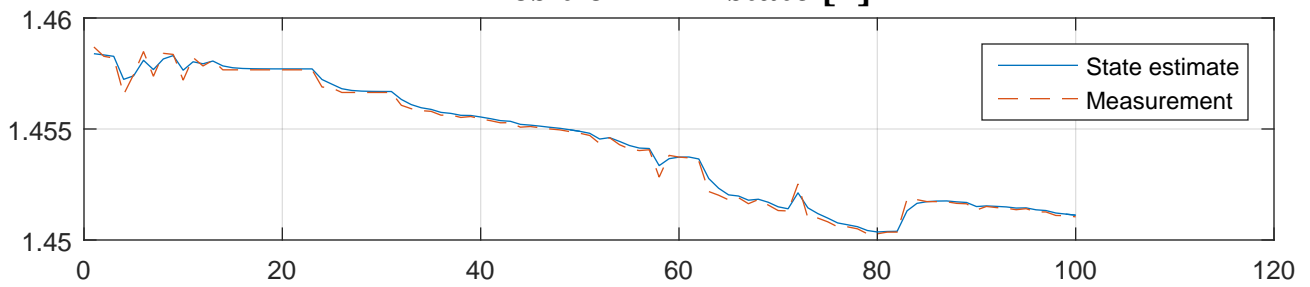
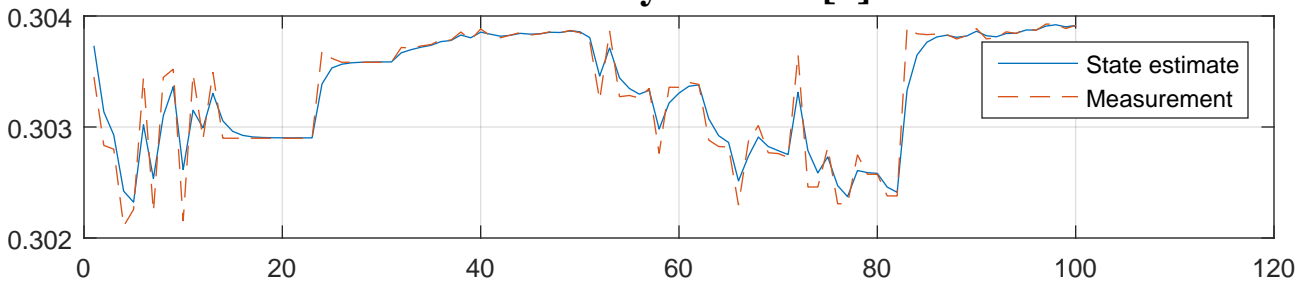


**Position x - x state [1]**



**Position y - x state [2]**



**Orientation - x state [3]**

