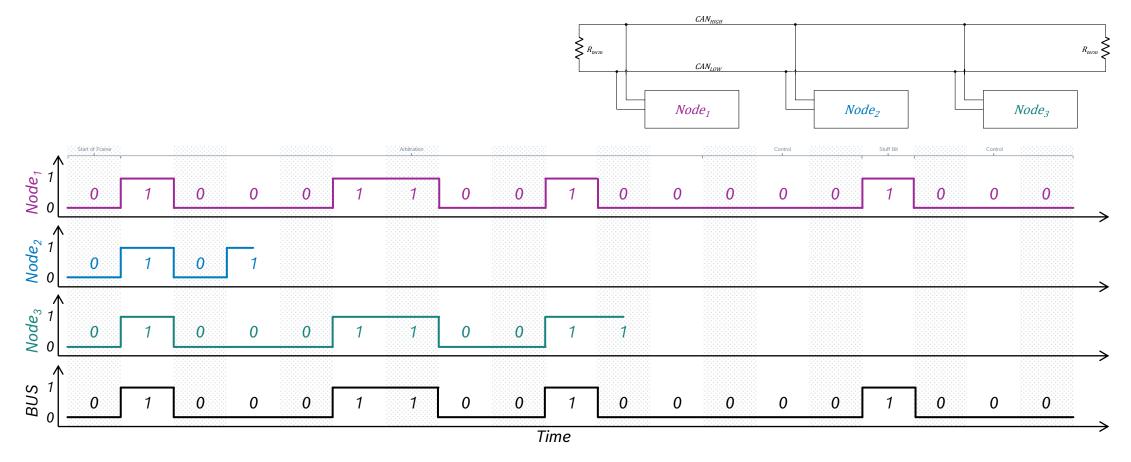


Controller Area Network (CAN)

Frame Format

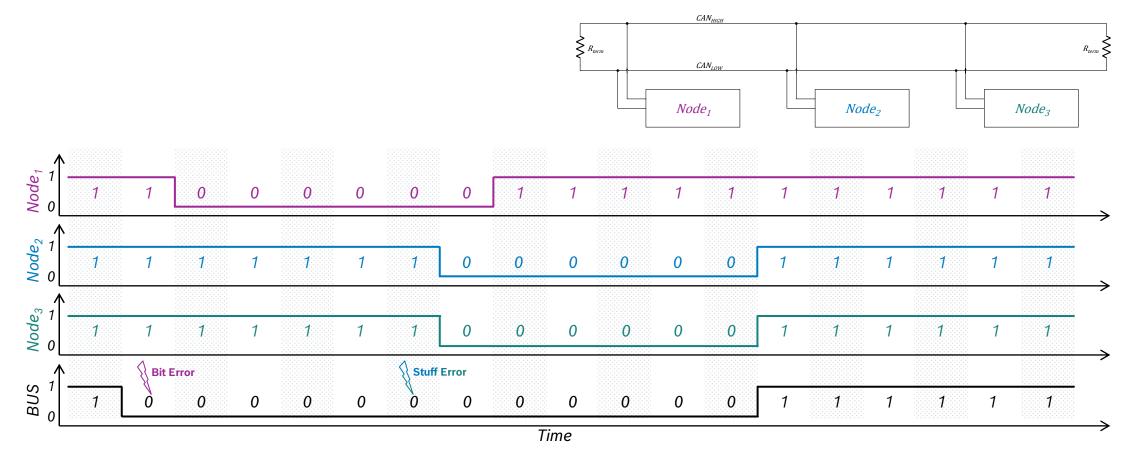


Controller Area Network (CAN) Arbitration



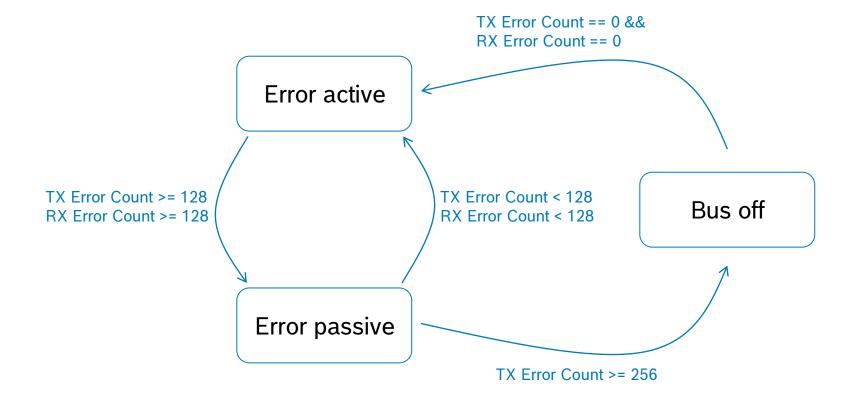


Controller Area Network (CAN) Error Handling



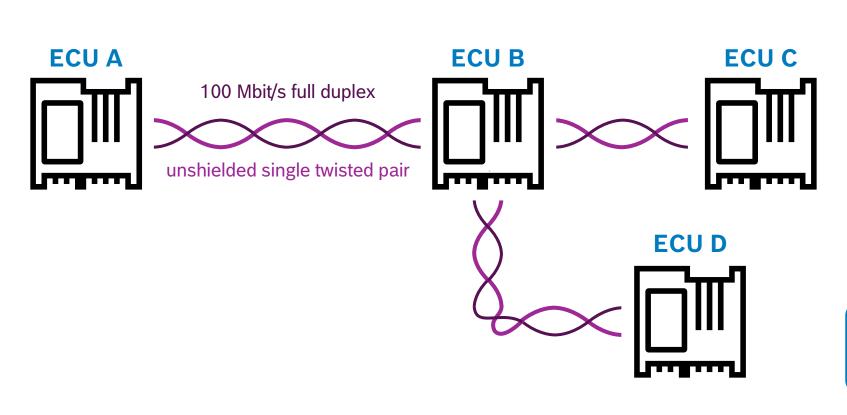


Controller Area Network (CAN) Error State



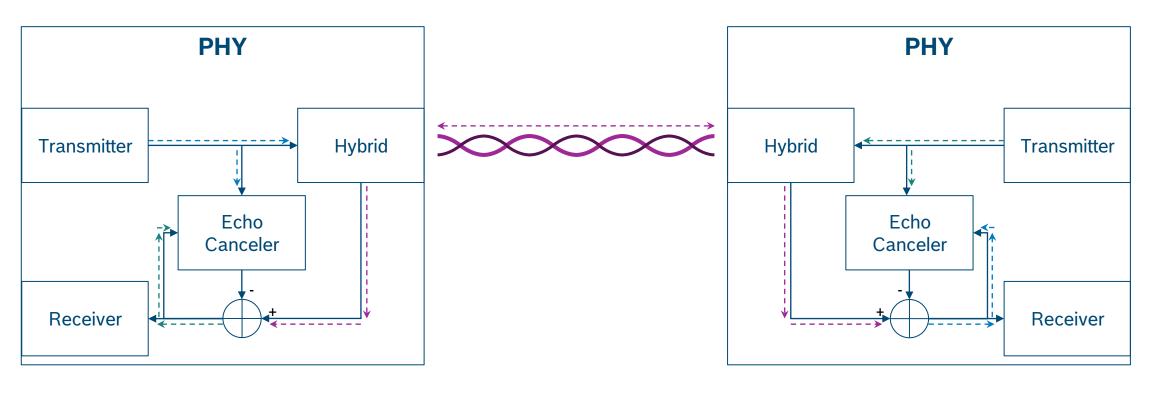


Automotive Ethernet (100Base-T1) Overview



Layer 7 **Application** Layer 6 **Presentation** Layer 5 Session Layer 4 **Transport** Layer 3 **Network** Layer 2 **Data Link Automotive Ethernet** Layer 1 **Physical**

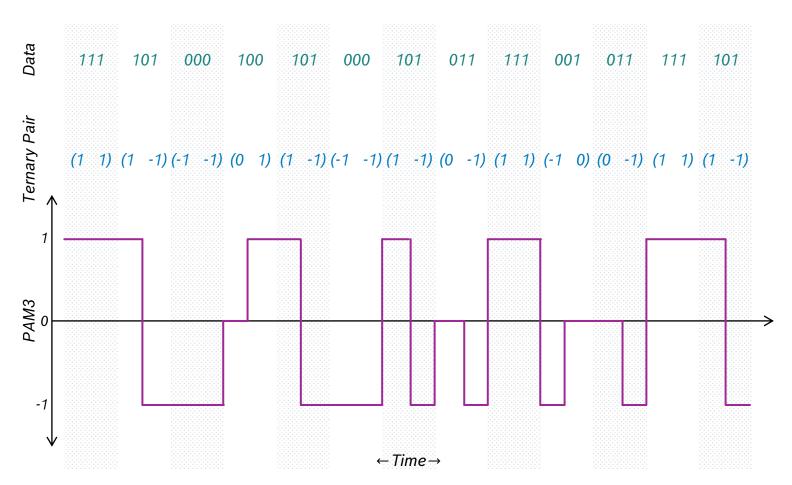
Automotive Ethernet (100Base-T1) PHY Schematic

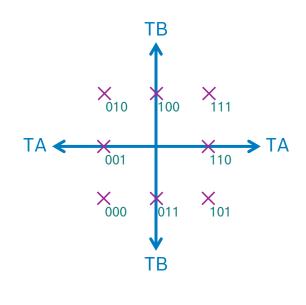




Automotive Ethernet (100Base-T1)

PAM3 Encoding







Automotive Ethernet (100Base-T1) Frame Format

Packet

up to 1329/1339/2006								
Preamble 7 Bytes	SFD 1 Byte	Destination Address	Source Address 6 Bytes	Length/ Type	MAC Client Data + Pad 46 to 1500/1504/1982 Bytes		FCS 2 Bytes	

p to 1518/1522/2000 Bvtes

Frame

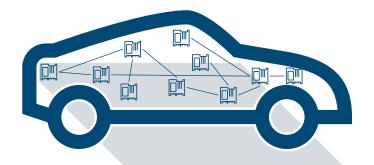


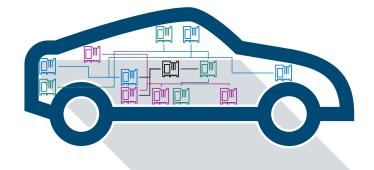
E/E Architectures Overview

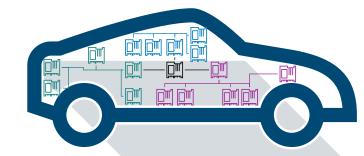
Distributed Architecture

Domain Architecture

Zone Architecture



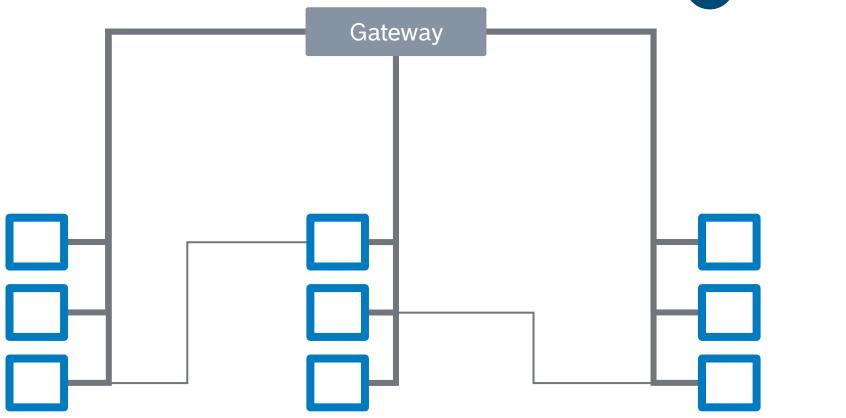






E/E Architectures **Distributed Architecture**

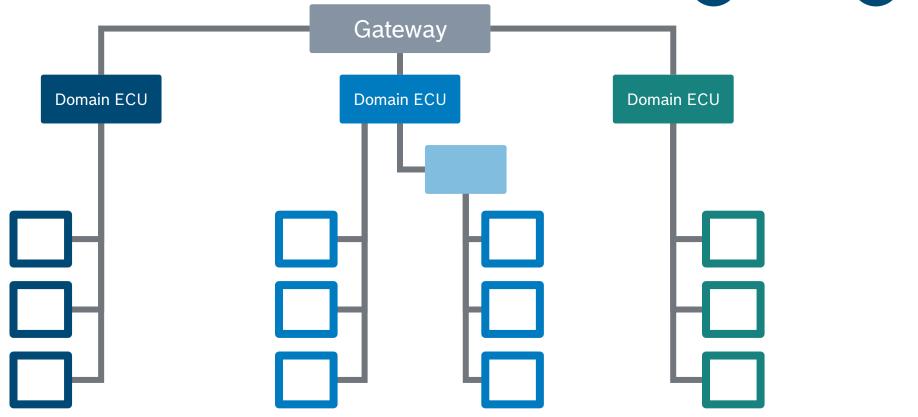






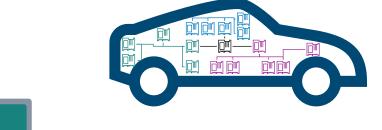
E/E Architectures

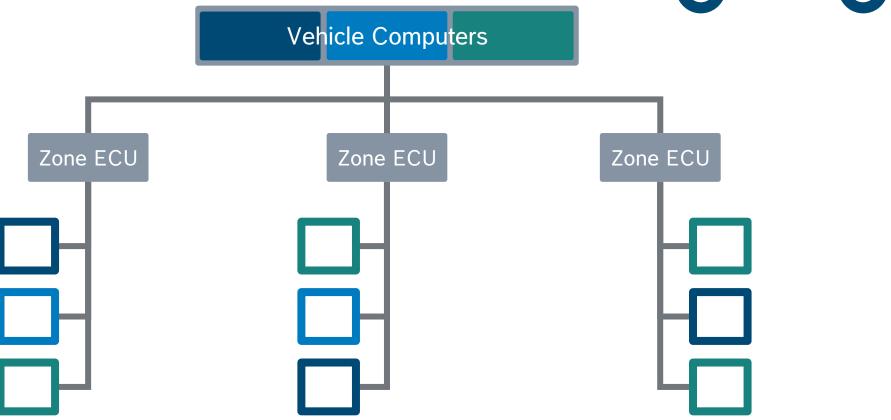






E/E Architectures Zone Architecture





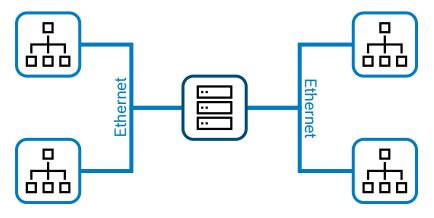




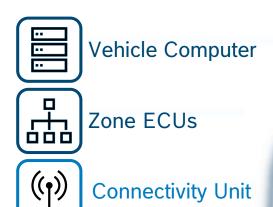


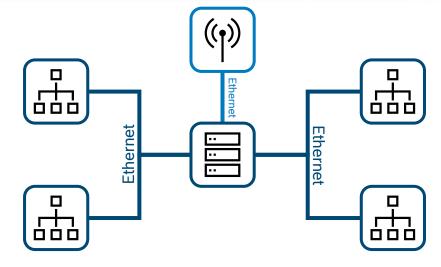




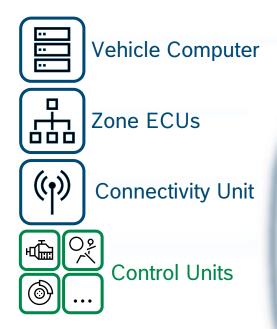


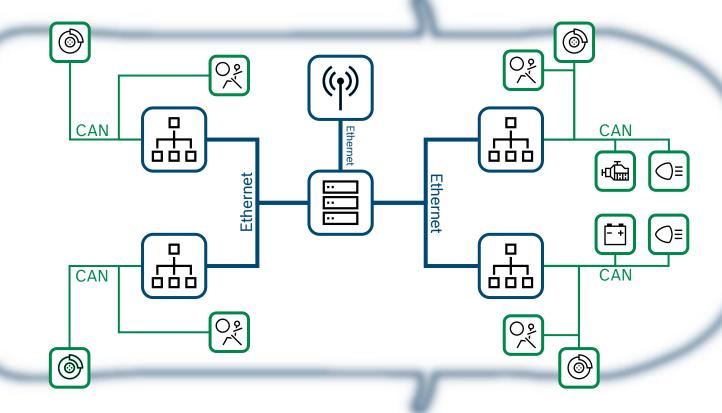






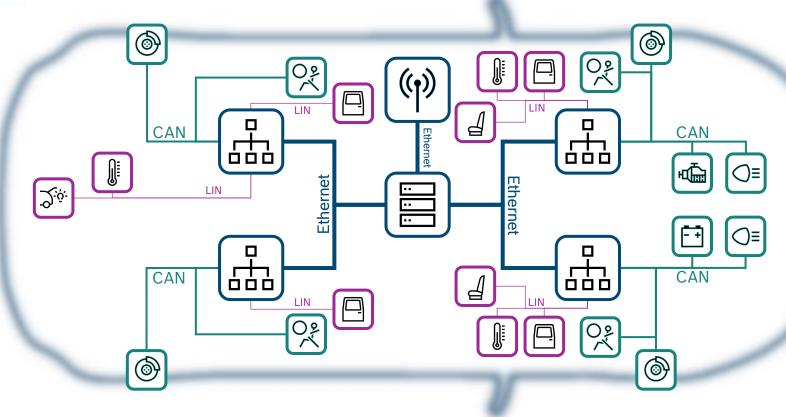






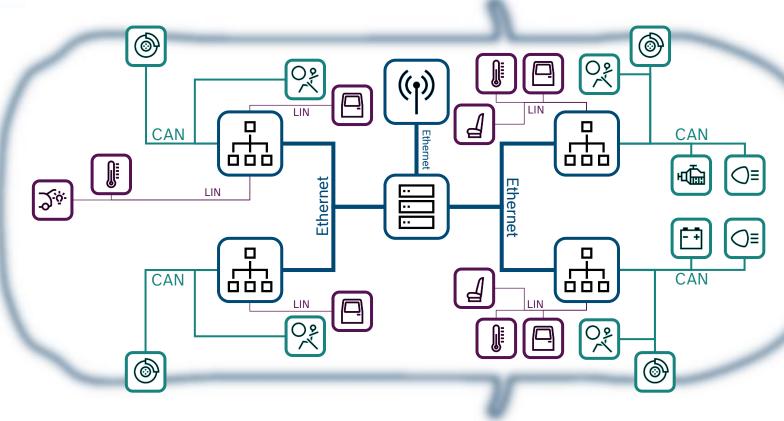
















Thank
You
For
Your
Attention

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Appendix A Abbreviations

ACK	Acknowledge	MSB	Most Significant Bit
ADAS	Advanced Driver Assistance System	PAM	Pulse-amplitude modulation
CAN	Controller Area Network	PID	Protected Identifier
CAN-FD	Controller Area Network Flexible Data-Rate	r	Reserved
CRC	Cyclic Redundancy Check	RTR	Remote Transmission Request
DEL	Sync Break Delimiter	Rx	Receive
DLC	Data Length Content	SCI	Serial Communication Interface
DoCAN	Diagnostic communication over CAN	SFD	Start Frame Delimiter
DoIP	Diagnostics over IP	SOF	Start of Frame
ECU	Electronic Control Unit	SRR	Substitute Remote Request
E/E Architecture	Electrical/Electronic Architecture	TCP	Transmission Control Protocol
FCS	Frame Check Sequence	Tx	Transmit
IDE	Identifier Extension	UDP	User Datagram Protocol
IP	Internet Protocol	UDS	Unified Diagnostic Services
LIN	Local Interconnect Network	UDSonCAN	Unified Diagnostic Services on CAN
LSB	Least Significant Bit	UDSonIP	Unified Diagnostic Services on IP
MAC	Media Access Control	UDSonLIN	Unified Diagnostic Services on LIN



MOST

Media Oriented Systems Transport

Appendix B

Relevant Standards

- [1] Institute of Electrical and Electronics Engineers, "IEEE Std 802.3bw: IEEE Standard for Ethernet Amendment 1: Physical Layer Specifications and Management Parameters for 100 Mb/s Operation over a Single Balanced Twisted Pair Cable (100BASE-T1)".
- [2] International Organization for Standardization, "ISO 11898: Road vehicles Controller area network (CAN)".
- [3] International Organization for Standardization, "ISO 17987: Road vehicles Local Interconnect Network (LIN)".

