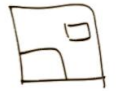


TODO

- try fuzzy DCSolve first
- think abt alternative search techniques
- what's allowed under the umbrella of 'objectness priors'?

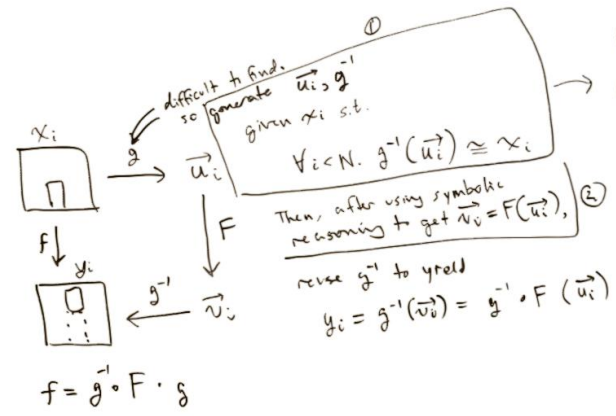


rect, pt, bitmap
(and hence, bad)

rect
pt x pt \rightarrow bitmap

prog
bitmap x bitmap \rightarrow bitmap

+ no recursive grammar



DCSolve

- doesn't allow composition of subs
(use one or the other)



- for small amts of data, we end up offloading search to term generation (enumerative search)

① Given $\{x_i\}_{i \in N}$, generate $\{\vec{u}_i\}_i, g^{-1}: \vec{u}_i \mapsto x_i$ s.t. $\forall i \in N. g^{-1}(\vec{u}_i) \cong x_i$.

Define approx match by taking L2 norm of pixel distance:

$$\text{error} = \sum_i \sum_{a,b} \mathbb{I}(g^{-1}(\vec{u}_i)_{a,b} \neq x_{i,a,b})$$

\uparrow over input pts \uparrow over pixels

$$\rightarrow -\log \sum_i \sum_{a,b} \mathbb{I}(g^{-1}(\vec{u}_i)_{a,b} = x_{i,a,b})$$