## 5/22 Initial notes + first steps

- 1) General dynamical systems background
  - @ Read Chapter 1 (pg 5-16) of "Introduction to Applied Nonlinear Dynamical Systems and Chaos" by Wiggins. Pay especial attention to Eq (1.1.1), and section 1.2A Linearization, and Theorem 1.2.5
  - (b) Evaluate the steady states (aka fixed points) of  $\dot{x} = \mu x M x^2 = x (\mu M x)$ , and evaluate their stability. This is the logistic equation.
- 2) 2-dimensional generalized Lotka-Volterra equations The 2D gLV equations are:  $\dot{x} = x(\mu_X + M_{xy})$   $\dot{y} = y(\mu_Y + M_{yx} + M_{yy})$ (2)
  - (a) (0,0) is a trivial steady state. Identify the singly-existing SSs  $(\bar{x},0)$  and  $(0,\bar{y})$  by identifying the value of  $\bar{x}$  and  $\bar{y}$ . Find the matrix equation that  $\bar{y}$  denotes the coexistent steady state  $(\bar{x},\bar{y})$ , but you don't need to solve the matrix equation by hand.
  - (b) Evaluate the stability of (0,0), (\overline{x},0), and (0,\overline{y}) as a print in terms of the parameters mx, my, Mxx, Mxy, Myx, Myy

    (c) What happens for Mxx >0 versus Mxx Lo? Think about how the
    - equations react to positive or negative parameter values
- 3) N-dimensional gLV equations

  The ND gLV equations are, for i=1,..., N,

$$\dot{X}_{i} = X_{i} \left( \mu_{i} + \sum_{j=1}^{N} M_{ij} X_{j} \right)$$
 (3)

- @ Ensure these reduce to Equation (2) for N=2
- (b) Show that there are 2" steady states, (How many 55s are there for Eq (2)? What are they?)
- Simulation

  (a) Simulate Eq (a) with in Python, Use numpy, 'np. linspace, 'scipy integrate', 'pyplot, matplotlish' 'scipy integrate ode int. (Coogle some examples with "numerical simulation and 'plt. plot' and in python." Use an "(IC) of xo=1, M=1, M=.5.
  - (b) Simulate Eq (2). Use  $M_X = M_Y = M_{XX} = M_{YY} = 1$ . Try (5 of  $(x_0, y_0) = (0.1, 0.9)$  and (0.9, 0.1). Use  $(M_{XY}, M_{YX}) = (0.5, 0.5)$  and (1.5, 1.5).

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