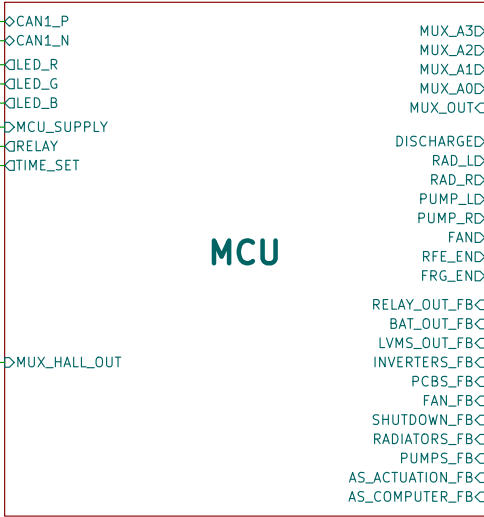


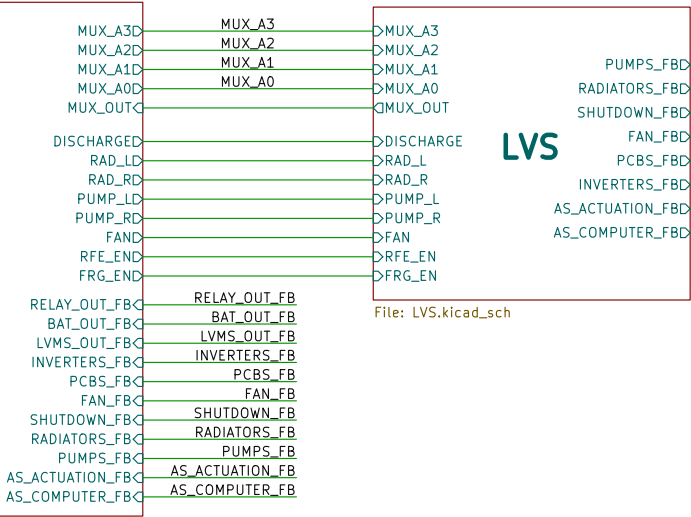
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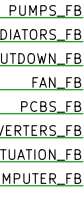
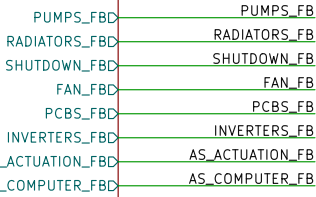
File: sensors.kicad_sch



File: MCU.kicad_sch



File: LVS.kicad_sch



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Nicolò Durisotto
E-Agle TRT

Sheet: /
File: fenice-bms-lv-hw.kicad_sch

Title: Fenice BMS LV

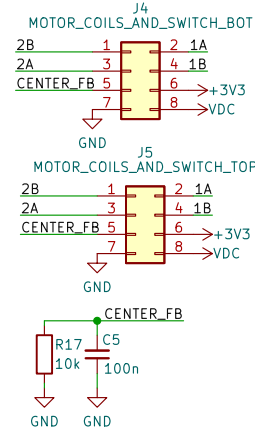
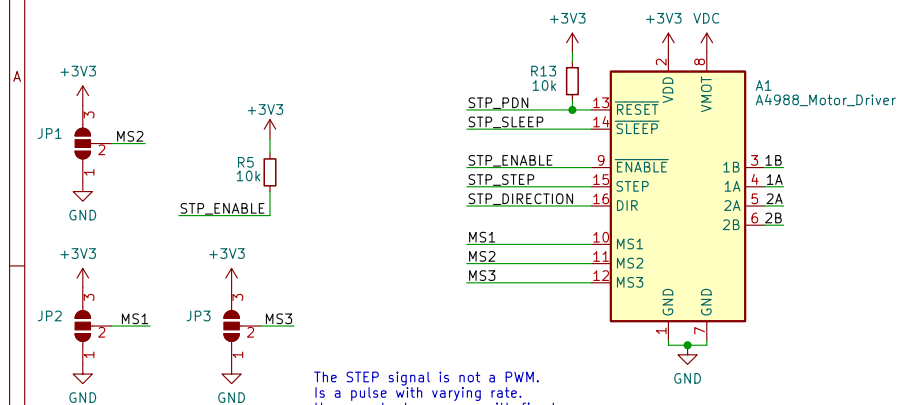
Size: A4
KiCad E.D.A. eeschema (6.0.2-0)

Date: 2021-10-12

Rev: 1.1

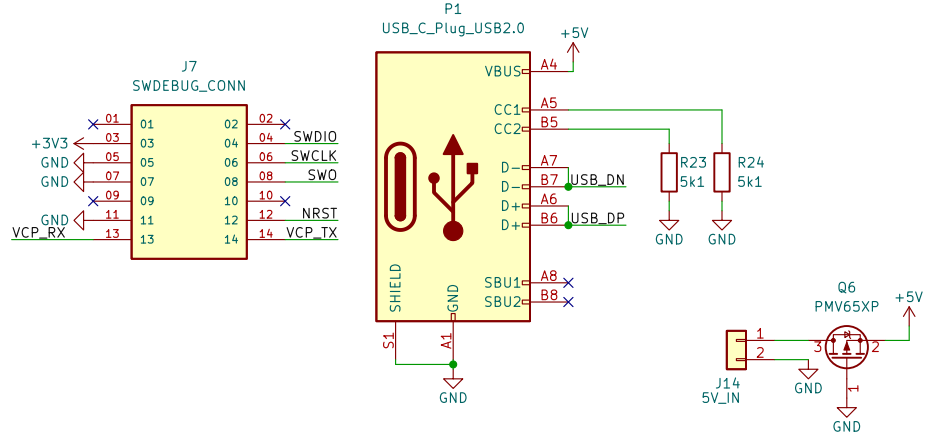
Id: 1/5

MOTOR DRIVER A4988

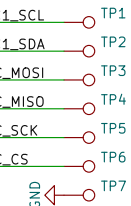


TMC2208 supports UART for unidirectional operations, the driver adapts to master's baud rate and so the pin 14 does not need an external clock unless a very high baud rate communication is needed.

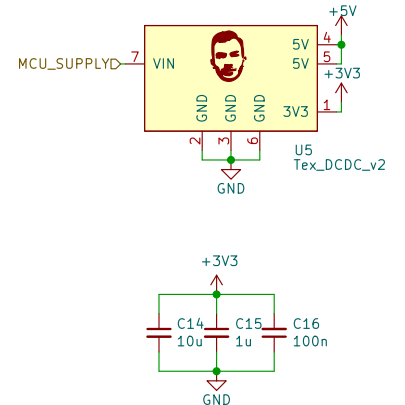
DEBUG CONNECTORS



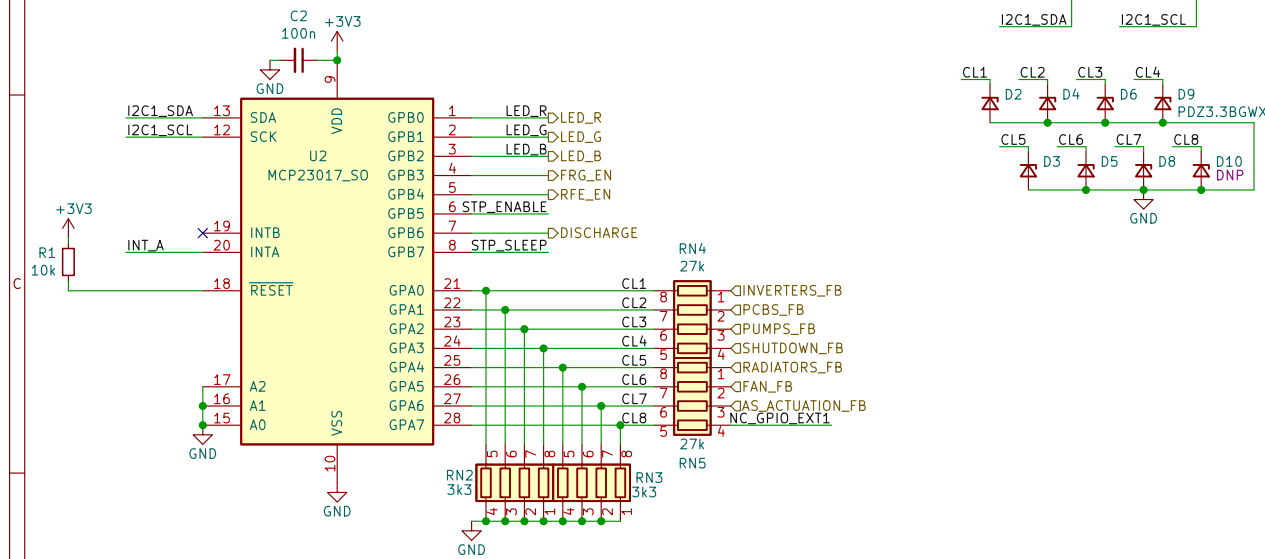
TESTPOINT



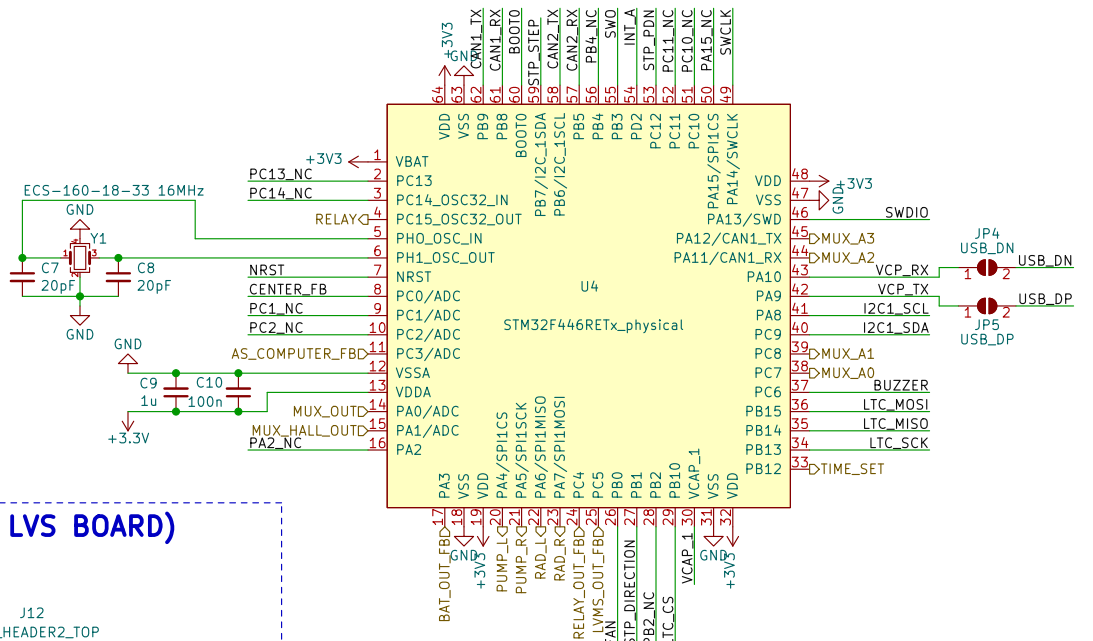
MCU POWER SUPPLY



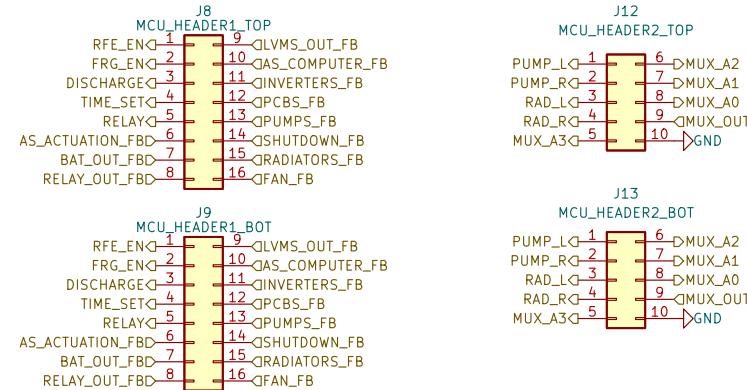
GPIO EXTENSION



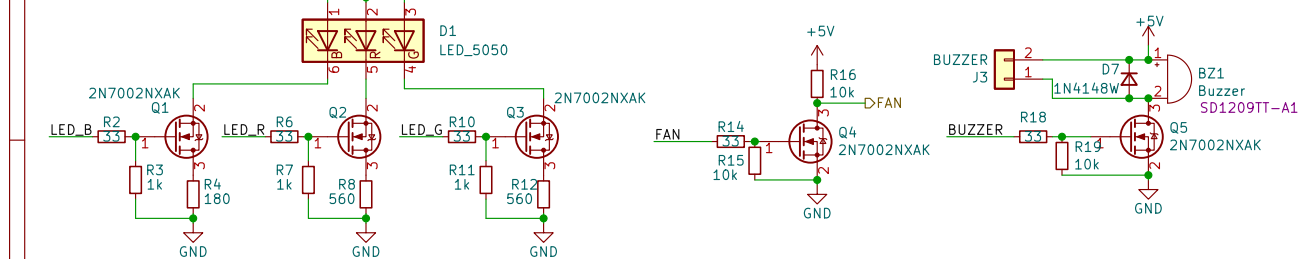
MCU



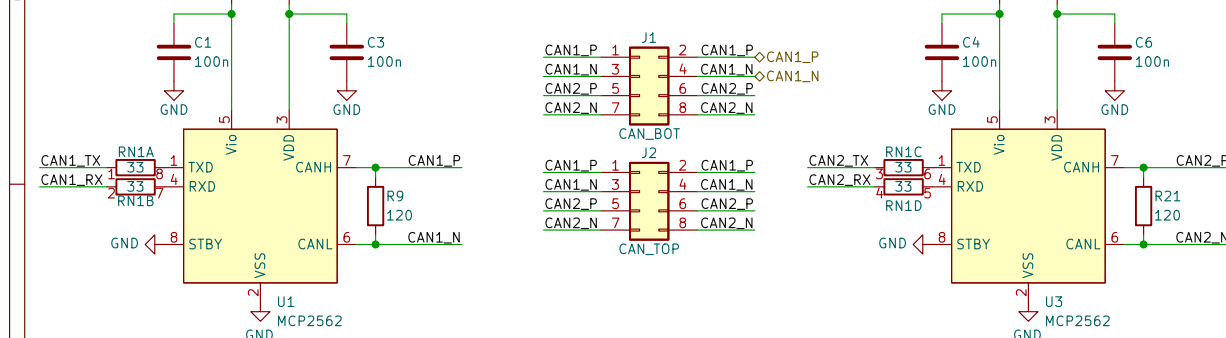
TOP TO BOTTOM HEADERS (MCU TO LVS BOARD)



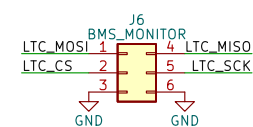
LED_OTHER, BUZZER AND FAN CONTROL



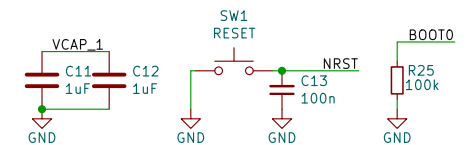
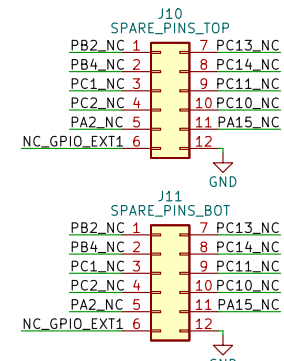
CAN TRANSCEIVERS



CELLBOARD



SPARE PINS



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Sheet: /MCU/
File: MCU.kicad_sch

Title: Fenice BMS LV

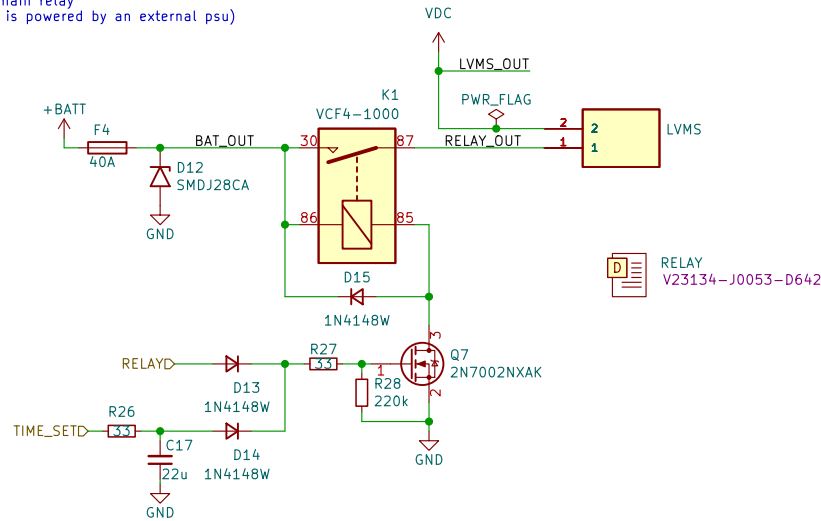
Size: A3 Date: 2021-10-12
KiCad E.D.A. eeschema (6.0.2-0)

Rev: 1.1
Id: 3/5

LVMS & BMS RELAY

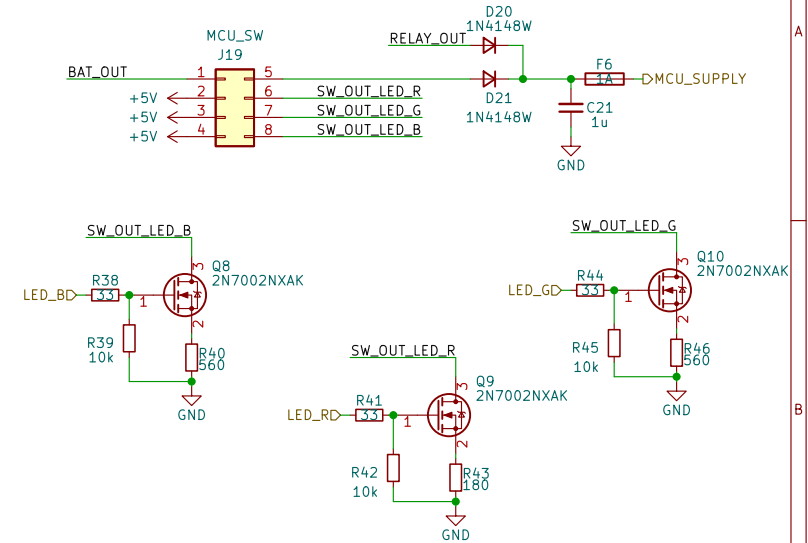
A note for SW:
if voltage at RELAY_OUT outside battery's
rated voltage, DO NOT close main relay
(this might happen if the car is powered by an external psu)

BAT_OUT_FB will also serve as feedback in order to add a self-kill switch for the MCU.
As stated in FSG rules, the LVMS must disable the whole LVS.

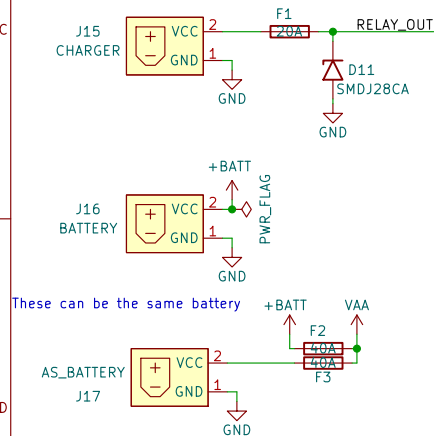


RELAY
V23134-J0053-D642

MCU SWITCH



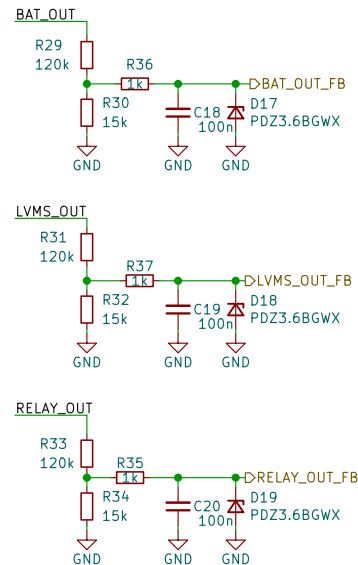
CHARGER & BATTERY CONNECTORS



These can be the same battery

A 40A fuse can be used as a jumper.
If a single battery pack is used it is
necessary to fit in the fuse to use the AS

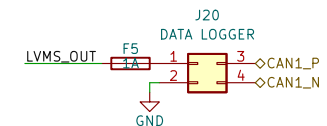
ANALOG VOLTAGES READING



For 28V the output voltage will be 3.11V

DATALOGGER

As stated in the 2022 FSG datalogger's datasheet:
The DL must be supplied by a voltage of 12 V DC to 60 V DC.
It draws a maximum power of 10 W.
It must be reasonably fused in the supply wiring.



EV 4.6.6
The datalogger must be directly supplied from the LVMS

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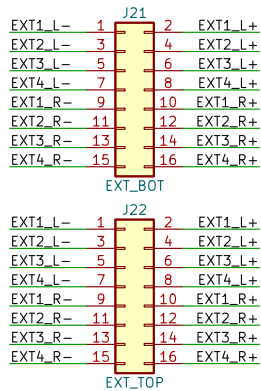
Sheet: /POWER_IN/
File: battery.kicad_sch

Title: Fenice BMS LV

Size: A4 Date: 2021-10-12
KiCad E.D.A. eschema (6.0.2-0)

Rev: 1.1
Id: 5/5

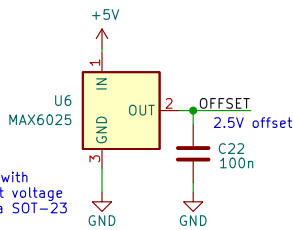
STRAIN GAUGES CONDITIONING



To determine opamp gain through Rg resistance:
 $G = 1 + (49400/R_g)$
For $G = 1.33$, $R = 164000 \text{ ohm}$
 $R = 150k$ will be chosen ($G = 1.33$)



Due to opamp's output and input swing the maximum voltage range for 3.3V is between 1.9 and 2.2V
For 5V is between 1.9V and 3.9 for input signals.
For this reason a voltage offset of 2.5V will be used.
As stated in AD8221's datasheet Vref has to be driven by a low impedance voltage source.
This can be confirmed by looking at the internal circuit diagram, an impedance on that input will affect the gain.
A voltage reference will then be used:



Also compatible with
LT1460 and most voltage
references with a SOT-23
package

Maximum voltage difference on Wheatstone bridge calculated knowing:

Maximum strain range = 10% (depends on the strain gauge type)
Reference resistance = 120 ohm
Maximum extension resistance = 132
Maximum compression resistance = 108
Amplifier gain = 1.33

Calculations at maximum extension:

$$V_- = (5 \cdot 120) / (120 + 132) = 2.38V$$
$$V_+ = (5 \cdot 132) / (120 + 132) = 2.62V$$

$$V_+ \cdot G - V_- \cdot G = 0.32V$$

Calculations at maximum compression:

$$V_- = (5 \cdot 120) / (120 + 108) = 2.63V$$
$$V_+ = (5 \cdot 108) / (120 + 108) = 2.37V$$

$$V_+ \cdot G - V_- \cdot G = -0.34V$$

With an offset of 2.5V:

$$2.18 < V_{out} < 2.79V$$

The gauge factor is calculated as follows considering the characteristics of the reference strain gauge (maximum length difference is 10% of standard length and 120 ohm resistance):

$$GF = \frac{\Delta R}{R \cdot \epsilon (\text{applied strain})} = 11$$

The gauge factor defines how much resistance changes in proportion to applied strain ϵ . To calculate the extension/compression:

$$\epsilon = \frac{\Delta l}{l}$$

$$\epsilon = \frac{\Delta R}{R \cdot GF}$$

Further calculations were put in the documentation

One sensor will measure output current from the batteries
One will be used to monitor the current from the charger

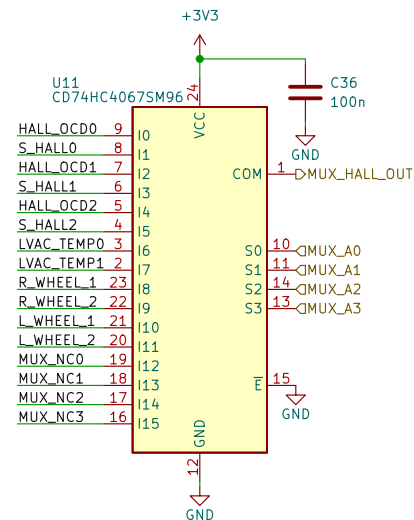
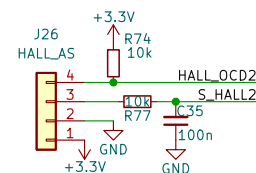
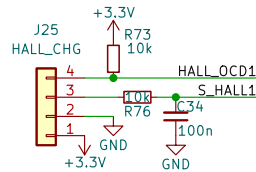
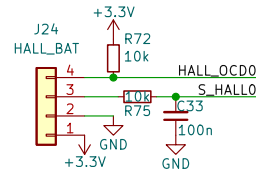
HALL CURRENT SENSORS

For the current sensor:

$V_{ref} = 1.65V$
Theoretical Sensitivity = 1.84 mV/A

$V_{out} = V_{ref} + \text{Current} \cdot \text{Sensitivity}$
Current = $(V_{out} - V_{ref}) / \text{Sensitivity}$

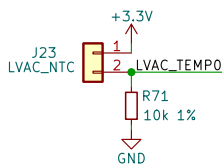
OCD is low when the current flowing
the current transducer is $2.92 \cdot I_{pn}$
 I_{pn} is the primary nominal current,
which in this case is 50A



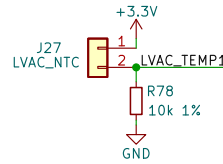
Temperature sensor to be put on mux input
for MCU pin availability issue

This can just be used during tests to
determine average current going through the AS

LVAC TEMPERATURE SENSORS



NTC Battery temperature sensor
10k



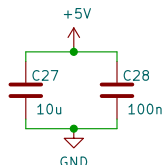
This can connector can be
attached to an NTC or alternatively
to another sensor that can be added later.

MUX_NC0
MUX_NC1
MUX_NC2
MUX_NC3

Cutoff Frequency for LPFs:

$$1 / (2 \cdot \pi \cdot 220 \cdot 10^{-7}) = 7234 \text{ Hz}$$

5V FILTER



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E-Agle TRT

Sheet: /SENSORS/
File: sensors.kicad_sch

Title: Fenice BMS LV

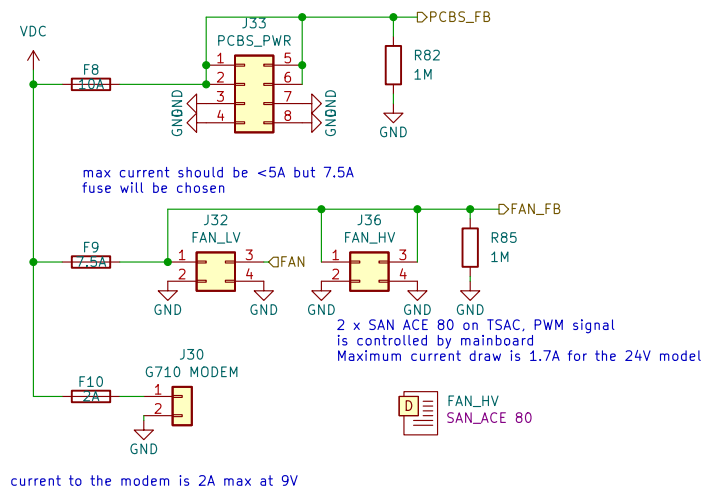
Size: A3 Date: 2021-10-12

Rev: 1.1

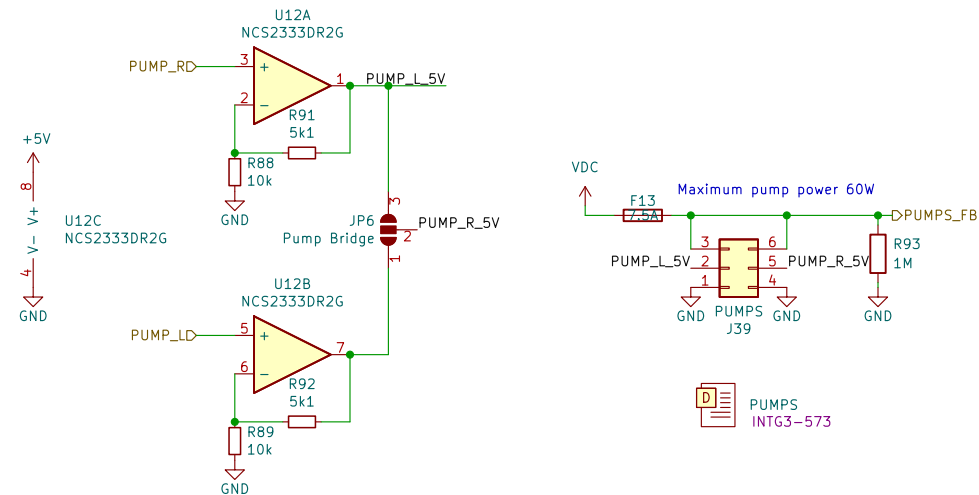
KiCad E.D.A. eeschema (6.0.2-0)

Id: 6/5

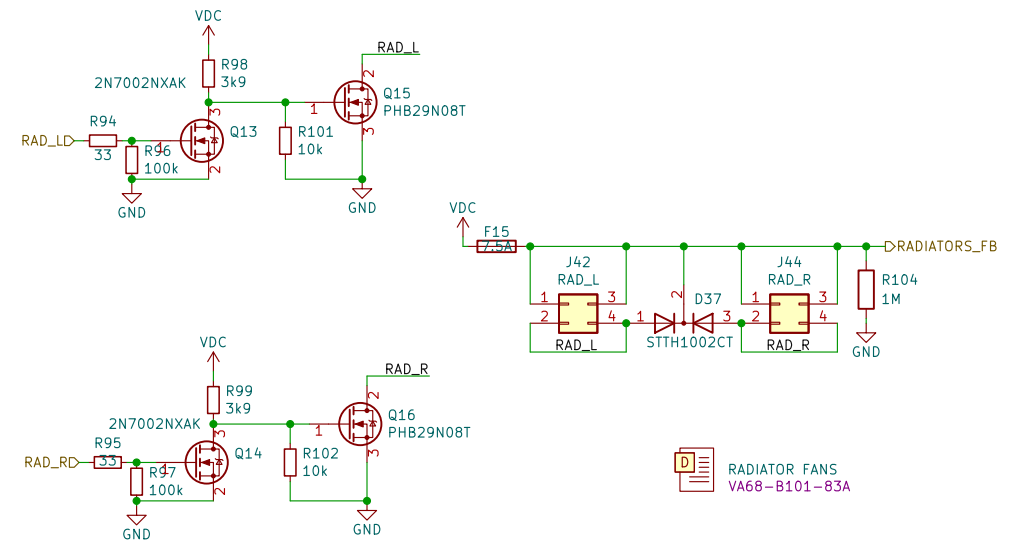
LVS CONNECTORS



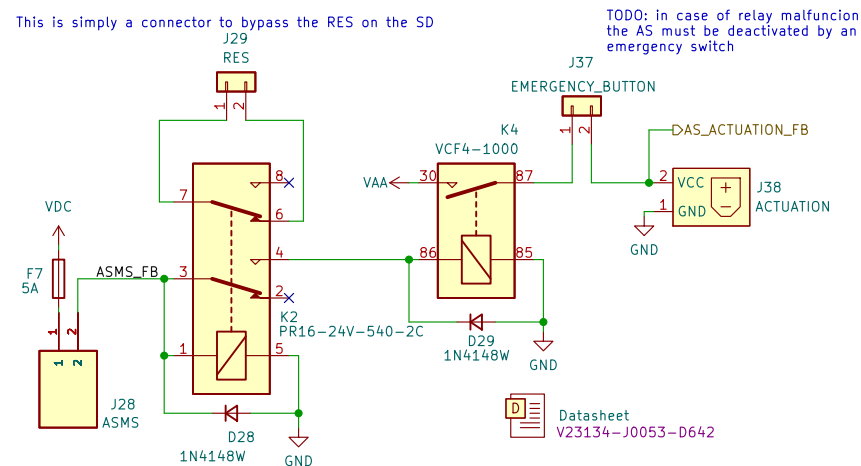
PUMPS



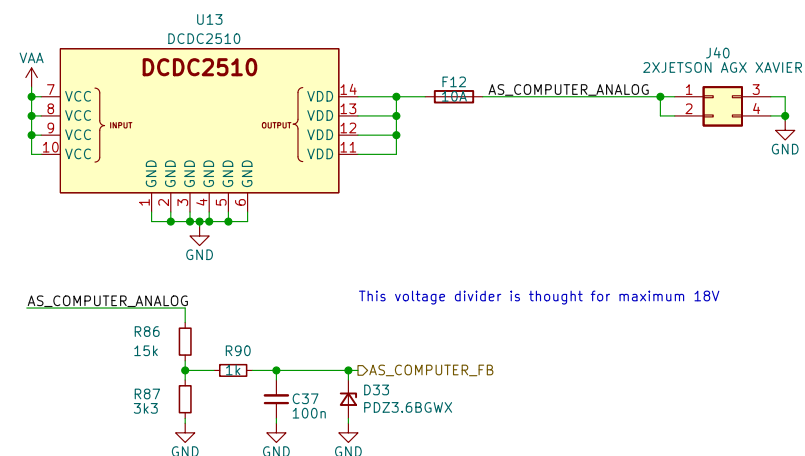
RADIATORS



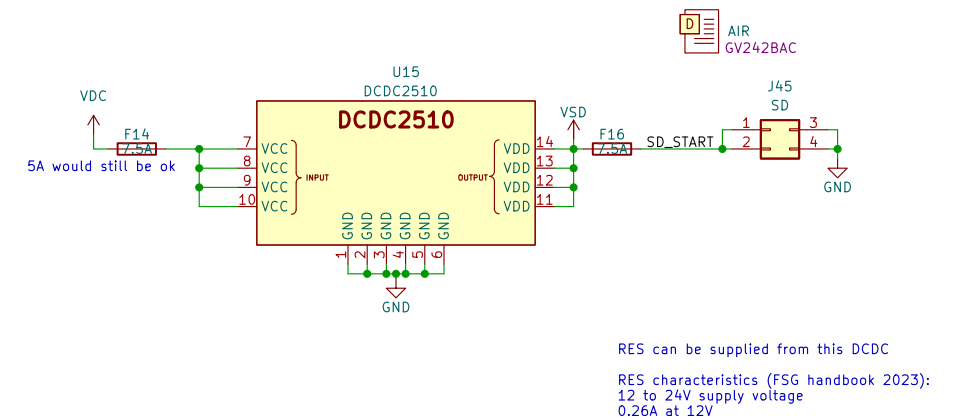
AUTONOMOUS DRIVE ENABLE



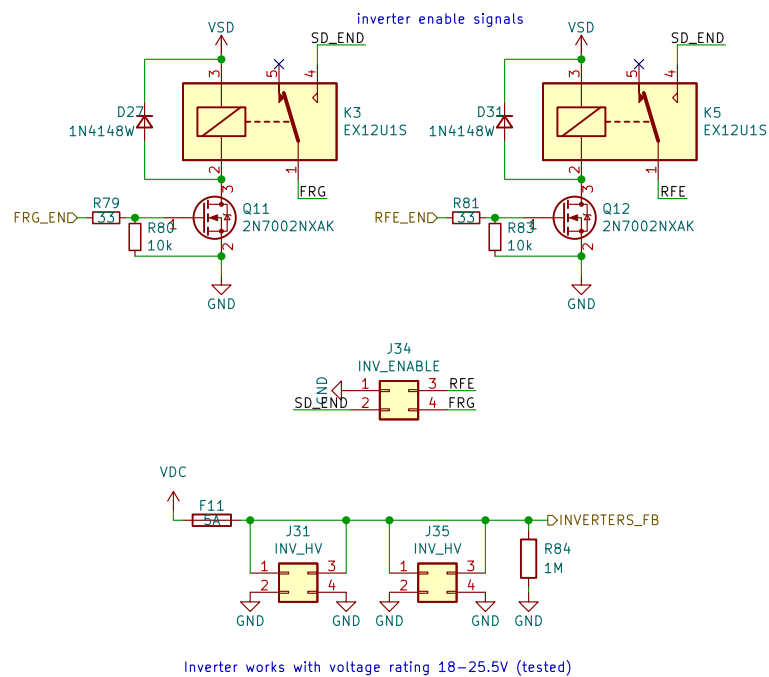
JETSON DCDC



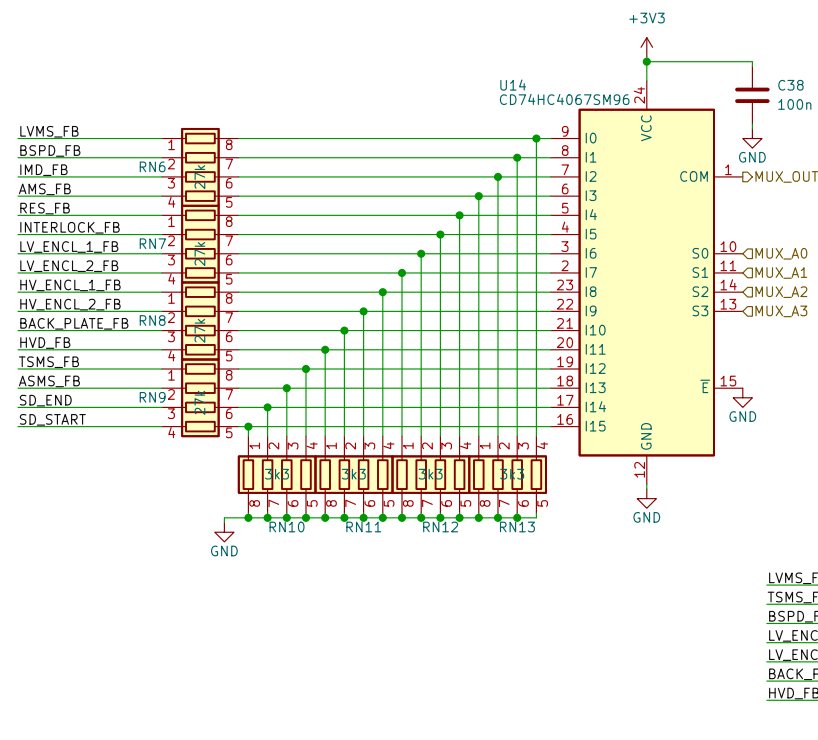
SHUTDOWN POWER SUPPLY



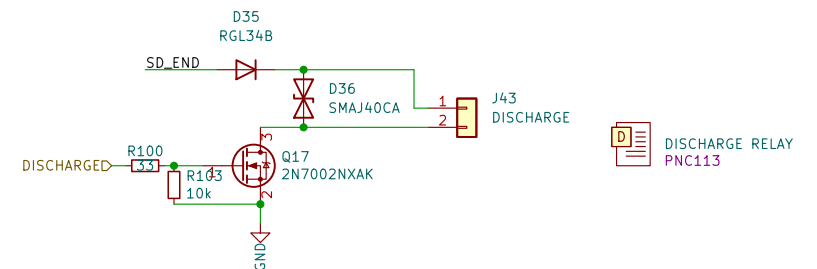
INVERTERS



SHUTDOWN FEEDBACKS



DISCHARGE MOSFET



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Nicolò Durisotto
E-Agle TRT
Sheet: /LVS/
File: LVS.kicad_s

Title: Fenice BMS LV

Size: A3	Date: 2021-10-12
KiCad E.D.A. eeschema (6.0.2-0)	

Rev: 1.1
Id: 7/5