

CA1_PC_model

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1 Modeling age-related changes in electrical activity in CA1 pyramidal cells

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1.1 Overview

We are interested in modeling age-related changes in ion channel expression and electrical activity in CA1 pyramidal cells (PCs). However, before we can investigate aging, we have to create a representative model cell of a young CA1 PC. PCs in the CA1 region of the hippocampus show diverse firing patterns, including repetitive slow firing with frequency adaptation, conditional bursting (bursting in response only to a stimulus), and endogenous bursting in the absence of stimulation. We can build a 3-dimensional model, based on electrophysiological data, to determine under what conditions these different firing patterns can be reproduced. We will vary primarily the density of ion channels in the model membrane and specific biophysical properties of the channels, such as their rate of activation. In this way, we can understand the different balances of currents that produce these firing patterns, and then compare the firing in young and aged PCs under different conditions. We can assume that the passive membrane properties of young and aged CA1 PCs are the same but that the cells differ in their calcium channel density, as shown in the experimental literature, to explore one aspect of aging in these cells. For more information, see our article “A biophysical minimal model to investigate age-related changes in CA1 pyramidal cell excitability”.

1.2 Setting up the notebook

First, we import the Python modules needed for computing and plotting figures. We include several commands to view plots in the Jupyter notebook, and to create figures with good resolution and large labels. These commands can be customized to produce figures with other specifications.

```
[1]: # import computing modules
import numpy as nu
import pyprocess as pyp # see Python documentation for install
```

```

# command to view figures in Jupyter notebook
%matplotlib inline

# import plotting modules and settings
import matplotlib.pyplot as pl
import matplotlib.ticker as ticker # rescaling units in figures
from mpl_toolkits.axes_grid1.inset_locator import mark_inset # figure insets
from mpl_toolkits.axes_grid1.inset_locator import inset_axes # figure insets

# commands to create high-resolution figures with large labels
%config InlineBackend.figure_formats = {'png', 'retina'}
pl.rcParams['figure.dpi']= 300 # higher res means figures take longer to
    ↳generate; comment out to speed up
pl.rcParams['axes.labelsize'] = 18 # fontsize for figure labels
pl.rcParams['axes.titleSize'] = 20 # fontsize for figure titles
pl.rcParams['font.size'] = 16 # fontsize for figure numbers
pl.rcParams['lines.linewidth'] = 1.6 # line width for plotting

```

1.3 Defining auxiliary functions

Next, we define the constants and auxiliary functions we need for the model. These include functions to construct the parameter dictionary, calculate the Boltzmann potential, and the sigmoidal function for the current activation curves.

```
[2]: # define constants
eCharge=1.60217733e-19 # Coulombs
kBoltzmann=1.38065812e-20 # mJ/K
zeroT=273.15 # degree Kelvin

# functions to build dictionary
def popDictKeys(di,keyList):
    ddi = di.copy()
    for kk in keyList:
        ddi.pop(kk)
    return ddi

def popDictKey(di,key):
    return {k:v for k,v in di.items() if k != key}

def gatherDicts(d, dList):
    for dl in dList:
        d.update(dl)
    return d

# calculate Boltzmann or thermal potential at specified temperature
def vBoltzmann(tempCelcius=37.0):
```

```

    return kBoltzmann*(zeroT+tempCelcius)/eCharge

# calculate sigmoids for the activation curves
def sigmoid(u,a):
    return u/(u + a)

# calculate slopes for voltsge derivative
def calcSecants(x,y):
    dydx = np.zeros(len(y))
    dydx[1:] = (y[1:]-y[:-1]) / (x[1:]-x[:-1])
    return dydx

# calcuate duration of action potentials (APs)
def calcPulseDuration(t,vAP,report=1):
    dvdt = calcSecants(t,vAP)
    a = dvdt.argmax()
    b = dvdt.argmin()
    if report==1:
        print('Pulse started at %g with max rate %g and ended at %g \
              with min rate %g'%(t[a],dvdt.max(),t[b],dvdt.min()))
    return t[b]-t[a]

# print Boltzmann/thermal potential
print('v_T = %g'%vBoltzmann(37))

```

v_T = 26.7268

1.4 Model for CA1 pyramidal cells

Now, we build a Python class that will be used to simulate the activity of CA1 PCs, given by the system of equations:

$$C_m \partial_t v = I_F - I_{NaT}(v, w) - I_{CaL}(v, c) - I_{DK}(v, w) - I_{SK}(v, c) - I_{NaK}(v) \quad (1)$$

$$\partial_t w = w(S_w(v) - w) R_w(v) \quad (2)$$

$$\partial_t c = r_c(c_\infty - c) - k_c I_{CaL}(v, c) \quad (3)$$

Different instances of the class can later be used to simulate different-aged PCs. The class includes a function which defines the right-hand side of the model. The model has three variables: the change in voltage (v), potassium channel activation (w), and intracellular calcium concentration (c). The currents include a transient sodium current (NaT), delayed rectifier potassium current (DK), L-type calcium current (CaL), calcium-dependent potassium current (SK), and a sodium-potassium pump (NaK).

Note that all potentials in the model are normalized by v_T . Also, all potentials in the model are arguments inside exponential functions. Therefore, there are a few calculations that can be

done before running a solver. The first two calculations that are repetitive are the normalization of potentials and the division of each of the currents by the membrane capacitance. For the normalization, we perform a change of variables $v \mapsto u = v/v_T$, which means that we can write a new equation from the fact that $\partial_t u = \partial_t v/v_T$. Having done the change of variables, we include the division by C_m by rewriting the amplitudes for each of the currents as $a_x \mapsto A_x = a_x/v_T C_m$. The new currents are then mapped $I_x \mapsto J_x = I_x/(v_T C_m)$. The resulting system looks like

$$\partial_t u = J_F - J_{NaT}(u, w) - J_{CaL}(u, c) - J_{DK}(u, w) - J_{SK}(u, c) - J_{NaK}(u). \quad (4)$$

```
[3]: # class for CA1 pyramidal cells (PCs)
class pyrCA1:
    nDim = 3;
    def __init__(self,pars):
        self.dict2ClassPars(pars)
        self.reparametrize()
        return

    # for building parameter dictionary
    def dict2ClassPars(self,di):
        for k in di.keys():
            exec("self.%s = %g"%(k,di[k])); #print(str1)
        return

    # reparametrize model based on updated parameter values
    # normalize current amplitudes by Boltzmann potential * membrane capacitance
    def reparametrize(self):
        self.u_half_Act_DK = self.v_half_Act_DK/self.v_T
        self.u_half_Act_NaT = self.v_half_Act_NaT/self.v_T
        self.u_half_Act_CaL = self.v_half_Act_CaL/self.v_T
        self.u_ATP = self.v_ATP/self.v_T
        self.u_Na = self.v_Na/self.v_T
        self.u_K = self.v_K/self.v_T
        self.u_NaK = self.u_ATP + 3*self.u_Na - 2*self.u_K
        self.v_NaK = self.u_NaK * self.v_T
        self.u0 = self.v0/self.v_T
        self.vTCm = self.v_T * self.C_m
        self.A_NaK = 2 * self.a_NaK / self.vTCm
        self.A_DK = 2 * self.a_DK / self.vTCm
        self.A_SK = 2 * self.a_SK / self.vTCm
        self.A_NaT = 2 * self.a_NaT / self.vTCm
        self.A_CaL = 4 * self.a_CaL / self.vTCm
        print('A_NaK = %g, A_DK = %g, A_SK = %g, A_NaT = %g, A_CaL = %g, \
all in V/s'%(self.A_NaK, self.A_DK, self.A_SK, self.A_NaT, self.A_CaL))
        print('a_NaK = %g, a_DK = %g, a_SK = %g, a_NaT = %g, a_CaL = %g, \
all in pA' %(self.a_NaK, self.a_DK, self.a_SK, self.a_NaT, self.a_CaL))
        return
```

```

# print normalized current amplitudes
def printNormAmps(self):
    print('A_NaK = %g, A_DK = %g, A_SK = %g, A_NaT = %g, A_CaL = %g, \
all in V/s'%(self.A_NaK, self.A_DK, self.A_SK, self.A_NaT, self.A_CaL))
    print('a_NaK = %g, a_DK = %g, a_SK = %g, a_NaT = %g, a_CaL = %g, \
all in pA'%(self.a_NaK, self.a_DK, self.a_SK, self.a_NaT, self.a_CaL))
    return

# forward rate of activation
def alpha_w(self,u):
    gb = self.b_Act_DK * self.g_Act_DK
    return self.r_Act_DK * nu.exp(gb*(u-self.u_half_Act_DK))

# backward rate of activation
def beta_w(self,u):
    gb = (self.b_Act_DK-1) * self.g_Act_DK
    return self.r_Act_DK * nu.exp(gb*(u-self.u_half_Act_DK))

# steady-state activation for delayed rectifier K+ channels
def ss_Act_DK(self,u):
    return 1/(1 + nu.exp(self.g_Act_DK * (self.u_half_Act_DK - u) ))

# steady-state activation for Na+ channels
def ss_Act_NaT(self,u):
    return 1/(1 + nu.exp( self.g_Act_NaT * (self.u_half_Act_NaT - u) ))

# steady-state activation for delayed rectifier Ca2+ channels
def ss_Act_CaL(self,u):
    return 1/(1 + nu.exp( self.g_Act_CaL * (self.u_half_Act_CaL - u) ))

# steady-state activation for SK channels
def ss_Act_SK(self,c):
    return sigmoid( c**self.g_Act_SK, self.in_Ca_half_Act_SK**self.g_Act_SK)

# flux calculations for different channels or pumps
def J_NaK(self,u):
    return self.A_NaK * nu.sinh((u - self.u_NaK)/2 )

def J_DK(self,x,u):
    """The original amplitude is a_DK = A_DK * C_m * v_T"""
    return self.A_DK * x * nu.sinh((u - self.u_K)/2 )

def J_SK(self,u,c):
    """The original amplitude is a_SK = A_SK * C_m * v_T"""
    return self.A_SK * self.ss_Act_SK(c) * nu.sinh((u - self.u_K)/2 )

def J_NaT(self,x,u):

```

```

"""The original amplitude is a_NaT = A_NaT * C_m * v_T"""
return self.A_NaT * self.ss_Act_NaT(u) * (1-x) * nu.sinh((u - self.u_Na)/
↪2 )

def J_CaL(self,u,c):
"""The original amplitude is a_CaL = A_CaL * C_m * v_T/2"""
return self.A_CaL * self.ss_Act_CaL(u) * nu.sinh( u - self.u_Ca )

# define current clamp protocol used to stimulate PCs
def IClamp(self):
    self.timeSamples = nu.arange(0,self.timeMax,self.timeStep)
    self.nSteps = len(self.timeSamples)
    self.iInds = nu.argwhere((self.timeSamples >= self.startIClamp) & \
                                (self.timeSamples < self.stopIClamp))
    self.jClamp = nu.zeros(self.nSteps)
    self.jClamp[nu.squeeze(self.iInds)] = self.iClampAmp/self.vTCm
    print(nu.squeeze(self.iInds),self.jClamp)
    return self.jClamp

# define OU forcing function
def ouForcing(self):
    self.timeSamples = nu.arange(0,self.timeMax,self.timeStep)
    self.nSteps = len(self.timeSamples)
    diffF=2*self.aSD/self.aTau
    aOU=pyp.OU_process(theta=1/self.aTau,mu=self.aMean,sigma=diffF)
    aOUPath= aOU.sample_path(self.timeSamples)[0] /self.vTCm
    return aOUPath

# define dynamics of variables; note that u is normalized voltage
def dynamics(self,Z):
    u,w,c = Z
    self.u_Ca = nu.log(self.out_Ca/c) / self.val_Ca
    aw = self.alpha_w(u); bw = self.beta_w(u)
    JK = (self.A_DK * w + self.A_SK * self.ss_Act_SK(c)) * nu.sinh((u - self.
↪u_K)/2)
    JCaL = self.J_CaL(u,c)
    dw = self.r_Act_DK * (w**self.expo_Act_DK) * (aw - (aw+bw)*w)
    du = self.A_F - self.J_NaK(u) - self.J_NaT(w,u) - JCaL - JK
    dc = self.r_in_Ca * (self.in_Ca_infny - c) - self.r_conv_Ca * JCaL
    #print('\n-----\n',u,w,c,'....',du,dw,dc)
    return nu.array([du,dw,dc])

# time steps for customized solver below
def RK2_Step(self, f, U):
    k = f(U) * self.timeStep / 2.0
    return U + self.timeStep * f(U + k)

```

```

# define customized Runge-Kutta solver
def RK2_Autonomous(self, parNames=[], parValues=[]):
    """Second-order Runge-Kutta method to solve  $x' = f(x)$  with  $U(t[0]) = U_0$ .
    Numerical Analysis, 6th Edition, by Burden and Faires, Brooks-Cole, 1997.
    """
    print('Calculating numerical solution')
    nForc=len(parNames)
    print(parNames,parValues, '%d forcing parameters'%nForc)
    self.timeSamples = nu.arange(0,self.timeMax,self.timeStep)
    self.nSteps = len(self.timeSamples)
    print('nSteps = %d'%self.nSteps)
    U = nu.zeros((self.nSteps, self.nDim), "float64")
    U[0] = nu.array([self.v0/self.v_T, self.w0, self.c0])
    if nForc>0:
        for i in range(self.nSteps-1):
            for nn in range(nForc):
                str1='self.%s = %g'%(parNames[nn],parValues[nn][i])
                exec(str1);
            U[i+1] = self.RK2_Step(self.dynamics, U[i])
    else:
        for i in range(self.nSteps-1):
            U[i+1] = self.RK2_Step(self.dynamics, U[i])
    self.u, self.w, self.c = U.transpose()
    self.v = self.u * self.v_T
    return self.v,self.w,self.c

# calculate various biophysical quantities, like non-normalized currents
def calcBiophysicsFromDynamics(self,v,w,c):
    u = v/self.v_T
    self.dvdt = calcSecants(self.timeSamples,v)
    self.wInf = self.ss_Act_DK(u);
    self.mInf = self.ss_Act_NaT(u);
    self.ninf = self.ss_Act_CaL(u);
    self.walpha = self.alpha_w(u);
    self.wbeta = self.beta_w(u);
    self.wtau = 1/(alpha_w + beta_w)
    self.jNaK = self.J_NaK(u) * self.vTCm;
    self.jDK = self.J_DK(w,u) * self.vTCm;
    self.jNaT = self.J_NaT(w,u) * self.vTCm
    self.jCaL = self.J_CaL(u,c) * self.vTCm;
    self.jSK = self.J_SK(u,c) * self.vTCm
    self.v_Ca = nu.log(self.out_Ca/c) * self.v_T / self.val_Ca
    return self.v,self.w,self.c

# calcuate duration of action potentials (APs)
def calcAPDuration(self,ta,tb):
    a = nu.int32(ta/self.timeStep)

```

```

b = nu.int32(tb/self.timeStep)
calcPulseDuration(self.timeSamples[a:b],self.v)
return

# define function for plotting steady states, currents, etc.
# can use this out of the box, or build customized figures
def plotSteadyStates(self):
    vSS = nu.linspace(-100,100.0,400);
    uSS = vSS / self.v_T
    wInf = self.ss_Act_DK(uSS);
    mInf = self.ss_Act_NaT(uSS);
    ninf = self.ss_Act_CaL(uSS)
    alphaw = self.alpha_w(uSS);
    betaw = self.beta_w(uSS);
    tauw = 1/(alphaw + betaw)
    tcw = (alphaw**self.expo_Act_DK) / (alphaw + betaw)**(self.expo_Act_DK -1)
    INaK = self.J_NaK(uSS) * self.vTCm;
    IDK = self.J_DK(wInf,uSS) * self.vTCm;
    INaT = self.J_NaT(wInf,uSS) * self.vTCm
    ICaL = self.J_CaL(uSS,0.00001)* self.vTCm;
    ISK = self.J_SK(uSS,0.00001)* self.vTCm
    #
    fig = pl.figure(figsize=(15,15)); rows=3; cols=1
    ax_w1 = fig.add_subplot(rows,cols,1); ax_w2 = ax_w1.twinx()
    ax_ss_Act = fig.add_subplot(rows,cols,2);
    ax_ssI1 = fig.add_subplot(rows,cols,3); ax_ssI2 = ax_ssI1.twinx()
    ax_w2.plot(vSS, alphaw, label=r'$\alpha_w(v)$');
    ax_w2.plot(vSS, betaw,label=r'$\beta_w(v)$');
    ax_w2.legend(loc='upper right');
    ax_w2.set_ylabel('1/ms',labelpad=30,rotation=-90)
    ax_w2.set_ylim(-0.1,5);
    ax_w1.plot(vSS, tauw, 'k', label=r'$\tau_w$');
    ax_w1.legend(loc='upper left'); ax_w1.set_ylabel('ms',labelpad=20)
    ax_w1.set_ylim(0,1.1*tauw.max());
    ax_ss_Act.plot(vSS, wInf, label=r'$w_{\infty}(v)$')
    ax_ss_Act.plot(vSS, mInf, label=r'$m_{\infty}(v)$')
    ax_ss_Act.plot(vSS, ninf, 'k', label=r'$n_{\infty}(v)$')
    ax_ss_Act.legend(loc='upper left');
    #
    ax_ssI1.plot([vSS.min(),vSS.max()], [0,0], 'k:')
    ax_ssI2.plot([vSS.min(),vSS.max()], [0,0], 'k:')
    ax_ssI2.plot(vSS,INaK, 'k', label=r'$a_{NaK} \varphi_{NaK}(v)$')
    ax_ssI1.plot(vSS, IDK, label=r'$a_{DK} w_{\infty}(v) \varphi_{DK}(v)$')
    ax_ssI1.plot(vSS,INaT, label=r'$a_{NaT} m_{\infty}(v) (1-w_{\infty}(v)) \varphi_{NaT}(v)$')
    ax_ssI1.plot(vSS,ICaL, label=r'$a_{CaL} n_{\infty}(v) \varphi_{CaL}(v)$')

```

```

    ax_ssI1.plot(vSS,ISK, label=r'$a_{SK} H_{SK}(c) \varphi_{SK}(v)$')
    ax_ssI1.legend(loc='upper left'); ax_ssI1.set_ylim(-6000,6000);
    ax_ssI1.set_xlabel('mV',labelpad=20);
    ax_ssI1.set_ylabel('pA');
    ax_ssI2.legend(loc='lower right'); ax_ssI2.set_ylabel('pA',labelpad=30, rotation=-90)
    ax_ssI2.set_xlabel('V(mV)');
    # figure letter labels
    ax_w1.text(-0.09, 1.05, 'A.', transform=ax_w1.transAxes, fontsize=18, fontweight='bold', \
                va='top',ha='right')
    ax_ss_Act.text(-0.09, 1.05, 'B.', transform=ax_ss_Act.transAxes, fontsize=18, fontweight='bold', \
                va='top',ha='right')
    ax_ssI1.text(-0.09, 1.05, 'C.', transform=ax_ssI1.transAxes, fontsize=18, fontweight='bold', \
                va='top',ha='right')
    return

# define function for plotting voltage, calcium dynamics, currents, etc.
# can use this out of the box, or build customized figures
def plotDynamicalProfile(self):
    figD = pl.figure(figsize=(15,15)); pl.ioff();
    rows=1; cols=2; maxLargeCurrent = 7000
    axBottom = 0.1; axTop = 1-axBottom
    axLeft= 0.075; lColW=0.7; rColW=0.25; rowHeight=0.3
    ax_v = figD.add_axes([axLeft,axTop,lColW,rowHeight]);
    ax_vCa = ax_v.twinx()
    ax_dv = figD.add_axes([2*axLeft + lColW, axTop,rColW,rowHeight]);
    ax_I = figD.add_axes([axLeft, axTop-rowHeight-0.1,lColW,rowHeight]);
    ax_Jdv = figD.add_axes([2*axLeft + lColW, axTop-rowHeight-0.1,rColW,rowHeight]);
    ax_c_SK = figD.add_axes([axLeft, axBottom,lColW,rowHeight]);
    ax_c = ax_c_SK.twinx()
    ax_cdv = figD.add_axes([2*axLeft + lColW, axBottom,rColW,rowHeight]);
    #
    ax_v.plot(self.timeSamples, v, 'k',ms=1, label=r'$v(t)$');
    ax_vCa.plot(self.timeSamples, self.v_Ca, 'b',ms=2, label=r'$v_{Ca}$');
    ax_dv.plot(self.dvdt,v,'k.', ms=1, label=r'$\partial_t v$');
    ax_I.plot(self.timeSamples, self.jNaT, 'g', ms=3, alpha = 0.65, \
                label=r'$I_{NaT}(v,w)$');
    ax_I.plot(self.timeSamples, self.jDK, 'r', ms=1, alpha = 0.65, \
                label=r'$I_{DK}(v,w)$');
    ax_I.plot(self.timeSamples, self.jCaL, 'b',ms=3, alpha = 0.65, \
                label=r'$I_{CaL}(v,c)$');

```

```

        ax_I.plot(self.timeSamples, self.jSK, 'm.', ms=1, alpha = 0.75,
        ↳label=r'$I_{SK}(v,c)$');
        ax_Jdv.plot(self.dvdt, self.jNaT, 'g.', ms=1, alpha = 0.65,
        ↳label=r'$(\partial_t v, I_{NaT})$');
        ax_Jdv.plot(self.dvdt, self.jDK, 'r.', ms=1, alpha = 0.65,
        ↳label=r'$(\partial_t v, I_{DK})$');
        ax_Jdv.plot(self.dvdt, self.jCaL, 'b', ms=1, alpha = 0.65,
        ↳label=r'$(\partial_t v, I_{CaL})$');
        ax_Jdv.plot(self.dvdt, self.jSK, 'm.', ms=1, alpha = 0.65,
        ↳label=r'$(\partial_t v, I_{SK})$');
        ax_c.plot(self.timeSamples, c*1000, 'b', ms=2, label=r'$c(t)$');
        ax_c_SK.plot(self.timeSamples, self.ss_Act_SK(c), 'm', ms=2,
        ↳label=r'$p_{SK}$');
        ax_cdv.plot(self.jCaL, c*1000, 'b.', ms=2, label=r'$(I_{CaL}, c)$');
        #
        ax_vCa.legend(loc='lower left'); ax_dv.set_xlabel(r'$\partial_t v$')
        ax_v.legend(loc='upper left'); ax_v.set_ylabel('mV')
        ax_I.legend(loc='upper left'); ax_I.set_ylabel('pA');
        ax_I.set_ylim(-maxLargeCurrent,maxLargeCurrent)
        ax_Jdv.legend(loc='upper left'); ax_Jdv.set_ylabel('pA');
        ax_Jdv.set_xlabel(r'$\partial_t v$')
        ax_Jdv.set_ylim(-maxLargeCurrent,maxLargeCurrent)
        ax_c.set_ylabel('uM',labelpad=10,rotation=0);
        ax_c_SK.set_ylim(0,1)
        ax_c_SK.set_ylabel('$P_{open}(K_S)$',labelpad=10,rotation=90);
        ax_c_SK.legend(loc='upper center');
        ax_c.legend(loc='upper right');
        ax_c.set_ylim(0,0.5);
        ax_cdv.set_ylim(0,0.5);
        ax_cdv.set_xlabel(r'$I_{CaL} (pA)$')
        pl.ion(); pl.draw()
    return

```

1.5 Building the parameter dictionary

Next, we build our parameter dictionary. We do this in parts, i.e. all the ion concentrations, valences, and other biophysical parameters like temperature are grouped together (ionBP), then all the current amplitudes (amps), etc. We then gather all these smaller dictionaries together in a larger main dictionary. Some of these parameter values will then stay fixed for all simulations, while others will be varied to generate different firing patterns or simulate aging.

```
[4]: # ion concentrations, valences, and biophysical params like temp, membrane
      ↳capacitance, etc.
# all units for concentration in mM; note 1uM would be 1e-3 and 1nM would be 1e-6
ionBP={'out_Ca': 1.5,
       'in_Ca': 1e-4,
```

```

'in_Ca_half_Act_SK':7.4e-4,
'in_Ca_infny':1e-4,
'val_Ca':2,
'val_Na':1,
'val_K':1,
'tempCelcius':37.0,
'C_m':25.0}
# current amplitudes; all units in pA
amps = {'a_NaT':1000.0,
         'a_NaK': 1000/100.0,
         'a_DK': 8000,
         'a_CaL': 25.0, #50, if aged PC
         'a_SK': 1400.0,
         'a_F': 0.0,
         'iClampAmp':100.0}
# activation slope factors, aka gating charges
gains = {'g_Act_NaT':5.0,
          'g_Act_DK':3.8,
          'g_Act_CaL':5.0,
          'g_Act_SK':2.0,
          'expo_Act_DK':1}
biases = {'b_Act_DK':0.3}
# rate of Ca2+ removal, K+ channel activation, Ca2+ conversion factor
rates = {'r_in_Ca': 1e-3,
          'r_Act_DK': 1.0,
          'r_conv_Ca': 3e-6}
# half-activation voltages, and Boltzmann calculation
volts = {'v_half_Act_DK': -1.0,
          'v_half_Act_NaT': -19.0,
          'v_half_Act_CaL': 3.0,
          'v_ATP':-420.0,
          'v_Na': 60.0, 'v_K':-89,
          'v_T': vBoltzmann(ionBP['tempCelcius'])}
# time steps, max time, and start and stop times for IClamp
times = {'timeStep':1.0/40.0,
          'timeMax':1200,
          'iCStart':200.0,
          'iCStop':1000.0}
# settings for OU forcing
ous = {'aMean':35.0,
        'aSD':20.0,
        'aTau':1/2.0}
# initial conditions for voltage, K+ channel activation, Ca2+ concentration
ics = {'v0':-70.0,
        'w0':0.001,
        'c0':1e-4}

```

```
# gather all dictionaries together (can replace different dictionaries for
# different configurations)
pars = gatherDicts(dict(), [ionBP,amps,gains,biases,rates,volts,times,ous,ics])
```

Now we can create an instance of the class, feeding in the parameter dictionary, and print values to check it's working correctly.

[5]: # create an instance of the class
`nrn = pyrCA1(pars)`
`#`
`print('v_T = %g mV, v_ATP = %g mV' % (nrn.v_T, nrn.v_ATP))`
`print('v_Na = %g mV, v_K = %g mV, v_NaK= %g mV' % (nrn.v_Na, nrn.v_K, nrn.v_NaK))`

```
A_NaK = 0.0299325, A_DK = 23.946, A_SK = 4.19055, A_NaT = 2.99325, A_CaL =
0.149663, all in V/s
a_NaK = 10, a_DK = 8000, a_SK = 1400, a_NaT = 1000, a_CaL = 25, all in
pA
v_T = 26.7268 mV, v_ATP = -420 mV
v_Na = 60 mV, v_K = -89 mV, v_NaK= -62 mV
```

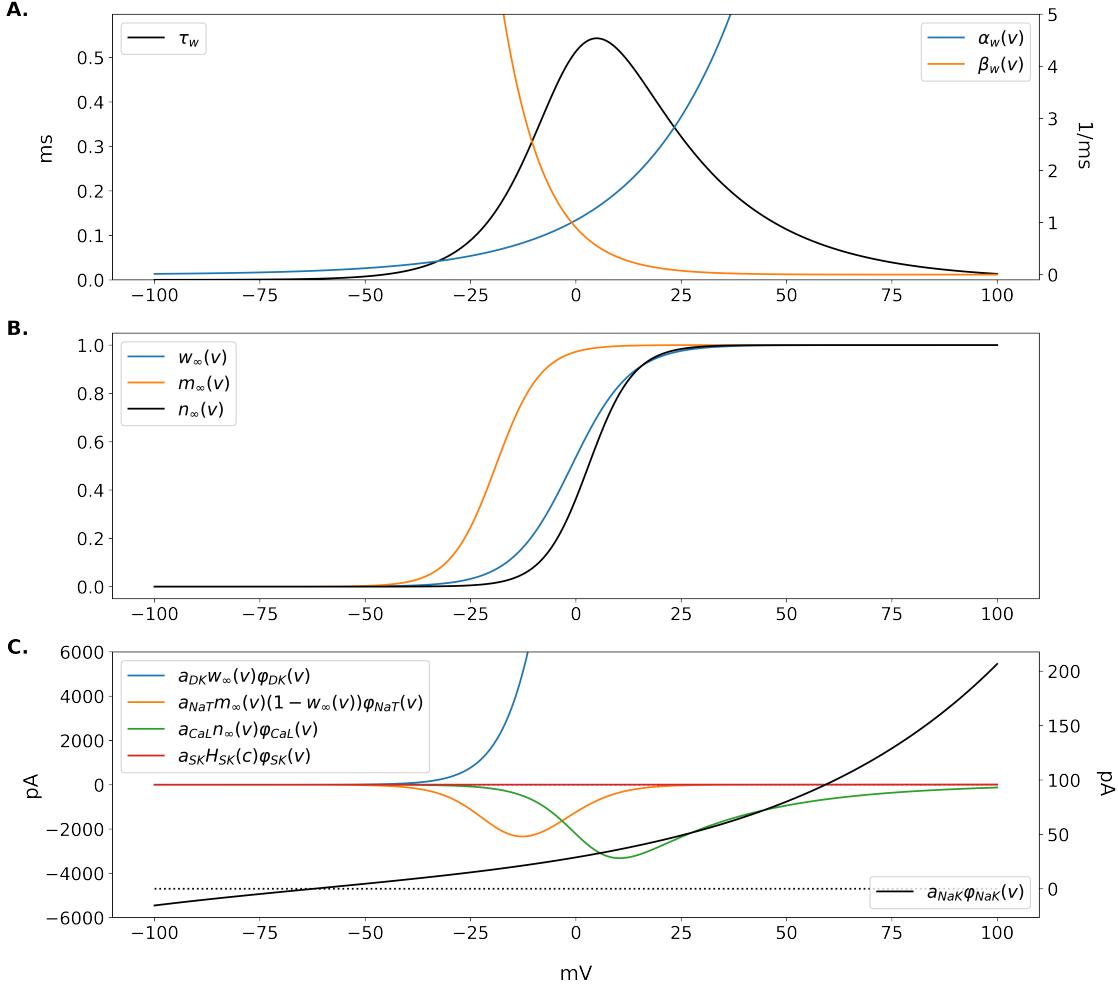
We can also check that the current clamp protocol for stimulation is working.

[6]: # checking I-Clamp protocol
`nrn.startIClamp = 100; nrn.stopIClamp = 150; nrn.iClampAmp=50; nrn.timeMax=400;`
`iClamp = nrn.IClamp()`

```
[4000 4001 4002 ... 5997 5998 5999] [0. 0. 0. ... 0. 0. 0.]
```

Finally, we can calculate and plot the steady-state activation curves, currents, etc.

[7]: vSS = nu.linspace(-100,100.0,400);
ySS = nu.exp(vSS / nrn.v_T)
wInf = nrn.ss_Act_DK(ySS); mInf = nrn.ss_Act_NaT(ySS); ninf = nrn.ss_Act_CaL(ySS)
alpha_w = nrn.alpha_w(ySS); beta_w = nrn.beta_w(ySS); tau_w = 1/(alpha_w + beta_w)
INaT = nrn.J_NaT(wInf,ySS) * nrn.vTCm
IDK = nrn.J_DK(wInf,ySS) * nrn.vTCm
ISK = nrn.J_SK(ySS,0.00001)* nrn.vTCm
INaK = nrn.J_NaK(ySS) * nrn.vTCm
nrn.u_Ca = nu.log(nrn.out_Ca/nrn.in_Ca) / nrn.val_Ca
ICaL = nrn.J_CaL(ySS,0.00001)* nrn.vTCm
#
nrn.plotSteadyStates();



Once we have everything set up, then we can move on to generating different firing patterns corresponding to PC activity.

1.6 Simulating CA1 PC electrical activity

1.6.1 Repetitive slow firing with spike frequency adaptation

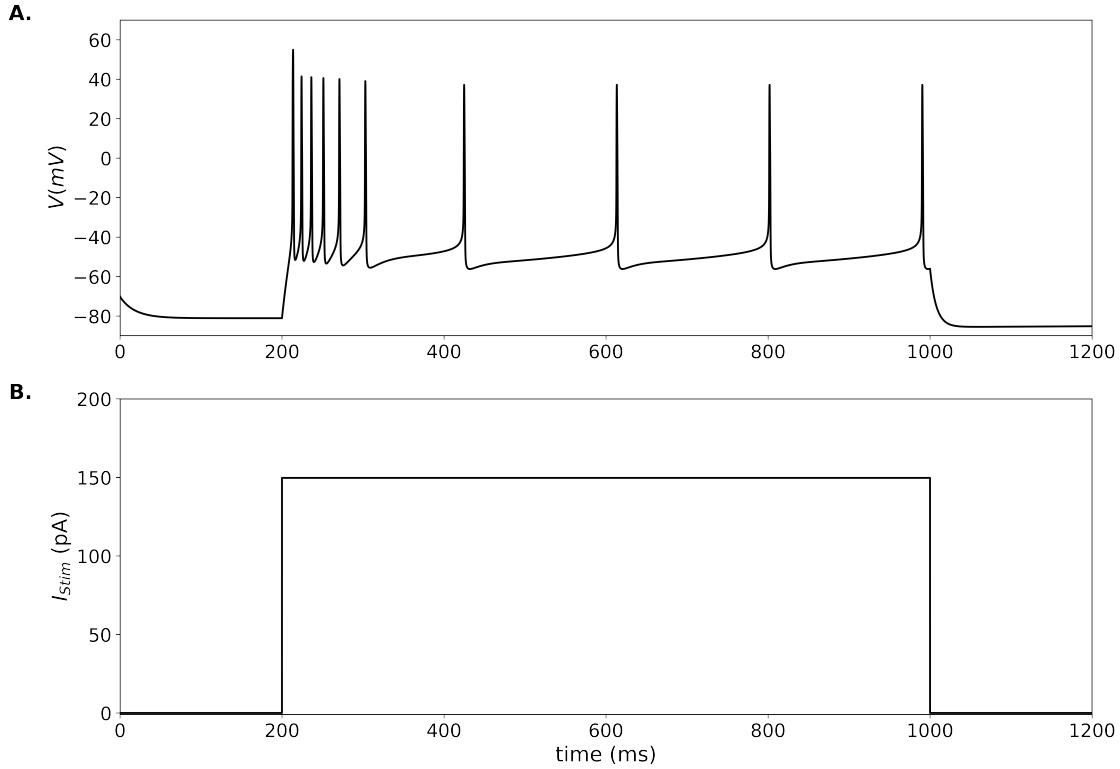
Many CA1 pyramidal cells respond to square-pulse current injection by firing several early spikes followed by marked adaptation, which slows the frequency of firing. In aged animals, this adaptation is more pronounced than in young animals, leading to a shorter initial period of fast spiking, followed by fewer spikes or even complete cessation of activity. The increased adaptation seen in aged PCs is functionally relevant, as it is correlated with learning impairment. (See our main article for more information and citations.) Thus, our first challenge was to tune the model to produce early-onset firing with spike frequency adaptation. The baseline parameter regime specified above produces this firing pattern (see article for more details). The following commands run the model:

```
[8]: # running with above parameters and class instance
nrn.reparametrize()
nrn.v0 = -70.0; nrn.w0 = 0.001; nrn.c0=1e-4;
nrn.timeMax = 1200.0; nrn.timeStep = 1.0/40.0;
nrn.startIClamp = 200; nrn.stopIClamp = 1000;
nrn.iClampAmp=1*100.0; # divide iClampAmp by vTCm for final stimulation
# amplitude (in nA)
iClamp = nrn.IClamp();
v,w,c = nrn.RK2_Autonomous(parNames=['A_F'],parValues=[iClamp,])
nrn.calcBiophysicsFromDynamics(v,w,c);
```

A_NaK = 0.0299325, A_DK = 23.946, A_SK = 4.19055, A_NaT = 2.99325, A_CaL = 0.149663, all in V/s
a_NaK = 10, a_DK = 8000, a_SK = 1400, a_NaT = 1000, a_CaL = 25, all in pA
[8000 8001 8002 ... 39997 39998 39999] [0. 0. 0. ... 0. 0. 0.]
Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters
nSteps = 48000

```
[9]: # plot results
ax1=list()
fig1=pl.figure(figsize=(15,11))
pl.ioff()
rows=2; cols=1
for s in np.arange(rows*cols):
    ax1.append(fig1.add_subplot(rows,cols,s+1))

ax1[0].plot(nrn.timeSamples, v, 'k', ms=1)
ax1[0].set_xlim(0,1200)
ax1[0].set_ylim(-90,70)
ax1[0].set_ylabel(r'$V(mV)$')
#
ax1[1].plot(nrn.timeSamples,iClamp*1000,'k')
ax1[1].set_xlim(0,1200)
ax1[1].set_ylim(-1,200)
ax1[1].set_ylabel('$I_{Stim}$ (pA)')
ax1[1].set_xlabel('time (ms)')
#
ax1[0].text(-0.09, 1.05, 'A.', transform=ax1[0].transAxes, fontsize=18,
# fontweight='bold', va='top', ha='right')
ax1[1].text(-0.09, 1.05, 'B.', transform=ax1[1].transAxes, fontsize=18,
# fontweight='bold', va='top', ha='right');
```



If we plot the spiking response above on a smaller time scale and also plot each current, we can see that the model produces ion currents within the same magnitude range as those seen in CA1 PC recordings (see paper for details and references).

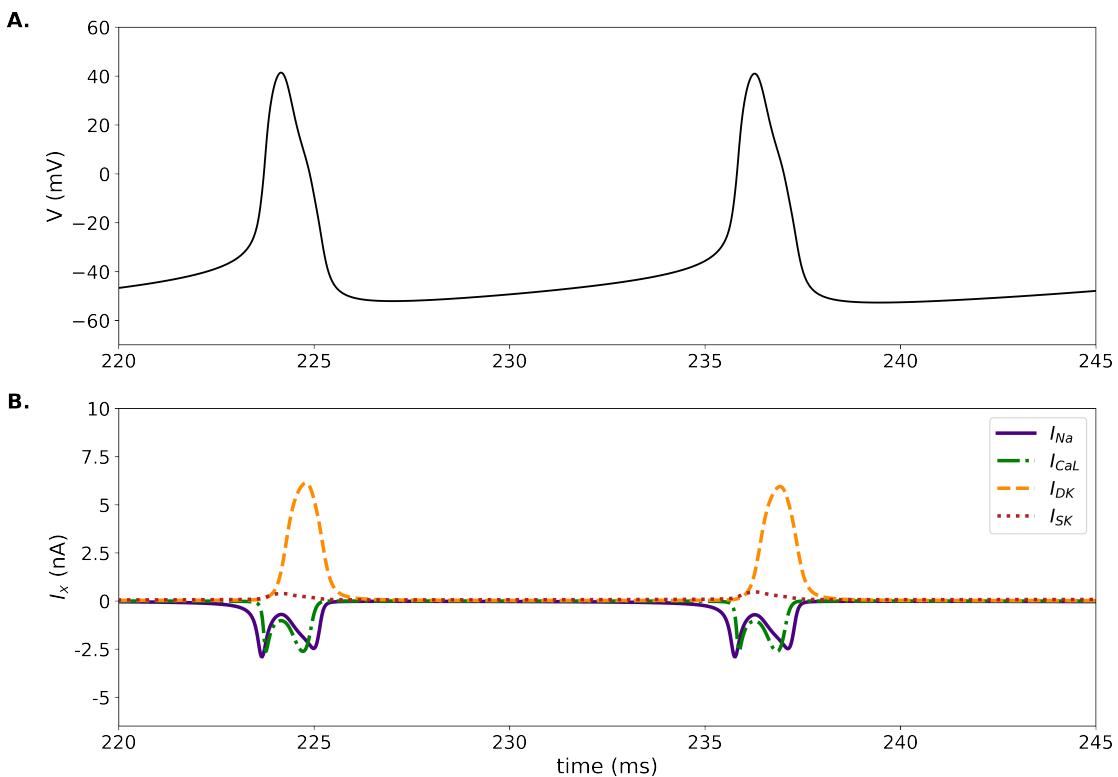
```
[10]: # plot just two spikes from above simulation and currents
ax1=list()
fig1=pl.figure(figsize=(15,11))
pl.ioff()
rows=2; cols=1
for s in np.arange(rows*cols):
    ax1.append(fig1.add_subplot(rows,cols,s+1))

ax1[0].plot(nrn.timeSamples, v,'k')
ax1[0].set_xlim(220,245)
ax1[0].set_ylim(-70,60)
ax1[0].set_ylabel('V (mV)')
#
ticks_y=ticker.FuncFormatter(lambda x, pos: '{0:g}'.format(x/1000))
ax1[1].yaxis.set_major_formatter(ticks_y)
ax1[1].plot(nrn.timeSamples, nrn.jNaT, linestyle='solid', linewidth=3.0, color="indigo", label=r'$I_{\text{Na}}$')
ax1[1].plot(nrn.timeSamples, nrn.jCaL, linestyle='dashdot', linewidth=3.0, color="green", label=r'$I_{\text{CaL}}$')
```

```

ax1[1].plot(nrn.timeSamples, nrn.jDK, linestyle='dashed', linewidth=3.0,
             color="darkorange", label=r'$I_{DK}$')
ax1[1].plot(nrn.timeSamples, nrn.jSK, linestyle='dotted', linewidth=3.0,
             color="firebrick", label=r'$I_{SK}$')
#ax1[1].plot(nrn.timeSamples, nrn.jNaK, label=r'$I_{NaK}$')
ax1[1].set_xlabel('time (ms)')
ax1[1].set_ylabel('$I_x$ (nA)')
ax1[1].set_xlim(220,245)
ax1[1].set_ylim(-6500,10000)
ax1[1].legend(loc="upper right")
#
ax1[0].text(-0.09, 1.05, 'A.', transform=ax1[0].transAxes, fontsize=18,
            fontweight='bold', va='top', ha='right')
ax1[1].text(-0.09, 1.05, 'B.', transform=ax1[1].transAxes, fontsize=18,
            fontweight='bold', va='top', ha='right');

```



We can now run the model for different sets of parameters to explore the effects on CA1 PC firing. To compare young and aged model PCs, we generate two instances of the class. The instances have all the same base set of parameters from the original instance except for the amplitude of the L-type Ca^{2+} current, which was set to produce currents of around 2-3 nA or 5-6 nA - roughly the same magnitudes as those seen in recordings from young and aged PCs, respectively (see main article for details).

```
[11]: # young PC
nrn_y = pyrCA1(pars)
nrn_y.a_CaL = 25.0;
nrn_y.reparametrize()
v,w,c = nrn_y.RK2_Autonomous(parNames=['A_F'],parValues=[iClamp,])
nrn_y.calcBiophysicsFromDynamics(v,w,c);

# aged (old) PC
nrn_o = pyrCA1(pars)
nrn_o.a_CaL = 50.0;
nrn_o.reparametrize()
v,w,c = nrn_o.RK2_Autonomous(parNames=['A_F'],parValues=[iClamp,])
nrn_o.calcBiophysicsFromDynamics(v,w,c);
```

```
A_NaK = 0.0299325, A_DK = 23.946, A_SK = 4.19055, A_NaT = 2.99325, A_CaL =
0.149663,           all in V/s
a_NaK = 10, a_DK = 8000, a_SK = 1400, a_NaT = 1000, a_CaL = 25,           all in
pA
A_NaK = 0.0299325, A_DK = 23.946, A_SK = 4.19055, A_NaT = 2.99325, A_CaL =
0.149663,           all in V/s
a_NaK = 10, a_DK = 8000, a_SK = 1400, a_NaT = 1000, a_CaL = 25,           all in
pA
Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0.])] 1 forcing parameters
nSteps = 48000
A_NaK = 0.0299325, A_DK = 23.946, A_SK = 4.19055, A_NaT = 2.99325, A_CaL =
0.149663,           all in V/s
a_NaK = 10, a_DK = 8000, a_SK = 1400, a_NaT = 1000, a_CaL = 25,           all in
pA
A_NaK = 0.0299325, A_DK = 23.946, A_SK = 4.19055, A_NaT = 2.99325, A_CaL =
0.299325,           all in V/s
a_NaK = 10, a_DK = 8000, a_SK = 1400, a_NaT = 1000, a_CaL = 50,           all in
pA
Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0.])] 1 forcing parameters
nSteps = 48000
```

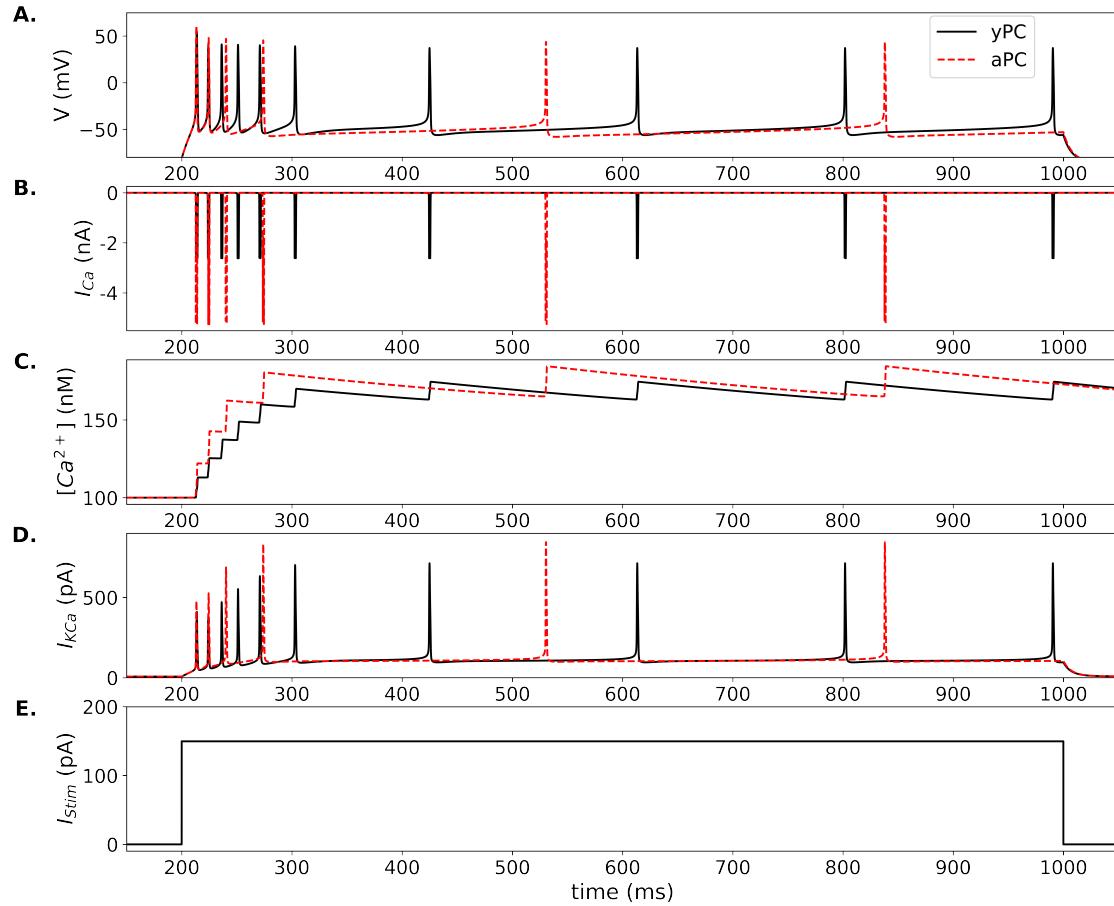
```
[12]: # plot results of previous simulations
ax1=list()
fig1=pl.figure(figsize=(15,13))
pl.ioff()
rows=5; cols=1
for s in np.arange(rows*cols):
    ax1.append(fig1.add_subplot(rows,cols,s+1))

ax1[0].plot(nrn_y.timeSamples,nrn_y.v,linestyle='solid',color='k',label='yPC')
ax1[0].plot(nrn_o.timeSamples,nrn_o.v,linestyle='dashed',color='r',label='aPC')
```

```

ax1[0].set_ylabel('V (mV)')
ax1[0].set_ylim(-80,75)
ax1[0].set_xlim(150,1050)
ax1[0].legend(loc=(0.81, 0.55))
#
ticks_y=ticker.FuncFormatter(lambda x, pos: '{0:g}'.format(x/1000))
ax1[1].yaxis.set_major_formatter(ticks_y)
ax1[1].plot(nrn_y.timeSamples,nrn_y.
             ↪jCaL,linestyle='solid',color='k',label=r'$I_{CaL}$')
ax1[1].plot(nrn_o.timeSamples,nrn_o.
             ↪jCaL,linestyle='dashed',color='r',label=r'$I_{CaL}$')
ax1[1].set_ylabel('$I_{CaL}$ (nA)')
ax1[1].set_xlim(150,1050)
#
scale_y=1e-6
ticks_y=ticker.FuncFormatter(lambda x, pos: '{0:g}'.format(x/scale_y))
ax1[2].yaxis.set_major_formatter(ticks_y)
ax1[2].plot(nrn_y.timeSamples,nrn_y.c,linestyle='solid',color='k')
ax1[2].plot(nrn_o.timeSamples,nrn_o.c,linestyle='dashed',color="r")
ax1[2].set_xlim(150,1050)
ax1[2].set_ylabel('[Ca^{2+}] (nM)')
#
ax1[3].plot(nrn_y.timeSamples,nrn_y.
             ↪jSK,linestyle='solid',color='k',label=r'$I_{SK}$')
ax1[3].plot(nrn_o.timeSamples,nrn_o.
             ↪jSK,linestyle='dashed',color='r',label=r'$I_{SK}$')
ax1[3].set_ylabel('$I_{SK}$ (pA)')
ax1[3].set_xlim(150,1050)
ax1[3].set_ylim(0,900)
#
ax1[4].plot(nrn.timeSamples,iClamp*1000,'k')
ax1[4].set_ylabel('$I_{Stim}$ (pA)')
ax1[4].set_xlim(150,1050)
ax1[4].set_ylim(-10,200)
ax1[4].set_xlabel('time (ms)')
#
ax1[0].text(-0.09, 1.05, 'A.', transform=ax1[0].transAxes, fontsize=18,
             ↪fontweight='bold', va='top', ha='right')
ax1[1].text(-0.09, 1.05, 'B.', transform=ax1[1].transAxes, fontsize=18,
             ↪fontweight='bold', va='top', ha='right')
ax1[2].text(-0.09, 1.05, 'C.', transform=ax1[2].transAxes, fontsize=18,
             ↪fontweight='bold', va='top', ha='right')
ax1[3].text(-0.09, 1.05, 'D.', transform=ax1[3].transAxes, fontsize=18,
             ↪fontweight='bold', va='top', ha='right')
ax1[4].text(-0.09, 1.05, 'E.', transform=ax1[4].transAxes, fontsize=18,
             ↪fontweight='bold', va='top', ha='right');

```



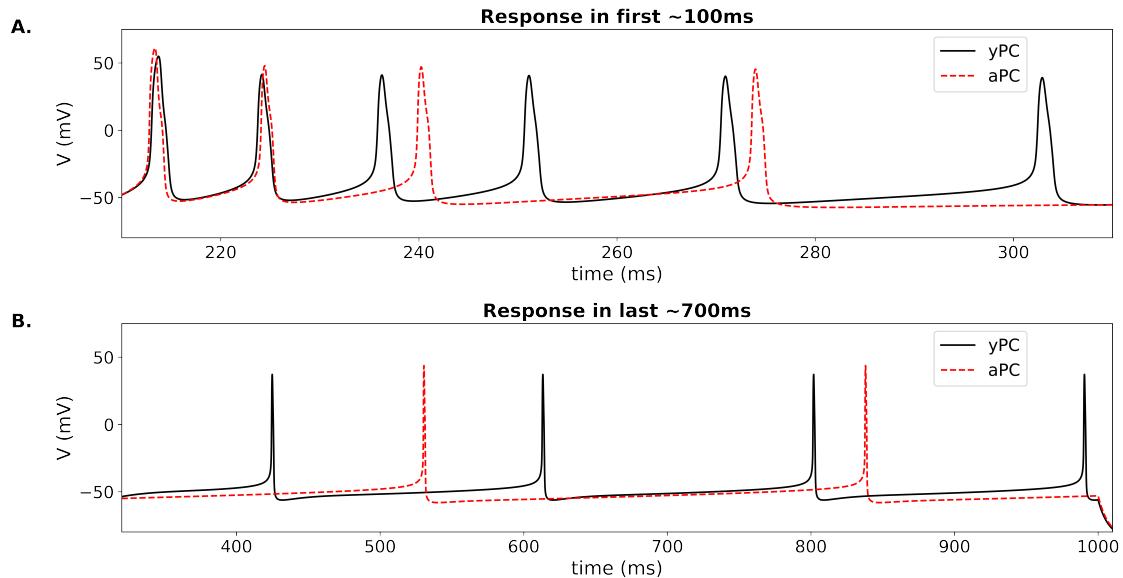
```
[62]: # plot results of previous simulations to compare time windows
ax1=list()
fig1=pl.figure(figsize=(15,8))
pl.ioff()
rows=2; cols=1
for s in np.arange(rows*cols):
    ax1.append(fig1.add_subplot(rows,cols,s+1))

ax1[0].title.set_text('Response in first ~100ms')
ax1[0].title.set_size(18)
ax1[0].title.set_weight('bold')
ax1[0].plot(nrn_y.timeSamples,nrn_y.v,linestyle='solid',color='k',label='yPC')
ax1[0].plot(nrn_o.timeSamples,nrn_o.v,linestyle='dashed',color='r',label='aPC')
ax1[0].set_ylabel('V (mV)')
ax1[0].set_ylim(-80,75)
ax1[0].set_xlim(210,310)
ax1[0].set_xlabel('time (ms)')
ax1[0].legend(loc=(0.82, 0.7))
#
```

```

ax1[1].title.set_text('Response in last ~700ms')
ax1[1].title.set_size(18)
ax1[1].title.set_weight('bold')
ax1[1].plot(nrn_y.timeSamples,nrn_y.v,linestyle='solid',color='k',label='yPC')
ax1[1].plot(nrn_o.timeSamples,nrn_o.v,linestyle='dashed',color='r',label='aPC')
ax1[1].set_ylabel('V (mV)')
ax1[1].set_ylim(-80,75)
ax1[1].set_xlim(320,1010)
ax1[1].set_xlabel('time (ms)')
ax1[1].legend(loc=(0.82, 0.7))
#
ax1[0].text(-0.09, 1.05, 'A.', transform=ax1[0].transAxes, fontsize=18,
    fontweight='bold', va='top', ha='right')
ax1[1].text(-0.09, 1.05, 'B.', transform=ax1[1].transAxes, fontsize=18,
    fontweight='bold', va='top', ha='right')
pl.tight_layout();

```



The change in Ca^{2+} channel expression in the model produces differences in spike frequency adaptation between young (solid black lines) and aged (dashed red lines) PCs. Increased Ca^{2+} influx in aged PCs leads to a larger SK current. This causes the initial number of spikes fired in the first 120 ms after stimulus onset to decrease from 6 to 4, and increases adaptation, thereby slowing firing to a greater extent in the aged PCs for the remaining period of current injection.

1.6.2 Afterhyperpolarizations

CA1 PCs stimulated with a short square-pulse current injection into the soma fire a quick burst of spikes, followed by a period during which the membrane potential dips below the resting potential

and remains there for hundreds of milliseconds to seconds. This period is known as an after-hyperpolarization (AHP). Experiments have shown that aged CA1 PCs have larger AHPs than young PCs, causing decreased excitability and spike failure (see main article for references).

For the following simulation, we rely on the original instance of the class and the previous parameter set. The only parameters we change are related to the current clamp protocol, and the maximum time for the simulation. We stimulate the model PC with a 100ms square pulse current injection of sufficient amplitude that it induces a burst of four spikes (as done in experiments) and then an AHP.

```
[63]: # use original nrn class and parameter set, just change pulse duration and
      ↪amplitude
nrn.reparametrize()
nrn.v0 = -70.0; nrn.w0 = 0.001; nrn.c0=1e-4;
nrn.timeMax = 4000.0; nrn.timeStep = 1.0/40.0;
nrn.startIClamp = 200; nrn.stopIClamp = 300; nrn.iClampAmp=1*75.0; iClamp = nrn.
      ↪IClamp()
v,w,c = nrn.RK2_Autonomous(parNames=['A_F'],parValues=[iClamp,])
nrn.calcBiophysicsFromDynamics(v,w,c);
```

```
A_NaK = 0.0299325, A_DK = 23.946, A_SK = 4.19055, A_NaT = 2.99325, A_CaL =
0.149663,           all in V/s
a_NaK = 10, a_DK = 8000, a_SK = 1400, a_NaT = 1000, a_CaL = 25,           all in
pA
[ 8000  8001  8002 ... 11997 11998 11999] [0. 0. 0. ... 0. 0. 0.]
Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters
nSteps = 160000
```

```
[64]: # plot results
ax1=list()
fig1=pl.figure(figsize=(15,11))
pl.ioff()
r=2; c=1
for s in nu.arange(r*c):
    ax1.append(fig1.add_subplot(r,c,s+1))

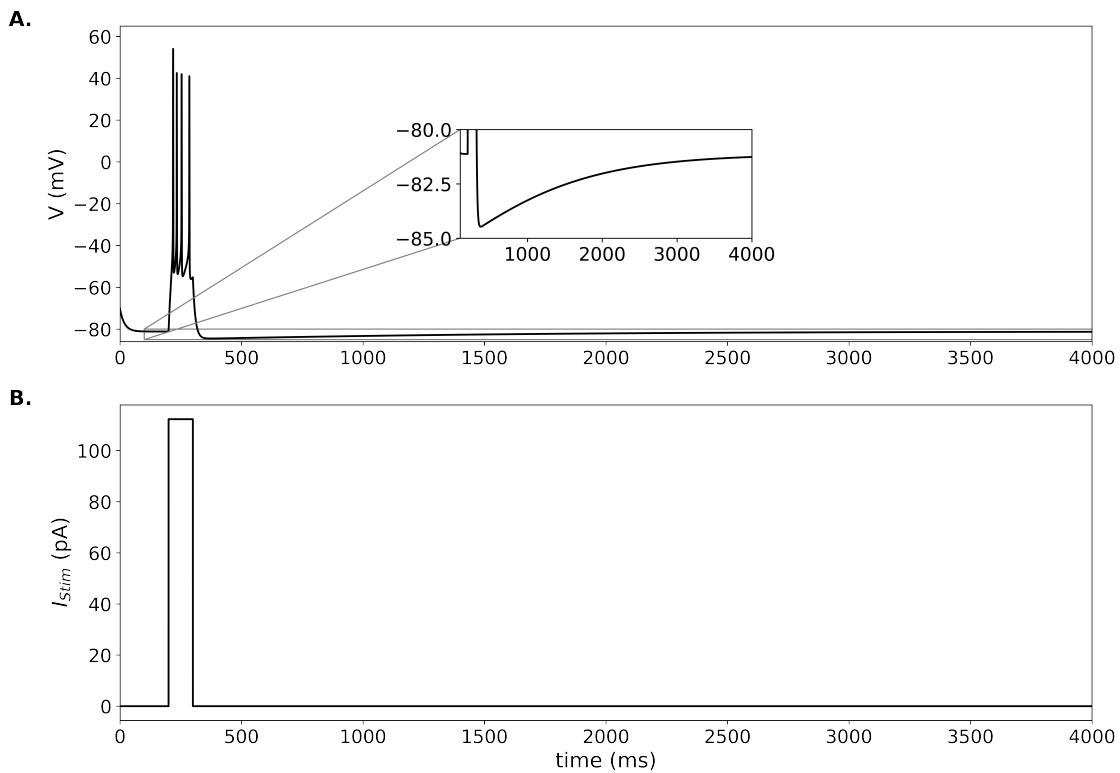
axins = inset_axes(ax1[0],
                   width="30%", # width = 30% of parent_bbox
                   height=1.3, # height : 1 inch
                   loc=10)

ax1[0].plot(nrn.timeSamples, v, 'k', ms=1)
ax1[0].set_ylabel('V (mV)')
ax1[0].set_xlim(0,nrn.timeMax)
ax1[0].set_ylim(-86,65)
mark_inset(ax1[0], axins, loc1=2, loc2=3, fc="none", ec="0.5")
axins.plot(nrn.timeSamples,nrn.v,'k')
```

```

x1, x2, y1, y2 = 100, 4000, -85, -80 # set x and y limits for inset
axins.set_xlim(x1, x2)
axins.set_ylim(y1, y2)
#
ax1[1].plot(nrn.timeSamples,iClamp*1000,'k')
ax1[1].set_ylabel('$I_{Stim}$ (pA)')
ax1[1].set_xlim(0,nrn.timeMax)
ax1[1].set_xlabel('time (ms)')
#
ax1[0].text(-0.09, 1.05, 'A.', transform=ax1[0].transAxes, fontsize=18,
    fontweight='bold', va='top', ha='right')
ax1[1].text(-0.09, 1.05, 'B.', transform=ax1[1].transAxes, fontsize=18,
    fontweight='bold', va='top', ha='right');

```



To explore the effects of aging on AHPs, we rely on the two previous instances of the class we defined above for young and aged cells, which differ only in the amplitude of their L-type Ca^{2+} current. We stimulate the model PCs with a 100ms square pulse current injection to induce a burst of four spikes in both young and aged cells. This required the current amplitude to be increased ($i\text{ClampAmp}$ 20 units higher) for aged cells. Since the same number of spikes is generated in each cell, their subsequent AHPs can be compared. Note, this may take a little while to run since they are long time windows for two cells.

```
[65]: # young PC
nrn_y.timeMax = 4000.0;
nrn_y.startIClamp = 200; nrn_y.stopIClamp = 300; nrn_y.iClampAmp=1*71.0; ↵
↪y_iClamp = nrn_y.IClamp()
v,w,c = nrn_y.RK2_Autonomous(parNames=['A_F'],parValues=[y_iClamp,])
nrn_y.calcBiophysicsFromDynamics(v,w,c);

# aged (old) PC
nrn_o.timeMax = 4000.0;
nrn_o.startIClamp = 200; nrn_o.stopIClamp = 300; nrn_o.iClampAmp=1*94.0; ↵
↪o_iClamp = nrn_o.IClamp()
v,w,c = nrn_o.RK2_Autonomous(parNames=['A_F'],parValues=[o_iClamp,])
nrn_o.calcBiophysicsFromDynamics(v,w,c);
```

```
[ 8000 8001 8002 ... 11997 11998 11999] [0. 0. 0. ... 0. 0. 0.]
Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters
nSteps = 160000
[ 8000 8001 8002 ... 11997 11998 11999] [0. 0. 0. ... 0. 0. 0.]
Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters
nSteps = 160000
```

```
[66]: # plot and compare AHPs in young and aged PCs
ax1=list()
fig1=pl.figure(figsize=(15,13))
pl.ioff()
rows=5; cols=1
for s in np.arange(rows*cols):
    ax1.append(fig1.add_subplot(rows,cols,s+1))

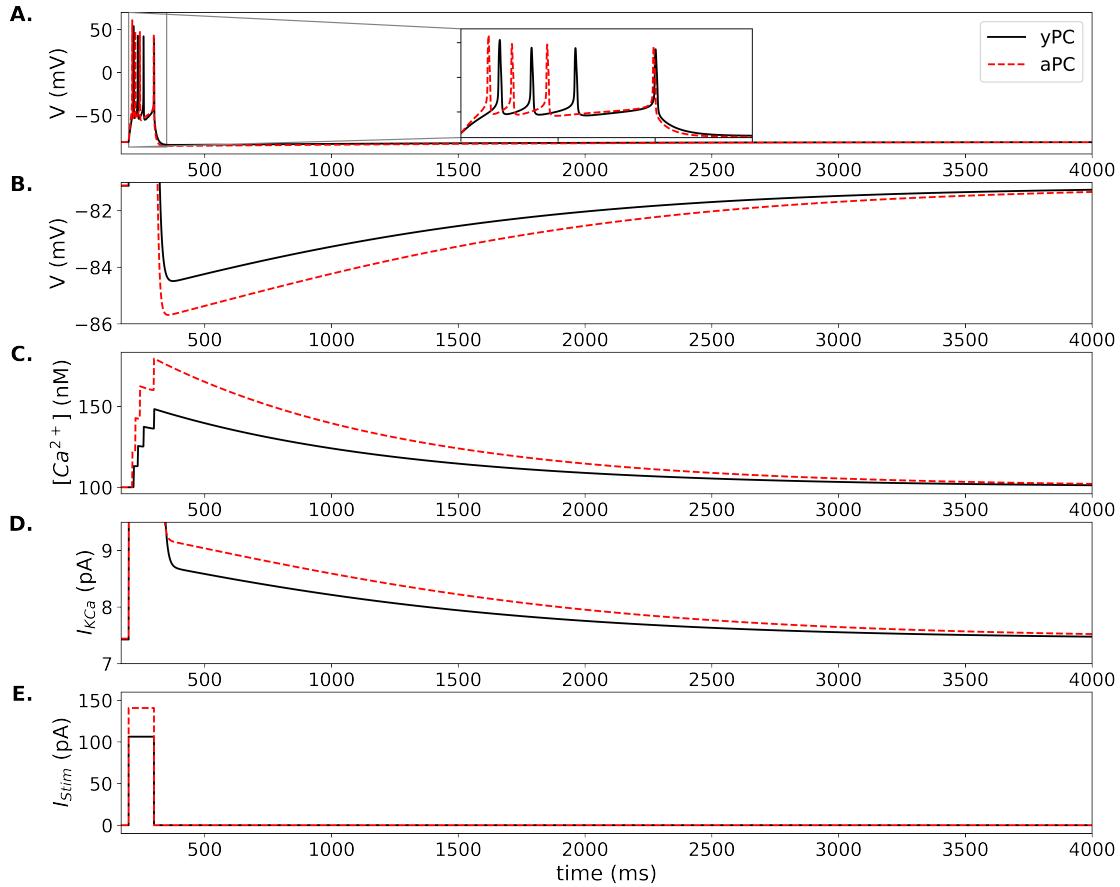
axins = inset_axes(ax1[0],
                    width="30%", # width = 30% of parent_bbox
                    height=1.3, # height : 1 inch
                    loc=10)

ax1[0].plot(nrn_y.timeSamples,nrn_y.v,linestyle='solid',color='k',label='yPC')
ax1[0].plot(nrn_o.timeSamples,nrn_o.v,linestyle='dashed',color='r',label='aPC')
ax1[0].set_ylabel('V (mV)')
ax1[0].set_ylim(-95,70)
ax1[0].set_xlim(170,nrn_o.timeMax)
ax1[0].legend()
#
mark_inset(ax1[0], axins, loc1=2, loc2=3, fc="none", ec="0.5")
axins.plot(nrn_y.timeSamples,nrn_y.v,linestyle='solid',color='k')
axins.plot(nrn_o.timeSamples,nrn_o.v,linestyle='dashed',color='r')
axins.set_xlim(200,350)
```

```

axins.set_ylim(-87,70)
pl.yticks(visible=False)
pl.xticks(visible=False)
#
ax1[1].plot(nrn_y.timeSamples,nrn_y.v,linestyle='solid',color='k')
ax1[1].plot(nrn_o.timeSamples,nrn_o.v,linestyle='dashed',color='r')
ax1[1].set_ylabel('V (mV)')
ax1[1].set_ylim(-86,-81)
ax1[1].set_xlim(170,nrn_o.timeMax)
#
scale_y2=1e-6
ticks_y=ticker.FuncFormatter(lambda x, pos: '{0:g}'.format(x/scale_y2))
ax1[2].yaxis.set_major_formatter(ticks_y)
ax1[2].plot(nrn_y.timeSamples,nrn_y.c,linestyle='solid',color='k')
ax1[2].plot(nrn_o.timeSamples,nrn_o.c,linestyle='dashed',color='r')
ax1[2].set_xlim(170,nrn_o.timeMax)
ax1[2].set_ylabel('[Ca^{2+}] (nM)')
#
ax1[3].plot(nrn_y.timeSamples,nrn_y.jSK,linestyle='solid',color='k')
ax1[3].plot(nrn_o.timeSamples,nrn_o.jSK,linestyle='dashed',color='r')
ax1[3].set_xlabel('time (ms)')
ax1[3].set_ylabel('$I_{KCa}$ (pA)')
ax1[3].set_xlim(170,nrn_o.timeMax)
ax1[3].set_ylim(7,9.5)
#
ax1[4].plot(nrn_y.timeSamples,y_iClamp*1000,linestyle='solid',color='k')
ax1[4].plot(nrn_o.timeSamples,o_iClamp*1000,linestyle='dashed',color='r')
ax1[4].set_ylabel('$I_{Stim}$ (pA)')
ax1[4].set_xlim(170,nrn_o.timeMax)
ax1[4].set_ylim(-10,160)
ax1[4].set_yticks(np.arange(0,160,50))
ax1[4].set_xlabel('time (ms)')
#
ax1[0].text(-0.09, 1.05, 'A.', transform=ax1[0].transAxes, fontsize=18,
    fontweight='bold', va='top', ha='right')
ax1[1].text(-0.09, 1.05, 'B.', transform=ax1[1].transAxes, fontsize=18,
    fontweight='bold', va='top', ha='right')
ax1[2].text(-0.09, 1.05, 'C.', transform=ax1[2].transAxes, fontsize=18,
    fontweight='bold', va='top', ha='right')
ax1[3].text(-0.09, 1.05, 'D.', transform=ax1[3].transAxes, fontsize=18,
    fontweight='bold', va='top', ha='right')
ax1[4].text(-0.09, 1.05, 'E.', transform=ax1[4].transAxes, fontsize=18,
    fontweight='bold', va='top', ha='right');

```



AHPs are observed in both young and aged model PCs, and with relative magnitudes similar to those observed in recordings. The increase in the Ca^{2+} channel expression in aged model PCs is sufficient to produce larger AHPs than seen in young PCs.

1.6.3 Conditional bursting

Experiments show that some CA1 PCs burst in response to current injection, a behavior known as conditional bursting because the cells only display this behavior in response to a stimulus. To reproduce this behavior in the model, we increased the amplitude of the Na^+ and SK currents, decreased the delayed rectifier K^+ current, and increased the rate of K^+ channel activation. We also altered the Ca^{2+} handling. (See main article for more details.)

```
[67]: # use original nrn class, change only necessary parameters
nrn.a_NaT = 1300;
nrn.a_NaK = nrn.a_NaT/100;
nrn.a_DK = 6000;
nrn.a_CaL = 25;
nrn.a_SK = 1600;
#
```

```

nrn.r_in_Ca = 5e-3;
nrn.r_Act_DK = 1.8;
nrn.r_conv_Ca = 6e-6;
#
nrn.reparametrize()
nrn.v0 = -70.0; nrn.w0 = 0.001; nrn.c0=1e-4;
nrn.timeMax = 1200.0; nrn.timeStep = 1.0/40.0;
nrn.startIClamp = 200; nrn.stopIClamp = 1000; nrn.iClampAmp=1*65.0; iClamp = nrn.IClamp()
v,w,c = nrn.RK2_Autonomous(parNames=['A_F'],parValues=[iClamp,])
nrn.calcBiophysicsFromDynamics(v,w,c);

```

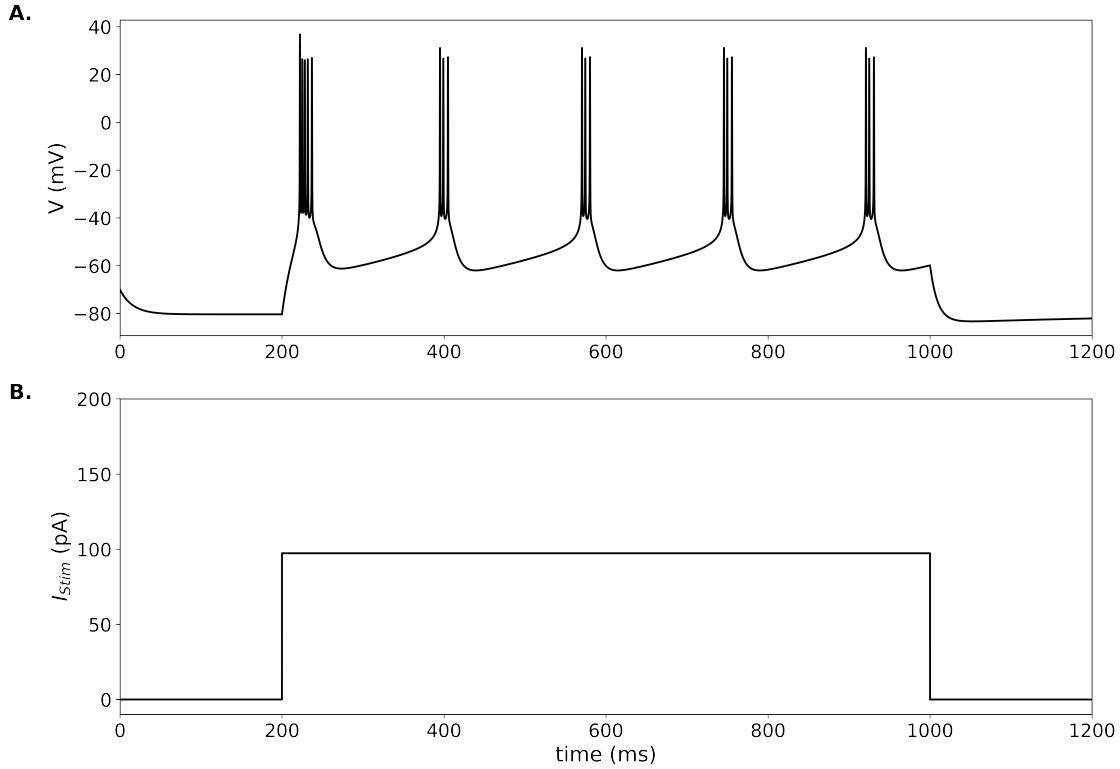
$A_{NaK} = 0.0389123$, $A_{DK} = 17.9595$, $A_{SK} = 4.7892$, $A_{NaT} = 3.89123$, $A_{CaL} = 0.149663$, all in V/s
 $a_{NaK} = 13$, $a_{DK} = 6000$, $a_{SK} = 1600$, $a_{NaT} = 1300$, $a_{CaL} = 25$, all in pA
 $[8000 \ 8001 \ 8002 \dots 39997 \ 39998 \ 39999] [0. \ 0. \ 0. \ \dots 0. \ 0. \ 0.]$
Calculating numerical solution
 $['A_F'] [array([0., 0., 0., \dots, 0., 0., 0.])] 1$ forcing parameters
nSteps = 48000

```

[68]: # plot results
ax1=list()
fig1=pl.figure(figsize=(15,11))
pl.ioff()
rows=2; cols=1
for s in nu.arange(rows*cols):
    ax1.append(fig1.add_subplot(rows,cols,s+1))

ax1[0].plot(nrn.timeSamples, v, 'k', ms=1)
ax1[0].set_ylabel('V (mV)')
ax1[0].set_xlim(0,1200)
#
ax1[1].plot(nrn.timeSamples,iClamp*1000,'k')
ax1[1].set_ylabel('$I_{Stim}$ (pA)')
ax1[1].set_xlim(0,1200)
ax1[1].set_ylim(-10,200)
ax1[1].set_xlabel('time (ms)')
#
ax1[0].text(-0.09, 1.05, 'A.', transform=ax1[0].transAxes, fontsize=18,
            fontweight='bold', va='top', ha='right')
ax1[1].text(-0.09, 1.05, 'B.', transform=ax1[1].transAxes, fontsize=18,
            fontweight='bold', va='top', ha='right');

```



As before, we can zoom in on the activity and plot the different ion currents to see their dynamics and amplitudes during bursting. Depending on what we want to observe, we can change the x and y limits (some currents are much larger than others).

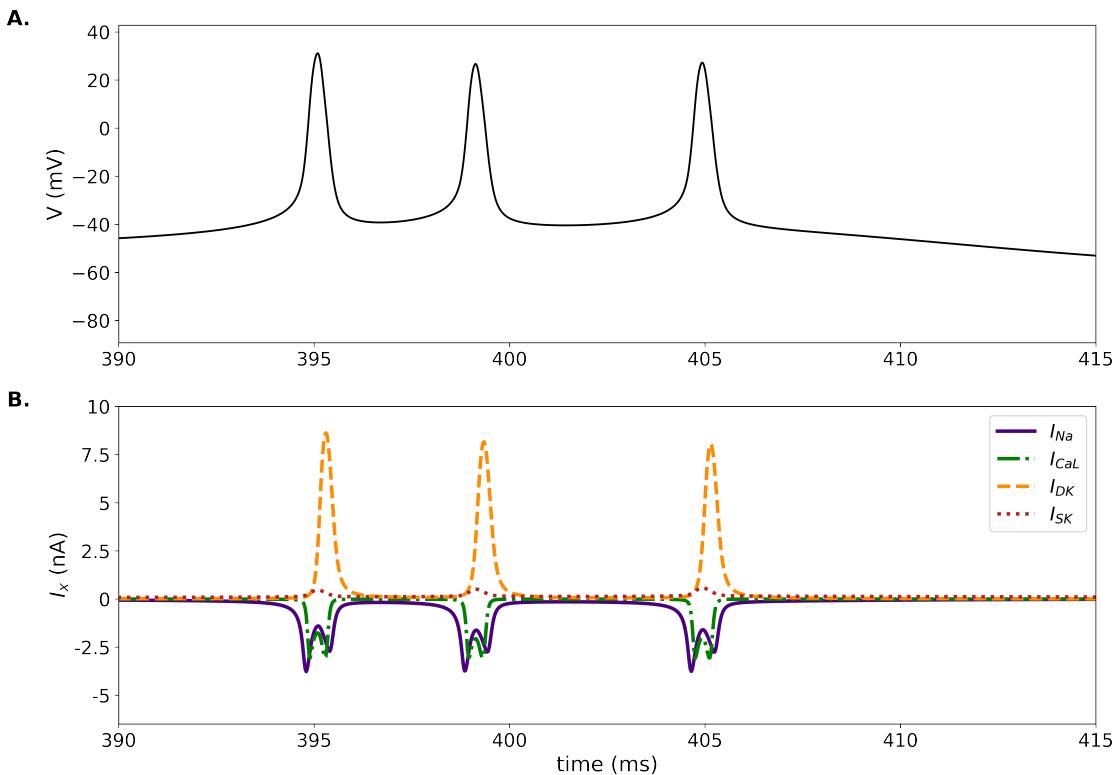
```
[69]: # plot just a few spikes from above simulation and currents
ax1=list()
fig1=pl.figure(figsize=(15,11))
pl.ioff()
rows=2; cols=1
for s in np.arange(rows*cols):
    ax1.append(fig1.add_subplot(rows,cols,s+1))

ax1[0].plot(nrn.timeSamples, v,'k')
ax1[0].set_ylabel('V (mV)')
ax1[0].set_xlim(390,415)
#
ticks_y=ticker.FuncFormatter(lambda x, pos: '{0:g}'.format(x/1000))
ax1[1].yaxis.set_major_formatter(ticks_y)
ax1[1].plot(nrn.timeSamples, nrn.jNaT, linestyle='solid', linewidth=3.0,
             color='indigo', label=r'$I_{Na}$')
ax1[1].plot(nrn.timeSamples, nrn.jCaL, linestyle='dashdot', linewidth=3.0,
             color='green', label=r'$I_{CaL}$')
```

```

ax1[1].plot(nrn.timeSamples, nrn.jDK, linestyle='dashed', linewidth=3.0, u
             ↵color='darkorange', label=r'$I_{DK}$')
ax1[1].plot(nrn.timeSamples, nrn.jSK, linestyle='dotted', linewidth=3.0, u
             ↵color='firebrick', label=r'$I_{SK}$')
#ax1[1].plot(nrn.timeSamples, nrn.jNaK, label=r'$I_{NaK}$')
ax1[1].set_xlabel('time (ms)')
ax1[1].set_ylabel('$I_x$ (nA)')
ax1[1].set_xlim(390,415)
ax1[1].set_ylim(-6500,10000)
ax1[1].legend(loc="upper right")
#
ax1[0].text(-0.09, 1.05, 'A.', transform=ax1[0].transAxes, fontsize=18, u
             ↵fontweight='bold', va='top', ha='right')
ax1[1].text(-0.09, 1.05, 'B.', transform=ax1[1].transAxes, fontsize=18, u
             ↵fontweight='bold', va='top', ha='right');

```



To compare the responses of young and aged PCs, we vary the Ca²⁺ channel amplitude as before. Just to be safe, we'll reestablish the class instances for young and aged PCs, and then change the necessary parameters to produce conditional bursting.

```
[70]: # young PC
nrn_y = pyrCA1(pars)
```

```

n rn_y.a_NaT = 1300;
n rn_y.a_NaK = n rn_y.a_NaT/100;
n rn_y.a_DK = 6000;
n rn_y.a_CaL = 25;
n rn_y.a_SK = 1600;
n rn_y.r_in_Ca = 5e-3;
n rn_y.r_Act_DK = 1.8;
n rn_y.r_conv_Ca = 6e-6;
#
n rn_y.reparametrize()
n rn_y.v0 = -70.0; n rn.w0 = 0.001; n rn.c0=1e-4;
n rn_y.timeMax = 1200.0; n rn.timeStep = 1.0/40.0;
n rn_y.startIClamp = 200; n rn_y.stopIClamp = 1000; n rn_y.iClampAmp=1*65.0; n rn_y.iClamp = n rn_y.IClamp()
v,w,c = n rn_y.RK2_Autonomous(parNames=['A_F'],parValues=[iClamp,])
n rn_y.calcBiophysicsFromDynamics(v,w,c)

# aged (old) PC
n rn_o = pyrCA1(pars)
n rn_o.a_NaT = 1300;
n rn_o.a_NaK = n rn_o.a_NaT/100;
n rn_o.a_DK = 6000;
n rn_o.a_CaL = 50;
n rn_o.a_SK = 1600;
n rn_o.r_in_Ca = 5e-3;
n rn_o.r_Act_DK = 1.8;
n rn_o.r_conv_Ca = 6e-6;
#
n rn_o.reparametrize()
n rn_o.v0 = -70.0; n rn.w0 = 0.001; n rn.c0=1e-4;
n rn_o.timeMax = 1200.0; n rn.timeStep = 1.0/40.0;
n rn_o.startIClamp = 200; n rn_o.stopIClamp = 1000; n rn_o.iClampAmp=1*65.0; n rn_o.iClamp = n rn_o.IClamp()
v,w,c = n rn_o.RK2_Autonomous(parNames=['A_F'],parValues=[iClamp,])
n rn_o.calcBiophysicsFromDynamics(v,w,c);

```

```

A_NaK = 0.0299325, A_DK = 23.946, A_SK = 4.19055, A_NaT = 2.99325, A_CaL =
0.149663, all in V/s
a_NaK = 10, a_DK = 8000, a_SK = 1400, a_NaT = 1000, a_CaL = 25, all in
pA
A_NaK = 0.0389123, A_DK = 17.9595, A_SK = 4.7892, A_NaT = 3.89123, A_CaL =
0.149663, all in V/s
a_NaK = 13, a_DK = 6000, a_SK = 1600, a_NaT = 1300, a_CaL = 25, all in
pA
[ 8000 8001 8002 ... 39997 39998 39999] [0. 0. 0. ... 0. 0. 0.]
Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters

```

```

nSteps = 48000
A_NaK = 0.0299325, A_DK = 23.946, A_SK = 4.19055, A_NaT = 2.99325, A_CaL =
0.149663, all in V/s
a_NaK = 10, a_DK = 8000, a_SK = 1400, a_NaT = 1000, a_CaL = 25, all in
pA
A_NaK = 0.0389123, A_DK = 17.9595, A_SK = 4.7892, A_NaT = 3.89123, A_CaL =
0.299325, all in V/s
a_NaK = 13, a_DK = 6000, a_SK = 1600, a_NaT = 1300, a_CaL = 50, all in
pA
[ 8000 8001 8002 ... 39997 39998 39999] [0. 0. 0. ... 0. 0. 0.]
Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters
nSteps = 48000

```

```
[71]: # plot and compare bursting in young and aged PCs
ax1=list()
fig1=pl.figure(figsize=(15,17))
pl.ioff()
rows=5; cols=1
for s in nu.arange(rows*cols):
    ax1.append(fig1.add_subplot(rows,cols,s+1))

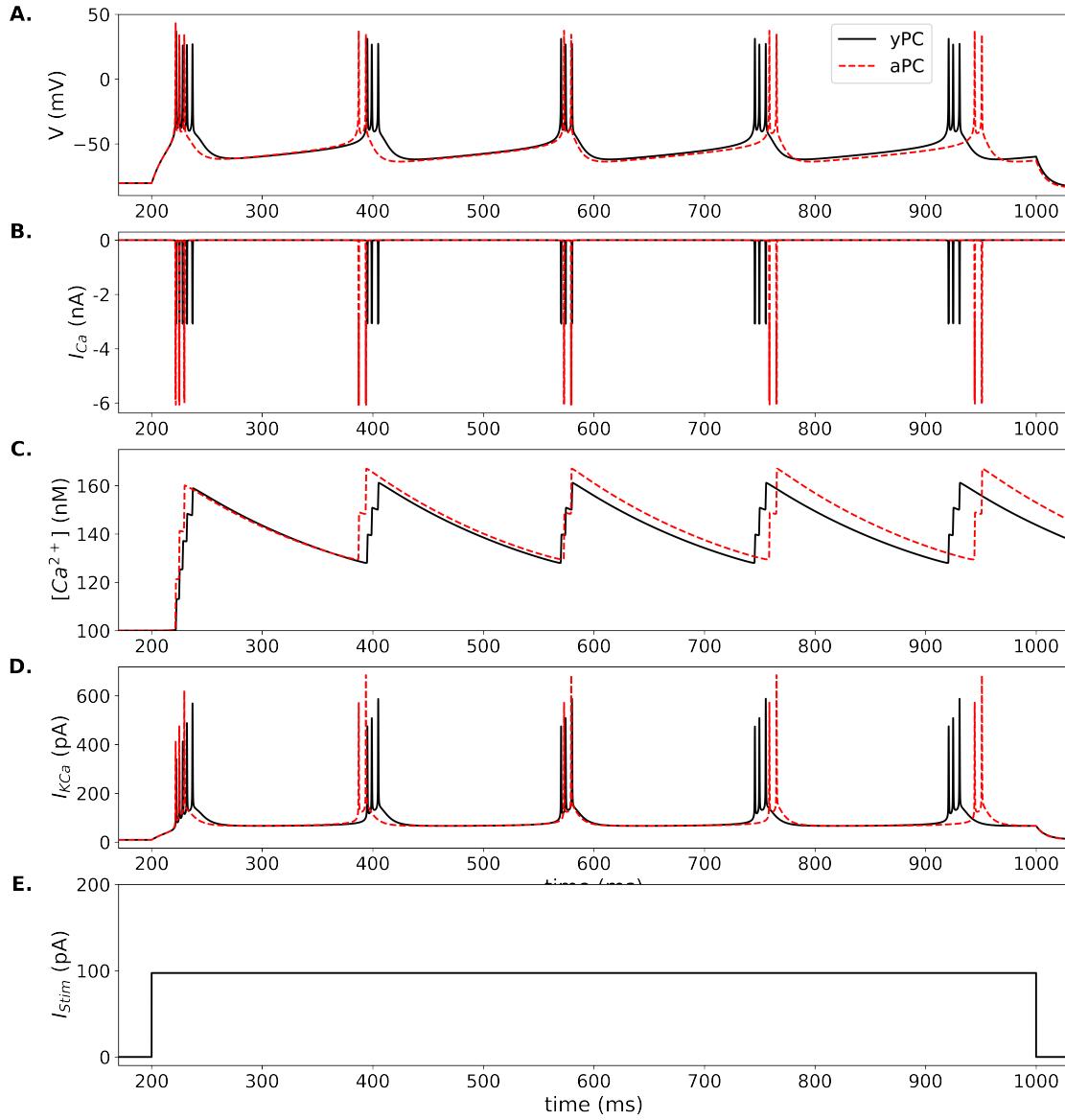
ax1[0].plot(nrn_y.timeSamples,nrn_y.v,linestyle='solid',color='k',label='yPC')
ax1[0].plot(nrn_o.timeSamples,nrn_o.v,linestyle='dashed',color='r',label='aPC')
ax1[0].set_ylabel('V (mV)')
ax1[0].set_ylim(-90,50)
ax1[0].set_xlim(170,1030)
ax1[0].legend(loc=(0.75, 0.62))
#
ticks_y=ticker.FuncFormatter(lambda x, pos: '{0:g}'.format(x/1000))
ax1[1].yaxis.set_major_formatter(ticks_y)
ax1[1].plot(nrn_y.timeSamples,nrn_y.jCaL,linestyle='solid',color='k')
ax1[1].plot(nrn_o.timeSamples,nrn_o.jCaL,linestyle='dashed',color='r')
ax1[1].set_ylabel('$I_{Ca}$ (nA)')
ax1[1].set_xlim(170,1030)
#
scale_y2=1e-6
ticks_y=ticker.FuncFormatter(lambda x, pos: '{0:g}'.format(x/scale_y2))
ax1[2].yaxis.set_major_formatter(ticks_y)
ax1[2].plot(nrn_y.timeSamples,nrn_y.c,linestyle='solid',color='k')
ax1[2].plot(nrn_o.timeSamples,nrn_o.c,linestyle='dashed',color='r')
ax1[2].set_xlim(170,1030)
ax1[2].set_ylim(1e-4,1.75e-4)
ax1[2].set_ylabel('[$Ca^{2+}] (nM)')
#
ax1[3].plot(nrn_y.timeSamples,nrn_y.jSK,linestyle='solid',color='k')
ax1[3].plot(nrn_o.timeSamples,nrn_o.jSK,linestyle='dashed',color='r')

```

```

ax1[3].set_xlabel('time (ms)')
ax1[3].set_ylabel('$I_{KCa}$ (pA)')
ax1[3].set_xlim(170,1030)
#
ax1[4].plot(nrn.timeSamples,iClamp*1000,'k')
ax1[4].set_ylabel('$I_{Stim}$ (pA)')
ax1[4].set_xlim(170,1030)
ax1[4].set_ylim(-10,200)
ax1[4].set_xlabel('time (ms)')
#
ax1[0].text(-0.09, 1.05, 'A.', transform=ax1[0].transAxes, fontsize=18,
    fontweight='bold', va='top', ha='right')
ax1[1].text(-0.09, 1.05, 'B.', transform=ax1[1].transAxes, fontsize=18,
    fontweight='bold', va='top', ha='right')
ax1[2].text(-0.09, 1.05, 'C.', transform=ax1[2].transAxes, fontsize=18,
    fontweight='bold', va='top', ha='right')
ax1[3].text(-0.09, 1.05, 'D.', transform=ax1[3].transAxes, fontsize=18,
    fontweight='bold', va='top', ha='right')
ax1[4].text(-0.09, 1.05, 'E.', transform=ax1[4].transAxes, fontsize=18,
    fontweight='bold', va='top', ha='right');

```



Due to the increased Ca^{2+} entry, aged PCs initially burst earlier than young PCs. However, they fire fewer spikes per burst. As intracellular Ca^{2+} increases and stays elevated, inducing a larger SK current, the activity of the aged PC slows and falls behind the young PC.

However, responses can vary depending on the stimulation. Now, we compare the responses of young and aged PCs to different stimulus amplitudes, ranging from 50 to 170 pA. Note, this simulation can take some time due to running multiple stimulation amplitudes for two cells.

```
[72]: stims=(34,54,74,94,114) # these are the iClampAmp values that go into the iClamp
      ↵protocol
      convs=list()
      for i in stims:
```

```

amp=int((i/nrn.vTCm)*1000)
convs.append(amp)
nstims=len(stims)
print(convs) # these are the converted stimulation amplitudes in pA

```

[50, 80, 110, 140, 170]

```

[73]: simsy = list()
simso = list()

for i in range(nstims):
    # young PC
    nrn_y.iClampAmp=stims[i]; iClamp = nrn_y.IClamp()
    v,w,c = nrn_y.RK2_Autonomous(parNames=['A_F'],parValues=[iClamp,]);
    oo=nrn_y.calcBiophysicsFromDynamics(v,w,c);
    simsy.append(oo);
    # aged (old) PC
    nrn_o.iClampAmp=stims[i]; iClamp = nrn_o.IClamp()
    v,w,c = nrn_o.RK2_Autonomous(parNames=['A_F'],parValues=[iClamp,]);
    oo=nrn_o.calcBiophysicsFromDynamics(v,w,c);
    simso.append(oo);

```

```

[ 8000 8001 8002 ... 39997 39998 39999] [0. 0. 0. ... 0. 0. 0.]
Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters
nSteps = 48000
[ 8000 8001 8002 ... 39997 39998 39999] [0. 0. 0. ... 0. 0. 0.]
Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters
nSteps = 48000
[ 8000 8001 8002 ... 39997 39998 39999] [0. 0. 0. ... 0. 0. 0.]
Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters
nSteps = 48000
[ 8000 8001 8002 ... 39997 39998 39999] [0. 0. 0. ... 0. 0. 0.]
Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters
nSteps = 48000
[ 8000 8001 8002 ... 39997 39998 39999] [0. 0. 0. ... 0. 0. 0.]
Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters
nSteps = 48000
[ 8000 8001 8002 ... 39997 39998 39999] [0. 0. 0. ... 0. 0. 0.]
Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters
nSteps = 48000
[ 8000 8001 8002 ... 39997 39998 39999] [0. 0. 0. ... 0. 0. 0.]
Calculating numerical solution

```

```

['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters
nSteps = 48000
[ 8000 8001 8002 ... 39997 39998 39999] [0. 0. 0. ... 0. 0. 0.]
Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters
nSteps = 48000
[ 8000 8001 8002 ... 39997 39998 39999] [0. 0. 0. ... 0. 0. 0.]
Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters
nSteps = 48000
[ 8000 8001 8002 ... 39997 39998 39999] [0. 0. 0. ... 0. 0. 0.]
Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters
nSteps = 48000

```

```
[74]: # plot the results of the above simulations
ax1=list()
fig1=pl.figure(figsize=(18,25))
pl.rcParams['lines.linewidth'] = 1.1
pl.ioff()
rows=nstims; cols=1
for s in nu.arange(rows*cols):
    ax1.append(fig1.add_subplot(rows,cols,s+1))

for i in range(nstims):
    # plot young PC activity
    ax1[i].plot(nrn_y.
    ↪timeSamples,simsy[i][0],linestyle='solid',color='k',label='yPC')
    ax1[i].text(0.5, 0.5,'%g'%(convs[i])+ 'pA',horizontalalignment='center', ↪
    ↪verticalalignment='center',size=25)
    ax1[i].set_ylabel('V (mV)')
    ax1[i].set_ylim(-90,65)
    ax1[i].set_xlim(150,1050)
    # plot aged PC activity
    ax1[i].plot(nrn_o.
    ↪timeSamples,simso[i][0],linestyle='dashed',color='r',label='aPC')
    ax1[i].text(0.5, 0.5,'%g'%(convs[i])+ 'pA',horizontalalignment='center', ↪
    ↪verticalalignment='center',size=25)
    ax1[i].set_ylabel('V (mV)')
    ax1[i].set_ylim(-90,65)
    ax1[i].set_xlim(150,1050)

ax1[0].legend(prop={'size': 20})
ax1[0].text(-0.2, 1.05, 'A.', transform=ax1[0].transAxes, fontsize=24, ↪
    ↪fontweight='bold', va='top', ha='right')
ax1[1].text(-0.2, 1.05, 'B.', transform=ax1[1].transAxes, fontsize=24, ↪
    ↪fontweight='bold', va='top', ha='right')
```

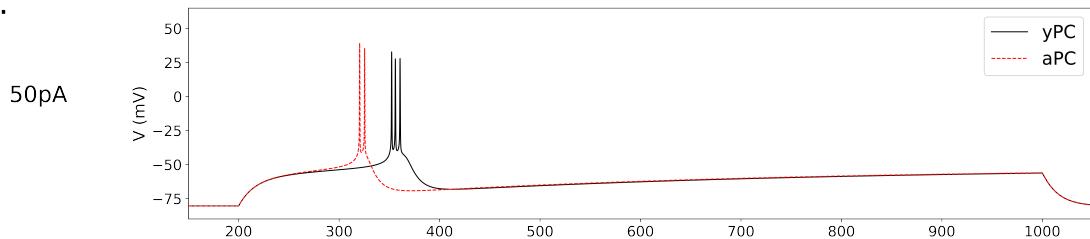
```

ax1[2].text(-0.2, 1.05, 'C.', transform=ax1[2].transAxes, fontsize=24,
    fontweight='bold', va='top', ha='right')
ax1[3].text(-0.2, 1.05, 'D.', transform=ax1[3].transAxes, fontsize=24,
    fontweight='bold', va='top', ha='right')
ax1[4].text(-0.2, 1.05, 'E.', transform=ax1[4].transAxes, fontsize=24,
    fontweight='bold', va='top', ha='right')

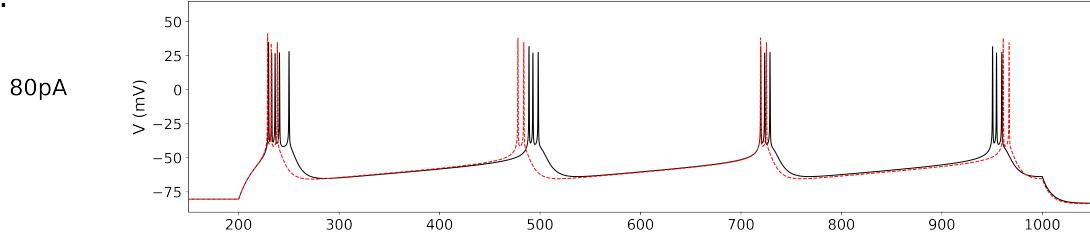
pl.xlabel('time (ms)');

```

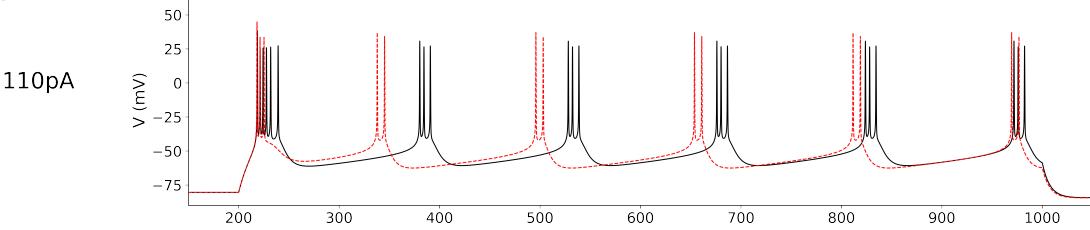
A.



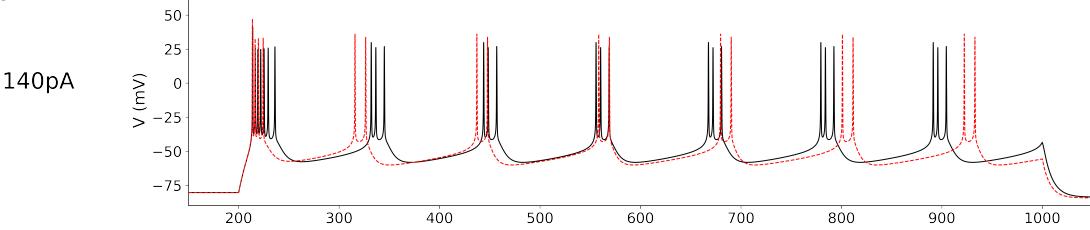
B.



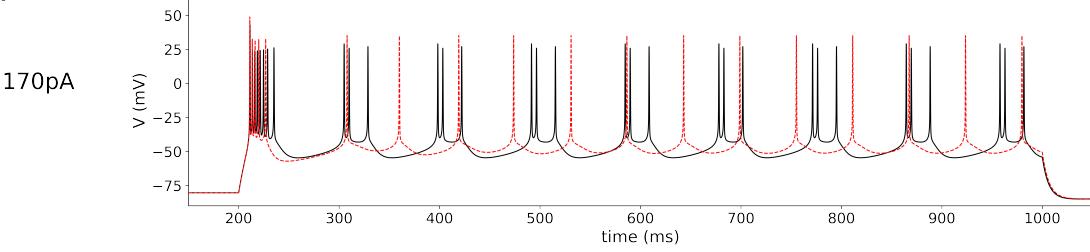
C.



D.



E.



1.6.4 Spontaneous bursting

Experiments have shown that some CA1 pyramidal cells burst spontaneously in the absence of any current injection. To reproduce this firing behavior, we lowered the Na^+ , delayed rectifier K^+ , and SK channel amplitudes, as well as the rate of activation for the delayed rectifier channel. We also altered the Ca^{2+} handling. Note that the stimulation amplitude is set to 0 pA.

```
[75]: nrn.a_NaT = 2300;
nrn.a_NaK = nrn.a_NaT/100;
nrn.a_DK = 7000;
nrn.a_CaL = 25;
nrn.a_SK = 300;
nrn.r_in_Ca = 5e-3;
nrn.r_Act_DK = 1.1;
nrn.r_conv_Ca = 6e-6;
#
nrn.reparametrize()
nrn.v0 = -70.0; nrn.w0 = 0.001; nrn.c0=1e-4;
nrn.timeMax = 3000.0; nrn.timeStep = 1.0/40.0;
nrn.startIClamp = 200; nrn.stopIClamp = 1000; nrn.iClampAmp=0*10.0; iClamp = nrn.IClamp()
v,w,c = nrn.RK2_Autonomous(parNames=['A_F'],parValues=[iClamp,])
nrn.calcBiophysicsFromDynamics(v,w,c);
```

```
A_NaK = 0.0688448, A_DK = 20.9528, A_SK = 0.897975, A_NaT = 6.88448, A_CaL =
0.149663, all in V/s
a_NaK = 23, a_DK = 7000, a_SK = 300, a_NaT = 2300, a_CaL = 25, all in pA
[ 8000 8001 8002 ... 39997 39998 39999] [0. 0. 0. ... 0. 0. 0.]
Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters
nSteps = 120000
```

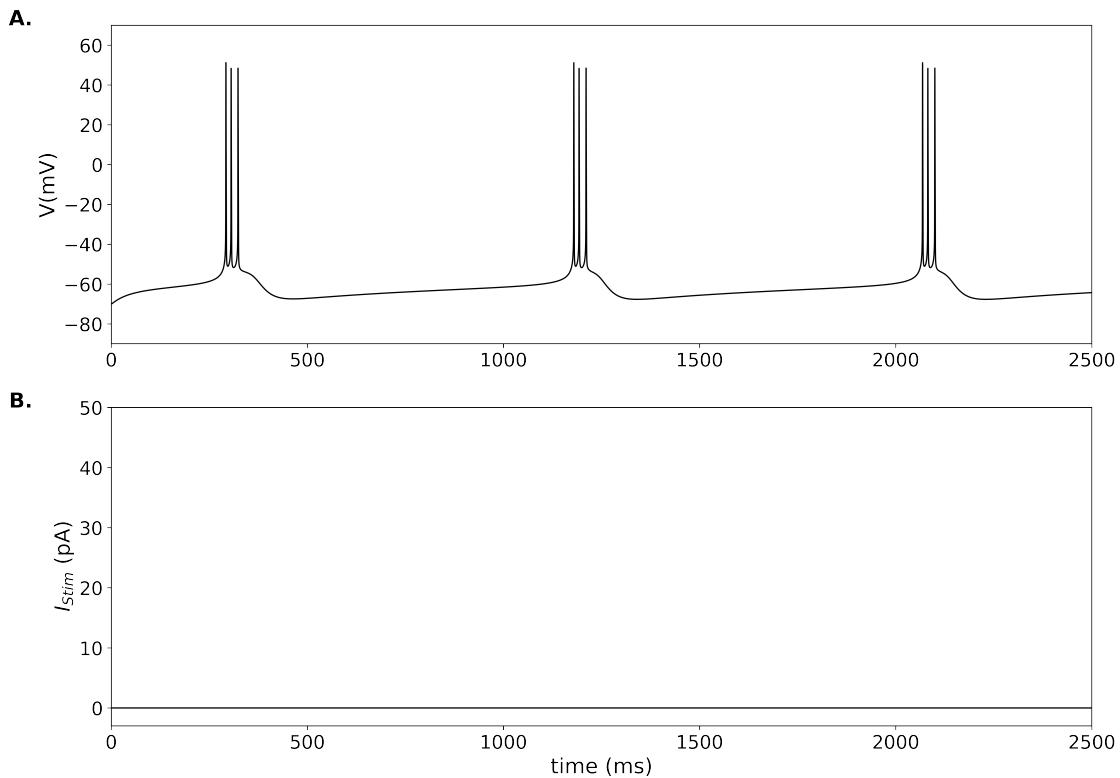
```
[76]: ax1=list()
fig1=pl.figure(figsize=(15,11))
pl.ioff()
rows=2; cols=1
for s in np.arange(rows*cols):
    ax1.append(fig1.add_subplot(rows,cols,s+1))

ax1[0].plot(nrn.timeSamples, v, 'k', ms=1)
ax1[0].set_ylabel('V(mV)')
ax1[0].set_xlim(0,2500)
ax1[0].set_ylim(-90,70)
#
ax1[1].plot(nrn.timeSamples,iClamp*1000,'k')
ax1[1].set_ylabel('$I_{Stim}$ (pA)')
ax1[1].set_xlim(0,2500)
ax1[1].set_ylim(-3,50)
```

```

ax1[1].set_xlabel('time (ms)');
#
ax1[0].text(-0.08, 1.05, 'A.', transform=ax1[0].transAxes, fontsize=18,
    fontweight='bold', va='top', ha='right')
ax1[1].text(-0.08, 1.05, 'B.', transform=ax1[1].transAxes, fontsize=18,
    fontweight='bold', va='top', ha='right');

```



```

[77]: # plot just a few spikes from above simulation and currents
ax1=list()
fig1=pl.figure(figsize=(15,11))
pl.ioff()
rows=2; cols=1
for s in nu.arange(rows*cols):
    ax1.append(fig1.add_subplot(rows,cols,s+1))

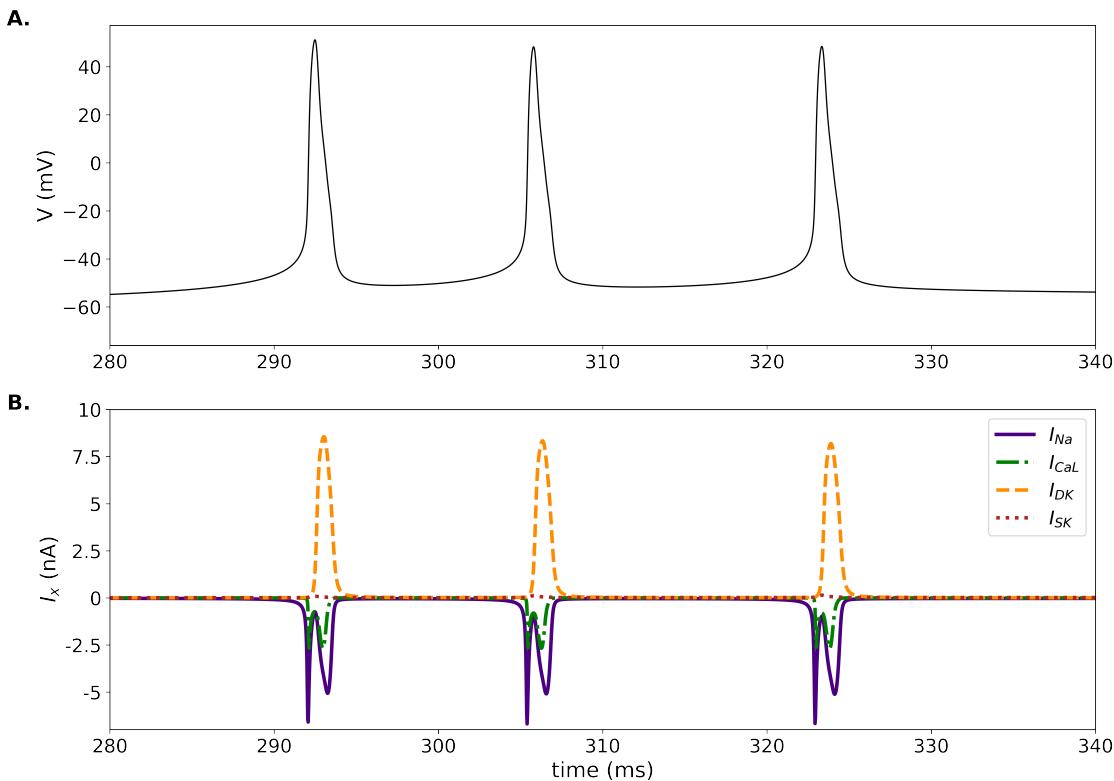
ax1[0].plot(nrn.timeSamples, v, 'k')
ax1[0].set_ylabel('V (mV)')
ax1[0].set_xlim(280,340)
#
ticks_y=ticker.FuncFormatter(lambda x, pos: '{0:g}'.format(x/1000))
ax1[1].yaxis.set_major_formatter(ticks_y)

```

```

ax1[1].plot(nrn.timeSamples, nrn.jNaT, linestyle='solid', linewidth=3.0,
             color='indigo', label=r'$I_{Na}$')
ax1[1].plot(nrn.timeSamples, nrn.jCaL, linestyle='dashdot', linewidth=3.0,
             color='green', label=r'$I_{CaL}$')
ax1[1].plot(nrn.timeSamples, nrn.jDK, linestyle='dashed', linewidth=3.0,
             color='darkorange', label=r'$I_{DK}$')
ax1[1].plot(nrn.timeSamples, nrn.jSK, linestyle='dotted', linewidth=3.0,
             color='firebrick', label=r'$I_{SK}$')
#ax1[1].plot(nrn.timeSamples, nrn.jNaK, label=r'$I_{NaK}$')
ax1[1].set_xlabel('time (ms)')
ax1[1].set_ylabel('$I_x$ (nA)')
ax1[1].set_xlim( 280,340)
ax1[1].set_ylim(-7000,10000)
ax1[1].legend(loc="upper right")
#
ax1[0].text(-0.08, 1.05, 'A.', transform=ax1[0].transAxes, fontsize=18,
             fontweight='bold', va='top', ha='right')
ax1[1].text(-0.08, 1.05, 'B.', transform=ax1[1].transAxes, fontsize=18,
             fontweight='bold', va='top', ha='right');

```



```
[78]: # young PC
n rn_y = pyrCA1(pars)
n rn_y.a_NaT = 2300;
n rn_y.a_NaK = n rn_y.a_NaT/100;
n rn_y.a_DK = 6500; # value changed from base line 7000 for Fig S10
n rn_y.a_CaL = 25;
n rn_y.a_SK = 300;
n rn_y.r_in_Ca = 5e-3;
n rn_y.r_Act_DK = 1.1;
n rn_y.r_conv_Ca = 6e-6;

n rn_y.reparametrize()
n rn_y.v0 = -70.0; n rn_y.w0 = 0.001; n rn_y.c0=1e-4;
n rn_y.timeMax = 3000.0;
n rn_y.startIClamp = 200; n rn_y.stopIClamp = 300; n rn_y.iClampAmp=0*10.0; iClamp
    ↪= n rn_y.IClamp()
v,w,c = n rn_y.RK2_Autonomous(parNames=['A_F'],parValues=[iClamp,])
n rn_y.calcBiophysicsFromDynamics(v,w,c)

# aged (old) PC
n rn_o = pyrCA1(pars)
n rn_o.a_NaT = 2300;
n rn_o.a_NaK = n rn_o.a_NaT/100;
n rn_o.a_DK = 6500; # value changed from base line 7000 for Fig S10
n rn_o.a_CaL = 50;
n rn_o.a_SK = 300;
n rn_o.r_in_Ca = 5e-3;
n rn_o.r_Act_DK = 1.1;
n rn_o.r_conv_Ca = 6e-6;

n rn_o.reparametrize()
n rn_o.v0 = -70.0; n rn_o.w0 = 0.001; n rn_o.c0=1e-4;
n rn_o.timeMax = 3000.0;
n rn_o.startIClamp = 200; n rn_o.stopIClamp = 1000; n rn_o.iClampAmp=0*10.0; iClamp
    ↪= n rn_o.IClamp()
v,w,c = n rn_o.RK2_Autonomous(parNames=['A_F'],parValues=[iClamp,])
n rn_o.calcBiophysicsFromDynamics(v,w,c);
```

$A_{NaK} = 0.0299325, A_{DK} = 23.946, A_{SK} = 4.19055, A_{NaT} = 2.99325, A_{CaL} = 0.149663,$ all in V/s
 $a_{NaK} = 10, a_{DK} = 8000, a_{SK} = 1400, a_{NaT} = 1000, a_{CaL} = 25,$ all in pA
 $A_{NaK} = 0.0688448, A_{DK} = 19.4561, A_{SK} = 0.897975, A_{NaT} = 6.88448, A_{CaL} = 0.149663,$ all in V/s
 $a_{NaK} = 23, a_{DK} = 6500, a_{SK} = 300, a_{NaT} = 2300, a_{CaL} = 25,$ all in pA
 $[8000 \ 8001 \ 8002 \dots 11997 \ 11998 \ 11999] [0. \ 0. \ 0. \ \dots 0. \ 0. \ 0.]$
 Calculating numerical solution

```

['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters
nSteps = 120000
A_NaK = 0.0299325, A_DK = 23.946, A_SK = 4.19055, A_NaT = 2.99325, A_CaL =
0.149663, all in V/s
a_NaK = 10, a_DK = 8000, a_SK = 1400, a_NaT = 1000, a_CaL = 25, all in
pA
A_NaK = 0.0688448, A_DK = 19.4561, A_SK = 0.897975, A_NaT = 6.88448, A_CaL =
0.299325, all in V/s
a_NaK = 23, a_DK = 6500, a_SK = 300, a_NaT = 2300, a_CaL = 50, all in pA
[ 8000 8001 8002 ... 39997 39998 39999] [0. 0. 0. ... 0. 0. 0.]
Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters
nSteps = 120000

```

```

[79]: # plot and compare bursting in young and aged PCs; note DK at 6500 for Fig. S10
ax1=list()
fig1=pl.figure(figsize=(15,17))
pl.ioff()
rows=5; cols=1
for s in nu.arange(rows*cols):
    ax1.append(fig1.add_subplot(rows,cols,s+1))

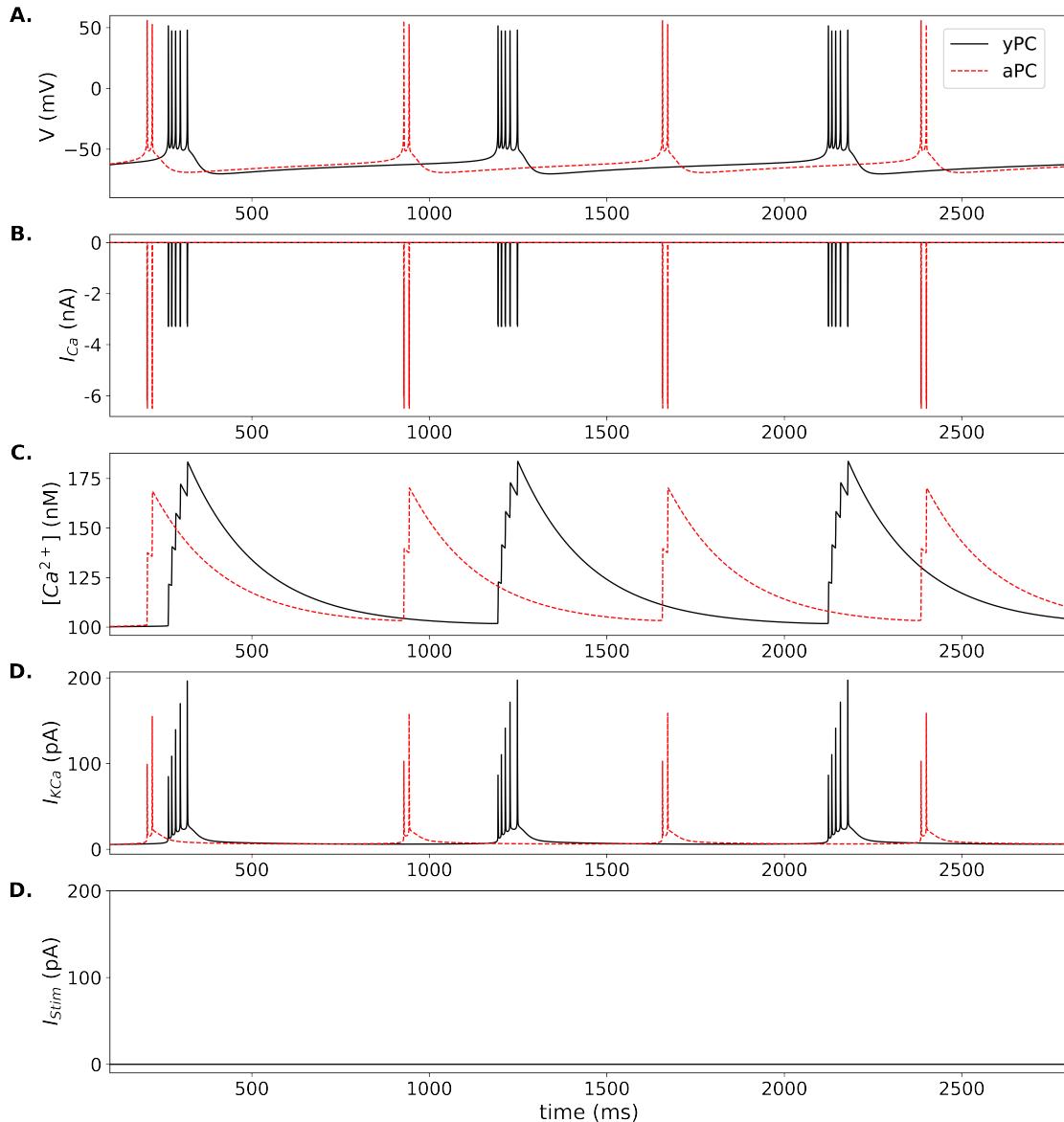
ax1[0].plot(nrn_y.timeSamples,nrn_y.v,linestyle='solid',color='k',label='yPC')
ax1[0].plot(nrn_o.timeSamples,nrn_o.v,linestyle='dashed',color='r',label='aPC')
ax1[0].set_ylabel('V (mV)')
ax1[0].set_ylim(-90,60)
ax1[0].set_xlim(100,2800)
ax1[0].legend(loc=(0.87, 0.6))
#
ticks_y=ticker.FuncFormatter(lambda x, pos: '{0:g}'.format(x/1000))
ax1[1].yaxis.set_major_formatter(ticks_y)
ax1[1].plot(nrn_y.timeSamples,nrn_y.jCaL,linestyle='solid',color='k')
ax1[1].plot(nrn_o.timeSamples,nrn_o.jCaL,linestyle='dashed',color='r')
ax1[1].set_ylabel('$I_{Ca}(nA)$')
ax1[1].set_xlim(100,2800)
#
scale_y2=1e-6
ticks_y=ticker.FuncFormatter(lambda x, pos: '{0:g}'.format(x/scale_y2))
ax1[2].yaxis.set_major_formatter(ticks_y)
ax1[2].plot(nrn_y.timeSamples,nrn_y.c,linestyle='solid',color='k')
ax1[2].plot(nrn_o.timeSamples,nrn_o.c,linestyle='dashed',color='r')
ax1[2].set_xlim(100,2800)
ax1[2].set_ylabel('[$Ca^{2+}] (nM)')
#
ax1[3].plot(nrn_y.timeSamples,nrn_y.jSK,linestyle='solid',color='k')
ax1[3].plot(nrn_o.timeSamples,nrn_o.jSK,linestyle='dashed',color='r')
ax1[3].set_ylabel('$I_{KCa}(pA)$')

```

```

ax1[3].set_xlim(100,2800)
#
ax1[4].plot(nrn.timeSamples,iClamp*1000,'k')
ax1[4].set_ylabel('$I_{Stim}$ (pA)')
ax1[4].set_xlim(100,2800)
ax1[4].set_ylim(-10,200)
ax1[4].set_xlabel('time (ms)')
#
ax1[0].text(-0.08, 1.05, 'A.', transform=ax1[0].transAxes, fontsize=18,
    fontweight='bold', va='top', ha='right')
ax1[1].text(-0.08, 1.05, 'B.', transform=ax1[1].transAxes, fontsize=18,
    fontweight='bold', va='top', ha='right')
ax1[2].text(-0.08, 1.05, 'C.', transform=ax1[2].transAxes, fontsize=18,
    fontweight='bold', va='top', ha='right')
ax1[3].text(-0.08, 1.05, 'D.', transform=ax1[3].transAxes, fontsize=18,
    fontweight='bold', va='top', ha='right')
ax1[4].text(-0.08, 1.05, 'D.', transform=ax1[4].transAxes, fontsize=18,
    fontweight='bold', va='top', ha='right');

```



```
[80]: # different DK amplitudes to loop through
aDKs=(8000,7500,7000,6500,6000)
naDKs=len(aDKs)

simsy = list()
simso = list()

for i in range(naDKs):
    # young PC
    nrn_y.a_DK=aDKs[i];
    nrn_y.reparametrize()
```

```

nrn_y.v0 = -70.0; nrn_y.w0 = 0.001; nrn_y.c0=1e-4;
nrn_y.iClampAmp=0*65.0; iClamp = nrn_y.IClamp()
v,w,c = nrn_y.RK2_Autonomous(parNames=['A_F'],parValues=[iClamp,]);
oo=nrn_y.calcBiophysicsFromDynamics(v,w,c);
simsy.append(oo);

# aged (old) PC
nrn_o.a_DK=aDKs[i];
nrn_o.reparametrize()
nrn_o.v0 = -70.0; nrn_o.w0 = 0.001; nrn_o.c0=1e-4;
nrn_o.iClampAmp=0*65.0; iClamp = nrn_o.IClamp()
v,w,c = nrn_o.RK2_Autonomous(parNames=['A_F'],parValues=[iClamp,]);
oo=nrn_o.calcBiophysicsFromDynamics(v,w,c);
simso.append(oo);

```

```

A_NaK = 0.0688448, A_DK = 23.946, A_SK = 0.897975, A_NaT = 6.88448, A_CaL =
0.149663,           all in V/s
a_NaK = 23, a_DK = 8000, a_SK = 300, a_NaT = 2300, a_CaL = 25,           all in pA
[ 8000 8001 8002 ... 11997 11998 11999] [0. 0. 0. ... 0. 0. 0.]
Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters
nSteps = 120000
A_NaK = 0.0688448, A_DK = 23.946, A_SK = 0.897975, A_NaT = 6.88448, A_CaL =
0.299325,           all in V/s
a_NaK = 23, a_DK = 8000, a_SK = 300, a_NaT = 2300, a_CaL = 50,           all in pA
[ 8000 8001 8002 ... 39997 39998 39999] [0. 0. 0. ... 0. 0. 0.]
Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters
nSteps = 120000
A_NaK = 0.0688448, A_DK = 22.4494, A_SK = 0.897975, A_NaT = 6.88448, A_CaL =
0.149663,           all in V/s
a_NaK = 23, a_DK = 7500, a_SK = 300, a_NaT = 2300, a_CaL = 25,           all in pA
[ 8000 8001 8002 ... 11997 11998 11999] [0. 0. 0. ... 0. 0. 0.]
Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters
nSteps = 120000
A_NaK = 0.0688448, A_DK = 22.4494, A_SK = 0.897975, A_NaT = 6.88448, A_CaL =
0.299325,           all in V/s
a_NaK = 23, a_DK = 7500, a_SK = 300, a_NaT = 2300, a_CaL = 50,           all in pA
[ 8000 8001 8002 ... 39997 39998 39999] [0. 0. 0. ... 0. 0. 0.]
Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters
nSteps = 120000
A_NaK = 0.0688448, A_DK = 20.9528, A_SK = 0.897975, A_NaT = 6.88448, A_CaL =
0.149663,           all in V/s
a_NaK = 23, a_DK = 7000, a_SK = 300, a_NaT = 2300, a_CaL = 25,           all in pA
[ 8000 8001 8002 ... 11997 11998 11999] [0. 0. 0. ... 0. 0. 0.]

```

```

Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters
nSteps = 120000
A_NaK = 0.0688448, A_DK = 20.9528, A_SK = 0.897975, A_NaT = 6.88448, A_CaL =
0.299325,           all in V/s
a_NaK = 23, a_DK = 7000, a_SK = 300, a_NaT = 2300, a_CaL = 50,           all in pA
[ 8000 8001 8002 ... 39997 39998 39999] [0. 0. 0. ... 0. 0. 0.]
Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters
nSteps = 120000
A_NaK = 0.0688448, A_DK = 19.4561, A_SK = 0.897975, A_NaT = 6.88448, A_CaL =
0.149663,           all in V/s
a_NaK = 23, a_DK = 6500, a_SK = 300, a_NaT = 2300, a_CaL = 25,           all in pA
[ 8000 8001 8002 ... 11997 11998 11999] [0. 0. 0. ... 0. 0. 0.]
Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters
nSteps = 120000
A_NaK = 0.0688448, A_DK = 19.4561, A_SK = 0.897975, A_NaT = 6.88448, A_CaL =
0.299325,           all in V/s
a_NaK = 23, a_DK = 6500, a_SK = 300, a_NaT = 2300, a_CaL = 50,           all in pA
[ 8000 8001 8002 ... 39997 39998 39999] [0. 0. 0. ... 0. 0. 0.]
Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters
nSteps = 120000
A_NaK = 0.0688448, A_DK = 17.9595, A_SK = 0.897975, A_NaT = 6.88448, A_CaL =
0.149663,           all in V/s
a_NaK = 23, a_DK = 6000, a_SK = 300, a_NaT = 2300, a_CaL = 25,           all in pA
[ 8000 8001 8002 ... 11997 11998 11999] [0. 0. 0. ... 0. 0. 0.]
Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters
nSteps = 120000
A_NaK = 0.0688448, A_DK = 17.9595, A_SK = 0.897975, A_NaT = 6.88448, A_CaL =
0.299325,           all in V/s
a_NaK = 23, a_DK = 6000, a_SK = 300, a_NaT = 2300, a_CaL = 50,           all in pA
[ 8000 8001 8002 ... 39997 39998 39999] [0. 0. 0. ... 0. 0. 0.]
Calculating numerical solution
['A_F'] [array([0., 0., 0., ..., 0., 0., 0.])] 1 forcing parameters
nSteps = 120000

```

[81]: # plot the results of the above simulations

```

ax1=list()
fig1=pl.figure(figsize=(15,20))
pl.rcParams['lines.linewidth'] = 1.1
pl.ioff()
rows=naDKs; cols=1
for s in nu.arange(rows*cols):
    ax1.append(fig1.add_subplot(rows,cols,s+1))

```

```

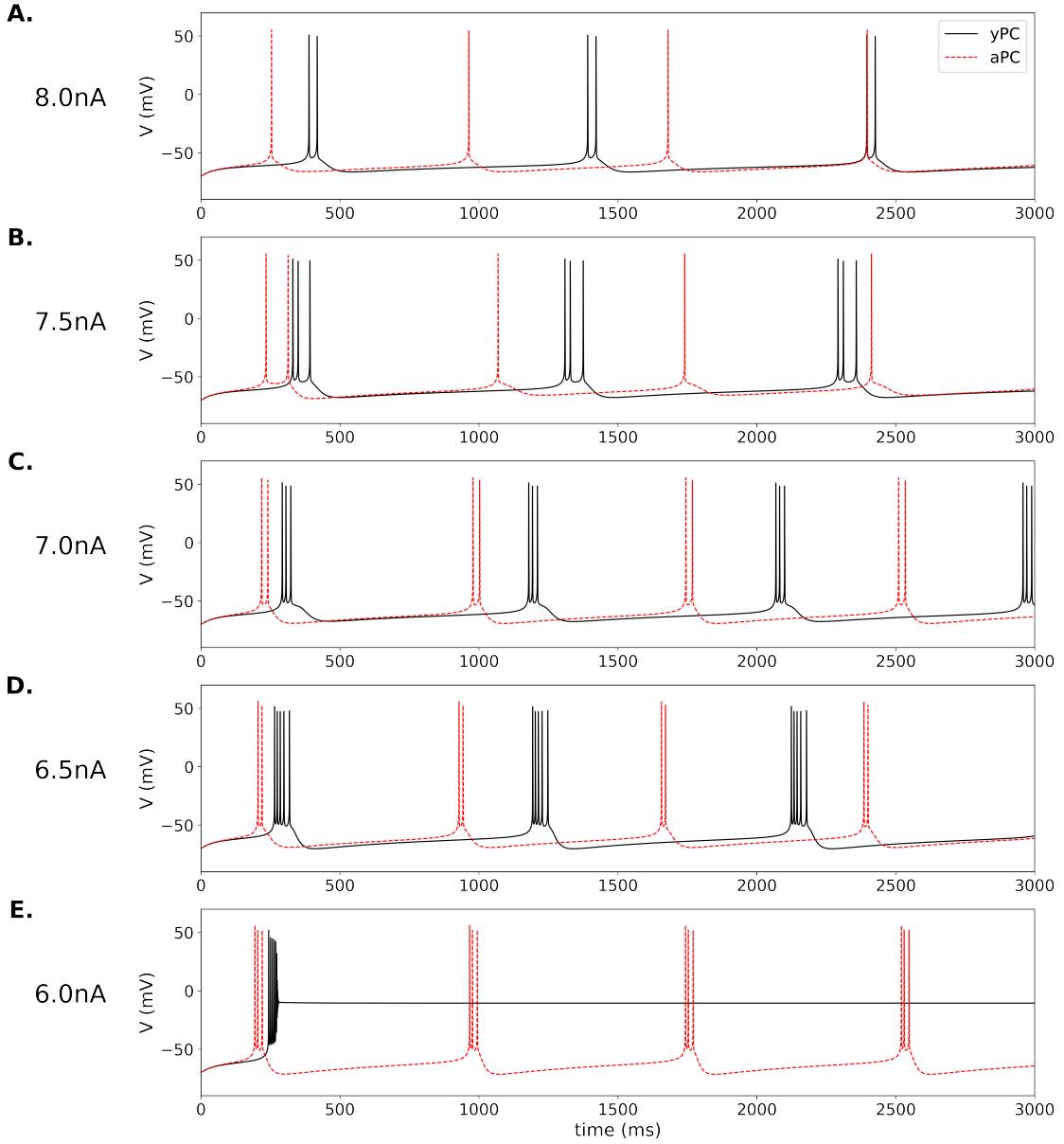
for i in range(naDKs):
    # plot young PC activity
    ax1[i].plot(nrn_y.
    ↪timeSamples,simsy[i][0],linestyle='solid',color='k',label='yPC')
    ax1[i].text(-0.2, 0.5, '%.1f' %(aDKs[i]/1000) + 'nA',size=25,transform=ax1[i].
    ↪transAxes)
    ax1[i].set_ylabel('V (mV)')
    ax1[i].set_ylim(-90,70)
    ax1[i].set_xlim(0,3000)

    # plot aged PC activity
    ax1[i].plot(nrn_o.
    ↪timeSamples,simso[i][0],linestyle='dashed',color='r',label='aPC')
    ax1[i].set_ylabel('V (mV)')
    ax1[i].set_ylim(-90,70)
    ax1[i].set_xlim(0,3000)

ax1[0].legend()
ax1[0].text(-0.2, 1.05, 'A.', transform=ax1[0].transAxes, fontsize=24, ↴
    ↪fontweight='bold', va='top', ha='right')
ax1[1].text(-0.2, 1.05, 'B.', transform=ax1[1].transAxes, fontsize=24, ↴
    ↪fontweight='bold', va='top', ha='right')
ax1[2].text(-0.2, 1.05, 'C.', transform=ax1[2].transAxes, fontsize=24, ↴
    ↪fontweight='bold', va='top', ha='right')
ax1[3].text(-0.2, 1.05, 'D.', transform=ax1[3].transAxes, fontsize=24, ↴
    ↪fontweight='bold', va='top', ha='right')
ax1[4].text(-0.2, 1.05, 'E.', transform=ax1[4].transAxes, fontsize=24, ↴
    ↪fontweight='bold', va='top', ha='right')

pl.xlabel('time (ms)');

```



1.7 Local field potential forcing

While square pulse stimulation is useful for examining the timing of neural responses, it is not a physiologically realistic stimulus. Instead, we can define an Ornstein-Uhlenbeck stochastic process to simulate local field potential (LFP) forcing that CA1 PCs could experience due to the electrical activity of cells in their vicinity. We set it up so one can easily switch between the different parameter sets that give either adaptive firing or conditional bursting to then see the effects of OU forcing. Note that these figures will not come out identical to those in the main paper, since the stimulation is a stochastic process, but the overall results will be similar.

```
[333]: # comparison of responses from yPC vs aPC to OU forcing
def compare_OU_Responses(nrn_y, nrn_o):
    ax1=list()
    fig1=pl.figure(figsize=(15,14))
    pl.ioff()
    rows=4; cols=1
    for s in np.arange(rows*cols):
        ax1.append(fig1.add_subplot(rows,cols,s+1))

    ax1[0].plot(nrn_y.timeSamples,nrn_y.v,linestyle='solid',color='k')
    ax1[0].set_ylabel('V (mV)')
    ax1[0].set_xlim(0,nrn_y.timeMax)
    ax1[0].set_ylim(-80,50)
    #
    ax1[1].plot(nrn_o.timeSamples,nrn_o.v,linestyle='dashed',color='r')
    ax1[1].set_ylabel('V (mV)')
    ax1[1].set_xlim(0,nrn_o.timeMax)
    ax1[1].set_ylim(-80,50)
    #
    ax1[2].plot(nrn_y.timeSamples,nrn_y.
    ↪v,linestyle='solid',color='k',label='yPC')
    ax1[2].plot(nrn_y.timeSamples,nrn_o.v,linestyle='dashed',color='r',alpha=0.
    ↪7,label='aPC')
    ax1[2].set_ylabel('V (mV)')
    ax1[2].set_xlim(0,nrn_y.timeMax)
    ax1[2].set_ylim(-80,50)
    #
    ax1[3].plot(nrn_y.timeSamples,ou1*1000,'k') # LFP stimulus is same for both
    ↪PCs, so plot only once
    ax1[3].set_xlabel('time (ms)')
    ax1[3].set_ylabel('$I_{LFP}$ (pA)')
    ax1[3].set_xlim(0,nrn_y.timeMax)
    ax1[3].set_ylim(-200,350)
    #
    ax1[0].text(-0.08, 1.05, 'A.', transform=ax1[0].transAxes, fontsize=18,
    ↪fontweight='bold', va='top', ha='right')
    ax1[1].text(-0.08, 1.05, 'B.', transform=ax1[1].transAxes, fontsize=18,
    ↪fontweight='bold', va='top', ha='right')
    ax1[2].text(-0.08, 1.05, 'C.', transform=ax1[2].transAxes, fontsize=18,
    ↪fontweight='bold', va='top', ha='right')
    ax1[3].text(-0.08, 1.05, 'D.', transform=ax1[3].transAxes, fontsize=18,
    ↪fontweight='bold', va='top', ha='right')
    ax1[2].legend(loc=(0.84, 0.65))

    pl.show();
    return fig1, ax1
```

```
[133]: # enter 1 to run the following parameter sets for adaptive firing mode
nrn_y.timeMax = 4000
nrn_y.aMean = 50.0;
nrn_y.aSD = 25.0;
nrn_y.aTau = 1/2.0;
ou1 = nrn_y.ouForcing()

if 1:
    # young PC
    nrn_y = pyrCA1(pars)
    nrn_y.a_NaT = 1000;
    nrn_y.a_NaK = nrn_y.a_NaT/100;
    nrn_y.a_DK = 8000;
    nrn_y.a_CaL = 25;
    nrn_y.a_SK = 1400;
    nrn_y.r_in_Ca = 1e-3;
    nrn_y.r_Act_DK = 1.0;
    nrn_y.r_conv_Ca = 3e-6;

    # aged (old) PC
    nrn_o = pyrCA1(pars)
    nrn_o.a_NaT = 1000;
    nrn_o.a_NaK = nrn_o.a_NaT/100;
    nrn_o.a_DK = 8000;
    nrn_o.a_CaL = 50;
    nrn_o.a_SK = 1400;
    nrn_o.r_in_Ca = 1e-3;
    nrn_o.r_Act_DK = 1.0;
    nrn_o.r_conv_Ca = 3e-6;

    nrn_y.reparametrize();
    nrn_o.reparametrize();
    nrn_y.timeMax = 4000.0; nrn_y.timeStep = 1.0/40.0;
    nrn_o.timeMax = 4000.0; nrn_o.timeStep = 1.0/40.0;
    v_y,w,c = nrn_y.RK2_Autonomous(parNames=['A_F'],parValues=[ou1]);
    v_o,w,c = nrn_o.RK2_Autonomous(parNames=['A_F'],parValues=[ou1]);

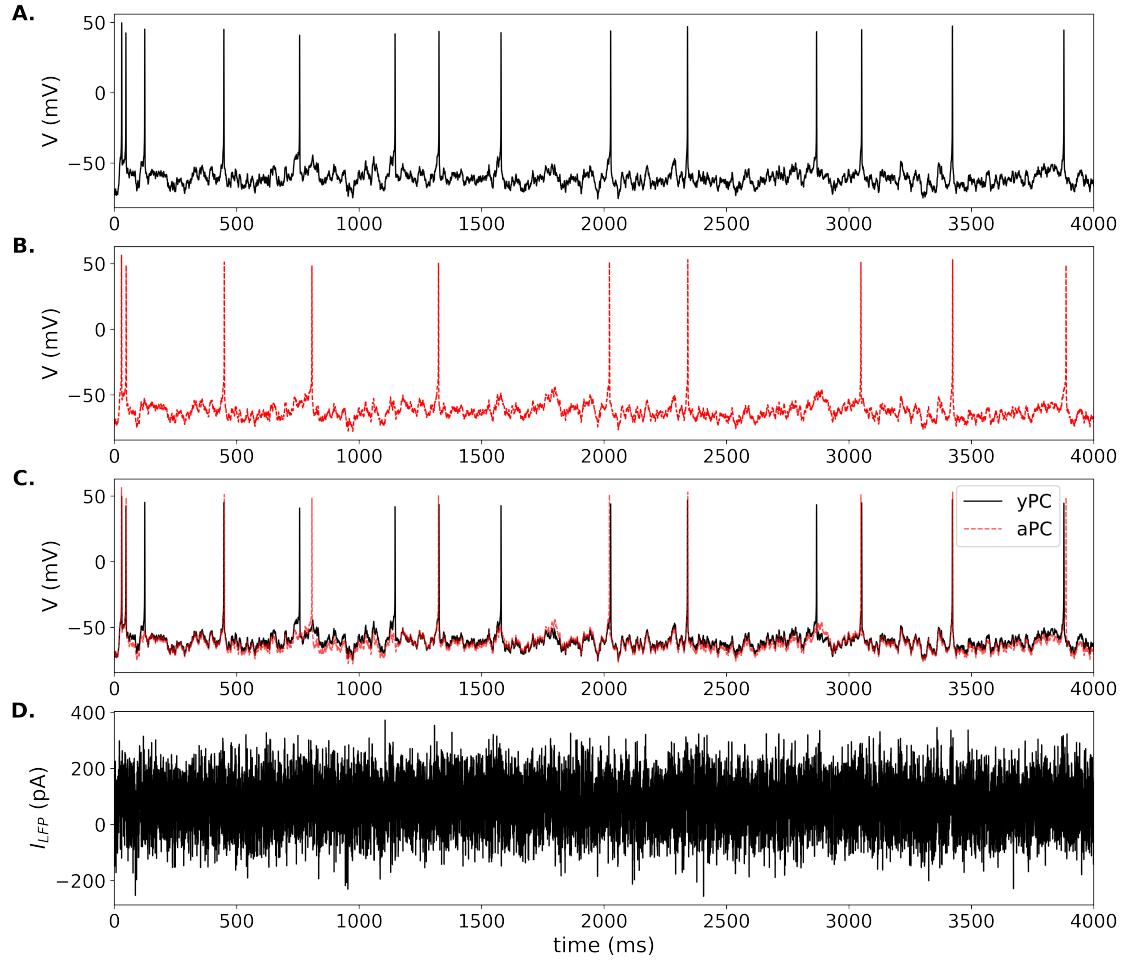
compare_OU_Responses(nrn_y, nrn_o);
```

A_NaK = 0.0299325, A_DK = 23.946, A_SK = 4.19055, A_NaT = 2.99325, A_CaL = 0.149663, all in V/s
a_NaK = 10, a_DK = 8000, a_SK = 1400, a_NaT = 1000, a_CaL = 25, all in pA
A_NaK = 0.0299325, A_DK = 23.946, A_SK = 4.19055, A_NaT = 2.99325, A_CaL = 0.149663, all in V/s
a_NaK = 10, a_DK = 8000, a_SK = 1400, a_NaT = 1000, a_CaL = 25, all in pA

```

A_NaK = 0.0299325, A_DK = 23.946, A_SK = 4.19055, A_NaT = 2.99325, A_CaL =
0.149663,           all in V/s
a_NaK = 10, a_DK = 8000, a_SK = 1400, a_NaT = 1000, a_CaL = 25,           all in
pA
A_NaK = 0.0299325, A_DK = 23.946, A_SK = 4.19055, A_NaT = 2.99325, A_CaL =
0.299325,           all in V/s
a_NaK = 10, a_DK = 8000, a_SK = 1400, a_NaT = 1000, a_CaL = 50,           all in
pA
Calculating numerical solution
['A_F'] [array([ 0.          , -0.04355484, -0.0689107 , ...,
0.00437766,
0.05698767,  0.07016356])] 1 forcing parameters
nSteps = 160000
Calculating numerical solution
['A_F'] [array([ 0.          , -0.04355484, -0.0689107 , ...,
0.00437766,
0.05698767,  0.07016356])] 1 forcing parameters
nSteps = 160000

```



```
[344]: # enter 1 to run the following parameters for conditional bursting mode
nrn_y.timeMax = 1500
nrn_y.aMean = 50.0 ;
nrn_y.aSD = 20.0;
nrn_y.aTau = 1/2.0;
ou1 = nrn_y.ouForcing()

if 1:
    # young PC
    nrn_y = pyrCA1(pars)
    nrn_y.a_NaT = 1300;
    nrn_y.a_NaK = nrn_y.a_NaT/100;
    nrn_y.a_DK = 6000;
    nrn_y.a_CaL = 25;
    nrn_y.a_SK = 1600;
    nrn_y.r_in_Ca = 5e-3;
    nrn_y.r_Act_DK = 1.8;
    nrn_y.r_conv_Ca = 6e-6;

    # aged (old) PC
    nrn_o = pyrCA1(pars)
    nrn_o.a_NaT = 1300;
    nrn_o.a_NaK = nrn_y.a_NaT/100;
    nrn_o.a_DK = 6000;
    nrn_o.a_CaL = 50;
    nrn_o.a_SK = 1600;
    nrn_o.r_in_Ca = 5e-3;
    nrn_o.r_Act_DK = 1.8;
    nrn_o.r_conv_Ca = 6e-6;

    nrn_y.reparametrize();
    nrn_o.reparametrize();
    nrn_y.timeMax = 1500.0; nrn_y.timeStep = 1.0/40.0;
    nrn_o.timeMax = 1500.0; nrn_o.timeStep = 1.0/40.0;
    v,w,c = nrn_y.RK2_Autonomous(parNames=['A_F'],parValues=[ou1]);
    v,w,c = nrn_o.RK2_Autonomous(parNames=['A_F'],parValues=[ou1]);

compare_OU_Responses(nrn_y, nrn_o);
```

A_NaK = 0.0299325, A_DK = 23.946, A_SK = 4.19055, A_NaT = 2.99325, A_CaL = 0.149663, all in V/s
a_NaK = 10, a_DK = 8000, a_SK = 1400, a_NaT = 1000, a_CaL = 25, all in pA
A_NaK = 0.0299325, A_DK = 23.946, A_SK = 4.19055, A_NaT = 2.99325, A_CaL = 0.149663, all in V/s
a_NaK = 10, a_DK = 8000, a_SK = 1400, a_NaT = 1000, a_CaL = 25, all in pA

```

A_NaK = 0.0389123, A_DK = 17.9595, A_SK = 4.7892, A_NaT = 3.89123, A_CaL =
0.149663,           all in V/s
a_NaK = 13, a_DK = 6000, a_SK = 1600, a_NaT = 1300, a_CaL = 25,           all in
pA
A_NaK = 0.0389123, A_DK = 17.9595, A_SK = 4.7892, A_NaT = 3.89123, A_CaL =
0.299325,           all in V/s
a_NaK = 13, a_DK = 6000, a_SK = 1600, a_NaT = 1300, a_CaL = 50,           all in
pA
Calculating numerical solution
['A_F'] [array([ 0.          ,  0.0066752 , -0.00374916, ..., -0.02686002,
   -0.03223091, -0.01485781])] 1 forcing parameters
nSteps = 60000
Calculating numerical solution
['A_F'] [array([ 0.          ,  0.0066752 , -0.00374916, ..., -0.02686002,
   -0.03223091, -0.01485781])] 1 forcing parameters
nSteps = 60000

```

